## **SIRIUS Innovations**

**System Overview** 

System Manual · 11/2011



# **Industrial Controls**

Answers for industry.



# **SIEMENS**

**Industrial Controls** 

SIRIUS Innovations - System Overview

**System Manual** 

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#### Legal information

#### Warning notice system

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

#### **A** DANGER

indicates that death or severe personal injury will result if proper precautions are not taken.

#### **WARNING**

indicates that death or severe personal injury may result if proper precautions are not taken.

#### **A** CAUTION

with a safety alert symbol, indicates that minor personal injury can result if proper precautions are not taken.

#### CAUTION

without a safety alert symbol, indicates that property damage can result if proper precautions are not taken.

#### NOTICE

indicates that an unintended result or situation can occur if the relevant information is not taken into account.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

#### **Qualified Personnel**

The product/system described in this documentation may be operated only by **personnel qualified** for the specific task in accordance with the relevant documentation, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

#### Proper use of Siemens products

Note the following:

#### **M** WARNING

Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be complied with. The information in the relevant documentation must be observed.

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#### **Disclaimer of Liability**

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

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SIRIUS Innovations System Overview

## 1.1 Introduction

## 1.1.1 Modular system for SIRIUS

#### System is everything: The SIRIUS modular system for the control cabinet

Siemens is one of the most important manufacturers of switching devices, whose product range extends from devices that switch just a few milliamps to motor starter protectors for power distribution. The process of configuring control cabinets must be quick, easy, flexible, and must enable you to create space-saving solutions.

This is exactly what Siemens offers with its unique SIRIUS modular system. This system offers all the functions and devices you will need for switching, starting, protecting, and monitoring motors and systems. In other words, it provides a modular range of standard components, which are perfectly matched to one another, can be combined really easily, and use the same accessories. That's how easy controls and distribution can be.

Continuous further development and constant innovations ensure that, with SIRIUS, you are ideally equipped to meet the challenges of today and tomorrow, and can benefit from cost-effective solutions. All the components that make up the SIRIUS modular system are characterized by a space-saving design and a high degree of flexibility. Configuration, installation, wiring, and maintenance work are all extremely quick and easy to perform.

In further developing these products, a great deal of emphasis has consistently been placed on meeting or even exceeding requirements in terms of essential performance features, electrical and mechanical durability, dimensions, and ease of mounting and maintenance.

Environmentally-friendly and recyclable materials have been developed and used in the system to reflect the ecological awareness that has grown at a quite incredible rate over the last decade in particular. In the field of low-voltage switching devices, this has resulted in the creation of modern industrial switching devices which fulfill all requirements with regard to environmental compatibility.

Building on decades of experience, a totally new generation of devices for performing switching, starting, protecting, and monitoring functions was created for the large and ever growing number of motorized operating mechanism in the range up to 18.5 kW: SIRIUS Innovations.

These new SIRIUS devices meet all requirements that have arisen in the field and can be used as individual devices, as modules for complete load feeders, or installed in low-voltage distribution boards or low-voltage switchgear. So no matter whether you want to configure load feeders with motor starter protectors or overload relays, contactors, or soft starters, SIRIUS has just the product you will need for any application.

#### 1.1.2 SIRIUS Innovations

#### SIRIUS stands for innovation

Siemens is constantly developing its product portfolio to enable it to meet the demands of industry, not only today, but in the future too. As part of this process, Siemens gathers customer feedback on an ongoing basis and considers it in conjunction with the global trends of tomorrow.

This manual underlines Siemens' claim to be a trendsetting company which offers you the very best products for switching, starting, protecting, and monitoring your motors and systems.

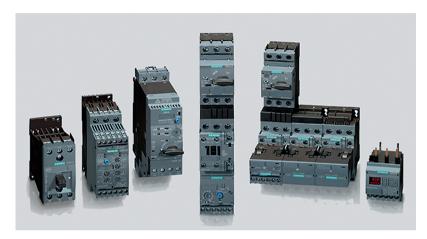


Figure 1-1 Innovations in the SIRIUS modular system

When coming up with these innovations for the SIRIUS modular system, particular importance was placed on reducing the amount of wiring needed, saving space, reducing the number of versions available, and providing operational reliability.

#### Simple and straightforward connection

The options for connecting to the higher-level control have now also been further improved: The SIRIUS modular system now not only features the AS-Interface, but also the IO-Link, which has been standardized as well. This ensures that switching devices can benefit from optimum interaction with our SIMATIC automation system and also with third-party controls.

The connection to the automation level is implemented via function modules, which are plugged onto contactors. However, these function modules are also available in a version for traditional parallel wiring, as well as in versions featuring AS-i or IO-Link interfaces. This simple version just contains the logic for performing the star-delta (wye-delta) functions of a feeder, for example. There is no longer any need to carry out laborious control circuit wiring work. The star-delta (wye-delta) times are set directly on the function module; all necessary interlocks are already integrated therein. The smaller width is not only due to the higher performance capability of the new devices, but also to the fact that the timing relay, for example, which used to be connected separately, has been done away with completely.

#### Monitoring in just a few short steps

More and more often, drives are being required to monitor complex processes or expensive machines to ensure they are functioning correctly. Previous solutions to such tasks involved quite a lot of wiring. That's why the current monitoring relay has been fully integrated in the main circuit in the new SIRIUS modular system. Designed like an overload relay, apparent or active current measuring can thus be added in just a few short steps; but phase sequence, phase failure, and other process-relevant data can also be evaluated too.

#### Reduced wiring

The infeed and power distribution options for a group of feeders has also been optimized in order to reduce the wiring in the main circuit. The SIRIUS 3RV29 infeed system now benefits, for example, from having a spring-loaded connection system available throughout, which means that whole groups of feeders can be assembled quickly and without the need for tools.

#### Minimized planning and configuration outlay

In order to reduce the effort involved in planning and configuration to a minimum, Siemens offers a range of Internet tools in addition to the standard documents in paper format. These tools can help you to select the most suitable product for your needs, to find the associated technical data quickly, and to put together the relevant technical documentation easily.

With its SIRIUS modular system switching devices in sizes S00 and S0, which have been completely redeveloped, Siemens can meet all requirements up to 32/40 A. This equates to over 80% of all typical applications.

#### Problem-free usage

With its versatile product range, the SIRIUS modular system offers technology which is suitable for use in all industries and all regions of the world. The products have been tested in accordance with common standards and have obtained the approvals required to ensure that they can be used anywhere in the world without any problems.

#### Flexible mounting options

The devices have been designed for installation on standard mounting rails ("DIN rails"), as well as for screw fixing. A whole range of link modules is available for easily connecting switching devices, both electrically and mechanically. These link modules are used to combine the individual components of the SIRIUS modular system together to create load feeders. If you make use of the spring-loaded connection system, this can even be done without the need for tools by simply plugging the different components together.

The spring-loaded connection system has now been extended to cover the entire product range of sizes S00 and S0 for the main circuit and the control circuit. The ring cable lug connection system is also available for use with particular applications and on request for certain regions.

## 1.2 Safety instructions

#### Five safety rules for work in or on electrical installations

A set of rules, which are summarized in DIN VDE 0105 as the "five safety rules", are defined for work in or on electrical installations as a preventative measure against electrical accidents:

- 1. Isolate
- 2. Secure against switching on again
- 3. Verify that the equipment is not live
- 4. Ground and short-circuit
- 5. Erect barriers around or cover adjacent live parts

These five safety rules must be applied in the above order prior to starting work on an electrical system. After completing the work, proceed in the reverse order.

It is assumed that every electrician is familiar with these rules.

#### **Explanations**

- The isolating distances between live and de-energized parts of the system must vary according to the operating voltage that is applied.
   In electrical installations, "isolate" refers to the disconnection of all poles of live parts.
   Disconnection of all poles can be achieved by, for example:
  - Switching off the miniature circuit breaker
  - Switching off the motor starter protector
  - Unscrewing fuses
  - Removing LV HRC fuses
- The feeder must be secured against inadvertent restarting to ensure that it remains isolated for the duration of the work. This can be achieved, for instance, by securing the motor starter protector and miniature circuit breaker with lockable blocking elements in the disconnected state, either using a lock or by unscrewing the fuses.
- 3. The deenergized state of the equipment should be verified using suitable test equipment, e.g. a two-pole voltmeter. Single-pole test pins are not suitable for this purpose. The absence of power must be established for all poles, phase to phase, and phase to N/PE.
- 4. Grounding and short-circuiting are only mandatory if the system has a nominal voltage greater than 1 kV. In this case, the system should always be grounded first and then connected to the live parts to be short-circuited.
- 5. These parts should be covered, or barriers erected around them, to avoid accidental contact during the work with adjacent parts that are still live.

## 1.3 Standards and approvals

## 1.3.1 Standards

The standards from Catalog IC 10 "SIRIUS Industrial Controls" in the appendix always apply. Below are some of the most important standards which apply to the innovations to the SIRIUS modular system.

### **Standards**

Table 1- 1 IEC/DIN EN/DIN VDE standards

IEC	DIN EN	DIN VDE	Title			
60947-1	60947-1	_	Low-voltage switchgear and controlgear: General rules			
60947-2	60947-2	_	Motor starter protectors			
60947-3	60947-3	_	Switches, disconnectors, switch-disconnectors and fuse-combination units			
60947-4-1	60947-4-1	_	Contactors and motor-starters: Electromechanical contactors and motor-starters			
60947-4-2	60947-4-2	_	Contactors and motor-starters: AC semiconductor motor controllers and starters			
60947-4-3	60947-4-3	_	AC semiconductor controllers and contactors for non-motorized loads			
	<u>.</u>	<u>.</u>	·			
60947-5-1	60947-5-1	_	Control circuit devices and switching elements: Electromechanical control circuit devices			
60947-6-2	60947-6-2	_	Multiple function equipment: Control and protective switching devices (or equipment) (CPS)			
60335-1	60335-1	_	Safety of household and similar electrical appliances - Part 1: General requirements			
_	50274	_	Low-voltage switchgear and controlgear assemblies - Protection against electric shock - Protection against unintentional direct contact with hazardous live parts			
	<u> </u>	<u> </u>				
60439-1	60439-1	_	Low-voltage switchgear and controlgear assemblies: Type-tested and partially type-tested assemblies			
_	50274	_	Low-voltage switchgear and controlgear assemblies - Protection against electric shock - Protection against unintentional direct contact with hazardous live parts			

#### 1.3 Standards and approvals

IEC	DIN EN	DIN VDE	Title
61140	61140	_	Protection against electric shock - Common aspects for installation and equipment
61000-4-1	61000-4-1	_	Electromagnetic compatibility (EMC); Part 4: Testing and measurement techniques; Section 1: Overview of IEC 61000-4 series
61000-6-3	61000-6-3	_	Electromagnetic compatibility (EMC); Generic standards - Emission standard for residential, commercial and light-industrial environments
61000-6-4	61000-6-4	_	Electromagnetic compatibility (EMC); Generic standards - Emission standard for industrial environments

Table 1- 2 UL/CSA/JIS standards

UL	CSA C22.2	ASME	JIS	Title		
UL 508	_	_	_	Industrial Control Equipment		
UL 489	_	_	_	Molded Case Circuit-Breakers, Molded Case Switche and Circuit Breaker Enclosures		
_	No. 14	_	_	Industrial Control Equipment		
_	No. 5	_	_	Molded Case Circuit-Breakers, Molded Case Switches, and Circuit Breaker Enclosures		
_	_	A17.5/B44.1	_	Elevator and Escalator Electrical Equipment		
_	_	_	C 8201-4-1	Low-Voltage Switchgear and Controlgear; Contactors and Motor-Starter		

## 1.3.2 Approvals, test certificates, characteristics

### Approvals, test certificates, characteristics

You can find an overview of the certifications available for low-voltage controls and distribution products and other technical documentation, updated daily, on the Internet (<a href="https://www.siemens.com/industrial-controls/support">www.siemens.com/industrial-controls/support</a>).

You can find further information in the appendix of Catalog IC 10 "SIRIUS Industrial Controls".

#### 1.4 Overview

#### 1.4.1 SIRIUS modular system

#### SIRIUS modular system

The SIRIUS product range comprises devices for use in switching, starting, protecting, and monitoring, as well as combinations thereof, which are known as "load feeders". Load feeders can be created from the following devices:

- 3RT/3RH contactors
- 3RF solid-state switching devices
- 3RW soft starters
- 3RV motor starter protectors
- Thermal (3RU) or solid-state (3RB) overload relays
- 3RR monitoring relays

Since all devices are matched to one both electrically and mechanically, they can be combined really easily to create load feeders. Alternatively, pre-assembled 3RA2 load feeders or 3RA6 compact starters are also available.

The devices named above are supplemented for the main circuit by devices for the control circuit: 3RA28 function modules for mounting on 3RT2 contactors and 3RA27 function modules for connection to the higher-level control.

			Size			
	Function	Components	S00	S0	S2	 S12
Main circuit	Switching and starting	Contactors		200	0000	To an analysis of the second s
		Solid-state switching devices	01	No.		
		Soft starters	14		200	 500

#### 1.4 Overview

			Size			
	Function	Components	S00	S0	S2	 S12
	Protecting	Motor starter protectors	000	000	9	
		Overload relays	12 de 15 de	- & 5 		
	Monitoring	Current monitoring relays				
	Feeders	Feeders				
		Compact starters	::0	24)		
Control circuit		Function modules for mounting on contactors	333200	-		
		Function modules for connection to the automation level	ASi	<b>IO</b> -Link		

## 1.4.2 SIRIUS Innovations manuals

This system manual focuses on the product descriptions of the SIRIUS Innovations in sizes S00 and S0 for motors in the performance range up to 18.5 kW (400 V). Products which have separate, device-specific manuals, are only briefly mentioned in this system manual. Comprehensive technical details for such devices can be found in the relevant device-specific manuals. You can download the manuals from the Internet (www.siemens.com/industrial-controls/manuals).

Information about	Is available in	
SIRIUS Innovations - System     Overview	"SIRIUS Innovations - System Overview" manual (Order number: 3ZX1012-0RA01-5AC1)	

Information about	Is available in
3RT2, 3RH2, and 3RA23/24 contactors and contactor assemblies	"SIRIUS Innovations - SIRIUS 3RT2 Contactors/Contactor Assemblies" manual (Order number: 3ZX1012-0RT20-5AB1)
3RF34 solid-state switching devices	"SIRIUS Innovations - SIRIUS 3RF34 Solid-State Switching Devices" manual (Order number: 3ZX1012-0RF34-5AC1)
3RW soft starters	Tild Saria
3RV2 motor starter protectors	"SIRIUS Innovations - SIRIUS 3RV2 Motor Starter Protector" manual (Order number: 3ZX1012-0RV20-5AC1)
3RU2, 3RB30/31 overload relays	"SIRIUS Innovations - SIRIUS 3RU2/3RB3 Overload Relays" manual (Order number: 3ZX1012-0RU20-5AC1)
3RB24 solid-state overload relay	"3RB24 Solid-State Overload Relay for IO-Link" manual (Order number: 3ZX1012-0RB24-0AC0)
3UG4 monitoring relays/ 3RR2 current monitoring relays	"3UG4/3RR2 Monitoring Relays" manual (Order number: 3ZX1012-0UG40-0AC0)
3RS1/3RS2 temperature monitoring relays	"3RS1/3RS2 Temperature Monitoring Relays" manual (Order number: 3ZX1012-0RS10-1AC1)
3UG48 monitoring relays	"3UG48 Monitoring Relay for IO-Link" manual (Order number: 3ZX1012-0UG48-0AC1)
3RS14/3RS15 temperature monitoring relays	"3RS14/3RS15 Temperature Monitoring Relay for IO-Link" manual (Order number: 3ZX1012-0RS14-0AC0)
3RA21/22 load feeders	"SIRIUS Innovations - SIRIUS 3RA21/3RA22 Load Feeders" manual (Order number: 3ZX1012-0RA21-5AC1)
3RA6 compact starters	"SIRIUS 3RA6 Compact Starter"     (http://support.automation.siemens.com/WW/view/en/27865     747) manual     (order number: 3RA6992-0A)
3RA28 function modules for mounting on contactors	"SIRIUS Innovations - SIRIUS 3RA28 function modules for mounting on 3RT2 contactors" (Order number: 3ZX1012-0RA28-5AC1)

Information about	Is available in
3RA27 function modules for connection to the higher-level control	Trunction Modules for AS-Interface" (http://support.automation.siemens.com/WW/view/en/39318 922) manual (order number: 3ZX1012-0RA27-0AC0)  Trunction Modules for IO-Link" (http://support.automation.siemens.com/WW/view/en/39319 600) manual (order number: 3ZX1012-0RA27-1AC1)
4SI SIRIUS electronic module (3RK1005-0LB00-0AA0)"	"4SI SIRIUS Electronic Module (3RK1005-0LB00-0AA0)"     manual     (http://support.automation.siemens.com/WW/view/en/37856     470)     (order no.:3ZX1012-0LB00-0AA1)

#### Reference

You can download the manuals from the Internet (<u>www.siemens.com/industrial-controls/manuals</u>).

Simply enter the order number of the relevant item into the search field.

Notes on further information (product information, product documentation, product selection, etc.) available on the Internet can be found in the chapter "More information (Page 193)".

#### **Correction sheet**

A correction sheet is included at the end of the manual. Please use it to record your suggestions for improvements, additions, and corrections, and return the sheet to us. This will help us to improve the next edition of the manual.

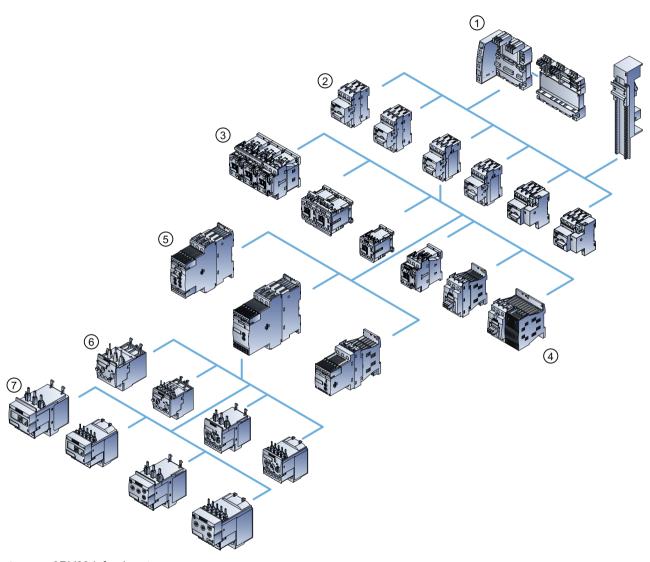
## 1.5 System properties

## 1.5.1 System properties

All the devices affected by the innovations in the SIRIUS modular system are available in two sizes (S00 up to 7.5 kW and S0 up to 18.5 kW at 400 V) and have a width of just 45 mm. The devices come with a uniform range of accessories for both sizes.

## 1.5.2 Modular system design

The individual SIRIUS Innovations components are modules from the complete SIRIUS modular system (up to size S12, 250 kW at 400 V), which are matched to one another in terms of their size and their technical data. This enables individual requirements to be met quickly and cost-effectively. And it goes without saying that this applies to the uniform range of accessories as well.



- 1 3RV29 infeed systems
- 2 3RV2 motor starter protectors
- 3 3RT2 contactors and contactor assemblies
- 4 3RF34 solid-state switching devices
- 5 3RW30/3RW40 soft starters
- 6 3RU2, 3RB3 overload relays
- 7 3RR2 current monitoring relays

Figure 1-2 Overview graphic (assembly in the control cabinet)

## 1.5.3 Switching technology

The SIRIUS modular system has the right technology for every application:

Table 1-3 Motor starting options

Application		Technology
Electromechanical starting	Direct-on-line start	3RT contactors, 3RA contactor assemblies, or 3RA6 compact starters
	Reversing start	<ul><li> 3RA reversing contactor assemblies</li><li> 3RA6 compact starters</li></ul>
	Star-delta (wye-delta) start	3RA contactor assemblies for star-delta (wye-delta) start
Electronic starting	Direct-on-line start	3RF solid-state switching devices
	Reversing start	3RF solid-state switching devices
	Soft start	3RW soft starters

#### Example: 3RT contactors, 3RA contactor assemblies, or 3RA6 compact starters

3RT contactors, 3RA contactor assemblies, or 3RA6 compact starters are used for all standard applications up to  $250\ kW.$ 

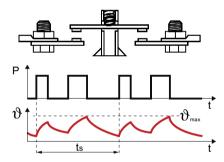


Figure 1-3 Direct switching through current feed of the contactor coil

#### Example: 3RF solid-state switching devices

3RF solid-state switching devices are used for frequent switching or reversing, of motors in parcel distribution systems, for example.

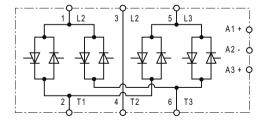


Figure 1-4 Two-phase switching through antiparallel thyristor pairs

#### **Example: 3RW soft starters**

3RW soft starters are used for soft starting and ramp-down, for pumps and fans, for example.

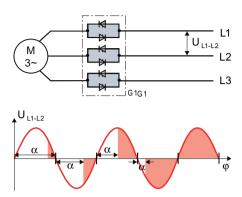


Figure 1-5 Phase angle control of the thyristor pairs

Technology selection depends on various factors. The table below provides an overview of the most important aspects:

Table 1-4 Technology selection

	Technology		
	Electromechanical	Electronic	
	3RT contactors, 3RA load feeders, or 3RA6 compact starters	3RF solid-state switching devices	3RW soft starters
		200	
Number of starts per hour	Average	High	Low
Switching service life	Average	Long	Average
Switching capacity	High	Low	High
Occurrence of current peaks	High	High	Low
Occurrence of torque peaks	High	High	Low
Reversing operation	Yes	Yes	No
Acoustic noise generation	Average	None	Low
Galvanic isolation	Yes	No	No
Shock and vibration resistance	Average	High	Average
Power loss	Low	High	Low

## 1.5.4 Uniform connection system

The devices are matched to one another in terms of their rated sizes and technical data.

- The same width guarantees quick mounting.
- Devices with the same rated current have the same terminals.
- Device combinations are matched to one another and offer screw-type, spring-loaded, and ring cable lug connection systems.

The SIRIUS modular system has the right connection system for every environment. The table below will help you to choose the right connection system:

Table 1-5 Connection systems

	Screw-type	Spring-loaded	Ring cable lug
Assembly/disassembl y time	Standard	Short	Long
Testing after transportation	Required	Not required	Required
Maintenance costs	Standard	Low	Standard
Contact reliability	Standard	High	Standard
Vibration/shock resistance	Standard	High	Standard
Ferrule required on conductor	Partially required	Not required	Required
Removal of the conductor	Standard	Easy	Laborious
Use of link modules	Standard	Easy: plug-in	Not possible
Available products	S00 to S12 (consistent)	S00 and S0 (consistent)	S00 and S0 (partially restricted)
Application frequency	80 %	15 %	5 %
Costs	Standard	Small surcharge	Standard

## 1.5.5 Flexible assembly methods

The SIRIUS modular system offers maximum flexibility in terms of configuration. The system components can be assembled as feeders or mounted separately.

Table 1-6 Assembly (mounted separately or assembled as feeders)

Separately mounted	Mounted as complete feeders
The system components are assembled	The system components are assembled as a unit
separately (e.g. on separate DIN rails).	(e.g. with a link module).

The SIRIUS modular system offers the right solution for every type of assembly:

Table 1-7 Assembly types

Assembly type	Benefit
Feeders assembled from individual SIRIUS devices	More than 40,000 tested combinations offer solutions for almost every application.
SIRIUS 3RA2 load feeders	More than 500 pre-assembled combinations facilitate rapid and fault-free control cabinet assembly.
SIRIUS 3RA6 compact starters	Compact devices with high integrated functionality for improved efficiency and reliability in the control cabinet.

## 1.5.6 Performance capability

All innovations in the SIRIUS modular system can be mounted side by side and operated at an ambient operating temperature of -25 °C to +60 °C. The SIRIUS modular system is optimally suited for applications in demanding environments (in terms of dust exposure, vibration and shock load; ATEX, etc.). All standard approvals have been obtained, making the system suitable for use all over the world. In 400 V systems, size S00 covers a performance range of up to 7.5 kW and size S0 up to 18.5 kW, with a width of just 45 mm. A short-circuit breaking capacity of up to 150 kA is available.

## 1.5.7 Assembly and mounting

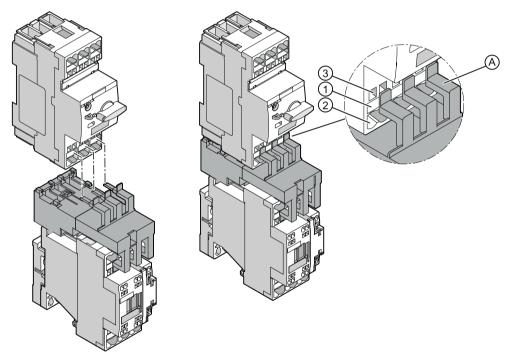
Accessories such as auxiliary switches and surge suppressors can be mounted quickly and disassembled in just a few short steps. Standard tools are required to disassemble components only very rarely. Siemens offers a standardized tool (screwdriver 3RA2908-1A) for disassembling conductors from spring-loaded terminals on all SIRIUS Innovations products.

#### 1.5.8 Load feeders

Link modules based on screw-type and spring-loaded connection systems are available for assembling device combinations and fuseless load feeders. The link modules establish the mechanical and electrical connections for the devices. Motor starter protectors can be combined with the following devices via link modules:

- Contactors
- Soft starter
- Solid-state switching devices

The SIRIUS Innovations products now also offer a "plug-in connection system" for assembling load feeders from devices with spring-loaded terminals. Contactors, solid-state switching devices, and soft starters can be connected to the motor starter protector by simply plugging them in via a link module:

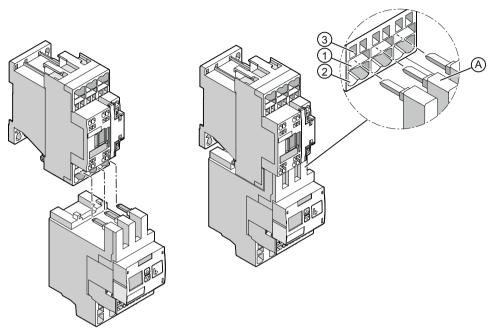


- A Link module
- 1 Slot for link modules
- Slot for conductor connection
- 3 Screwdriver opening for assembly/disassembly without a link module

Figure 1-6 Link module

The link module is first attached to the device to be connected, then the resulting unit is plugged on to the motor starter protector. This ensures that the requisite electrical and mechanical connections are established in the main circuit.

Overload relays and current monitoring relays can easily be attached to contactors and solidstate switching devices in a similar way, without the need for another link module:



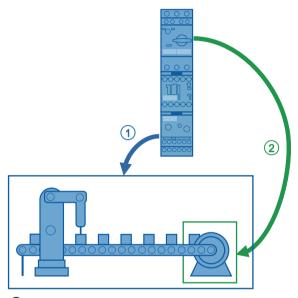
- A Current monitoring relay
- Slot for link modules
- Slot for conductor connection
- 3 Screwdriver opening for assembly/disassembly without a link module

Figure 1-7 Plug-in connection system on the current monitoring relay

## 1.5.9 Application monitoring

The current monitoring relays, which enable intelligent protective functions to be easily implemented within the application, are a central component of the innovations made to the SIRIUS modular system.

Increasing numbers of customers require application monitoring in addition to motor protection. Overload protection (based on I²t measuring/calculation) provides information on the motorized load, but it does not necessarily allow for conclusions to be drawn regarding the correct execution of processes within the machine. 2- or 3-phase current monitoring with SIRIUS 3RR2 current monitoring relays facilitates the direct monitoring and protection of the application.



- Application monitoring
- 2 Motor protection

Figure 1-8 Application monitoring

#### 1.5.10 Communication

SIRIUS switching devices can be connected to higher-level control systems using conventional wiring, but also by means of intelligent wiring and a fieldbus:

- IO-Link
- AS-Interface

SIRIUS switching devices are linked into the Siemens Totally Integrated Automation concept via function modules. Totally Integrated Automation offers the user uniformity in terms of configuration, programming, data storage, and communication.

SIRIUS switching devices are connected to the automation level via AS-Interface or IO-Link, without any additional wiring. These interfaces ensure that information about the switch position and the readiness of the feeder for operation is transferred, and that contactor control is implemented. In addition to these three items of information relating to feeders, IO-Link also transfers diagnostics data.

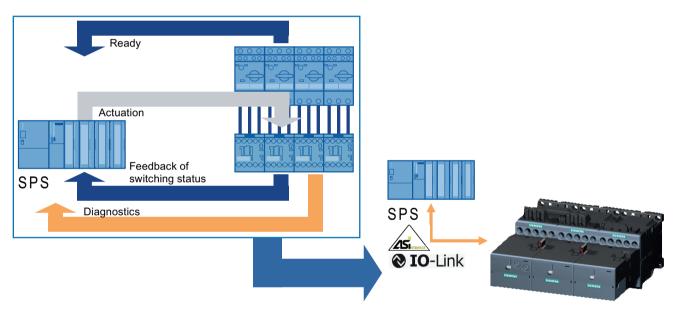


Figure 1-9 Communication via AS-Interface or IO-Link

## 1.5.11 Safety applications

SIRIUS switching devices are often used in parts of the system which have a bearing on safety. The Safety Integrated concept enables uniform solutions to be created, from safety relays through to fail-safe communication via AS-Interface or PROFIBUS DP.

#### Example

SIRIUS contactor in a safety application:

- Motor starter protectors in combination with undervoltage release and contactor: PL d (ISO 13849-1) or SIL 2 (IEC 62061)
- Contactor assemblies for star-delta (wye-delta) start:
   PL e (ISO 13849-1) or SIL 3 (IEC 62061)

## 1.5.12 Environmental protection

Siemens attaches great importance to the subject of eco-design. Our company-internal standard SN 36350 on environmentally compatible product design has been permanently integrated in our product development processes since 1993. Our production meets the highest quality and environmental standards.

The CO<sub>2</sub> balance is another important topic as regards the manufacturing processes used for our products. All Siemens products are eco-labeled in accordance with DIN EN ISO 14021 as a matter of course. This process of eco-labeling makes our environmentally-compatible product design more transparent and ensures that a continual improvement in the CO<sub>2</sub> balance can be observed.

## 1.5.13 Energy efficiency

#### 1.5.13.1 Energy efficiency

The **SIRIUS** modular system offers products that significantly reduce energy consumption in the control cabinet thanks to their minimum intrinsic power losses. The modular system includes devices that not only switch reliably, but also measure energy and thus supply solutions for energy-optimized drive concepts.

Energy efficiency increases resulting from the use of SIRIUS Innovations can be divided into three topic areas:

- Acquisition of measured energy values
- Reduction in intrinsic power losses
- Optimal drive solution

These three pillars form the basis of optimized energy management with the support of SIRIUS Innovations.

### 1.5.13.2 Acquisition of measured energy values

#### Acquisition of measured energy values (identification of energy flows)

One of the essential starting points for increasing energy efficiency is the acquisition of energy flows through detailed analysis of the machinery and systems used. You can do without installing additional measuring instruments if you use switching devices with integral current acquisition and communication interface at the planning phase, e.g. motor starters of the SIMATIC ET 200S distributed I/O device. These switching devices can transfer the up-to-date current value to the higher-level controller via PROFIBUS or PROFINET. With overload relays for IO-Link, monitoring relays for IO-Link, the SIMOCODE motor protection and control device, or the SIRIUS 3RW44 soft starter, further additional measured values such as voltage and power values can be acquired and transferred. Like the ET 200S motor starter and the High Feature motor starter, the M200D motor starter in degree of protection IP65 offers current values in the standard format of the PROFlenergy profile. This simplifies integration into energy management systems. The measured values of the actuators – thus simultaneously serving as sensors – can be dragged and dropped to the visualization system of the energy data.

Thanks to evaluation and analysis of the measured current values, energy management systems are able to make an assessment of the current situation and thus shut down individual load groups or consumers.

#### 1.5.13.3 Reduction in intrinsic power losses

#### Reduction in intrinsic power losses (calculation of potential savings)

Each device installed in a control cabinet produces a power loss. For example, devices with integral power electronics (e.g. soft starters) are already burdened with higher power losses than non-solid-state power contactors. Significantly higher power losses are sustained when using frequency converters.

The power loss can be perceived in the form of heat that usually has to be minimized with high energy consumption using, for example, fans or air conditioners requiring regular maintenance. By using SIRIUS soft starters, the power semiconductors are bypassed after the power-up phase with the help of bypass contacts. This reduces the resulting heat losses to a minimum.

When using **SIRIUS** contactors, the potential savings in the main circuit are extremely low since the electromechanical contacts generate very low intrinsic heat losses. The savings potential is to be found in the control circuit where the pickup currents and holding currents of conventional AC coils or DC coils are reduced by up to 92% thanks to modern control electronics.

The control electronics of these contactors with electronic operating mechanism (UC drive) offer the following benefits:

- Smaller power supply units in the control circuit thanks to significantly reduced pickup currents and holding currents
- Control optionally with DC voltage or AC voltage
- Reduced stockkeeping thanks to wide voltage ranges
- Control by 0.5 A outputs of the controller
- Avoidance of overvoltage damage in the control electronics thanks to integral suppressor circuit

In the sphere of influence of IEC standards, **fuseless** design of **load feeders** has become established. The preferred method of protecting plants, cables and motors is to use circuit breakers or motor starter protectors with conventional electromechanical design. The protective function against overload is performed with the help of bimetal strips with low heat losses. These losses are reduced by up to 20% on the SIRIUS Innovations (size S0) thanks to the use of modern materials, so that it has been possible to increase the maximum settable current from 25 A to 40 A.

The current setting ranges of the **SIRIUS motor starter protectors** overlap (size S00: 11 ... 16 A and size S0: 14 ... 20 A). If the user requires, for example, a motor starter protector for a 7.5 kW IE2 motor ( $I_N = 14.7$  A), the size S0 motor starter protector is the obvious choice since the intrinsic power losses can be reduced by up to 40% thanks to the low setting of the overload protection.

As well as the widespread use of fuseless load feeders, the following reasons speak in favor of the design with SIRIUS overload relays (thermal or electronic):

- Differentiation of the signals for overload and short-circuit
- Extremely high short-circuit breaking capacity in high rated operating voltage ranges in combination with fuses

Further benefits result from the use of solid-state overload relays instead of the widely used thermal overload relays:

- Wide setting range of the rated operational current of up to 1:10
- Adjustable tripping classes (also suitable for heavy starting)
- Remote reset after overload tripping

Thanks to the use of the solid-state overload relays and the fact that there is no need for the motor starter protector, power losses are reduced by up to 98%. This reduction in intrinsic heat buildup can significantly simplify air-conditioning in the control cabinet, particularly with compact constructions.

The **SIRIUS** compact starter represents a new class of energy-efficient switching devices. The combination of motor starter protector, contactor and solid-state overload relay in one enclosure, and the specified benefits of each individual device result in savings in intrinsic power losses of up to 80% compared to conventional load feeders.

Consistent use of energy-efficient switching devices allow significant reductions in the intrinsic losses of the devices and the associated measures for heat dissipation in the control cabinet. This essential benefit affects not only power costs but also the availability of the plant.

#### 1.5.13.4 Optimal drive solution

#### Optimal drive solution (specific measures for realizing potential energy savings)

Three-phase induction motors have a substantial responsibility for the power of a machine. These motors can be operated in the most diverse ways. While the optimal area of application of the frequency converters is in closed-loop speed control, soft starters specialize in the regulation of current and torque during start-up and run-down. In combination with the contactor-based motor starters and load feeders, soft starters have a cost-optimized design for long operating periods at rated speed of the motors.

In such applications, the obvious choice is the combination with motors of Energy Efficiency Class 2 (IE2) or high-efficiency motors of Energy Efficiency Class 3 (IE3). These motors have especially low power losses in operation and thus improve the energy balance.

The power losses of the devices increase as the functionality increases. Choosing an optimal drive solution requires economic dimensioning of the motor power to avoid generating high losses with overdimensioned motors and later having to adapt an overdimensioned application to low requirements using a frequency converter. Simple closed-loop control methods, such as two-step controllers, usually represent an ecologically better and economically more favorable alternative.

Further savings potential, e.g. with pumps, fans or compressors, the obvious choice is a combination of a cascaded frequency converter and switching devices. In this case, the switching devices cover the basic load requirements of the plant, and the frequency converter covers the variable proportion of the application. This means the following benefits of both drive systems can be optimally exploited:

- Very user-friendly closed-loop control
- Low intrinsic energy losses with simultaneously high efficiency

#### 1.5.13.5 Energy efficiency examples

The devices which make up the SIRIUS modular system are designed for minimum power loss, and passively and actively support the realization of efficient systems and applications.

The SIRIUS Innovations devices have an average 10% lower intrinsic power loss so that as well as saving on energy costs, the heat generated in the control cabinet can also be reduced. This enables a higher packing density in the control cabinet and reduces the cooling capacity.

The following examples show the reduction in intrinsic power loss compared to the predecessor devices.

#### Product example soft starters

- Reduction of peak loads by up to 60%.
  - The soft starter protects the connected products and systems both on the connection and drive sides.
- Minimum intrinsic power loss thanks to integrated bypasses.
  - The complete soft starter portfolio bridges the thyristors during operation by means of bypasses and thus enables the intrinsic power loss to be reduced to contactor level.
  - 1 W power loss requires 3 W cooling expenditure. Typical frequency converters generate a power loss which is 30 times higher than that created by a comparable soft starter (bypass operation) and thus require 90 times the cooling expenditure.
- The most space-saving starter ever.
  - Volume reduction compared to typical contactor assemblies for star-delta (wye-delta) start: 66 %.
  - Volume reduction compared to typical frequency converters: up to 98%.

#### Product example contactors

- Minimized holding and closing power.
  - The aspects of low power loss and further optimization of the holding and closing power ratings played an important role in the development of SIRIUS contactors.
  - SIRIUS contactors with electronically controlled coils support further reduction of the holding power by up to 90%.
  - All SIRIUS contactors can be used on the Chinese market, as they meet the Chinese energy efficiency standard GB 21518-2008 for AC contactors in accordance with "Grade 2". The contactors thus far exceed the minimum requirement ("Grade 3") and are optimally equipped for the future.

#### Product example compact starters

- Only one switching point for minimized losses on the current path.
  - Thanks to the combined functions of a solid-state overload relay, a motor starter protector, and a contactor in a single device, transfer resistances (switching points, cable transitions, etc.) are reduced to a minimum.

#### 1.6 Customer benefits

### Product example overload relays

- Electronics instead of bimetal for minimized intrinsic power loss.
  - In addition to a wide setting range of up to 1:10, the application of electronic sensors and actuators facilitates intrinsic power loss reductions of more than 98%.
- Optimized thermal release (bimetal).
  - For devices with thermal overload relay, the power loss compared to predecessor products is reduced by 5 to 10% thanks to the optimized bimetal release.

#### 1.6 Customer benefits

#### **Customer benefits**

SIRIUS offers benefits in the following areas:

- · Assembly and handling
- Planning and configuration
- Connection to the automation level
- System monitoring

Table 1-8 Customer benefits

Area	Technical highlights	Customer benefits
	Proven and optimized modularity and functional diversity in the SIRIUS modular system	Maximum flexibility for application-oriented solutions
	Performance increase with unchanged size, functions which are already integrated, and "all-in-one" solution with compact starters	Space savings in the control cabinet
	Reduced variance, e.g. thanks to size- independent accessories and wide voltage and wide setting ranges	Reduced storage costs as well as planning and ordering expenditure
Assembly and handling	<ul> <li>Integrated spring-loaded connection system</li> <li>Assembly of starters with plug-in connection system</li> </ul>	Reduced wiring expenditure and fault avoidance in terms of assembly and handling
	Corresponding infeed systems and integrated functionalities	

Area	Technical highlights	Customer benefits
System monitoring	Monitoring relays and function modules for extremely simple application monitoring	Operational reliability and system availability
	End-of-lifetime detection for 3RA6 compact starter	
	Comprehensive diagnostics messages	
Connection to the automation level	Easy connection to AS-i or IO-Link	Optimum integration in the automation environment (TIA)
Planning and configuration	<ul><li>Comprehensive planning and configuration tools</li><li>Numerous approvals</li></ul>	<ul><li>Simplified system planning and documentation</li><li>Global applicability</li></ul>
	Numerous combination tests for SIRIUS	

SIRIUS offers the perfect solution throughout the entire product lifecycle:

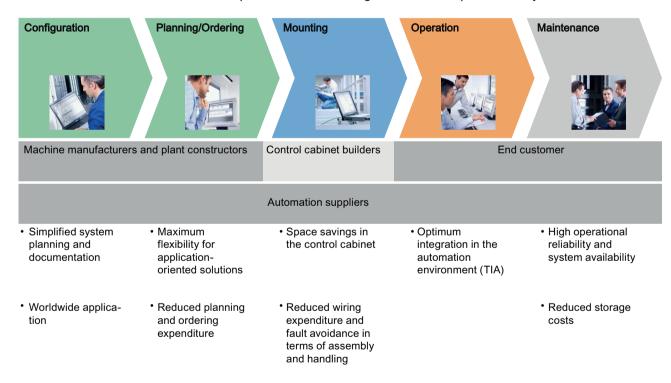


Figure 1-10 Customer benefits by product lifecycle

# 1.7 Components and combinations

# 1.7.1 Switching and starting

## 1.7.1.1 SIRIUS 3RT2 contactors

## 3RT2 contactors



Figure 1-11 S0 contactor

SIRIUS 3RT2 contactors and contactor assemblies offer maximum flexibility in terms of dimensioning, handling, and function:

Table 1-9 3RT2 contactors and contactor assemblies

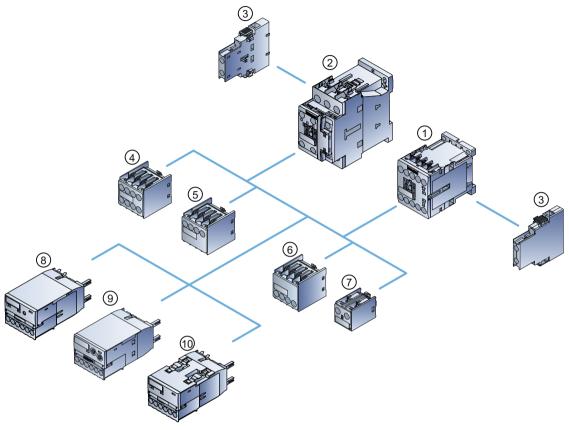
Area	Customer benefits
Functions	Power contactors (motors, resistive loads) and contactor relays
	Conventional (S00 and S0) and electronic drive (S0 only; reduced power consumption)
	Function modules for mounting on contactors and for connection to the automation level (AS-i/IO-Link)
	Reversing contactor: space-saving mechanical interlock for S00 and S0
Dimensioning and design	Performance increase: S00 (7.5 kW, 16 A), S0 (18.5 kW, 38 A)
	Width 45 mm
	Integrated auxiliary switches in both S00 and S0
	Auxiliary switches in identical design for S00 and S0
	Screw-type, spring-loaded, and ring cable lug connection systems, plus solder pin connection system (S00 only)

Area	Customer benefits
Mounting advantages	Contactor assemblies (for star-delta (wye-delta) start, reversing contactor assembly, 2 contactors in series)
	Contactor assembly for star-delta (wye-delta) start:
	- Up to 22 kW
	<ul> <li>Control circuit wiring integrated in function modules, incl. electrical and mechanical interlock</li> </ul>
	Easy assembly of contactor assemblies and feeders by means of link modules for screw-type and spring-loaded terminals
	Integrated cable duct for feeder-oriented assembly (with S0)
Application areas/customer benefits	Easy connection of feeders to the automation level via AS-Interface or IO- Link
	Performance increase up to 18.5 kW in 45 mm width
	Safety applications: Motor starter protectors in combination with
	<ul> <li>Undervoltage release and contactor usable in PL d/SIL 2</li> </ul>
	<ul> <li>Star-delta (wye-delta) starter usable in PL e/SIL 3</li> </ul>
	Comprehensive approvals for global applicability

# Reference

More information	Is available in
	the chapter "SIRIUS 3RT2, 3RH2, 3RA23/3RA24 contactors/contactor assemblies (Page 97)".

# Fitting of auxiliary switches on 3RT2 contactors (size S00 and S0)



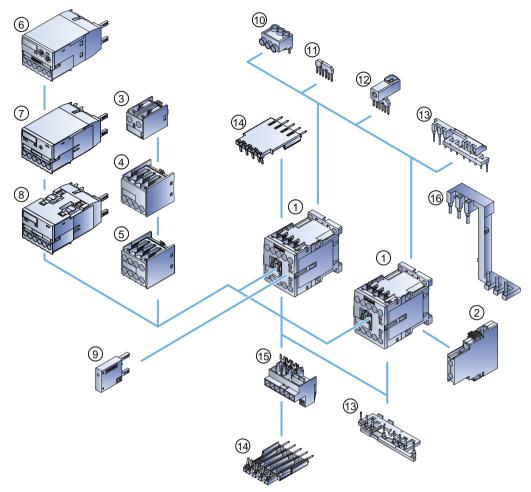
- 1 Contactor size S00
- 2 Contactor size S0
- 3 Laterally mountable auxiliary switch block (right or left), 2-pole
- 4 Auxiliary switch block for snapping onto the front, 4-pole
- 5 Auxiliary switch block for snapping onto the front, 2-pole (cable entry from above)
- 6 Auxiliary switch block for snapping onto the front, 2-pole (cable entry from below)
- Auxiliary switch block for snapping onto the front, 1-pole (cable entry from above or below)
- 8 Function module for AS-Interface, direct-on-line start
- 9 3RA28 function modules
- 10 Function module for IO-Link, direct-on-line start

Figure 1-12 Fitting of auxiliary switches on 3RT2 contactors (size S00 and S0)

#### Note

Combining 2-pole auxiliary switches for mounting on the front with a lateral auxiliary switch is not permitted.

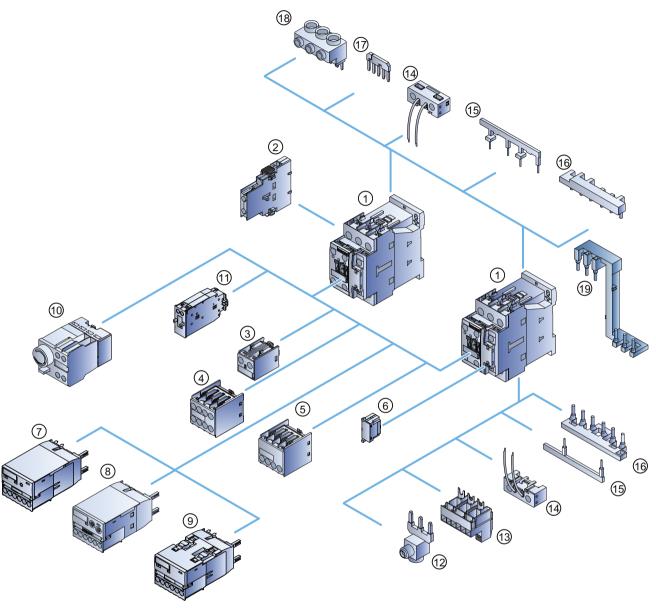
## Size-specific accessories for 3RT2 contactors (size S00)



- 1 Contactor size S00
- 2 Laterally mountable auxiliary switch block (right or left), 2-pole
- 3 Auxiliary switch block for snapping onto the front, 1-pole (cable entry from above or below)
- 4 Auxiliary switch block for snapping onto the front, 2-pole (cable entry from above or below)
- 5 Auxiliary switch block for snapping onto the front, 4-pole
- 6 3RA28 function modules
- 7 Function module for AS-Interface, direct-on-line start
- 8 Function module for IO-Link, direct-on-line start
- 9 Surge suppressor
- 10 3-phase infeed terminal
- 11 Star jumper, 3-pole, without connection terminal
- 12 Parallel switching connector, 3-pole or 4-pole, with connection terminal
- 13 Wiring modules on the top and bottom, for connecting the main and control current paths
- 14 Solder pin adapter
- 15 Terminal module (adapter) for contactors with screw connections
- 16 Safety main circuit connectors for 2 contactors

Figure 1-13 Size-specific accessories for 3RT2 contactors (size S00)

# Size-specific accessories for contactors (size S0)



- 1 Contactor size S0
- 2 Laterally mountable auxiliary switch block (right or left), 2-pole
- 3 Auxiliary switch block for snapping onto the front, 1-pole (cable entry from above or below)
- 4 Auxiliary switch block for snapping onto the front, 4-pole
- 5 Auxiliary switch block for snapping onto the front, 2-pole (cable entry from above or below)
- 6 Surge suppressor
- 7 Function module for AS-Interface, direct-on-line start
- 8 3RA28 function modules
- 9 Function module for IO-Link, direct-on-line start
- 10 Pneumatic delay block
- 11 Mechanical latch

- 12 Parallel switching connector
- 13 Terminal module (adapter) for contactors with screw connections
- 14 Coil terminal module, top and bottom
- Wiring modules, top and bottom, for connecting the control current paths
- Wiring modules, top and bottom, for connecting the main current paths
- 17 Star jumper, 3-pole, without connection terminal
- 18 3-phase infeed terminal
- 19 Safety main circuit connectors for 2 contactors

Figure 1-14 Size-specific accessories for 3RT2 contactors (size S0)

# 1.7.1.2 SIRIUS 3RF34 solid-state switching devices

# 3RF34 solid-state switching devices



Figure 1-15 Solid-state switching device

SIRIUS 3RF34 solid-state switching devices feature a heat sink integrated in the insulated enclosure, so no grounding is required.

Table 1- 10 3RF34 solid-state switching devices

Area	Customer benefits
Functions	<ul> <li>Instantaneous switching solid-state contactors for motor switching</li> <li>Direct-on-line and reversing contactor (integrated electric interlock).</li> </ul>
Dimensioning and design	<ul> <li>S0 (0.5 to 16 A)</li> <li>Width 45 mm (2.2 kW/5.4 A) or 90 mm (7.5 kW/16 A)</li> <li>24 V DC and 110 to 230 V AC</li> <li>Rated voltage up to 600 V</li> <li>Insulated enclosure</li> <li>Optimized sizing and few power versions up to 7.5 kW</li> <li>Screw-type and spring-loaded terminals</li> </ul>

# 1.7 Components and combinations

Area	Customer benefits
Mounting	Combination with protection devices and monitoring devices
advantages	Side-by-side assembly possible
	Easy connection to the motor starter protector by means of link module
	Connection option for solid-state overload relay or current monitoring relay
	Removable terminals for auxiliary circuit wiring
Application areas/customer benefits	Wear- and noise-free operation for frequent motor switching
	Long service life (over 100 million operating cycles)
	Comprehensive approvals for global applicability

# Reference

More information	Is available in	
about SIRIUS 3RF34 solid-state switching devices	the chapter "SIRIUS 3RF34 solid-state switching devices (Page 111)".	

## 1.7.1.3 SIRIUS 3RW30/40 soft starters

## 3RW30/40 soft starters



Figure 1-16 S0 soft starter

The SIRIUS 3RW30 soft starters for standard applications in 200 to 480 V systems (3RW40: 200 to 600 V) provide basic functionalities at cost-optimized prices:

Table 1- 11 3RW30/40 soft starters

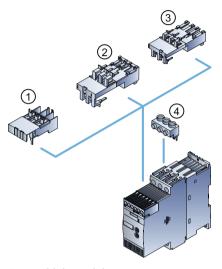
Area	Customer benefits
Functions	<ul> <li>Soft starting for simple startup conditions</li> <li>Integrated bypass contact system</li> <li>Integrated protection functions for motor starter and soft starter (3RW40)</li> <li>Two-phase "polarity balancing" control method (consistently up to 250 kW)</li> <li>Thermistor motor protection (optional with 3RW40)</li> <li>Settable current limiting (3RW40)</li> </ul>
Dimensioning and design	Performance increase of 2 performance classes in smaller sizes:  S00 up to 17.6 A  S0 up to 38 A  S2 up to 72 A  45 mm width (18.5 kW/38 A)  Screw-type and spring-loaded terminals
Mounting advantages	<ul> <li>Easy commissioning and maintenance</li> <li>Matched with the SIRIUS modular system</li> <li>Easy retrofitting with wiring already installed</li> <li>Parameterizable output (3RW40)</li> </ul>
Application areas/customer benefits	<ul> <li>Considerable power savings through integrated bypass contact system</li> <li>Adjustable tripping classes (3RW40)</li> <li>Integrated diagnostics functions (3RW40)</li> <li>Comprehensive approvals for global applicability, also ATEX (3RW40)</li> </ul>

# 1.7 Components and combinations

#### Reference

More information	Is available in
about SIRIUS 3RW30/40 soft starters	the chapter "SIRIUS 3RW30/3RW40 soft starters (Page 121)".

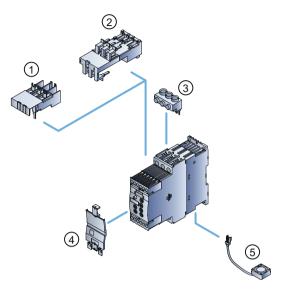
## Accessories for 3RW30 soft starters



- 1 Link module to motor starter protector with screw-type terminals
- 2 Link module to motor starter protector with spring-loaded terminals (size S0)
- 3 Link module to motor starter protector with spring-loaded terminals (size S00)
- 4 Infeed terminal (sizes S00 and S0)

Figure 1-17 Accessories for 3RW30 soft starters

# Accessories for 3RW40 soft starters



- 1 Link module to motor starter protector with screw-type terminals
- 2 Link module to motor starter protector with spring-loaded terminals
- 3 Infeed terminal
- 4 Sealing cover
- 5 Fan for increased switching frequency

Figure 1-18 Accessories for 3RW40 soft starters

# 1.7.2 Protecting

# 1.7.2.1 SIRIUS 3RV2 motor starter protectors

# 3RV2 motor starter protectors



Figure 1-19 Motor starter protector S0

SIRIUS 3RV2 motor starter protectors can be combined with other SIRIUS devices easily and flexibly, while also saving on space and wiring:

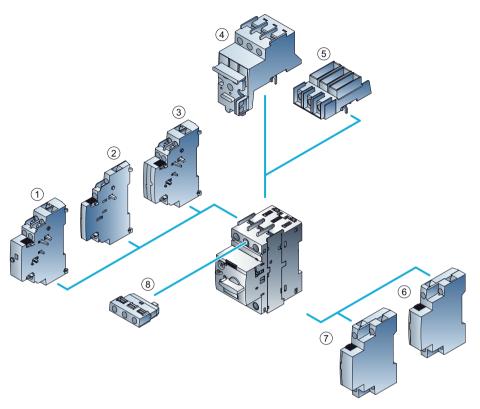
Table 1- 12 3RV2 motor starter protectors

Area	Customer benefits
Functions	<ul> <li>Short-circuit protection, overload protection, switching (manual), isolation</li> <li>Fuseless</li> <li>Motor protection, starter protection, system protection, and transformer protection</li> </ul>
Dimensioning and design	<ul> <li>S00 and S0 (up to 40 A in a width of only 45 mm)</li> <li>Choice of connection systems: <ul> <li>Screw-type terminals</li> <li>Spring-loaded terminals</li> <li>Ring cable lugs</li> </ul> </li> </ul>
Mounting advantages	Easily and rapidly combinable with any SIRIUS switching device     Reduced main circuit wiring through combination with:     SIRIUS infeed system     3-phase busbar system     Infeed system for 3RA6 compact starters     8US busbar system
Application areas/customer benefits	<ul> <li>Minimized space requirements</li> <li>Reduced power consumption</li> <li>Global applicability thanks to comprehensive approvals</li> </ul>

#### Reference

More information	Is available in
•	the chapter "SIRIUS 3RV2 motor starter protectors (Page 135)".

# Accessories for 3RV2 motor starter protectors

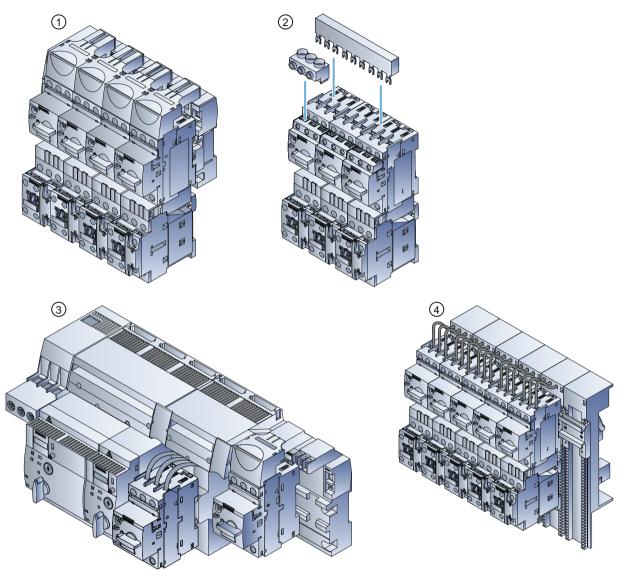


- 1 Signaling switch
- 2 Lateral auxiliary switch with 2 contacts
- 3 Lateral auxiliary switch with 4 contacts
- 4 Disconnector module
- 5 Terminal block type E
- 6 Undervoltage release
- 7 Shunt release
- 8 Transverse auxiliary switch

Figure 1-20 Accessories for 3RV2 motor starter protectors

# Infeed systems

The SIRIUS modular system has the right infeed for every requirement.

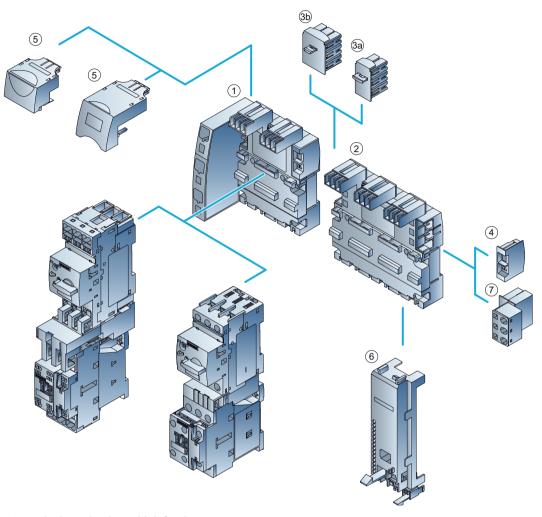


- 1 SIRIUS infeed system (3RV2917)
- 2 3-phase busbar system (3RV1915)
- 3 Combination of 3RA68 infeed system for compact starter and 3RV2917 infeed system for motor starter protector
- 4 Busbar system (8US)

Figure 1-21 Infeed systems

# 1.7.2.2 SIRIUS 3RV2917 infeed system

# 3RV2917 infeed system



- 1 3-phase busbar with infeed
- 2 3-phase busbar for system expansion
- 3 Expansion plug
- 4 End cap
- 5 Connector
- 6 Contactor base
- 7 Outgoing terminal

Figure 1-22 3RV2917 infeed system

# 1.7.2.3 SIRIUS 3RU2/3RB3 overload relays

# 3RU2/3RB3 overload relays



Figure 1-23 S0 overload relay

The thermal and solid-state overload relays are available in the modular system with graded functionality, which reflects their flexible applicability.

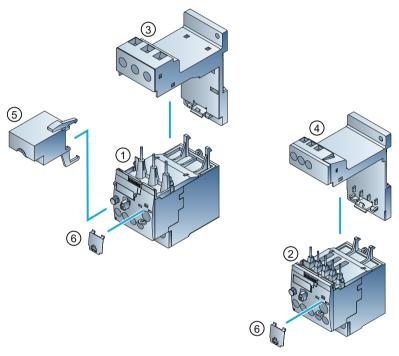
Table 1- 13 3RU2/3RB3 overload relays

Area	Customer benefits
Functions	<ul> <li>Current-dependent motor protection</li> <li>Modular system: Graded functionality for individual requirements</li> <li>Integrated temperature compensation</li> <li>Integrated remote reset with 3RB31</li> </ul>
Dimensioning and design	<ul> <li>Performance increase: <ul> <li>S00 (7.5 kW/16 A)</li> <li>S0 (18.5 kW/up to 40 A)</li> </ul> </li> <li>45 mm width (40 A)</li> <li>Large wide setting range of 1:4 with 3RB3</li> <li>High long-term stability through special bimetals with 3RU2</li> <li>Matched and uniform accessories for thermal and solid-state overload relays</li> <li>Screw-type, spring-loaded, ring cable lug connection system (only with 3RU2)</li> </ul>
Mounting advantages	<ul> <li>Optional direct mounting on contactor or stand-alone assembly</li> <li>Removable terminals for control circuit wiring (3RB3)</li> <li>Same stand-alone assembly support for 3RU2 and 3RB3, with screw-type and spring-loaded connection systems</li> </ul>
Application areas/customer benefits	<ul> <li>98% lower power consumption than conventional solutions (3RB3)</li> <li>Lower power loss compared to predecessor (5 to 10% with 3RU2)</li> <li>Optimum adjustability to the motor current: overlapping ranges up to 60°C, above that up to 70°C without overlapping</li> <li>Comprehensive approvals for global applicability (e.g. ATEX)</li> </ul>

## Reference

More information	Is available in
about the SIRIUS 3RU2/3RB3 overload relays and the 3RB24 solid-state overload relays for IO-Link	the chapter "SIRIUS 3RU2/3RB3, 3RB24 overload relays (Page 141)".

# Accessories for 3RU2 and 3RB30/31 overload relays



- 1 Overload relay size S0
- 2 Overload relay size S00
- 3 Stand-alone assembly support, size S0
- 4 Stand-alone assembly support, size S00
- 5 Electrical remote reset, sizes S00 and S0 (3RU2 only)
- 6 Sealing cover, sizes S00 and S0

Figure 1-24 Accessories for 3RU2 and 3RB30/31 overload relays

# 1.7.3 Monitoring

# 1.7.3.1 SIRIUS 3RR2 current monitoring relays

# 3RR2 current monitoring relays



Figure 1-25 S0 current monitoring relays

The SIRIUS 3RR2 current monitoring relays are ideally suited to a range of applications, thanks to the flexible way in which they can be adjusted:

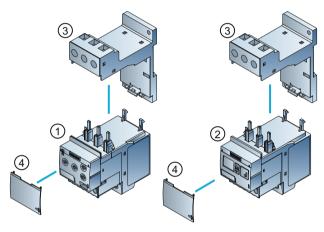
Table 1- 14 3RR2 current monitoring relays

Area	Customer benefits	
Functions	Analog or digital setting	
	Overcurrent and undercurrent monitoring	
	Phase sequence, phase failure, and fault current monitoring	
	Apparent or active current monitoring	
	Freely parameterizable threshold values and delay times	
	Manual and automatic reset	
Dimensioning and	S00, S0 (1.6 up to 40 A with only two versions)	
design	• 24 V AC/DC, 24 to 240 V AC/DC	
	160 to 690 V wide voltage range in the main circuit	
	• 45 mm width (40 A)	
	1 CO contact and 1 semiconductor output	
	Clear status signals on the display	
	Screw-type and spring-loaded terminals	
Mounting	Removable terminals for auxiliary circuit wiring	
advantages	Direct mounting on contactor	
	Same stand-alone mounting support as with overload relays	
Application	One device for overload and underload monitoring	
areas/customer benefits	Integrated assembly:	
benefits	<ul> <li>Reduced wiring</li> </ul>	
	No separate transformers required	
	<ul> <li>3-phase current monitoring with further monitoring options</li> </ul>	
	Current monitoring relay for feeder-integrated load monitoring	
	Detection of fast and substantial, as well as slight and "subtle" changes	

## Reference

More information	Is available in
about the SIRIUS 3RR2 current monitoring relays, 3UG4 monitoring relays, 3UG48 monitoring relays for IO-Link, 3RS1/3RS2 temperature monitoring relays, and 3RS14/3RS15 temperature monitoring relays for IO-Link	the chapter "SIRIUS 3UG4/3RR2, 3RS1/3RS2, 3UG48, 3RS14/3RS15 monitoring relays (Page 153)".

# Accessories for 3RR2 current monitoring relays



- 1 3RR21 current monitoring relays
- 2 3RR22 current monitoring relays
- 3 Stand-alone mounting support
- 4 Sealing cover

Figure 1-26 3RR2 current monitoring relays

## 1.7.4 Feeders

# 1.7.4.1 SIRIUS 3RA21/22 load feeders

## Load feeders



Figure 1-27 S0 load feeder

The tested load feeders offer switching and protection functions. Thanks to their multiple combination options, they can be easily configured for almost any requirement.

Table 1- 15 Load feeders

Area	Customer benefits
Functions	Switching and protection functions in one mechanical unit
	High short-circuit breaking capacity
	Tested combinations (fuseless and fused)
	Coordination types 1 and 2 (tested up to 150 kA)
	Tested for CLASS 10, 20, 30
	With motor starter protectors or MSPs for starter combinations
	With contactor, solid-state contactor, and soft starter
	Connection to the automation level via IO-Link and AS-i
Dimensioning and	Tested for all common line voltages
design	• S00, S0 (0.06 up to 18.5 kW)
	Pre-assembled SIRIUS 3RA2 feeders with 230 V AC and 24 V DC
Mounting	Easy mounting of individual components into tested combinations
advantages	Direct connection of switching devices
	Perfectly matched accessories
	Screw-type, spring-loaded, ring cable lug connection systems
Application	Completely pre-assembled load feeders
areas/customer benefits	Comprehensive type tests for load feeders for self-assembly by the customer (approx. 40,000 combinations)
	Comprehensive approvals for global applicability
	Comprehensive dimensioning, planning, and construction support

#### Accessories for load feeders

The main accessories for 3RV2 motor starter protectors, and those for 3RT2 contactors (such as side-mounted and transverse auxiliary switches, current limiters, undervoltage limiters, rotary operating mechanisms, busbar adapters, etc.) can be used for 3RA21/22 load feeders and feeders for self-assembly.

# 3RA21/22 pre-assembled load feeders

The 3RA21/22 fuseless load feeders can be ordered as a complete device for direct-on-line starting or reversing operation. Sizes S00 and S0 are both available with either screw-type or spring-loaded connection systems.

#### Reference

More information	Is available in
about SIRIUS 3RA21/22 load feeders	the chapter "SIRIUS 3RA21/22 load feeders (Page 165)".

#### 1.7.4.2 SIRIUS 3RA6 compact starters

#### 3RA6 compact starter



Figure 1-28 Compact starter

The SIRIUS 3RA6 compact starter is a compact, highly integrated device which features state-of-the-art controls, including practical diagnostics functions. The compact starter ensures improved efficiency and reliability in the control cabinet.

# 1.7 Components and combinations

Table 1- 16 3RA6 compact starters

Area	Customer benefits
Functions	Direct-on-line starter and reversing starter
	Short-circuit protection, electronic overload protection, functional switching, and line protection
	Mechanical and electrical interlock with reversing starter
	IO-Link and AS-i connection
	Manual and automatic reset (remote reset via control)
Dimensioning and	• S0 (0.1 up to 32 A/15 kW)
design	Width of 45 mm (direct-on-line starter) or 90 mm (reversing starter)
	5 setting ranges from 0.1 A to 32 A
	Weld-free contacts (end-of-service-life indication)
	Screw-type and spring-loaded connection systems with removable terminals in the main and auxiliary circuits
Mounting	SIRIUS 3RA68 infeed system for simpler, space-saving installation
advantages	Connection of cables up to 70 mm²
	Coding and locking options in the 3RA6 compact starter
	Screw-type and spring-loaded terminals
	Removable terminals for easy and quick replacement if service is required (permanent wiring)
	Optional control kit for testing the main current path
Application	Integrated diagnostics functions
areas/customer benefits	Large wide voltage ranges and wide setting ranges
	Three different power infeed options
	Comprehensive approvals for global applicability
	Fast and standardized configuration thanks to full integration in STEP 7

## **Versions**

The 3RA6 compact starter is available in the following versions:

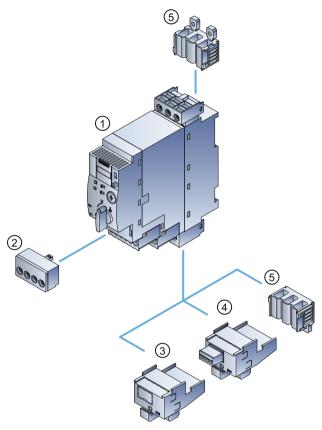
Table 1- 17 3RA6 compact starter versions

Version	Image
Compact starter direct-on-line version	
Compact starter reversing version	
Compact starter direct-on-line, IO-Link version	
Compact starter reversing, IO-Link version	

# Reference

More information	Is available in
About the 3RA6 compact starter	the chapter "SIRIUS 3RA6 compact starters
	(Page 171)".

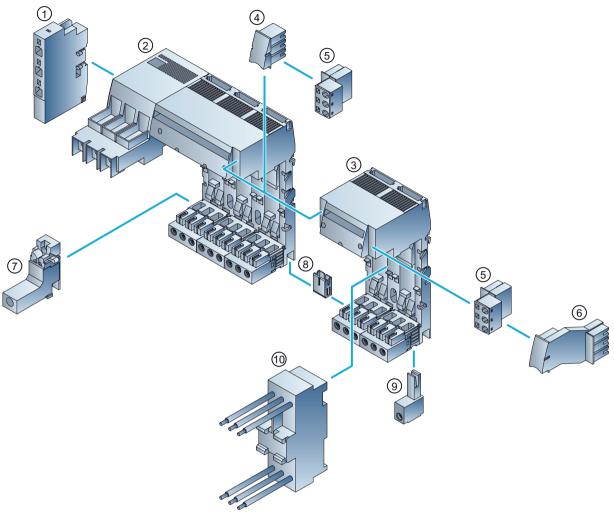
# Accessories for 3RA6 compact starters



- 1 3RA6 compact starter
- 2 External auxiliary switch block
- 3 AS-i add-on module
- 4 AS-i add-on module with:
  - Two local inputs for safe disconnection
  - Two additional digital inputs
  - One additional digital input and one digital output
  - Two additional digital outputs
  - For on-site control
- 5 Adapter for screw mounting

Figure 1-29 Accessories for 3RA6 compact starters

# Infeed system for 3RA6 compact starter



- 1 Infeed on left or right using spring-loaded connection system
- 2 Infeed on left using screw-type connection system
- 3 Expansion module
- 4 Expansion plug
- 5 Terminal block
- 6 Expansion plug for 3RV19
- 7 PE infeed
- 8 PE expansion plug
- 9 PE tap
- 45 mm adapter for infeed system for 3RA6

Figure 1-30 Infeed system for 3RA6 compact starter

## 1.7.5 Function modules



Figure 1-31 Function modules

Function modules are used to perform various control jobs on automatic production lines and for processing machines. They are suited to all time-delayed switching operations in control, starting, protection, and regulation circuits, and ensure a high degree of repeat accuracy for delay times, once they have been set.

Function modules are divided into those with a communication connection (AS-Interface or IO-Link) and those without a communication connection.

Communication-capable 3RA27 function modules are available for the following contactors and contactor assemblies:

- For direct-on-line start
- For reversing start
- For star-delta (wye-delta) start

# 1.7.5.1 SIRIUS 3RA28 function modules for mounting on SIRIUS 3RT2 contactors

# 3RA28 function modules for mounting on 3RT2 contactors

SIRIUS 3RA28 function modules for mounting on SIRIUS 3RT2 contactors enable the control circuit wiring to be reduced significantly. With star-delta (wye-delta) starters, for example, they replace the control circuit wiring in its entirety.

Table 1- 18 3RA28 function modules for mounting on 3RT2 contactors

Area	Customer benefits
Functions	<ul> <li>Direct-on-line, reversing, and star-delta (wye-delta) start</li> <li>Time-delayed switching of contactors (0.05 to 100 s)</li> </ul>
	<ul> <li>ON-delay and OFF-delay versions</li> <li>Star-delta (wye-delta) function module without extra control circuit wiring</li> <li>Switch position indication for the contactor via a mechanical plunger</li> </ul>
Dimensioning and design	<ul> <li>Only one version for S00 and S0</li> <li>Suitable for control voltages of 24 to 240 V AC/DC</li> <li>Contactor coil controlled via semiconductor output</li> <li>Star-delta (wye-delta) switchover 0.5 to 60 s</li> <li>Star-delta (wye-delta) changeover delay: 50 ms</li> </ul>
Mounting advantages	<ul> <li>Easy plug-on assembly of a starter, without tools</li> <li>Removable terminals</li> <li>Screw-type and spring-loaded terminals</li> </ul>
Application areas/customer benefits	<ul> <li>Assembly of star-delta (wye-delta) starters, including timing function and electrical interlock, without additional wiring</li> <li>Universal applicability thanks to wide voltage and time ranges</li> </ul>

# Assembly

With 3RA28 function modules, a starter can be easily assembled by combining individual modules together or by using pre-assembled combinations.

Type of starter	Individual modules	Pre-assembled combinations
Direct-on-line start	+	22722
	105	
Reversing start	22222	00000000000000000000000000000000000000
	+	
	All Maries and Maries	
Star-delta (wye-delta) start	+	Will construction
	The same	
	A Real Property lies	
	+	

# Reference

More information	Is available in
About 3RA28 function modules for direct-on-line start and star-delta (wye-delta) start	the chapter "SIRIUS 3RA28 function modules for mounting on 3RT2 contactors (Page 179)".
About function modules for reversing starting	the chapter "SIRIUS 3RT2, 3RH2, 3RA23/3RA24 contactors/contactor assemblies (Page 97)".

## 1.7.5.2 SIRIUS 3RA27 function modules for connection to the automation level

#### 3RA27 function modules for connection to the automation level

3RA27 function modules are integrated into the higher-level control system via an IO-Link master or AS-Interface. They facilitate the simple exchange of data with the control.

Communication-capable function modules are mounted on contactors or contactor assemblies with a communication connection from the SIRIUS device family.

Table 1- 19 3RA27 function modules for connection to the automation level

Area	Customer benefits
Functions	Connection of direct-on-line, reversing, and star-delta (wye-delta) starters to the automation level
	Function modules with IO-Link or AS-i interface
	2- or 3-wire communication to the control
	Integrated logic functions for starter types
	Replacement of laborious control circuit wiring
	Additional diagnostics via IO-Link.
Dimensioning and	One module for both sizes S00 and S0
design	Standard motor starter profile for all starter types
	Starter-oriented configuration in the TIA environment
	IO-Link:
	Up to 4 feeders in one group per channel on the master
	<ul> <li>Addressing not required</li> </ul>
	• AS-i
	One address per feeder
	– Max. 62 addresses
Mounting	Just a few cable connections to the control
advantages	Considerably minimized wiring complexity within a starter
	Also available as pre-assembled contactor assemblies (e.g. star-delta (wye-delta) starters)
	No control circuit wiring to the motor starter protector (voltage check)
	Available with screw-type and spring-loaded connection systems
Application	Easy and fast connection of a load feeder to the control
areas/customer benefits	Reduced number of I/O channels on the control
Denenta	Easy and fast configuration
	Improved transparency through integrated diagnostics

# **Assembly**

With the 3RA27 function modules, feeder functions are realized with contactors and a connection is established with the control. This connection is realized via IO-Link or AS-i (3RA2712) or via parallel wiring (3RA28).

Table 1-20 Assembly of 3RA27 function modules

Type of starter	Assembly
Direct-on-line start	Statute Coco Coco Coco Coco Coco Coco Coco Coc
Reversing start	SIGNAL SI
Star-delta (wye-delta) start	SITURES SITURES SITURES

#### Reference

More information	Is available in
about 3RA27 function modules for IO-Link	the chapter "3RA2711 function modules for IO-Link (Page 177)".
about 3RA27 function modules for AS-Interface	the chapter "3RA2712 function modules for AS-Interface (Page 178)".

## 1.7.6 Device combinations

The flexible designs enable the individual devices to be combined in myriad different ways. More than 40,000 combinations have been tested, which offer solutions for almost every application. Over 500 pre-assembled combinations are available, facilitating rapid and fault-free control cabinet assembly.

#### **Device combinations**

The combination matrix below shows which devices can be combined for the main circuit:

		Switching and starting			Protecting			Monitoring
		3RT2	3RF34	3RW30/40	3RV2	3RU2	3RB30/31	3RR2
Contactors	3RT2				x s	хsо	хs	x s
Solid-state switching devices	3RF34				х	_	х	х
Soft starters	3RW30/40				x s			
Motor starter protectors	3RV2	хs	х	x s				
Overload relays	3RU2	xso						
	3RB30/31	хs	х					
Current monitoring relays	3RR2	хs	х					

- x Screw-type terminals
- s Spring-loaded terminals
- o Ring cable lug connection system
- Mechanical connection with link module
- Direct mechanical connection

Figure 1-32 Device combinations

## 1.7 Components and combinations

#### Link modules

Link modules can be used to easily assemble feeders from individual devices. The table below shows the different combination options for devices with screw-type and spring-loaded connection systems:

Combination device	3RV2 motor starter	3RT2 contactors;	Link modules			
	protectors  3RW30, 3RW40 soft starters; 3RF34 solid-state contactors		3RV2 motor starter protectors with screw-type terminals	3RV2 motor starter protectors with spring-loaded terminals		
	Size	Size				
Link modules for connection of sw	itching devices to 3RV	/2 motor starter protec	tors 1)			
3RT2 contactors with AC or DC coil	S00	S00	3RA1921-1DA00	3RA2911-2AA00		
3RT2 contactors with AC coil	S0	S0	3RA2921-1AA00	3RA2921-2AA00		
3RT2 contactors with DC coil	S0	S0	3RA2921-1BA00	3RA2921-2AA00		
3RW30 soft starters	S00	S00	3RA2921-1BA00	3RA2911-2GA00		
3RW30/3RW40 soft starters	S0	S0	3RA2921-1BA00	3RA2921-2GA00		
3RF34 solid-state switching devices	S00	S00	3RA2921-1BA00	_		
Hybrid link modules for connection of contactors with a spring-loaded connection system to 3RV2 motor starter protectors with a screw-type connection system <sup>1)</sup>						
3RT2 contactors with AC or DC coil S00		S00	3RA2911-2FA00	_		
3RT2 contactors with AC or DC coil	S0	S0	3RA2921-2FA00			

The link modules and hybrid link modules cannot be used for 3RV2.21-4PA1. and 3RV2.21-4FA1. motor starter protectors or 3RV27 and 3RV28 circuit breakers.

# 1.8 Mounting and disassembly

## Mounting and disassembly

Within each device size, the mounting options are identical.

Table 1-21 Mounting options

Size	Mounting	Disassembly
S00, S0	Screw mounting	Disassembly with a screwdriver
	Snap-on mounting on 35 mm DIN rail (according to DIN EN 60715)	Disassembly without tools

# 1.8.1 Screw mounting

#### Screw mounting

SIRIUS switching devices can be screwed onto a level surface.

Push-in lugs are required in order to fasten the 3RV2 motor starter protectors with screws.

# 1.8.2 Snap-on mounting

## **Snap-on mounting**

SIRIUS Innovations products in sizes S00 and S0 are snapped onto 35 mm DIN rails according to DIN EN 60 715, without tools.

The tables below describe how to snap a component onto a DIN rail, using a contactor (size S00) as an example. The procedure is the same for all SIRIUS switching devices.

Table 1-22 Mounting on a DIN rail

Step	Operating instruction	Image
1	Position the device on the top edge of the DIN rail. Press down until it snaps onto the bottom edge of the DIN rail.	1

# 1.8 Mounting and disassembly

Table 1-23 Disassembling from a DIN rail

Step	Operating instruction	Image
1	To disassemble the device, press it down, pushing against the mounting springs. Swivel the device to remove it.	

Refer to the product manuals or operating instructions for specific details of how to snap the different devices onto DIN rails.

# 1.9 Connection

# 1.9.1 Connection systems

#### 1.9.1.1 Screw connection

#### Screw connection

Within each device size, the terminals are identical. The current which the various devices of a particular size are able to switch is also the same. This means that the same tool, torque, and conductor cross-section is used when working on all SIRIUS Innovations products of the same size. The stripped lengths are identical too; this is important for pre-assembled cables.

Size S00 and S0 devices feature screw-type terminals with captive screws and terminal washers. The screw-type terminals also allow for the connection of 2 conductors with different cross-sections.



#### Hazardous voltage.

Will cause death or serious injury.

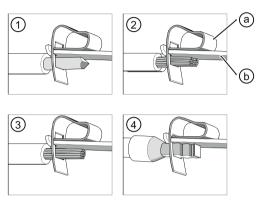
Turn off and lock out all power supplying this device before working on this device.

Use the following tool to establish the connection: The screws are designed for a size PZ 2 Pozidriv screwdriver at rated currents of up to 40 A.

## 1.9.1.2 Spring-loaded connection

#### Spring-loaded connection

Spring-loaded connection systems are found consistently on all SIRIUS Innovations products. They make wiring quick and maintenance-free, while also meeting high demands in terms of vibration and shock resistance.



- Solid
- ② Finely stranded
- 3 Stranded
- Finely stranded with end sleeve
- a Spring-loaded terminal
- b Busbar

Figure 1-33 Spring-loaded terminal

The spring-loaded terminal on the switching devices clamps copper conductors from 0.25 mm² (removable terminal) to 10 mm² (main circuit terminal, size S0). For more details, see the information about conductor cross-sections in the chapter titled "Conductor cross-sections for spring-loaded connection systems (Page 79)". The conductors can be clamped directly or you can pre-treat them to add a form of splice protection. This could involve attaching end sleeves or pin cable lugs to the ends of the conductors; the tidiest solution is to use conductors whose ends have been sealed by means of ultrasound.

The devices are equipped with a two-wire connection, i.e. two independent connections per current path. Just one conductor is connected to each clamping point. The spring-loaded terminal presses the conductor against the busbar, which curves around inside the terminal. The high contact pressure per unit area achieved in this way is gas-tight. The spring-loaded terminal presses flat against the conductor, but does not damage it. The spring force of the spring-loaded terminal has been dimensioned such that the clamping force adjusts to the conductor diameter automatically. This ensures that any conductor deformation caused by settling, creepage, or yielding is compensated for. The clamping point cannot become loose of its own accord. This connection is vibration- and shock-proof. Vibrations or shocks will not damage the conductor, nor will they cause contact separation. These terminals are particularly well suited for use with machines and systems which are subject to stresses such as these, e.g. vibrators, rail vehicles, and elevators.

The contact pressure between the conductor and the busbar is set to an optimum level, so this clamp connection is appropriate for high-voltage applications, as well as for transferring voltages and currents in the mV or mA range within instrumentation and electronic components.

Catalog IC 10 "SIRIUS Industrial Controls" offers a standard screwdriver, which can be used as the operating tool for opening the spring-loaded connections.

The table below describes the procedure for creating a spring-loaded connection:



### Hazardous voltage.

Will cause death or serious injury.

Turn off and lock out all power supplying this device before working on this device.

Table 1-24 Connecting the spring-loaded terminal

Step	Operating instruction	Image
1	Insert the screwdriver into the bottommost (A) or topmost (B) operating slot on the right-hand side.	
2	Press the screwdriver down (A) or up (B), then push it into the operating slot as far as it will go.	A ~10° / 2
	The screwdriver blade keeps the spring-loaded terminal open automatically.	B ~10° \ 2
3	Insert the conductor into the oval connection slot.	3
4	Remove the screwdriver. The terminal closes and the conductor is now securely clamped.	4

#### 1.9 Connection

#### **NOTICE**

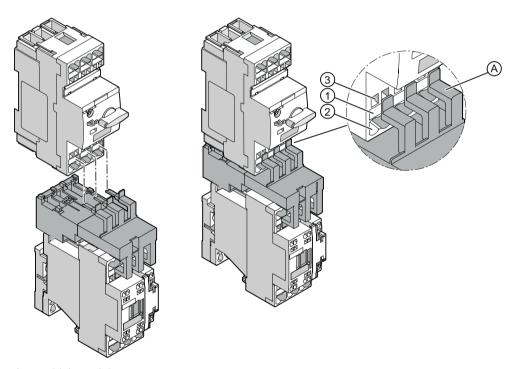
#### Damage to the spring-loaded terminal!

If you insert the screwdriver into the central opening on the spring-loaded terminal, this could damage the terminal.

Do not insert the screwdriver into the central opening on the spring-loaded terminal.

#### Link modules

Link modules enable load feeders to be assembled without tools, simply by plugging the relevant devices in.



- A Link module
- Slot for link modules
- ② Slot for conductor connection
- 3 Screwdriver opening for mounting/disassembly without a link module

Figure 1-34 Link module

#### **NOTICE**

#### Damage to the spring-loaded terminal of the link module

If a conductor is plugged into the socket for conductor connection when a link module is used, it can be damaged.

If a link module is used, do not plug a conductor into the slot for conductor connection.

### Insulating stop

With conductor cross-sections which are  $\leq 1 \text{ mm}^2$ , you should use an insulating stop to prevent the conductor insulation from being clamped. The insulating stop can be used with the following devices:

Table 1- 25 Overview table - Use of insulating stop for conductor cross-sections ≤ 1 mm<sup>2</sup>

	Size S00		Size S0	
	Main circuit	Control circuit	Main circuit	Control circuit
3RT2/3RH2 contactors (basic devices)	2	2	_	1
Accessories for 3RT2 contactors (e.g. auxiliary switches)	_	1	_	1
3RF34 solid-state switching devices	_	_	2	_
3RW30/40 soft starters	2	0	_	0
3RV2 motor starter protectors (basic devices)	2	1	_	1
Accessories for 3RV2 motor starter protectors (e.g. auxiliary switches)	_	1	_	1
3RU2 thermal overload relays	_	1	_	1
3RB3 solid-state overload relays	_	0	_	0
3RA6 compact starters	_	_	_	0
3RA27/3RA28 function modules		0	_	0
3RR2 current monitoring relays	_	0	_	0

0: No insulating stop required

1: Insulating stop 3RT1916-4AJ02

2: Insulating stop 3RT2916-4AJ02

—: Not relevant (e.g. conductor cross-section ≤ 1 mm²) or not available

#### 1.9 Connection

The graphic below shows how the insulating stop is used:

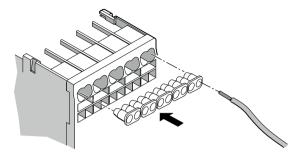


Figure 1-35 Insulating stop on spring-loaded connection system

### 1.9.1.3 Ring cable lug connection

### Ring cable lug connection

The ring cable lug connection is equipped with an M3 or M4 combination screw. A special cover ensures finger-safety. See the information on ring cable lugs in the chapter titled "Conductor cross-sections for ring cable lug connection system (Page 81)".

# **DANGER**

### Hazardous voltage.

Will cause death or serious injury.

Turn off and lock out all power supplying this device before working on this device.

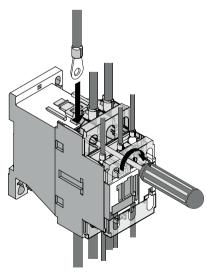


Figure 1-36 Ring cable lug connection system

#### 1.9.2 Conductor cross-sections

#### Conductor cross-sections

Due to SIRIUS being a modular system, the conductor cross-sections of all the devices of one size are identical.

### 1.9.2.1 Conductor cross-sections for screw-type connection systems

### Conductor cross-sections for screw-type connection systems

The tables below define the permissible conductor cross-sections for main terminals and auxiliary conductor connections in sizes S00 and S0 for screw-type connection systems.

Table 1- 26 Main conductors of size S00 with M3 combination screws

		Motor starter protectors	Contactors	Overload relays <sup>1)</sup> , current monitoring relays <sup>1)</sup>
Tool		Pozidriv size PZ 2, Ø 5 to 6 mm		
Tightening torque		0.8 to 1.2 Nm		
Solid and stranded	<del>-</del> 10 <del></del>		2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>
		2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>
		Max. 2 x 4 mm <sup>2</sup>	Max. 2 x 4 mm <sup>2</sup>	Max. 2 x 4 mm <sup>2</sup>
Finely stranded with	<del>-</del> 10 <del></del>	2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>
end sleeve DIN 46228 Part 1		2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>
AWG			2 x (20 to 16)	2 x (20 to 16)
		2 x (18 to 14)	2 x (18 to 14)	2 x (18 to 14)
		2 x 12	2 x 12	2 x 12

<sup>&</sup>lt;sup>1)</sup> Only 1 conductor can be clamped on the stand-alone assembly support.

#### 1.9 Connection

Table 1-27 Main conductors of size S0 with M4 combination screws

		Motor starter protectors	Contactors	Overload relays 1), current monitoring relays 1)
Tool	<b>₩</b>	Pozidriv size PZ 2, Ø 5 to 6 mm		
Tightening torque		2.0 to 2.5 Nm		
Solid and stranded	l <del>&lt;</del> 10→l	2 x (1.0 to 2.5) mm <sup>2</sup>	2 x (1.0 to 2.5) mm <sup>2</sup>	2 x (1.0 to 2.5) mm <sup>2</sup>
		2 x (2.5 to 10) mm <sup>2</sup>	2 x (2.5 to 10) mm <sup>2</sup>	2 x (2.5 to 10) mm <sup>2</sup>
Finely stranded with	+10-+	2 x (1 to 2.5) mm²	2 x (1 to 2.5) mm <sup>2</sup>	2 x (1 to 2.5) mm²
end sleeve DIN 46228 Part 1		2 x (2.5 to 6) mm <sup>2</sup>	2 x (2.5 to 6) mm <sup>2</sup>	2 x (2.5 to 6) mm <sup>2</sup>
DIN 40220 Part 1	,	Max. 1 x 10 mm <sup>2</sup>	Max. 1 x 10 mm <sup>2</sup>	Max. 1 x 10 mm <sup>2</sup>
AWG		2 x (16 to 12)	2 x (16 to 12)	2 x (16 to 12)
		2 x (14 to 8)	2 x (14 to 8)	2 x (14 to 8)

<sup>1)</sup> Only 1 conductor can be clamped on the stand-alone assembly support.

Table 1-28 Auxiliary conductors of size S00/S0 with M3 combination screws

		Accessories for motor starter protectors, accessories for contactors, overload relays	Contactors, size S00	Contactors, size S0
Tool	Pozidriv size PZ 2, Ø 5 to 6 mm			
Tightening torque		0.8 to 1.2 Nm		
Solid and stranded	<del>-</del> 10 <del></del>	2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>
		2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>
			Max. 2 x 4 mm <sup>2</sup>	
Finely stranded with	<del>-</del> 10 <del></del>	2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>
end sleeve DIN 46228 Part 1		2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>	2 x (0.75 to 2.5) mm <sup>2</sup>
AWG		2 x (20 to 16)	2 x (20 to 16)	2 x (20 to 16)
		2 x (18 to 14)	2 x (18 to 14)	2 x (18 to 14)
			2 x 12	

Table 1-29 Removable terminal

		Removable terminal
Tool	*	Pozidriv size PZ 2, Ø 6 mm
Tightening torque		0.8 to 1.2 Nm
Solid and stranded	<del></del> 10 <del></del>	1 x (0.5 to 4) mm <sup>2</sup>
		2 x (0.5 to 2.5) mm <sup>2</sup>
Finely stranded with	<del>+</del> 10- <del></del>	1 x (0.5 to 2.5) mm <sup>2</sup>
end sleeve		2 x (0.5 to 1.5) mm <sup>2</sup>
AWG		2 x (20 to 14)

## 1.9.2.2 Conductor cross-sections for spring-loaded connection systems

## Conductor cross-sections for spring-loaded connection systems

The tables below define the permissible conductor cross-sections for main terminals and auxiliary conductor connections in sizes S00 and S0 for spring-loaded connection systems.

Table 1-30 Main conductors of size S00

		Motor starter protectors, contactors	Overload relays, current monitoring relays
Tool		Ø 3.5 x 0.5 (8WA2880/8WA Ø 3.0 x 0.5 (3RA2808-1A)	A2803)
Solid and stranded	10→	2 x (0.5 to 4.0) mm <sup>2</sup>	0.5 to 4.0 mm <sup>2</sup>
Finely stranded without end sleeve	<b>→</b> 10→	2 x (0.5 to 2.5) mm <sup>2</sup>	0.5 to 2.5 mm <sup>2</sup>
Finely stranded with end sleeve (DIN 46 228 Part 1)	+10-	2 x (0.5 to 2.5) mm <sup>2</sup>	0.5 to 2.5 mm <sup>2</sup>
AWG		2 x (20 to 12)	2 x (20 to 12)

### 1.9 Connection

Table 1-31 Main conductors of size S0

		Motor starter protectors, contactors	Overload relays, current monitoring relays
		Ø 3.5 x 0.5 (8WA2880/8WA2803) Ø 3.0 x 0.5 (3RA2808-1A)	
Solid and stranded	-10-	2 x (1.0 to 10) mm <sup>2</sup>	1.0 to 10 mm <sup>2</sup>
Finely stranded without end sleeve	<del>-</del> 10-+	2 x (1.0 to 6.0) mm <sup>2</sup>	1.0 to 6.0 mm <sup>2</sup>
Finely stranded with end sleeve (DIN 46 228 Part 1)	<b>+10→</b>	2 x (1.0 to 6.0) mm <sup>2</sup>	1.0 to 6.0 mm <sup>2</sup>
AWG		2 x (18 to 8)	2 x (18 to 8)

Table 1- 32 Auxiliary conductors of size S00/S0

		Contactors, size S00, basic devices	Contactors, size S0, integrated auxiliary switches, overload relays, accessories for contactors, accessories for motor starter protectors
Tool	Ø 3.5 x 0.5 (8WA2880/8WA2803) Ø 3.0 x 0.5 (3RA2808-1A)		A2803)
Solid and stranded	±10-+	2 x (0.5 to 4) mm <sup>2</sup>	2 x (0.5 to 2.5) mm <sup>2</sup>
Finely stranded without end sleeve	<del>-</del> 10-+	2 x (0.5 to 2.5) mm <sup>2</sup>	2 x (0.5 to 2.5) mm <sup>2</sup>
Finely stranded with end sleeve (DIN 46 228 Part 1)	<b>→10</b> →	2 x (0.5 to 2.5) mm <sup>2</sup>	2 x (0.5 to 1.5) mm <sup>2</sup>
AWG		2 x (20 to 12)	2 x (20 to 14)

Table 1-33 Removable terminal

		Removable terminal
Tool		Ø 3.0 x 0.5 (3RA2808-1A)
Solid and stranded	-10-	2 x (0.25 to 1.5) mm <sup>2</sup>
Finely stranded without end sleeve	<del>-10-+</del>	2 x (0.25 to 1.5) mm <sup>2</sup>
Finely stranded with end sleeve	<b>+10→</b>	2 x (0.25 to 1.5) mm <sup>2</sup>
AWG		2 x (24 to 16)

### 1.9.2.3 Conductor cross-sections for ring cable lug connection system

### Conductor cross-sections for ring cable lug connection system

The tables below define the permissible conductor cross-sections for main terminals and auxiliary conductor connections in sizes S00 and S0 for ring cable lug connection systems.

Table 1-34 Main conductors and auxiliary conductors of size S00 with M3 combination screws

		SIRIUS devices
Tool		Pozidriv size 2, Ø 5 to 6 mm
Tightening torque		0.8 to 1.2 Nm
Ring cable lug 1)		d <sub>2</sub> = min. 3.2 mm
	d <sub>2</sub> d <sub>3</sub>	d <sub>3</sub> = max. 7.5 mm

#### 1.9 Connection

Table 1-35 Main conductors and auxiliary conductors of size S0 with M4 combination screws

		SIRIUS devices
Tool		Pozidriv size 2, Ø 5 to 6 mm
Tightening torque		2.0 to 2.5 Nm
Ring cable lug 1)		d <sub>2</sub> = min. 4.3 mm
	d <sub>2</sub> d <sub>3</sub>	d <sub>3</sub> = max. 12.2 mm

- <sup>1)</sup> The following ring cable lugs are approved for achieving the required clearances and creepage distances:
- For applications according to IEC 60947-1:
  - DIN 46237 (with insulating sleeve)
  - JIS CS805 type RAV (with insulating sleeve)
  - JIS CS805 type RAP (with insulating sleeve)
- For applications according to UL 508:
  - DIN 46 234 (without insulating sleeve)
  - DIN 46225 (without insulating sleeve)
  - JIS CS805 (without insulating sleeve)

A shrink-on sleeve must be used to insulate ring cable lugs without an insulating sleeve. The following conditions must be met:

- Application temperature: -55 °C to +155 °C
- UL 224 approved
- Flame-protected



# **DANGER**

#### Hazardous voltage.

Will cause death or serious injury.

Only use approved ring cable lugs to meet the required clearances and creepage distances.

## 1.9.3 Image database

### Internal circuit diagrams

You can find the internal circuit diagrams for SIRIUS Innovations products online in the image database (www.siemens.com/industrial-controls/bilddb).

Enter the order number of the device in the "Order number" field and, in the "Type of object" selection menu on the left-hand side, select "Unit wiring diagram".

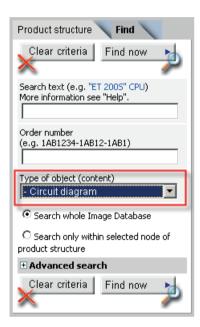


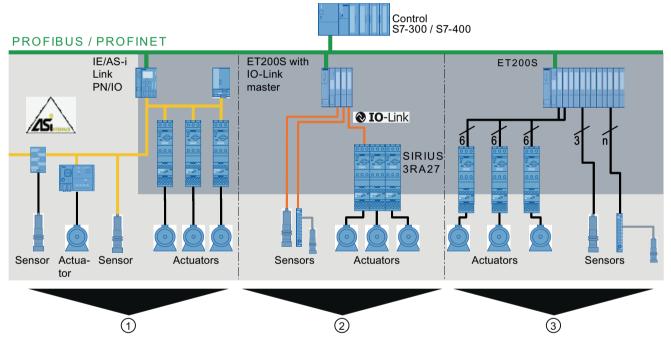
Figure 1-37 Image database

# 1.10 Connection to the higher-level control

### 1.10.1 Connection to the higher-level control

#### Connection to the higher-level control

The communication-capable SIRIUS Innovations from Siemens provide the user with a uniform automation solution. Automation functions can be implemented consistently, from field devices through to the control cabinet and beyond to human machine interfaces and visualization stations. The concept is based on AS-Interface and PROFIBUS DP, two standardized and open fieldbus systems which can be connected to almost all the control systems provided by well-known manufacturers.



- 1 Acquisition or connection of distributed I/Os and distributed load feeders.
- 2 A point-to-point connection is established via IO-Link if a number of signals are grouped together.
- 3 Classic wiring via digital I/Os is used if the number of signals is manageable.

Figure 1-38 Options for connection to the automation level

In addition to the established fieldbus systems, SIRIUS Innovations also safeguard communication right up to the "final mile" on the actuator side. In a similar way to with PROFIBUS DP and AS-Interface, a user organization made up of a range of renowned manufacturers ensures that control data, status data, and diagnostics data can now be transferred in accordance with a uniform communication standard via IO-Link intelligent wiring, as well as via classic parallel wiring.

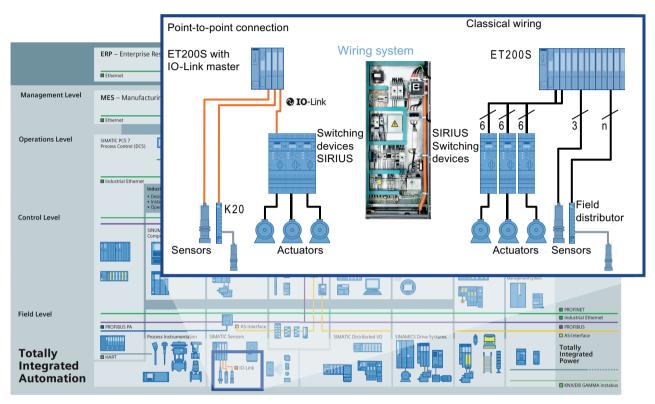


Figure 1-39 Connection to the higher-level control

SIRIUS switching devices can be connected to higher-level control systems using conventional wiring, but also by means of intelligent wiring and a fieldbus:

- IO-Link
- AS-Interface

SIRIUS switching devices are linked into the Siemens Totally Integrated Automation concept via function modules. Totally Integrated Automation offers the user uniformity in terms of configuration, programming, data storage, and communication.

#### 1.10 Connection to the higher-level control

SIRIUS switching devices are connected to the automation level via AS-Interface or IO-Link, without any additional wiring. These interfaces ensure that information about the switch position and the readiness of the feeder for operation is transferred, and that contactor control is implemented. In addition to these three items of information relating to feeders, IO-Link also transfers diagnostics data.

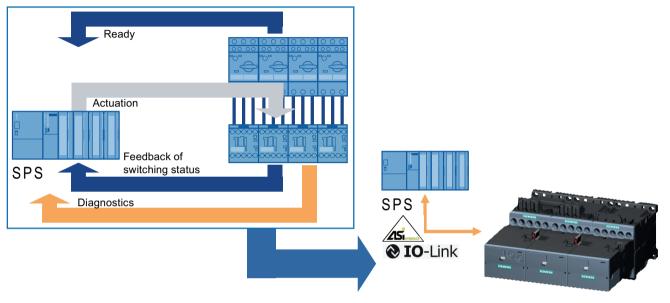


Figure 1-40 Communication via AS-Interface or IO-Link

SIRIUS 3RA27 function modules or SIRIUS 3RA6 compact starters can communicate with a higher-level control either via the AS-i fieldbus or via the IO-Link wiring system. Cyclic data transmission (DIs and DOs) is identical for both IO-Link and AS-i.

Table 1- 36 Motor starter profile

Standard moto	r starter profile	Group diagnostics (only with IO-Link)		
• 4 DI, 2 DO	(per feeder)	Device fault		
2 LEDs for "Device" and "Group fault"		No main voltage (motor starter protector		
DI 0.0	Ready	tripped)		
DI 0.1	Motor ON	Auxiliary voltage 24 V DC (U <sub>aux</sub> ) missing		
DI 0.2	Group fault	Signaling limit position right/left		
DI 0.3	Group warning	Manual/local mode		
DO 0.0	Motor ON or Motor CW			
DO 0.1	Motor CCW			

#### 1.10.2 IO-Link

IO-Link is a new communication standard for sensors and actuators - defined by the PROFIBUS User Organization (PNO). The IO-Link technology is based on a point-to-point connection of the sensors and actuators to the control. Therefore, this technology is not a bus system, but an enhanced version of a classic point-to-point connection. In addition to the cyclic operating data, comprehensive parameters and diagnostics data are transferred for the connected sensors and actuators. The same 3-wire connecting cable as currently used for standard sensors is used.

#### IO-Link is:

- An open and standardized system for transmitting device-specific data.
- An intelligent wiring system positioned between conventional wiring and fieldbus systems.
- A system which offers advantages in the control cabinet and is integrated in the TIA concept.

IO-Link is thus an intelligent wiring system which is fully integrated in TIA.

#### 1.10.2.1 Overview

### Components of an IO-Link system

Only 2 components are required to use IO-Link:

- IO-Link master
- IO-Link device (e.g. IO-Link sensor/switching device, IO-Link I/O module)

### Compatibility of IO-Link

IO-Link guarantees compatibility between standard modules and those with IO-Link capability as follows:

- IO-Link sensors/actuators can generally be operated on IO-Link modules (master) and on standard I/O modules.
- Both IO-Link sensors/actuators and current standard sensors/actuators can be used on IO-Link modules (master).
- If conventional components are used in the IO-Link system, naturally only the standard functions are available in this case.

#### Expansion by means of IO-Link I/O modules

The compatibility of IO-Link means that you can connect standard (conventional) sensors/actuators to it too. This can be implemented especially cost-effectively with IO-Link I/O modules that permit the connection of several sensors/actuators to the controller via one cable.

1.10 Connection to the higher-level control

### Analog signals

One further advantage of the IO-Link technology is that analog signals are digitized directly in the IO-Link sensor and are then transmitted digitally via IO-Link communication. This prevents any interference and eliminates the need for cable shielding.

#### Integration in STEP 7

Integration of the device configuration into the STEP 7 environment ensures:

- Simple and fast engineering.
- Consistent data storage.
- Fast location and clearance of faults.

This raises productivity across all phases of the system lifecycle – configuration, commissioning, and operation. With the Siemens IO-Link solution, even sensors/actuators and switching devices below the fieldbus level are optimally integrated with their complete performance capability in the Totally Integrated Automation (TIA) environment.

#### 1.10.2.2 Benefits

#### **Benefits**

The IO-link system offers important benefits when connecting complex (intelligent) sensors/actuators:

- Dynamic modification of the sensor and actuator parameters directly via the PLC.
- Possibility of device replacement during operation without a programming device/PC, by means of re-parameterization via the consistent storage of parameters.
- Fast commissioning due to central data storage.
- Integrated diagnostics information as far as the sensor and actuator levels.
- Uniform and significantly reduced wiring of different sensors/actuators/switching devices.
- Fewer parameterization tools.
- Integrated communication: transmission of process data and service data between sensors/actuators and the control.
- Uniform and transparent configuration and programming by means of a parameterization tool (Port Configurator Tool, PCT) integrated into SIMATIC STEP 7.
- Transparent representation of all parameter and diagnostics data.
- Reduced costs during configuration and commissioning.
- Alarms and indicators for preventive maintenance.

### 1.10.2.3 Applications

### **Applications**

IO-Link can be used in the following applications:

- Simple connection of complex sensors/actuators with a large number of parameters to the control.
- Optimum replacement of IO-Link modules for sensor/actuator boxes when connecting binary sensors.

In both cases, all diagnostics data is transmitted to the higher-level control via IO-Link. Parameter settings can be changed during operation. A sensor/actuator can be replaced without a programming device/PC thanks to the central data storage feature.

The IO-Link range comprises:

- IO-Link master
- IO-Link module K20
- IO-Link starting controls
- IO-Link switching controls
- IO-Link sensors

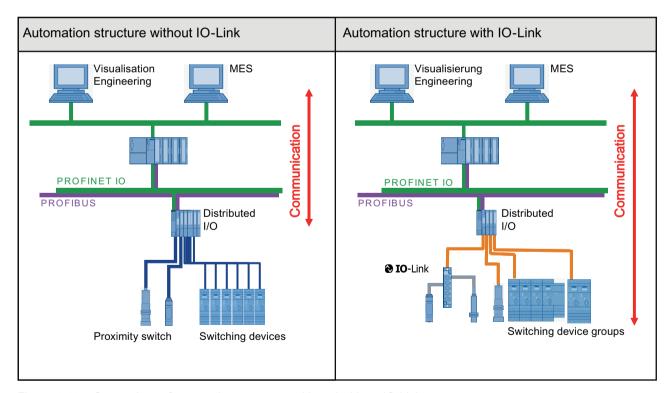


Figure 1-41 Comparison of automation structures with and without IO-Link

1.10 Connection to the higher-level control

#### SIRIUS 4SI electronic module

Ideally suited to connecting SIRIUS Innovations products to IO-Link is the IO-Link master for SIRIUS controls: the SIRIUS 4SI electronic module for SIMATIC ET 200S.

The SIRIUS 4SI electronic module facilitates the efficient and space-saving integration of IO-Link-capable SIRIUS switching devices into the TIA world. It connects up to 16 SIRIUS load feeders to the higher-level control environment.

Table 1- 37 SIRIUS 4SI electronic module

Area	Customer benefits
Functions	Integration of IO-Link-capable SIRIUS controls in the distributed I/O ET 200S.
	Diagnostics data.
	Status display and group fault signaling.
Dimensioning and design	Width 15 mm.
	4 IO-Link ports.
	Connection of up to 16 load feeders.
Mounting advantages	Considerably reduced wiring and space requirements in the control cabinet.
	Terminal modules with screw-type, spring- loaded, and insulation displacement connection system.
Application areas/customer benefits	Considerably lower price (50%) than the IO- Link master if only SIRIUS devices are used.
	Reduced wiring     (5 cable connections for 4 feeders).
	Fast module selection via the ET 200 configurator.

The figure below uses an example to show where the SIRIUS 4SI electronic module is positioned within the SIRIUS controls.

- 1 Interface module IM...
- 2 Power module electronic PM-E
- 3 Electronic module, e.g. SIRIUS 4SI, DI, DO, AI, AO, CP, FM
- 4 Power module drives PM-D
- 5 Motor starter
- 6 Frequency converter ICU
- 7 Frequency converter IPM
- 8 Termination module
- 9 SIRIUS modular system with IO-Link (e.g. SIRIUS 3RA6 compact starters)

Figure 1-42 Options for connection to the automation level

#### 1.10.3 AS-Interface

#### 1.10.3.1 Overview

The AS-Interface is an open, international standard in accordance with EN 50295 and IEC 62026-2 for process communication and field communication. Leading manufacturers of actuators and sensors worldwide support AS-Interface.

AS-Interface is a single master system. For direct integration into automation systems from Siemens, e.g. S7-300 or S7-1200, communications processors (CPs or CMs) are the obvious choice. In addition, AS-i networks can also be connected via PROFINET or PROFIBUS with the help of routers (links).

In both cases, the lower-level AS-i networks with connected actuators and sensors can be parameterized and diagnosed direct from the controller.

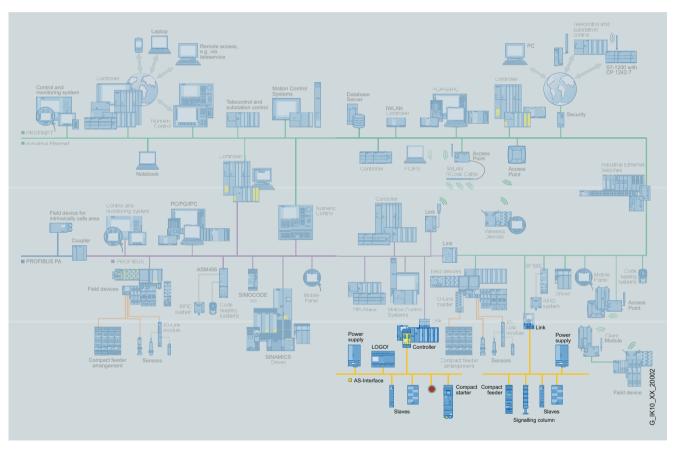


Figure 1-43 AS-Interface

#### 1.10.3.2 Benefits

An important characteristic of the AS-Interface technology is the use of a shared two-wire cable for data transmission including distribution of auxiliary power to the sensors and actuators in high degree of protection IP65/67. One AS-Interface power supply unit is used per AS-i network to distribute the auxiliary power.

The AS-i network is installed with the help of a profiled (reverse-polarity-protected) AS-Interface cable on which the AS-i slaves can be mounted as desired. The AS-i network is electrically contacted by the piercing contacts of the AS-i slaves (insulation displacement method). Any bus topology can therefore be chosen.

Complex control cable wiring in the control cabinet and terminal blocks can be replaced with AS-Interface. Thanks to a specially developed cable and the insulation displacement method, the AS-Interface cable can be connected anywhere. This concept is extremely flexible and enables you to make huge savings.

### 1.10.3.3 Operating modes

In general, the following operating modes are distinguished between for the master interfaces:

- I/O data exchange:
   In this operating mode, the inputs and outputs of the binary AS-Interface slaves are read and written to.
- Analog value transmission: AS-Interface masters in accordance with AS-Interface Specification V2.1 or V3.0 support integral analog value processing. This means that data can be exchanged using analog AS-Interface slaves (in accordance with analog profile 7.3 or 7.4) just as easily as with digital slaves.
- Command interface:

As well as I/O data exchange with binary and analog AS-Interface slaves, the AS-Interface masters provide a range of other functions using the command interface. Thus, for example, slave addresses can be allocated, parameter values can be transferred, or diagnostics information can be read out from user programs.

#### 1.10.3.4 Process communication and field communication

The AS-Interface is used where individual actuators and sensors are distributed at different locations on a machine (e.g. in a bottling plant or production line, etc.). AS-Interface replaces complex cable harnesses and connects binary and analog actuators and sensors such as proximity switches, valves, or indicator lights with a control, such as SIMATIC, or a PC.

In practice this means that the installation process is really simple, because both data and power are transported via the same cable. No expert knowledge is required for installation and commissioning. Furthermore, thanks to the simple cable laying procedure and the clear cable structure, as well as the special design of the cable, you not only significantly reduce the risk of errors, but also service and maintenance costs.

#### 1.10 Connection to the higher-level control

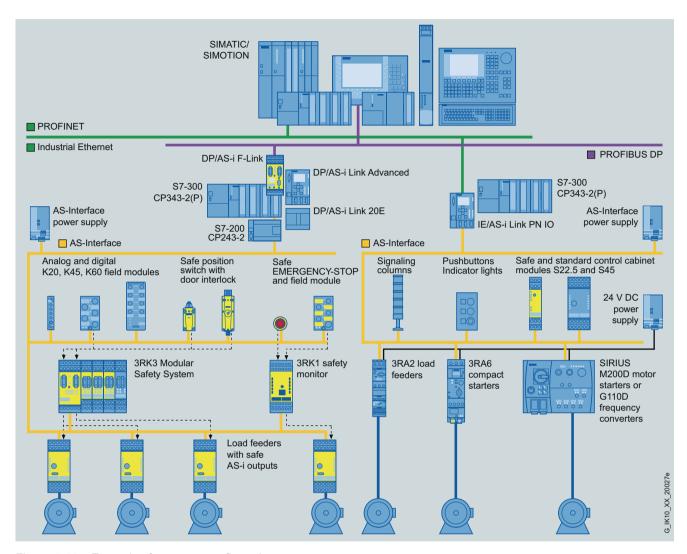


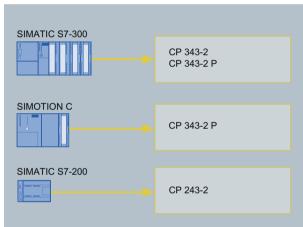
Figure 1-44 Example of a system configuration

### 1.10.3.5 System components

Numerous system components are offered to perform communication. The main components of a system installation are:

- Master interfaces for central control units such as SIMATIC S7, ET 200 M distributed I/O, or routers from PROFIBUS/PROFINET to AS-Interface
- AS-Interface shaped cable
- Network components, e.g. repeater and extension plug
- Power supply unit for powering the slaves
- Modules for connecting standard sensors/actuators
- Sensors and actuators with integrated AS-i slave (e.g. motor starters, soft starters, load feeders, pushbuttons, indicator lights, or position switches)
- Secure modules for transferring safety-related data over AS-Interface
- Addressing device for setting slave addresses during commissioning

AS-Interface Master



#### AS-Interface Links

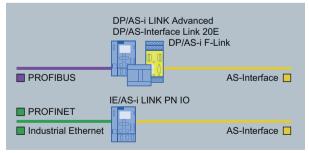


Figure 1-45 AS-Interface master and AS-Interface links

#### 1.10.3.6 Technical data

Feature	Specification
Standard	EN 50295/IEC 61158
Topology	Line topology, star topology, or tree topology (same as electrical installation)
Transmission medium	Unshielded twisted pair (2 x 1.5 mm²) for data and auxiliary power
Connection system	Contacting of the AS-Interface cable using insulation displacement
Maximum cable length	100 m without repeater 200 m with extension plug 300 m with 2 repeaters connected in series 600 m with extension plugs and 2 repeaters connected in parallel With parallel connection, more repeaters allow for longer cable lengths
Maximum cycle time	5 ms for maximum configuration with standard addresses 10 ms for maximum configuration with A/B addresses Profile-specific for Spec 3.0 slaves
Number of stations per AS-Interface segment	31 slaves in accordance with AS-Interface Spec. V2.0 62 slaves (A/B method) in accordance with AS-Interface Spec. V2.1 and V3.0, integrated analog value transmission
Number of binary sensors/actuators	Max. 124 DI/124 DO acc. to Spec. V2.0 Max. 248 DI/186 DO acc. to Spec. V2.1 Max. 496 DI/496 DO acc. to Spec. V3.0
Access method	Cyclic polling master/slave procedure, cyclic data acceptance by host (PLC, PC)
Error control	Identification and resending of faulty messages

#### 1.10.3.7 More information

#### More information

Always observe the conditions and constraints for use and the additional information available for the modules referred to above.

### **AS-Interface System Manual**

More information about the AS-Interface is available in the AS-Interface System Manual.

The system manual can be downloaded from the Internet free of charge:

- German version (http://support.automation.siemens.com/WW/view/de/26250840)
- English version (http://support.automation.siemens.com/WW/view/en/26250840)

The AS-Interface System Manual can also be supplied in paper format in both languages.

#### Internet

More information can be found on the Internet (http://support.automation.siemens.com/WW/view/en/10805888/130000).

# 2.1 Overview of the contactor range

The SIRIUS range offers various switching devices for the safe and functional switching of electrical loads. The table below provides an overview of the contactor versions and contactor assemblies available in size S00/S0 (table contains versions featuring screw-type terminals).

Size	3RH2 contactor relays	3RT2 power contactors	3RA23 reversing contactor assembly	3RA24 contactor assembly for star-delta (wye-delta) start
S00				
S0				

## 2.2 Device versions

Various different switching devices are available for switching electrical loads. The contactor is the ideal device for performing switching operations which are frequently repeated; it is the most commonly used switching device in industry, mechanical engineering, and the manufacture of switching stations.

#### 2.2 Device versions

The SIRIUS contactor range with a width of 45 mm (size S00/S0) comprises:

- 3RT20 power contactors for switching motors of up to 18.5 kW/400 V (AC-3) and resistive loads of up to 50 A (AC-1)
- 3RH2 contactor relays for switching in the control circuit with contact versions of 4 NO contacts, 3 NO contacts + 1 NC contact, and 2 NO contacts + 2 NC contacts
- 3RA23 (reversing) and 3RA24 (star-delta (wye-delta)) contactor assemblies

## 2.2.1 3RH2 contactor relays

3RH2 contactor relays are available in the versions detailed below. The contactors can be supplied with AC and DC drives of between 24 V and 230 V (preferred voltages). Different voltage versions are available on request.

#### **Versions**

Table 2- 1 Versions of the 3RH2 contactor relays

Feature	Specifications	ations Contactors for special applications				
Version	Contactor relay for switching in the auxiliary circuit	Contactor relay with extended operating range for switching auxiliary circuits  Auxiliary coupling relay for switching auxiliary circuits				
Number of poles	4 / 8	4	4			
Size	S00					
Width	45 mm					

#### Connection systems

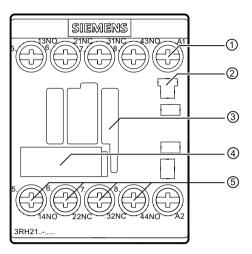
The contactor relays can be supplied with the connection systems detailed below.

Table 2- 2 Connection systems available for 3RH2 contactor relays

Connection system	Contactor relay for switching in the auxiliary circuit	Contactor relay with extended operating range	Coupling relay for switching auxiliary circuits
Screw connection	✓	✓	✓
Spring-loaded connection	✓	✓	✓
Ring cable lug connection	✓		
Solder pin connection (only possible in conjunction with the "solder pin adapter" optional accessory)	1	1	1

The illustrations below show example equipment features of the 3RH2 contactor relays for switching in the auxiliary circuit.

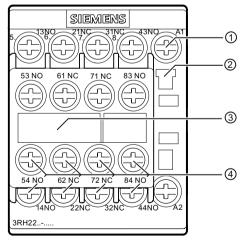
### 3RH21 contactor relay, 4-pole



- 1 Coil terminal on the front
- 2 Location hole for surge suppression
- 3 Location hole for 1-, 2-, and 4-pole auxiliary switch blocks
- 4 Labeling plate
- 5 Auxiliary contacts

Figure 2-1 3RH21..-.... contactor relay, 4-pole, size S00, overview

#### 3RH22 contactor relay, 8-pole



- 1 Coil terminal on the front
- 2 Location hole for surge suppression
- 3 Labeling plate
- 4 Auxiliary contacts

Figure 2-2 3RH22..-.... contactor relay with auxiliary switch block on the front which cannot be removed, 8-pole, size S00, overview

### 2.2.2 3RT2 power contactors

The table below shows the different versions of the 3RT2 power contactors. The contactors are equipped with AC and DC drive options. An electronic UC drive can also be ordered for size S0. Special communication-capable contactors are available for integration via AS-Interface or IO-Link by means of 3RA27 function modules; these contactors enable the voltage of the main circuit to be tapped directly. The communication-capable power contactor is supplied with a 24 V DC drive option.

#### Versions

Table 2-3 Versions of the 3RT2 power contactors

Feature Specifications						
Version		Power contactor for switching electrical loads	Power contactor with extended operating range	Coupling relay for switching electrical loads	3RT23 power contactor for switching resistive loads	3RT25 power contactor with 2 NO contacts and 2 NC contacts
Number of poles		3	3	3	4	2 NO contacts + 2 NC contacts
Number of S00 integrated		1 NO contact or 1 NC contact	1 NO contact or 1 NC contact	1 NO contact or 1 NC contact		
auxiliary S0 contacts		1 NO contact and 1 NC contact	1 NO contact and 1 NC contact	1 NO contact and 1 NC contact	1 NO contact and 1 NC contact	1 NO contact and 1 NC contact
Size	•	S00/S0				
Width	Width 45 mm					

### **Connection systems**

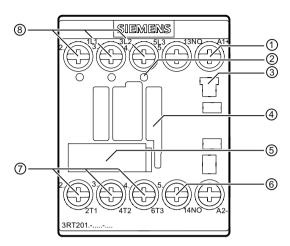
The power contactors can be supplied with the connection systems detailed below:

Table 2-4 Connection systems available for 3RT2 power contactors

Connection system	Power contactor for switching electrical loads	Power contactor with extended operating range	Coupling relay for switching electrical loads	3RT23 power contactor for switching resistive loads/3RT25 power contactor with 2 NO contacts and 2 NC contacts
Screw connection	✓	✓	✓	✓
Spring-loaded connection	✓	1	✓	<b>√</b>
Ring cable lug connection	✓			
Solder pin connection (only possible in conjunction with the "solder pin adapter" optional accessory)	√ (size S00 only)	√ (size S00 only)	√ (size S00 only)	

The illustrations below show example equipment features of the 3RT2 power contactors for switching motorized loads.

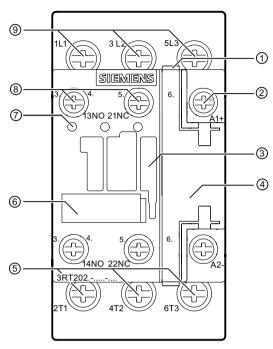
### 3RT2 power contactors (size S00)



- 1 Coil terminal on the front
- 2 Openings for voltage tap of the main circuit (communication-capable power contactor only)
- 3 Location hole for surge suppression
- 4 Location hole for 1-, 2-, and 4-pole auxiliary switch blocks
- 5 Labeling plate
- 6 1 auxiliary contact integrated (1 NO contact)
- 7 Contactor's main circuit terminal to the load/motor connection (T1, T2, T3)
- 8 Contactor's main circuit terminal to the power network (L1, L2, L3)

Figure 2-3 3RT201.-.... power contactor, size S00, overview

### 3RT2 power contactors (size S0)



- 1 Cable duct
- 2 Coil terminal on the front
- 3 Location hole for 1-, 2-, and 4-pole auxiliary switch blocks
- 4 Location hole for surge suppression (underneath flap)
- 5 Contactor's main circuit terminal to the load/motor connection (T1, T2, T3)
- 6 Labeling plate
- 7 Openings for voltage tap of the main circuit (communication-capable power contactor only)
- 8 2 auxiliary contacts integrated (1 NO contact and 1 NC contact)
- 9 Contactor's main circuit terminal to the power network (L1, L2, L3)

Figure 2-4 3RT202.-.... power contactor, size S0, overview

## 2.2.3 3RA23 reversing contactor assemblies

The reversing contactor assemblies of sizes S00 and S0 are available in two versions:

- Fully wired and tested with electrical and mechanical interlock.
- As a kit for customer assembly.

The fully wired and tested reversing contactor assembly consists of 2 contactors of the same power rating, each with an NC contact in the basic device, link modules and wiring modules. The contactors are mechanically and electrically interlocked (NC contact interlock). The contactor assemblies for reversing are climate-proof. They are safe to touch according to DIN EN 61140.

#### Connection systems

The fully wired 3RA23 reversing contactor assembly is available either with a screw-type connection system or a spring-loaded connection system.

The illustrations below show the fully assembled reversing contactor assemblies, in the version with the screw-type connection system.

Table 2-5 Illustrations of the 3RA23 reversing contactor assembly (size S00 and S0)

3RA23 reversing contactor assembly, screw connection, size S00	3RA23 reversing contactor assembly, screw connection, size S0

Table 2-6 Screw connection

Rated data AC-2 and AC-3 at 50 Hz 400 V AC		Size	Order No.	Order No.				
Power	Operational current l₀		Contactor	Mechanical interlock 1)	Assembly	Fully-wired and tested contactor		
[kW]	[A]					assemblies		
3	7	S00	3RT2015-12		3RA2913- 2AA1	3RA2315-8XB30-1		
4	9		3RT2016-12			3RA2316-8XB30-1		
5,5	12		3RT2017-12			3RA2317-8XB30-1		
7,5	16		3RT2018-12			3RA2318-8XB30-1		
5,5	12	S0	3RT2024-10		3RA2923- 2AA1	3RA2324-8XB30-1		
7,5	16		3RT2025-10			3RA2325-8XB30-1		
11	25		3RT2026-10			3RA2326-8XB30-1		
15	32		3RT2027-10			3RA2327-8XB30-1		
18,5	38		3RT2028-10			3RA2328-8XB30-1		

<sup>1)</sup> The interlock can only be ordered with the kit.

<sup>&</sup>lt;sup>2)</sup> The assembly kit contains: Mechanical interlock, connecting clips for 2 contactors, wiring modules on the top and bottom (main circuits, control circuits and auxiliary circuits)

#### 2.2 Device versions

Table 2-7 Spring-loaded connection

Rated data AC-2 and AC-3 at 50 Hz 400 V AC		Size	Order No.	Order No.			
Power	Operational current le		Contactor	Mechanical interlock 1)	Assembly kit <sup>2)</sup>	Fully-wired and tested contactor	
[kW]	[A]					assemblies	
3	7	S00	3RT2015-22		3RA2913- 2AA2 <sup>2)</sup>	3RA2315-8XB30-2	
4	9		3RT2016-22			3RA2316-8XB30-2	
5,5	12		3RT2017-22			3RA2317-8XB30-2	
7,5	16		3RT2018-22			3RA2318-8XB30-2	
5,5	12	S0	3RT2024-20		3RA2923- 2AA2 <sup>3)</sup>	3RA2324-8XB30-2	
7,5	16		3RT2025-20			3RA2325-8XB30-2	
11	25		3RT2026-20			3RA2326-8XB30-2	
15	32		3RT2027-20			3RA2327-8XB30-2	
18,5	38		3RT2028-20			3RA2328-8XB30-2	

<sup>1)</sup> The interlock can only be ordered with the kit.

### Reversing contactor assemblies with communication interface

The reversing contactor assemblies with communication interface are required for mounting the function modules for connection to the automation level via the bus system.

The assembly kit contains: Mechanical interlock, connecting clips for 2 contactors, wiring modules on the top and bottom (main circuits, control circuits and auxiliary circuits).

<sup>&</sup>lt;sup>3)</sup> The assembly kit contains: Mechanical interlock, connecting clips for 2 contactors, wiring modules on the top and bottom (main circuits).

## 2.2.4 3RA24 contactor assemblies for star-delta (wye-delta) start

The 3RA24 contactor assembly for star-delta (wye-delta) start consists of three 3-pole contactors (line contactor, star contactor, and delta contactor), main circuit wiring modules, and plug-on function modules for the control circuit wiring.

The 3RA24 contactor assembly for star-delta (wye-delta) start of sizes S00 and S0 is available in two versions:

- Fully wired and tested with electrical and mechanical interlock.
- As a kit for customer assembly.

The fully wired 3RA24 contactor assemblies for star-delta (wye-delta) start can be ordered with the following plug-on function modules:

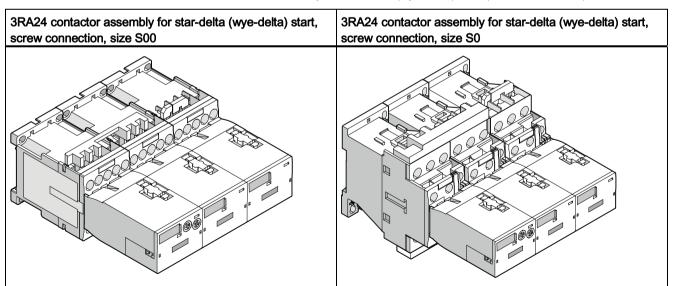
- Without a communication connection.
- With a communication connection.

#### Connection systems

The fully wired 3RA24 contactor assembly for star-delta (wye-delta) start can be supplied either with a screw-type connection system or a spring-loaded connection system.

The illustrations below show the fully assembled contactor assembly for star-delta (wye-delta) start without a communication connection, in the version with the screw-type connection system.

Table 2-8 Illustrations of the 3RA24 contactor assembly for star-delta (wye-delta) start (sizes S00 and S0)



## 2.2.5 Drive options

## **Drive options**

The following drive types are available for 3RH2 contactor relays and 3RT2 power contactors:

	AC drive			DC drive			UC drive
Size	S00, S0 S00			S00, S0			S0
Drive type	50 Hz	60 Hz	50/60 Hz	DC standard drive	DC drive with low power input	DC drives for railway applications	AC or DC connection possible
Preferred voltages	<ul><li>24 V</li><li>110 V</li><li>230 V</li></ul>				<ul><li>24 V</li><li>110 V</li><li>220 V</li></ul>		<ul><li>24 V</li><li>110 V</li><li>220/230 V</li></ul>
Contactor specificatio n	Contactor relays and power contactors with 50 Hz coil (standard version for size S0)	Contactor relays and power contactor s with 60 Hz coil	Contactor relays and power contactors with 50/60 Hz coil (standard version for size S00)	Contactor relays and power contactor s with DC coil	Contactor relays and power contactors with DC coil, optimized for direct control via PLC	Contactor relays and power contactors with DC coil, optimized for railway applications	Power contactors with electronic coil control for control with AC or DC voltage
	<ul> <li>3RT20 power contactors</li> <li>3RH2 contactor relays</li> <li>3RA23 + 3RA24 contactor assemblies</li> </ul>			lies	Coupling relays (versions of the 3RT2 contactors and 3RH2 contactor relays)	Versions of the 3RT2 power contactors and 3RH2 contactor relays	Versions of the 3RT202 power contactors

Additional voltage versions are available on request.

#### Note

The 3RT201 contactors. (size S00) are not suitable for switching capacitors (e.g. DC link capacitors of frequency converters).

## 2.3 Applications

## **Utilization categories**

According to DIN EN 60947-4-1, the application area of and the load applied to power contactors can be identified by looking at the specified utilization category in conjunction with the specified rated operational current or the motor power and the rated voltage. The table below lists the most important utilization categories for contactors.

Utilization	Utilization categories		
AC	Main circuit contacts: Utilization category for AC voltages		
AC-1	Non-inductive or slightly inductive loads, resistance furnaces		
AC-2	Slip-ring motors: starting, switching off		
AC-3	Squirrel-cage motors: starting, switching-off motors during running		
AC-4	Squirrel-cage motors: starting, plugging, inching		
AC-5a	Switching of discharge lamp controls		
AC-5b	Switching of incandescent lamps		
AC-6a	Switching of transformers		
AC-6b	Switching of capacitor banks		
DC	Main circuit contacts: Utilization category for DC voltages		
DC-1	Non-inductive or slightly inductive loads, resistance furnaces		
DC-3	Shunt-wound motors: Starting, plugging, reversing, inching, dynamic braking		
DC-5	Series-wound motors: Starting, plugging, reversing, inching, dynamic braking		
AC	Auxiliary circuit contacts: Utilization category for AC voltages		
AC-12	Control of resistive loads and solid-state loads with isolation by opto couplers		
AC-14	Control of small electromagnetic loads (max. 72 VA)		
AC-15	Control of electromagnetic loads (over 72 VA)		
DC	Auxiliary circuit contacts: Utilization category for DC voltages		
DC-12	Control of resistive loads and solid-state loads with isolation by opto couplers		
DC-13	Control of electromagnets		

## 2.4 Performance features

The SIRIUS range of contactors offers the following technical advantages:

Technical highlights	Customer benefits
Uniform connection systems:	The right connection for every application (e.g. operational reliability (vibration-resistant, non-temperature-specific, etc.) and less wiring thanks to spring-loaded connection system)
Screw connection	
Spring-loaded connection	
Ring cable lug connection	
Solder pin connection	
Link modules for any device combination from the SIRIUS modular system	Fast, error-free installation for screw-type and spring-loaded connection system
Power contactors up to 38 A (18.5 kW) in 45 mm width	Space and cost savings
Factory-fitted integrated auxiliary switches	Reduced installation complexity
High contact reliability of the auxiliary switches	Enhanced operational reliability (reduction of fault signals)
Joint range of accessories for size S00 and S0	Easy to configure, reduced stockkeeping
Plug-on function modules for connection without tools	Fault avoidance and reduced wiring (without tools)
Connection to AS-Interface or IO-Link	Reduced wiring and integration in TIA

## Reference

More information	Is available in
about the 3RT2, 3RH2, and 3RA23/3RA24 contactors and contactor assemblies	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS Innovations - SIRIUS 3RT2 Contactors/Contactor Assemblies" manual.

SIRIUS 3RF34 solid-state switching devices

3

#### 3.1 Device versions

Solid-state switching devices are primarily used in single-phase applications, which have to meet the following requirements:

- Very high switching frequencies (> 1000 switching operations per hour)
- Resistive loads

The SIRIUS modular system features single- and three-phase solid-state contactors and solid-state relays for the frequent switching of resistive loads. Three-phase solid-state contactors and solid-state reversing contactors are available for switching motorized loads. Standardized function modules for various applications complete the range of SIRIUS solid-state switching devices.

The solid-state contactor and solid-state reversing contactor versions listed in this manual are intended specifically for operation on three-phase motors up to 7.5 kW.

#### Overview

These 2-phase controlled instantaneous switching solid-state switching devices are operated in two mounting widths in an insulating enclosure:

- In 45 mm width
  - Up to 5.2 A as solid-state contactor (motor contactor) or
  - Up to 5.4 A as solid-state reversing contactor and
- In 90 mm width
  - Up to 16 A as solid-state contactor or
  - Up to 7.4 A as solid-state reversing contactor

This means that it is possible to operate motors up to 7.5 kW.

The solid-state contactors and solid-state reversing contactors for screw-type connection can be connected directly to a motor starter protector with a 3RA2921-1BA00 link module. Direct mounting of a 3RB30/3RB31 solid-state overload relay and, in some cases, a 3RR2 current monitoring relay, is also possible. This provides a time-saving way of implementing rapid-switching motor feeders with and without fuses.

#### 3.1 Device versions

#### **Versions**

The following table provides an overview of the versions of the 3RF34 instantaneous switching solid-state contactors for switching motors.

Table 3- 1 Versions of solid-state switching devices

Characteristic	Versions			
Version	Solid-state contactor	Solid-state reversing contactor		
Description	Complete devices in insulated enclosures for frequent switching on and switching off of AC drives.	Compact design of the reversing circuit for frequent switching on and switching off of AC drives with continuous reversal of the direction of rotation		
Order numbers	3RF34BB	3RF34BD		
Size	S0			
Width (motor power <sup>1)</sup> /max.	• 45 mm (motors up to 2.2 kW, 5.2 A)	• 45 mm (motors up to 2.2 kW, 5.4 A)		
rated operational current)	• 90 mm (motors up to 7.5 kW, 16 A)	• 90 mm (motors up to 3.0 kW, 7.4 A)		
Number of poles	3	3		
Connection system	Screw-type and spring-loaded terminals	Screw-type		
Rated operating voltage	Up to 600 V	Up to 480 V		
Rated control supply voltage	24 V DC and 110 to 230 V AC			
Switching delay ON-delay OFF-delay	1 ms (24 V DC), 5 ms (110 to 230 V AC) 1 ms (24 V DC), 30 ms (110 to 230 V AC) plus up to one half-wave	5 ms (24 V DC), 20 ms (110 to 230 V AC) 5 ms (24 V DC), 10 ms (110 to 230 V AC) plus up to one half-wave		
Interlock time	60 to 100 ms (24 V DC), 50 to 100 ms (110 to 230 V AC)			
Enclosure	Insulated (no grounding required)			
Control connections	Screw-type connection system and spring- loaded connection system, removable terminal for auxiliary circuit wiring (2 contacts)	Screw-type connection system, removable terminal for auxiliary circuit wiring (3 contacts)		

<sup>1)</sup> Rating data relates to 400 V line voltage

## 3.2 Applications

#### Solid-state switching devices for switching motors

The **solid-state contactors** for the wear-free and noiseless switching of motors are designed for the frequent switching on and switching off of AC drives up to 7.5 kW as well as for reversing up to 3.0 kW. The devices are fully insulated and can be mounted directly on motor starter protectors and overload relays or SIRIUS current monitoring relays, which makes them really easy to integrate into motor feeders.

These 3-phase solid-state contactors are equipped with a 2-phase control which is particularly suitable for typical motor circuits without a connection to the neutral conductor.

The integration of four current paths to form a single reversing circuit, accommodated in one enclosure, makes the **solid-state reversing contactor** a particularly compact solution. Unlike conventional systems which require two contactors, width can be reduced by up to 50% with the 3-phase solid-state reversing contactors. Devices with a width of 45 mm cover motors up to 2.2 kW and those with a width of 90 mm cover motors up to 3 kW.

Integration in the SIRIUS modular system facilitates connection to a SIRIUS motor starter protector via a link module or to a 3RB30/3RB31 solid-state overload relay or a 3RR2 current monitoring relay without additional steps. As a result, fuseless or fused motor feeders can be implemented quickly and easily.

#### Main features:

- Insulated enclosure with integrated heat sink
- Degree of protection IP20
- Integrated mounting foot for snapping on a DIN rail or mounting on a support plate
- Variety of connection systems
- Plug-in control connection
- LED to indicate control voltage

# 3.3 Application environment

## General operating conditions

The following table lists the general operating conditions under which the product may be operated.

Table 3- 2 General operating conditions

Operating conditions	Value
Degree of protection	IP20
Ambient temperature during operation	- 25 to 60 °C
Installation altitude	0 to 1000 m;
	at > 1,000 m seek advice from Technical Assistance (www.siemens.com/industrial-controls/technical-assistance)
Shock resistance	15 g/11 ms; acc. to DIN IEC 68-2-27
Vibration resistance	2 g; acc. to DIN IEC 68-2-6
EMC conditions	Acc. to DIN IEC 60947-4-2, DIN IEC 61000-4-2, DIN IEC 61000-4-4, DIN IEC 61000-4-5, and DIN IEC 61000-4-6,
Insulation strength 50/60 Hz	4,000 V <sub>rms</sub>

## 3.4 Solid-state switching devices

connection system

#### Operator controls and equipment

#### Solid-state contactor

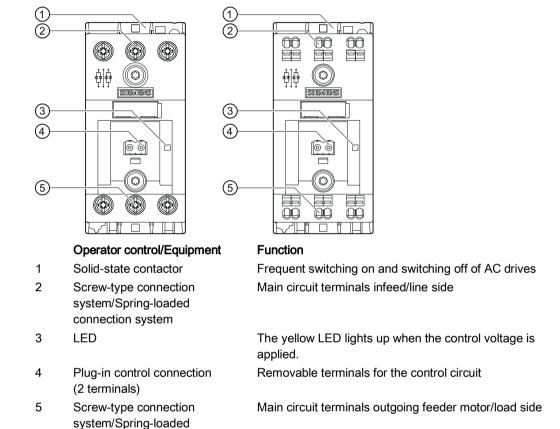
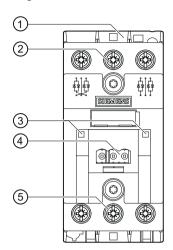


Figure 3-1 Solid-state contactor overview - Screw-type connection system and spring-loaded connection system

## Solid-state reversing contactor

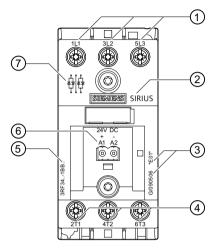


	Operator control/Equipment	Function
1	Solid-state contactor	Frequent switching on and switching off of AC drives
2	Screw-type connection system	Main circuit terminals infeed/line side
3	LEDs	The left-hand LED lights up yellow when counterclockwise rotation is activated (control voltage applied at terminal A1 and A2).
		The right-hand LED lights up yellow when clockwise rotation is activated (control voltage applied at terminal A3 and A2).
4	Plug-in control connection (3 terminals)	Removable terminals for the control circuit
5	Screw-type connection system	Main circuit terminals outgoing feeder motor/load side

Figure 3-2 Solid-state reversing contactor overview - Screw-type connection system

## 3.5 Device labels

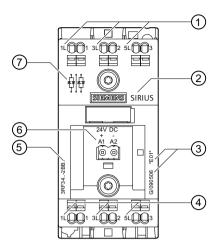
#### **Device labels**



- 1 Labeling to identify the main circuit terminals infeed/line side
- 2 SIRIUS (device group)
- 3 Production date/Product version
- 4 Labeling to identify the main circuit terminals outgoing feeder motor/load side
- 5 Order designation
- 6 Labeling to identify the control circuit terminals and indication of the control voltage (See also the diagrams below, "Labeling on solid-state contactors, zoom view".)
- 7 Circuit diagram

Figure 3-3 Labeling to identify solid-state contactors with screw-type connection system

#### 3.5 Device labels



- 1 Labeling to identify the main circuit terminals infeed/line side
- 2 SIRIUS (device group)
- 3 Production date/Product version
- 4 Labeling to identify the main circuit terminals outgoing feeder motor/load side
- 5 Order designation
- 6 Labeling to identify the control circuit terminals and indication of the control voltage (See also the diagrams below, "Labeling on solid-state contactors, zoom view".)
- 7 Circuit diagram

Figure 3-4 Labeling to identify solid-state contactors with spring-loaded terminals

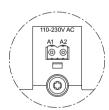


Figure 3-5 Labeling on solid-state contactors with AC control voltage, zoom view

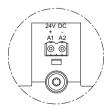
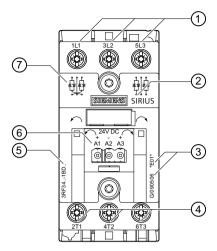


Figure 3-6 Labeling on solid-state contactors with DC control voltage, zoom view



- 1 Labeling to identify the main circuit terminals infeed/line side
- 2 SIRIUS (device group)
- 3 Production date/Product version
- 4 Labeling to identify the main circuit terminals outgoing feeder motor/load side
- 5 Order designation
- 6 Labeling to identify the control circuit terminals and indication of the control voltage (See also the diagrams below, "Labeling on solid-state reversing contactors, zoom view".)
- 7 Circuit diagram

Figure 3-7 Labeling to identify solid-state reversing contactors with screw connection

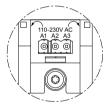


Figure 3-8 Labeling on solid-state reversing contactors with AC control voltage, zoom view

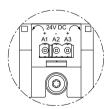


Figure 3-9 Labeling on solid-state reversing contactors with DC control voltage, zoom view

# 3.6 Advantages of solid-state switching devices

## Technical advantages/Customer benefits

Table 3-3 Advantages of solid-state switching devices

Technical highlights	Customer benefits		
Top customer benefits			
Removable terminals for auxiliary circuit wiring	Avoidance of wiring errors if devices need to be replaced		
Integrated electrical interlocking	Cost savings and fault avoidance		
All motor contactors available in spring-loaded connection system	Improved operational reliability and quicker wiring		
Wear-free switching	Long contact service life avoids cyclic replacement in applications with high switching frequency. The system is in operation for longer.		
Other customer benefits			
Screw connection with practical cross-sections	Flexible cable selection based on application at hand		
Link modules from motor starter protector to switching device	Fast, fault-free assembly for screw-type connection system		
Noise-free switching	Can be used in residential environments thank to reduced switching noise		
Integrated combination tests for fuseless and fused assembly	Planning reliability		
Comprehensive approvals	Global applicability		
Uniform tools and torques for all devices	Quick and easy installation		
Only a small number of different power versions up to 7.5 kW	Easy configuration		
Versions supporting wide voltage range 110 to 230 V AC	Saves storage costs thanks to a reduction of the number of variants at the customer end		
Extensive CAx data provision	Easy and fault-free configuration		
Data sheets in 10 languages per order number	Daily updated technical data available in 10 languages		

#### Reference

More information	Is available in
about the 3RF34 solid-state switching devices	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS Innovations - SIRIUS 3RF34 Solid-State Switching Devices" manual.

SIRIUS 3RW30/3RW40 soft starters

## 4.1 Fields of application

Soft starters are used to start three-phase induction motors with reduced torque and reduced starting current.

## SIRIUS soft starter family

The SIEMENS SIRIUS soft starter family comprises three different versions with different functionalities and prices.

#### 3RW30 and 3RW40

Simple or standard applications are covered by the SIRIUS 3RW30 and 3RW40 soft starters and are described in a separate manual.

#### 3RW44

The SIRIUS 3RW44 soft starter is used if higher functionality is specified, e.g. communication over PROFIBUS or the availability of measuring and monitoring values, as well as for ultra-heavy-duty starting. The SIRIUS 3RW44 soft starter is described in a separate system manual.

### 4.2 Reference

#### Reference

More information	Is available in
about the 3RW soft starters	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS 3RW30/3RW40 Soft Starters" manual and the "SIRIUS 3RW44 Soft Starters" manual.

4.3 Basic physical principles of a three-phase induction motor

## 4.3 Basic physical principles of a three-phase induction motor

#### 4.3.1 Use

SIRIUS soft starters are used to reduce the current and torque of a three-phase induction motor during the startup process.

## 4.3.2 Three-phase induction motor

## Fields of application

Three-phase induction motors are used in a wide range of applications in commerce, industry, and trade owing to their simple, robust design and their minimal maintenance.

#### **Problem**

If a three-phase induction motor is started directly, its typical current and torque characteristics can cause disturbances in the supply system and the load machine.

## Starting current

Three-phase induction motors have a high direct starting current I<sub>starting</sub>. Depending on the motor type, this current can be between three and fifteen times as high as the rated operational current. Seven or eight times the motor's rated current can be assumed as a typical value.

## Disadvantage

This results in the following disadvantage:

 Higher load on the electrical supply system. The supply system must therefore be dimensioned for this higher power during the motor startup.

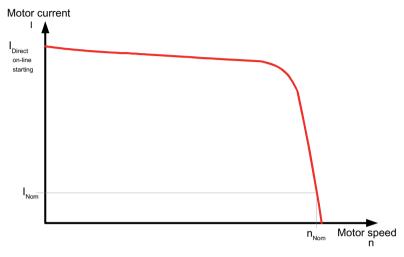


Figure 4-1 Typical starting current characteristic of a three-phase induction motor

### Starting torque

The starting torque and the breakdown torque can usually be assumed to be between two and four times the rated torque. From the point of view of the load machine, this means that the starting and acceleration forces exert a higher mechanical load on the machine and the product being conveyed compared to nominal operation.

### Disadvantages

This results in the following disadvantages

- A higher load is placed on the machine's mechanical components
- The costs for replacing worn parts and maintaining the application are higher

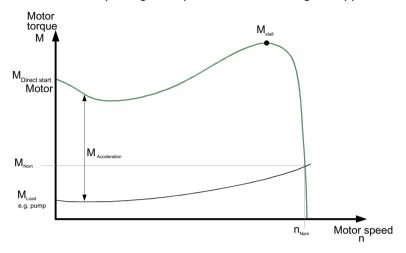


Figure 4-2 Typical starting torque characteristic of a three-phase induction motor

### Remedy

The SIRIUS 3RW30 and 3RW40 electronic soft starters allow the current and torque characteristics during starting to be optimally adapted to the requirements of each application.

## 4.4 Functional principle of the SIRIUS 3RW30 and 3RW40 soft starters

The SIRIUS 3RW30 and 3RW40 soft starters have two antiparallel thyristors in two out of the three phases. These are one thyristor for the positive and one for the negative half-wave in each case (see Figure 4-5 Phase angle control and schematic diagram of a two-phase controlled soft starter with integral bypass contacts (Page 127)). The current in the third, uncontrolled phase is the sum of the currents in the controlled phases.

The rms value of the motor voltage is increased (from a settable starting voltage) to the rated motor voltage within a definable ramp-up time by means of the phase angle control.

The motor current changes in proportion to the voltage applied to the motor. As a result, the starting current is reduced by the factor of this voltage.

There is a quadratic relationship between the torque and the voltage applied to the motor. As a result, the starting torque is reduced quadratically in relation to this voltage.

### Example

#### SIEMENS 1LG4253AA motor (55 kW)

Rated data at 400 V

P<sub>e</sub>: 55 kW l<sub>e</sub>: 100 A

Idirect starting: Approx. 700 A

M<sub>e</sub>: 355 Nm; e.g.:  $M_e = 9.55 \times 55 \text{ kW } \times \frac{1000}{1480 \text{ min}^{-1}}$ 

 $n_e$ : 1480 rpm

M<sub>direct starting</sub>: Approx. 700 Nm

Set starting voltage: 50 % (½ of mains voltage)

=> I<sub>starting</sub> ½ of direct starting current (approx. 350 A) => M<sub>starting</sub> ¼ of direct starting torque (approx. 175 Nm)

The diagrams below show the starting current and torque characteristics for a three-phase induction motor in combination with a soft starter:

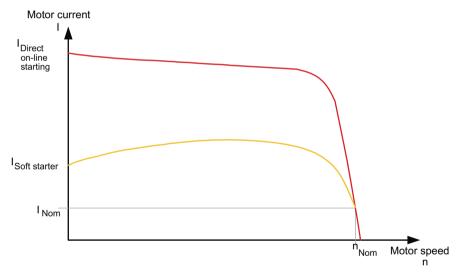


Figure 4-3 Reduced current characteristic of a three-phase induction motor during starting with a SIRIUS 3RW30 or 3RW40 soft starter

#### 4.4 Functional principle of the SIRIUS 3RW30 and 3RW40 soft starters

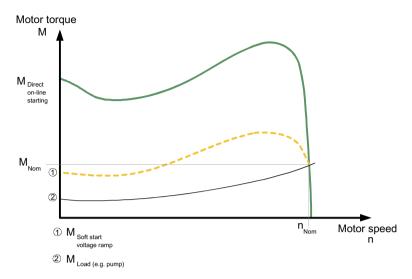


Figure 4-4 Reduced torque characteristic of a three-phase induction motor during starting with a SIRIUS 3RW30 or 3RW40 soft starter

#### Soft start /soft ramp-down

This means that, since the motor voltage is controlled by the electronic soft starter during the startup process, the consumed starting current and the starting torque generated in the motor are also controlled.

The same principle is applied during the stop process. This ensures that the torque generated in the motor is gradually reduced, so that the application can stop smoothly (the soft ramp-down function is only supported by the 3RW40).

The frequency remains constant during this process and corresponds to the mains frequency, in contrast to frequency controlled starting and stopping of a frequency converter.

#### See also

Bypass mode (Page 127)

## 4.4.1 Bypass mode

#### Bypass mode

Once the motor has been started up correctly, the thyristors are subject to fully advanced control, meaning that the whole mains voltage is applied to the motor terminals. As the motor voltage does not have to be controlled during operation, the thyristors are bridged by integral bypass contacts that are rated for AC1 current. This minimizes the waste heat generated during uninterrupted duty (which is caused by the thyristor's power loss), and minimizes heating up of the switching device's environment.

The bypass contacts are protected by an integrated, electronic arc quenching system during operation. If they are opened in the event of a fault, e.g. if the control voltage is temporarily interrupted, mechanical vibrations occur, or the coil operating mechanism or the main contact spring has reached the end of its service life and is defective, the equipment is not damaged.

The diagram below shows the method of operation of the SIRIUS 3RW30 and 3RW40 soft starters:

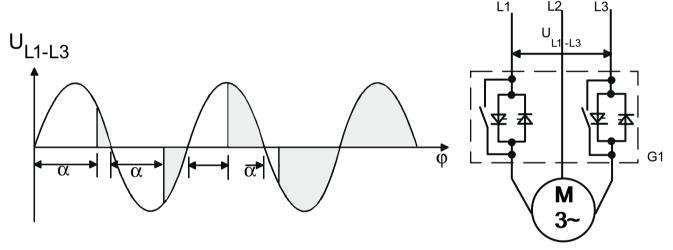


Figure 4-5 Phase angle control and schematic diagram of a two-phase controlled soft starter with integral bypass contacts

## 4.4.2 Method of operation of a two-phase controlled soft starter

A special method of operation is used for the SIRIUS 3RW30 and 3RW40 two-phase controlled soft starters based on SIEMENS' patented "polarity balancing" control principle.

#### Two-phase control

The SIRIUS 3RW30 and 3RW40 soft starters are two-phase controlled soft starters, in other words they are designed with two antiparallel thyristors in each of phases L1 and L3. Phase 2 is an uncontrolled phase, which is merely guided through the starter by a copper connection.

In a two-phase controlled soft starter, the current that results from the superimposition of the two controlled phases flows in the uncontrolled phase. The main advantages of two-phase control include the more compact size compared to a three-phase version and the lower hardware costs.

The occurrence of DC components, caused by the phase angle and the overlapping phase currents, is a negative physical effect of two-phase control during the startup process that can mean a louder noise is produced by the motor. The "polarity balancing" control principle was developed and patented by SIEMENS to prevent these DC components during starting.

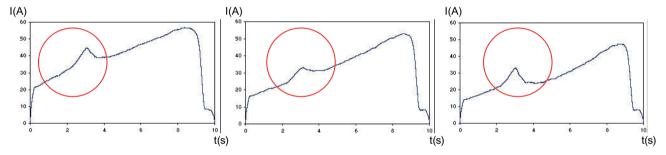


Figure 4-6 Current characteristic and occurrence of DC components in the three phases without "polarity balancing"

## Polarity balancing

"Polarity balancing" effectively eliminates these DC components during the ramp-up phase. It allows the motor to be started up with a constant speed, torque, and current rise.

The acoustic quality of the startup process comes very close to that of a three-phase controlled startup. This is made possible by the continuous dynamic alignment and balancing of current half-waves with different polarities during the motor startup.

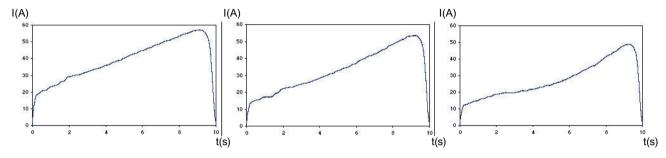


Figure 4-7 Current characteristic in the three phases without DC components thanks to "polarity balancing"

### 4.4.3 Starting current asymmetry

With two-phase control the starting current is asymmetrical for physical reasons, because the current in the uncontrolled phase is the sum of the currents in the two controlled phases.

This asymmetry can be as much as 30 to 40% during starting (ratio of minimum current to maximum current in all three phases).

Even though this cannot be influenced, it is not critical in most applications. It could cause an insufficiently rated fuse to trip in the uncontrolled phase, for instance. Recommended fuse ratings can be found in the "SIRIUS 3RW30/3RW40 Soft Starters" manual.

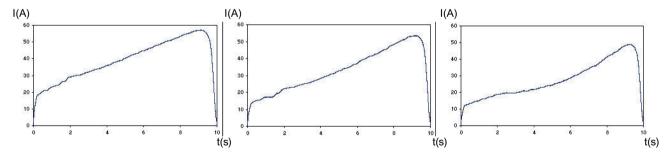


Figure 4-8 Starting current asymmetry

#### 4.4 Functional principle of the SIRIUS 3RW30 and 3RW40 soft starters

#### Note

If wye-delta starters are exchanged for soft starters in an existing system, you should check the fuse ratings in the feeder in order to avoid false tripping. This is particularly important in connection with heavy-duty starting or if the fuse that is installed has already been operated close to the thermal tripping limit with the wye-delta assembly.

All elements of the main circuit (such as fuses, motor starter protectors, and switching devices) must be dimensioned for direct starting and according to the on-site short-circuit conditions, and ordered separately.

You can find recommended fuse and motor starter protector ratings for the feeder with soft starter in the "SIRIUS 3RW30/3RW40 Soft Starters" manual.

#### Reference

More information	Is available in
about the recommended fuse ratings	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS 3RW30/3RW40 Soft Starters" manual.
about the recommended fuse and motor starter protector ratings for the feeder with soft starter	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS 3RW30/3RW40 Soft Starters" manual.

#### 4.4.4 Applications and use

#### Applications and selection criteria

The SIRIUS 3RW30 and 3RW40 soft starters represent a good alternative to direct or wyedelta starters.

The most important advantages are:

- Soft start
- Soft stop (3RW40 only)
- Uninterrupted switching without current peaks that place a heavy load on the system
- Simple installation and commissioning
- Compact, space-saving design

## **Applications**

The typical applications include:

- Conveyor belts
- Roller conveyors
- Compressors
- Fans
- Pumps
- Hydraulic pumps
- Agitators
- Circular saws / band saws

## **Advantages**

Conveyor belts and transport systems:

- Smooth starting
- Smooth stopping

Rotary pumps and piston pumps:

- No pressure surges
- Increased service life of the pipe system

Agitators and mixers:

Reduced starting current

#### Fans:

• Protection for the gearbox and V belt

## 4.5 Comparison of device functions

## 4.5.1 Soft starter functions

				S managamana 1955
		SIRIUS 3RW30	SIRIUS 3RW40	SIRIUS 3RW44
		Standard applications	Standard applications	High Feature applications
Rated current at 40 °C / 50 °C	A	3106 / 3 98		29 1214 / 26 1076
Rated operational voltage	V	200480	200600	200690
Motor rating at 400 V / 460 V •Standard connection •Inside-delta circuit	kW /hp	1.555 / 1.5 75	5.5250 / 7.5 300 -	15710 / 15 950 221200 / 30 1700
Ambient temperature	°C	-25+60	-25+60	0 + 6 0
Soft start/soft stop		<b>✓</b> <sup>1)</sup>	V	V
Voltage ramp		<b>~</b>	V	V
Starting/stopping voltage	%	40100	40100	20100
Ramp-up and ramp-down time	S	020	020	1360
Torque control		_	-	V
Starting/stopping torque	%	_	_	20100
Torque limiting	%	_	_	20200
Ramp time	s	_	_	1360
Integrated jumper contact system		<b>V</b>	<b>v</b>	V
Intrinsic device protection		_	<i>V</i>	<u> </u>
Motor overload protection		_	<b>√</b> <sup>7)</sup>	·
Thermistor motor protection		_	<b>v</b> <sup>2)</sup>	<b>V</b>
Integrated remote RESET		_	<b>v</b> <sup>3)</sup>	
Settable current limiting		_	<i>V</i>	<u> </u>
Inside-delta circuit		_	-	<b>V</b>
Breakaway torque		_	_	<u> </u>
Creep speed in both directions of rotation		_	_	
Pump stop		_	_	<b>4</b> )
DC braking		_	_	4) 5)
Combined braking		_	_	<b>√</b> <sup>4) 5)</sup>
Motor heating		_	-	
Communication		_		With PROFIBUS DP (option)
External display and operator control module		-	-	(option)
Status measured value display		_	-	(option)
Error log		_	_	· ·
Events list		_	_	V
Min/max pointer function		_	-	
Trace function		_	_	<b>(</b> 6)
Programmable control inputs and outputs		_	_	
Number of parameter sets		1	1	3
Parameterizing software (SoftStarterES)		' -	-	, , , , , , , , , , , , , , , , , , ,
Power semiconductors (thyristors)		2 controlled phases	2 controlled phases	3 controlled phases
Screw terminals		✓ Controlled phases	∠ controlled priases	or controlled priases ✓
Spring-loaded terminals		<i>V</i>	<i>V</i>	V
UL/CSA		<i>V</i>	<i>∨</i>	V
CE mark		<i>V</i>	<i>V</i>	V
Soft starting under heavy-duty starting		_	_	<b>✓</b> <sup>4)</sup>
Support for configuration			_ c selection slider, Technical Assistance ++4	<u> </u>

Support for configuration

✔ Function available; – function not available.

1) For 3RW30 only soft start.

2) Optional up to size S3 (device variants).

Win-Soft Starter, electronic selection slider, Technical Assistance ++49 9118955900

3) For 3RW402. to 3RW404.; for 3RW405. and 3RW407. optional.

4) If necessary, overdimension soft starter and motor.

5) Not possible in inside-delta circuit.

6) Trace function with SoftStarterES software.7) Acc. to ATEX

## Reference

More information	Is available in
about the 3RW soft starters	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS 3RW30/3RW40 Soft Starters" manual and the "SIRIUS 3RW44 Soft Starters" manual.

4.5 Comparison of device functions

SIRIUS 3RV2 motor starter protectors

## 5.1 Introduction

### **Applications**

3RV2 motor starter protectors are compact current-limiting devices which have been optimized for load feeders. They are used for switching and protecting three-phase motors and other loads. The scalable setting ranges mean that a suitable motor starter protector can provide protection for all standard motors, even at ambient temperatures of > 60 °C. All 3RV2 motor starter protectors are fitted with a rotary operating mechanism.

#### **Functions**

The motor starter protectors protect loads against overloads and short circuits. They also feature a lockable switch to facilitate manual switching on and off (e.g. in the event of repair work).

## System integration

In both electrical and mechanical terms the motor starter protectors are compatible with 3RT contactors, 3RF solid-state contactors, and 3RW soft starters. They can be integrated in the feeder by means of direct mounting. 3RV2 motor starter protectors are available in two sizes, S00 and S0.

#### Connection systems

The motor starter protectors are available with the following connection system options:

- Screw-type connection system (up to 40 A)
- Spring-loaded connection system (up to 32 A)
- Ring cable lug connection system (up to 32 A)

#### Accessories

The accessories have been tailored to the motor starter protectors; they can be mounted easily and without the need for tools.

## 5.2 Versions

#### **Device versions**

- Motor starter protectors, standard version (3RV20)
  - Overload and short-circuit protection
- Motor starter protectors with relay function (3RV21)
  - Short-circuit protection and auto-RESET in the event of overload in one device
- MSP for starter combinations (3RV23)
  - Short-circuit protection only
  - Combined with solid-state overload relay, large setting ranges and auto-RESET
- MSP for transformer protection (3RV24)
  - Standard version for transformers
- Circuit breakers in accordance with UL489 (3RV27/3RV28)
   Overload protection, short-circuit protection, and transformer protection

#### **Sizes**

3RV2 motor starter protectors are available in two sizes, S00 and S0.

The table below lists the sizes and the corresponding maximum rated current at a voltage of 400 V AC. The last column of the table indicates the maximum power of the three-phase motor which is suitable for the relevant size.

Table 5- 1 Motor starter protector sizes

Size	Width	Max. rated current	Power of three-phase motor
S00	45 mm <sup>1)</sup>	16 A	7.5 kW
S0	45 mm <sup>1)</sup>	40 A <sup>2)</sup>	18.5 kW

<sup>1) 3</sup>RV21: 65 mm

#### Number of poles

3RV2 motor starter protectors have 3 poles.

<sup>2) 3</sup>RV20 and 3RV23 only

## 5.3 Applications

#### General

3RV2 motor starter protectors are used for switching and protecting the following loads:

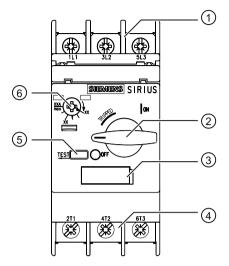
- Three-phase motors up to 18.5 kW at 400 V AC
- Loads with rated currents of up to 40 A

## Special applications

The various 3RV2 motor starter protectors are suitable for:

- Short-circuit protection
- Motor protection (also with overload relay function)
- System protection
- Short-circuit protection for starter combinations
- Transformer protection
- As main and EMERGENCY OFF switches
- Use in IT systems
- Switching direct current
- Hazardous areas (ATEX)
- Use as Branch Circuit Protection Device (BCPD) according to UL (3RV27/28)

## 5.4 Motor starter protectors



#### 1 Terminals:

Up to two conductors with different cross-sections can be connected for the main and auxiliary circuits. The auxiliary circuit can be connected using either screw terminals or spring-loaded terminals. Some device versions are also available with ring cable lug connection.

- 2 Rotary operating mechanism:
  - For switching on and off, displaying a possible tripping operation, integrated locking device
- 3 Labe
- 4 Connection for mounting contactors, solid-state contactors, and soft starters in various connection systems:
  - · Direct mounting using link modules
  - Separately using connecting cables
- 5 TEST function:

Facilitates the testing of the release mechanism.

6 Motor current setting:

The large rotary button provides an easy means of setting the device to the rated motor current.

Figure 5-1 Equipment, 3RV20 motor starter protectors

A sealable transparent cover can be optionally mounted (accessory). The cover prevents the motor setting being adjusted (this option is not available for 3RV23/3RV27/3RV28).

## 5.5 Performance features

SIRIUS motor starter protectors boast the following technical advantages:

Technical highlights	Customer benefits		
10-20% less power consumption than previous solutions	<ul> <li>Reduced temperature rise in the control cabinet</li> <li>Cost savings during operation</li> </ul>		
Uniform connection systems:  Screw connection Spring-loaded connection Ring cable lug connection	The right connection for every application (e.g. operational reliability (vibration-resistant, non-temperature-specific, etc.) and less wiring thanks to spring-loaded connection system)		
Link modules for any device combination from the SIRIUS modular system	Fast, error-free installation for screw-type connection system and spring-loaded connection system		
Motor starter protectors up to 40 A (18.5 kW) in 45 mm width	Space and cost savings		
Motor starter protector combined with undervoltage release and contactor can be used as a Cat. 3 feeder in accordance with EN 951-1, SIL 2 in accordance with IEC 62061 or PL d 13849-1	Safety solution can be implemented with just one switching device		
Factory-fitted integrated auxiliary switches	Reduced installation complexity		
Joint range of accessories for size S00 and S0	Easy to configure, reduced stockkeeping		
Current values graded in accordance with all standard motors	<ul> <li>The right motor starter protector for every standard motor</li> <li>Integrated protection even for ambient temperatures &gt; 60 °C</li> </ul>		
Bimetals with extreme long-term stability	Operational reliability over many years		
Compatible for use in all infeed systems (combs, 3RA6, 3RV29 infeed, 8US)	Maximum flexibility in terms of power infeed		

## Reference

Is available in	
the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS Innovations - SIRIUS 3RV2 Motor Starter Protectors" manual.	

5.5 Performance features

# SIRIUS 3RU2/3RB3, 3RB24 overload relays

6

## 6.1 SIRIUS 3RU2/3RB3 overload relays

#### 6.1.1 Introduction

#### 3RU21 thermal overload relays

3RU21 thermal overload relays up to 40 A have been designed to provide current-dependent protection for loads with normal starting against impermissibly high temperature rises due to overload, phase asymmetry or phase failure.

An overload or phase failure results in an increase of the motor current beyond the set rated motor current. Via heating elements, this current rise increasingly heats up the bimetal strips located inside the device. The deflection of these bimetal strips eventually activates the auxiliary contacts via a release mechanism. The contacts then disconnect the load via a contactor. (The contactor function is not an integral component of the overload relay).

#### 3RB30/3RB31 solid-state overload relays

3RB30/3RB31 solid-state overload relays up to 40 A have been designed to provide current-dependent protection for loads with normal and heavy-duty starting against impermissibly high temperature rises due to overload, phase asymmetry or phase failure.

An overload, phase asymmetry or a phase failure results in an increase of the motor current beyond the set rated motor current.

This current rise is detected by the current transformers integrated in the devices and evaluated by corresponding solid-state circuits which then supply a pulse to the auxiliary contacts. The contacts then disconnect the load via a contactor. (The contactor function is not an integral component of the overload relay).

In addition to current-dependent protection for loads against impermissibly high temperature rise caused by overload, phase asymmetry, and phase failure, 3RB31 solid-state overload relays feature internal ground-fault detection (not possible in conjunction with contactor assemblies for star-delta (wye-delta) start). This provides protection of loads against high-impedance faults to ground caused by damaged insulation, moisture, condensation, etc.

#### System integration

The overload relays have been matched to the contactors in the 3RT2 series both electrically and mechanically and can be integrated in the feeder by means of direct mounting. The 3RU2 thermal overload relays and the 3RB30 and 3RB31 solid-state overload relays are available in two sizes, S00 and S0.

### Connection systems

The overload relays are available with the following connection system options:

- Screw-type connection system
- Spring-loaded connection system
- Ring cable lug connection system (3RU21 only)

#### Accessories

The accessories have been tailored to the overload relays; they can be mounted easily and without the need for tools.

#### 6.1.2 Versions

#### Sizes, setting ranges, and device versions

The table below provides an overview of the various sizes in which 3RU21 thermal overload relays and 3RB30/3RB31 solid-state overload relays are available. The maximum rated currents, the minimum and maximum setting ranges, and the available tripping classes are listed for each individual size.

Table 6-1 Sizes

Size (width 45 mm each)	3RU21 thermal overload relay	3RB30 solid-state overload relay	3RB31 solid-state overload relay
Rated operational voltage U <sub>e</sub>	690 V AC	690 V AC	690 V AC
Rated frequency	50/60 Hz	50/60 Hz	50/60 Hz
Tripping classes	CLASS 10	CLASS 10 or 20 (fixed)	CLASS 5, 10, 20, 30 (adjustable)
Current ranges	S00: 0.11 to 16 A	-	-
for 3RU21 thermal overload relays	S0: 1.8 to 40 A		
Current ranges	-	S00: 0.1 to 16 A	S00: 0.1 to 16 A
for 3RB3 solid-state overload relays		S0: 0.1 to 40 A	S0: 0.1 to 40 A
Rated operational power for three-	S00: 0.04 to 7.5 kW	S00: 0.04 to 7.5 kW	0.04 kW
phase motors at 400 V AC	S0: 0.75 to 18.5 kW	S0: 0.04 to 18.5 kW	to 18.5 kW

3RB30/3RB31 solid-state overload relays have the same dimensions as 3RU21 thermal overload relays. As a result, the thermal overload relays can be replaced easily with the electronic variant 3RB30/3RB31. This is necessary, for example, when lower demands are placed on overload protection (wide setting ranges (1:4), for example, or even reduced power loss and, as a result, minimized energy consumption).

## 6.1.3 Applications

Table 6-2 Overview of applications

Applications	3RU21	3RB30/3RB31	
System protection	<b>√</b> 1)	<b>√</b> 1)	
Motor protection	✓	✓	
Alternating current, 3-phase	✓	✓	
Alternating current, 1-phase	✓	-	
DC current	✓	-	

In the main circuit, the devices provide overload protection for the assigned electrical loads (e.g. motors), feeder cable, and other switching and protection devices in the respective load feeder. The 3 phases have to be under symmetrical load.

### 3RU21 thermal overload relays

3RU21 thermal overload relays have been designed to protect three-phase loads, DC loads, and single-phase AC loads.

#### Note

#### Protection of DC loads/single-phase AC loads

If a 3RU21 thermal overload relay is to be used to protect DC loads or single-phase AC loads, all the bimetal strips have to be heated. Therefore, all of the relay's main current paths have to be connected in series.

#### 3RB30/3RB31 solid-state overload relays

3RB30/3RB31 solid-state overload relays are designed to protect three-phase loads in sinusoidal 50/60 Hz voltage supplies.

#### Note

#### DC loads/Single-phase AC loads

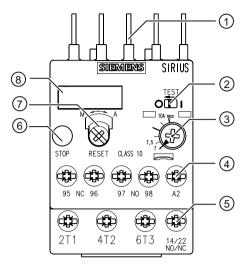
The relay is not suitable for protecting DC loads or single-phase AC loads. In the case of loads with single-pole load, the 3RU21 thermal overload relay or the 3RB22/3RB23 solid-state overload relay (only suitable for the protection of single-phase AC loads) should be used.

### The advantages of load feeders with overload relays

Installing load feeders with overload relays (fuses + contactor + overload relay or MSP for starter combinations/circuit breaker (acc. to UL) + contactor + overload relay) has the following advantages over configurations without overload relays (motor starter protector + contactor):

- Overload release and short-circuit release are signaled separately. In the event of a short
  circuit the fuses or the MSP for starter combinations/circuit breaker (acc. to UL) limit the
  short-circuit current and in the event of an overload the overload relay disconnects the
  contactor (and thus the load).
- At voltages higher than 400 V, fuses have a short-circuit breaking capacity of more than 100 kA. Therefore, the fused option comprising fuses + contactor + overload relay is often used in 690 V supplies.
- An automatic RESET can be performed easily in conjunction with an overload relay. As a result, the feeder does not have to be powered back up locally following an overload release.
- Attachable electrical and mechanical RESET modules which are compatible for use with all sizes enable 3RU21 thermal overload relays to be reset remotely. Mechanical RESET modules which are compatible for use with all sizes can also be attached to 3RB30/3RB31 solid-state overload relays. An electrical remote RESET is an integral component of the 3RB31.
- Lengthy start times can be achieved with 3RB30/3RB31 solid-state overload relays.
- 3RB30/3RB31 solid-state overload relays support wide setting ranges of 1:4.
- MSP for starter combinations/circuit breaker (acc. to UL) + contactor + overload relay combinations have the advantage that the load feeder can be isolated easily and all three poles can be disconnected in the event of a short circuit.

## 6.1.4 3RU21 thermal overload relays



1 Connection for contactor mounting:

In terms of their electrical and mechanical features and their design, these pins are perfectly compatible with the 3RT2 contactors for the direct mounting of overload relays. Stand-alone assembly is also an option (in conjunction with a stand-alone assembly module).

- 2 Switch position indicator and TEST function for wiring: Indicates a trip and facilitates testing of the wiring.
- 3 Motor current setting:

The large rotary button provides an easy means of setting the device to the rated motor current.

4 Control circuit terminal::

A screw-type, spring-loaded or ring cable lug connection system can be used to connect the control circuit.

Information about the date of manufacture and product version appears below.

5 Main circuit terminal:

A screw-type, spring-loaded or ring cable lug connection system can be used to connect the main circuit terminal.

6 STOP button:

Pressing the button opens the NC contact, thereby disconnecting the downstream contactor. The NC contact closes again when the button is released.

- 7 Selector switch for manual/automatic RESET and RESET button:
  This switch is used to choose between manual and automatic RESET. A device set to manual RESET can be reset locally by pressing the RESET button. The device can be reset remotely using the RESET modules (accessories) which are compatible for use with all sizes.
- 8 Label

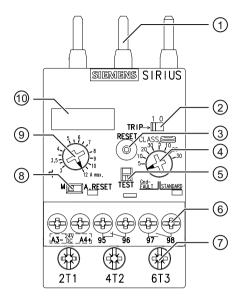
Figure 6-1 Equipment, 3RU21 overload relay

A sealable transparent cover can be optionally mounted (accessory). It stops the motor setting being tampered with.

#### **Auxiliary contacts**

3RU21 thermal overload relays are equipped with an NO contact for the "tripped" message and an NC contact for disconnecting the contactor.

## 6.1.5 3RB30/3RB31 solid-state overload relays



1 Connection for contactor mounting:

In terms of their electrical and mechanical features and their design, these pins are perfectly compatible with the 3RT2 contactors for the direct mounting of overload relays. Stand-alone assembly is also an option (in some cases in conjunction with a stand-alone assembly module).

- Switch position indicator and TEST function for wiring: Indicates a trip and facilitates testing of the wiring.
- 3 RESET button

A device set to manual RESET can be reset locally by pressing the RESET button. On the 3RB31 an electronic remote RESET is integrated.

- Tripping class setting/Internal ground-fault detection (3RB31 only):
  This rotary switch is used to set the required tripping class dependent upon the starting conditions and activate internal ground-fault detection.
- Electronics test (device test):
   Enables a test of all major device components and functions.
- 6 Control circuit terminal (removable):

A screw-type or spring-loaded system can be used to connect the control circuit terminal.

- 7 Main circuit terminal:
  - A screw-type or spring-loaded system can be used to connect the main circuit terminal.
- 8 Selector switch for manual/automatic RESET and RESET button:
  - The slide switch is used to choose between manual and automatic RESET. A device set to manual RESET can be reset locally by pressing the RESET button. On the 3RB31 an electrical remote RESET is integrated.
  - Information about the date of manufacture and product version appears below.
- 9 Motor current setting:

The large rotary button provides an easy means of setting the device to the rated motor current.

10 Label

Figure 6-2 Equipment, 3RB30/3RB31 overload relays

A sealable transparent cover can be optionally mounted (accessory). It stops the motor setting being tampered with.

#### **Auxiliary contacts**

3RB30/3RB31 solid-state overload relays are equipped with an NO contact for the "tripped" message and an NC contact for disconnecting the contactor.

#### Reference

More information	Is available in
about the 3RU2, 3RB30/3RB31 overload relays	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS Innovations - SIRIUS 3RU2/3RB3 Overload Relays" manual.

## 6.2 3RB24 solid-state overload relay for IO-Link

#### 6.2.1 Properties

#### Solid-state overload relay for IO-Link

The solid-state overload relay, comprising the 3RB24 evaluation module and a 3RB29 current measuring module, protects electrical equipment (e.g. three-phase motors) with two different protection mechanisms: overload protection and thermistor protection. Ground fault detection can also be enabled via IO-Link.

In conjunction with the 3RT contactors, the solid-state overload relay for IO-Link can be used as a direct-on-line starter, reversing starter or, with the help of an additional circuit, as a stardelta (wye-delta) starter. It is possible to read out diagnostics data, such as the current, via IO-Link and to further process this data in the higher-level controller.

#### 6.2.2 System structure

#### **Device concept**

The 3RB24 solid-state overload relay has a modular device concept. Each device consists of a motor-current-independent evaluation module, and a motor-current-dependent current measuring module. Both modules are connected electrically to each other by connecting cable via the interface.

Optionally, the 3RA6935-0A operator panel can be connected to the front of the evaluation module.

#### Requirements

You require the following tools for system setup:

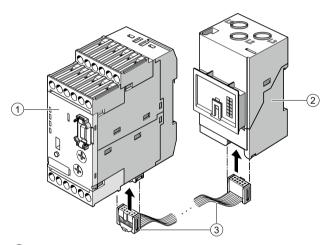
- 1 x evaluation module 3RB2483-4A .1
- 1 x current measuring module 3RB29.6-2...
- 1 x connecting cable 3RB2987-2.

#### Note

The connecting cable 3RB2987-2B for linking the evaluation module and the current measuring module is only to be used when the evaluation module is mounted direct on the current measuring module.

#### System structure

The following graphic illustrates the design principle of a system.



- ① Evaluation module 3RB2483-4A .1
- 2 Current measuring module 3RB29.6-2...
- 3 Connecting cable 3RB2987-2.

Figure 6-3 System structure

#### 6.2.3 Functions

#### Overview of the basic functions

The 3RB24 solid-state overload relay for IO-Link offers the following basic functions:

Protective function:

- Current-dependent protection of loads against overload
- Current-dependent protection of loads against phase asymmetry
- Current-dependent protection of loads against phase failure
- Cold conductor (PTC) sensor circuit (thermistor protection)
- Protection of loads against incomplete ground faults

#### Motor starter function:

Control of the relay contacts for operating the connected contactors via IO-Link

#### Diagnostics and monitoring:

- Output of an analog signal DC 4 mA to DC 20 mA as an image of the flowing motor current
- Diagnostics via IO-Link for further processing in the higher-level controller, e.g. device status with regard to protective functions, parameterization and transfer of the measured current value

#### Note

Fuses or circuit breakers must be used for short-circuit protection.

#### Overload protection/phase asymmetry/phase failure

The 3RB24 solid-state overload relays for IO-Link are modular in design and are supplied with power via the IO-Link master. The associated 3RB29 current measuring modules can be ordered in different sizes and cover a current range of 0.3 to 630 A. This means the right current measuring module can be selected for every application. A current setting up to 820 A is possible in conjunction with a series transformer. The solid-state overload relays have been designed to provide current-dependent protection for loads with normal starting and heavy starting against impermissibly high temperature rises due to overload, phase asymmetry or phase failure. The devices can be used as direct-on-line starters, reversing starters or, with the help of an additional circuit, as star-delta (wye-delta) starters.

#### 6.2 3RB24 solid-state overload relay for IO-Link

Overload, phase asymmetry or phase failure results in an increase of the motor current beyond the set rated operational current of the motor. This increase in current is detected using a current measuring module, and electronically analyzed by a connected 3RB24 evaluation module. The evaluation electronics send a signal to the auxiliary contacts. The auxiliary contacts then disconnect the contactor and the load. The break time depends on the ratio of the tripping current to the rated operational current  $I_e$  and is stored in the form of a tripping characteristic with long-term stability.

The status "Tripped" is signaled by an "OVERLOAD" LED showing a permanently red light and a "DEVICE / IO-Link" LED showing a permanently red light. The "OVERLOAD" LED flickers to indicate an imminent relay trip following violation of a limit current resulting from overload, phase asymmetry or phase failure. This overload warning is reported as a general warning via the IO-Link to the higher-level controller.

If, after a tripping operation, the voltage supply of the overload relay is interrupted within the recovery time of 3 minutes, the time starts again when the supply is restored, and a period of 3 minutes must elapse before the device is ready for service again.

#### Thermistor protection

The 3RB24 solid-state overload relays for IO-Link offer the option of direct temperature monitoring of the motor windings. Full motor protection is implemented by connection of a cold conductor (PTC) sensor circuit monitored for short-circuit and wire break.

With this temperature-dependent protection, the loads can be protected against overtemperature resulting indirectly from restricted coolant flow, for example, and undetectable by current measurement. In the case of overtemperature, the devices shut down the contactor and thus the loads via the auxiliary contact.

The status "Tripped" is signaled by a "THERMISTOR" LED showing a permanently red light and a "DEVICE / IO-Link" LED showing a permanently red light.

#### NOTICE

To guarantee sure functioning of the short-circuit detection in the thermistor circuit, the line resistance must not exceed 10  $\Omega$  in the case of a short-circuited thermistor.

#### Ground fault protection

To also protect the loads against high-resistance short circuits due to damage to the insulation, humidity or condensation the solid-state overload relays for IO-Link offer the possibility of internal ground fault detection.

#### Note

Internal ground fault detection is not possible in conjunction with contactor assemblies for star-delta (wye-delta) start.

In the event of a ground fault, the relays trip instantaneously.

The "Tripped" status is signaled by means of a "GND FAULT" LED showing a permanently red light and a "DEVICE / IO-Link" LED showing a permanently red light, and it can also be signaled via IO-Link.

Ground fault detection can be enabled or parameterized in the solid-state overload relay when using with motors with 3-conductor connection (without N connection). Ground fault detection is disabled in the delivery state.

#### Self-monitoring

The 3RB24 solid-state overload relay for IO-Link has a self-monitoring feature. The overload relay constantly monitors its own basic functions and trips if an internal fault is detected.

#### Electrical interlock

The electrical interlock prevents simultaneous selection of direction of rotation 1 and direction of rotation 2. If direction of rotation 1 and direction of rotation 2 are selected simultaneously, the overload relay outputs a process image error.

The switchover time is the time provided for changing the direction of rotation. The switchover time is 0.5 s and cannot be parameterized. The electrical interlock is also active during the switchover time, in other words, selection of a direction of rotation only becomes effective 0.5 s after revoking a selection signal for the other direction of rotation.

#### Residual current detection

The 3RB24 solid-state overload relay for IO-Link has internal residual current detection and checks for a current-free state with regard to an active or non-active control command. If not, the device switches off and signals a fault.

A current flow is detected if the current is greater than 12% of the rated operational current. Detection takes place 1.5 s after switching the overload relay on or off.

The table below represents the different states.

Table 6-3 Residual current detection

Switch-on command	Current flow	Response/state	Message
pending	detected	Device ready for service	No fault message
pending	not detected	Residual current tripping	Fault message and shutdown of the auxiliary contacts
not pending	detected	Switching element defective	Fault message (no further response possible)
not pending	not detected	Device ready for service	No fault message

More information	Is available in
about 3RB24 solid-state overload relay for IO- Link	the chapter "SIRIUS Innovations manuals (Page 18)" in the "3RB24 Solid-State Overload
	Relay for IO-Link" manual.

# SIRIUS 3UG4/3RR2, 3RS1/3RS2, 3UG48, 3RS14/3RS15 monitoring relays

## 7.1 3UG4 / 3RR2 monitoring relays

#### **Product description**

The tried and tested SIRIUS monitoring relays for electrical and mechanical quantities enable constant monitoring of all important characteristic quantities that provide information about the reliability performance of the plant. Sudden disturbances and gradual changes, which may reveal a maintenance requirement, for example, are both indicated. By means of relay outputs, the monitoring relays enable direct shutdown of the affected sections of the plant as well as issuing an alarm (e.g. by switching on a warning lamp). To respond flexibly to short-term disturbances such as voltage dips or load variation, the monitoring relays have settable delay times. This avoids unnecessary alarming and shutdowns while enhancing plant availability.

The individual 3UG4 monitoring relays offer the following functions in various combinations:

- Undershoot and/or overshoot of liquid levels
- Phase sequence
- Phase failure, neutral failure
- Phase asymmetry
- Undershoot and/or overshoot of voltage thresholds
- Undershoot and/or overshoot of current thresholds
- Undershoot and/or overshoot of power factor thresholds
- Monitoring of the active current or apparent current
- Monitoring of the fault current
- Monitoring the insulation resistance
- Undershoot and/or overshoot of speed thresholds

The 3RT2 contactors for mounting on 3RR2 current monitoring relays offer:

- Phase sequence
- Phase failure
- Undershoot and/or overshoot of current thresholds
- Monitoring of the active current or apparent current
- Monitoring of the fault current

#### 7.1.1 Overview of the functions

## 7.1.1.1 3RR2 current monitoring relays

Table 7-1 Functions of the 3RR21 / 3RR22 current monitoring relays for analog and digital setting

Function	Current monitoring relay								
	3RR21	3RR22							
Current monitoring									
Monitoring for undercurrent	2p	3р							
Monitoring for overcurrent	2p	3р							
Apparent current monitoring	✓	✓							
Active current monitoring	_	✓							
Range monitoring	2p	3p							
Monitoring for phase failure, wire break	2p	3р							
Monitoring for phase sequence	_	✓							
Internal ground-fault detection (fault current monitoring)	_	✓							
Blocking current monitoring	_	✓							
Supply voltage									
Self-powered, without auxiliary voltage	_								
Externally powered, with auxiliary voltage	✓	✓							

✓: Function available

2p: Monitoring is 2-phase

3p: Monitoring is 3-phase

-: Function not available

## 7.1.1.2 3UG45 / 3UG46 monitoring relays

Table 7-2 Functions of the 3UG45/3UG46 monitoring relays for analog and digital setting

Function	Мо	nitori	ing r	elays	<b>3</b>													
	3U(	<b>345</b>				3U0	3UG46											
	01	11	12	13	8	14	15	16	17	18	31	32	33	21	22	41	24	51
Line monitoring and voltage monit	toring	)																
Monitoring for phase sequence	_	✓	✓	✓	_	✓	✓	✓	✓	✓	—	_	_	_	_	_	_	_
Monitoring for phase failure	_	<sub>0</sub> 1)	✓	✓	_	✓	✓	✓	✓	✓	—	_	—	_	_	_	_	_
Monitoring for asymmetry	_	_	10 %	20 %	_	✓	○2)	○2)	✓	✓	_	_	_	_	_	_	_	_
Monitoring for undervoltage	_	_	_	Зр	_	Зр	Зр	Зр	Зр	Зр	1p	1p	1p	_	_	_	_	_
Monitoring for overvoltage	_	_	_	—	_	—	3р	Зр	Зр	3р	1p	1p	1p	_	_	_	_	_
Monitoring for neutral failure								✓		✓								
Automatic direction of rotation correction in the case of incorrect phase sequence	_					_	_		1	1	_	_		_	_	_	_	_
Power factor monitoring and current monitoring																		
Monitoring for undercurrent	_	_	_	_	_	_	_	_	_	_	_	_	_	1p	1p	1p	_	_
Monitoring for overcurrent	_	_	_	_	_	_	_	—	_	_	_	_	_	1p	1p	1p	_	_
Active current monitoring	_	_	_	_	_	_	_	_	—	_	_	_	_	_	_	✓	_	_
Apparent current monitoring	_	_	_	_	_	_	_	_	_	_	_	_	_	✓	✓	_	_	_
Power factor monitoring	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	✓	_	_
Fault current monitoring/insulation	n mor	nitori	ng															
Monitoring for fault current/ground fault	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	✓	_
Insulation monitoring	_	_	_	_	✓	_	_	_	_	_	_	_	_	_	_	_	_	_
Filling level monitoring	•																	
Monitoring for filling level overshoot/resistance overshoot	✓			_			_	_	_	_	_	_	_	_	_	_	_	_
Monitoring for filling level undershoot/resistance undershoot	✓			_			_					_		_	_	_	_	_
Speed monitoring																		
Monitoring for speed overshoot			_		_				_	_			_			_		✓
Monitoring for speed undershoot	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	✓

7.2 3RS1/3RS2 temperature monitoring relays

Function	Мо	nitori	ing r	elays	6													
	3U(	G45				300	346											
	01	11	12	13	8	14	15	16	17	18	31	32	33	21	22	41	24	51
Rated control and supply voltage																		
Self-powered, without auxiliary voltage	_	✓	✓	✓	_	✓	✓	✓	✓	✓	_	_	✓	_	_	✓	_	_
Externally powered, with auxiliary voltage	✓	_	_	_	✓	_	_	_	_	_	✓	✓	_	✓	✓	_	✓	✓

- ✓: Function available
- 1p: Monitoring is 1-phase
- 3p: Monitoring is 3-phase
- -: Function not available
- o: Function available with limitations
- 1) Detection causes problems with regenerative power recovery.
- 2) By monitoring the voltage thresholds.

#### Reference

More information	Is available in
	the chapter "SIRIUS Innovations manuals (Page 18)" of the "3UG4/3RR2 Monitoring Relays" manual.

## 7.2 3RS1/3RS2 temperature monitoring relays

## 7.2.1 Product description

#### **Product description**

The temperature monitoring relays are used for measuring temperatures in solid, liquid, and gaseous media. The temperature is sensed by the sensors in the medium and evaluated by the device. It is monitored for overshoot, undershoot or, on digital device versions, remaining within a working range (range function).

The family comprises the following devices:

- Devices for analog setting, with one or two limit values
- Digital devices for 1 sensor (e.g. alternative to temperature controllers for low-end applications)
- Digital devices for up to 3 sensors (optimized for monitoring large motors)

## 7.2.2 Overview of the functions (3RS10/ 11/ 20/ 21)

#### **Function**

Table 7-3 Functions of the 3RS1 / 3RS2 temperature monitoring relays

Function	Temp	eratur	e moni	toring	relays											
	3RS10							3RS	20 <sup>2)</sup>	3RS	11					3RS21 <sup>2)</sup>
	00	10	20	30	40	41	42	40	41	00	01	20	21	40	42	40
Settings	а	а	а	а	d	d	d	d	d	а	а	а	а	d	d	d
Connectable senso	Connectable sensor type															
Resistance sensors	✓	✓	✓	✓	✓	✓	1	✓	✓							
Thermocouple										✓	✓	✓	✓	✓	✓	✓
Number of sensors that can be monitored	1	1	1	1	1	3	1	1	3	1	1	1	1	1	1	1
Temperature monit	oring															
Temperature monitoring for overshoot	1		1		✓	✓	✓	1	✓	1	✓	✓	✓	✓	1	✓
Temperature monitoring for undershoot		✓		✓	✓	✓	✓	✓	✓					✓	1	✓
Number of limit values that can be set1)	1	1	2	2	2	2	2	2	2	1	1	2	2	2	2	2

<sup>&</sup>lt;sup>1)</sup> The device versions with two limit values can be switched between the open-circuit principle NO and the closed-circuit principle NC.

✓: Function available

--: Function not available

a: Analog setting

d: Digital setting

More information	Is available in
about the 3RS1/3RS2 temperature monitorelays	the chapter "SIRIUS Innovations manuals (Page 18)" in the "3RS1/3RS2 Temperature Monitoring Relays" manual.

<sup>2)</sup> Temperature scale of the sensors in degrees Fahrenheit [°F].

## 7.3 3UG48 monitoring relays for IO-Link

#### 7.3.1 Product description

#### **Product description**

The tried and tested SIRIUS monitoring relays for electrical and mechanical quantities enable constant monitoring of all important characteristic quantities that provide information about the reliability performance of the plant. Sudden disturbances and gradual changes, which may reveal a maintenance requirement, for example, are both indicated. Through relay outputs, the monitoring relays enable direct shutdown of the affected sections of the plant as well as alarming (e.g. by switching a warning lamp). To respond flexibly to short-term disturbances such as voltage dips or load variation, the monitoring relays have settable delay times. This avoids unnecessary alarming and shutdowns while enhancing plant availability.

The individual monitoring relays provide the following functions in different combinations:

- Phase sequence
- Phase failure, neutral failure
- Phase asymmetry
- Voltage below and / or above thresholds
- Current below and / or above thresholds
- Power factor below and / or above thresholds
- Monitoring of the active current or apparent current
- Speed below and / or above thresholds

The new SIRIUS 3UG48 monitoring relays for IO-Link offer many other performance features in addition to monitoring functions:

- Measured value transmission (including resolution and unit) to the higher-level control.
   On some device variations, it is possible to parameterize which value will be transmitted cyclically.
- Transmission of alarm flags to the higher-level control.
- Comprehensive diagnostics capability by querying the precise cause of the error in the diagnostic data record.
- Remote parameterization additionally possible (supplementing local parameterization or instead of local parameterization).
- Fast parameterization of identical devices by duplicating the parameter assignment in the higher-level control.
- Parameter transfer by means of Upload to the higher-level control via- IO-Link call or by parameter server¹) when using an IO-Link master in IO-Link Communication Specification V1.1 or higher).
- Local parameter assignment can be disabled via IO-Link.
- To prevent automatic startup after a power failure and to avoid losing diagnostic data, errors can be configured so that they are saved to non-volatile memory.
- Linking to a higher-level control makes it possible to assign parameters to the monitoring relays via a display unit. The measured values can be displayed directly in a control room or at the machine/control cabinet.

<sup>1)</sup> The parameter server provides an assurance of consistent central data management in the event of changes to parameters (made locally or via the control). The "Parameter server" function supports the automatic backup of parameter data (automatic re-assignment of parameter data if a device is replaced).

Up until now, using redundant sensors and/or analog signal converters to transfer measured values to a higher-level control incurred significant additional expense and wiring effort. Combining the autonomous monitoring relay with IO-Link communication reduces this wiring effort and lowers costs.

As the availability of up-to-date measured values means that the higher-level control can take care of the control tasks within the plant, the continued availability of the output relays on the monitoring relays increases the plant's operational reliability (e.g. by shutting down the plant if thresholds are exceeded that should not even be reached under normal operating conditions).

The monitoring relays continue to function autonomously in spite of the IO-Link connection. Parameters can be assigned locally at the device, independently of a higher-level control. As long as the 24 VDC power supply is available, the monitoring relays will function if the controller fails or is not yet available. If the 3UG48 monitoring relay is used for IO-Link without a connection to a higher-level control, because of the integrated SIO-Mode, the devices feature an additional semiconductor output that switches when settable warning thresholds are exceeded.

7.3 3UG48 monitoring relays for IO-Link

## 7.3.2 Overview of the functions

Table 7-4 Functions of the 3UG48 monitoring relays for IO-Link

		3UG48 monitoring relays										
	15	16	32	22	41	51						
Line monitoring and voltage monitoring												
Monitoring for phase sequence	✓	✓	_	_	_	_						
Monitoring for phase failure	✓	✓	_	_	_	_						
Monitoring for asymmetry	✓	✓	_	_	_	_						
Monitoring for undervoltage	3р	3р	1p	_	_	_						
Monitoring for overvoltage	3р	3р	1p	_	_							
Monitoring for N-conductor failure		✓	_	_	_	_						
Cos phi monitoring and current monitor	ring											
Monitoring for undercurrent	_	_	_	1p	1p	_						
Monitoring for overcurrent	_	_	_	1p	1p	_						
Active current monitoring	_	_	_	_	1p	_						
Apparent current monitoring	_	_	_	1p	_	_						
Monitoring for cos phi	_	_	_	_	1p	_						
Speed monitoring	•											
Monitoring for speed overshoot	_	_	_	_	_	✓						
Monitoring for speed undershoot	_	_	_	_	_	✓						
Power supply												
External power supply (via the IO-Link master or an external 24 V DC voltage source)	1	✓	<b>√</b>	✓	1	✓						

✓: Function available

1p: Monitoring is single-phase

3p: Monitoring is 3-phase

-: Function not available

More information	Is available in
about the 3UG48 monitoring relays for IO-Link	the chapter "SIRIUS Innovations manuals (Page 18)" of the "3UG48 Monitoring Relays" manual.

#### 7.4.1 Product description

#### **Product description**

The new SIRIUS 3RS14/3RS15 temperature monitoring relays for IO-Link are used to measure temperatures in solid, liquid, and gaseous media. The temperature is sensed by the sensors in the medium and evaluated by the device. Up to 2 limit values for overshoot, undershoot, or staying within a working range (range function) are monitored. In addition to providing warning and shutdown functions in the event of temperature deviations, the devices can be used as temperature controllers (single-step control, two-step control, or three-step control).

The devices differ in terms of the type and number of temperature sensors that can be connected to them:

- 3RS14: Connection for 1 or up to 3 resistance sensors
- 3RS15: Connection for 1 thermocouple

The 3RS14/3RS15 temperature monitoring relays for IO-Link offer many other performance features in addition to monitoring functions:

- Transmission of measured values (including resolution and unit) to the higher-level control
  - Local display and transmission of the temperature unit (°C or °F) can be parameterized. The temperature measured value transferred from temperature monitoring relays with more than one resistance sensor can be adjusted. Some device versions allow you to set which value is transferred cyclically.
- Transfer of alarm flags to the higher-level control.
- Comprehensive diagnostics capability by querying the precise cause of the error in the diagnostic data record.
- Remote parameterization is also possible (instead of local parameter assignment).
- Fast parameterization of identical devices by duplicating the parameter assignment in the higher-level control.
- Parameter transfer by means of Upload to the higher-level control via- IO-Link call or by parameter server<sup>1)</sup> when using an IO-Link master in IO-Link Communication Specification V1.1 or higher).
- Local parameter assignment can be disabled via IO-Link.
- To prevent automatic startup after a power failure and in order not to lose diagnostic data, errors can be configured so that they are saved to non-volatile memory.
- Linking to a higher-level control makes it possible to assign parameters to the monitoring relays via a display unit. The measured values can be displayed directly in a control room or at the machine/control cabinet.

<sup>1)</sup> The parameter server provides an assurance of consistent central data management in the event of changes to parameters (made locally or via the control). The "Parameter server" function supports the automatic backup of parameter data (automatic re-assignment of parameter data if a device is replaced).

Up until now, using redundant sensors and/or analog signal converters to transfer measured values to a higher-level control incurred significant additional expense and wiring effort. Combining the autonomous monitoring relays with IO-Link communication reduces this wiring outlay and cuts costs.

As the availability of up-to-date measured values means that the higher-level control can take care of the control tasks within the plant, the continued availability of the output relays on the monitoring relays increases the plant's operational reliability (e.g. by shutting down the plant if limit values that cannot be achieved under normal operating conditions are overshot).

The monitoring relays continue to function autonomously in spite of the IO-Link connection. Parameters can be assigned locally at the device, independently of a higher-level control. As long as the 24 VDC power supply is available, the monitoring relays will function should the controller fail or not yet be available.

#### 7.4.2 Overview of the functions

#### **Function**

Table 7-5 Functions of the temperature monitoring relays for IO-Link

Function	Temperature monitoring relays									
	3R	S14	3RS15							
	40	41	40							
Connectable sensor type										
Resistance sensors	✓	✓								
Thermocouple			✓							
Number of sensors that can be monitored	1	3	1							
Temperature monitoring										
Temperature monitoring for overshoot	✓	<b>√</b>	<b>√</b>							
Temperature monitoring for undershoot	✓	✓	✓							
Number of limit values that can be set1)	2	2	2							

<sup>1)</sup> It is possible to switch between the open-circuit principle NOand the closed-circuit principle NC.

<sup>✓:</sup> Function available

<sup>--:</sup> Function not available

More information	Is available in
relays for IO-Link	the chapter "SIRIUS Innovations manuals (Page 18)" of the "3RS14/3RS15 Temperature Monitoring Relays for IO-Link" manual.

SIRIUS 3RA21/22 load feeders

#### 8.1 Overview

#### Fuseless load feeders

Fuseless load feeders are device combinations comprising a 3RV motor starter protector for overload and short-circuit protection and a 3RT contactor for normal switching. The SIRIUS portfolio features two different configuration options for fuseless load feeders.

- 3RA2 tested pre-assembled complete devices
- Tested combinations of individual devices

#### 8.2 Device versions

The modular standard components in the SIRIUS modular system are ideally matched and support the configuration of fuseless load feeders. The load feeders are also available as 3RA2 complete devices.

Both options are characterized by the following features.

- Type of coordination 1 or 2
- Rated control supply voltage
- Mounting on busbar or DIN rail
- Screw or spring-loaded connection

A detailed overview of the fuseless load feeders product range appears below.

#### Types of coordination

Fuseless load feeders up to 38 A (discrete configuration of individual devices) and 32 A (preassembled complete devices) can be configured in sizes S00 and S0. The overall width is 45 mm for all individual devices.

The table below lists the maximum power of the three-phase motor for pre-assembled 3RA2 complete devices based on the type of coordination at a voltage of 400 V AC.

Table 8- 1 Motor starter protector sizes

Size	Type of coordination	Power of three-phase motor
S00	1	0.06 to 7.5 kW
	2	0.06 to 1.5 kW
S0	1	7.5 to 15 kW
	2	1.5 to 15 kW

#### **Auxiliary contacts**

The following auxiliary contacts are integrated into fuseless load feeders dependent upon size.

Table 8-2 Integrated auxiliary contacts

Size	Direct feeder	Reversing feeder
S00	1 NO contact is integrated in the contactor.	1 NC contact is integrated in the contactor.
S0		1 NO contact and 1 NC contact are integrated in the contactor. The NC contact is assigned to the interlock.

#### Assembly/Installation

The devices are prepared for DIN rail mounting, for mounting on a 60 mm busbar or for mounting directly on a wall. The smaller sizes can be snapped directly onto a DIN rail without the need for adapters.

Table 8-3 Mounting options

Starter combination Size		Direct-on-line starter		Reversing starter	
		S00	S0	S00	S0
Mountir	ng on a standard rail				
	Snap-on mounting without adapter	✓	✓	✓	
	With DIN rail adapter	✓	✓	✓	✓
Busbar	mounting				
	With busbar adapter	✓	✓	✓	✓
Wall mo	ounting				
	Direct	<b>√</b>	<b>√</b>	<b>√</b>	✓
	With DIN rail adapter	✓	<b>✓</b>	✓	✓

#### 8.2.1 Pre-assembled complete devices

#### Pre-assembled complete devices

3RA2 fuseless load feeders are pre-assembled complete devices; they are delivered readywired and with all mechanical connections established. The devices are available in sizes S00 and S0 for direct-on-line starting or reversing operation. The fuseless load feeders can be ordered with or without pre-assembled busbar adapters for mounting on a DIN rail or busbar.

#### Connection systems

3RA2 fuseless load feeders are available with the following connection system options.

Table 8-4 Connection systems available for 3RA2 fuseless load feeders

Connection system	3RA2 pre-assembled complete devices
Screw connection	<b>√</b> 1)
Spring-loaded connection	✓
Ring cable lug connection	

<sup>&</sup>lt;sup>1)</sup> The link module for the S00 load feeder can also be used to mount an S00 contactor on an S0 motor starter protector.

#### Rated powers

3RA2 pre-assembled feeders are dimensioned for the following powers:

- Direct-on-line starters up to 15 kW (32 A)
- Reversing starters up to 15 kW (32 A)

#### Control supply voltages of 3RA2 load feeders

3RA2 pre-assembled feeders are available for the following rated control supply voltages:

- 230 V AC / 50/60 Hz
- 24 V DC

#### 8.2.2 Self-assembled load feeders

#### Assembly of load feeders from individual devices

Self-assembly load feeders comprising individual devices are available as an alternative to the 3RA2 complete device. The following components can be combined via the intermediary of a link module.

- Motor starter protector and contactor
- Motor starter protector and soft starter
- Motor starter protector and solid-state contactor

The modularity of the SIRIUS system means that the standard devices are perfectly matched from both a mechanical and an electrical point of view. Wiring kits for contactor assemblies for reversing and star-delta (wye-delta) start in various connection systems provide a straightforward means of assembling starter combinations. Assembly kits are available for mounting self-assembled load feeders on DIN rails or busbars.

#### Configuration of three-part combinations

You are basically advised to refrain from setting up combinations of a motor starter protector, a contactor and an overload relay or a monitoring relay as a completely assembled three-part combination. If this should nevertheless be necessary, the following restrictions apply:

Motor starter protector + contactor + solid-state overload relay/3RR overload relay

Thermal restrictions	Mechanical restrictions
No restrictions	DIN rail adapter required

Motor starter protector + contactor + thermal overload relay

Thermal restrictions:	Mechanical restrictions
Reduce permissible ambient temperature by 20 K	DIN rail adapter required
No side-by-side mounting (> 5 mm clearance for vertical installation, > 20 mm for horizontal installation)	
Current derating to 0.87 % of In	

#### **Connection systems**

Self-assembled fuseless load feeders are available with the following connection system options.

Table 8-5 Connection systems available for self-assembled fuseless load feeders

Connection system	Self-assembled fuseless load feeders
Screw connection	✓
Spring-loaded connection	✓
Ring cable lug connection	<b>√</b> 1)

<sup>1)</sup> These versions can be snapped onto a DIN rail. Mounting on a busbar adapter is not possible.

#### Rated powers

The pre-assembled feeders are dimensioned for the following powers:

- Direct-on-line starters up to 17.5 kW (38 A)
- Reversing starters up to 17.5 kW (38 A)

#### Control supply voltages of load feeders

The individual devices can be ordered with different rated control supply voltages as appropriate for the application area of the fuseless load feeders.

## 8.3 Applications

Fuseless load feeders can be used anywhere in industrial electrical applications where fuse, contactor, and overload relay combinations were previously used. The increased functionality of the motor starter protector (unlike a fuse combination, it can be used as an EMERGENCY OFF and as a disconnector) means that a fuseless load feeder is capable of solving numerous applications easily.

## 8.4 Application environment

3RA2 load feeders are climate-proof. They are designed for use in enclosed spaces in which no severe operating conditions prevail (e.g. dust, caustic vapors, hazardous gases).

If they are to be installed in dusty or damp rooms, suitable enclosures must be provided.

More information	Is available in
	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS Innovations - SIRIUS 3RA21/3RA22 Load Feeders" manual.

SIRIUS 3RA6 compact starters

9

## 9.1 System overview

#### **Features**

The SIRIUS compact starter is a universal, weld-free motor feeder in accordance with IEC/EN 60947-6-2. It combines the functions of a circuit breaker, a solid-state overload relay and a contactor within a single enclosure and can be used in any application involving the direct starting of standard three-phase motors with a rating of up to 32 A (approx. 15 kW/400 V).

The compact starter is available as either a direct or a reversing starter.

As an option, an AS-i mounting module can be mounted on the 3RA61/3RA62 compact starter with a 24 V control supply voltage. The AS-i mounting module enables the compact starter to communicate via an AS-Interface.

The 3RA64/3RA65 compact starter with IO-Link can communicate via IO-Link.

Table 9-1 Compact starter communication options

Compact starter	Communication
3RA61/3RA62 compact starter without optional AS-i mounting module	Communication via auxiliary contacts and signaling contacts
3RA61/3RA62 compact starter (24 V) with optional AS-i mounting module	Communication via AS-Interface
3RA64/3RA65 compact starter with IO-Link	Communication via IO-Link

#### Accessories

You can find more information in the chapter SIRIUS Innovations manuals (Page 18) in the "SIRIUS 3RA6 Compact Starter" manual.

#### 9.2 Automation environment

In addition to the 3RA61/3RA62 compact starter and the 3RA64/3RA65 compact starter with IO-Link, this document also describes the following accessories:

Table 9-2 Accessories for the compact starter

Accessories	Description
Auxiliary switch block for compact starter	Optional auxiliary switch block in the following versions: 2 NO contacts, 2 NC contacts or 1 NO contact + 1 NC contact.
AS-i mounting module	The AS-i mounting module enables the 3RA61/3RA62 compact starter with 24 V control supply voltage to communicate via an AS-Interface.
Control kit	Tool for closing the main contacts manually by means of the handle.
Adapter for screw fastening the compact starter	The adapters for screw fastening enable you to install the compact starter on a level surface (screw fastening).
Terminals for "Combination Controller Type E"	The terminals conform to the clearances and creepage distances stipulated by UL 508 (Type E).
Infeed system for 3RA6	The infeed system for 3RA6 is a modular infeed system with an optional PE system. The permanent wiring means that compact starters can be mounted quickly and easily.
3-phase busbar	The 3-phase busbar enables several compact starters to be fed using a single infeed terminal.
8US busbar adapter	The 8US busbar adapter enables the compact starter to be mechanically fastened and electrically connected to a busbar system.
Door-coupling rotary operating mechanism	Door-coupling rotary operating mechanisms enable compact starters to be operated with the control cabinet doors closed.

## 9.2 Automation environment

#### Main circuit

The following supply options are available for the compact starter's main circuit:

- Parallel wiring
- Infeed system for 3RA6
- 3RV19 3-phase busbar
- 8US busbar adapter

You can find more information in the chapter SIRIUS Innovations manuals (Page 18) in the "SIRIUS 3RA6 Compact Starter" manual.

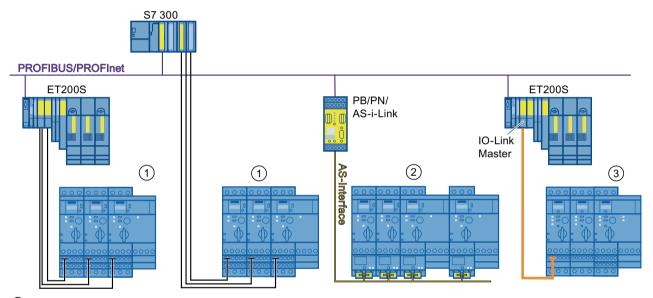
#### Control circuit and supply circuit

The control circuit can be structured as follows:

Table 9-3 Control circuit (configuration)

Compact starter	Control system
3RA61/3RA62 compact starter without optional AS-i mounting module	Parallel wiring to control system (e.g. PLC)
3RA61/3RA62 compact starter (24 V) with optional AS-i mounting module	AS-Interface
3RA64/3RA65 compact starter with IO-Link	IO-Link

#### Examples of how the compact starter can be integrated into the automation environment



- ① 3RA61/3RA62 compact starter without AS-i mounting module
- ② 3RA61/3RA62 compact starter with AS-i mounting module
- 3 3RA64/3RA65 compact starter with IO-Link

Figure 9-1 Integration into the automation environment

## 9.3 3RA61/3RA62 compact starter without optional AS-i mounting module

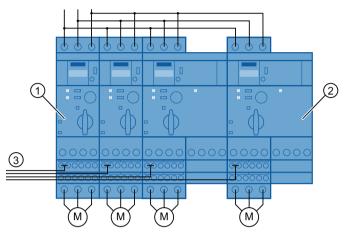
#### Configuration of parallel wiring

The 3RA61/3RA62 compact starter is connected to the control system via parallel wiring. Control takes place via the following terminals:

- Direct starter: A1+, A2-
- Reversing starter: A1+, A2/B2-, B1+

9.4 3RA61/3RA62 compact starter with optional AS-i mounting module

#### View of parallel wiring



- 3RA61 compact starter (direct starter)
- ② 3RA62 compact starter (reversing starter)
- 3 Connection to control system (e.g. PLC)

Figure 9-2 System configuration with 3RA61/3RA62 compact starter without AS-i mounting module

## 9.4 3RA61/3RA62 compact starter with optional AS-i mounting module

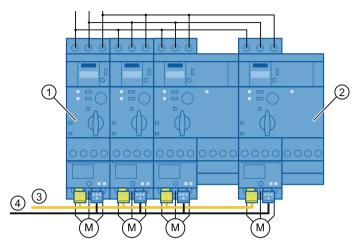
The 3RA61/3RA62 compact starter with 24 V control supply voltage can be controlled via an AS-Interface. The actuator sensor interface (AS-Interface) is a modular networking system for sensors and actuators at the lowest field level.

#### Configuration with AS-Interface

If the AS-Interface is being used for control purposes, the AS-i mounting module needs to be installed on the 3RA61/3RA62 compact starter (24 V) instead of the two auxiliary circuit terminals. The AS-i and auxiliary voltage cables are connected to the AS-i mounting module.

An AS-i power supply is used to feed the AS-i voltage into the AS-i cable, which also serves as a communication cable between the AS-i master and slave. The auxiliary voltage is supplied by a 24 VDC PELV power supply in accordance with VDE 0106 safety class III.

#### View with AS-Interface



- 1 3RA61 compact starter (direct starter) with AS-i mounting module
- 2 3RA62 compact starter (reversing starter) with AS-i mounting module
- 3 AS-i
- 4 External voltage supply (AUX PWR)

Figure 9-3 System configuration 3RA61/3RA62 compact starter with AS-i mounting module

#### Reference

More information	Is available in
about AS Interface	"System AS Interface" manual (order number: 3RK2703-3AB02-1AA1).
about connecting the AS-i mounting module	"System AS Interface" manual (order number: 3RK2703-3AB02-1AA1).

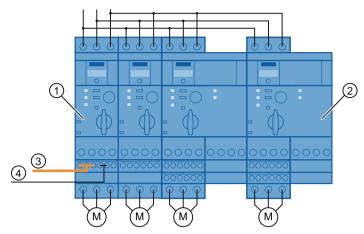
## 9.5 3RA64/3RA65 compact starter with IO-Link

#### Configuration with IO-Link

The 3RA64/3RA65 compact starter with IO-Link is controlled via IO-Link. The auxiliary voltage V<sub>Aux</sub> (24 V DC) is connected via a separate terminal.

Direct starters and reversing starters can be combined as desired to form a group of four compact starters. For this purpose, three other compact starters are installed to the right of the first compact starter and linked using a 14-core connecting cable. These three compact starters do not require their own connection to IO-Link via the removable terminal since they are supplied with data and auxiliary voltage V<sub>Aux</sub> via the 14-core connection cable (8 mm, 200 mm).

#### View with IO-link



- 3RA64 compact starter with IO-Link (direct starter)
- ② 3RA65 compact starter with IO-Link (reversing starter)
- ③ IO-Link
- 4 Auxiliary voltage V<sub>Aux</sub>

Figure 9-4 System configuration with 3RA64/3RA65 compact starter with IO-Link

More information	Is available in	
•	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS 3RA6 Compact Starter" manual.	

SIRIUS 3RA27/3RA28 function modules 10

## 10.1 3RA27 function modules for connection to the higher-level control

#### 10.1.1 3RA2711 function modules for IO-Link

#### Function modules for IO-Link

Function modules for IO-Link are integrated in the higher-level control system via an IO-Link master. They are mounted on contactors with a communication link or contactor combinations from the SIRIUS device family.

The following contactors and contactor combinations are available for the function modules for IO-Link:

- For direct starting
- For reversing starting
- For star-delta starting

The function modules are divided into basic modules and coupling modules. Coupling modules are connected with the basic module or another coupling module via module connectors.

The process image of the function module outputs controls the starter. The process image of the inputs represents the status of the starter.

#### Operator panel

The starters are controlled with the operator panel in manual mode. The states of the device are also queried for up to 4 starters.

The operator panel is connected to the last available interface of a starter group via the 10-core connecting cable.

The voltage supply of the operator panel is provided with the 2 m long connecting cable.

More information	Is available in
about the 3RA2711 function modules for IO-Link	the chapter "SIRIUS Innovations manuals (Page 18)" of the "Function Modules for IO-Link" manual.

#### 10.1.2 3RA2712 function modules for AS-Interface

#### Function modules for AS-Interface

Function modules for AS-Interface are mounted on contactors or contactor combinations of the SIRIUS device family, and they connect these with the AS-Interface.

The function modules for AS-Interface are available for the following contactors and contactor combinations:

- For direct starting
- For reverse starting
- For star-delta starting

The function modules are divided into basic modules and coupling modules. Coupling modules are connected with the basic module or another coupling module via module connectors.

Basic modules are connected with the AS-Interface using a removable terminal. For this purpose, the AS-Interface cable and the auxiliary voltage are connected to the basic module's removable terminal.

The process image of the function modules controls the starter. The process image of the inputs represents the status of the starter.

#### AS-i addressing unit

The AS-i addressing unit can be used to control the contactors and display the process image independently of the AS-i bus.

More information	Is available in
about the 3RA2712 function modules for AS-Interface	the chapter "SIRIUS Innovations manuals (Page 18)" of the "Function Modules for AS-Interface" manual.

## 10.2 SIRIUS 3RA28 function modules for mounting on 3RT2 contactors

#### **Applications**

Function modules are used to perform various control jobs on automatic production lines and for processing machines. They are suited to all time-delayed switching operations in control, starting, protection, and regulation circuits, and ensure a high degree of repeat accuracy for delay times, once they have been set.

The function modules are subdivided into function modules with communication interfacing and function modules without communication interfacing.

Function modules	
3RA28 function modules	Solid-state timing relays with semiconductor output
	Solid-state time-delay auxiliary switches
	Function module for star-delta (wye-delta) start
3RA27 function modules with communication	Function modules for AS-Interface
connection	Function modules for IO-Link

This chapter describes 3RA28 function modules without a communication connection. You will find information about function modules with a communication connection in the corresponding manuals (see Reference).

#### **Function**

Function modules are used to delay switching functions.

#### System integration

The 3RA28 function modules have been matched to the contactors in the 3RT2 and 3RH2 series both electrically and mechanically and can be integrated in the feeders by directly mounting them on contactors. The function modules can be used for size S00/S0 contactors.

The 3RA27 function modules can only be used for communication-capable contactors.

#### Connection system

Users can choose either function modules with screw-type connection system or function modules with spring-loaded connection system.

#### 10.2.1 Device versions

#### **Device versions**

- Function modules for direct on-line start
  - Solid-state timing relays with semiconductor output
  - Solid-state time-delay auxiliary switches
- Function modules for star-delta (wye-delta) start
- Function modules for reversing start (kit for reversing contactor assemblies)

The kit for reversing contactor assemblies consists of the following components:

- Mechanical interlocking
- Two connecting clips for two contactors
- Wiring modules, top and bottom

#### Characteristics

The table below provides an overview of the versions of 3RA28 function modules for mounting on 3RT2 and 3RH2 contactors.

Characterist	st Versions			
ic	Function modules for direct on-line start		Function module for	
	Solid-state timing relay with semiconductor output	Solid-state time-delay auxiliary switch	star-delta (wye-delta) start	
Function	ON-delay and OFF-delay with auxiliary voltage	ON-delay and OFF-delay with/without auxiliary voltage	Star-delta (wye-delta) function	
Order numbers	3RA2811CW10/ 3RA2812DW10	3RA2813W10/ 3RA2814W10/ 3RA2815W10	3RA2816-0EW20 comprising: 1 basic module (3RA2912-0) 2 coupling modules (3RA2911-0)	
Size One module for contactor sizes S00 and S0				
Width	45 mm		135 mm (3 x 45 mm)	
Connection system	the state of the s		Without terminals (can be used for contactor screw-type and spring-loaded connection systems)	

#### **NOTICE**

No further auxiliary switch blocks may be mounted on the basic devices when using the 3RA27/3RA28 function modules.

# 3RA28 version overview

Order number	Function	Output		
Screw connection	Screw connection			
3RA2811-1CW10	ON-delay, two-wire	Thyristor		
3RA2812-1DW10	OFF-delay with auxiliary voltage	PowerMOS		
3RA2813-1AW10	ON-delay	1 CO contact		
3RA2813-1FW10	ON-delay	1 NO contact 1 NC contact		
3RA2814-1AW10	OFF-delay with auxiliary voltage	1 CO contact		
3RA2814-1FW10	OFF-delay with auxiliary voltage	1 NO contact 1 NC contact		
3RA2815-1AW10	OFF-delay without auxiliary voltage	1 CO contact		
3RA2815-1FW10	OFF-delay without auxiliary voltage	1 NO contact 1 NC contact		
Spring-loaded conne	ction			
3RA2811-2CW10	ON-delay, two-wire	Thyristor		
3RA2812-2DW10	OFF-delay with auxiliary voltage	PowerMos		
3RA2813-2AW10	ON-delay	1 CO contact		
3RA2813-2FW10	ON-delay	1 NO contact 1 NC contact		
3RA2814-2AW10	OFF-delay with auxiliary voltage	1 CO contact		
3RA2814-2FW10	OFF-delay with auxiliary voltage	1 NO contact 1 NC contact		
3RA2815-2AW10	OFF-delay without auxiliary voltage	1 CO contact		
3RA2815-2FW10	OFF-delay without auxiliary voltage	1 NO contact 1 NC contact		
Plug-in, without terminals				
3RA2816-0EW20	Star-delta (wye-delta) function module	2 NO contacts (internal)		
3RA2912-0	Star-delta (wye-delta) basic module	_		
3RA2911-0	Star-delta (wye-delta) coupling module	1 NO contact (internal)		
3RA2910-0	Sealable cover cap	_		

The 8th digit of the order number identifies the type of the terminals:

- 0: No terminals
- 1: Screw-type terminals
- 2: Spring-loaded terminals

# 10.2.2 Performance features

#### **Features**

The function modules have the following features:

Function module		Features		
Function modules for direct-on-line start	Solid-state timing relays with semiconductor output	<ul> <li>ON-delay (1 NO contact)</li> <li>OFF-delay with auxiliary voltage (1 NO contact)</li> <li>Versions with screw-type and spring-loaded connection systems</li> </ul>		
Solid-state time-delay auxiliary switches		ON-delay (1 NO contact + 1 NC contact or 1 CO contact)     OFF-delay with/without auxiliary voltage (1 NO contact + 1 NC contact or 1 CO contact)     Versions with screw-type and spring-loaded connection systems		
Function modules for star-delta (wye- delta) start	Star-delta (wye-delta) start	<ul> <li>Control exclusively via contactor A1/A2 – no further control circuit wiring required</li> <li>No control circuit wiring (plug-in system and connecting cables)</li> <li>Interchange proof construction</li> <li>Timing function for switching over from star to delta in basic module</li> <li>Electrical interlock without additional wiring</li> <li>Changeover delay time set to a non-adjustable value of 50 ms</li> </ul>		

# 10.2.3 Applications

# 10.2.3.1 Function modules for direct-on-line start

# **Applications**

The function modules for direct-on-line start are used for the time-delayed switching of contactors. The following different function modules are available:

- Solid-state timing relay with semiconductor output
- Solid-state time-delay auxiliary switch with 1 CO contactor or 1 NC contact/1 NO contact

#### Features of direct-on-line starters

The function module for direct-on-line start has the following features:

- All modules with wide control voltage range
- Integrated varistor (surge suppressor)
- One module for both sizes S00 and S0
- Wide voltage range (24 to 240 V AC/DC)
- 3 selectable time ranges (1 s, 10 s, 100 s)
- Operating time adjustment from 5 to 100% per time range
- Switch position indicator for the contactor below (plunger)

# 10.2.3.2 Function modules for star-delta (wye-delta) start

# **Applications**

The function module for star-delta (wye-delta) start is used to switch from star (wye) to delta operation.

#### **Features**

The function module for star-delta (wye-delta) start has the following features:

- All modules with wide control voltage range
- Integrated varistor (surge suppressor)
- One module kit for contactor screw-type and spring-loaded connection systems
- One module kit for both S00 and S0 size contactors (options only with main circuit connecting comb)
- Wide voltage range (24 to 240 V AC/DC) and
- 3 selectable time ranges (10 s, 30 s, 60 s)
- Operating time adjustment from 5 to 100% per time range (corresponds to 0.5 s to 60 s)
- Changeover delay set to a non-adjustable value of 50 ms
- Switch position indication for the contactor below in the form of a mechanical switch position indicator (plunger)
- Control exclusively via A1/A2 on the line contactor below
- No further wiring required

The wide voltage and the wide time range ensure advanced use of the function modules.

# 3RA2816-0EW20 function module for contactor assemblies for star-delta (wye-delta) start

The function module for plugging into contactor assemblies for star-delta (wye-delta) start for size S00 and S0 comprises the following devices:

- 1 basic module with time setting
- 2 coupling modules with corresponding connecting cable to coupling or function module

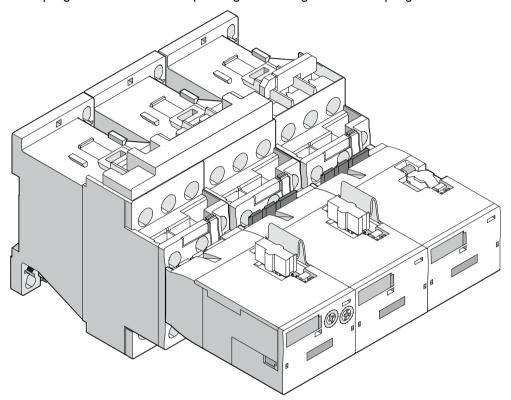


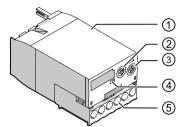
Figure 10-1 Star-delta (wye-delta) starter, completely assembled

The function module replaces the entire control circuit wiring and combines the functions of the following devices and tasks:

- Timing relay star-delta (wye-delta) function
- Auxiliary switches
- Auxiliary conductor wiring
- Electrical interlock
- Switch position indicator for the contactor below (plunger)

# 10.2.4 3RA28 function modules

Function module for direct-on-line start (solid-state timing relays with semiconductor output/solid-state time-delay auxiliary switches)



1 Timing relay attachment

2 Time range selector switch: Sets the time base (1 s, 10 s, 100 s) 3 Operating time adjustment switch: Sets the relative time (5 to 100%)

4 Mechanical plunger: Indicates the switching state of the contactor

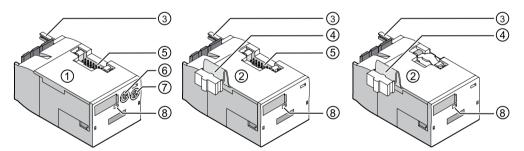
5 Screw-type/spring-loaded The terminals are available as both screw-type and

connections: spring-loaded connections.

Figure 10-2 Solid-state timing relay with semiconductor output/solid-state time-delay auxiliary switches

# Function module for star-delta (wye-delta) start

The function module for star-delta (wye-delta) start comprises a basic module with integrated control logic and two coupling modules of the same type.



- 1 Basic module with integrated control logic
- 2 Coupling module

3 Coil control: Basic module: Voltage measurement at the line contactor

Coupling module: Controls the contactor below

4 Ribbon cable: Electrical connection of modules

5 Slot for connecting cable: Routes the supply voltage and electrical interlock

6 Time range selector switch: Sets the time base (10 s, 30 s, 60 s)
7 Operating time adjustment switch: Sets the relative time (5 to 100%)

8 Mechanical plunger: Indicates the switching state of the contactor

Figure 10-3 Basic module and coupling modules for the contactor assembly for star-delta (wye-delta) start

10.2 SIRIUS 3RA28 function modules for mounting on 3RT2 contactors

# Reference

More information	Is available in
	the chapter "SIRIUS Innovations manuals (Page 18)" in the manual "SIRIUS Innovations - SIRIUS 3RA28 Function Modules for Mounting on 3RT2 Contactors".

SIRIUS 4SI electronic module for SIMATIC ET 200S

# **Properties**

The 4SI SIRIUS electronic module is a 4-channel serial interface module. Its main features are as follows:

- Connection of up to 4 SIRIUS devices with IO-Link interface
- The 4SI SIRIUS is a single-width (15 mm) electronic module that can be used with the following terminal modules:
  - TM-E15S26-A1, TM-E15C26-A1 and TM-E15N26-A1
- Replacing the 4SI SIRIUS electronic module without programming device (via user program)
- Supports I&M data
- Supports firmware update
- Extended temperature range from 0 to 55°C with vertical installation.

# Configuring

Configuration of the 4SI SIRIUS electronic module takes place in two steps with STEP 7 V5.4 SP5 or higher:

• In HW Config, you configure the 4SI SIRIUS electronic module using the HSP or the GSD file. You can download the GSD files from the Internet (http://www.siemens.de/comdec).

With STEP 7V5.4 SP5 or higher			
ET 200S PROFIBUS	IM151-1 STANDARD	6ES7151-1AA05-0AB0	
interface modules	IM151-1 HIGH FEATURE *	6ES7151-1BA02-0AB0	
ET 200S PROFINET interface modules	IM151-3 PN	6ES7151-3AA23-0AB0, V6.1 or higher	
	IM151-3 PN HF **	6ES7151-3BA23-0AB0, V6.1 or higher	
	IM151-3 PN FO **	6ES7151-3BB23-0AB0, V6.1 or higher	
	IM151-3 PN HS **	6ES7151-3BA60-0AB0, V2.1 or higher	
Only using HSP:			
ET 200S PROFIBUS- CPU	IM151-7 CPU	6ES7151-7AA20-0AB0, V2.6 or higher	
	IM151-7 F-CPU	6ES7151-7FA20-0AB0, V2.6 or higher	
ET 200S PROFINET- CPU	IM151-8 PN/DP CPU	6ES7151-8AB00-0AB0, V2.7 or higher	
	IM151-8 F-CPU	6ES7151-8FB00-0AB0, V2.7 or higher	

- \* Not possible in conjunction with fail-safe modules or isochronous mode when configuring using GSD.
- \*\* Configuring using GSD not possible in conjunction with fail-safe modules (with HF and FO) and isochronous mode (with HS)

#### Note

Using an IO-Link master behind a CPU IM151-7 or CPU IM151-8 in IO-Link (actuator) operating mode

If the 4SI SIRIUS is located behind an ET200S-CPU, the last valid output value may be output in the following cases:

- Switching on the load voltage on the power module PM-E
- Inserting the 4SI SIRIUS
- CPU startup

Workaround: Write a valid output value in the I/O address area of the 4SI SIRIUS in the respective execution level (e.g. OB 100, ...).

You configure the connected SIRIUS devices with the Port Configurator tool (S7-PCT V2.x).

#### Note

To parameterize the SIRIUS devices, these must be physically available and an online connection to the SIRIUS devices must be made via the S7-PCT.

# Reference

More information	Is available in	
about the SIRIUS 4SI electronic module for SIMATIC ET 200S	the chapter "SIRIUS Innovations manuals (Page 18)" in the "SIRIUS 4SI Electronic Module" manual.	

# Types of coordination



# Types of coordination

Standard DIN EN 60947-4-1 (VDE 0660 Part 102) or IEC 60947-4-1 distinguishes between two types of coordination (type of coordination), which are referred to as coordination type "1" and coordination type "2". The short circuit that needs to be dealt with is cleared reliably and safely with both types of coordination; the only differences are in the extent of the damage sustained by the device following a short circuit.

# Type of coordination 1

It is permissible for the fuseless load feeder to be incapable of functioning after each short-circuit disconnection. Damage to the contactor and the overload release is also permissible. For 3RA2, the motor starter protector alone always achieves type of coordination "2".

# Type of coordination 2

After short-circuit disconnection, there must be no damage to the overload release or to any other part. The 3RA2 fuseless load feeder can resume operation without any parts having to be repaired or replaced. Welding of the contactor contacts only is permitted if these can be separated easily without significant deformation.

Literature

# B.1 More information

# More information

More information is available from Siemens on the Internet via the following links.

#### Product documentation

You will find a list of manuals/operating instructions, characteristic curves, and certificates on the Internet (www.siemens.com/industrial-controls/support).

#### Product information

Catalogs and other informative documents can be obtained from the Information Center and Download Center (www.siemens.com/industrial-controls/infomaterial).

#### Online ordering system

You will find the online ordering system with all the latest data on the ordering and information platform (www.siemens.com/industrial-controls/mall).

#### Technical Assistance

Siemens supports you with all technical product and system enquiries – both before and after delivery. You can access our Service & Support Portal on the Internet (<a href="https://www.siemens.com/industrial-controls/technical-assistance">www.siemens.com/industrial-controls/technical-assistance</a>). You can also submit your question directly to a technical consultant using our support request service.

B.1 More information

Correction sheet

# **Correction sheet**

Fax response

Have you noticed any errors while reading this manual? If so, please use this form to tell us about them. We welcome comments and suggestions for improvement.

To SIEMENS AG	From (please complete): Name
I IA CE MK&ST 3	Company/Department
92220 Amberg / Germany	Address
Fax: +49 (0)9621-80-3337	
Manual title:	
Table C- 1 Errors, comments, and	suggestions for improvements
1	

# Glossary

# 3-phase busbar

The 3-phase busbar enables several motor starter protectors or compact starters to be fed using a single infeed terminal.

# 8US busbar adapter

The 8US busbar adapter enables motor starter protectors, load feeders, or compact starters to be mechanically fastened and electrically connected to a busbar system.

#### a release

Short designation for "inverse-time delayed overload release".

# Adapter for screw mounting

The adapters for screw mounting enable you to mount the compact starter on a level surface.

#### **Approvals**

Approval of switching devices and switchgear in accordance with national standards, some of which must be met on a mandatory basis, which exist in addition to "IEC", "CENELEC", and "CEE" guidelines, for example. So, the North American market (the USA and Canada) requires UL or CSA approvals, for instance. There is also an obligation to label the equipment accordingly, i.e. the approval mark must be inscribed on the device itself.

#### **AS-Interface**

The AS-Interface is an open, international standard in accordance with EN 50295 and IEC 62026-2 for process communication and field communication. Leading manufacturers of actuators and sensors worldwide support AS-Interface. The electrical and mechanical specifications of the AS-Interface Association are disclosed to interested companies.

#### Assembly method

SIRIUS offers maximum flexibility in terms of configuration. The system components can be assembled as feeders or mounted separately.

# Auxiliary switch block for compact starter

Optional auxiliary switch block in the following versions: 2 NO contacts, 2 NC contacts or 1 NO contact plus 1 NC contact.

# AWG (American Wire Gauge)

A standard measure for conductors used in the USA, which is assigned to a specific cross-sectional area of a conductor or wire. Each AWG number represents a jump of 26% in the cross-sectional area. The thicker the wire, the smaller the AWG number.

#### Basic module

Function modules consist of at least one basic module, which can be expanded by adding coupling modules as required. The basic module contains the control logic and, for star-delta (wye-delta) modules, the time setting for starting in star operation and a 10-pin connector into which the plug connectors on the coupling modules are inserted.

#### Bypass operation

Once the motor has been started up correctly, the thyristors in the SIRIUS soft starters are subject to fully advanced control, meaning that the whole line voltage is applied to the motor terminals. As the motor voltage does not have to be controlled during operation, the thyristors are bridged by integral bypass contacts that are rated for AC1 current. This minimizes the waste heat generated during continuous operation (which is caused by the thyristors' power loss), and prevents the switching device's environment from heating up.

#### CLASS (time)

See "Tripping class".

#### Closing power

The power input of the magnet coils of a contactor, which is required to set the magnet system in motion. In AC operation, this power input is usually higher than the holding power. When running SIRIUS contactors in DC operation, the closing power is equal to the holding power.

#### Connection system

SIRIUS has the right connection system for every environment: screw terminals, spring-loaded terminals, or ring cable lug connection.

#### Contactor

Switching device with just one neutral position, usually without a mechanical lock, which is not activated manually and which, under normal circuit conditions, including an operating overload, can switch on, conduct and switch off currents. Contactors are primarily used where high switching frequencies are involved. A distinction is made between: contactors for switching motors (motor switches) and contactor relays for control purposes.

# Contactor assembly for star-delta (wye-delta) start

Contactor assembly which switches the motor to the star circuit during startup (1/3 of the starting current compared to delta startup) and back to the delta circuit after a certain period of time. Contactor assemblies for star-delta (wye-delta) start are used in situations where a high starting current has to be avoided in order to reduce the effects on the mechanical components or the line.

#### Control kit

Tool for closing the main contacts manually by means of the handle.

# Coupling module

Function modules consist of at least one basic module, which can be expanded by adding coupling modules as required. The coupling module includes one NO contact and one 10-pole connecting cable with a plug connector for insertion into the coupling module and basic module; it is used for the mutual interlocking of star and delta operation. The communication-capable version transfers signals to the other contactors and implements the electrical interlock (reversing/star-delta (wye-delta) start) - in this case, there is no integrated connecting cable.

# **Current limiting for soft starters**

The SIRIUS 3RW40 soft starter measures the phase current (motor current) continuously with the help of integrated current transformers. The motor current that flows during the startup process can be actively limited by means of the soft starter. The current limiting function takes priority over the voltage ramp function. As soon as a parameterizable current limit is reached, in other words, the voltage ramp is interrupted and the motor is started with the current limiting value until it has started up successfully.

The current limiting function is always active with SIRIUS 3RW40 soft starters. If the current limiting potentiometer is set to the right endstop (maximum), the starting current is limited to five times the set rated motor current.

The current limiting value is set to the current required during startup as a factor of the rated motor current. Since the starting current is asymmetrical, the set current corresponds to the arithmetic mean value for the three phases.

# Current monitoring relays

Current monitoring relays are used to monitor motors or other loads for underload and overload. The level of current permits extensive conclusions to be drawn about the powered process or plant, e.g. a torn belt, pump no-load operation, tool wear, hoist overload or blockage. With multi-phase monitoring, the phase sequence, phase failure, or fault current can be monitored too. If the current measured values are outside the defined range, an alert will be issued or a disconnection initiated either immediately or with a time delay.

# Current setting range (of an overcurrent release)

The range between the lowest and highest current value to which the release can be set.

#### Door-coupling rotary operating mechanism

Door-coupling rotary operating mechanisms enable motor starter protectors/circuit breakers and compact starters to be operated with the control cabinet doors closed.

#### **Electrical interlock**

Electrical dependency between switching devices, implemented by means of circuitry. Auxiliary contacts or auxiliary switches are usually used to realize an electrical interlock.

# **Explosion protection**

Prerequisite for using electrical equipment in hazardous areas conforming to DIN EN 50014 (VDE 0170/0171). In terms of explosion protection, you must ensure that equipment which may generate explosive arcs (plasma) during operation is enclosed in a flameproof casing. This means that, although the potentially explosive mixture could penetrate the enclosure, if an explosion were to occur inside it then no explosive flame could escape.

#### **Function module**

Different function modules are used for:

- Direct-on-line start
- Reversing start
- Star-delta (wye-delta) start

Function modules are also available in communication-capable versions with AS-i or IO-Link, in order to establish a connection to a higher-level control system.

#### Function module for direct-on-line start

This function module is used for the time-delayed switching of contactors.

# Function module for reversing start

The function module for reversing start is used to control a reversing starter. The version without a fieldbus interface consists of bridge modules, while the version for AS-Interface or IO-Link comprises basic and coupling modules. In all three cases, the electrical interlocks for protection in both directions are already in place.

# Function module for star-delta (wye-delta) start

The function module for star-delta (wye-delta) start is used for toggling between star (wye) and delta operation. It consists of one basic module and two coupling modules. The electrical interlocks are already in place in the modules.

# Generalized phase control for soft starters

With SIRIUS soft starters, the rms value of the motor voltage is increased (from a settable starting voltage) to the rated motor voltage within a definable start time by means of the phase control of two anti-parallel thyristor pairs.

The motor current changes in proportion to the voltage applied to the motor. As a result, the starting current is reduced by the factor of this voltage.

There is a quadratic relationship between the torque and the voltage applied to the motor. As a result, the starting torque is reduced quadratically in relation to this voltage.

# Heavy-duty starting

Heavy starting exists if a motor requires more than 10 to 15 seconds from being switched on to reaching its rated speed on account of its special load conditions. When heavy starting exists, the load torque of the machine to be driven is greater during startup than in rated operation. It takes a long time for the rated speed to be reached because large centrifugal masses need to be accelerated (e.g. on rolling mills, centrifuges). Special overload relays (heavy-duty starting relays, solid-state overload relays) or thermistor motor protection devices must be used to protect heavy-starting motors.

# Heavy-duty starting for soft starters

Assuming that certain conditions and constraints apply, the SIRIUS soft starter size must be at least one performance class higher than the motor rating for heavy-duty starting (CLASS 20 startup). The tables in the relevant product manual provide sample set values and device dimensions.

#### Holding power

The power input of the magnet coils of a contactor, which depends on the continuously consumed current, and which is required to hold the magnet system in the ON state.

# Infeed system for 3RA6

The infeed system for 3RA6 enables several compact starters to be fed using an infeed system designed to modular principles with retained wiring.

#### Instantaneous short-circuit release

Release for a motor starter protector/circuit breaker, which provides short-circuit protection for the downstream load or the cable. The instantaneous short-circuit release must disable all poles of the motor starter protector/circuit breaker (acc. to UL) instantaneously or with a short-time delay in the event of a short circuit.

#### Intrinsic device protection for soft starters

The SIRIUS 3RW40 soft starter features integrated intrinsic device protection, which protects the thyristors from thermal overload. This is achieved by measuring the current via transformers in the three phases on the one hand, and also by measuring the temperature via thermal sensors on the thyristor heat sink. If the internal, permanently set trip value is exceeded, the soft starter will switch off automatically.

#### Inverse-time delayed overload release (a release)

A thermal overload release which works with a time delay that decreases as the current rises.

#### **IO-Link**

IO-Link is a new communication standard for sensors and actuators - defined by the PROFIBUS User Organization (PNO). The IO-Link technology is based on a point-to-point connection of the sensors and actuators to the control. Therefore, this technology is not a bus system, but an enhanced version of a classic point-to-point connection. In addition to the cyclic operating data, comprehensive parameters and diagnostics data are transferred for the connected sensors and actuators. The connection system consists of a three-pole standard cable or three single wires.

# Leakage current

If semiconductors are used to control the current flow, no galvanic isolation can take place within the device. This means that, even when the supply is disconnected, if a connected load is present then a small residual current, known as the leakage current, will still flow.

# Low-voltage switchgear and controlgear combination

A switchgear and controlgear combination is a grouping of one or more low-voltage switching devices with associated equipment for controlling, measuring, and indicating, together with the associated protective devices and control devices. The manufacturer is responsible for all assembly work, including all internal electrical and mechanical connections and structural parts.

#### Main switch

Every industrial machine which falls under the scope of DIN EN 60204 Part 1 (VDE 0113, Part 1) must be equipped with a main switch which disconnects all electrical equipment from the network while cleaning, maintenance, and repair work is being carried out, as well as during long periods of downtime. Usually a switch which can be operated by hand is stipulated in order to prevent electrical or mechanical hazards. The main switch can also function as an EMERGENCY-STOP device.

It must meet the following requirements:

- 1. Externally accessible handle
- 2. Only one "Off" position and one "On" position with allocated stops
- 3. Two positions labeled "0" and "I"
- 4. Lockable "Off" position
- 5. Cover for the power supply terminals to protect against accidental contact
- 6. The switching capacity must correspond to AC-23 for motor switches and AC-22 for load-break switches (utilization category).
- 7. Switch position displayed automatically

#### Mirror contacts of power contactors

A mirror contact is an NC contact, which cannot be closed at the same time as an NO main contact (according to EN 60947-5-1, Annex F).

#### Modular system

The SIRIUS modular system offers all the functions and devices needed for switching, starting, protecting, and monitoring motors and systems. In other words, it provides a modular range of standard components, which are perfectly matched to one another, can be combined really easily, and use the same accessories.

#### Motor protection

Protection for three-phase motors against overload and short circuit, i.e. protection for the winding insulation against impermissible heating.

#### Motor starter protectors

Generally a latch-operated switch, which can switch on, conduct, and switch off currents in the circuit under normal operating conditions; it can also switch on the current up to the point of a short circuit under specified operating conditions that are not normal, conduct current for a defined period, and interrupt it too.

#### n release

Short designation for "instantaneous electromagnetic overcurrent release".

#### **OFF-delay**

The time interval effected by a timing relay or timer (on contactors, for example) between a switch-off command being issued and the contacts of the timing relay or timer reaching their initial position.

#### ON time in %

The duty ratio ON time in % is the ratio between the load duration and the cycle duration for loads that are frequently switched on and off.

# Operating range

Range within which the operating voltage of a switching device (e.g. a contactor) may deviate from the rated operating voltage without impairing the operational reliability of the switching device (e.g. contactor drop-out).

## Overload relays

Inverse-time delayed relay which responds to an overload in accordance with a time-current characteristic, thus protecting the switching device and load from overloads.

#### Overload release

Overcurrent release that provides protection against overload.

#### Phase loss sensitivity

A product feature which enables the protective device to respond even when a three-phase induction motor is running in single-phase operation, before the motor sustains thermal damage (DIN VDE 0660 Part 102).

# Polarity balancing for soft starters

In two-phase controlled SIRIUS 3RW30 and 3RW40 soft starters, the current that results from the superimposition of the two controlled phases flows in the uncontrolled phase. The main advantages of two-phase control include the more compact size compared to a three-phase version and the lower hardware costs.

The occurrence of DC components, caused by the phase control and the overlapping of phase currents, is a negative physical effect of two-phase control during the startup process that can mean a louder noise is produced by the motor. The "Polarity Balancing" control principle was developed and patented by SIEMENS to prevent these DC components during starting.

""Polarity Balancing" effectively eliminates these DC components during the startup phase. It allows the motor to be started up with a constant speed, torque, and current rise. The acoustic quality of the startup process comes very close to that of a three-phase controlled startup. This is made possible by the continuous dynamic alignment and balancing of current half-waves with different polarities during motor startup.

#### Positively driven contacts for contactor relays

Positively driven contact elements are a combination of "n" NO contacts and "m" NC contacts, which are designed such that they cannot be closed simultaneously (EN 60947-5-1, Annex L).

# Preferred wiring for star-delta (wye-delta) starters

According to the preferred wiring, the motor terminals of a motor running in the clockwise direction are connected correctly if phase L1 is connected to motor terminals U1 and V2, L2 to V1 and W2, and L3 to W1 and U2. This order should be observed during installation in order to keep the switchover current peaks in a motor running in the clockwise direction as low as possible during switchover from star to delta operation.

# Protective technology

A basic distinction can be made between two current-based protective technologies: thermal and electronic protection. Motor starter protectors and thermal overload relays provide protection by means of bimetal releases, while solid-state overload relays, 3RW40 soft starters, and 3RA6 compact starters offer protection via electronic means. Electronic protective devices not only offer a significantly lower level of power loss, they also provide a wide setting range of 1:4 and, as a result, much less variance than thermal releases. The SIRIUS modular system offers the right solution for every type of switching technology.

#### Ramp time

With SIRIUS soft starters, the length of the set ramp time determines the time taken to increase the motor voltage from the parameterized starting voltage to the line voltage. This influences the motor's acceleration torque, which drives the load during the startup process. A longer ramp time results in a lower acceleration torque as the motor is started up. The startup is slower and smoother as a result. The ramp time should be long enough for the motor to reach its nominal speed. If the time selected is too short, in other words if the ramp time ends before the motor has started up successfully, a very high starting current that can even equal the direct starting current at the same speed occurs at this instant.

# Ramp-down time

The "Ramp-down time" potentiometer on the SIRIUS 3RW40 soft starter allows you to specify how long power should still be supplied to the motor after the ON command has been removed. The torque generated in the motor is reduced by means of a voltage ramp function within this ramp-down time and the application stops smoothly.

# Ramp-up detection for soft starters

The SIRIUS 3RW40 soft starter is equipped with an integrated ramp-up detection function. If it detects a motor startup, the motor voltage is immediately increased to 100% of the line voltage. The internal bypass contacts close and the thyristors are bridged.

# Rated conditional short-circuit current Iq

The guaranteed short-circuit breaking capacity of switchgear assemblies and load feeders, also called "rated conditional short-circuit current".

#### Rated data for the control circuit

The most important rated data for the control circuit in terms of selecting a switching device (e.g. a contactor) are the rated control supply voltage U<sub>s</sub> (voltage of the coil terminal) with the associated frequency (e.g. 50 Hz), as well as the power input of the coil (closing power and holding power) in the case of contactors, for example.

#### Rated data for the main circuit

The most important rated data for the main circuit in terms of selecting a switching device (e.g. a contactor) are the rated operational current I<sub>e</sub> (current specified by the conditions of use) or the rated power (motor power), as well as the corresponding rated voltage U<sub>e</sub>.

# Rated impulse withstand voltage (U<sub>imp</sub>)

Peak value of a surge voltage with a defined waveform and polarity, which can be applied to the device under specified test conditions without the device failing and to which the clearances refer. The rated impulse withstand voltage of a device must be equal to or greater than the transient overvoltages which occur in the network on which the device is being used.

#### Rated insulation voltage Ui

Voltage value which specifies the insulation strength of the switching device or accessory and to which the insulation tests and the creepages and clearances refer. The maximum rated operational voltage must not be greater than the rated insulation voltage under any circumstances.

#### Rated service short-circuit breaking capacity Ics

Compared to the rated ultimate short-circuit breaking capacity  $I_{cu}$ , the test conditions here are stricter and the short-circuit current is usually lower. Determined using test sequence II, operating sequence O-t-CO-t-CO (O = open, t = time, CO = close-open). The function of the motor starter protector/circuit breaker must remain unrestricted following this test.

#### Rated short-circuit breaking capacity Icn

According to IEC 60947-2 and DIN EN 60947-2, the rated short-circuit breaking capacity of a motor starter protector/circuit breaker is the value of the short-circuit current, which it can switch off at the rated operational voltage, rated frequency, and specified power factor (or specified time constant). The value of the prospective current (for alternating current, the rms value of the AC component) specified by the manufacturer applies. For AC motor starter protectors/circuit breakers, the rated short-circuit breaking capacity must be independent of the magnitude of the DC (direct-current) component. The rated short-circuit breaking capacity also ensures that the motor starter protector/circuit breaker can switch off every current up to the rated short-circuit breaking capacity in the event of a line-frequency recovery voltage with 110% of the rated operational voltage.

#### This applies

- For alternating current, at every value of the power factor, but not lower than the value defined in the relevant test specification
- For direct current, if no other specifications have been made to the contrary by the manufacturer, with every time constant, but not greater than the value defined in the relevant test specification.

The short-circuit breaking capacity does not apply in the event of a line-frequency recovery voltage above 110% of the rated operational voltage.

#### Rated ultimate short-circuit breaking capacity Icu

Maximum short-circuit current  $I_k$  (limit value of the rated short-circuit breaking capacity), which can switch the motor starter protector/circuit breaker off under specific conditions. Determined using test sequence III, operating sequence O-t-CO (O = open, t = time, CO = close-open). The function of the motor starter protector/circuit breaker may be restricted following this test.

#### Recovery time

When a protection function in a switching device has been tripped (e.g. motor starter protector, soft starter, overload relay, or current monitoring relay), the motor cannot be restarted until a recovery time has elapsed. The length of the recovery time will vary, depending on the cause of the error. For more information, refer to the corresponding product documentation.

# Response delay

The response delay is the time from when you start to enter a command until the first contact connection is made, at the contactor, for example.

#### **RoHS**

EC Directive 2002/95/EC concerning the restriction of the use of certain hazardous substances in electrical and electronic equipment regulates the use of hazardous substances in devices and components. The English abbreviation RoHS is used to refer to this directive: (Restriction of the use of certain hazardous substances), as well as all related measures for implementing it into national legislation.

#### Service life

Period of time for which the switching device will work properly under normal operating conditions. This is specified as the number of operating cycles, the electrical durability (e.g. contact erosion), and the mechanical durability (e.g. operating cycles without load).

#### Short-circuit strength

This is the resistivity of a switching device in the closed state, along with its components (e.g. releases), or a complete switchgear, to the electrodynamic (dynamic strength) and thermal (thermal strength) stresses which arise in the event of a short circuit. The characteristic for the dynamic stress is the rated peak withstand current, which is the maximum instantaneous value of the short-circuit current. The characteristic for the thermal stress of the short-circuit current is the root-mean-square value of the short-circuit current throughout its duration.

# SIL (Safety Integrity Level)

Discrete level (one of three possibilities) for defining safety integrity specifications of safety-related control functions. Safety integrity level 3 is the highest possible level, level 1 the lowest.

#### Soft ramp-down

The same principle as that used for soft starting is applied during the ramp-down process. This ensures that the torque generated in the motor is reduced gradually, so that the application can ramp down smoothly.

In "soft ramp-down" mode, the natural stop process of the load is decelerated. The function is used when the load must be prevented from stopping abruptly. This is typically the case in applications with a low mass inertia or a high counter-torque.

#### Soft start

Since the motor voltage is controlled (phase control) by an electronic soft starter during the startup process, the consumed starting current and the starting torque generated in the motor are also controlled.

#### Soft starter

This is a motor starter which reduces the starting torque (starting torque, break loose torque) and the starting current of the motor in order to decrease the vibrations experienced by the driven machine and to prevent current peaks in the network. The starting torque is reduced because the supply voltage is initially set to a value lower than the rated voltage of the motor (the starting torque is proportional to the square of the voltage applied). The terminal voltage can be increased as soon as the motor starts to run. Classic ways of reducing the terminal voltage are star-delta (wye-delta) start, startup via resistors in the stator, and startup with an auto-transformer, for example. The use of solid-state motor controllers with switched thyristor circuits is becoming more and more prevalent as a way of controlling the terminal voltage on squirrel-cage motors. See also "Soft starting" and "Soft ramp-down".

#### Space above the arc chute

When a switching device is being operated, particularly when highly inductive load currents or short-circuit currents are being switched off, the ionized gases generated by the arc are pressed out of the openings in the arc chute. In order to ensure that the concentration of these ionized gases does not reach a hazardous level, a specific clearance must be provided above or in front of the device. This space above the arc chute is defined by the manufacturer (usually on the dimension drawings) and depends on whether exposed live conductors (e.g. busbars), conductive structural components, and insulating partitions can be found on the switching device. Arc chute attachments can be mounted to larger motor starter protectors in order to reduce the required clearance and therefore the space required in the control cabinet. No space is required above the arc chute for vacuum circuit breakers and vacuum contactors, since the arc will not escape from the vacuum chute and no ionized gases will be released.

# Star-delta (wye-delta) starter

See "Contactor assembly for star-delta (wye-delta) start".

#### Starting current

Three-phase induction motors have a high direct starting current I<sub>starting</sub>. Depending on the motor type, this current can be between three and fifteen times as high as the rated operational current. Seven or eight times the rated motor current can be assumed as a typical value.

#### Starting torque

The starting torque and the breakdown torque can usually be assumed to be between two and four times the rated torque. From the point of view of the load machine, this means that the starting and acceleration forces exert a higher mechanical load on the machine and the product being conveyed compared to nominal operation.

# Starting voltage

The starting voltage determines the starting torque of the motor for SIRIUS soft starters. A lower starting voltage results in a lower starting torque and a lower starting current. The starting voltage selected must be sufficiently high to ensure that motor starts up smoothly as soon as the start command is received by the soft starter.

# Switching frequency

Number of operating cycles per time unit (e.g. 15 operations per hour).

The maximum permissible switching frequency must not be exceeded because the SIRIUS soft starters could be damaged due to thermal overloading. The switching frequency of SIRIUS soft starters size S0 to S3 can be increased by installing an optional additional fan.

#### Switching technology

A basic distinction can be made between two types of switching technology: On the electromechanical side, there are contactors, contactor assemblies, and compact starters which can be used to implement solutions for direct-on-line start, reversing start, and stardelta (wye-delta) start. Frequent switching or reversing, soft starting, and soft ramp-down, on the other hand, are initiated using electronic switching devices: solid-state switching devices and soft starters. The SIRIUS modular system offers the right solution for every type of switching technology.

#### Temperature compensation

With inverse-time delayed (thermal) overload releases and relays, not only the current, but also the ambient temperature has an effect on the tripping time. An additional bimetal strip, which is not heated up by the current, can be used to compensate for the influence of the ambient temperature. If solid-state overload relays are used, electronic compensation is possible.

# Terminals for "Self Protected Combination Motor Controller Type E"

The terminals conform to the clearances and creepage distances stipulated by UL 508 (Type E).

#### Thermistor motor protection

Motor protection provided by temperature sensors (PTC sensors) integrated in the windings. These sensors monitor the winding temperature directly.

# Time-delayed auxiliary switch

Module which can be integrated into various combinations of auxiliary switches and can usually be retrofitted to a switching device too.

# Timing relay

Switching device with electronic time delay, which opens or closes contacts after a specified period of time has elapsed.

#### Tripping characteristic curve

The tripping characteristic (curve) is the graphical representation of the relationship between the tripping time and the controlling variable. The time-current diagram can be used to find out, for example, how long it will take for the release or the tripping relay to respond at a particular current.

# Tripping class (CLASS)

The tripping class of a current-dependent overload relay (including thermal and solid-state overload relays and releases) specifies the maximum tripping time from cold at a particular load. The tripping class number (e.g. CLASS 10, 20, 30) represents the maximum permissible tripping time in seconds when the relay is subjected to a symmetrical 3-pole load from cold with 7.2 times the current setting (IEC 947-4-1; DIN VDE 0660 Part 107). Tripping classes 20 and 30 are used for protecting the motor under heavy-duty starting conditions, for example.

# Tripping current (of an overload release)

The current value at which a release trips within a certain time.

#### Two-phase control

With solid-state switching devices like soft starters or solid-state contactors, two out of three active phases are controlled by means of semiconductors. For example, SIRIUS 3RW30 and 3RW40 soft starters feature two anti-parallel thyristors in each of phases L1 and L3. Phase L2 is an uncontrolled phase, which is routed through the starter via a copper link and connected directly to the corresponding output terminal.

# Types of coordination

Standard DIN EN 60947-4-1 (VDE 0660 Part 102) or IEC 60947-4-1 distinguishes between two types of coordination (type of coordination), which are referred to as coordination type "1" and coordination type "2". The short circuit that needs to be dealt with is cleared reliably and safely with both types of coordination; the only differences are in the extent of the damage sustained by the device following a short circuit.

For additional information, please refer to the appendix.

## **Utilization category**

According to DIN EN 60947-4-1, the application area of and the load applied to power contactors can be identified by looking at the specified utilization category in conjunction with the specified rated operational current or the motor power and the rated voltage. An example is utilization category AC-3 for starting and switching off squirrel-cage motors.

#### Voltage ramp

The SIRIUS 3RW30 and 3RW40 soft starters achieve soft starting by means of a voltage ramp. The motor terminal voltage is increased from a parameterizable starting voltage up to the line voltage within a definable start time.

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