

# Speed control with SIMATIC S7-1200 and SINAMICS V90PN via PROFINET

SINAMICS V90 PN

<https://support.industry.siemens.com/cs/ww/en/view/109739222>

Siemens  
Industry  
Online  
Support



# Legal information

## Use of application examples

Application examples illustrate the solution of automation tasks through an interaction of several components in the form of text, graphics and/or software modules. The application examples are a free service by Siemens AG and/or a subsidiary of Siemens AG ("Siemens"). They are non-binding and make no claim to completeness or functionality regarding configuration and equipment. The application examples merely offer help with typical tasks; they do not constitute customer-specific solutions. You yourself are responsible for the proper and safe operation of the products in accordance with applicable regulations and must also check the function of the respective application example and customize it for your system.

Siemens grants you the non-exclusive, non-sublicensable and non-transferable right to have the application examples used by technically trained personnel. Any change to the application examples is your responsibility. Sharing the application examples with third parties or copying the application examples or excerpts thereof is permitted only in combination with your own products. The application examples are not required to undergo the customary tests and quality inspections of a chargeable product; they may have functional and performance defects as well as errors. It is your responsibility to use them in such a manner that any malfunctions that may occur do not result in property damage or injury to persons.

## Disclaimer of liability

Siemens shall not assume any liability, for any legal reason whatsoever, including, without limitation, liability for the usability, availability, completeness and freedom from defects of the application examples as well as for related information, configuration and performance data and any damage caused thereby. This shall not apply in cases of mandatory liability, for example under the German Product Liability Act, or in cases of intent, gross negligence, or culpable loss of life, bodily injury or damage to health, non-compliance with a guarantee, fraudulent non-disclosure of a defect, or culpable breach of material contractual obligations. Claims for damages arising from a breach of material contractual obligations shall however be limited to the foreseeable damage typical of the type of agreement, unless liability arises from intent or gross negligence or is based on loss of life, bodily injury or damage to health. The foregoing provisions do not imply any change in the burden of proof to your detriment. You shall indemnify Siemens against existing or future claims of third parties in this connection except where Siemens is mandatorily liable.

By using the application examples you acknowledge that Siemens cannot be held liable for any damage beyond the liability provisions described.

## Other information

Siemens reserves the right to make changes to the application examples at any time without notice. In case of discrepancies between the suggestions in the application examples and other Siemens publications such as catalogs, the content of the other documentation shall have precedence.

The Siemens terms of use (<https://support.industry.siemens.com>) shall also apply.

## Security information

Siemens provides products and solutions with industrial security functions that support the secure operation of plants, systems, machines and networks.

In order to protect plants, systems, machines and networks against cyber threats, it is necessary to implement – and continuously maintain – a holistic, state-of-the-art industrial security concept. Siemens' products and solutions constitute one element of such a concept.

Customers are responsible for preventing unauthorized access to their plants, systems, machines and networks. Such systems, machines and components should only be connected to an enterprise network or the internet if and to the extent such a connection is necessary and only when appropriate security measures (e.g. firewalls and/or network segmentation) are in place. For additional information on industrial security measures that may be implemented, please visit <https://www.siemens.com/industrialsecurity>.

Siemens' products and solutions undergo continuous development to make them more secure. Siemens strongly recommends that product updates are applied as soon as they are available and that the latest product versions are used. Use of product versions that are no longer supported, and failure to apply the latest updates may increase customer's exposure to cyber threats.

To stay informed about product updates, subscribe to the Siemens Industrial Security RSS Feed at: <http://www.siemens.com/industrialsecurity>.

# Table of contents

<b>Legal information .....</b>	<b>2</b>
<b>1 Task.....</b>	<b>4</b>
<b>2 Solution.....</b>	<b>5</b>
2.1 Solution overview .....	5
2.2 Hardware and Software Components .....	5
2.2.1 Validity .....	5
2.2.2 Used Components.....	6
<b>3 Basics .....</b>	<b>7</b>
3.1 Basics regarding SINAMICS V90 PN version .....	7
3.2 Basic parameter configuration regarding SINAMICS V90 PN .....	7
3.2.1 Configure PROFINET settings via SINAMICS V-ASSISTANT .....	7
3.2.2 Configure ramp-function generator via SINAMICS V-ASSISTANT .....	9
3.2.3 Configure PROFINET settings via the TIA Portal .....	10
<b>4 Installation and Startup.....</b>	<b>17</b>
4.1 Installation of the hardware .....	17
4.2 Startup (JOG from drive side) .....	18
4.3 Startup (Profinet communication).....	18
<b>5 Operation of the application.....</b>	<b>19</b>
5.1 Scenario A .....	19
5.2 Scenario B.....	21
<b>6 Appendix .....</b>	<b>25</b>
6.1 Service and support .....	25
6.2 Contact .....	26
6.3 Links and literature .....	26
6.4 Change documentation .....	26

# 1 Task

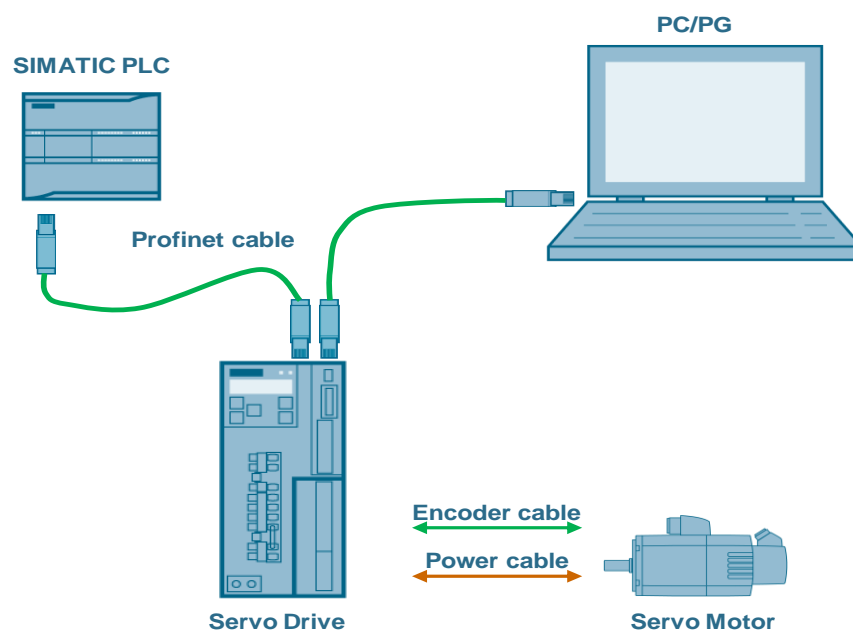
## Introduction

Speed control is one of the three basic functions for SINAMICS V90 and Profinet communication is a new and advanced feature. In this manual, the basic application of speed control with Profinet communication for SINAMICS V90 will be described in detail.

## Overview of the automation task

The figure below provides an overview of the automation task.

Figure 1-1





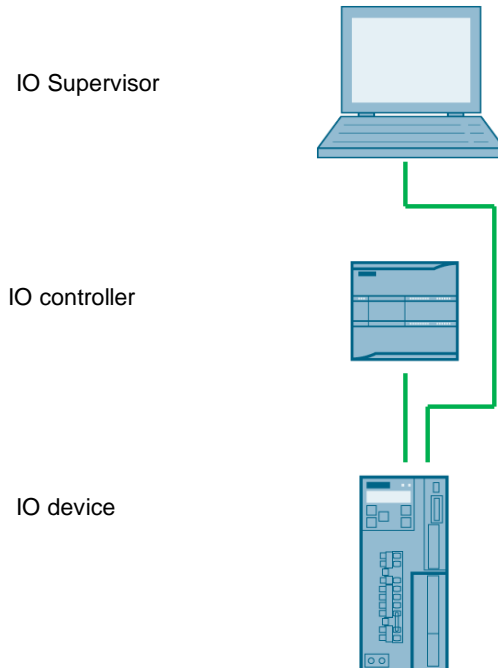
## 2 Solution

### 2.1 Solution overview

#### Schema Display

The following figure displays the most important components of the solution:

Figure 2-1



#### Delimitation

This application does not include a description of

- Profinet communication
- SINAMICS V90 PN version
- BOP operation of SINAMICS V90

Basic knowledge of these topics is assumed.

#### Required knowledge

Basic knowledge on TIA Portal is assumed.

## 2.2 Hardware and Software Components

### 2.2.1 Validity

This application example is valid for

- TIA Portal V16
- S7-1200 CPU with PN interface
- SINAMICS V90 PN FW V10401
- SIMOTICS S-1FL6 Li motor

## 2.2.2 Used Components

The application was generated with the following components:

### Hardware components

Table 2-1

Component	No.	Article number	Note
SIMATIC S7-1200 1214C DC/DC/DC	1	6ES7214-1AG40-0XB0	V4.4
SINAMICS V90 PN 200V	1	6SL3210-5FB10-2UF0	200W
SIMOTICS S-1FL6 Li motor	1	1FL6032-2AF21-1AA1	200W

### Standard software components

Table 2-2

Component	No.	Article number	Note
TIA Portal	1		V16
SINAMICS V- ASSISTANT	1		V1.06.02

### Sample files and projects

The following list includes all files and projects that are used in this example.

Table 2-3

Component	Note
109739222_S7-1200_V90PN_Speed_Dezenral_ DOC_v13.en.pdf	Documentation
109739222_SpeedControl_V90_S7-1200_MOVE_ PROJ_V16.zip	Project file for Scenario A
109739222_SpeedControl_V90_S7-1200_SINA_SPEED_ PROJ_V16.zip	Project file for Scenario B

## 3 Basics

### 3.1 Basics regarding SINAMICS V90 PN version

SINAMICS V90 PN supports the following telegrams:

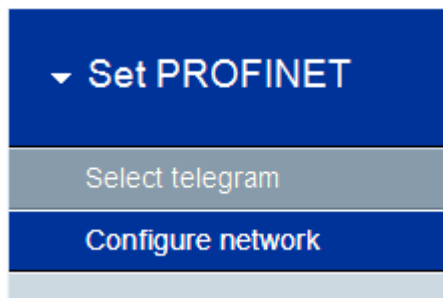
- Standard telegram 1
- Standard telegram 2
- Standard telegram 3
- Standard telegram 5
- Siemens telegram 102
- Siemens telegram 105

Siemens telegram 105 is the default telegram for SINAMICS V90 PN. Since Siemens telegram 105 is for IRT application, which S7-1200 1214C does not support, **the standard telegram 1 has to be used in this basic application.**

### 3.2 Basic parameter configuration regarding SINAMICS V90 PN

#### 3.2.1 Configure PROFINET settings via SINAMICS V-ASSISTANT

The following parameters can be configured with the SINAMICS V-ASSISTANT from the PROFINET settings menu field:



In this menu filed, you can configure:

- **Communication telegram:** in this tab you can also check the PZD structure and values:

Speed control mode

Selection of telegrams

The current telegram: 1: Standard telegram 1, PZD-2/2

The supplementary telegram: ---

The process data (PZD) links are set up automatically in accordance with the PROFIdrive telegram number setting. The telegram structure and PZD values of selected telegram are shown as below tables.

PZD structure and values

Receptive direction (PZD count=2):

STW1 (PZD1)

Telegram

Description

Value

STW1

Control word 1

0000H

bit0

rising edge = ON (pulses can be enabled); 0 = OFF

0

bit1

1 = No OFF2 (enable is possible); 0 = OFF2 (rm...

0

bit2

1 = No OFF3 (enable possible); 0 = OFF3 (braking...

0

bit3

1 = Enable operation (pulses can be enabled); 0 = ...

0

bit4

1 = Operating condition (the ramp-function genera...

0

bit5

1 = Continue ramp-function generator; 0 = Freeze ...

0

bit6

1 = Enable setpoint; 0 = Inhibit setpoint (set the ra...

0

bit7

rising edge= 1: Acknowledge faults

0

bit8

Reserved

0

bit9

Reserved

0

bit10

1 = Control via PLC

0

bit11

1 = Setpoint inversion

0

bit12

Reserved

0

bit13

Reserved

0

bit14

Reserved

0

bit15

Reserved

0

Transmit direction (PZD count=2):

ZSW1 (PZD1)

Telegram

Description

Value

ZSW1

Status word 1

0000H

bit0

1 = Ready for servo on

0

bit1

1 = Ready for operation

0

bit2

1 = Operation enabled

0

bit3

1 = Fault present

0

bit4

1 = No coast down active (OFF2 inactive)

0

bit5

1 = No fast stop active (OFF3 inactive)

0

bit6

1 = Switching on inhibited active

0

bit7

1 = Alarm present

0

bit8

1 = Speed setpoint - actual value deviation within t...

0

bit9

1 = Control requested

0

bit10

1 = f or n comparison value reached/exceeded

0

bit11

1 = I, M, or P limit reached

0

bit12

1 = Open the holding brake

0

bit13

1 = No motor overtemperature alarm

0

bit14

1 = Motor rotates forwards (n\_act >= 0); 0 = Motor ...

0

bit15

1 = No alarm, thermal overload, power unit

0

- **Network:**

Name of PN station <input type="text"/> 0 / 239 Note: Only numbers(0-9), letters in lower case(a-z) and characters (- and _) in English are acceptable.	Active name of PN station <input type="text"/>
<b>IP protocol</b> IP address of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> Subnet mask of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> Default gateway of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/>	<b>Active IP protocol</b> IP address of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> Subnet mask of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> Default gateway of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> MAC address of PN station: <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/> <input type="text"/>
Save and activate the PN station name and IP protocol <input type="button" value="Save and active"/>	
Note: 1 The network configuration is activated after clicked the button "Save and active" and restarted the drive. 2 The network can be configured either via TIA portal or V-ASSISTANT. 3 If IP protocol is configured in TIA portal by "Set IP address in the project", the actual active protocol is always took over by TIA setting.	

**NOTE** the configurations must be saved and active. Then should restart the drive.

Table 3-1: PROFINET relevant parameters

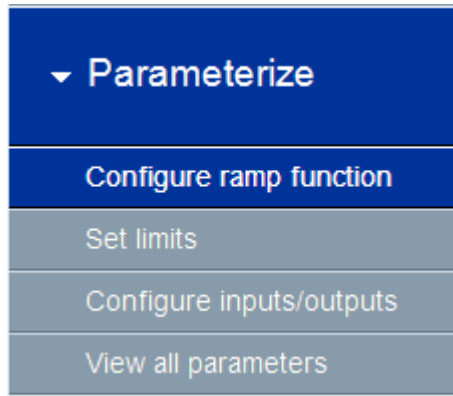
Par. No.	Description	Set value
P922	Telegram selection	1
P8921	PN IP address. There are four indexes. Each index maps to a segment of the IP address. <b>Note:</b> after successful configuration, the values will be changed to 0 automatically.	Example IP address: <b>192.168.0.2</b> P8921[0]=192 P8921[1]=168 P8921[2]=0 P8921[3]=2
P8923	PN Subnet Mask of Station. There are four indexes. Each index maps to a segment of the subnet mask. <b>Note:</b> after successful configuration, the values will be changed to 0 automatically.	Example Subnet mask: <b>255.255.255.0</b> P8923[0]=255 P8923[1]=255 P8923[2]=255 P8923[3]=0
P8925	PN interface configuration <b>Note:</b> after successful configuration, the values will be changed to 0 automatically.	2 Note: after setting p8921 and p8923, p8925 should be set to be 2 for activating the PN communication.
r8931	PN IP address of station active	
r8932	PN default gateway of station active	
r8933	PN MAC address of station	



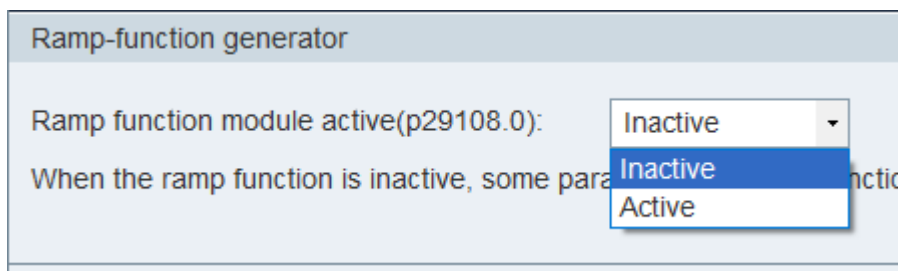
### 3.2.2 Configure ramp-function generator via SINAMICS V-ASSISTANT

The configuration of ramp-function generator should be configured via the SINAMICS V-ASSISTANT.

The ramp-function generator can be configured with the Parameterize menu field of SINAMICS V-ASSISTANT.



At the tab “**Set parameter setpoint**”, you can choose to activate the ramp-function generator or deactivate it:



**Note** There is a need to restart the drive after you’ve activated or deactivated the ramp-function generator.

In our example, the ramp-function generator should be activated. You can choose to use the basic ramp-function generator or extended ramp-function generator:

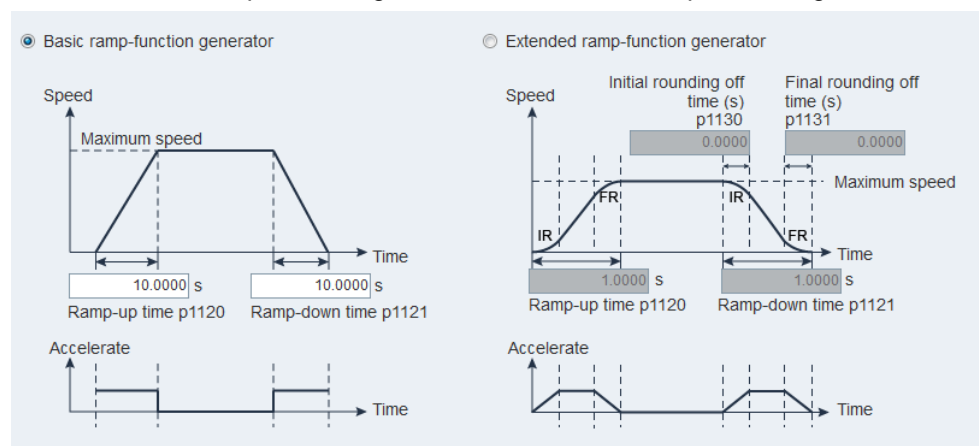


Table 3-2: Ramp-function generator relevant parameters

Par. No.	Description	Set value
P1115	Ramp-function generator selection	0
P1120	Ramp-up time	10 s
P1121	Ramp-down time	10 s
P1130	Initial rounding-off time	0 s
P1131	Final rounding-off time	0 s

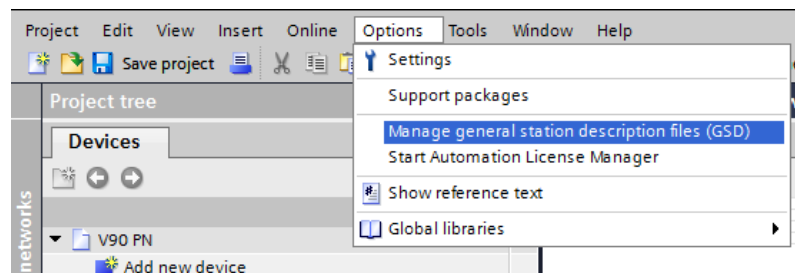
### 3.2.3 Configure PROFINET settings via the TIA Portal

#### 3.2.3.1 Configure SINAMICS V90 PN

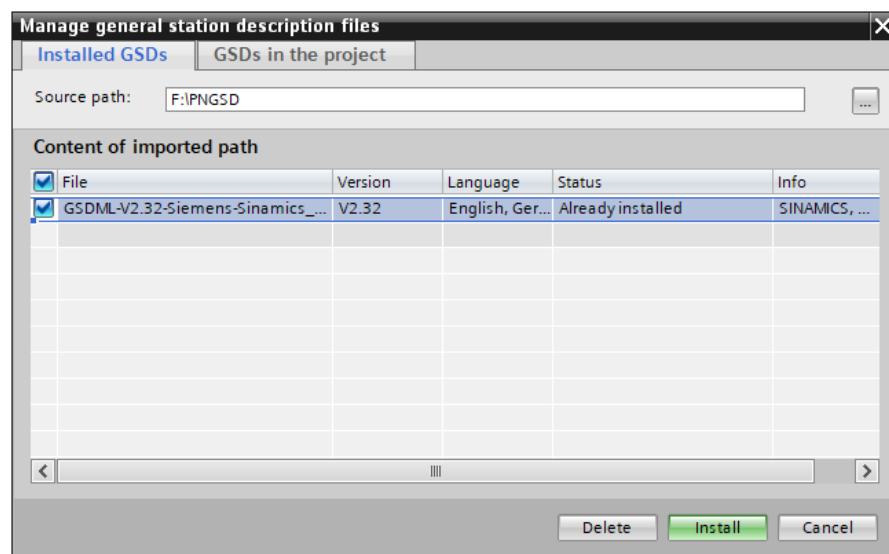
The PROFINET settings of SINAMICS V90 PN can be configured in the TIA Portal as follows:

1. Create a new project and switch to project view.
2. Input the V90 PN GSD file.

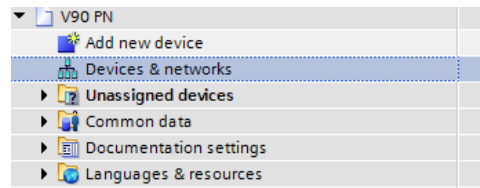
**Note** Installation of V90 PN GSD file is only necessary for TIA Portal prior to V13 (including V13).



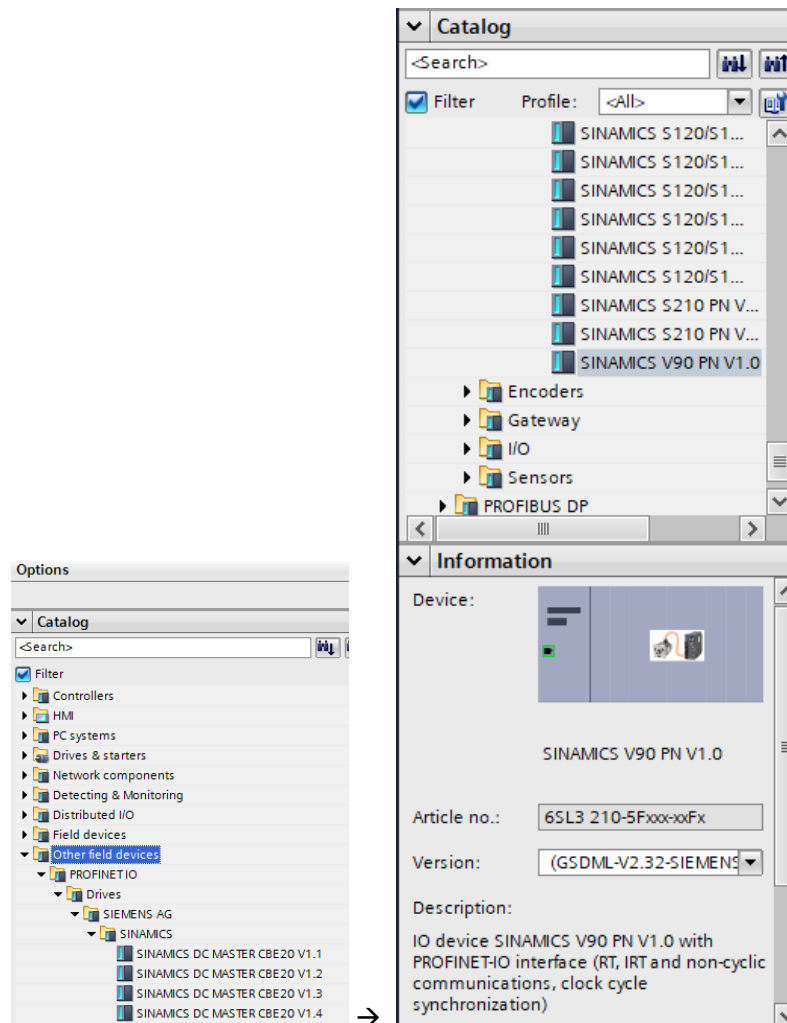
3. Find the GSD file and select it. Press the “Install” button to install it.



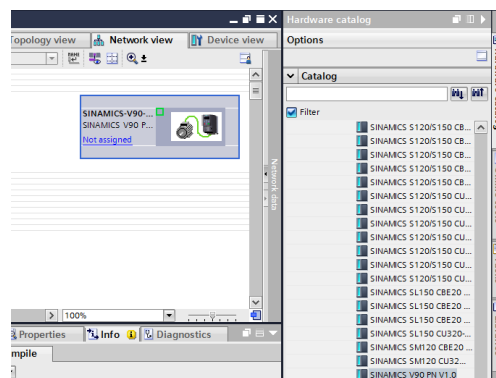
- Click the node **"Devices & networks"** from the device tree on the left side.



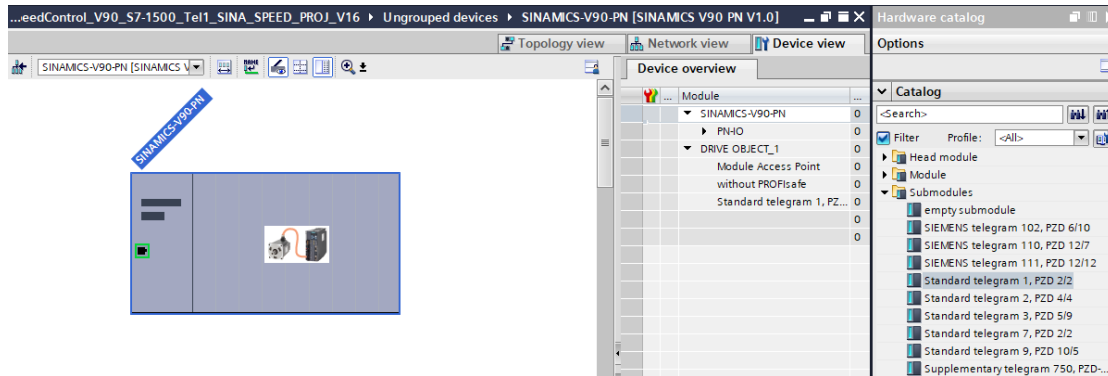
- Select V90 PN from the **"other filed drives"** of catalog tree on the right side.



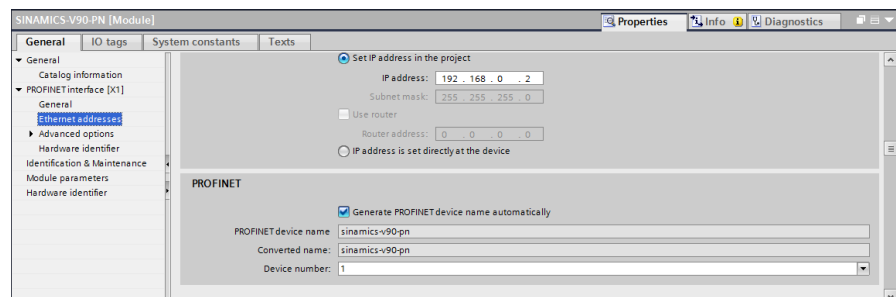
- Double-click the V90 PN node or drag it to the network view:



7. Configure the **Communication Telegram** in the device view; for example, standard telegram 1:

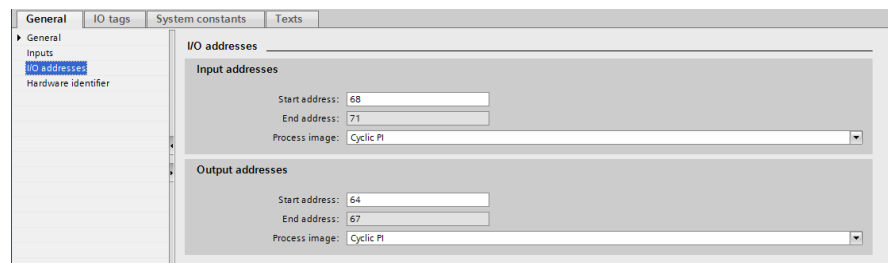


8. Now from the Properties tab, you can the Ethernet address and device name.



The device name should be the same as the accessible device shown at the Online access tree.

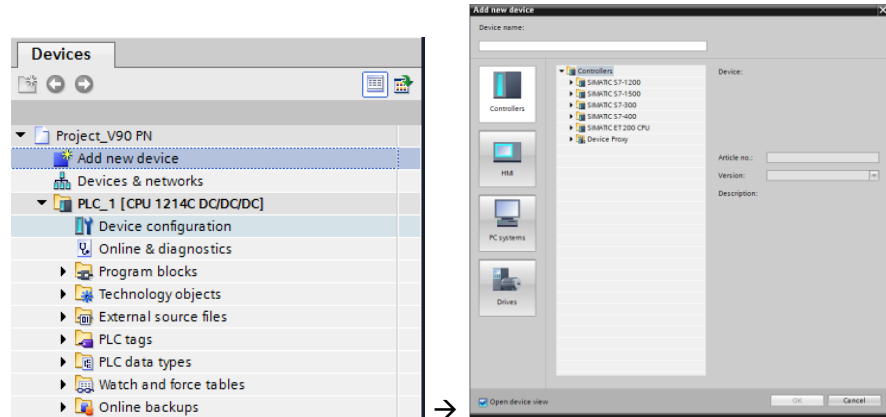
9. You can also configure the I/O address of the communication telegram from the Properties Tab:



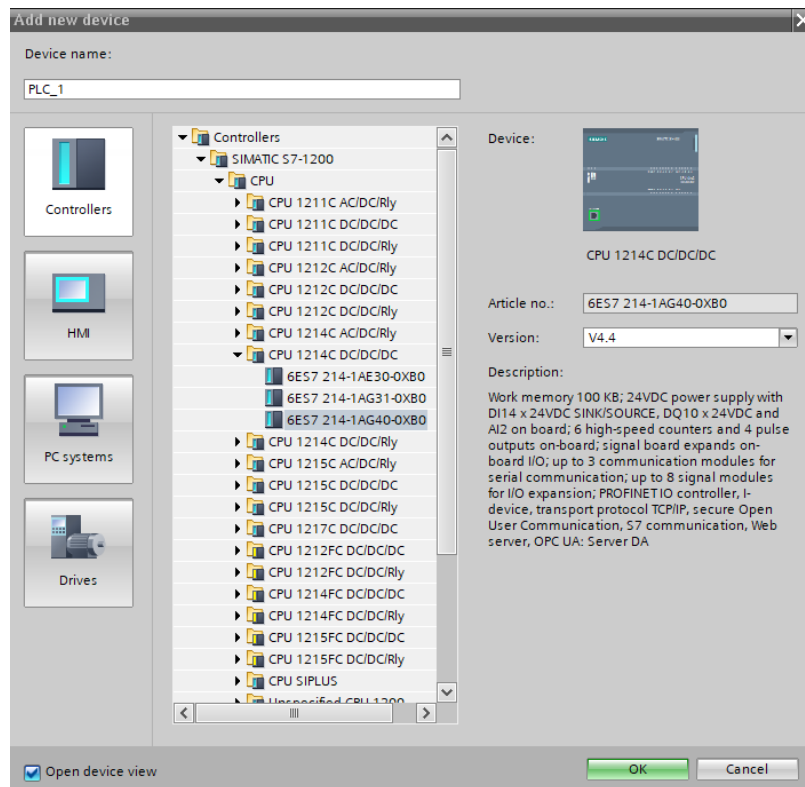
### 3.2.3.2 Configure S7-1200 CPU

The PROFINET settings of SIMATIC S7-1200 CPU can be configured in the TIA Portal as follows:

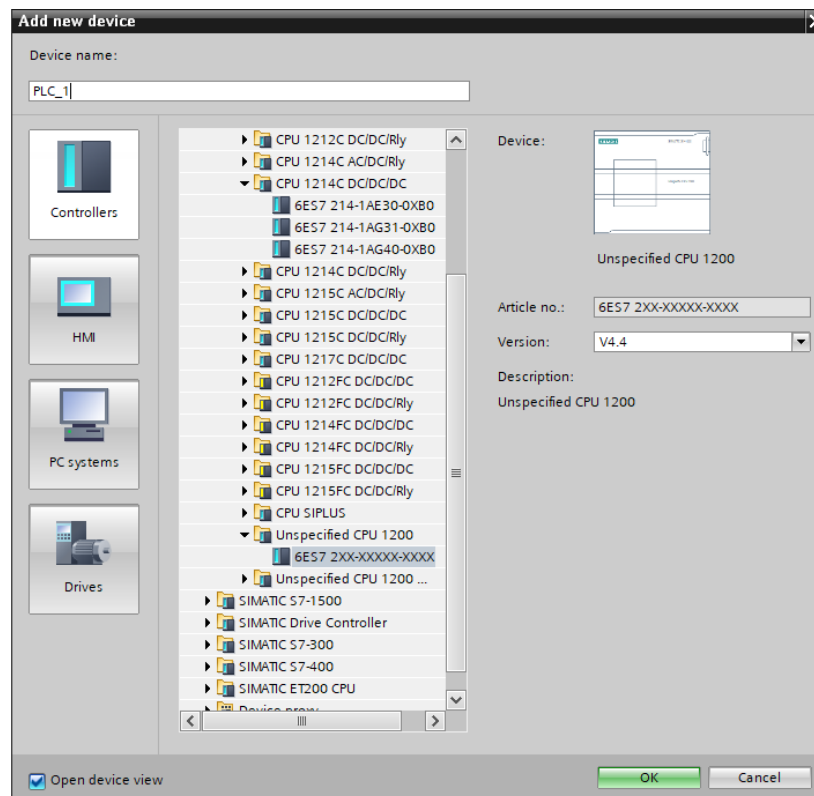
1. Double-click the node **"Add new device"** from the Device tree:



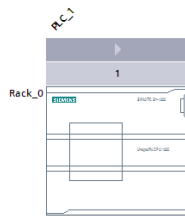
2. Here, if you know the detailed information about the S7-1200 modules, you can directly find the type and add it into the project



Otherwise, you can add an unspecified CPU 1200 into the project:



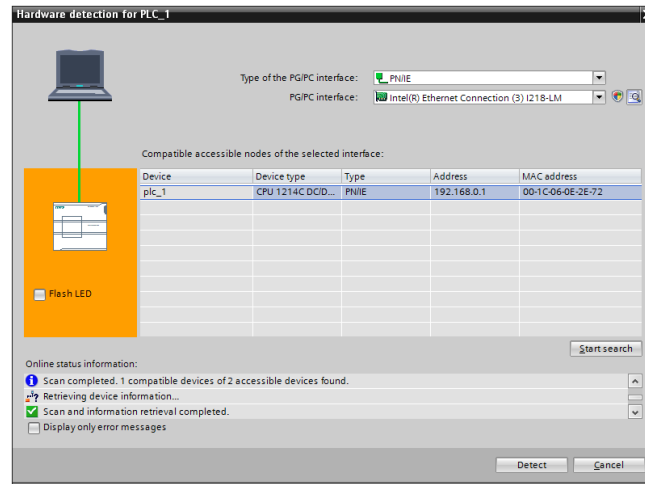
3. If an unspecified 1200 CPU has been added into the project, you can detect the connected CPU by clicking the **"Detect"** and search it with online access:



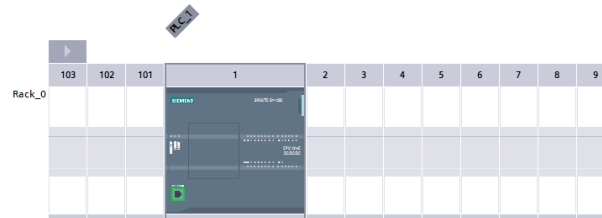
The device is not specified.  
 → Please use the [Hardware catalog](#) to specify the CPU.  
 → or **detect** the configuration of the connected device.



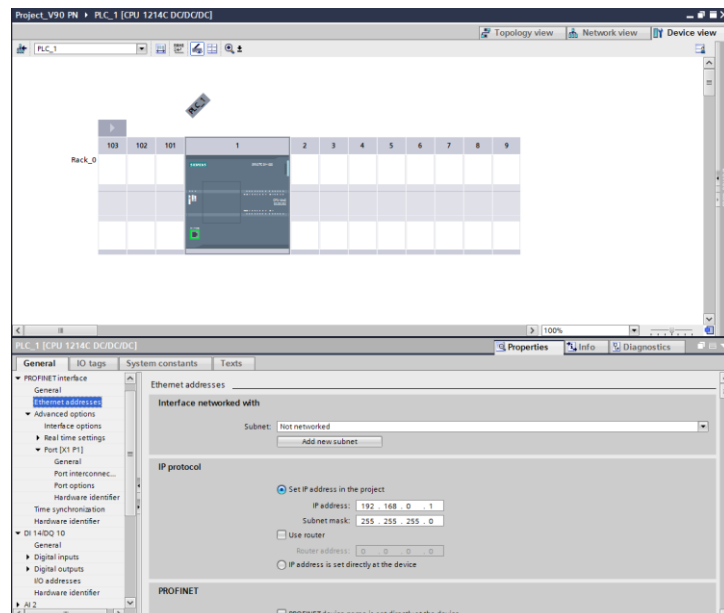
Start the search by clicking the “**Start search**” button, and the connected S7-1200 CPU will be found if the PROFINET network communication works properly:



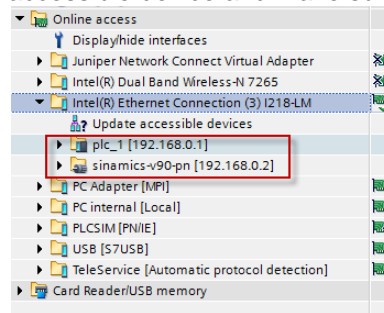
4. Press “**Detect**” button to detect the connected CPU:



5. Double-click the PLC CPU to enter properties of the CPU in the device view:



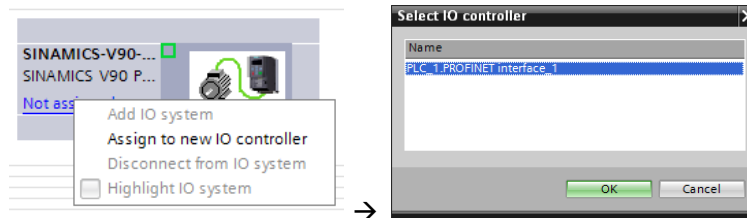
Here, you can configure information about the device name, Ethernet address... You can also use the “**Online access**” node to find the accessible device and make sure the information are consistent:



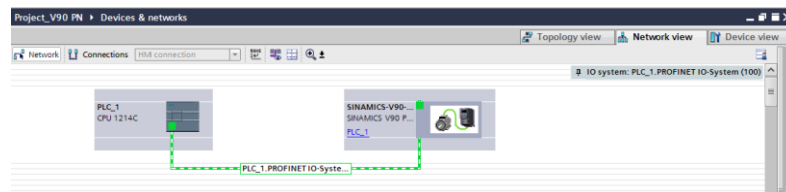
### 3.2.3.3 Connect SINAMICS V90 PN with S7-1200 CPU

After the configurations of both SINAMICS V90 PN and S7-1200 CPU, you need to connect SINAMICS V90 PN to S7-1200 CPU:

1. Right-click the “Not assign”:



2. And the connected network view is shown as follows:

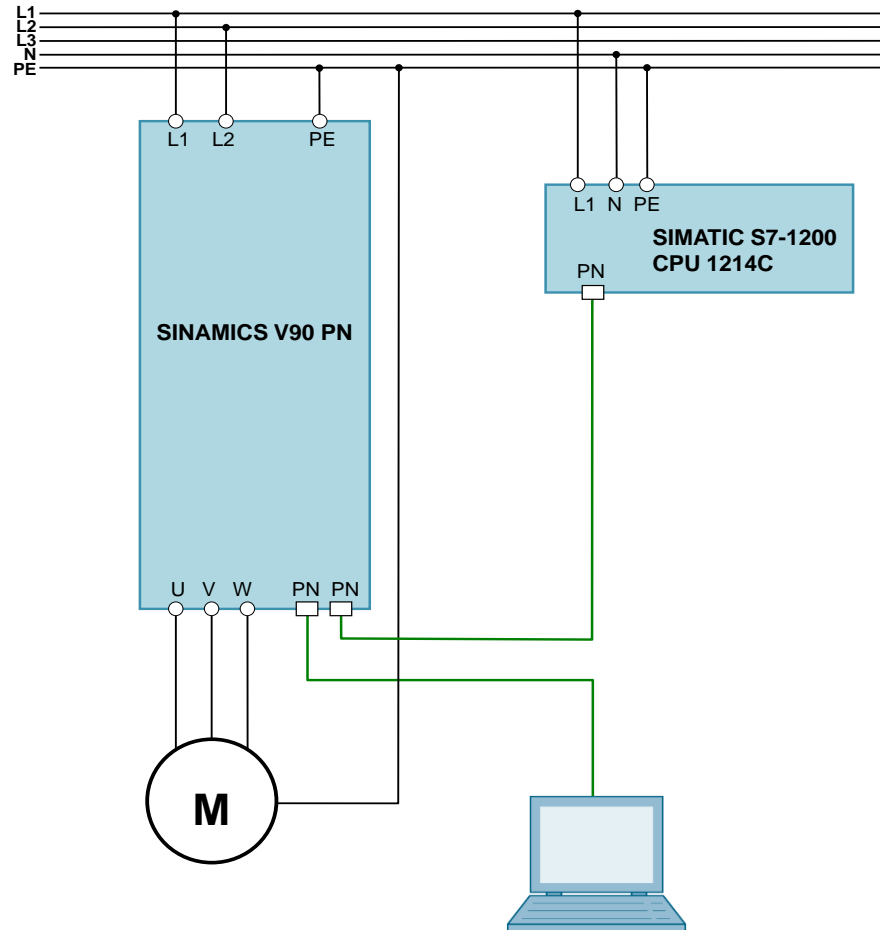


## 4 Installation and Startup

### 4.1 Installation of the hardware

The figure below shows the hardware configuration of the application:

Figure 4-1



## 4.2 Startup (JOG from drive side)

Table 4-1

Nr.	Action	Remarks
1.	Set drive parameter p29108 to be 1.	JOG function is enabled when p29108=1
2.	Save the parameters and then restart the drive again.	
3.	Switch to JOG menu with drive BOP operation.	
4.	Press ▲ or ▼ button to run the motor.	
5.	After finish the JOG funtion, set P29108 to 0.	
6.	Save the parameters and then restart the drive again.	

## 4.3 Startup (Profinet communication)

Table 4-2

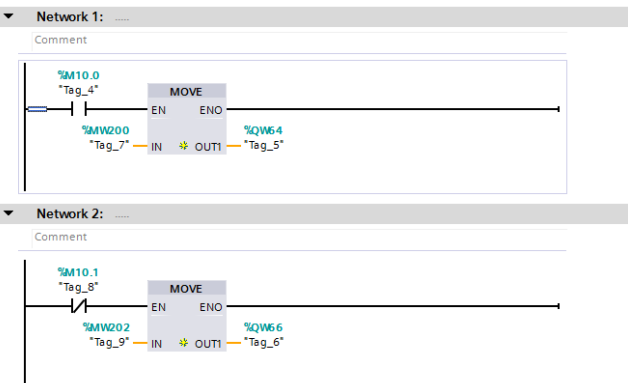
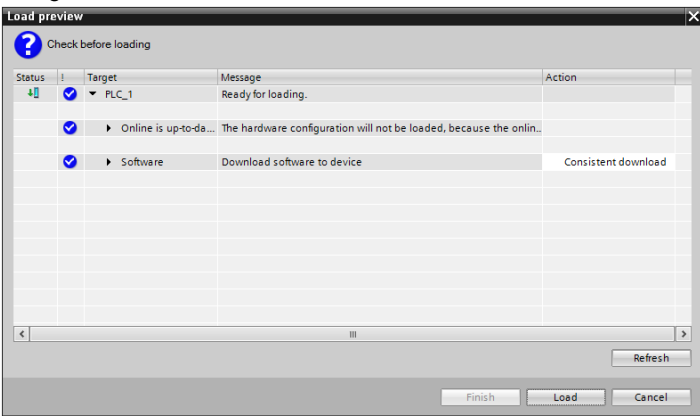
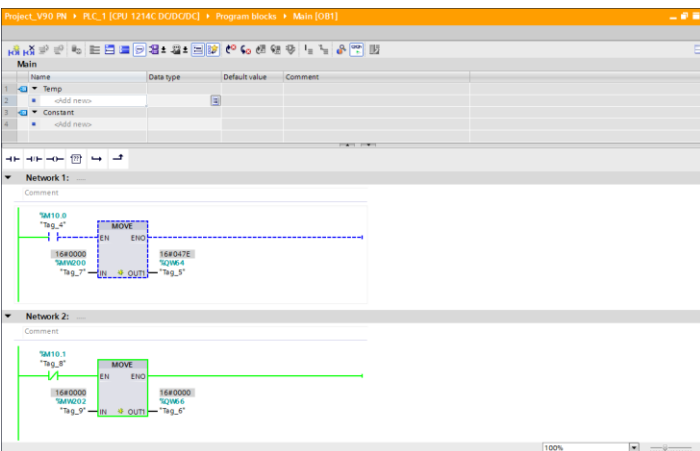
Nr.	Action	Remarks
1.	Set drive parameter p922 to be 1.	Select standard telegram 1
2.	Make device & network configurations in the TIA Portal: <ul style="list-style-type: none"> <li>• <i>Device name</i></li> <li>• <i>IP address</i></li> <li>• <i>Telegram</i></li> </ul>	As shown in section 3.2.3
3.	Go online to test the Profinet communication.	
4.	Download configurations into controller and device if the communication works.	

## 5 Operation of the application

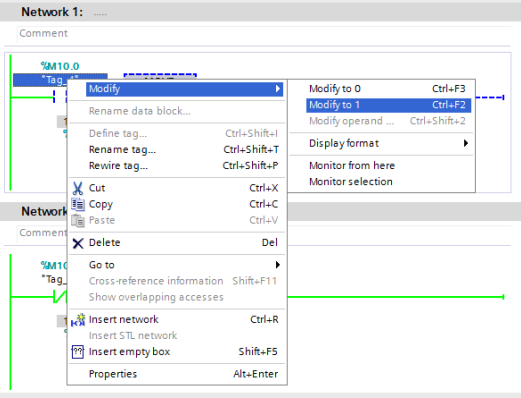
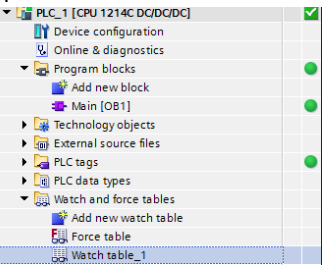
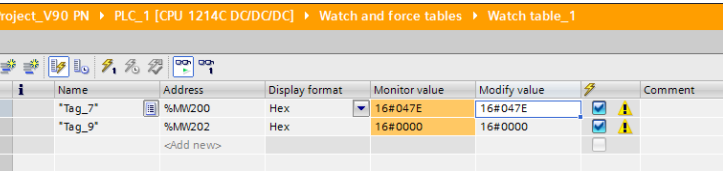
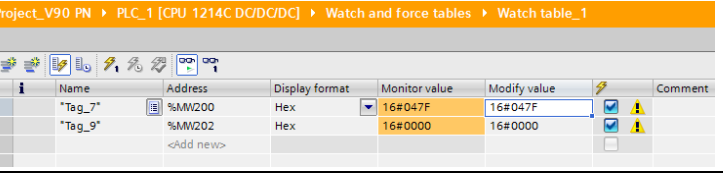
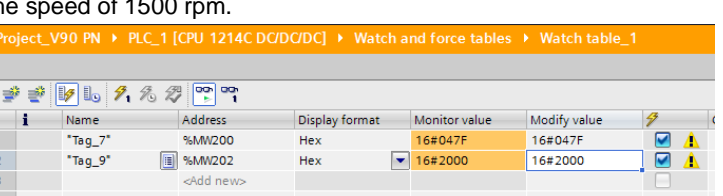
### 5.1 Scenario A

In scenario A, we use Move instruction for programming and run the motor with watch table:

Table 5-1

Nr.	Action	Remarks
1.	<p>Program as follows:</p> 	
2.	<p>Compile the PLC program and download the program and its configurations into S7-1200 CPU.</p> 	
3.	<p>Switch to online mode and enable monitor function:</p> 	
4.	Modify M10.0 to 1:	

## 5 Operation of the application

Nr.	Action	Remarks
		
5.	<p>Open the watch table 1:</p> 	
6.	<p>Write value <b>16#47E</b> into QW64:</p> <p>Project_V90 PN &gt; PLC_1 [CPU 1214C DC/DC/DC] &gt; Watch and force tables &gt; Watch table_1</p> 	<p><b>Q address:</b> 64 ... 67</p>
7.	<p>Write value <b>16#47F</b> into QW64, and then the drive turns to servo on.</p> <p>Project_V90 PN &gt; PLC_1 [CPU 1214C DC/DC/DC] &gt; Watch and force tables &gt; Watch table_1</p> 	
8.	<p>Write value <b>16#2000</b> into QW66, and then the motor starts running at the speed of 1500 rpm.</p> <p>Project_V90 PN &gt; PLC_1 [CPU 1214C DC/DC/DC] &gt; Watch and force tables &gt; Watch table_1</p> 	<p><b>QW66:</b> speed setpoint.</p> <p><b>Scaling factor:</b> 4000 hex = value of drive parameter p2000</p>



## 5.2 Scenario B

The function block “SinaSpeed” is integrated in TIA Portal, especially for speed control with standard telegram 1.

### Note

The library is integrated in the Startdrive. You can download the latest library from SIEMENS product and information pages (<http://support.automation.siemens.com/WW/view/en/109771710>).

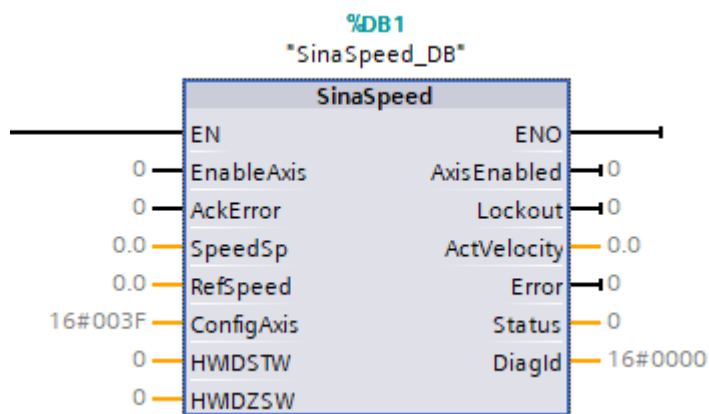


Table 5-2-1 Input interface of “SinaSpeed”

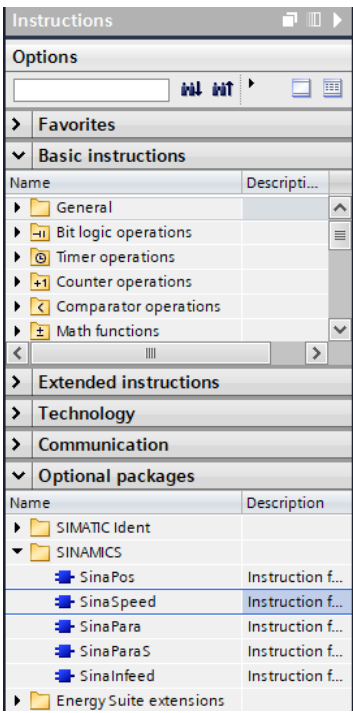
Input signal	Type	Default	Meaning
EnableAxis	BOOL	0	“Off1” = 1 → switch on the drive
AckError	BOOL	0	Acknowledgement of axis faults → “AckFit” = 1
SpeedSp	REAL	0.0 [rpm]	Speed setpoint
RefSpeed	REAL	0.0 [rpm]	Rated speed of the drive → p2000
ConfigAxis	Word	16#003F	Configure of the drive control
HWIDSTW	HW_ID/INT	0	Symbolic name or HW ID/IO address on the SIMATIC S7-1200 of the setpoint slot ( <b>SetPoint</b> )
HWIDZSW	HW_ID/INT	0	Symbolic name or HW ID/IO address on the SIMATIC S7-1200 of the actual value slot ( <b>Actual Value</b> )

Table 5-2-2 Output interface of “SinaSpeed”

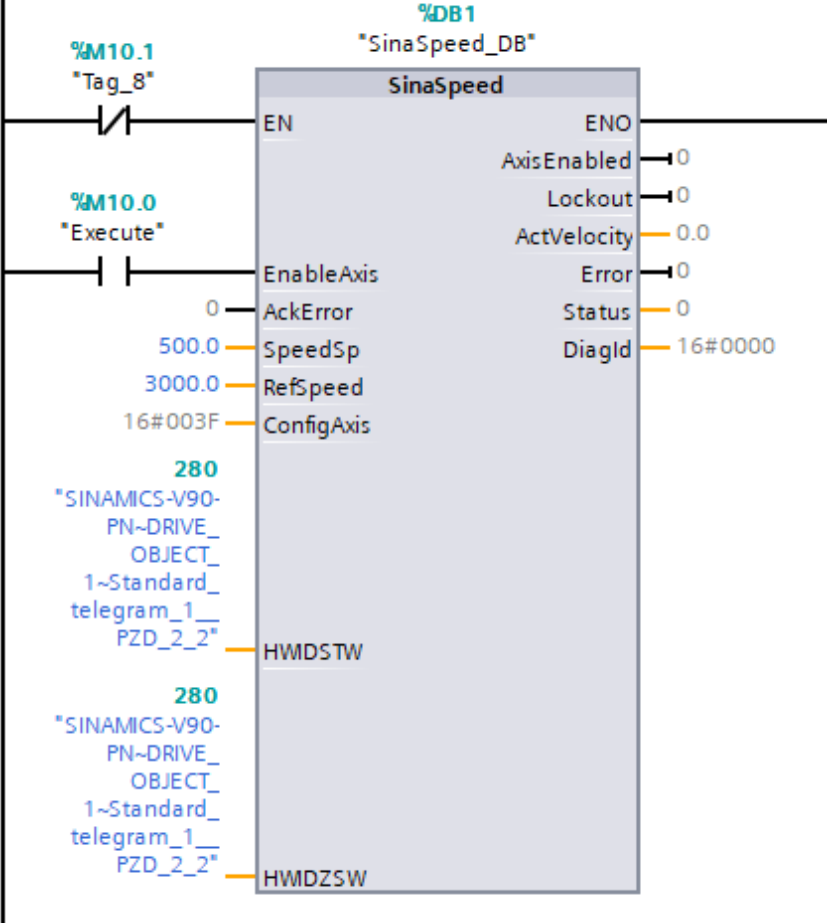
Input signal	Type	Default	Meaning
AxisEnabled	BOOL	0	Operating mode is executed or enabled
Lockout	BOOL	0	1= switch-on inhibit active
ActVelocity	real	0.0[rpm]	Actual speed
Error	BOOL	0	1=group fault present
Status	INT	0	Status of the function block
DiagID	WORD	0	Expanded communication error

In scenario B, we will use “SinaSpeed” in the library for programming and run the motor.

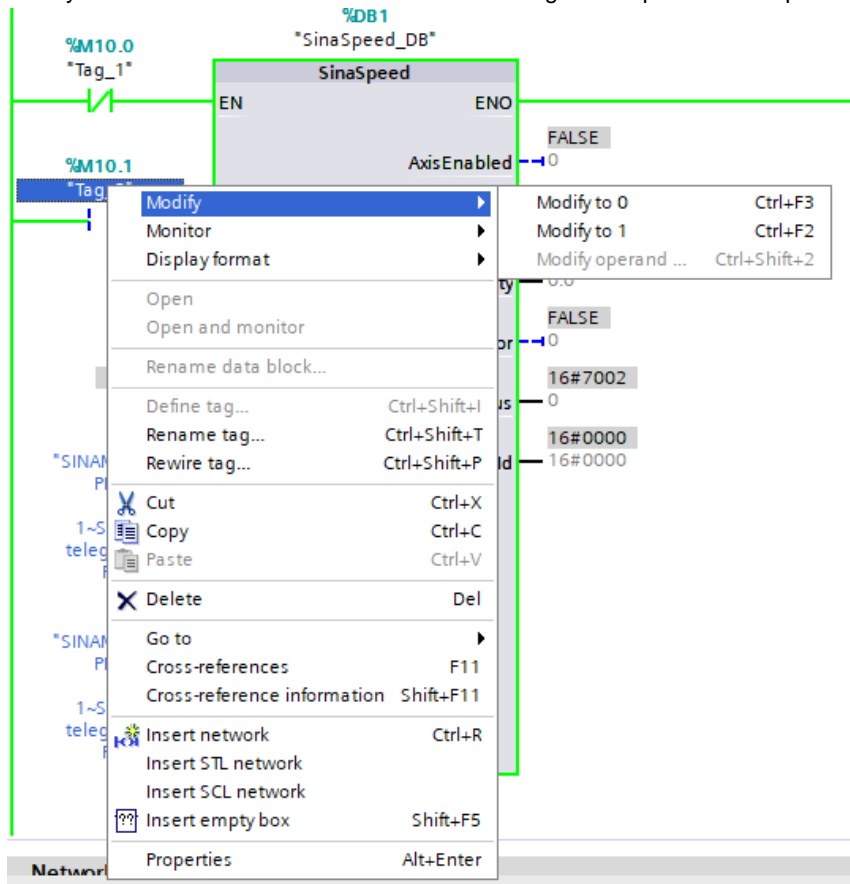
Table 5-2-3 Operation with “SinaSpeed”

Nr.	Action	Remarks
1.	<p>When you have installed the startdrive, you can find it at the optional package as follows:</p> 	

## 5 Operation of the application

Nr.	Action	Remarks
2.	<p>Insert or drag "SinaSpeed" into the PLC main block and make program as follows:</p> 	
3.	Switch to online mode and activate the monitoring function.	

5 Operation of the application

Nr.	Action	Remarks
4.	<p>Modify M10.0 to 1 and then the motor starts running at the speed of 500 rpm.</p> 	

## 6 Appendix

### 6.1 Service and support

#### Industry Online Support

Do you have any questions or need assistance?

Siemens Industry Online Support offers round the clock access to our entire service and support know-how and portfolio.

The Industry Online Support is the central address for information about our products, solutions and services.

Product information, manuals, downloads, FAQs, application examples and videos – all information is accessible with just a few mouse clicks:

[support.industry.siemens.com](https://support.industry.siemens.com)

#### Technical Support

The Technical Support of Siemens Industry provides you fast and competent support regarding all technical queries with numerous tailor-made offers – ranging from basic support to individual support contracts. Please send queries to Technical Support via Web form:

[www.siemens.com/industry/supportrequest](https://www.siemens.com/industry/supportrequest)

#### SITRAIN – Digital Industry Academy

We support you with our globally available training courses for industry with practical experience, innovative learning methods and a concept that's tailored to the customer's specific needs.

For more information on our offered trainings and courses, as well as their locations and dates, refer to our web page:

[www.siemens.com/sitrain](https://www.siemens.com/sitrain)

#### Service offer

Our range of services includes the following:

- Plant data services
- Spare parts services
- Repair services
- On-site and maintenance services
- Retrofitting and modernization services
- Service programs and contracts

You can find detailed information on our range of services in the service catalog web page:

[support.industry.siemens.com/cs/sc](https://support.industry.siemens.com/cs/sc)

#### Industry Online Support app

You will receive optimum support wherever you are with the "Siemens Industry Online Support" app. The app is available for iOS and Android:

[support.industry.siemens.com/cs/ww/en/sc/2067](https://support.industry.siemens.com/cs/ww/en/sc/2067)

## 6.2 Contact

Siemens Ltd., China  
 DF M3-BF GMC  
 No. 18 Siemens Road  
 Jiangning Development Zone  
 Nanjing, 211100  
 China  
 mailto: [mc\\_gmc\\_mp\\_asia.cn@siemens.com](mailto:mc_gmc_mp_asia.cn@siemens.com)

## 6.3 Links and literature

Table 6-1

No.	Topic
\1\	Siemens Industry Online Support <a href="https://support.industry.siemens.com">https://support.industry.siemens.com</a>
\2\	Link to this entry page of this application example <a href="https://support.industry.siemens.com/cs/ww/en/view/109739222">https://support.industry.siemens.com/cs/ww/en/view/109739222</a>
\3\	

## 6.4 Change documentation

Table 6-2

Version	Date	Modifications
V0.1	02/2016	First version
V1.0	03/2016	Final version
V1.1	03/2018	Upgrade project to TIA V15
V1.2	05/2019	Upgrade project to TIA V15 SP1
V1.3	04/2020	Upgrade project to TIA V16