# **SIEMENS**

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#### **Safety Guidelines**

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

#### **A** DANGER

indicates that death or severe personal injury will result if proper precautions are not taken.

#### **A**WARNING

indicates that death or severe personal injury may result if proper precautions are not taken.

#### **A**CAUTION

with a safety alert symbol, indicates that minor personal injury can result if proper precautions are not taken.

#### **CAUTION**

without a safety alert symbol, indicates that property damage can result if proper precautions are not taken.

#### **NOTICE**

indicates that an unintended result or situation can occur if the corresponding information is not taken into account.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

#### **Qualified Personnel**

The device/system may only be set up and used in conjunction with this documentation. Commissioning and operation of a device/system may only be performed by **qualified personnel**. Within the context of the safety notes in this documentation qualified persons are defined as persons who are authorized to commission, ground and label devices, systems and circuits in accordance with established safety practices and standards.

#### **Prescribed Usage**

Note the following:

#### **A**WARNING

This device may only be used for the applications described in the catalog or the technical description and only in connection with devices or components from other manufacturers which have been approved or recommended by Siemens. Correct, reliable operation of the product requires proper transport, storage, positioning and assembly as well as careful operation and maintenance.

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#### Disclaimer of Liability

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

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### **Preface**

#### Purpose of the manual

This manual supplements the *ET 200S Distributed I/O System* Operating Instructions. General functions for the ET 200S are described in the *ET 200S Distributed I/O System* Operating Instructions.

The information in this document along with the operating instructions enables you to commission the ET 200S.

#### Basic knowledge requirements

To understand these operating instructions you should have general knowledge of automation engineering.

#### Scope of the manual

This manual applies to this ET 200S module. It describes the components that are valid at the time of publication.

#### Recycling and disposal

Thanks to the fact that it is low in contaminants, this ET 200S module is recyclable. For environmentally compliant recycling and disposal of your electronic waste, please contact a company certified for the disposal of electronic waste.

#### Additional support

If you have any questions relating to the products described in these operating instructions, and do not find the answers in this document, please contact your local Siemens representative.

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The portal to our technical documentation for the various SIMATIC products and systems is available at:

http://www.siemens.com/automation/simatic/portal

The online catalog and ordering system are available at: http://www.siemens.com/automation/mall

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We offer courses to help you get started with the ET 200S and the SIMATIC S7 automation system. Please contact your regional training center or the central training center in D - 90327, Nuremberg, Germany.

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- Your local contact for Automation & Drives in our contact database.
- Information about on-site services, repairs, spare parts. Lots more can be found on our "Services" pages.

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Properties

### 1.1 2AI TC HF analog electronic module (6ES7134-4NB01-0AB0)

#### **Properties**

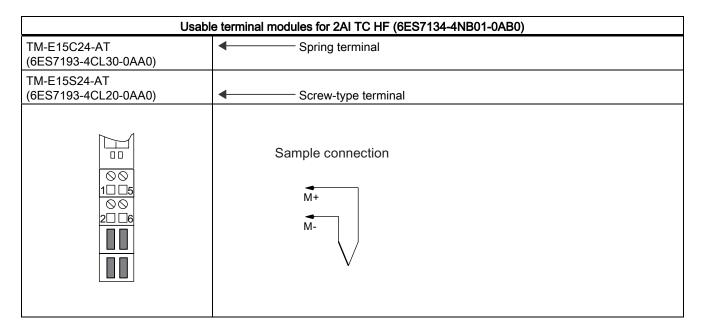
- 2 inputs for thermocouple or voltage measurement
- Input ranges:
  - Voltage measurement: ± 80 mV, resolution 15 bits + sign
  - Thermocouples: Types E, N, J, K, L, S, R, B, T, C, resolution 15 bits + sign
- Isolated from the load voltage L+
- Linearization of the sensor characteristic curves
- Permitted common-mode voltage 140 VDC/100 VAC
- Internal reference junction in connection with TM-E15S24-AT or TM-E15C24-AT

### General terminal assignment

Terminal assignment for 2AI TC HF (6ES7134-4NB01-0AB0)								
Terminal Assignment Terminal Assignment Notes								
1	M <sub>0</sub> +	5	M <sub>1+</sub>	M <sub>n+</sub> : Measuring line positive, channel n				
2	M <sub>0-</sub>	6	M <sub>1-</sub>	M <sub>n-</sub> : Measuring line negative, channel n				

1.1 2AI TC HF analog electronic module (6ES7134-4NB01-0AB0)

#### Usable terminal modules



### **Block diagram**

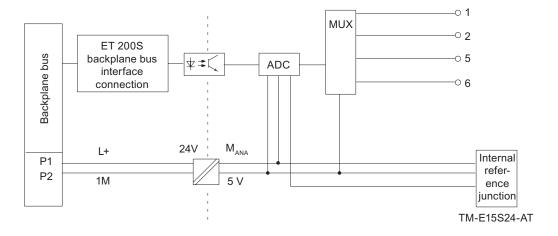


Figure 1-1 Block diagram of the 2AI TC HF

### 2AI TC HF technical specifications (6ES7134-4NB01-0AB0)

Dimensions	and weight			
Width (mm)	15			
Weight	Approx. 40 g			
Module-sp	ecific data			
Supports isochronous operation	no			
Number of inputs	2			
Cable length				
Shielded	Max. 50 m			
Parameter length	4 bytes			
Address space	4 bytes			
Voltages, curre	ents, potentials			
Rated load voltage L+ (from the power module)	24 VDC			
Reverse polarity protection	Yes			
Electrical isolation				
Between the channels and backplane bus	Yes			
Between the channels and load voltage L+	Yes			
Between the channels	No			
Permissible potential difference				
Between M <sub>ANA</sub> and the central grounding point (U <sub>iso</sub> )	75 VDC / 60 VAC			
Between the inputs and Mana (Ucm)	140 VDC / 100 VAC			
Insulation tested	500 VDC			
Current consumption				
From load voltage L+	Max. 30 mA			
Power dissipation of the module	Typically 0.6 W			
Status, interruj	ots, diagnostics			
Diagnostics function				
Group error	Red "SF" LED			
Diagnostic functions readable	Yes			
	e generation			
Measuring principle Integration time/conversion time/resolution per channel:	Integrative			
Integration time can be assigned parameters	Yes			
Interference frequency suppression in Hz		50		
Integration time in ms	16,7	20		
Basic conversion time incl. integration time in ms	66	80		
Additional conversion time for wire break check diagnosis in ms	5	5		
Cycle time in ms	Number of active channels per module x conversion time			
Resolution (including overrange)     15 bits plus sign				

### 1.1 2AI TC HF analog electronic module (6ES7134-4NB01-0AB0)

Suppression of interference, limits of error						
	erence, infines of error					
Noise suppression for $f = n \times (f1 \pm 1 \%)$ , $(f1 = interference frequency)$						
Common-mode interference (Uss)	min. 90 dB					
Series-mode interference	min. 70 dB					
(peak interference value < rated value of input						
range)						
Crosstalk between the inputs	Min50 dB					
Operational limit for ±80 mV (over the entire temperature range with reference to the input range)	± 0,1 %					
Operational limit for thermocouples (over the entire temperature range with reference to the input range) <sup>1</sup>	± 1.5 K					
Operational limit for thermocouple type C (in the entire temperature range with reference to the input range) <sup>1</sup>	± 7 K					
Basic error limit for ±80 mV (operational limit at 25 °C with reference to the input range)	± 0,05 %					
Basic error limit for thermocouples (operational limit at 25 °C with reference to input range) <sup>1</sup>	± 1 K					
Basic error limit for thermocouples of type C (operational limit at 25 °C with reference to the input range) <sup>1</sup>	± 5 K					
Temperature error (with reference to the input range)	± 0.005 %/K					
Linearity error (with reference to the input range)	± 0,01 %					
Repeatability (in steady state at 25°C with reference to input range)	± 0,05 %					
Overall error limits using internal compensation						
<ul> <li>Operational limit (in the entire temperature range with a static, thermal state, ambient temperature change &lt; 0.3 K/min)<sup>2</sup></li> </ul>	± 2.5 K					
<ul> <li>Basic error limit (operational limit at 25°C with a static, thermal state, ambient temperature change &lt; 0.3 K/min)<sup>3</sup></li> </ul>	± 1.5 K					
Data for select	cting a sensor					
Input range (rated value)/input resistance						
Voltage	$\pm$ 80m V/min. 1 M $\Omega$					
Thermocouple	Type E, N, J, K, L, S, R, B, T, C/min. 1 $M\Omega$					
Permitted input voltage (destruction limit)	± 20 V, continuous					
Connection of the sensors						
For measuring voltage	Supported					
Characteristic curve linearization	Yes, can be assigned parameters for type E, N, J, K, L, S, R, B, T, C as per IEC 584					

Temperature compensation						
Internal temperature compensation	Possible with TM	Possible with TM-E15S24-ATTM-E15C24-AT				
External temperature compensation by looping a compensating box into the measuring circuit	Possible, one ex channel	ternal compensating box per				
Smoothing of the measured values	ng of the measured values  Yes, can be assigned parameters in 4 s means of digital filtering					
	Step	Time constant				
	None	1 x cycle time				
	Weak	4 x cycle time				
	Medium	32 x cycle time				
	Strong	64 x cycle time				

<sup>&</sup>lt;sup>1</sup> The specified error limits apply starting with the following temperatures:

- Thermocouple Type T: -200°C
- Thermocouple Type K: -100°C
- Thermocouple Type B: +700°C
- Thermocouple Type N: -150°C
- Thermocouple Type E: -150°C
- Thermocouple Type R: +200°C
- Thermocouple Type S: +100°C
- <sup>2</sup> In the case of thermocouple Type C: ± 8 K
- <sup>3</sup> In the case of thermocouple Type C: ± 6 K

#### Compensation of thermocouples with a compensating box

As well as the error limits of the 2AI TC HF electronic module (see Table "Technical specifications 2AI TC HF (6ES7134-4NB01-0AB0)" in this chapter) you must also take the accuracy of the compensating box into account.

#### Internal compensation with TM-E 15S24-AT or TM-E15C24-AT

ted channel with internal compensation must be arameters separately.  the 2AI TC HF directly next to a power module with any current (> 3 A). An incoming current of 10 A can					
ng current (> 3 A). An incoming current of 10 A can					
ırther ± 2 K error.					
must be in a static state <sup>1</sup> to ensure that the specified achieved.					
achieved 30 minutes after the static state has been					
The overall malfunction of the channel is caused by the combination of the input error and the internal compensation error.					

1.1 2AI TC HF analog electronic module (6ES7134-4NB01-0AB0)

Parameters

### 2.1 Parameters

Table 2-1 Parameters for analog input module

2AI TC HF	Range of values	Default setting	Applicability
Group diagnostics (parameter assignment error,	Disable	Disable	Module
internal error)	Enable		
Diagnostics: Overflow/underflow	Disable	Disable	Module
	Enable		
Diagnostics: Wire-break check *	Disable	Disable	Channel
	Enable		
Smoothing	None	None	Channel
	Weak		
	Medium		
	Strong		
Temperature unit	Celsius	Celsius	Module
	Fahrenheit		
Comparison point	None	None	Channel
	Yes (i.e., internal)		
Type/range of measurement	Deactivated	TC-EL Type K	Channel
	Voltage ±80 mV	(NiCr-Ni)	
	TC-EL Type T (Cu-CuNi)		
	TC-EL Type K (NiCr-Ni)		
	TC-EL Type B (PtRh-PtRh)		
	TC-EL Type C (WRe-WRe)		
	TC-EL Type N (NiCrSi-NiSi)		
	TC-EL Type E (NiCr-CuNi)		
	TC-EL Type R (PtRh-Pt)		
	TC-EL Type S (PtRh-Pt)		
	TC-EL Type J (Fe-Cu-Ni)		
	TC-EL Type L (Fe-Cu-Ni)		

<sup>\*</sup> Only with thermocouples. A parameter assignment error occurs when the wire break diagnostics are enabled in the voltage measuring range. The module does not start up.

### 2.2 Parameter description

#### **Smoothing**

The individual measured values are smoothed by digital filtering. The smoothing can be adjusted in four steps, in which the smoothing factor k multiplied with cycle time of the electronic module equals the time constant of the smoothing filter. The greater the smoothing, the greater the time constant of the filter.

The following diagrams show the step response with the various smoothing factors in relation to the number of module cycles.

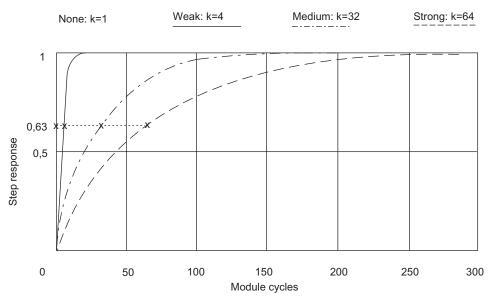
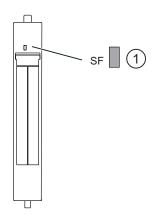


Figure 2-1 Smoothing with the 2AI TC HF

Diagnostics

# 3.1 Diagnostics using LED display

### LED display



① Batch error (red)

### Status and error displays

Event (LED)	Cause	Remedy			
SF					
On	No configuration or incorrect module plugged in. No load voltage.present There is a diagnostic message.	Check the parameter assignment. Check the load voltage. Evaluate the diagnostics.			

# 3.2 Error types

### Analog input module error types

Table 3-1 Error types

	Error type	Meaning	Remedy
16 <sub>D</sub>	10000: Parameter assignment error	Module cannot use the parameter for the channel:	Correct the configuration (align actual and set configuration).
		Inserted module does not match the one configured.	Correct the parameter assignment (wire break
		Incorrect parameter assignment.	diagnostics only parameterized for the permitted measuring ranges).
9 <sub>D</sub>	01001: Error	Internal module error (diagnostic message at channel 0 applies to the entire module)	Replace the module.
<b>7</b> <sub>D</sub>	00111: Upper limit exceeded	Value is above the overshoot range.	Correct the module/final controlling element tuning.
8 <sub>D</sub>	01000: Lower limit value undershot	Value is below the underrange.	Correct the module/final controlling element tuning.
6 <sub>D</sub>	00110: Open circuit	Line to the encoder interrupted.	Correct the process wiring.
21 <sub>D</sub>	10101: Reference channel error	Error on the reference channel	Check the reference module

Analog value representation

# 4

#### 4.1 Introduction

#### Electronic modules with analog outputs

With the electronic module with analog inputs, continuously variable signals, such as those occurring in temperature measurement and resistance measurement, can be acquired, evaluated, and converted to digital values for further processing.

### 4.2 Analog value representation for measuring range with SIMATIC S7

#### Analog value representation

With the same nominal range, the digitized analog value is the same for input and output values. Analog values are represented in two's complement.

The following table shows the analog value representation of the analog electronic modules.

Table 4-1 Analog value representation (SIMATIC S7 format)

Resolution	Analog value															
Bit number	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Significance of the bits	S	214	213	212	211	210	<b>2</b> <sup>9</sup>	28	27	<b>2</b> <sup>6</sup>	<b>2</b> <sup>5</sup>	24	23	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	20

#### Sign

The sign (S) of the analog value is always in bit number 15:

- "0" → +
- "1" → -

4.2 Analog value representation for measuring range with SIMATIC S7

#### Output value

The following table shows the representation of the binary analog values and the corresponding decimal and hexadecimal representation of the units of the analog values.

The table below shows the resolutions 11, 12, 13, and 15 bit + sign. Each analog value is entered left aligned in the ACCU. The bits marked with "x" are set to "0".

Table 4-2 Output values (SIMATIC S7 format)

Resolution in bits	l	Jnits	Analog value			
	Decimal	Hexadecimal	High byte	Low byte		
11+S	16	10 <sub>H</sub>	S000000	0 0 1 x x x x		
12+S	8	8н	S000000	0 0 0 1 x x x		
13+S	4	4н	\$000000	0 0 0 0 1 x x		
15 + sign	1	1н	S000000	000001		

### 4.3 Measuring ranges

### 4.3.1 Measuring ranges for thermocouples

#### Introduction

The following tables contain the digitized analog values for the measuring ranges of the analog input modules.

Since the binary representation of the analog values is always the same, these tables only compare the measuring ranges with the units.

### Measuring range for thermocouple: Type B

Table 4-3 SIMATIC S7 format: Type B measuring range in °C and °F

Type B in °C	l	Inits	Type B in °F	Uı	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 2070,0	32767	7FFF <sub>H</sub>	> 3276,6	32767	7FFF <sub>H</sub>	Overflow
2070,0	20700	50DCн	3276,6	32766	7FFE <sub>H</sub>	
:	:	:	:	:	:	Overshoot range
1820,1	18201	4719н	2786,6	27866	6CDA <sub>н</sub>	
1820,0	18200	4718 <sub>H</sub>	2786,5	27865	6CD9 <sub>H</sub>	
:	:	:	:	:	:	Nominal range
0,0	0	0000н	32	320	0140н	
-0,1	-1	FFFF <sub>H</sub>	31,9	319	013Fн	
:	:	:	:	:	:	Underrange
-120,0	-1200	FB50 <sub>H</sub>	-184,0	-1840	F8D0 <sub>H</sub>	
< -120,0	-32768	8000н	< -184,0	-32768	8000н	Underflow

### 4.3 Measuring ranges

### Measuring range for thermocouple: Type C

Table 4-4 SIMATIC S7 format: Type C measuring range in °C and °F

Type C in °C	L	Inits	Type C in °F	Ur	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 2500,0	32767	7FFF <sub>H</sub>	> 3276,6	32767	7FFF <sub>H</sub>	Overflow
2500,0	25000	61A8 <sub>H</sub>	3276,6	32766	7FFE <sub>H</sub>	
:	:	:	:	:	:	Overshoot range
2315,1	23151	5A6Fн	2786,6	27866	6CDAн	
2315,0	23150	5A6E <sub>н</sub>	2786,5	27865	6CD9 <sub>H</sub>	
:	:	:	:	:	:	Nominal range
0,0	0	0000н	32,0	320	0140н	
0,1	-1	FFFF <sub>H</sub>	31,9	319	013Fн	
:	:	:	:	:	:	Underrange
-120,0	-1200	FB50 <sub>H</sub>	-184,0	-1840	F8D0 <sub>H</sub>	
< -120,0	-32768	8000н	< -184,0	-32768	8000н	Underflow

### Measuring range for thermocouple Type E

Table 4-5 SIMATIC S7 format: Type E measuring range in °C and °F

Type E in °C	L	Inits	Type E in °F	Ur	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 1200,0	32767	7FFF <sub>H</sub>	> 2192,0	32767	7FFF <sub>H</sub>	Overflow
1200,0	12000	2EE0 <sub>H</sub>	2192,0	21920	55A0 <sub>н</sub>	
:	:	:	:	:	:	Overshoot range
1000,1	10001	2711н	1832,1	18321	4791н	
1000,0	10000	2710 <sub>H</sub>	1832,0	18320	4790н	
:	:	:	:	:	:	Nominal range
-270,0	-2700	F574 <sub>H</sub>	-454,0	-4540	EE44 <sub>H</sub>	
< -270,0	- 32768	8000н	< -454,0	- 32768	8000н	Underflow

### Measuring range for thermocouple Type J

Table 4-6 SIMATIC S7 format: Type J measuring range in °C and °F

Type J in °C	L	Inits	Type J in °F	Units		Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 1450,0	32767	7FFF <sub>H</sub>	> 2642,0	32767	7FFF <sub>H</sub>	Overflow
1450,0	14500	38A4 <sub>H</sub>	2642,0	26420	6734 <sub>H</sub>	
:	:	:	:	:	:	Overshoot range
1200,1	12010	2EEA <sub>H</sub>	2192,1	21921	55А1н	
1200,0	12000	2EE0 <sub>H</sub>	2192,0	21920	55A0 <sub>н</sub>	
:	:	:	:	:	:	Nominal range
-210,0	-2100	F7CC <sub>H</sub>	-346,0	-3460	F27C <sub>H</sub>	
< -210,0	- 32768	8000н	< -346,0	- 32768	8000н	Underflow

### Measuring range for thermocouple Type K

Table 4-7 SIMATIC S7 format: Type K measuring range in °C and °F

Type K in °C	l	Inits	Type K in °F	Ur	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 1622,0	32767	7FFF <sub>H</sub>	> 2951,6	32767	7FFF <sub>H</sub>	Overflow
1622,0	16220	3F5Cн	2951,6	29516	734Сн	
:	:	:	:	:	:	Overshoot range
1372,1	13721	3599н	2501,7	25062	61В9н	
1372,0	13720	3589н	2501,6	25061	61В8н	
:	:	:	:	:	:	Nominal range
-270,0	-2700	F574 <sub>H</sub>	-454,0	-4540	EE44 <sub>H</sub>	
< -270,0	- 32768	8000н	< -454,0	- 32768	8000н	Underflow

### 4.3 Measuring ranges

### Measuring range for thermocouple Type L

Table 4-8 SIMATIC S7 format: Type L measuring range in °C and °F

Type L in °C	L	Inits	Type L in °F	Units		Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 1150,0	32767	7FFF <sub>H</sub>	> 2102,0	32767	7FFF <sub>H</sub>	Overflow
1150,0	11500	2CEC <sub>H</sub>	2102,0	21020	521C <sub>н</sub>	
:	:	:	:	:	:	Overshoot range
900,1	9001	2329н	1652,1	16521	4089н	
900,0	9000	2328н	1652,0	16520	4088н	
:	:	:	:	:	:	Nominal range
-200,0	-2000	F830 <sub>H</sub>	-328,0	-3280	F330 <sub>н</sub>	
< -200,0	-32768	8000н	< -328,0	-32768	8000н	Underflow

### Measuring range for thermocouple Type N

Table 4-9 SIMATIC S7 format: Type N measuring range in °C and °F

Type N in °C	ι	Inits	Type N in °F	Ur	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 1550,0	32767	7FFF <sub>H</sub>	> 2822,0	32767	7FFF <sub>H</sub>	Overflow
1550,0	15500	3С8Сн	2822,0	28220	6Е3Сн	
:	:	:	:	:	:	Overshoot range
1300,1	13001	32С9н	2372,1	23721	5СА9н	
1300,0	13000	32C8 <sub>H</sub>	2372,0	23720	5CA8 <sub>н</sub>	
:	:	:	:	:	:	Nominal range
-270,0	-2700	F574 <sub>H</sub>	-454,0	-4540	EE44 <sub>H</sub>	
< -270,0	-32768	8000н	-32768	8000н	<ee44<sub>H</ee44<sub>	Underflow

### Measuring range for thermocouple Types R, S

Table 4-10 SIMATIC S7 format: Type R, S measuring range in °C and °F

Type R, S in °C	U	Inits	Type R, S in °F	Ur	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 2019,0	32767	7FFF <sub>H</sub>	> 3276,6	32767	7FFF <sub>H</sub>	Overflow
2019,0	20190	4EDE <sub>H</sub>	3276,6	32766	7FFE <sub>H</sub>	
:	:	:	:	:	:	Overshoot range
1769,1	17691	451B <sub>H</sub>	3216,3	32163	7DA3н	
1769,0	17690	451A <sub>H</sub>	3216,2	32162	7DA2 <sub>H</sub>	
:	:	:	:	:	:	Nominal range
-50,0	-500	FE0C <sub>H</sub>	-58,0	-580	FDBCH	
-50,1	-510	FE0B <sub>H</sub>	-58,1	-581	FDBB <sub>H</sub>	
:	:	:	:	:	:	Underrange
-170,0	-1700	F95C <sub>H</sub>	-274,0	-2740	F54C <sub>H</sub>	
< -170,0	-32768	8000н	< -274,0	-32768	8000н	Underflow

### Measuring range for thermocouple Type T

Table 4-11 SIMATIC S7 format: Type T measuring range in °C and °F

Type T in °C	ľ	Jnits	Type T in °F	Uı	nits	Range
	Decimal	Hexadecima I		Decimal	Hexadeci mal	
> 540,0	32767	7FFF <sub>H</sub>	> 1004,0	32767	7FFF <sub>H</sub>	Overflow
540,0	5400	1518 <sub>H</sub>	1004,0	10040	2738н	
:	:	:				Overshoot range
400,1	4001	0FA1н	752,1	7521	1DC1н	
400,0	4000	0FA0 <sub>н</sub>	752,0	7520	1D60 <sub>H</sub>	
:	:	:	:	:	:	Nominal range
-270,0	-2700	F574 <sub>H</sub>	-454,0	-4540	EE44 <sub>H</sub>	
< -270,0	-32768	8000н	< -454,0	-32768	8000н	Underflow

#### 4.3 Measuring ranges

### 4.3.2 Voltage measuring ranges

Voltage measuring ranges: ±80 mV

Table 4-12 SIMATIC S7 format: Measuring range ±80 mV

Measuring range ±80 mV	Units		Range
	Decimal	Hexadecimal	
> 94,071	32767	7FFF <sub>H</sub>	Overflow
94,071	32511	7EFF <sub>H</sub>	
:	:	:	Overshoot range
80,003	27649	6С01н	
80,000	27648	6С00н	
60,000	20736	5100 <sub>H</sub>	
:	:	:	Nominal range
-60,000	-20736	AF00 <sub>H</sub>	
-80,000	-27648	9400 <sub>H</sub>	
-80,003	-27649	93FF <sub>н</sub>	
:	:	:	Underrange
-94,074	-32512	8100 <sub>H</sub>	
< -94,074	-32768	8000н	Underflow

# Measured values in the event of a wire break, depending on the diagnostics enabled for voltage measurement

In the case of the measuring ranges for types B, C, E, J, K, L, N, R, S, and T thermocouples, the following additional information applies:

Table 4-13 Measured values in the event of a wire break, depending on the diagnostics enabled for voltage measurement

Format		Parameter assignment	Measu	ired values	Description
			Decimal	Hexadecimal	
S7	•	"Wire-break check" diagnostics enabled	32767	7FFF <sub>H</sub>	"Open circuit" diagnostic message
	•	"Overflow/underflow" diagnostics disabled	-32767	8000н	Measured value after leaving the underrange
					"Lower limit value undershot" diagnostic message
	•	"Wire-break check" diagnostics disabled			Open input: Undefined measured value

### 4.4 Effect on analog value representation

### 4.4.1 Effect of the supply voltage and the operating state on analog input values

The input values of the analog modules are dependent on the supply voltage for electronics/encoders and on the operating state of the PLC (CPU of the DP master). This is illustrated by the table below.

Table 4-14 Relationship between the analog input values for the operating state of the PLC (CPU of the DP master) and the supply voltage L+

Operating state of the PLC (CPU of the DP master)		Supply voltage L+ on ET 200S (power module)	Input value of the electronic module with analog inputs (evaluation possible on the CPU of the DP master)
POWER ON	RUN	L+ present	Process values
			7FFF <sub>H</sub> until first conversion after startup, or after assignment of parameters for the module is completed.
		L+ missing	7FFF <sub>H</sub>
POWER ON	STOP	L+ present	Process value
		L+ missing	7FFF <sub>H</sub>
POWER OFF	-	L+ present	-
		L+ missing	-

### 4.4.2 Effect of the value range on the 2AI TC HF analog input

The way electronic modules respond to analog inputs depends on where the input values fall within the value range. This is illustrated by the table below.

Table 4-15 Response of the analog modules, depending on where the analog input value falls within the range of values

Measured value within	Input value in SIMATIC S7 format	Input value in SIMATIC S5 format
Nominal range	Measured value	Measured value
Over-/underrange	Measured value	Measured value
Overflow	7FFF <sub>H</sub>	End of the overshoot range +1 plus overflow bit
Underflow	8000 <sub>H</sub>	End of the underrange -1 plus overflow bit
Prior to parameter assignment, or incorrect parameter assignment	7FFF <sub>H</sub>	7FFF <sub>H</sub>

4.4 Effect on analog value representation

Connecting

### 5.1 Connecting measuring sensors

#### Introduction

You can connect encoders with voltage signals and thermocouples to the 2AI TC HF analog input module.

In this chapter you will find out how to connect the measuring encoders and what to watch out for when doing so.

#### Cables for analog signals

You should use shielded and twisted-pair cables for the analog signals. This reduces the effect of interference. You should ground the shield of the analog cables at both ends. If there are differences in potential between the cable ends, an equipotential bonding current that may interfere with the analog signals will flow across the shield. If this is the case, you should only ground the shield at one end of the cable.

#### Analog input modules

The analog input modules are electrically isolated:

- Between the logic and backplane bus
- Between the load voltage and the channels.
  - Electrical isolation: No link between MANA and the central grounding point (UISO)

#### Note

Ensure that this difference in potential  $U_{\rm ISO}$  does not exceed the permitted value. If there is a possibility of exceeding the permitted value, establish a connection between terminal  $M_{\rm ANA}$  and the central grounding point.

#### Connecting measuring encoders to analog inputs

There can be only a limited potential difference  $U_{\text{CM}}$  (common mode) between the measuring lines M- of the input channels and the reference point of the measuring circuit  $M_{\text{ANA}}$ . To ensure that the permitted value is not exceeded, you must take different steps depending on the whether the encoders are isolated or non-isolated. The steps you have to take are described in this chapter.

#### 5.1 Connecting measuring sensors

#### Abbreviations used

The meanings of the abbreviations in the figures below are as follows:

M+: Measuring line (positive)M- Measuring line (negative)M Ground connection

L+ Rated load voltage 24 V DC

U<sub>CM</sub> Potential difference between inputs and reference potential of the measuring

circuit MANA

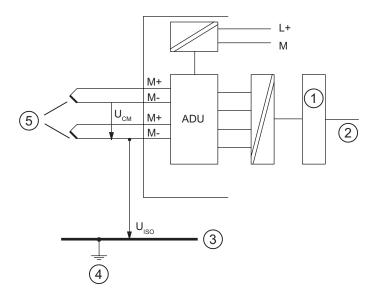
U<sub>ISO</sub> Potential difference between M- and central grounding point

#### Isolated measuring encoders

The isolated measuring encoders are not connected to the local ground potential. These can be potential-free. Depending on local conditions or interference, potential differences  $U_{CM}$  (static or dynamic) can occur between the measuring lines M- of the input channels and the reference point of the measuring circuit  $M_{ANA}$ .

The permitted value for U<sub>CM</sub> must not be exceeded, even in environments with strong EMC interference.

The following schematic representation illustrates the connection of isolated measuring encoders to the optically isolated analog input modules.



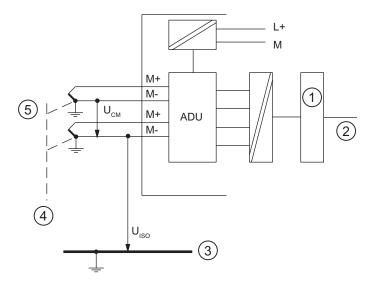
- ① Logic
- ② Backplane bus
- 3 Ground bus
- ④ Central grounding point
- ⑤ Isolated measuring encoders

### Non-isolated measuring encoders

The non-isolated measuring encoders are connected to the local ground potential. You must connect  $M_{\text{ANA}}$  to the ground potential. Depending on local conditions or interference, potential differences  $U_{\text{CM}}$  (static or dynamic) can occur between the locally distributed measuring points.

If the permitted value for  $U_{\text{CM}}$  is exceeded, there must be equipotential bonding conductors between the measuring points.

The following schematic representation illustrates the connection of non-isolated measuring encoders to an optically isolated analog input module.



- ① Logic
- ② Backplane bus
- 3 Ground bus
- ④ Equipotential bonding conductor
- ⑤ Non-isolated measuring encoders

#### Non-isolated thermocouples

When using non-isolated thermocouples, you must comply with the permitted common mode voltage.

### 5.2 Connecting thermocouples

#### Introduction

This section contains additional information on connecting thermocouples.

#### Compensation of the comparison point temperature

There are various ways of obtaining the comparison point temperature in order to get an absolute temperature value from the temperature difference between the comparison point and the measuring point.

Table 5-1 Compensation of the comparison point temperature

Option	Description	Comparison point parameters				
No compensation	It is not just the temperature of the measuring point that you need to record: The temperature of the comparison point (transition from Cu line to thermocouple line) also affects the thermoelectromotive force. The measured value on its own is incorrect.	None				
Using a compensating box on the supply lines of a single thermocouple	You compensate using a compensating box. The compensating box is the transition point from the Cu line to the thermocouple line. No further processing is necessary using the 2AI TC ST.	None				
Internal compensation in the case of the 2AI TC HF	There is a temperature sensor in the TM-E15S24-AT and TM-E15C24-AT terminal modules. The temperature sensor reports the temperature of the terminals to the 2AI TC HF. This value is then calculated together with the measured value from the channel of the electronic module.	2AI TC HF: Reference junction: Yes				

#### Extension to a comparison point

The thermocouples can be extended from their connection point by means of compensating lines to the comparison point (transition to Cu line) or the compensating box. The comparison point can also be an ET 200S terminal module.

The compensating lines are made of the same material as the wires of the thermocouple. The supply lines are made of copper. Ensure the correct polarity when connecting.

#### Using a compensating box

The effect of the temperature on the comparison point of a thermocouple (such as a terminal box) can be adjusted with a compensating box.

The compensating box contains a bridge circuit that is adjusted for a certain comparison point temperature (compensating temperature). You connect the thermocouples or their compensating lines to the compensating box. The compensating box then forms the comparison point.

If the actual reference temperature differs from the compensating temperature, the temperature-dependent bridge resistance changes. A positive or negative compensation voltage occurs; this is added to the thermo-electromotive force.

Compensating boxes with a **comparison point temperature of 0°C** must be used for the compensation of the analog input modules.

#### Note:

- The power supply to the compensating box must be isolated.
- The power supply unit must have adequate interference filtering (by means of a grounded shielding winding, for example).

### 5.3 Wiring unused channels on analog input modules

#### Rules

Pay attention to the following instructions when wiring unused channels:

- "Deactivate" unused input channels when assigning parameters.
- A deactivated channel always returns the value 7FFF<sub>H</sub>.
- The module cycle time is halved with the 2AI TC HF standard module.
- To adhere to the permissible potential differences (U<sub>CM</sub>), you must wire jumpers on the terminal module for the unused channels.

Analog input module	TM connecting terminal							
	Channel 0		Channel 1					
	1	2	3	4	5	6	7	8
2AI TC HF	•	•			•	•		

5.4 Using the shield connection

## 5.4 Using the shield connection

#### Rules

To prevent interference we recommend the following for analog electronic modules:

- Use shielded wires to the sensors and actuators.
- Lay out the wire shields on the shield connection.
- Connect the shield connection to the ground bus with low impedance.

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