

# SIEMENS

## RUGGEDCOM RS416

### Installation Guide

#### Preface

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#### Introduction

---

1

#### Installing Device

---

2

#### Communication Ports

---

3

#### Technical Specifications

---

4

#### Dimension Drawings

---

5

#### Certification

---

6

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# Table of Contents

Preface .....	v
Alerts .....	v
Related Documents .....	v
Accessing Documentation .....	v
Training .....	vi
Customer Support .....	vi
 Chapter 1	
<b>Introduction .....</b>	<b>1</b>
1.1 Feature Highlights .....	1
1.2 Ports, Controls and Indicator LEDs .....	3
 Chapter 2	
<b>Installing Device .....</b>	<b>5</b>
2.1 Mounting the Device .....	5
2.1.1 Mounting the Device to a Rack .....	6
2.1.2 Mounting the Device on a DIN Rail .....	7
2.1.3 Mounting the Device to a Panel .....	7
2.2 Connecting Power .....	8
2.2.1 Connecting AC Power .....	9
2.2.2 Connecting DC Power .....	10
2.2.3 Wiring Examples .....	11
2.3 Connecting the Failsafe Alarm Relay .....	14
2.4 Grounding the Device .....	15
2.5 Connecting to the Device .....	15
2.6 Cabling Recommendations .....	16
 Chapter 3	
<b>Communication Ports .....</b>	<b>17</b>
3.1 Copper Ethernet Ports .....	17
3.2 Fiber Optic Ethernet Ports .....	18
3.3 Serial Ports .....	19
3.4 Connecting Multiple RS485 Devices .....	22
3.5 Time Synchronization .....	23
3.5.1 IRIG-B Ports .....	23

---

3.5.2 IRIG-B Connection Considerations .....	24
Chapter 4	
<b>Technical Specifications .....</b>	<b>25</b>
4.1 Power Supply Specifications .....	25
4.2 Failsafe Relay Specifications .....	25
4.3 Copper Ethernet Port Specifications .....	26
4.4 Fiber Optic Ethernet Port Specifications .....	26
4.4.1 10Base-FL Ethernet Optical Specifications .....	26
4.4.2 Fast Ethernet (100 Mbps) Optical Specifications .....	26
4.5 Serial Port Specifications .....	27
4.5.1 Copper Serial Port Specifications .....	27
4.5.2 Fiber Serial Port Specifications .....	28
4.6 IRIG-B Ports .....	28
4.7 Operating Environment .....	28
4.8 Mechanical Specifications .....	28
Chapter 5	
<b>Dimension Drawings .....</b>	<b>29</b>
Chapter 6	
<b>Certification .....</b>	<b>33</b>
6.1 Agency Approvals .....	33
6.2 FCC Compliance .....	33
6.3 Industry Canada Compliance .....	33
6.4 EMI and Environmental Type Tests .....	34

# Preface

This guide describes the RUGGEDCOM RS416. It describes the major features of the device, installation, commissioning and important technical specifications.

It is intended for use by network technical support personnel who are responsible for the installation, commissioning and maintenance of the device. It is also recommended for use by network and system planners, system programmers, and line technicians.

## Alerts

The following types of alerts are used when necessary to highlight important information.



### **DANGER!**

*DANGER alerts describe imminently hazardous situations that, if not avoided, will result in death or serious injury.*



### **WARNING!**

*WARNING alerts describe hazardous situations that, if not avoided, may result in serious injury and/or equipment damage.*



### **CAUTION!**

*CAUTION alerts describe hazardous situations that, if not avoided, may result in equipment damage.*



### **IMPORTANT!**

*IMPORTANT alerts provide important information that should be known before performing a procedure or step, or using a feature.*



### **NOTE**

*NOTE alerts provide additional information, such as facts, tips and details.*

## Related Documents

Other documents that may be of interest include:

- *ROS User Guide for the RS416*

## Accessing Documentation

The latest Hardware Installation Guides and Software User Guides for most RUGGEDCOM products are available online at [www.siemens.com/ruggedcom](http://www.siemens.com/ruggedcom).

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- **Mobile App**

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- Submit SRs or check on the status of an existing SR
- Find and contact a local contact person
- Ask questions or share knowledge with fellow Siemens customers and the support community via the forum
- And much more...

# 1 Introduction

The RUGGEDCOM RS416 is an industrially hardened serial device server with an integrated, fully managed, Ethernet switch, designed to operate reliably in electrically harsh and climatically demanding environments. Featuring a modular design that can support IEEE 1588 and IRIG-B time synchronization, up to 16 serial ports and up to four Ethernet ports, the RS416 is able to interconnect and synchronize multiple types of intelligent electronic devices (IEDs).

The time source is provided via IEEE 1588 v2 and converted to IRIG-B for distribution to the IEDs via the serial ports or dedicated IRIG-B cabling. Each serial port supports standard data communications plus an IRIG-B time-synchronization output. Using the RS416 results in fewer connectivity devices reducing overall system costs and extends the useful life of existing legacy IEDs minimizing capital expenditure for new equipment.

The RS416 provides a high level of immunity to electromagnetic interference and heavy electrical surges typical of environments found in electric utility substations, factory floors or in curb side traffic control cabinets. The RS416 meets or exceeds a wide range of industry standards including IEC 61850-3, IEEE 1613, IEC 61000-6-2 and IEC 61800-3. The RS416 also features a wide operating temperature range of -40 to 85 °C (-40 to 185 °F) allowing it to be installed in virtually any location.

The embedded Rugged Operating System (ROS®) within the RS416 provides advanced layer 2 and layer 3 networking functions, advanced cyber security features, and a full array of intelligent functionality for high network availability and manageability. Coupled with the ruggedized hardware design, the RS416 is ideal for creating mission-critical, real-time, control applications in any harsh environment.

The following sections provide more information about the RS416:

- [Section 1.1, “Feature Highlights”](#)
- [Section 1.2, “Ports, Controls and Indicator LEDs”](#)

## Section 1.1

# Feature Highlights

### Serial Device Server

- Modular design allows for 4, 8, 12, or 16 serial ports
- Fully compliant EIA RS422/TIA RS485, RS422, RS232 serial ports (software selectable) with IRIG-B outputs
- Serial fiber interface (ST)
- Transmit serial data over an IP network
- Support for Modbus TCP, DNP 3, TIN serial protocols
- Baud rates up to 230 kbps
- Raw socket mode allows conversion of any serial protocol
- Point-to-point and multi-point modes
- Converts Modbus RTU to Modbus
- Supports multiple Modbus masters
- Converts DNP3.0 to DNP over UDP/TCP

### **Ethernet Ports**

- Integrated Ethernet switch
- Copper or fiber options
- Supports IEEE 1588 v2
- Non-blocking, store and forward switching

### **IRIG-B Option**

- Conversion from IEEE 1588 v2
- One IRIG-B PWM/PPS Output
- One IRIG-B PWM Input
- Supports TTL levels (Format B002, B003)
- BNC Connectors

### **IEEE 1588**

- Internal clock is synchronized with IEEE 1588 version 2
- 100 $\mu$ s time accuracy

### **Cyber Security Features**

- Multi-level user passwords
- SSH/SSL (128-bit encryption)
- Enable/disable ports, MAC based port security
- Port based network access control (802.1x)
- VLAN (802.1Q) to segregate and secure network traffic
- RADIUS centralized password management
- SNMPv3 authentication and 56-bit encryption

### **Rated for Reliability in Harsh Environments**

- Immunity to EMI and heavy electrical surges
- Meets IEEE 1613 (electric utility substations)
- Exceeds IEC 61850-3 (electric utility substations)
- Exceeds IEC 61800-3 (variable speed drive systems)
- Exceeds IEC 61000-6-2 (generic industrial)
- Exceeds NEMA TS-2 (traffic control equipment)
- Fully independent 2 kV (RMS) isolated serial ports
- -40 to 85 °C (-40 to 185 °F) operating temperature (no fans)
- 18 AWG galvanized steel enclosure

### **Universal Power Supply Options**

- Fully integrated, dual-redundant (optional) power supplies
- Universal high-voltage range: 88-300 VDC or 85-264 VAC
- Popular low voltage ranges: 24 VDC (10-36 VDC), 48 VDC (36-59VDC)
- Terminal blocks for reliable maintenance free connections

- CSA/UL 60950-1 safety approved to 85 °C (185 °F)

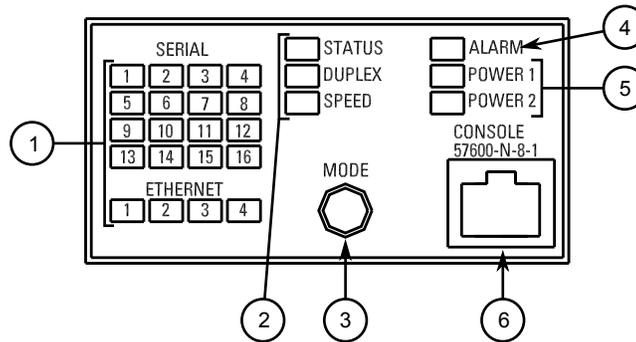
### Management Tools

- Web-based, Telnet, CLI management interfaces
- SNMP v1, v2 and v3
- Remote Monitoring (RMON)
- Rich set of diagnostics with logging and alarms

## Section 1.2

# Ports, Controls and Indicator LEDs

The RS416 features various ports, controls and indicator LEDs on the display panel for configuring and troubleshooting the device. The display panel can be located on the rear, front or top of the device, depending on the mounting configuration.



**Figure 1: Display Panel**

1. Port Status Indicator LEDs 2. Display Mode Indicator LEDs 3. Mode Button 4. Alarm Indicator LED 5. Power Module Indicator LEDs 6. RS232 Serial Console Port (RJ45)

### Port Status Indicator LEDs

These LEDs indicate the state of each port.

When Status mode is selected, these LEDs indicate when ports are active.

- Green (Solid) = Link detected
- Green (Blinking) = Link activity
- Off = No link detected

When Duplex mode is selected, these LEDs indicate when ports are operating in full or half duplex mode.

- Green (Solid) = Full duplex mode
- Orange (Solid) = Half duplex mode
- Off = No link detected

When Speed mode is selected, these LEDs indicate the port speed.

- Green (Solid) = 1000 Mb/s
- Green (Blinking) = 100 Mb/s
- Orange (Solid) = 10 Mb/s
- Off = No link detected

---

<b>Display Mode Indicator LEDs</b>	These LEDs indicate the current display mode for the port status indicator LEDs (i.e. Status, Duplex or Speed).
<b>Mode button</b>	The <b>Mode</b> button sets the display mode for the port status indicator LEDs (i.e. Status, Duplex or Speed). It can also be used to reset the device if held for 5 seconds.
<b>Alarm Indicator LED</b>	The alarm indicator LED illuminates when an alarm condition exists.
<b>Power Module Indicator LEDs</b>	These LEDs indicate the status of the power modules. <ul style="list-style-type: none"><li>• Green = The power supply is supplying power</li><li>• Red = Power supply failure</li><li>• Off = No power supply is installed</li></ul>
<b>RS232 Serial Console Port</b>	This port is for interfacing directly with the device and accessing initial management functions.

---

# 2 Installing Device

The following sections describe how to install the device, including mounting the device, installing/removing modules, connecting power, and connecting the device to the network.



## **DANGER!**

*Electrocution hazard – risk of serious personal injury and/or damage to equipment. Before performing any maintenance tasks, make sure all power to the device has been disconnected and wait approximately two minutes for any remaining energy to dissipate.*



## **WARNING!**

*Radiation hazard – risk of serious personal injury. This product contains a laser system and is classified as a CLASS 1 LASER PRODUCT. Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.*



## **IMPORTANT!**

*This product contains no user-serviceable parts. Attempted service by unauthorized personnel shall render all warranties null and void.*

*Changes or modifications not expressly approved by Siemens Canada Ltd. could invalidate specifications, test results, and agency approvals, and void the user's authority to operate the equipment.*



## **IMPORTANT!**

*This product should be installed in a restricted access location where access can only be gained by authorized personnel who have been informed of the restrictions and any precautions that must be taken. Access must only be possible through the use of a tool, lock and key, or other means of security, and controlled by the authority responsible for the location.*

- [Section 2.1, “Mounting the Device”](#)
- [Section 2.2, “Connecting Power”](#)
- [Section 2.3, “Connecting the Failsafe Alarm Relay”](#)
- [Section 2.4, “Grounding the Device”](#)
- [Section 2.5, “Connecting to the Device”](#)
- [Section 2.6, “Cabling Recommendations”](#)

## Section 2.1

# Mounting the Device

The RS416 is designed for maximum mounting and display flexibility. It can be equipped with connectors that allow it to be installed in a 48 cm (19 in) rack, 35 mm (1.4 in) DIN rail, or directly on a panel.



**NOTE**

For detailed dimensions of the device with either rack, DIN rail or panel hardware installed, refer to [Chapter 5, Dimension Drawings](#).

The following sections describe the various methods of mounting the device:

- [Section 2.1.1, “Mounting the Device to a Rack”](#)
- [Section 2.1.2, “Mounting the Device on a DIN Rail”](#)
- [Section 2.1.3, “Mounting the Device to a Panel”](#)

Section 2.1.1

## Mounting the Device to a Rack

For rack mount installations, the RS416 can be equipped with rack mount adapters pre-installed at the front or rear of the chassis. Additional adapters are provided to further secure the device in high-vibration or seismically active locations.

To secure the device to a standard 48 cm (19 in) rack, do the following:



**NOTE**

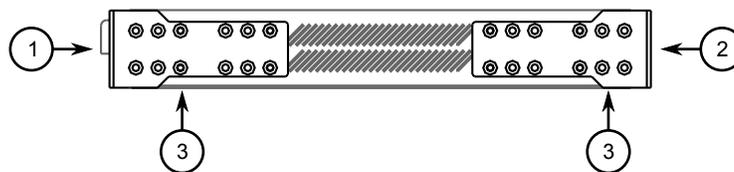
The device can be ordered with the communication ports located at the front or rear of the device. Placing the ports at the rear allows all data and power cabling to be installed and connected at the rear of the rack.

1. Make sure the rack mount adapters are installed on the correct side of the chassis.



**NOTE**

The chassis features multiple mounting holes, allowing the rack mount adapters to be installed up to 25 mm (1 in) from the face of the device.



**Figure 2: Rack Mount Adaptors**

1. Rear 2. Front 3. Rack Mount Adaptor

2. If required, install adapters on the opposite side of the device to protect from vibrations.
3. Insert the device into the rack.



**NOTE**

Since heat within the device is channelled to the enclosure, it is recommended that 1 rack-unit of space, or 44 mm (1.75 in), be kept empty above the device. This allows a small amount of convectional airflow.

Forced airflow is not required. However, any increase in airflow will result in a reduction of ambient temperature and improve the long-term reliability of all equipment mounted in the rack space.

- Secure the adapters to the rack using the supplied hardware.

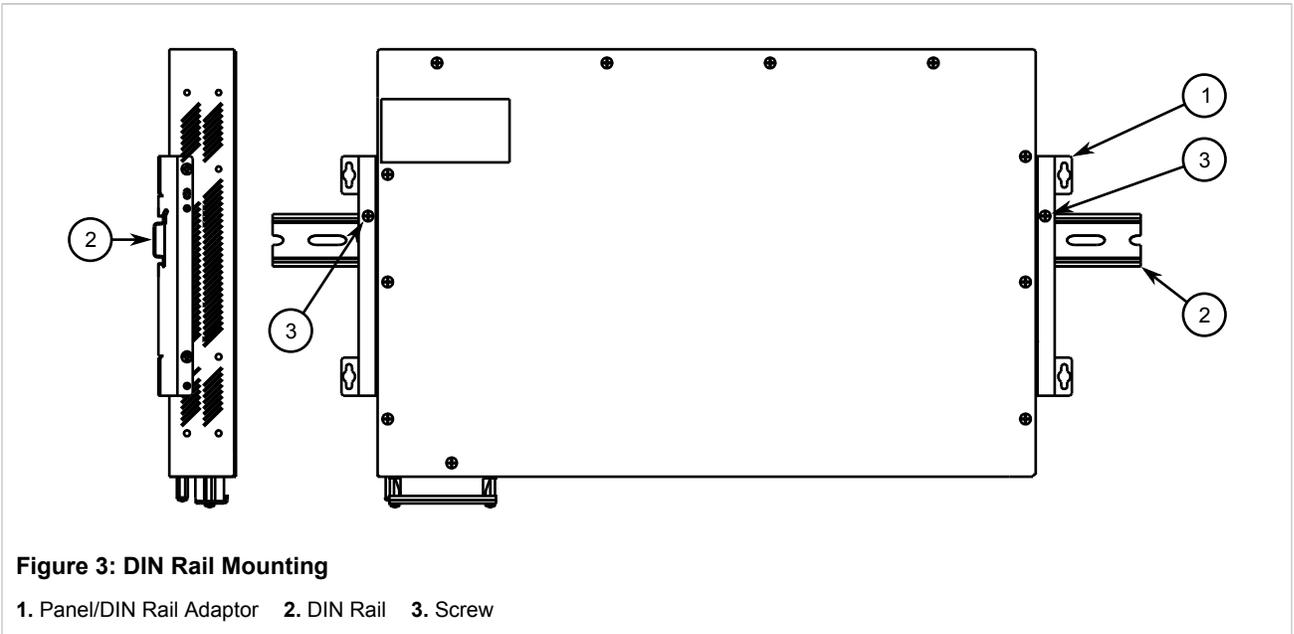
### Section 2.1.2

## Mounting the Device on a DIN Rail

For DIN rail installations, the RS416 can be equipped with panel/DIN rail adapters pre-installed on each side of the chassis. The adapters allow the device to be slid onto a standard 35 mm (1.4 in) DIN rail.

To mount the device to a DIN rail, do the following:

- Align the adapters with the DIN rails and slide the device into place.



- Install one of the supplied screws on either side of the device to secure the adapters to the DIN rails.

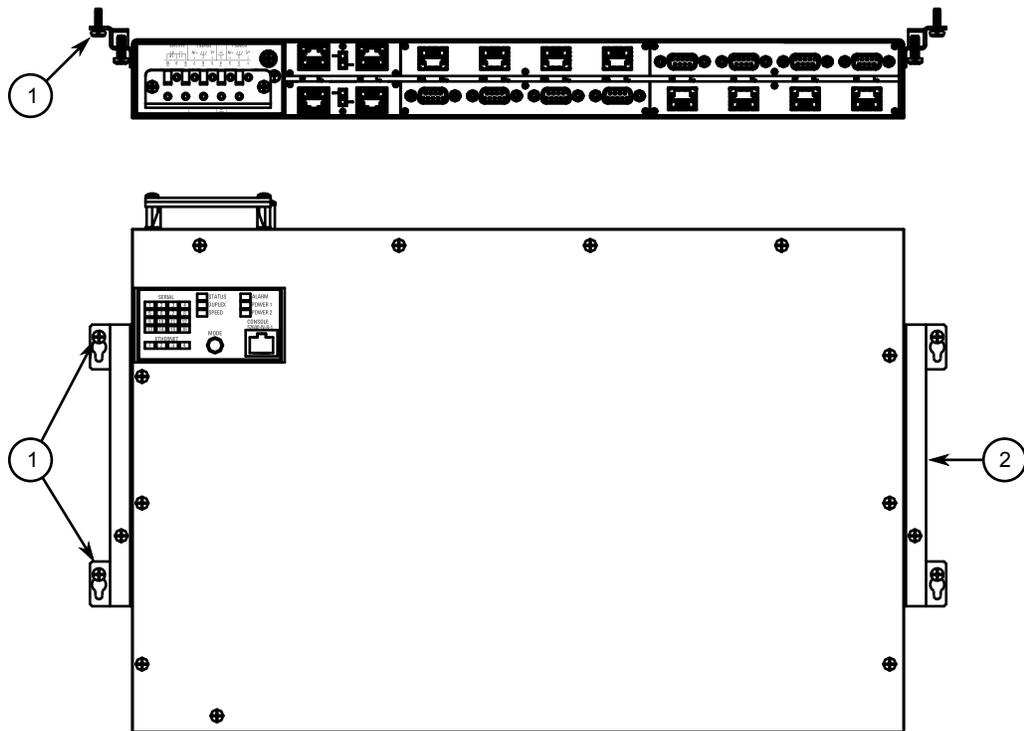
### Section 2.1.3

## Mounting the Device to a Panel

For panel installations, the RS416 can be equipped with panel/DIN rail adapters pre-installed on each side of the chassis. The adapters allow the device to be attached to a panel using screws.

To mount the device to a panel, do the following:

- Place the device against the panel and align the adapters with the mounting holes.



**Figure 4: Panel Mounting**

1. Screw 2. Panel/DIN Rail Adaptor

2. Install the supplied screws to secure the adapters to the panel.

## Section 2.2

# Connecting Power

The RS416 supports single or dual redundant high AC and/or low DC power supplies. The use of two power modules is recommended to provide redundancy and load balancing.

The RS416 can be equipped with either a screw-type or pluggable terminal block, which provides power to both power supplies. The screw-type terminal block is installed using Phillips screws and compression plates, allowing either bare wire connections or crimped terminal lugs. Use #6 size ring lugs for secure, reliable connections under severe shock or vibration.



### NOTE

- For maximum redundancy in a dual power supply configuration, use two independent power sources.
- For 100-240 VAC rated equipment, an appropriately rated AC circuit breaker must be installed.
- For 88-300 VDC rated equipment, an appropriately rated DC circuit breaker must be installed.
- Use only #16 gage copper wiring when connecting terminal blocks.
- A circuit breaker is not required for 12, 24 or 48 VDC rated power supplies.

- *It is recommended to provide a separate circuit breaker for each power supply module.*
- *Equipment must be installed according to applicable local wiring codes and standards.*

The following sections describe how to connect power to the device:

- [Section 2.2.1, “Connecting AC Power”](#)
- [Section 2.2.2, “Connecting DC Power”](#)
- [Section 2.2.3, “Wiring Examples”](#)

### Section 2.2.1

## Connecting AC Power

To connect a high AC power supply to the device, do the following:



### CAUTION!

*Electrical hazard – risk of damage to equipment. Do not connect AC power cables to a DC power supply terminal block. Damage to the power supply may occur.*



### CAUTION!

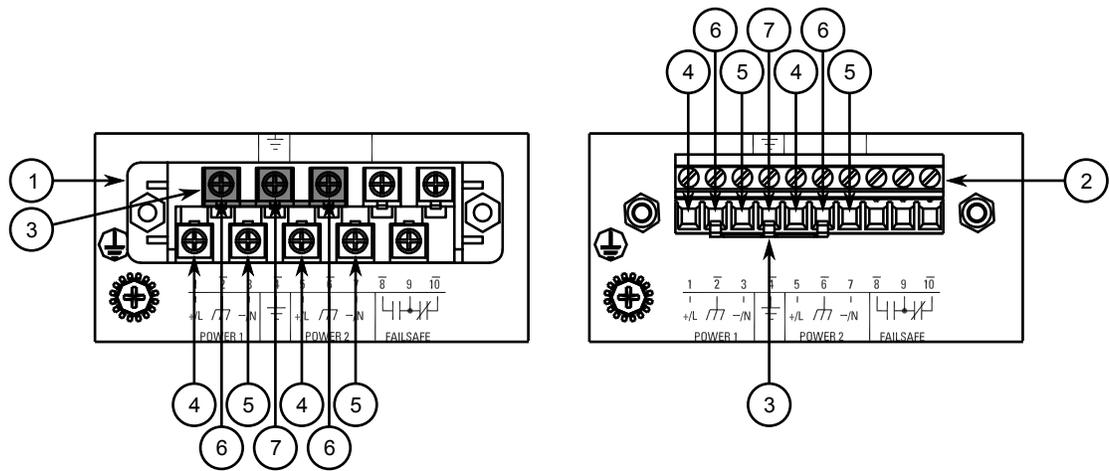
*Electrical hazard – risk of damage to equipment. Before testing the dielectric strength (HIPOT) in the field, remove the metal jumper. This metal jumper connects transient suppression circuitry to chassis ground and must be removed in order to avoid damage to transient suppression circuitry during testing.*



### NOTE

*The terminal block is divided into separate terminals for each internal power supply. Make sure to connect the external power supply to the appropriate terminals.*

1. Remove the terminal block cover.
2. If a screw-type terminal block is installed, remove the screws from the appropriate terminals. Use these screws along with #6 ring lugs to secure the wires to the terminal block.
3. Connect the positive wire from the power source to the positive/live (+/L) terminal on the terminal block. For more information, refer to [Section 2.2.3, “Wiring Examples”](#).



**Figure 5: Terminal Block Wiring**

1. Screw-Type Terminal Block 2. Pluggable Terminal Block 3. Jumper 4. Positive/Live (+/L) Terminal 5. Negative/Neutral (-/N) Terminal (-/N) 6. Surge Ground Terminal 7. Chassis Ground Terminal

4. Connect the negative wire from the power source to the negative/neutral (-/N) terminal on the terminal block. For more information, refer to [Section 2.2.3, “Wiring Examples”](#).
5. Install the supplied metal jumper between terminals 2, 4 and 6 to connect the surge ground terminals to the chassis ground terminal. The surge ground terminals are used as the ground conductor for all surge and transient suppression circuitry internal to the unit.
6. Connect the ground terminal on the power source to the chassis ground terminal on the device. For more information, refer to [Section 2.4, “Grounding the Device”](#)



**DANGER!**

*Electrocution hazard – risk of death, serious personal injury and/or damage to the device. Make sure the supplied terminal block cover is always installed before the device is powered.*

7. Install the terminal block cover.

Section 2.2.2

## Connecting DC Power

To connect a single high or low DC power supply to the device, do the following:



**CAUTION!**

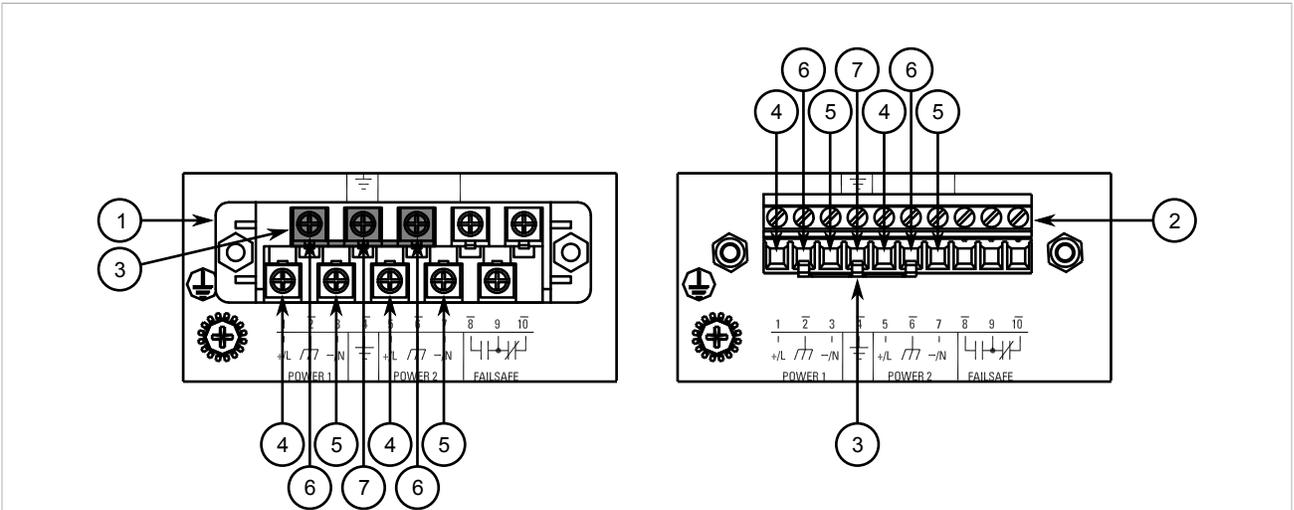
*Electrical hazard – risk of damage to equipment. Before testing the dielectric strength (HIPOT) in the field, remove the metal jumper. This metal jumper connects transient suppression circuitry to chassis ground and must be removed in order to avoid damage to transient suppression circuitry during testing.*



**NOTE**

*The screw-type terminal block is installed using Philips screws and compression plates, allowing either bare wire connections or crimped terminal lugs. Use #6 size ring lugs for secure, reliable screws, which must be removed to make connections.*

1. Remove the terminal block cover.
2. If a screw-type terminal block is installed, remove the screws from the appropriate terminals. Use these screws along with #6 ring lugs to secure the wires to the terminal block.
3. Connect the positive wire from the power source to the positive/live (+/L) terminal on the terminal block. For more information, refer to [Section 2.2.3, "Wiring Examples"](#).



**Figure 6: Terminal Block Wiring**

1. Screw-Type Terminal Block 2. Pluggable Terminal Block 3. Jumper 4. Positive/Live (+/L) Terminal 5. Negative/Neutral (-/N) Terminal 6. Surge Ground Terminal 7. Chassis Ground Terminal

4. Connect the negative wire from the power source to the negative/neutral (-/N) terminal on the terminal block. For more information, refer to [Section 2.2.3, "Wiring Examples"](#).
5. Install the supplied metal jumper between terminals 2, 4 and 6 to connect the surge ground terminals to the chassis ground terminal. The surge ground terminals are used as the ground conductor for all surge and transient suppression circuitry internal to the unit.
6. Connect the ground terminal on the power source to the chassis ground terminal on the device. For more information, refer to [Section 2.4, "Grounding the Device"](#)



**DANGER!**

*Electrocution hazard – risk of death, serious personal injury and/or damage to the device. Make sure the supplied terminal block cover is always installed before the device is powered.*

7. Install the terminal block cover.

Section 2.2.3

## Wiring Examples

The following illustrate how to connect power to single and dual power supplies.

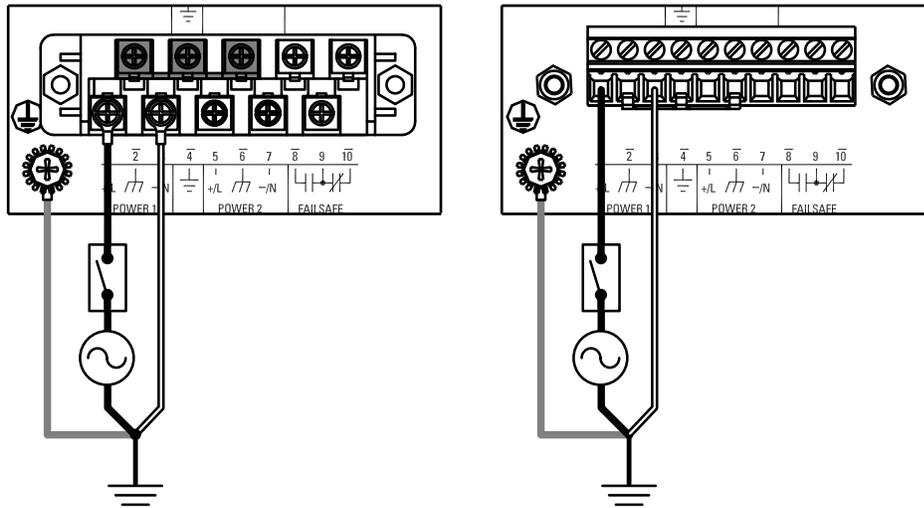


Figure 7: Single AC Power Supply

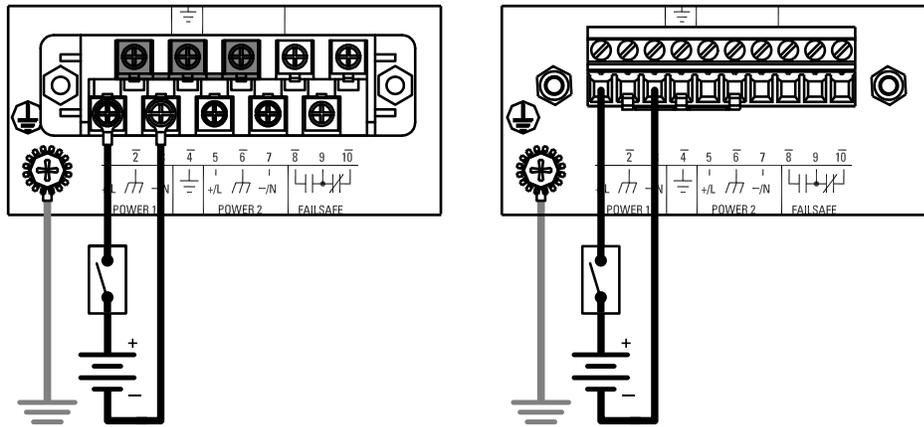


Figure 8: Single DC Power Supply

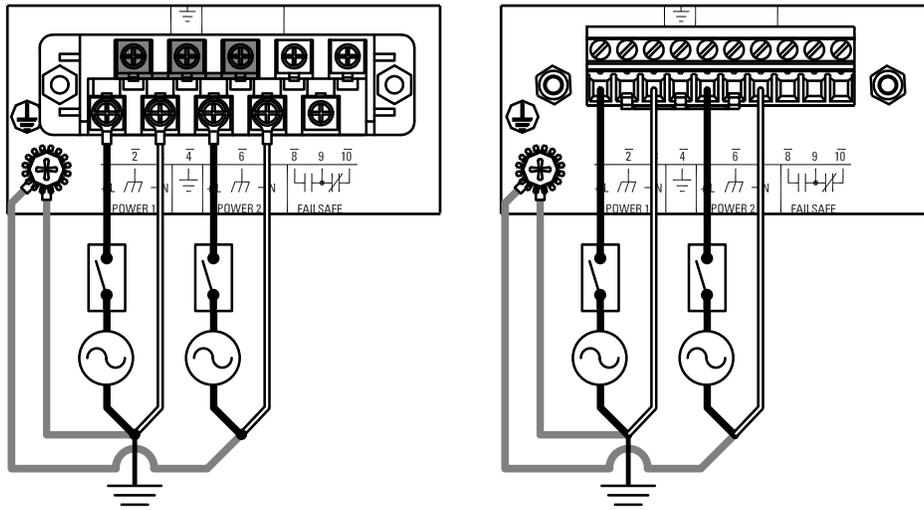


Figure 9: Dual AC Power Supply

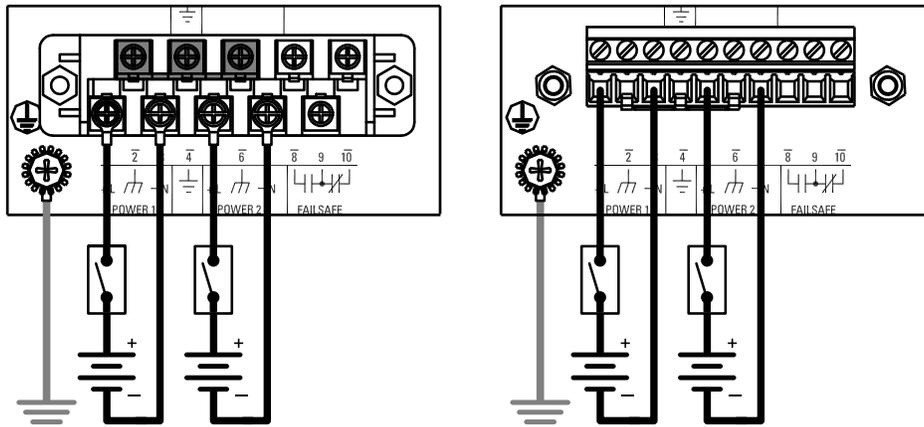
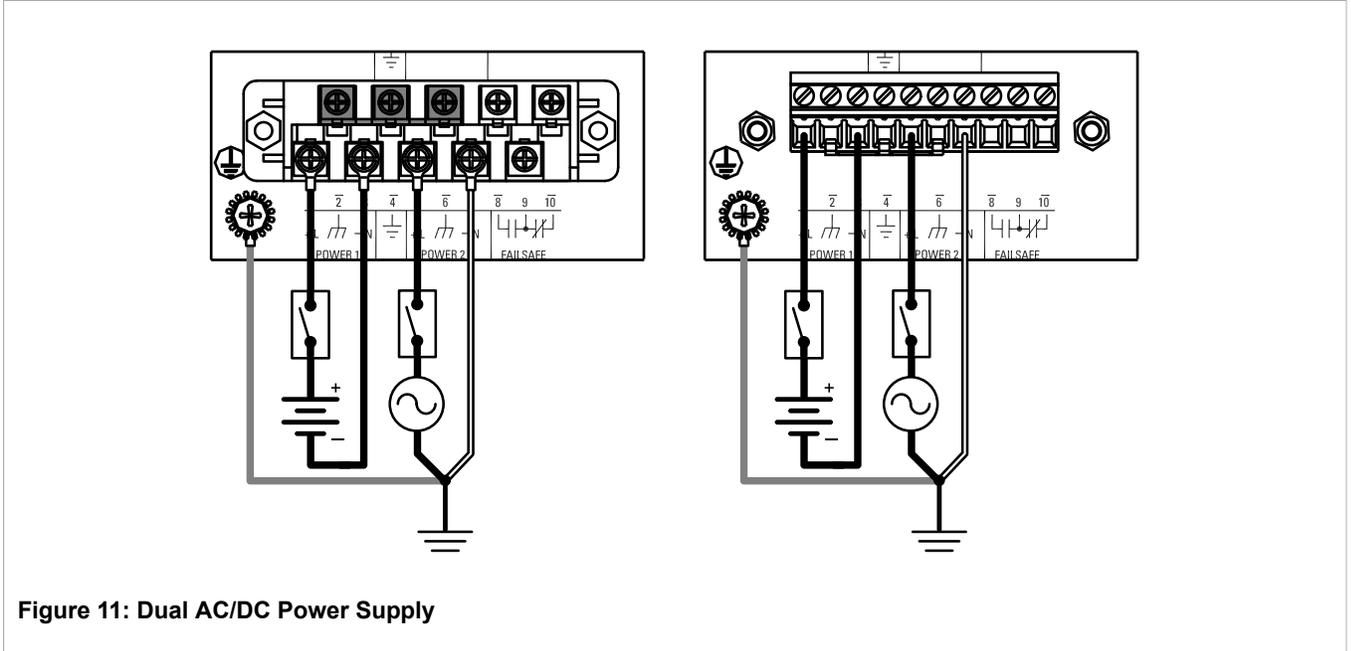


Figure 10: Dual DC Power Supply



Section 2.3

## Connecting the Failsafe Alarm Relay

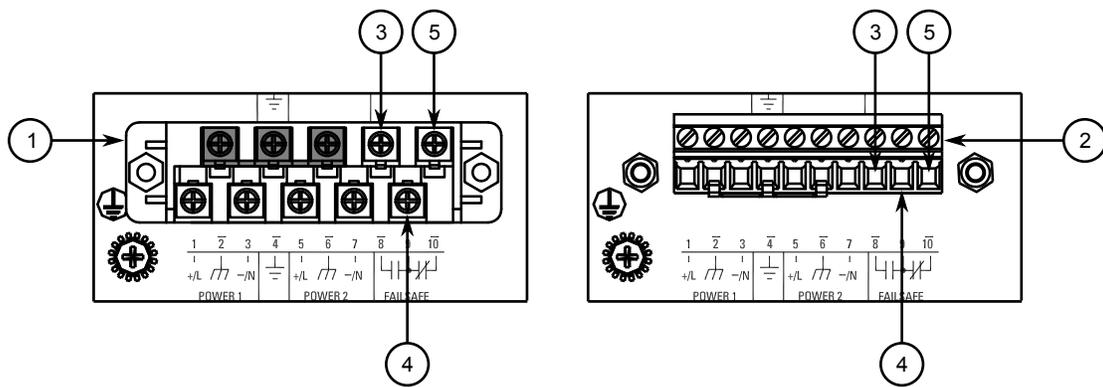
The failsafe relay can be configured to latch based on alarm conditions. The NO (Normally Open) contact is closed when the unit is powered and there are no active alarms. If the device is not powered or if an active alarm is configured, the relay opens the NO contact and closes the NC (Normally Closed) contact.



**NOTE**

*Control of the failsafe relay output is configurable through ROS. One common application for this relay is to signal an alarm if a power failure occurs. For more information, refer to the ROS User Guide for the RS416.*

The following shows the proper relay connections.



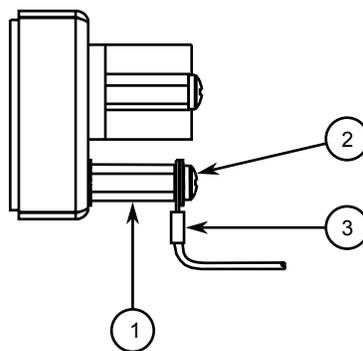
**Figure 12: Failsafe Alarm Relay Wiring**

1. Screw-Type Terminal Block   2. Pluggable Terminal Block   3. Normally Open Terminal   4. Common Terminal   5. Normally Closed Terminal

#### Section 2.4

## Grounding the Device

The RS416 chassis ground terminal uses a #6-32 screw. It is recommended to terminate the ground connection with a #6 ring lug and torque it to 1.7 N·m (15 lbf·in).



**Figure 13: Chassis Ground Connection**

1. Stainless Steel Stud   2. #6-32 Screw   3. #6 Ring Lug

#### Section 2.5

## Connecting to the Device

The following describes the various methods for accessing the ROS console and Web interfaces on the device. For more detailed instructions, refer to the *ROS User Guide* for the RS416.

## RS232 Console Port

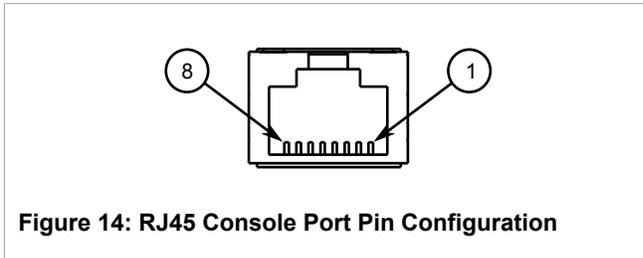
Connect a PC or terminal directly to the RS232 console port to access the boot-time control and ROS interfaces. The console port provides access to ROS's console and Web interfaces.



### IMPORTANT!

*The console port is intended to be used only as a temporary connection during initial configuration or troubleshooting.*

Connection to the console port is made using an RJ45-to-DB9 console cable. The following is the pin-out for the console port:



Pin		Name	Description
RJ45 Male	DB9 Female		
1	6	DSR <sup>a</sup>	Data Set Ready
2	1	Reserved (Do Not Connect)	
3	4	DTR <sup>a</sup>	Data Terminal Ready
4	5	GND	Signal Ground
5	2	RxD	Receive Data (to DTE)
6	3	TxD	Transmit Data (from DTE)
7	8	CTS <sup>b</sup>	Clear to Send
8	7	RTS <sup>b</sup>	Read to Send
1	9	RI <sup>c</sup>	Ring Indicator

<sup>a</sup> The DSR, DCD and DTR pins are connected together internally.

<sup>b</sup> The CTS and RTS pins are connected together internally.

<sup>c</sup> RI is not connected.

## Communication Ports

Connect any of the available Ethernet ports on the device to a management switch and access the ROS console and Web interfaces via the device's IP address. For more information about available ports, refer to [Chapter 3, Communication Ports](#).

### Section 2.6

# Cabling Recommendations

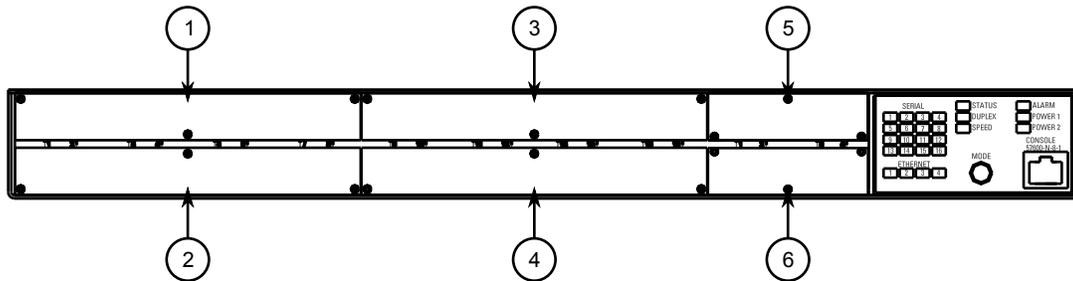
Siemens does not recommend the use of copper cabling of any length for critical, real-time substation automation applications. All copper Ethernet ports on RUGGEDCOM products include transient suppression circuitry to protect against damage from electrical transients and conform with IEC 61850-3 and IEEE 1613 Class 1 standards. This means that during a transient electrical event, communications errors or interruptions may occur, but recovery is automatic.

Siemens also does not recommend using copper Ethernet ports to interface with devices in the field across distances that could produce high levels of ground potential rise (i.e. greater than 2500 V), during line-to-ground fault conditions.

# 3 Communication Ports

The RS416 can be equipped with various types of communication ports to enhance its abilities and performance. To determine which ports are equipped on the device, refer to the factory data file available through ROS. For more information on how to access the factory data file, refer to the *ROS User Guide* for the RS416.

Each communication port type has a specific place in the RS416 chassis.



**Figure 15: Port Assignment**

1. Slot 1 2. Slot 2 3. Slot 3 4. Slot 4 5. Slot 5 6. Slot 6

Slot	Type
1 to 4	Serial Ports
5 to 6	Fast Ethernet (10/100Base-TX, 10Base-FL or 10/100Base-FX) or IRIG-B Ports

The following sections describe the available ports:

- [Section 3.1, “Copper Ethernet Ports”](#)
- [Section 3.2, “Fiber Optic Ethernet Ports”](#)
- [Section 3.3, “Serial Ports”](#)
- [Section 3.4, “Connecting Multiple RS485 Devices”](#)
- [Section 3.5, “Time Synchronization”](#)

## Section 3.1

# Copper Ethernet Ports

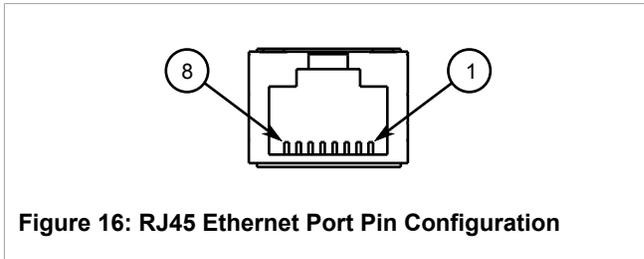
The RS416 supports several 10/100Base-TX Ethernet ports that allow connection to standard Category 5 (CAT-5) unshielded twisted-pair (UTP) cables with RJ45 male connectors. The RJ45 connectors are directly connected to the chassis ground on the device and can accept CAT-5 shielded twisted-pair (STP) cables.

Each port features a **Speed** and **Link** LED that indicates the state of the port.

LED	State	Description
Speed	Yellow	The port is operating at 100 Mbps

LED	State	Description
	Off	The port is operating at 10 Mbps
Link	Yellow (Solid)	Link established
	Yellow (Blinking)	Link activity
	Off	No link detected

The following is the pin-out for the RJ45 male connector:



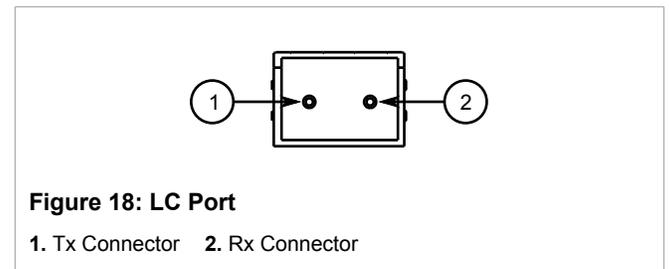
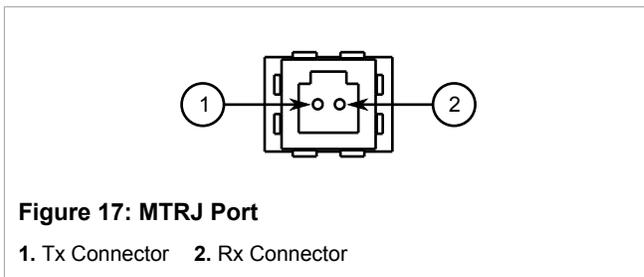
Pin	Name	Description
1	RX+	Receive Data+
2	RX-	Receive Data-
3	TX+	Transmit Data+
4		Reserved (Do Not Connect)
5		Reserved (Do Not Connect)
6	TX-	Transmit Data-
7		Reserved (Do Not Connect)
8		Reserved (Do Not Connect)

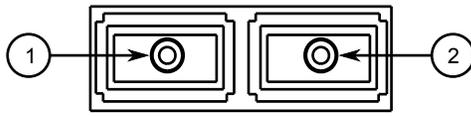
For specifications on the available copper Ethernet ports, refer to [Section 4.3, “Copper Ethernet Port Specifications”](#).

Section 3.2

## Fiber Optic Ethernet Ports

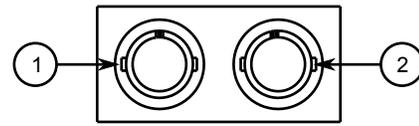
Fiber optic Ethernet ports are available with either MTRJ (Mechanical Transfer Registered Jack), LC (Lucent Connector), SC (Standard or Subscriber Connector) or ST (Straight Tip) connectors. Make sure the Transmit (Tx) and Receive (Rx) connections of each port are properly connected and matched to establish a proper link.





**Figure 19: SC Port**

1. Tx Connector 2. Rx Connector



**Figure 20: ST Port**

1. Tx Connector 2. Rx Connector

For specifications on the available fiber optic Ethernet ports, refer to [Section 4.4, “Fiber Optic Ethernet Port Specifications”](#).

Section 3.3

## Serial Ports

The RS416 supports serial cards with fiber serial ST (Straight Tip) connectors, RS232/RS485/RS422 DB9 serial ports or RS232/RS485/RS422 RJ45 serial ports.

Serial DB9 and RJ45 ports can be run in RS232, RS485 or RS422 mode. They can also be ordered with IRIG-B time code support.



**NOTE**

*On power-up, all serial RJ45 ports default to RS485 mode. Each port can be individually set to RS232, RS485 or RS422 mode through ROS. For more information, refer to the ROS User Guide for the RS416.*



**NOTE**

*For information about how to connect devices configured to run in RS485 mode, refer to [Section 3.4, “Connecting Multiple RS485 Devices”](#).*

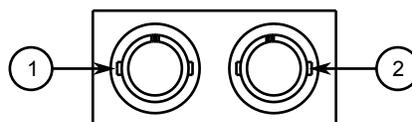
All serial ports feature an LED that indicates the current state of the port.

State	Description
Green	Link activity detected
Off	No link detected

For specifications on serial ports, refer to [Section 4.5, “Serial Port Specifications”](#).

The following is the pin-out description for ST, DB9 and RJ45 serial ports:

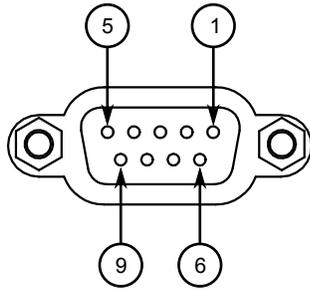
### Fiber Serial Port



**Figure 21: ST Port**

1. Tx Connector 2. Rx Connector

## Serial DB9 Port



**Figure 22: Serial DB9 Port Pin Configuration**

Pin	Mode		
	RS232 DCE	RS485	RS422
1	DCD <sup>a</sup>		
2	TX <sup>b</sup>	TX/RX+	TX+
3	RX <sup>b</sup>		RX+
4	DTR <sup>a</sup>		
5	Common (Isolated) Ground		
6	DSR <sup>a</sup>		RX-
7	RTS	TX/RX-	TX-
8	CTS		
9	RI <sup>c</sup>		
Shield	Chassis Ground		

<sup>a</sup> The DSR, DCD and DTR pins are connected together internally.

<sup>b</sup> In RS232 DCE mode, ports transmit to DTE devices on pin 2 and receive from DTE on pin 3.

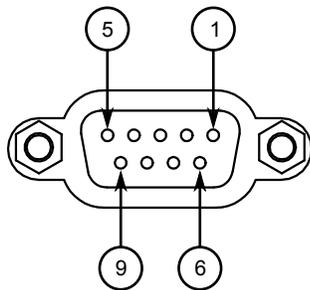
<sup>c</sup> RI is not connected.



### NOTE

Pins 1, 4 and 6 and pins 7 and 8 are connected internally. In RS232 mode, these pins enter a high impedance state. A DTE that asserts RTS will see CTS asserted. However, the device will not perform hardware flow control.

## Serial DB9 Port with IRIG-B Support



**Figure 23: Serial DB9 Port Pin Configuration**

Pin	Mode		
	RS232 DTE	RS485	RS422
1			RX-
2	RX <sup>d</sup>	TX/RX+	TX+
3	TX <sup>d</sup>		RX+
4	IRIG-B+		
5	Common (Isolated) Ground		
6	Common (Isolated) Ground		
7	RTS	TX/RX-	TX-
8	CTS		
9	Common (Isolated) Ground		
Shield	Chassis Ground		

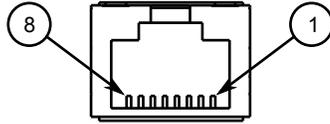
<sup>d</sup> In RS232 DTE mode, ports transmit to DTE devices on pin 2 and receive from DTE on pin 3.



**NOTE**

Pins 7 and 8 are connected internally. In RS232 mode, these pins enter a high impedance state. A DTE that asserts RTS will see CTS asserted. However, the device will not perform hardware flow control.

**Serial RJ45 Port**



**Figure 24: Serial RJ45 Port Pin Configuration**

Pin	RS232 Mode	RS485 Mode	RS422 Mode
1	DSR <sup>e</sup>		RX-
2	DCD <sup>e</sup>		
3	DTR <sup>e</sup>		
4	Common (Isolated) Ground		
5	RXD <sup>f</sup>		RX+
6	TXD <sup>f</sup>	TX/RX+	TX+
7	CTS		
8	RTS	TX/RX-	TX-
Shield	Chassis Ground		

<sup>e</sup> The DSR, DCD and DTR pins are connected together internally.

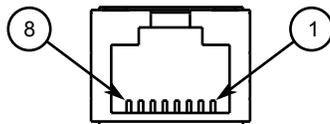
<sup>f</sup> In RS232 mode, the RJ45 ports conform to EIA-561 DTE, which transmit on TXD and receive on RXD.



**NOTE**

Pins 1, 2 and 3 and pins 7 and 8 are connected internally. In RS232 mode, these pins enter a high impedance state. A DTE that asserts RTS will see CTS asserted. However, the device will not perform hardware flow control.

**Serial RJ45 Port with IRIG-B Support**



**Figure 25: Serial RJ45 Port Pin Configuration**

Pin	RS232 Mode	RS485 Mode	RS422 Mode
1			RX-
2	+IRIG-B		
3	Common (Isolated) Ground		
4	Common (Isolated) Ground		
5	RXD <sup>g</sup>		RX+
6	TXD <sup>g</sup>	TX/RX+	TX+
7	CTS		
8	RTS	TX/RX-	TX-
Shield	Chassis Ground		

<sup>g</sup> In RS232 mode, the RJ45 ports conform to EIA-561 DTE, which transmit on TXD and receive on RXD.



**NOTE**

*Pins 7 and 8 are connected internally. In RS232 mode, these pins enter a high impedance state. A DTE that asserts RTS will see CTS asserted. However, the device will not perform hardware flow control.*

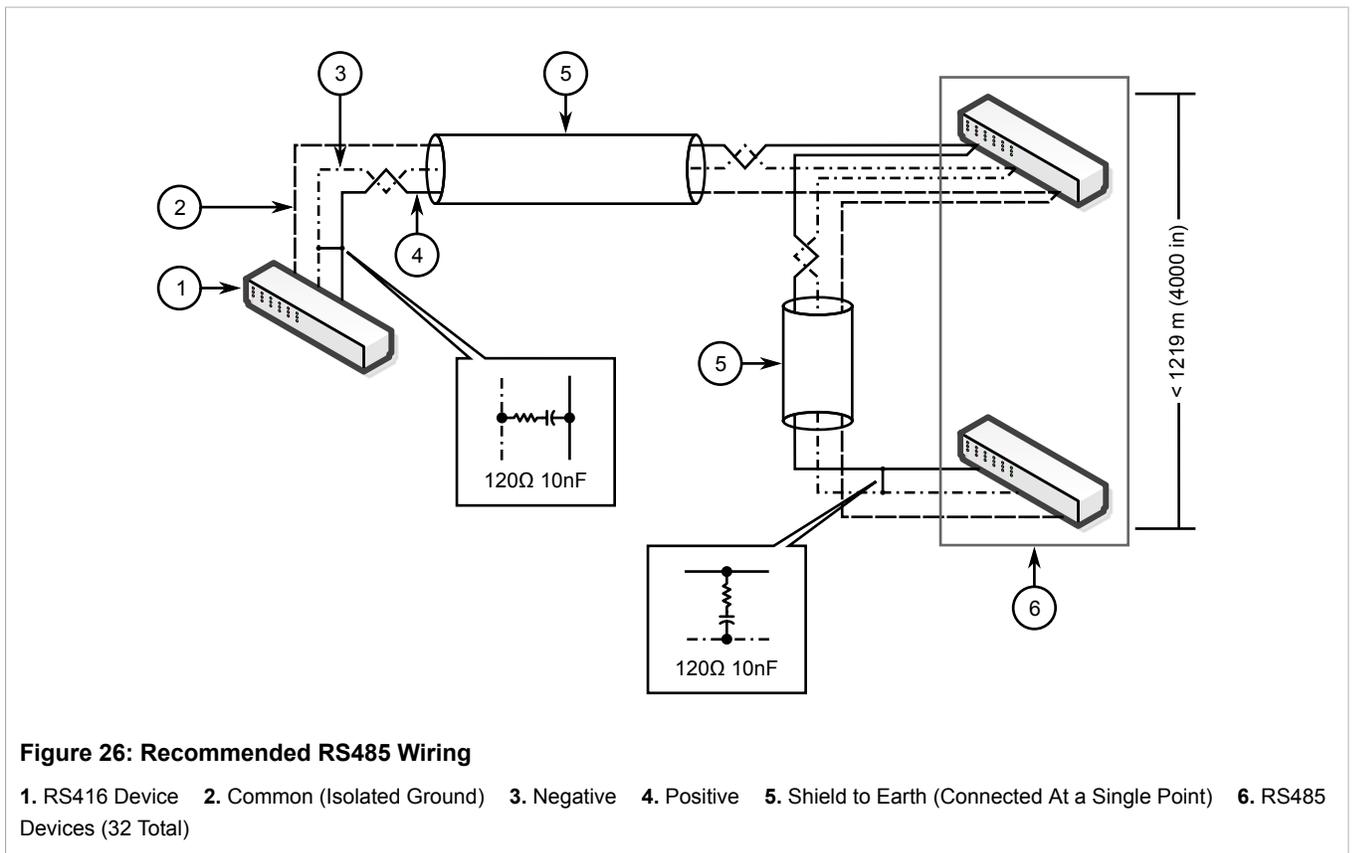
Section 3.4

# Connecting Multiple RS485 Devices

Each RS485 port can communicate with multiple RS485 devices by wiring devices together in sequence over a single twisted pair with transmit and receive signals on the same two wires (half duplex). For reliable, continuous communication, adhere to the following guidelines:

- To minimize the effects of ambient electrical noise, use shielded cabling.
- The correct polarity must be observed throughout a single sequence or ring.
- The number of devices wired should not exceed 32, and total distance should be less than 1219 m (4000 ft) at 100 kbps.
- The Common terminals should be connected to the common wire inside the shield.
- The shield should be connected to earth ground at a single point to avoid loop currents.
- The twisted pair should be terminated at each end of the chain.

The following shows the recommended RS485 wiring.



## Section 3.5

# Time Synchronization

The RS416 is able to derive and provide time synchronization via Ethernet using the Precision Time Protocol (PTP) and NTP (Network Time Protocol). With the IRIG-B module is installed, the RS416 is also able to synchronize to received IRIG-B time signal and to distribute it via BNC and via serial ports equipped with IRIG-B signals. Please refer to the data sheet for ordering options.

The following are the time synchronization sources supported by the RS416 for time synchronization.

Synchronization Source	Without IRIG Module	With IRIG Module
NTP	Yes	Yes
IEEE 1588 v2	Yes	Yes
IRIG-B PWM	No	Yes

The following are the time synchronization services supported by the RS416.

Synchronization Service	Without IRIG Module	With IRIG Module
NTP	Yes	Yes
IEEE 1588 v2	Yes	Yes
IRIG-B PWM	No	Yes

NTP (Network Time Protocol) is the standard for synchronizing the clocks of computer systems throughout the Internet and is suitable for systems that require accuracies on the order of 1 ms.

IRIG-B (Inter Range Instrumentation Group, mod B) time synchronization is an established, inter-device time synchronization mechanism which provides accuracy on the order of 1ms to 1 $\mu$ s.

IEEE 1588 is designed to fill a niche not well served by either NTP or IRIG-B. IEEE1588 is designed for local systems requiring accuracies on the order of 100 nanoseconds. IEEE 1588 is also designed for applications that cannot bear the cost of a GPS receiver at each node or for which GPS signals are inaccessible. Every Ethernet port on the RS416 supports IEEE1588.

## Section 3.5.1

## IRIG-B Ports

The IRIG-B output ports described in sections 3.3 and 3.5 derive their time from the IRIG-B module, which occupies one slot in lieu of a two-port Ethernet module. The IRIGB module has one dedicated input and one dedicated output. These ports operate in IRIG-B PWM mode (IRIG-B006 or IRIG-B007) only.

The following figure shows the layout of the BNC connectors on the IRIG-B I/O board. The LED in the center of the board, indicated by the mark, reflects the status of the received IRIG-B signal, and is described in the following table.



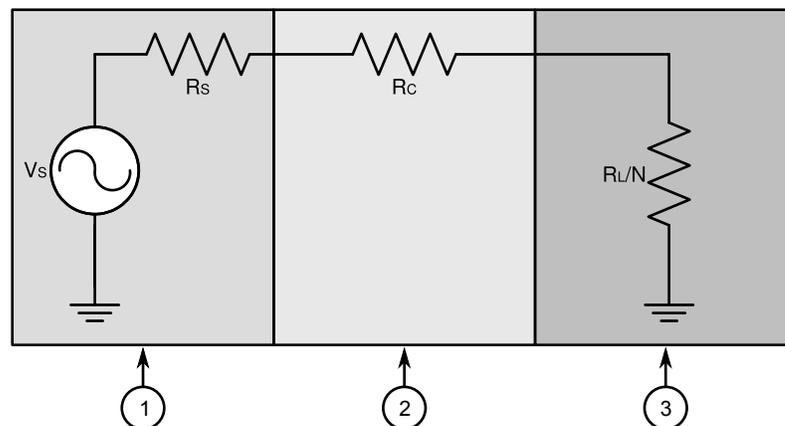
**Figure 27: IRIG-B Daughter Board BNC Connections**

LED Color	Meaning
Off	No IRIG-B signal detected
Red	Errors detected in received IRIG-B signal
Green	Received IRIG-B signal is good

Section 3.5.2

## IRIG-B Connection Considerations

The number of IRIG-B devices that can be connected to a given IRIG-B output is dependent on the cabling type and length, as well as the input impedances of connected devices. The following shows a simplified circuit diagram of the interface between an IRIG-B output and connected devices.



**Figure 28: IRIG-B Simplified Schematic**

1. Source 2. Cabling 3. Device

The maximum number of devices (N) that can be connected to the source is determined by verifying that the source current ( $I_S$ ) required to drive the connected devices is less than the maximum drive current the output can provide, and that the load voltage ( $V_L$ ) seen by the connected devices is greater than their minimum required voltage. For IRIG-B port specifications, refer to [Section 4.6, "IRIG-B Ports"](#).

# 4 Technical Specifications

The following sections provide important technical specifications related to the device and available modules:

- [Section 4.1, “Power Supply Specifications”](#)
- [Section 4.2, “Failsafe Relay Specifications”](#)
- [Section 4.3, “Copper Ethernet Port Specifications”](#)
- [Section 4.4, “Fiber Optic Ethernet Port Specifications”](#)
- [Section 4.5, “Serial Port Specifications”](#)
- [Section 4.6, “IRIG-B Ports”](#)
- [Section 4.7, “Operating Environment”](#)
- [Section 4.8, “Mechanical Specifications”](#)

## Section 4.1

# Power Supply Specifications

Power Supply Type	Input Range		Internal Fuse Rating <sup>a,b</sup>	Isolation	Maximum Power Consumption <sup>c</sup>
	Minimum	Maximum			
12 VDC	10 VDC	36 VDC	6.3 A(F)	1.5 kVDC	25 W
24 VDC					
48 VDC	36 VDC	59 VDC	3.15 A(T)		
HI (125/250 VDC) <sup>d</sup>	88 VDC	300 VDC	2 A(T)	4 kVAC, 5.5 kVDC	
HI (110/230 VAC) <sup>d</sup>	85 VAC	264 VAC			

<sup>a</sup> (F) denotes fast-acting fuse

<sup>b</sup> (T) denotes time-delay fuse.

<sup>c</sup> Power consumption varies based on configuration. 10/100Base-TX ports consume roughly 1 W less than fiber optic ports.

<sup>d</sup> The HI power supply is the same power supply for both AC and DC.

## Section 4.2

# Failsafe Relay Specifications

Maximum Switching Voltage	Rated Switching Current
30 VAC	0.3 A, 1.0 A
80 VDC	0.3

Section 4.3

## Copper Ethernet Port Specifications

The following details the specifications for copper Ethernet ports that can be ordered with the RS416.

Speed <sup>e</sup>	Connector	Duplex <sup>e</sup>	Cable Type <sup>f</sup>	Wiring Standard <sup>g</sup>	Maximum Distance <sup>h</sup>	Isolation <sup>i</sup>
10/100Base-TX	RJ45	FDX/HDX	> CAT-5	TIA/EIA T568A/B	100 m (328 ft)	1.5 kV

<sup>e</sup> Auto-negotiating.

<sup>f</sup> Shielded or unshielded.

<sup>g</sup> Auto-crossover and auto-polarity.

<sup>h</sup> Typical distance. Dependent on the number of connectors and splices.

<sup>i</sup> RMS 1 minute.

Section 4.4

## Fiber Optic Ethernet Port Specifications

The following sections detail fiber optic specifications for ports that can be equipped on the RS416..

- [Section 4.4.1, “10Base-FL Ethernet Optical Specifications”](#)
- [Section 4.4.2, “Fast Ethernet \(100 Mbps\) Optical Specifications”](#)

Section 4.4.1

### 10Base-FL Ethernet Optical Specifications

Mode	Connector Type	Cable Type (µm)	Tx λ (typ.) (nm)	Tx min (dBm)	Tx max (dBm)	Rx Sensitivity (dBm)	Rx Saturation (dBm)	Distance (typ.) (km)	Power Budget (dB)
MM	ST	62.5/125	850	-16	-9	-34	-11.2	2	18
		50/125		-19.8	-12.8				14.2

Section 4.4.2

### Fast Ethernet (100 Mbps) Optical Specifications

Mode	Connector Type	Cable Type (µm)	Tx λ (typ.) (nm)	Tx min. (dBm)	Tx max. (dBm)	Rx Sensitivity (dBm)	Rx Saturation (dBm)	Distance (typ.) (km)	Power Budget (dB)
MM	ST	62.5/125	1300	-19	-14	-31	-14	2	12
		50/125		-22.5					8.5
MM	SC	62.5/125	1300	-19	-14	-31	-14	2	12

Mode	Connector Type	Cable Type (µm)	Tx λ (typ.) (nm)	Tx min. (dBm)	Tx max. (dBm)	Rx Sensitivity (dBm)	Rx Saturation (dBm)	Distance (typ.) (km)	Power Budget (dB)
		50/125		-22.5					8.5
MM	MTRJ	62.5/125	1300	-19	-14	-31	-14	2	12
		50/125		-22.5					8.5
SM	ST	9/125	1300	-15	-8	-32	-3	20	17
SM	SC	9/125	1300	-15	-8	-31	-7	20	16
SM	LC	9/125	1300	-15	-8	-34	-7	20	19
SM	LC	9/125	1300	-15	-8	-34	-7	20	19
SM	SC	9/125	1300	-5	0	-34	-3	50	29
SM	LC	9/125	1300	-5	0	-35	3	50	30
SM	SC	9/125	1300	0	5	-37	0	90	37
SM	LC	9/125	1300	0	5	-37	0	90	37
MM	MTRJ	62.5/125	1300	-19	-14	-31	-14	2	12
	LC	50/125		-22.5					8.5

Section 4.5

## Serial Port Specifications

The following sections detail specifications for ports that can be equipped on the RS416.

- [Section 4.5.1, “Copper Serial Port Specifications”](#)
- [Section 4.5.2, “Fiber Serial Port Specifications”](#)

Section 4.5.1

### Copper Serial Port Specifications

Baud Rate	Connector	Isolation
1200 to 230400 kbps	DB9	2.5 kV
1200 to 230400 kbps	RJ45	2.5 kV
1200 to 230400 kbps	DB9	2.5 kV
1200 to 230400 kbps	RJ45	2.5 kV

Section 4.5.2

## Fiber Serial Port Specifications

Mode	Connector	Typical Distance (km)	Optical Wavelength (nm)	Cable Size
Multimode	ST	5	850	50/125
				62.5/125

Section 4.6

## IRIG-B Ports

Table: IRIG-B PWM Input

Parameter	Typical Value
Input Voltage	TTL-Compatible
Input Impedance	> 200 kΩ

Table: IRIG-B Port Output Specifications

Parameter	Typical Value
Output Current ( $I_S$ )	100 mA

Section 4.7

## Operating Environment

Parameter	Range	Comments
Ambient Operating Temperature	-40 to 85 °C (-40 to 185 °F)	Measured from a 30 cm (12 in) radius surrounding the center of the enclosure.
Ambient Relative Humidity	5% to 95%	Non-condensing
Ambient Storage Temperature	-40 to 85 °C (-40 to 185 °F)	

Section 4.8

## Mechanical Specifications

Parameter	Value
Dimensions	Refer to <a href="#">Chapter 5, Dimension Drawings</a>
Weight	4.5 kg (10 lbs)
Ingress Protection	IP40 (1 mm or 0.04 in objects)
Enclosure	18 AWG Galvanized Steel

# 5 Dimension Drawings



**NOTE**

All dimensions are in millimeters, unless otherwise stated.

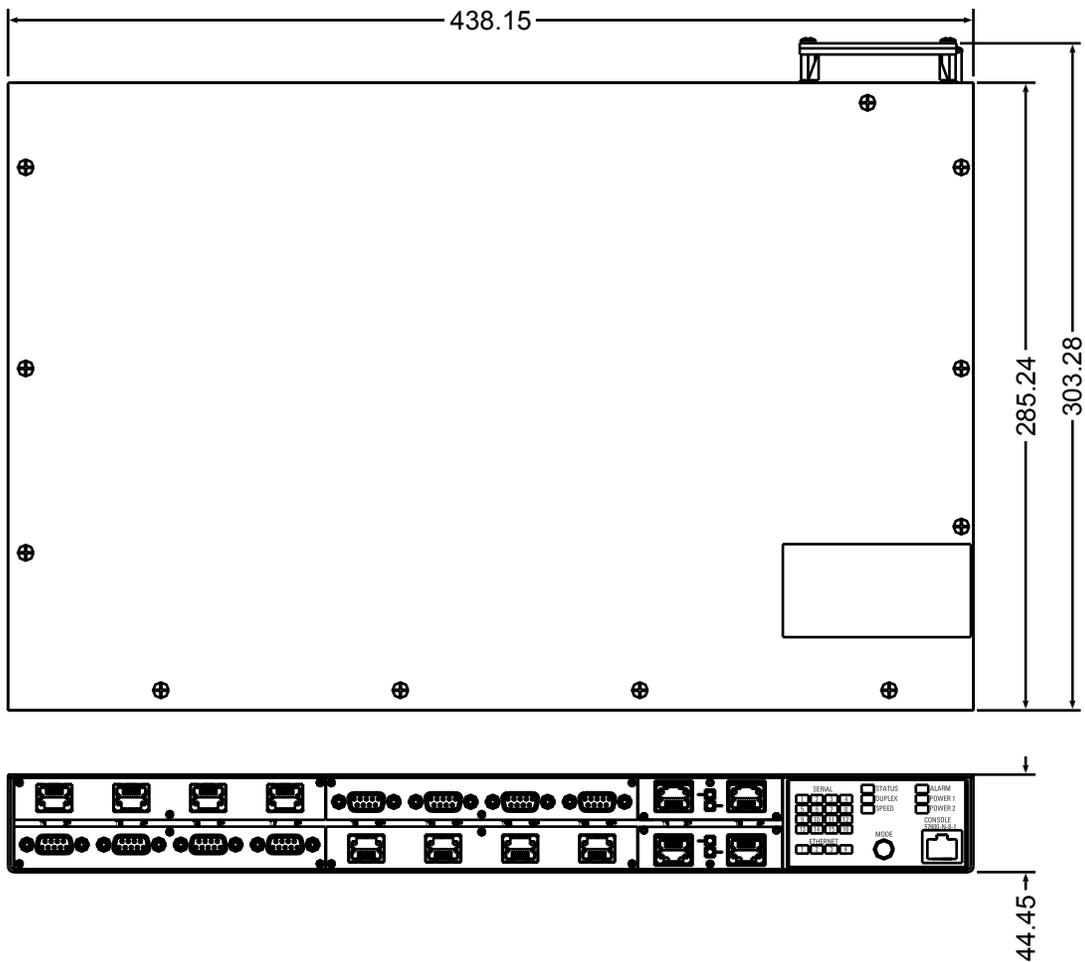


Figure 29: Overall Dimensions

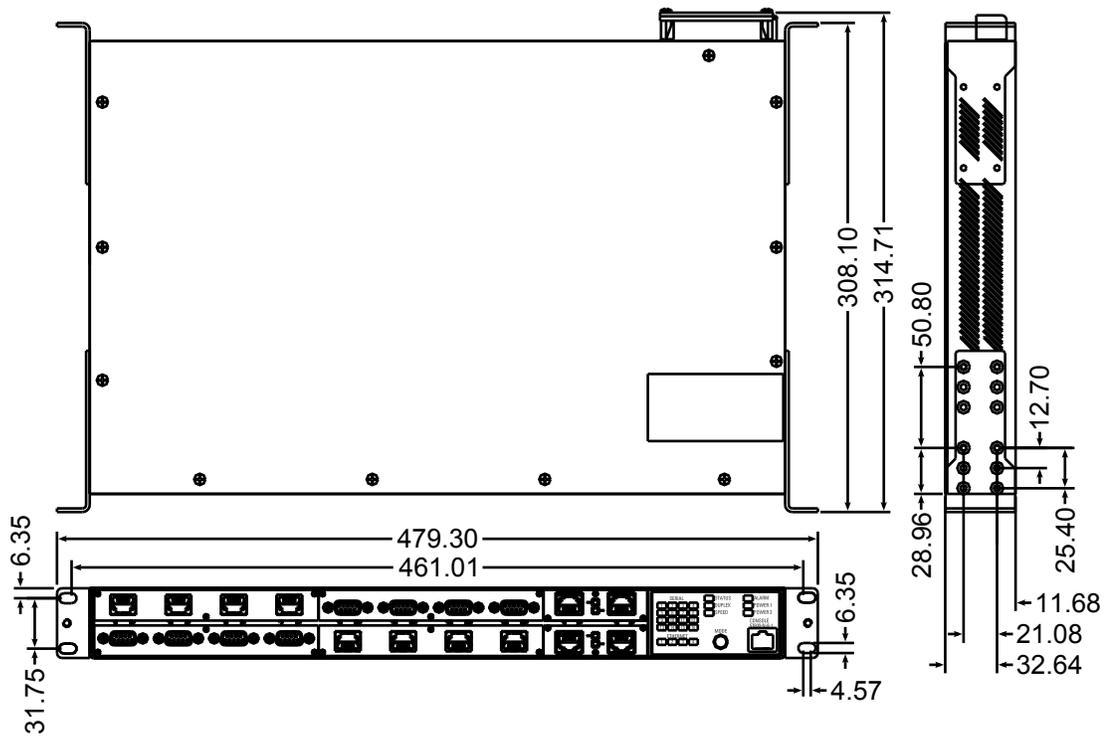


Figure 30: Rack Mount Dimensions

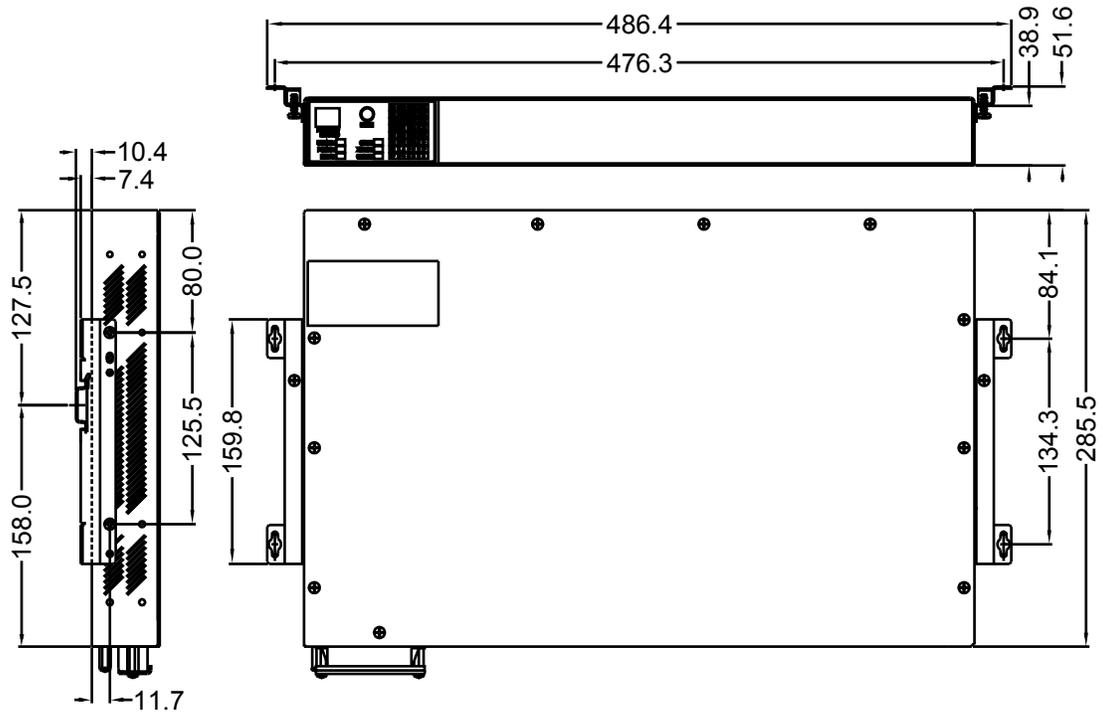


Figure 31: Panel and DIN Rail Mount Dimensions



# 6 Certification

The RS416 device has been thoroughly tested to guarantee its conformance with recognized standards and has received approval from recognized regulatory agencies.

- [Section 6.1, “Agency Approvals”](#)
- [Section 6.2, “FCC Compliance”](#)
- [Section 6.3, “Industry Canada Compliance”](#)
- [Section 6.4, “EMI and Environmental Type Tests”](#)

## Section 6.1

### Agency Approvals

Agency	Standards	Comments
CSA	CSA C22.2 No. 60950-1, UL 60950-1	Approved
CE	EN 60950-1, EN 61000-6-2, EN 55022, EN 50581, EN 60825-1	Approved
FCC	FCC Part 15, Class A	Approved
FDA/CDRH	21 CFR Chapter I, Sub-chapter J	Compliant

## Section 6.2

### FCC Compliance

This equipment has been tested and found to comply with the limits for a Class A digital device pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment.

This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference on his own expense.

## Section 6.3

### Industry Canada Compliance

CAN ICES-3 (A) / NMB-3 (A)

Section 6.4

# EMI and Environmental Type Tests

The RS416 has passed the following EMI and environmental tests.

## IEC 61850-3 Type Tests

Test	Description	Test Levels	Severity Levels	
IEC 61000-4-2	ESD	Enclosure Contact	+/- 8 kV	4
		Enclosure Air	+/- 15 kV	4
IEC 61000-4-3	Radiated RFI	Enclosure ports	20 V/m	Note <sup>a</sup>
IEC 61000-4-4	Burst (Fast Transient)	Signal ports	+/- 4 kV @ 2.5 kHz	Note <sup>a</sup>
		DC Power ports	+/- 4 kV	4
		AC Power ports	+/- 4 kV	4
		Earth ground ports	+/- 4 kV	4
IEC 61000-4-5	Surge	Signal ports	+/- 4 kV line-to-earth, +/- 2 kV line-to-line	4
		DC Power ports	+/- 2 kV line-to-earth, +/- 1 kV line-to-line	3
		AC Power ports	+/- 4 kV line-to-earth, +/- 2 kV line-to-line	4
IEC 61000-4-6	Induced (Conducted) RFI	Signal ports	10 V	3
		DC Power ports	10 V	3
		AC Power ports	10 V	3
		Earth ground ports	10 V	3
IEC 61000-4-8	Magnetic Field	Enclosure ports	40 A/m continuous, 1000 A/m for 1 s	Note <sup>a</sup>
			1000 A/m for 1 s	5
IEC 61000-4-29	Voltage Dips and Interrupts	DC Power ports	30% for 0.1 s, 60% for 0.1 s, 100% for 0.05 s	
IEC 61000-4-11		AC Power ports	30% for 1 period, 60% for 50 periods	
IEC 61000-4-12	Damped Oscillatory	Signal ports	2.5 kV common, 1 kV differential mode @ 1 MHz	3
		DC Power ports	2.5 kV common, 1 kV differential mode @ 1 MHz	3
		AC Power ports	2.5 kV common, 1 kV differential mode @ 1 MHz	3
IEC 61000-4-16	Mains Frequency Voltage	Signal ports	30 V Continuous, 300 V for 1 s	4
		DC Power ports	30 V Continuous, 300 V for 1 s	4

Test	Description		Test Levels	Severity Levels
IEC 61000-4-17	Ripple on DC Power Supply	DC Power ports	10%	3
IEC 60255-5	Dielectric Strength	Signal ports	2 kVAC (Fail-Safe Relay output)	
		DC Power ports	1.5 kVDC	
		AC Power ports	2 kVDC	
	HV Impulse	Signal ports	5 kV (Fail-Safe Relay Output)	
		DC Power ports	5 kV	
		AC Power ports	5 kV	

<sup>a</sup> Siemens specified severity level.

### IEEE 1613 (C37.90.x) EMI Immunity Type Tests



**NOTE**

The RS416 meets Class 2 requirements for an all-fiber configuration and Class 1 requirements for copper ports.

IEEE Test	IEEE 1613 Clause	Description		Test Levels
C37.90.3	9	ESD	Enclosure Contact	+/- 8 kV
			Enclosure Air	+/- 15 kV
C37.90.2	8	Radiated RFI	Enclosure ports	35 V/m
C37.90.1	7	Fast Transient	Signal ports	+/- 4 kV @ 2.5 kHz
			DC Power ports	+/- 4 kV
			AC Power ports	+/- 4 kV
			Earth ground ports	+/- 4 kV
		Oscillatory	Signal ports	2.5 kV common mode @ 1MHz
			DC Power ports	2.5 kV common and differential mode @ 1MHz
C37.90	6	HV Impulse	Signal ports	5 kV (Failsafe Relay)
			DC Power ports	5 kV
			AC Power ports	5 kV
		Dielectric Strength	Signal ports	2 kVAC (Failsafe Relay)
			DC Power ports	1.5 kVDC
			AC Power ports	2 kVAC

### Environmental Type Tests

Test	Description		Test Levels	Severity Levels
IEC 60068-2-1	Cold Temperature	Test Ad	-40 °C (-40 °F), 16 Hours	

Test	Description		Test Levels	Severity Levels
IEC 60068-2-2	Dry Heat	Test Bd	85 °C (185 °F), 16 Hours	
IEC 60068-2-30	Humidity (Damp Heat, Cyclic)	Test Db	95% (non-condensing), 55 °C (131 °F), 6 cycles	
IEC 60255-21-1	Vibration		2 g @ 10-150 Hz	Class 2
IEC 60255-21-2	Shock		30 g @ 11 ms	Class 2