

**SIEMENS**



Application Example • 09/2016

# Display of SINAMICS Error Messages in Runtime Professional

SINAMICS G120, WinCC Runtime Professional



<https://support.industry.siemens.com/cs/ww/en/view/109738320>

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# 1 Task

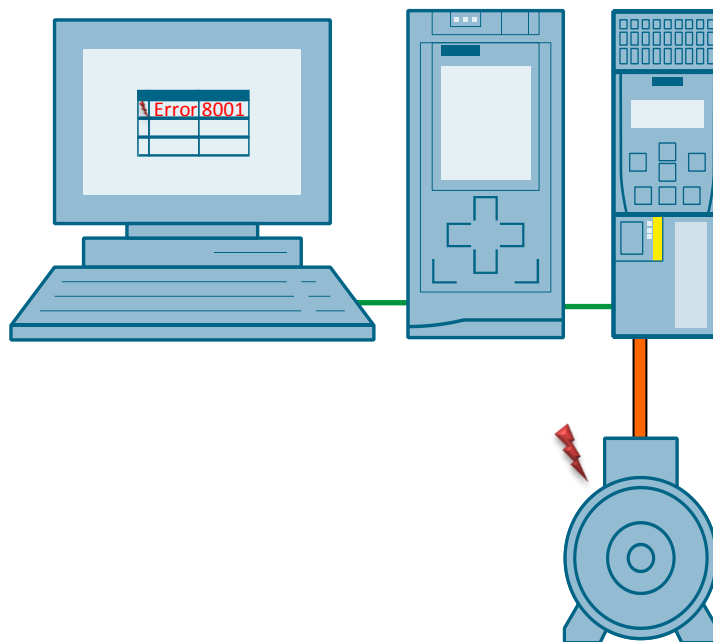
## Description of the automation task

This application example shows how you can read warning and error messages from the frequency converter and display them in the alarm view of WinCC Runtime Professional.

## Overview of the automation task

The figure below provides an overview of the automation task.

Figure 1-1

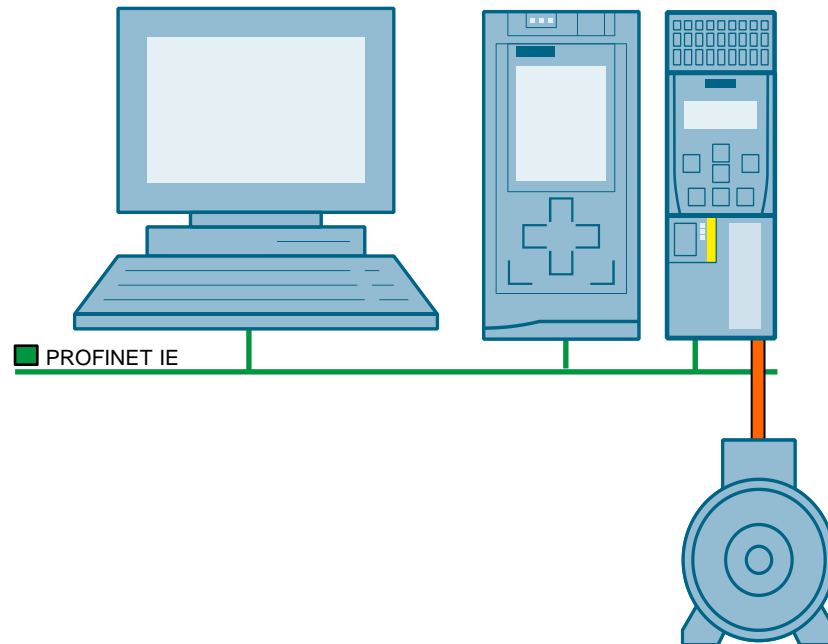


## 2 Solution

### 2.1 Configuration

#### Diagrammatic representation

Figure 2-1



#### Example

Using WinCC Runtime Professional, you want to:

- Display warning and error messages via the alarm view

#### Required knowledge

To implement the solution described in this document, basic knowledge of the following topics is required:

- Automation technology
- Commissioning of the SINAMICS G120 frequency converter

## 2.2 Hardware and software components

### 2.2.1 Validity

This application is valid for

- TIA Portal V13 SP1 Update 7

### 2.2.2 Components used

The application was created with the following components:

#### Hardware components

Table 2-1

Component	No.	Article number	Note
SINAMICS Control Unit CU240E-2 PN-F	1	6SL3244-0BB13-1FA0	Firmware >= V4.7
SINAMICS PM240-2	1	6SL3210-1PB13-0AL0	
SIMATIC IPC 677D	1	6AV7260-5GM40-0XX0	Alternatively, you can use a different IPC.
SIMATIC S7 1516-3 PN/DP	1	6ES7516-3AN00-0AB0	Alternatively, you can use a different S7-1500.
Low-voltage motor	1	1LA7060-4AB10-Z	

#### Software components

Table 2-2

Component	No.	Article number	Note
SINAMICS Startdrive V13	1	6SL3072-4DA02-0XG0	
WinCC Runtime Professional V13	1	6AV2105-....3-0	
STEP 7 Professional V13	1	6ES7822-1..03	

#### Sample files and projects

The following list contains all files and projects that are used in this example.

Table 2-3

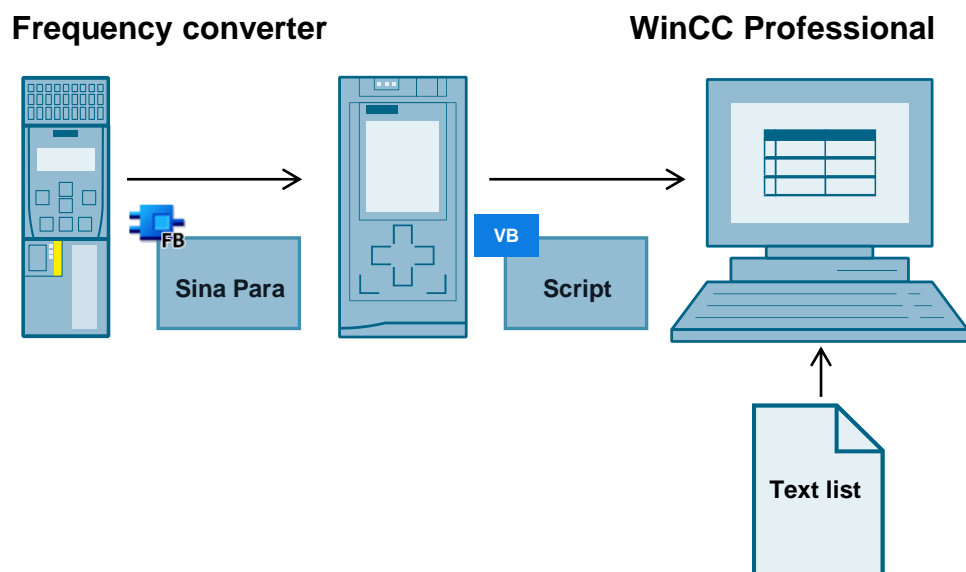
Component	Note
109738320_HMI_FU_CODE_v13.zip	This zip file contains the WinCC TIA Portal project.
109738320_HMI_FU_DOKU_v13_e.pdf	This document.

## 3 Basics

### 3.1 Access to converter parameters

Parameters in the SINAMICS drive are accessed using the SINA PARA block of the S7-1500. Parameter 2132 (current warning messages) and parameter 2131 (current error messages) are read with the aid of the SINA block. Using a VBScript script, the warning and error messages are displayed as user alarms in the alarm view of WinCC Professional. The text list contains the error and warning message of the respective SINAMICS drive.

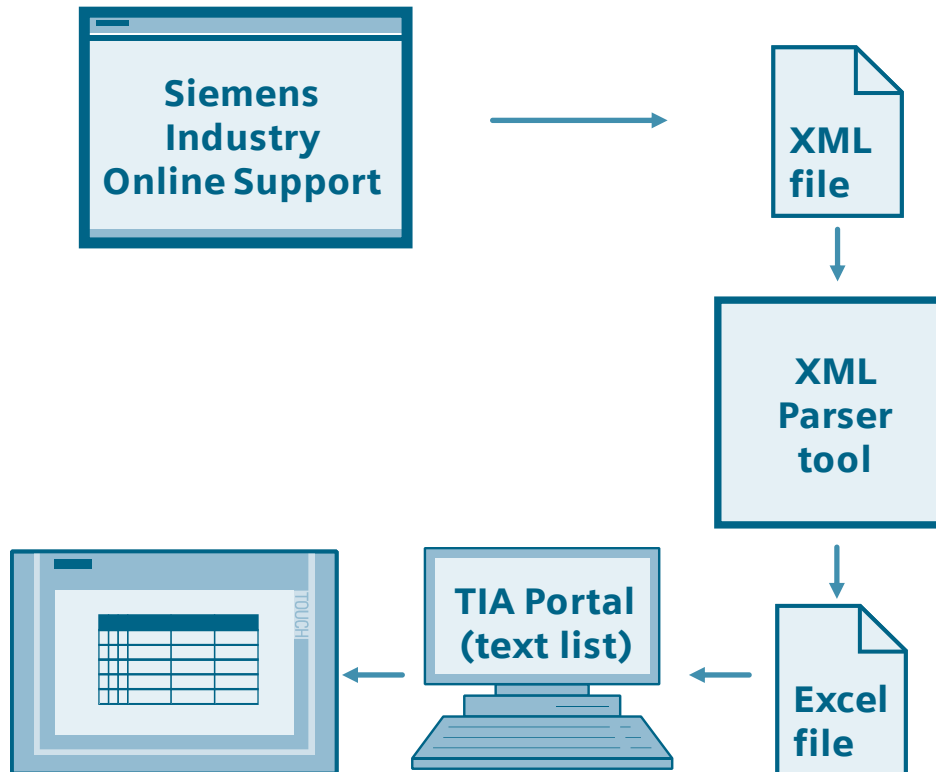
Figure 3-1



## 3.2 Creating error messages in WinCC Professional

In [Industry Online Support](#), you will find an XML file that contains fault and warning messages for your drive component and firmware. This file must be downloaded from the Internet. With the aid of the [XML Parser](#) tool, the XML file can be converted to Excel. This format can be inserted into a text list of your TIA Portal project. With the aid of a user alarm, the HMI with the error and warning messages is linked to a text list. It is displayed in the HMI via an alarm view.

Figure 3-2





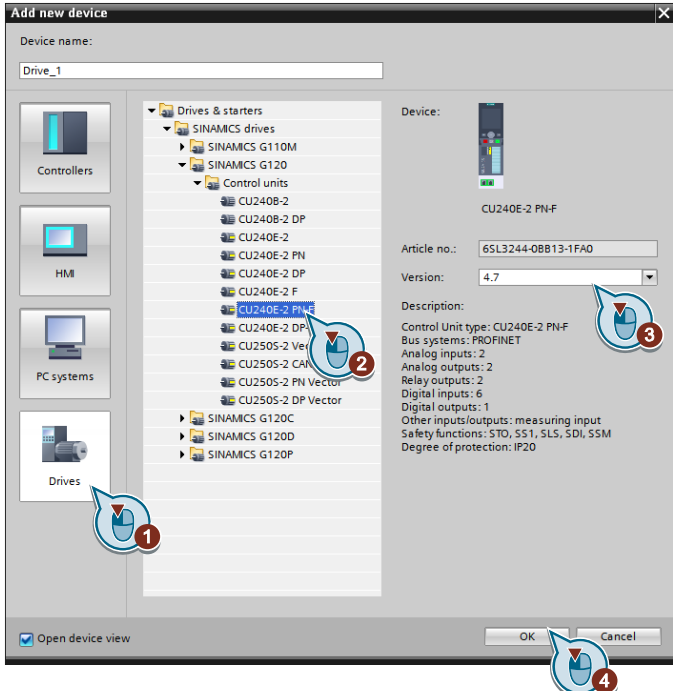
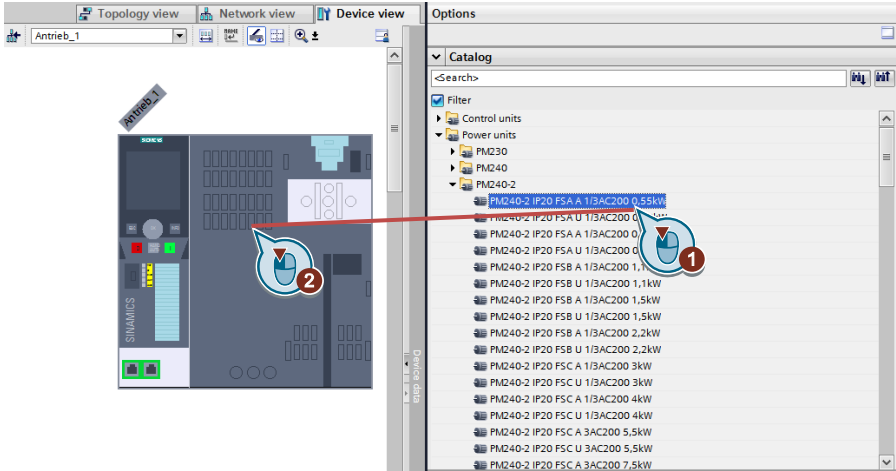
# 4 Configuration and Project Engineering: Drive

## 4.1 Adding the frequency converter to the project

If the “Startdrive” option package is installed in TIA Portal, the G120 can be added as a new device, configured and parameterized. Alternatively, you can configure the frequency converter using STARTER plus SSP for version 4.7 or higher.

For the “Startdrive” option package, please refer to the following Entry ID: [68034568](https://www.siemens.com/press/en/entry/68034568)

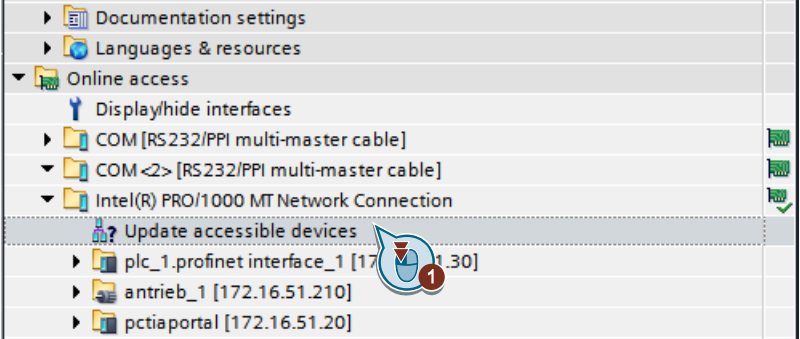
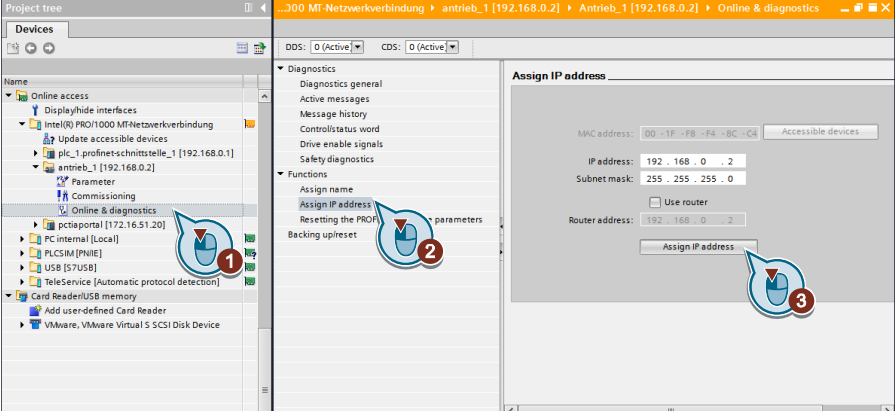
Table 4-1

No.	Action
1.	<p>Add a control unit to your project: In the project tree, go to “Add new device → Drives” and select your control unit.</p> 
2.	<p>Add the power module to your control unit.</p> 

## 4.2 Setting the Ethernet address

In order to establish a connection via Ethernet, assign an IP address to the SINAMICS converter. To do this, the SINAMICS offers the following options:

Table 4-2

No.	Procedure
1.	<p>In the “Online access” menu, double-click the “Update accessible devices” menu item.</p> 
2.	<p>In the list of accessible devices, select the drive and activate “Online &amp; diagnostics”. Then assign an IP address and a PROFINET name to the converter.</p> 

### 4.3 Running the Commissioning Wizard

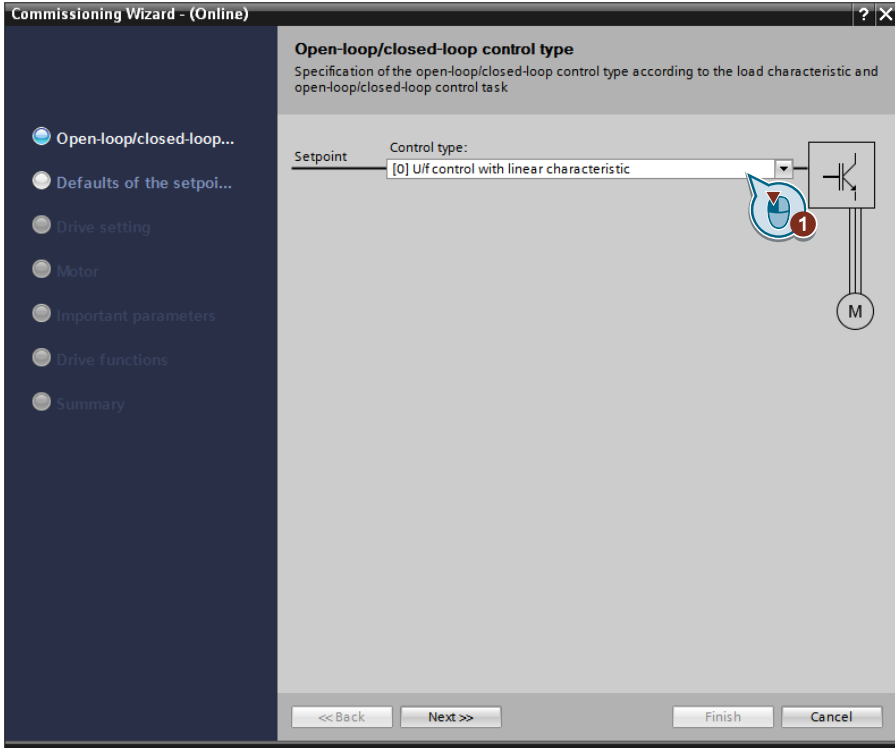
The Startdrive Commissioning Wizard allows you to perform commissioning in a short time. Startdrive supports offline commissioning in the project or online commissioning directly on the drive unit. After offline commissioning, download the configuration from the PG/PC to the unit; after online commissioning, download the configuration from the drive unit to your project. In the next step, you will get to know online commissioning.

**Note**

**Quick online commissioning**

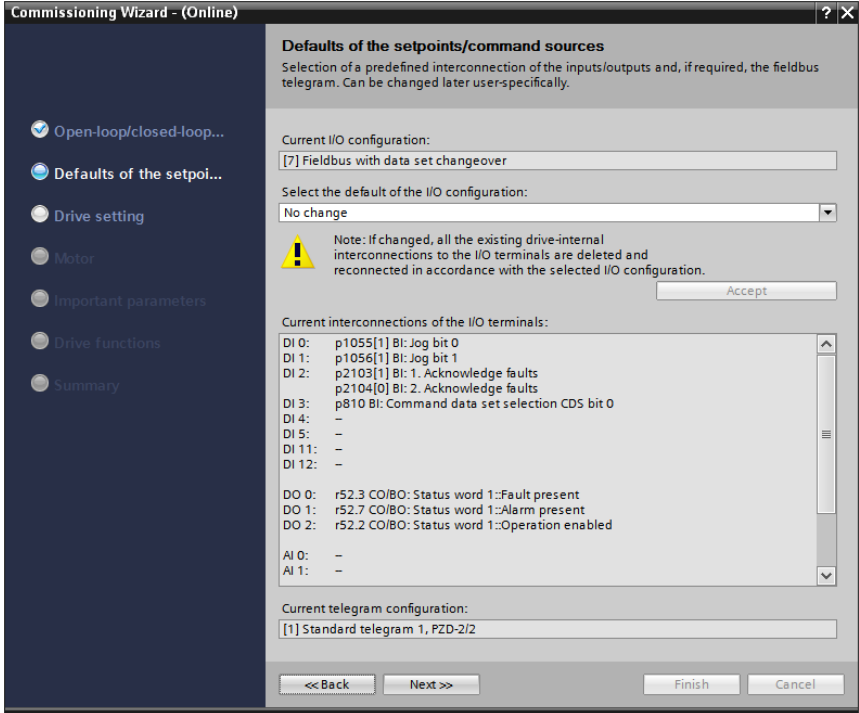
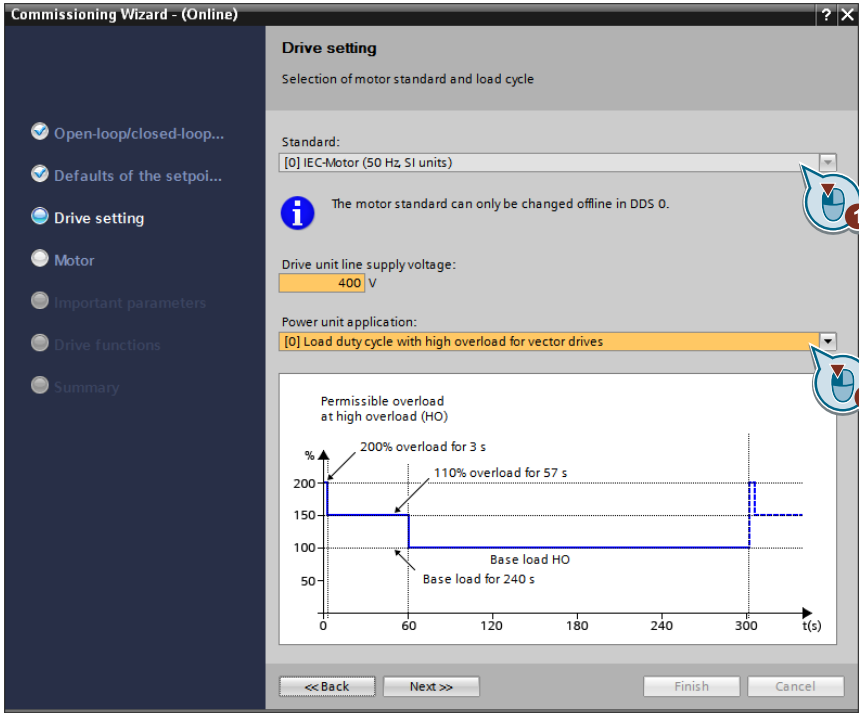
Before commissioning, you have to connect Startdrive online to the drive unit.

Table 4-3

No.	Action
1.	In the project navigator, select the drive unit and in the context menu, select "Go online".
2.	In the project navigator, double-click "Commissioning". A window appears in the workspace. In the workspace, click "Commissioning Wizard". The wizard starts.
3.	<p>Set the open-loop/closed-loop control type. Click "Next" to confirm the settings.</p> 

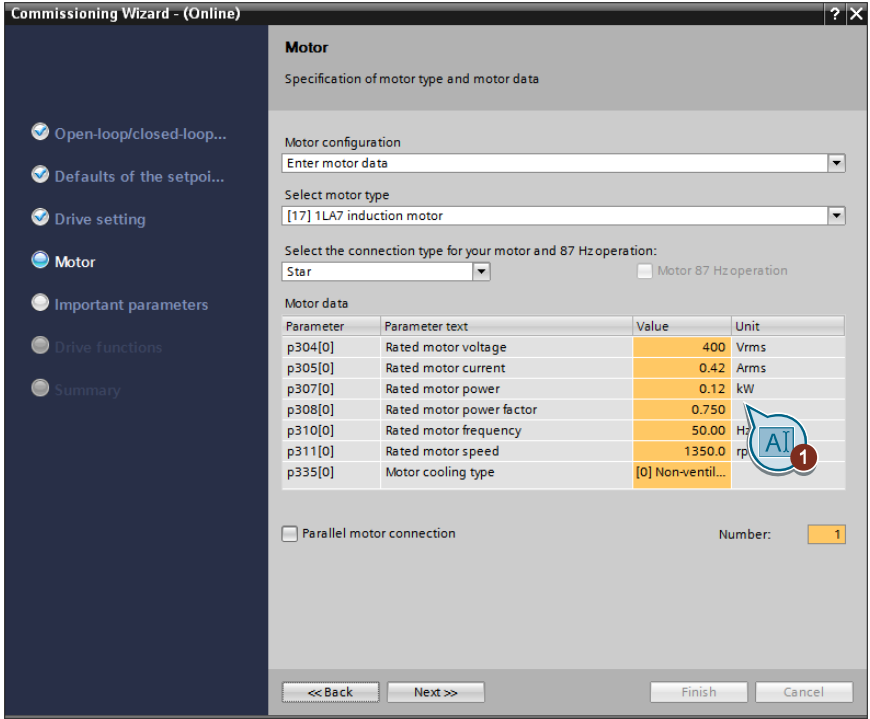
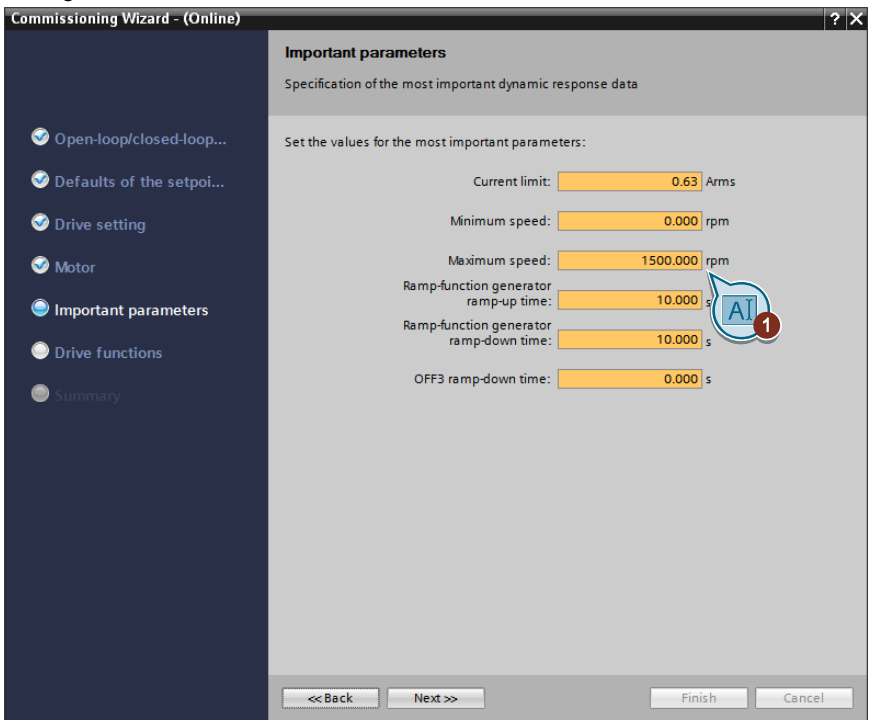
## 4 Configuration and Project Engineering: Drive

### 4.3 Running the Commissioning Wizard

No.	Action
4.	<p>Select the setpoints and command sources. Click "Next" to confirm the settings.</p> 
5.	<p>The motor standard used is "IEC motor 50Hz SI units", the power unit application is "Load duty cycle with high overload for vector drives". Click "Next" to confirm the settings.</p> 

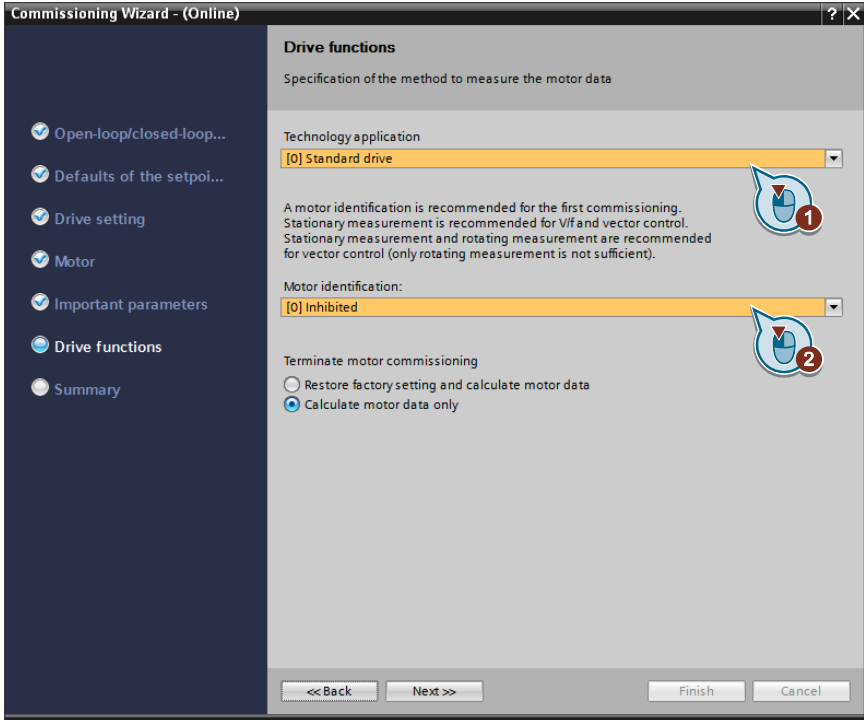
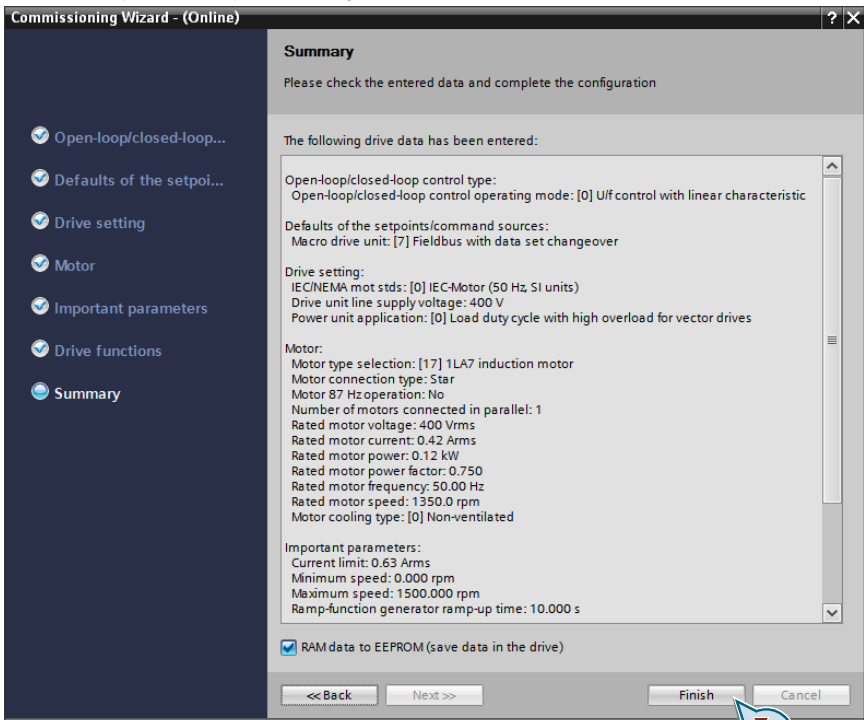
## 4 Configuration and Project Engineering: Drive

### 4.3 Running the Commissioning Wizard

No.	Action																																
6.	<p>For the motor data, refer to the motor rating plate and enter it in the Motor dialog. Click "Next" to confirm the settings.</p>  <p>Commissioning Wizard - (Online)</p> <p><b>Motor</b> Specification of motor type and motor data</p> <p>Motor configuration Enter motor data</p> <p>Select motor type [17] 1LA7 induction motor</p> <p>Select the connection type for your motor and 87 Hz operation: Star <input type="checkbox"/> Motor 87 Hz operation</p> <p>Motor data</p> <table border="1"> <thead> <tr> <th>Parameter</th> <th>Parameter text</th> <th>Value</th> <th>Unit</th> </tr> </thead> <tbody> <tr> <td>p304[0]</td> <td>Rated motor voltage</td> <td>400</td> <td>Vrms</td> </tr> <tr> <td>p305[0]</td> <td>Rated motor current</td> <td>0.42</td> <td>Arms</td> </tr> <tr> <td>p307[0]</td> <td>Rated motor power</td> <td>0.12</td> <td>kW</td> </tr> <tr> <td>p308[0]</td> <td>Rated motor power factor</td> <td>0.750</td> <td></td> </tr> <tr> <td>p310[0]</td> <td>Rated motor frequency</td> <td>50.00</td> <td>Hz</td> </tr> <tr> <td>p311[0]</td> <td>Rated motor speed</td> <td>1350.0</td> <td>rpm</td> </tr> <tr> <td>p335[0]</td> <td>Motor cooling type</td> <td>[0] Non-ventil...</td> <td></td> </tr> </tbody> </table> <p><input type="checkbox"/> Parallel motor connection Number: 1</p> <p>&lt;&lt; Back Next &gt;&gt; Finish Cancel</p>	Parameter	Parameter text	Value	Unit	p304[0]	Rated motor voltage	400	Vrms	p305[0]	Rated motor current	0.42	Arms	p307[0]	Rated motor power	0.12	kW	p308[0]	Rated motor power factor	0.750		p310[0]	Rated motor frequency	50.00	Hz	p311[0]	Rated motor speed	1350.0	rpm	p335[0]	Motor cooling type	[0] Non-ventil...	
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p335[0]	Motor cooling type	[0] Non-ventil...																															
7.	<p>In the "Important parameters" dialog, you can customize the ramp-up times, the current limit and the minimum and maximum speed. Click "Next" to confirm the settings.</p>  <p>Commissioning Wizard - (Online)</p> <p><b>Important parameters</b> Specification of the most important dynamic response data</p> <p>Set the values for the most important parameters:</p> <p>Current limit: 0.63 Arms</p> <p>Minimum speed: 0.000 rpm</p> <p>Maximum speed: 1500.000 rpm</p> <p>Ramp-function generator ramp-up time: 10.000 s</p> <p>Ramp-function generator ramp-down time: 10.000 s</p> <p>OFF3 ramp-down time: 0.000 s</p> <p>&lt;&lt; Back Next &gt;&gt; Finish Cancel</p>																																

## 4 Configuration and Project Engineering: Drive

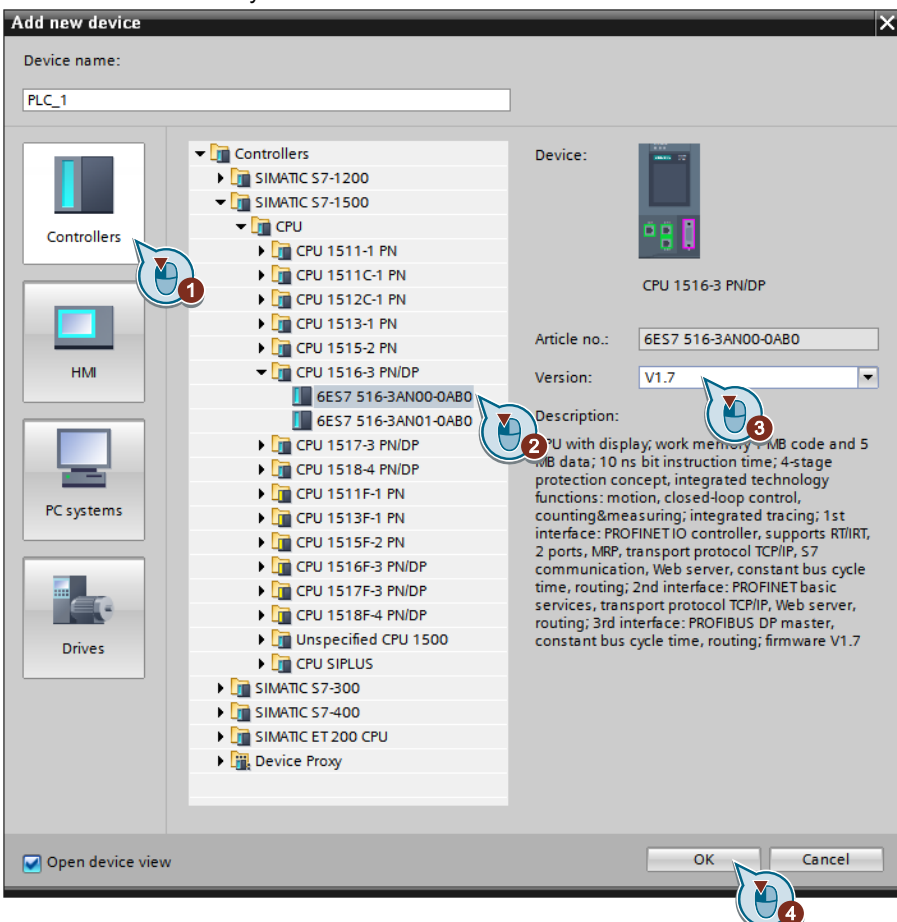
### 4.3 Running the Commissioning Wizard

No.	Action
8.	<p>Specify the motor identification. Click "Next" to confirm the settings.</p> 
9.	<p>In Summary, confirm your settings and click the Finish button.</p> 

# 5 Configuration and Project Engineering: PLC

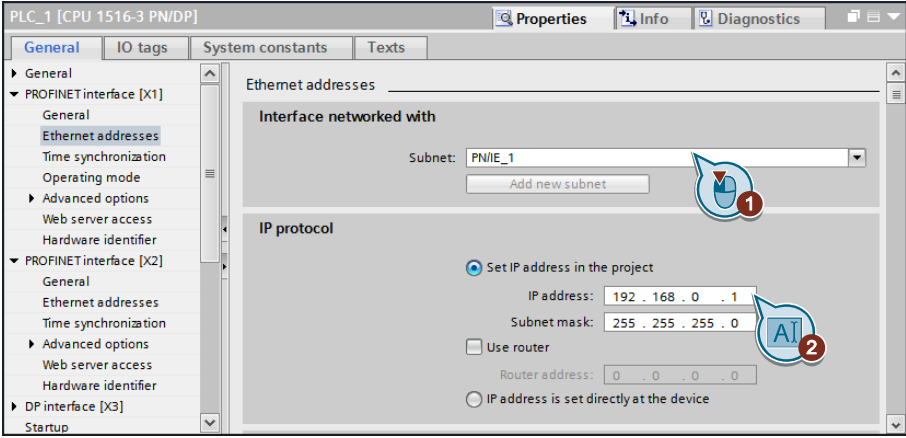
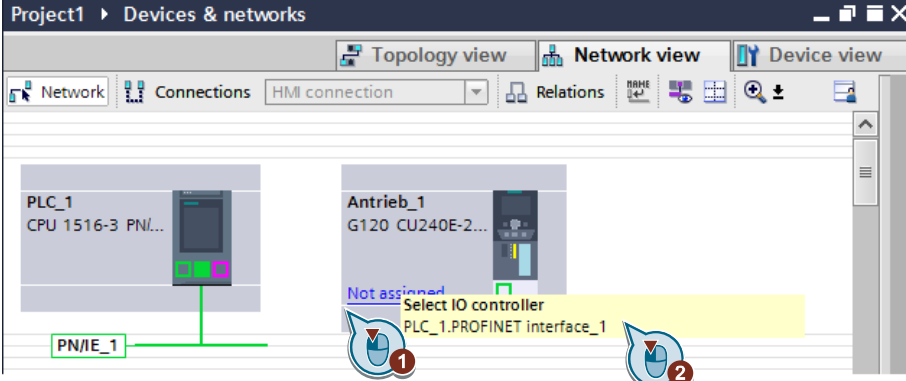
## 5.1 Adding the PLC to the project

Table 5-1

No.	Action
1.	<p>Add a controller to your project: In the project tree, go to “Add new device → Controllers” and select your controller.</p>  <p>The screenshot shows the 'Add new device' dialog box. On the left, there are icons for 'Controllers', 'HMI', 'PC systems', and 'Drives'. The 'Controllers' icon is highlighted with a blue callout '1'. The main area shows a tree view of controllers, with 'CPU 1516-3 PN/DP' selected, highlighted with a blue callout '2'. The 'Article no.' field contains '6ES7 516-3AN00-0AB0' and the 'Version' dropdown is set to 'V1.7', both highlighted with a blue callout '3'. The 'Description' field contains detailed technical specifications for the CPU. At the bottom, the 'Open device view' checkbox is checked, and the 'OK' button is highlighted with a blue callout '4'.</p>

## 5 Configuration and Project Engineering: PLC

### 5.1 Adding the PLC to the project

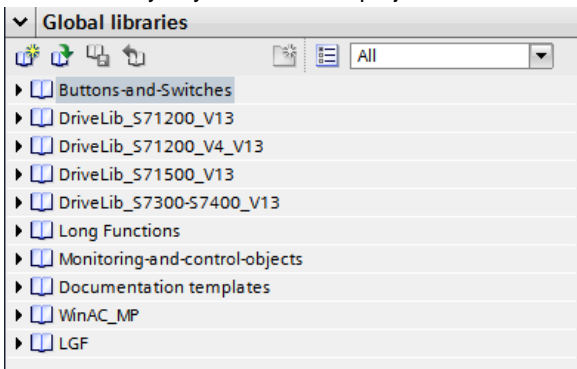
No.	Action
2.	<p>Select a subnet and assign an IP address to your controller that is in the same network as your frequency converter.</p> 
3.	<p>Open the Devices &amp; networks view. Assign a controller to the control unit.</p> 



## 5.2 Adding the DriveLib library

The DriveLib library provides standard blocks for easy implementation of a cyclic/acyclic communication connection between a SIMATIC S7-300/400/1200/1500 controller and a drive with the SINAMICS S/G converter system.

Table 5-2

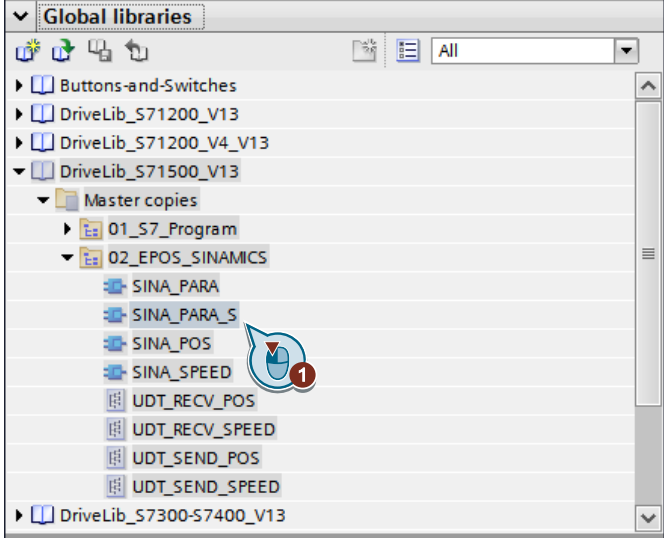
No.	Action
1.	Download the Drive LIB library at this Entry ID link: <a href="https://www.siemens.com/entry/109475044">109475044</a>
2.	Unzip the library.
3.	In TIA Portal, open the “Libraries” task card.
4.	Add the library to your TIA Portal project. 

### 5.3 Adding the SINA\_PARA\_S block to the controller

The SINA\_Para\_S function block is used to easily connect different SINAMICS S/G converter systems to a SIMATIC S7 controller. The block can be used with the following CPUs: S7-300/400/1200/1500.

The acyclic communication block FB287 (SINA\_PARA\_S) provides the user with a predefined interface for easy read/write access to any SINAMICS drive parameters. The only data the user has to specify is the parameter number, a possible index and – for write access – a parameter value. After starting the job, the job is processed autonomously.

For more information about the block, please refer to the following Entry ID: [109475044](#)

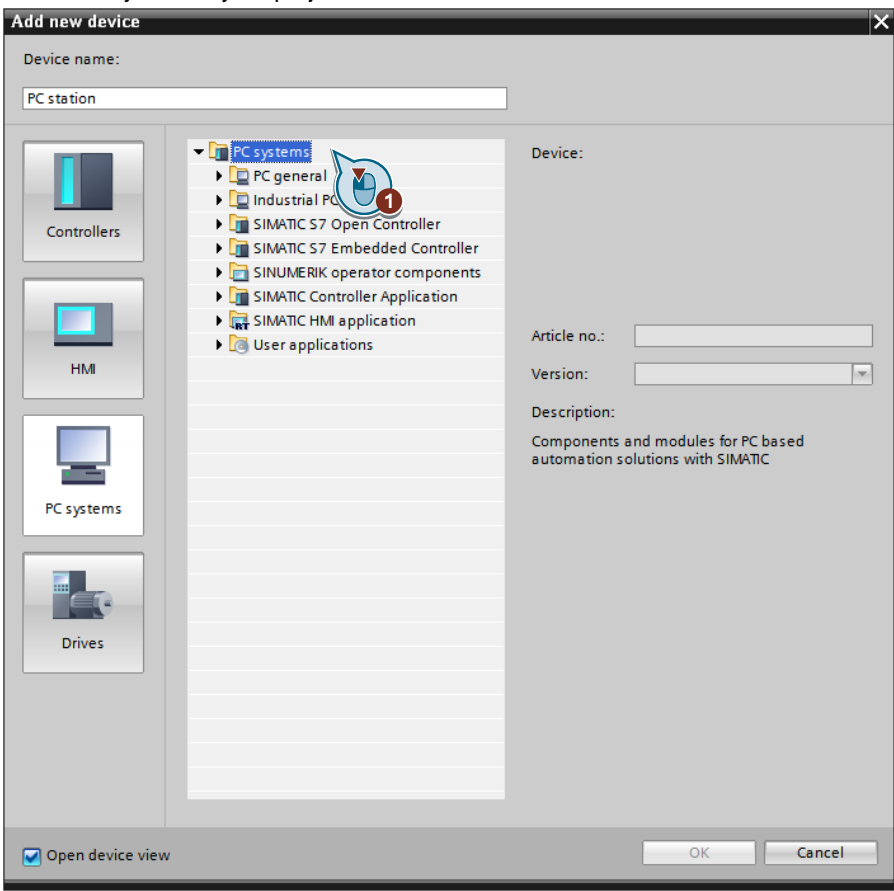
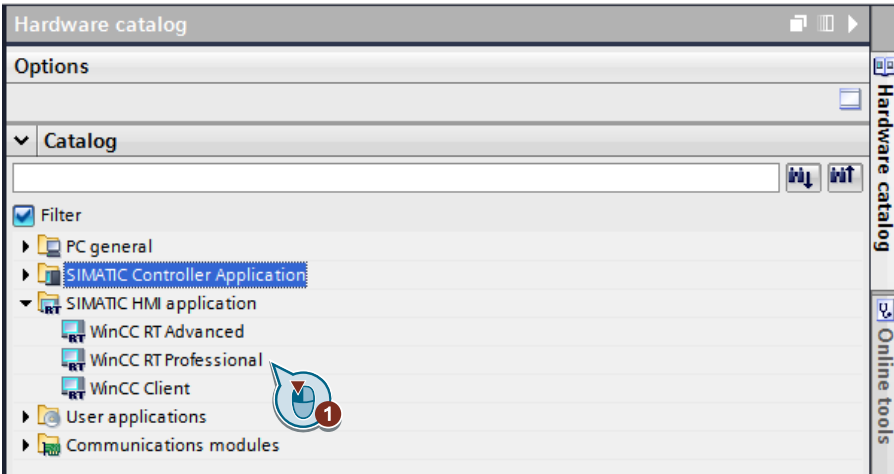
No.	Action
1.	<p>Insert the SINA_PARA_S block twice into your organization block OB1.</p>  <p>The screenshot shows the 'Global libraries' window with the following structure:</p> <ul style="list-style-type: none"><li>Global libraries<ul style="list-style-type: none"><li>Buttons-and-Switches</li><li>DriveLib_S71200_V13</li><li>DriveLib_S71200_V4_V13</li><li>DriveLib_S71500_V13<ul style="list-style-type: none"><li>Master copies<ul style="list-style-type: none"><li>01_S7_Program</li><li>02_EPOS_SINAMICS<ul style="list-style-type: none"><li>SINA_PARA</li><li><b>SINA_PARA_S</b> (highlighted with a red circle and '1')</li><li>SINA_POS</li><li>SINA_SPEED</li><li>UDT_RECV_POS</li><li>UDT_RECV_SPEED</li><li>UDT_SEND_POS</li><li>UDT_SEND_SPEED</li></ul></li></ul></li></ul></li><li>DriveLib_S7300-S7400_V13</li></ul></li></ul>

No.	Action																								
2.	<p>Read the error message [parameter 2131] of the SINAMICS G120 using the SINA block.</p> <p>The "StartFaultmessage" PLC tag was created for starting the read job. The current error number is written to the "ReadFaultNumber" tag.</p> <table border="1"> <thead> <tr> <th>Input signal</th> <th>Type</th> <th>Meaning</th> </tr> </thead> <tbody> <tr> <td>Start</td> <td>BOOL</td> <td>Start of read job</td> </tr> <tr> <td>ReadWrite</td> <td>BOOL</td> <td>Type of job 0 = read, 1 = write</td> </tr> <tr> <td>LAddr</td> <td>HW-IO/INT</td> <td>Hardware ID/address of axis or drive</td> </tr> <tr> <td>ParaNo</td> <td>INT</td> <td>Parameter number [parameter 2131 = error message]</td> </tr> <tr> <td>Value Write</td> <td>REAL</td> <td>Value of parameter</td> </tr> <tr> <td>AxisNO</td> <td>INT</td> <td>Axis number/axis ID for system with multiple axes</td> </tr> <tr> <td>ValueRead</td> <td>REAL</td> <td>Value of read parameter</td> </tr> </tbody> </table> <p><b>Network 1: fault number</b></p>	Input signal	Type	Meaning	Start	BOOL	Start of read job	ReadWrite	BOOL	Type of job 0 = read, 1 = write	LAddr	HW-IO/INT	Hardware ID/address of axis or drive	ParaNo	INT	Parameter number [parameter 2131 = error message]	Value Write	REAL	Value of parameter	AxisNO	INT	Axis number/axis ID for system with multiple axes	ValueRead	REAL	Value of read parameter
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AxisNO	INT	Axis number/axis ID for system with multiple axes																							
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3.	<p>Read the warning message [parameter 2132] of the SINAMICS G120 using the SINA block.</p> <p>The "StartWarningmessage" PLC tag was created for starting the read job. The current warning number is written to the "ReadWarningNumber" tag.</p> <table border="1"> <thead> <tr> <th>Input signal</th> <th>Type</th> <th>Meaning</th> </tr> </thead> <tbody> <tr> <td>Start</td> <td>BOOL</td> <td>Start of read job</td> </tr> <tr> <td>ReadWrite</td> <td>BOOL</td> <td>Type of job 0 = read, 1 = write</td> </tr> <tr> <td>LAddr</td> <td>HW-IO/INT</td> <td>Hardware ID/address of axis or drive</td> </tr> <tr> <td>ParaNo</td> <td>INT</td> <td>Parameter number [parameter 2132 = warning message]</td> </tr> <tr> <td>Value Write</td> <td>REAL</td> <td>Value of parameter</td> </tr> <tr> <td>AxisNO</td> <td>INT</td> <td>Axis number/axis ID for system with multiple axes</td> </tr> <tr> <td>ValueRead</td> <td>REAL</td> <td>Value of read parameter</td> </tr> </tbody> </table> <p>Network 2: warning number</p> <p>Comment</p>	Input signal	Type	Meaning	Start	BOOL	Start of read job	ReadWrite	BOOL	Type of job 0 = read, 1 = write	LAddr	HW-IO/INT	Hardware ID/address of axis or drive	ParaNo	INT	Parameter number [parameter 2132 = warning message]	Value Write	REAL	Value of parameter	AxisNO	INT	Axis number/axis ID for system with multiple axes	ValueRead	REAL	Value of read parameter
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Value Write	REAL	Value of parameter																							
AxisNO	INT	Axis number/axis ID for system with multiple axes																							
ValueRead	REAL	Value of read parameter																							

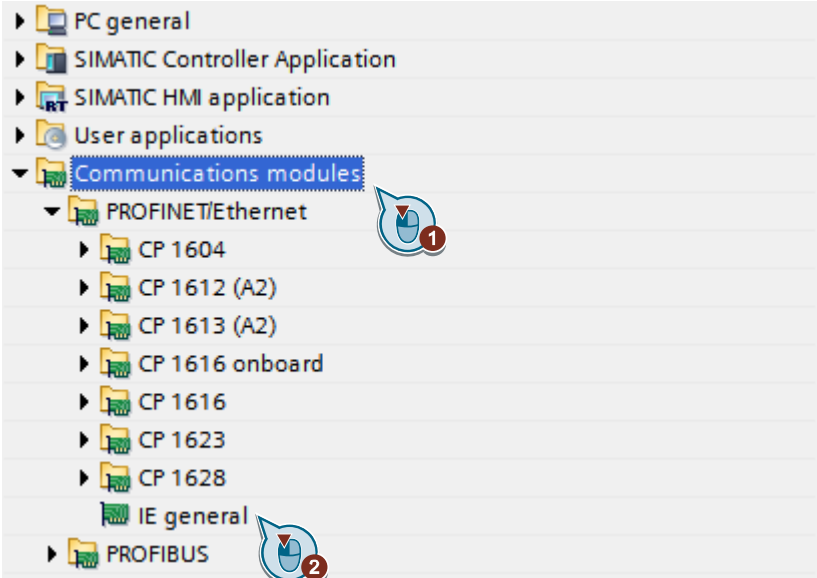
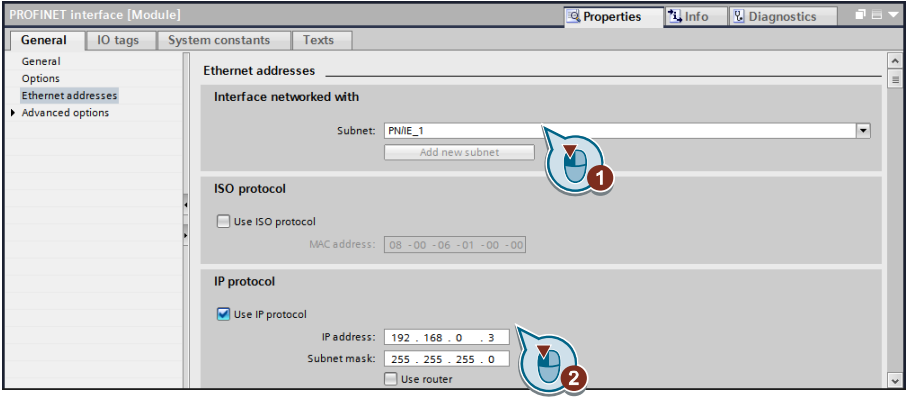
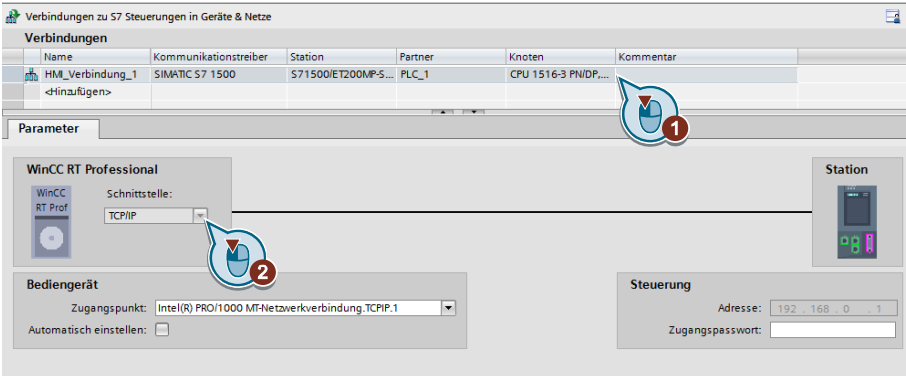
## 5.4 Setting the IP address on the PC station

Table 5-3

No.	Action
1.	<p>Add a PC system to your project.</p> 
2.	<p>Select WinCC RT Professional as the HMI application.</p> 

## 5 Configuration and Project Engineering: PLC

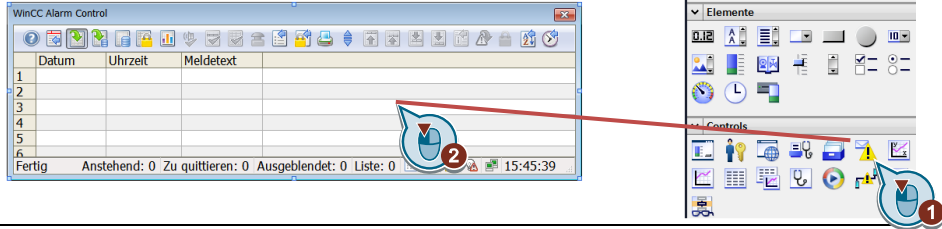
### 5.4 Setting the IP address on the PC station

No.	Action
3	<p>Add a communications module.</p> 
4.	<p>Assign a subnet to your PC system. Assign an IP address and a subnet mask in the same network as your frequency converter.</p> 
5.	<p>Configure an HMI connection to the S7 controller.</p> 

## 5.5 Configuring the alarm view

Table 5-4

No.	Action
1.	Insert an "alarm view" into the desired screen in order to display the messages on the HMI. To insert an "alarm view", use drag and drop to move the alarm view from the "Tools" task card in the "Controls" palette to the screen.

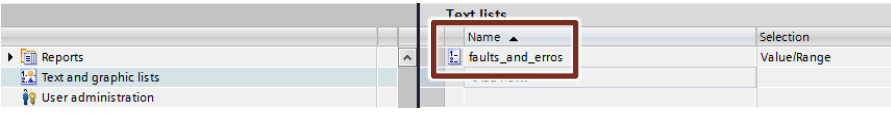
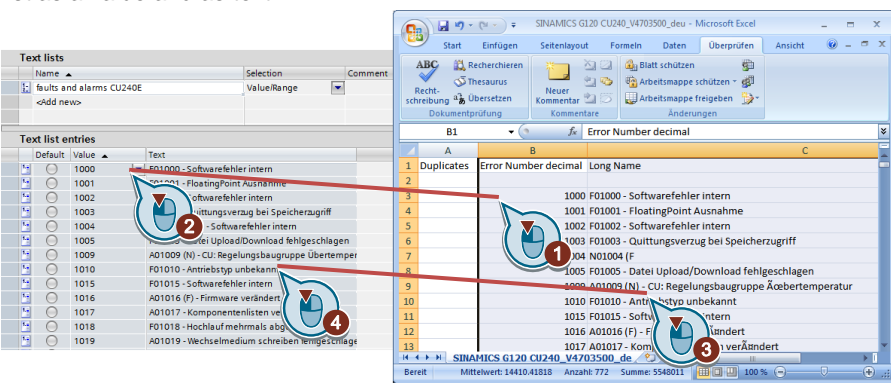
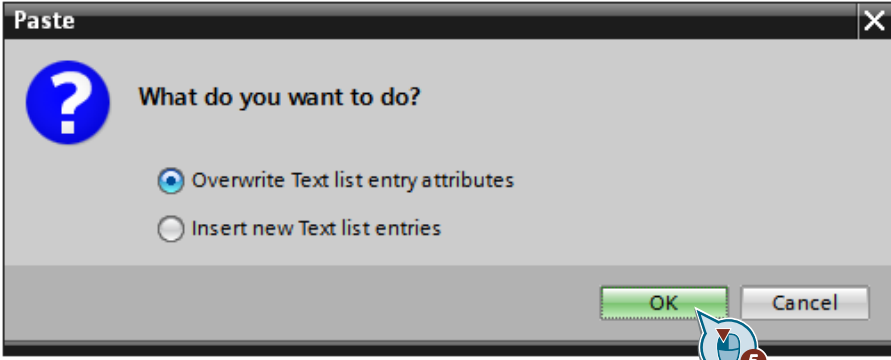




## 5.6 Generating a text list with the SINAMICS XML Parser

In [Industry Online Support](#), you will find an XML file that contains fault and warning messages for your drive component and firmware. For the SINAMICS Control Unit CU240E-2 PN-F firmware version 4.7 described in the application example, the fault and warning messages can be found at the following Entry ID link: [92554110](#). With the aid of the XML Parser tool, the XML file can be converted to Excel. The following section shows you how to convert the faults and warnings to Excel for a CU240E-2 PN-F.

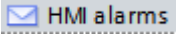
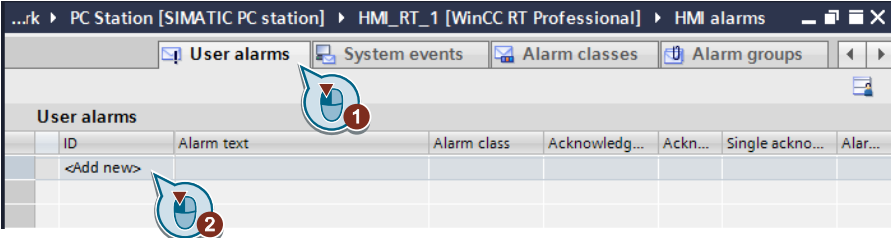
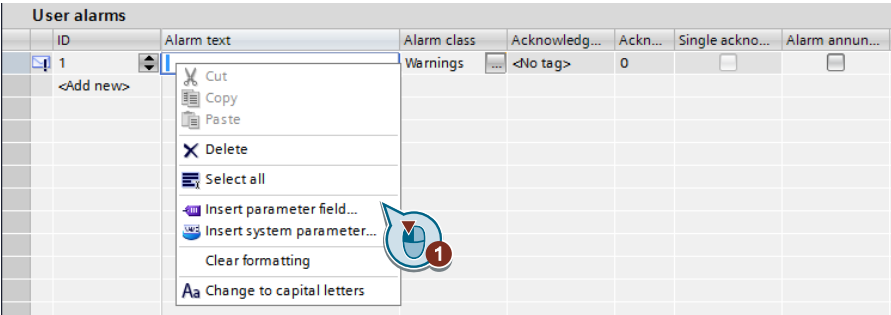
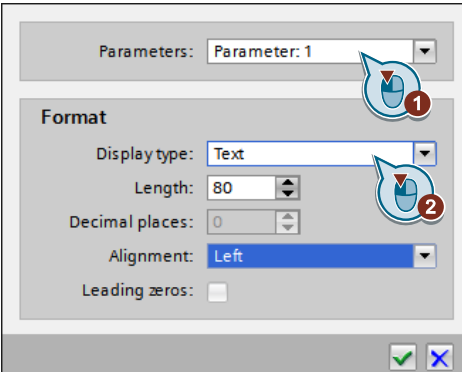
Table 5-5



No.	Action
1.	Download the fault and warning messages for your SINAMICS Control Unit with its firmware version from <a href="#">Industry Online Support</a> to your computer.
2.	Use the XML parser to generate an Excel spreadsheet with fault and warning messages. For detailed information on the XML parser, please refer to the following Entry ID: <a href="#">77467239</a>
3.	Generate a text list for the drive's fault and warning messages. 
4.	Copy, column by column, the fault and warning messages to the newly created text list as a value and as text.  <p>When copying the columns, you will be prompted to overwrite them. Click the  button.</p>

## 5.7 Configuring a user alarm

In the project, a user alarm is configured with the aid of a script: Using the SINA block, the error and warning messages of the SINAMICS are read from the PLC. With the aid of the “LookupText” function, the error number is linked to the configured error texts from the text list and displayed in the alarm view. For more information on how to configure messages and alarms in WinCC (TIA Portal), please refer to Entry ID: [62121503](#)

Table 5-6

No.	Action
1.	In the project tree, open HMI alarms. 
2.	Open the “User alarms” tab. Add a new user alarm. 
3.	Open the “Insert parameter field...” tab. 
4.	Select a parameter. In Display type, select “Text”. 

No.	Action
5.	<p>Configure the following actions to a button.</p> <p>Pressing the button sets the “StartWarningMessage” tag to true. This executes the SINA_PARA_S block that returns the drive’s current warning number.</p>  <p>Releasing the button starts the “EAWarning” script that, with the aid of the text list, converts the current error number to error text.</p> 
6.	<p>Create the following script.</p> <p>The script checks the SINA_PARA_S block’s warning number. As soon as the warning number is 0, the drive is OK. If the number is not 0, a user alarm is called. To this end, the current warning number is linked to the text list using the “LookupText” command and then displayed in the alarm view.</p> <pre data-bbox="469 853 1366 1944"> 1 2 3 Sub EAWarning () 4 5 'Check warning message is active 6 If SmartTags("ReadWarningNumber") = 0 Then 7 HMIRuntime.Trace "Drive OK" &amp; vbCrLf 8 Else 9 10 'Read actual language 11 Dim language 12 language = HMIRuntime.Language 13 SmartTags("HMIlanguage") = language 14 15 'German text 1031 16 If language = 1031 Then 17 LookupText "warningtext", "ReadWarningNumber", "de-DE", "faults_and_errors" 18 End If 19 20 'Englisch text 1033 21 If language = 1033 Then 22 LookupText "warningtext", "ReadWarningNumber", "en-US", "faults_and_errors" 23 End If 24 25 'Create User Alarm 26 If (language = 1033 Or language = 1031) Then 27 Dim userAlarm 28 Dim ID_UA 29 Dim State_UserAlarm 30 ID_UA = "2" 31 State_UserAlarm = "1" 32 Dim text 33 text = SmartTags("warningtext") 34 Set userAlarm = HMIRuntime.Alarms(ID_UA) 35 userAlarm.State = State_UserAlarm 36 userAlarm.ProcessValues(1) = text 37 userAlarm.ProcessValues(2) = text 38 userAlarm.Create "MyApplication" 39 Else 40 HMIRuntime.Trace "Language not configured" &amp; vbCrLf 41 End If 42 43 44 End If 45 46 End Sub </pre>
7.	Repeat steps 1 through 6 for the error messages.

## 6 Operation of the Application

Before you start up the configuration, check the wiring of the components.

### 6.1 Starting up the sample project

Table 6-1

No.	Action
1.	Unzip the "109738320_HMI_FU_CODE_v13.zip" file.
2.	Start TIA Portal.
3.	Unzip the "FrequencyConverter.zap13" project.
4.	Download the SIMATIC WinCC project to your PC station.
5.	Download the SIMATIC Startdrive project to your frequency converter.

### 6.2 Using the sample project

Figure 6-1

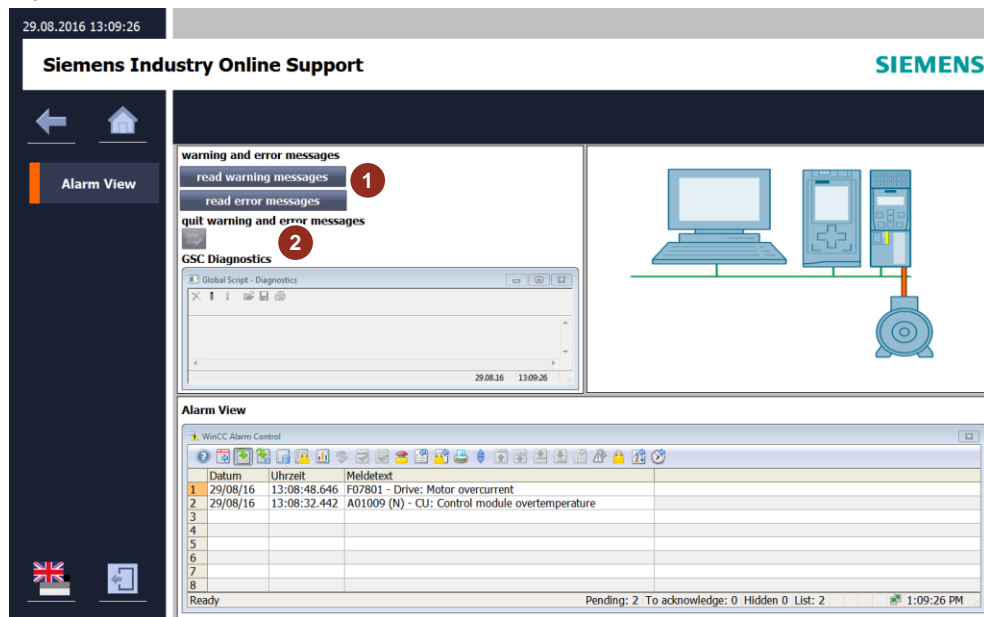


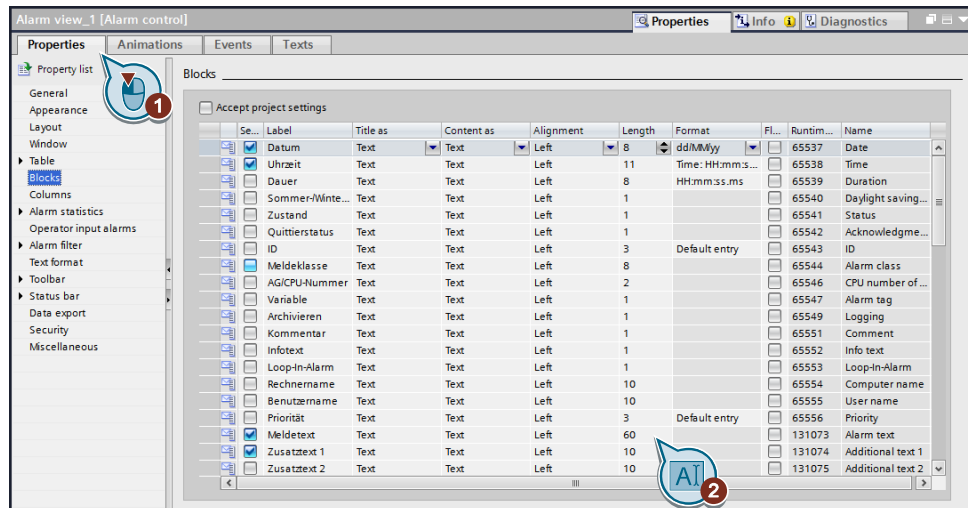
Table 6-2

No.	Action
1.	Two buttons allow you to read the warning and error message.
2.	As soon as the faults have been set to outgoing in the drive, they can be acknowledged using the button.

## 7 Further Notes, Tips and Tricks, etc.

### 7.1 Resizing the alarm text in the Alarm Control

In order to fully display the alarm text in the alarm view, resize the alarm text: In the control, go to Properties --> Blocks. Resize the alarm text length.



### 7.2 Drive blocks

To control the drive for speed input or positioning, you can use the technology object or the DriveLib library.

For more information, please refer to Entry ID [109475044](#) and Entry ID [78788716](#).

## 8 Links & Literature

Table 8-1

	Topic
\1\	Siemens Industry Online Support <a href="https://support.industry.siemens.com">https://support.industry.siemens.com</a>
\2\	Download page of the entry <a href="https://support.industry.siemens.com/cs/ww/en/view/109738320">https://support.industry.siemens.com/cs/ww/en/view/109738320</a>
\3\	XML Parser <a href="https://support.industry.siemens.com/cs/ww/en/view/77467239">https://support.industry.siemens.com/cs/ww/en/view/77467239</a>

## 9 History

Table 9-1

Version	Date	Modifications
V1.0	09/2016	First version