

Industry Online Support

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NEWS

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# SINUMERIK ONE MCP commissioning

SINUMERIK ONE

https://support.industry.siemens.com/cs/ww/en/view/109794252

Siemens Industry Online Support



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# 1 Introduction

### 1.1 Task

Integrating SINUMERIK ONE MCP 1900, MCP 2200, MCP 2200c, MCP 2400 or customized MCP - connected to the Industrial Ethernet - in the PLC of SINUMERIK ONE.

### 1.2 Principle of operation

The hardware is integrated using special, specified data types, which are transferred to a function block (ModMCPCtrlMilling), which in turn ensures that the signals are distributed to the HMI, axis and channel interface.

### 1.3 Components used

This application example was created with these hardware and software components: Table 1-1

Component	Numbe r	Article number	Note
TIA Portal V16	1		
SINUMERIK ONE STEP 7 Toolbox V16	1		
SINUMERIK ONE 1760	1	6FC5317-6AA00-0AA0	
MCP 2400c	1	6FC5303-0AP51-0BA0	
24" Touch Panel	1		

This application example consists of the following components:

Table 1-2

Component	File name	Note
TIA library		
TIA project example		

# 2 Engineering

# 2.1 Hardware configuration



## 2.2 Configuration

### 2.2.1 Configuring PLC data types for the input and output image

Create new data types in the project navigation in the TIA Portal under "PLC data types". This is shown as example for mcpIn2400c and mcpOut2400c in the following diagram.





Fig. 2-2



The data types for the input/output image always reflect the existing hardware. The input image always comprises

- The Base Input Block
- The individual keypads
- The powerrides
- The handwheels

This sequence is fixed, the number of keypads and powerrides is variable. The input images of the handwheels are always transferred, even if there are no handwheels. See Fig. 2-2 for the assignment of the existing hardware to the PLC data types.

The output image always comprises

- The Base Output Block
- The individual keypads
- The powerrides

This sequence is also fixed, the number of keypads and powerrides is variable. There are no handwheels in the output image. The assignment of the existing hardware is analogous to the input image, see Fig. 2-2.

There are no gaps in the PLC data type or placeholders if there are only 2 or 3 keypads or only one powerride.

In the example, data types mcpIn2400c and mcpOut2400c comprise the "Modular MCP Data Types" provided with the base program.



The names of the individual data type components can be freely selected. Names used in the example

KeypadModeGroupe	keypad to control JOG, AUTO, REF etc.
KeypadOEM1	keypad to be used by the OEM
KeypadOEM2	keypad to be used by the OEM
KeypadAxis	keypad to select axes and traversing keys etc.
Powerride1	1 Powerride
Powerride2	2 Powerride
handwheel	1 and 2 handwheels

#### 2.2.2 Assignment of the MCP inputs/outputs

To be able to use the inputs/outputs of the MCP in the PLC program they still have to be assigned.

- Either via a global data block
- Or directly assigned via the PLC tag table

#### Assignment via a global data block

Project tree								
Devices								
EN .		-01	42 B.	Reena	rtual values 🔒 Spanshot 🍬 🛤 Convisnansi	nots to start values	R. R. Load st	art values as a
			MCP	and we have a second of the				
Name			Nam	•	Data type	Offse	t Start value	Retain
<ul> <li>SINUMERIK One ModMcn IE NC6 14 V2.0</li> </ul>	~	1 -6		tatic	both type	01130	c start tande	
Add new device	-	2 -		r in	"mcp2400cin"	0.0		E E
A Devices & networks		3 4		Base	"LBP_typeModularMcpBaseInput"	0.0		Ä
SINUMERIK ONE [NCU 1760]		4 -		KeyPadModeGroup	"LBP_typeModularMcpModeGroupInput"	6.0		Ă
Device configuration		5 ┥		KeyPadOem1	"LBP_typeModularMcpUniversalInput"	10.0		Ă
MOD_MCP_IE [PLC NCU 1760]	=	6 -		KeyPadOem2	"LBP_typeModularMcpUniversalInput"	14.0		Ā
Device configuration		7 \prec		KeypadAxis	"LBP_typeModularMcpAxisInput"	18.0		Ā
Q Online & diagnostics		8 \prec		PowerrideSpindle	"LBP_typePowerrideInput"	22.0		
🕶 🙀 Software units		9 🔩		PowerrideFeed	"LBP_typePowerrideInput"	24.0		
📑 Add new software unit		10 🖪	•	Handwheel	"LBP_typeHandwheel"	26.0		
💌 🕁 Program blocks		11 🚽		out	"mcp2400cOut"	30.0		
💣 Add new block		12 🖪		Base	"LBP_typeModularMcpBaseOutput"	30.0		
allesWasManSoBraucht		13 🖪	•	KeyPadModeGroup	"LBP_typeModularMcpModeGroupOutput"	32.0		
🕨 🛅 ОВ		14 🔩	•	KeypadOem1	"LBP_typeModularMcpUniversalOutput"	36.0		
SINUMERIK ONE PLC BP		15 \prec	•	KeypadOem2	"LBP_typeModularMcpUniversalOutput"	40.0		
🔻 🔚 User		16 🚽		<ul> <li>KeypadAxis</li> </ul>	"LBP_typeModularMcpAxisOutput"	44.0		
ModMCPCtrlMilling [FB219]		17 \prec	•	<ul> <li>PowerrideSpindle</li> </ul>	"LBP_typePowerrideOutput"	48.0		
PowerRideLedControl [FB3003]		18 🖪	•	PowerrideFeed	"LBP_typePowerrideOutput"	54.0		
instDBModMCPCtrlMilling [DB3002]								
LBP_OpUnitComm_DB [DB25001]								
LBP_Powerride_DB [DB63]								
LBP_Powerride_DBsp [DB65]								
myMCP [DB64]								
PowerrideDaten [DB62]								

In the example, a global data block with the name "myMCP" was created under "Program Blocks" in subgroup "User". It is not permissible that this data block is optimized from a memory perspective. An "in" range and an "out" range are created in the data block. This range is then assigned to the data type that was created.

"in" -> mcp2400cIn and "out" -> mcp2400cOut.

You can view the complete assignment by opening ranges "in" / "out".

#### Assignment via the PLC tag table

FIG. 2-5 Project tree	u ( si	inumerikOneMcpModula	rBeispiel_IE → ONE [NCU 1760]	ONEMcpIE [PLC NCU 1	760] → PLC tags	• USEI	₹► MCI	P [2]	
Devices									📲 Tags
8	- E -	ê 🔄 🖻 🔂 🕾 🛍							
		MCP							
<ul> <li>SinumerikOneMcpModularBeispiel_IE</li> </ul>		Name	Data type	Address	Retain	Acces	Writa	Visibl	Supervis Cor
💕 Add new device	1	- myMcpin	"mcpIn2400c"	%10.0					
📩 Devices & networks	2	myMcpOut	"mcpOut2400c"	%Q0.0					
• 100 [NCU 1760]	3	<add new=""></add>						<b>V</b>	
Device configuration									
• • Im ONEMcpIE (PLC NCU 1760)									
Device configuration									
Q Online & diagnostics									
Software units									
Program blocks									
Technology objects									
External source files									
🔻 🔚 PLC tags									
a Show all tags									
📑 Add new tag table									
💥 Standard-Variablentabelle [105]									
Ta USER									
5 MCP [2]									
PLC data types									
Watch and force tables									

In the example, a USER subgroup was created in the project navigation under "PLC Tags". A PLC tag table "MCP" was created in this subgroup.

In this subgroup, name "myMcpIn", data type "mcpIn2400c" was assigned hardware address "I0.0" – and name "myMcpOut", data type "mcpOut2400c" was assigned hardware address "Q0.0".

You can completely view the assignment by opening the identifier.

-3111	amento	onemepmodularbeispier			ioj - ric tags	0311		- [Z]		
									🕣 Tage	s 🗉 User co
÷		) H 😷 🗊								u
4000.	MCP									
	Na	ime	Data type	Address	Retain	Acces	Writa	Visibl	Supervis	Comment
1		myMcpin	"mcpin2400c"	%I0.0						
2		▶ Base	LBP_typeModularMcpBaseInput	%I0.0						Preliminary - Inp
3	-00	<ul> <li>KeyPadModeGroup</li> </ul>	LBP_typeModularMcpModeGroupI	%16.0						Preliminary - Inp
4		reset	Bool	%16.0		<ul> <li>Image: A start of the start of</li></ul>	<b>V</b>	<b>V</b>		input image n+
5	-00	cycleStop	Bool	%I6.1		<ul> <li>Image: A start of the start of</li></ul>	<b>V</b>	<b>V</b>		input image n+
6	-00	cycleStart	Bool	%16.2		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
7		singleBlock	Bool	%16.3		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
8		inc100	Bool	%16.4		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
9		inc1000	Bool	%16.5		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
10		auto	Bool	%16.6		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
11		inc1	Bool	%16.7		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
12		inc10	Bool	%17.0		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
13		mda	Bool	%17.1		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
14		teachin	Bool	%17.2		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
15		incVar	Bool	%17.3		<b>V</b>	<b>V</b>	<b>V</b>		input image n+
16		jog	Bool	%17.4		<ul> <li>Image: A start of the start of</li></ul>	<b>V</b>	<b>V</b>		input image n+
17	-	repos	Bool	%17.5		<ul> <li>Image: A start of the start of</li></ul>	<b>V</b>	<b>V</b>		input image n+
18	-	refPoint	Bool	%17.6		<ul> <li>Image: A start of the start of</li></ul>	<b>V</b>	<b>V</b>		input image n+
19	-	reserved17	Bool	%17.7		<b>V</b>	<b>V</b>			
20	-		D 1	NID 0						



#### 2.2.3 Configuring "LBP\_ConfigBP" in OB "Startup"

In this configuration, the MCP is operated at X120 (IE = Industrial Ethernet). Fig. 2-7

:=1
:="myMcpIn"
:="myMcpOut"
:=192
:=S5T#700MS
:=NULL
:=NULL
:=0
:=S5T#700MS
:=FALSE
:=FALSE
:=FALSE
:=FALSE
:=B#16#55
:=0

You can see the call of LBP\_ConfigBP in the startup OB in Fig 2-6; this assigns the MCP input/output signals via the PLC tag table.

Fig. 2-8

CALL "LBP_ConfigBP"	
MCPNum	:=1
MCP1In	:="myMCP".in
MCP1Out	:="myMCP".out
MCP1BusAdr	:=192
MCP1Timeout	:=S5T#700MS
MCP2In	:=NULL
MCP2Out	:=NULL
MCP2BusAdr	:=0
MCP2Timeout	:=S5T#700MS
MCP1Stop	:=FALSE
MCP2Stop	:=FALSE
MCP1NotSend	:=FALSE
MCP2NotSend	:=FALSE
MCPBusType	:=B#16#55
HTIf	:=0
ITTT-	- DITOO O

You can see the call of LBP\_ConfigBP in the startup OB in Fig 2-7; this assigns the MCP input/output signals via the global data block.

Interconnecting "LBP\_ConfigBP"

- MCPNum: Number of connected machine control panels.
- MCP1In: The "in" section of the global data block (myMCP.in) or the PLCTag (myMcpIn) is interconnected here for the inputs of the MCP.
- MCP1Out: Just the same as for the input, the "out" section of the global data block (myMCP.Out) or the PLCTag (myMcpOut) for the outputs of the MCP is interconnected here.
- MCP1BusAdr: The address set at the DIP switches of the MCP is specified here. Refer to the MCP documentation for a description of the DIP switches.
- MCPBusType: Bus type 5 IE is selected here
- Regarding the MCP, all other parameters can be left at their preassigned default settings

#### 2.2.4 Configuring "ModMCPCtrlMilling"

Block "ModMCPCtrlMilling" is used to transfer data from the machine operator panel (MCP milling version) to the NC / PLC interface. ModMCPCtrlMilling is executed as function block (FB). The block is written in SCL and is not know-how protected; users can adapt the block to address their specific requirements.



Name	P type	Data type	Comment
ExternNcStart	IN	Bool	Signal from an external NC start key is internally OR'ed with the NC start key
BAGNo	IN	Int	Number of mode group to which the mode signals are transferred
SpindleIFNo	IN	Byte	Number of the axis/spindle in which the spindle- data is transferred
FeedOvr	IN	USInt	Position of the feed override switch in the Gray code format
SpindleOvr	IN	USInt	Position of the spindle override switch in the Gray code format
ConfigDB	IN	"LBP_typeConfigData"	Data block "LBP_ConfigData" of the base program with the global configuration data.
MCPBaseIn	IN	"LBP_typeModularMcpBaseInput"	Basis component of the input image of the SINUMERIK ONE MCP, here in example "myMcpIn.Base"
MCPAxisIn	IN	"LBP_typeModularMcpAxisInput"	Input image of the Axis keypad, here in the example "myMcpIn.KeypadAxis"
MCPModeGroupIn	IN	"LBP_typeModularMcpModeGroupInput"	Input image of the BAG (mode group) keypad, here in the example "myMcpIn.KeyPadMod eGroup"
MCPAxisOut	OUT	"LBP_typeModularMcpAxisOutput"	Output image of the Axis keypad, here in the example "myMcpOut.KeypadAxi s"
MCPModeGroupOut	OUT	"LBP_typeModularMcpModeGroupOutput "	Output image of the BAG (mode group) keypad, here in the example "myMcpout.KeyPadMo deGroup"
Status	OUT	Word	Block error messages as hexadecimal value, see Table xx
Error	OUT	Bool	Block error occurred, evaluate the status.

Table 2-1: Parameters of ModMCPCtrlMilling

#### 2 Engineering

Name	P type	Data type	Comment
NcDB	IN_OUT	"LBP_typeNC"	Base program data block, NC signals "LBP_NC"
ModeGroupDB	IN_OUT	"LBP_typeModeGroup"	Base program data block in which the channel signals are transferred, here in the example "LBP_Chan1"
ChanDB	IN_OUT	"LBP_typeChanX"	Base program data block in which the channel signals are transferred, here in the example "LBP_Chan1"

Number	<b>Type</b>	Description
16#7000	S	No error
16#7001	Е	Invalid BAG (mode group) number
16#7002	Е	Channel is invalid
16#7003		

<sup>1)</sup>S=Status / E= Error

#### 2.2.5 Information about input parameters

#### - ExternNcStart:

Signal from an external NC start key is internally OR'ed with the NC start key. This input can be used for the NC start key in the Powerride. In the project example, a signal was implemented in block "PowerRideLedControl".

#### - BAGNo:

Number of the mode group in which the mode signals are transferred

#### - SpindlelFNo:

Number of the axis/spindle to which the spindle data is transferred (number of the associated machine axis)

#### - FeedOvr:, SpindleOvr:

Position of the override switch in the Gray code format

The Powerrides on the MCP are not evaluated in this block. The Powerrides are parameterized and evaluated in a separate block.

#### - ConfigDB:

Data block "LBP\_ConfigData" of the base program with the global configuration data.

#### MCPBaseIn:

\_

Basis component of the input image of SINUMERIK ONE MCP, in the example "myMcpIn.Base" or "myMcpIn.Base"

#### MCPAxisIn:

Input image of the Axis keypad, in the example "myMcp.In.KeypadAxis" or "myMcpIn.KeypadAxis"

#### MCPModeGroupIn:

Input image of the BAG (mode group) keypad, in the example "myMcp.In.KeyPadModeGroup" or "myMcpIn.KeyPadModeGroup"

#### - MCPAxisOut:

Output image of the Axis keypad, in the example "myMcp.Out.KeypadAxis" or "myMcpOut.KeypadAxis"

#### MCPModeGroupOut:

Output image of the BAG (mode group) keypad, in the example "myMcp.out.KeyPadModeGroup" or "myMcpout.KeyPadModeGroup"

#### - Status:

Block error messages as hexadecimal values, see Table xx??

- Error:

Block error occurred, evaluate the status.

- NcDB :

Base program data block, NC signals "LBP\_NC"

ModeGroupDB:

Data block of the base program, operating mode signals, signals "LBP\_ModeGroup"

ChanDB:

Base program data block in which the channel signals are transferred, here in the example "LBP\_Chan1"

#### 2.2.6 Configuring block LBP\_Powerride

Block LBP\_Powerride is included in the SINUMERIK ONE STEP 7 Toolbox. This block is used to process the input/output signals of the Powerride. The configuration of the Powerride is saved in a configuration data block and transferred to the block interface. Additional information is provided in the block documentation in the online help in the TIA Portal.

```
CALL "LBP_Powerride", "LBP_Powerride_DB"
  enable
                 :="PowerrideDaten".feedOverRideEnable
  preset
                 :="PowerrideDaten".feedOverRidePreset
  forceSwitchPos1 := "PowerrideDaten".feedOverRideForcePos1
  pushButtonLED := "PowerrideDaten".feedOverRidePushButtonLed
  presetValue := "PowerrideDaten".feedOverRidePresetValue
             :="PowerrideDaten".feedOverRideValid
  valid
  error
          :="PowerrideDaten".feedOverRideError
  pushButton := "PowerrideDaten".feedOverRidePushButton
  ovrFactor := "PowerrideDaten".feedOverRideOvrFactor
  grayCode := "PowerrideDaten".feedOverRideGrayCode
                 :="PowerrideDaten".feedOverRideSwitchPos
  switchPos
                 :="PowerrideDaten".feedOverRideStatus
  status
                 :="myMcpIn".PowerrideFeed
  deviceIn
  deviceOut
                 :="myMcpOut".PowerrideFeed
  configuration :="LBP PowerrideConfig".configFeed
```

In the project example, the input-output signals of the block are combined in a "PowerrideData" data block.

Signals that are used in the example:

- enable: Must be supplied with "True" in order to activate Powerride.
- pushButtonLED: Switches on and switches off the LED
- pushButton: Signal as to whether the Powerride was pressed
- grayCode: Output signal of the Powerride position is transferred to block "ModMCPCtrIMilling".
- deviceIn: Input image of the Powerride, here "myMcp.In.PowerrideFeed"
- deviceOut: Output image of the Powerride, here "myMcp.In.PowerrideFeed"
- configuration: configFeed area from data block "LBP\_PowerrideConfig"

Block LBP\_Powerride is called a second time for the spindle override. However, the configuration for a spindle override is used here.

# 3 Appendix

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# 3.2 Links and references

#### Table 3-1

No.	Торіс		
\1\	iemens Industry Online Support		
	https://support.industry.siemens.com		
\2\	Link to the entry page of the application example		
	https://support.industry.siemens.com/cs/ww/en/view/109794252		
\3\			

# 3.3 Change documentation

Table 3-2

Version	Date	Revision
V1.0	04/2021	First Edition