# SIEMENS

# SINUMERIK

# SINUMERIK 840D sl/828D Milling

**Operating Manual** 

Valid for:	
SINUMERIK 828D with CNC system software Version 4.3	\$

CNC software for 840D sl/ 840DE sl Version 2.6 SP1 SINUMERIK Operate Version 2.6 SP1 for PCU/PC

#### Preface

Introduction	1
Setting up the machine	2
Execution in manual mode	3
Machining the workpiece	4
Simulating machining	5
Creating G code program	6
Creating a ShopMill program	7
Programming technological functions (cycles)	8
Multi-channel view	9
User variables	10
Teaching in a program	11
Tool management	12
Program management	13
Setting up drives	14
HT 8	15
Easy Message (828D only)	16
Easy Extend (828D only)	17
Service Planner (828D only)	18
Ladder Viewer and Ladder add-on (828D only)	19
Alarms, error messages, and system alarms	20
Appendix	Α

#### Legal information

#### Warning notice system

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

#### 

indicates that death or severe personal injury will result if proper precautions are not taken.

#### 

indicates that death or severe personal injury may result if proper precautions are not taken.

#### 

with a safety alert symbol, indicates that minor personal injury can result if proper precautions are not taken.

#### CAUTION

without a safety alert symbol, indicates that property damage can result if proper precautions are not taken.

#### NOTICE

indicates that an unintended result or situation can occur if the corresponding information is not taken into account.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

#### **Qualified Personnel**

The product/system described in this documentation may be operated only by **personnel qualified** for the specific task in accordance with the relevant documentation for the specific task, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

#### Proper use of Siemens products

Note the following:

#### 

Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be adhered to. The information in the relevant documentation must be observed.

#### Trademarks

All names identified by ® are registered trademarks of the Siemens AG. The remaining trademarks in this publication may be trademarks whose use by third parties for their own purposes could violate the rights of the owner.

#### **Disclaimer of Liability**

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

# Preface

#### Structure of the documentation

The SINUMERIK documentation is organized in three parts:

- General documentation
- User documentation
- Manufacturer/service documentation

Information on the following topics is available at http://www.siemens.com/motioncontrol/docu:

Ordering documentation

Here you can find an up-to-date overview of publications.

Downloading documentation

Links to more information for downloading files from Service & Support.

Researching documentation online

Information on DOConCD and direct access to the publications in DOConWEB.

• Compiling individual documentation on the basis of Siemens contents with the My Documentation Manager (MDM), refer to http://www.siemens.com/mdm.

My Documentation Manager provides you with a range of features for generating your own machine documentation.

• Training and FAQs

Information on our range of training courses and FAQs (frequently asked questions) is available via the page navigation.

#### Target group

This documentation is intended for users of milling machines running the SINUMERIK Operate software.

#### **Benefits**

The operating manual familiarizes users with the operator controls and operating commands. It instructs users on how to respond to faults and take corrective action.

#### Standard scope

This documentation only describes the functionality of the standard version. Extensions or changes made by the machine tool manufacturer are documented by the machine tool manufacturer.

Other functions not described in this documentation might be executable in the control. However, no claim can be made regarding the availability of these functions when the equipment is first supplied or in the event of servicing.

For the sake of simplicity, this documentation does not contain all detailed information about all types of the product and cannot cover every conceivable case of installation, operation, or maintenance.

#### Terms

The meanings of some basic terms used in this documentation are given below:

• Program

A program is a sequence of instructions to the CNC which combine to produce a specific workpiece on the machine.

Contour

The term contour refers generally to the outline of a workpiece. More specifically, it refers to the section of the program that defines the outline of a workpiece comprising individual elements.

Cycle

A cycle, e.g. milling a rectangular pocket, is a subprogram defined in SINUMERIK Operate for executing a frequently repeated machining operation.

#### **Technical Support**

If you have any technical questions, please contact our hotline:

	Europe/Africa	
Telephone	+49 911 895 7222	
Fax	+49 911 895 7223	
0.14 €/min from	0.14 €/min from a German landline; cell phone charges may vary.	
Internet	http://www.siemens.com/automation/support-request	

	Americas
Telephone	+1 423 262 2522
Fax	+1 423 262 2200
E-mail	mailto:techsupport.sea@siemens.com

	Asia/Pacific
Telephone	+86 1064 757575
Fax	+86 1064 747474
E-mail	mailto:support.asia.automation@siemens.com

#### Note

Country-specific telephone numbers for technical support are provided under the following Internet address:

http://www.automation.siemens.com/partner

#### Questions about the manual

If you have any queries (suggestions, corrections) in relation to this documentation, please fax or e-mail us:

Fax	+49 9131- 98 2176
E-mail	mailto:docu.motioncontrol@siemens.com

A fax form is available in the appendix of this document.

#### Internet address

http://www.siemens.com/motioncontrol

Preface

# Table of contents

	Preface		
1	Introdu	ction	
	1.1	Product overview	17
	1.2	Operator panel fronts	
	1.2.1	Overview	
	1.2.2	Keys of the operator panel	
	1.3	Machine control panels	27
	1.3.1	Overview	
	1.3.2	Controls on the machine control panel	27
	1.4	User interface	
	1.4.1	Screen layout	
	1.4.2	Status display	
	1.4.3	Actual value window	
	1.4.4	T,F,S window	
	1.4.5	Current block display	
	1.4.6 1.4.7	Operation via softkeys and buttons	
	1.4.7	Entering or selecting parameters Pocket calculator	
	1.4.0	Context menu	
	1.4.10	Touch operation	
	1.4.11	Changing the user interface language	
	1.4.12	Entering Asian characters	
	1.4.13	Protection levels	46
	1.4.14	Online help in SINUMERIK Operate	48
2	Setting	up the machine	51
	2.1	Switching on and switching off	51
	2.2	Approaching a reference point	
	2.2.1	Referencing axes	
	2.2.2	User agreement	53
	2.3	Operating modes	
	2.3.1	General	
	2.3.2	Modes groups and channels	
	2.3.3	Channel switchover	57
	2.4	Settings for the machine	59
	2.4.1	Switching over the coordinate system (MCS/WCS)	
	2.4.2	Switching the unit of measurement	59
	2.4.3	Setting the work offset	60
	2.5	Measuring the tool	63
	2.5.1	Measuring a tool manually	
	2.5.2	Measuring the tool length with the workpiece as reference point	
	2.5.3	Measuring radius or diameter	
	2.5.4	Fixed point calibration	
	2.5.5	Measuring a tool with an electrical tool probe	66

2.5.6	Calibrating the electrical tool probe	
2.6 2.6.1 2.6.2 2.6.3 2.6.4 2.6.5 2.6.6 2.6.7 2.6.8 2.6.9 2.6.10 2.6.11 2.6.12	Measuring the workpiece zero Overview Sequence of operations Examples with manual swivel Calibrating the electronic workpiece probe Setting the edge Edge measurement Measuring a corner Measuring a pocket and hole Measuring a spigot Aligning the plane Defining the measurement function selection Corrections after measurement of the zero point	
2.7 2.7.1 2.7.2 2.7.3 2.7.4 2.7.5 2.7.6 2.7.7	Work offsets Display active zero offset Displaying the work offset "overview" Displaying and editing base zero offset Displaying and editing settable zero offset Displaying the zero offset details. Deleting a work offset Measuring the workpiece zero	
2.8 2.8.1 2.8.2	Monitoring axis and spindle data Specify working area limitations Editing spindle data	109
2.9	Displaying setting data lists	111
2.10	Handwheel assignment	112
2.11 2.11.1 2.11.2 2.11.3 2.11.4	MDA Loading an MDA program from the Program Manager Saving an MDA program Executing an MDA program Deleting an MDA program	
Execution	on in manual mode	117
3.1	General	117
3.2 3.2.1 3.2.2 3.2.3 3.2.4	Selecting a tool and spindle T, S, M windows Selecting a tool Starting and stopping a spindle manually Position spindle	
3.3 3.3.1 3.3.2	Traversing axes Traverse axes by a defined increment Traversing axes by a variable increment	122
3.4	Positioning axes	125
3.5	Swiveling	126
3.6	Simple face milling of workpiece	131
3.7	Default settings for manual mode	134

3

4	Machini	ing the workpiece	135
	4.1	Starting and stopping machining	135
	4.2	Selecting a program	
	4.3	Testing a program	
	4.4 4.4.1 4.4.2 4.4.3	Displaying the current program block Current block display Displaying a basic block Display program level	140 140
	4.5	Correcting a program	143
	4.6	Repositioning axes	145
	4.7 4.7.1 4.7.2 4.7.3 4.7.4 4.7.5 4.7.6 4.7.7	Starting machining at a specific point Use block search Continuing program from search target Simple search target definition Defining an interruption point as search target Entering the search target via search pointer Parameters for block search in the search pointer Block search mode	
	4.8 4.8.1 4.8.2	Intervening in the program sequence Program control Skip blocks	154
	4.9	Overstore	
	4.10 4.10.1 4.10.2 4.10.3 4.10.4 4.10.5 4.10.6	Editing a program Searching in programs Replacing program text Copying/pasting/deleting a program block Renumber program Opening a second program Editor settings	
	4.11 4.11.1 4.11.2 4.11.3	Displaying G Functions and Auxiliary Functions Selected G functions All G functions Auxiliary functions	168 170 171
	4.12	Displaying the program runtime and counting workpieces	
	4.13	Setting for automatic mode	
5		ting machining	
	5.1	Overview	
	5.2	Simulation before machining of the workpiece	
	5.3	Simultaneous recording before machining of the workpiece	
	5.4	Simultaneous recording during machining of the workpiece	
	5.5 5.5.1 5.5.2 5.5.3	Different views of a workpiece Plan view 3D view Side views	
	5.6	Editing the simulation display	

	5.6.1 5.6.2	Entering blank details Showing and hiding the tool path	
	5.7 5.7.1	Program control during the simulation Changing the feedrate	193 193
	5.7.2	Simulating the program block by block	194
	5.8 5.8.1 5.8.2	Changing and adapting a simulation graphic Enlarging or reducing the graphical representation Panning a graphical representation	195
	5.8.3 5.8.4 5.8.5	Rotating the graphical representation Modifying the viewport Defining cutting planes	196 197
	5.9	Displaying simulation alarms	199
6	Creating	g G code program	201
	6.1	Graphical programming	201
	6.2	Program views	202
	6.3	Program structure	205
	6.4 6.4.1	Basics Machining planes	206
	6.4.2	Current planes in cycles and input screens	
	6.4.3	Programming a tool (T)	207
	6.5	Generating a G code program	208
	6.6	Blank input	210
	6.7	Machining plane, milling direction, retraction plane, safe clearance and feedrate (PL, RP, SC, F)	212
	6.7 6.8		
	6.8 6.9	SC, F) Selection of the cycles via softkey Calling technology functions	213 218
	6.8 6.9 6.9.1	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters	213 218 218
	6.8 6.9 6.9.1 6.9.2	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters Setting data for cycles	213 218 218 218
	6.8 6.9 6.9.1	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters	213 218 218 218 218 218
	6.8 6.9 6.9.1 6.9.2 6.9.3	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters Setting data for cycles Checking cycle parameters	213 218 218 218 218 219
	6.8 6.9 6.9.1 6.9.2 6.9.3 6.9.4	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters Setting data for cycles Checking cycle parameters Changing a cycle call	213 218 218 218 218 219 220
7	6.8 6.9.1 6.9.2 6.9.3 6.9.4 6.9.5 6.10	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters. Setting data for cycles. Checking cycle parameters. Changing a cycle call Additional functions in the input screens.	213 218 218 218 218 219 220 221
7	6.8 6.9.1 6.9.2 6.9.3 6.9.4 6.9.5 6.10	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters Setting data for cycles Checking cycle parameters Changing a cycle call Additional functions in the input screens Measuring cycle support	213 218 218 218 218 219 220 221 <b>223</b>
7	6.8 6.9.1 6.9.2 6.9.3 6.9.4 6.9.5 6.10 <b>Creating</b>	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters. Setting data for cycles. Checking cycle parameters. Changing a cycle call Additional functions in the input screens. Measuring cycle support a ShopMill program	213 218 218 218 218 219 220 221 223 224
7	6.8 6.9 6.9.1 6.9.2 6.9.3 6.9.4 6.9.5 6.10 <b>Creating</b> 7.1	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters Setting data for cycles Checking cycle parameters Changing a cycle call Additional functions in the input screens Measuring cycle support <b>a ShopMill program</b> Program views Program structure Basic information	213 218 218 218 219 220 221 223 224 228 229
7	<ul> <li>6.8</li> <li>6.9</li> <li>6.9.1</li> <li>6.9.2</li> <li>6.9.3</li> <li>6.9.4</li> <li>6.9.5</li> <li>6.10</li> <li>Creating</li> <li>7.1</li> <li>7.2</li> <li>7.3</li> <li>7.3.1</li> </ul>	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters. Setting data for cycles. Checking cycle parameters. Changing a cycle call Additional functions in the input screens. Measuring cycle support <b>a ShopMill program</b> Program views Program structure Basic information Machining planes	213 218 218 218 219 220 221 223 224 228 229 229 229
7	6.8 6.9 6.9.1 6.9.2 6.9.3 6.9.4 6.9.5 6.10 <b>Creating</b> 7.1 7.2 7.3 7.3.1 7.3.2	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters. Setting data for cycles. Checking cycle parameters. Changing a cycle call Additional functions in the input screens. Measuring cycle support <b>a ShopMill program</b> Program views Program structure Basic information. Machining planes Polar coordinates	213 218 218 218 219 220 221 223 224 228 229 229 229 229
7	6.8 6.9.1 6.9.2 6.9.3 6.9.4 6.9.5 6.10 <b>Creating</b> 7.1 7.2 7.3 7.3.1 7.3.2 7.3.3	SC, F)Selection of the cycles via softkey Calling technology functions	213 218 218 218 219 220 221 223 223 228 229 229 229 229 229 230
7	<ul> <li>6.8</li> <li>6.9</li> <li>6.9.1</li> <li>6.9.2</li> <li>6.9.3</li> <li>6.9.4</li> <li>6.9.5</li> <li>6.10</li> <li>Creating</li> <li>7.1</li> <li>7.2</li> <li>7.3</li> <li>7.3.1</li> <li>7.3.2</li> <li>7.3.3</li> <li>7.4</li> </ul>	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters. Setting data for cycles. Checking cycle parameters. Changing a cycle call Additional functions in the input screens. Measuring cycle support <b>Ja ShopMill program</b> Program views Program structure Basic information. Machining planes Polar coordinates Absolute and incremental dimensions Creating a ShopMill program	213 218 218 218 219 220 221 221 223 224 228 229 229 229 232
7	<ul> <li>6.8</li> <li>6.9</li> <li>6.9.1</li> <li>6.9.2</li> <li>6.9.3</li> <li>6.9.4</li> <li>6.9.5</li> <li>6.10</li> <li>Creating</li> <li>7.1</li> <li>7.2</li> <li>7.3</li> <li>7.3.1</li> <li>7.3.2</li> <li>7.3.3</li> <li>7.4</li> <li>7.5</li> </ul>	SC, F)	213 218 218 218 219 220 220 221 223 224 228 229 229 229 229 230 232
7	<ul> <li>6.8</li> <li>6.9</li> <li>6.9.1</li> <li>6.9.2</li> <li>6.9.3</li> <li>6.9.4</li> <li>6.9.5</li> <li>6.10</li> <li>Creating</li> <li>7.1</li> <li>7.2</li> <li>7.3</li> <li>7.3.1</li> <li>7.3.2</li> <li>7.3.3</li> <li>7.4</li> </ul>	SC, F) Selection of the cycles via softkey Calling technology functions Hiding cycle parameters. Setting data for cycles. Checking cycle parameters. Changing a cycle call Additional functions in the input screens. Measuring cycle support <b>Ja ShopMill program</b> Program views Program structure Basic information. Machining planes Polar coordinates Absolute and incremental dimensions Creating a ShopMill program	213 218 218 218 219 220 221 221 223 228 229 229 229 229 230 233 235

7.8	Defining machine functions	238
7.9	Call work offsets	240
7.10	Repeating program blocks	241
7.11	Specifying the number of workpieces	243
7.12	Changing program blocks	244
7.13	Changing program settings	
7.14	Selection of the cycles via softkey	
7.15	Calling technology functions	
7.15.1	Additional functions in the input screens	
7.15.2	Checking input parameters	
7.15.3	Setting data for technological functions	
7.15.4	Changing a cycle call	
7.16	Measuring cycle support	253
7.17	Example, standard machining	
7.17.1	Workpiece drawing	
7.17.2	Programming	
7.17.3	Results/simulation test	
7.17.4	G code machining program	
Prograr	nming technological functions (cycles)	273
8.1	Drilling	273
8.1.1	General	
8.1.2	Centering (CYCLE81)	
8.1.3	Drilling (CYCLE82)	
8.1.4	Reaming (CYCLE85)	
8.1.5	Deep-hole drilling (CYCLE83)	
8.1.6	Boring (CYCLE86)	
8.1.7	Tapping (CYCLE84, 840)	
8.1.8	Drill and thread milling (CYCLE78)	
8.1.9	Positioning and position patterns.	
8.1.10	Arbitrary positions (CYCLE802)	
8.1.11	Position pattern Line (HOLES1), Grid or Frame (CYCLE801)	
8.1.12	Circle position pattern (HOLES2)	
8.1.13	Repeating positions	
8.2	Milling	
8.2.1	Face milling (CYCLE61)	
8.2.2	Rectangular pocket (POCKET3)	
8.2.3	Circular pocket (POCKET4)	
8.2.4	Rectangular spigot (CYCLE76)	
8.2.5	Circular spigot (CYCLE77)	
8.2.6	Multi-edge (CYCLE79)	
8.2.7	Longitudinal groove (SLOT1)	
8.2.8	Circumferential groove (SLOT2)	
8.2.9	Open groove (CYCLE899)	
8.2.10	Long hole (LONGHOLE) - only for G code programs	
8.2.11	Thread milling (CYCLE70)	
8.2.12	Engraving (CYCLE60)	
8.3	Contour milling	
8.3.1	General	

8

8.3.2 8.3.3 8.3.4 8.3.5 8.3.6 8.3.7 8.3.8 8.3.9 8.3.10 8.3.11 8.3.12 8.3.13	Representation of the contour Creating a new contour Creating contour elements. Changing the contour. Contour call (CYCLE62) - only for G code program. Path milling (CYCLE72). Contour pocket/contour spigot (CYCLE63/64). Predrilling contour pocket (CYCLE64). Milling contour pocket (CYCLE63). Residual material contour pocket (CYCLE63). Residual material contour spigot (CYCLE63).	340 342 347 348 349 353 354 357 360 362
8.4 8.4.1 8.4.2 8.4.3 8.4.4 8.4.5 8.4.6 8.4.7 8.4.8	Turning - only for G code programs General Stock removal (CYCLE951) Groove (CYCLE930) Undercut form E and F (CYCLE940) Thread undercut (CYCLE940) Thread turning (CYCLE940) Thread turning (CYCLE99) Thread chain (CYCLE98) Cut-off (CYCLE92)	366 369 371 373 376 384 387
8.5 8.5.1 8.5.2 8.5.3 8.5.4 8.5.5 8.5.6 8.5.7 8.5.8 8.5.9 8.5.10 8.5.11 8.5.12	Contour turning - only for G code programs General information. Representation of the contour. Creating a new contour Creating contour elements Changing the contour. Contour call (CYCLE62). Stock removal (CYCLE952). Stock removal residual (CYCLE952). Grooving (CYCLE952). Grooving residual material (CYCLE952). Plunge turning (CYCLE952).	389 390 391 392 398 399 400 405 407 409 411 414
8.6 8.6.1 8.6.2 8.6.2.1 8.6.2.2 8.6.3 8.6.4	Further cycles and functions Swiveling plane/tool (CYCLE800) Swiveling tool (CYCLE800) Swiveling tool/preloading milling tools - only for G code program (CYCLE800) Swiveling tool/orienting milling tools - only for G code program (CYCLE800) High-speed settings (CYCLE832) Subroutines	416 424 424 425 426
8.7 8.7.1 8.7.2 8.7.3 8.7.4 8.7.5 8.7.6 8.7.6 8.7.7 8.7.8 8.7.9 8.7.10 8.7.11	Further cycles and functions ShopMill Transformations Translation Rotation Scaling Mirroring Straight or circular machining Programming a straight line Programming a circle with known center point Programming a circle with known radius Helix Polar coordinates	430 431 432 433 433 433 434 436 437 438 439

	8.7.12 8.7.13 8.7.14	Straight polar Circle polar Obstacle	442
9	Multi-ch	annel view	
	9.1	Multi-channel view	445
	9.2	Multi-channel view in the "Machine" operating area	446
	9.3	Setting the multi-channel view	449
10	User va	riables	451
	10.1	Overview	451
	10.2	R parameters	452
	10.3	Global GUD	453
	10.4	Channel GUD	455
	10.5	Local LUD	456
	10.6	Program PUD	457
	10.7	Searching for user data	458
	10.8	Defining and activating user variables	459
11	Teachin	ng in a program	461
	11.1	Overview	461
	11.2	General sequence	462
	11.3 11.3.1	Inserting a block Input parameters for teach-in blocks	
	11.4 11.4.1 11.4.2 11.4.3 11.4.4 11.4.5	Teach-in via window General Teach in rapid traverse G0 Teach in straight G1 Teaching in circle intermediate and circle end point CIP Teach-in A spline	
	11.5	Editing a block	
	11.6	Selecting a block	
	11.7	Deleting a block	
12		anagement	
	12.1	Lists for the tool management	
	12.2	Magazine management	
	12.3	Tool types	476
	12.4	Tool dimensioning	
	12.5 12.5.1 12.5.2 12.5.3 12.5.4 12.5.5	Tool list Additional data Creating a new tool Measuring the tool Managing several cutting edges Delete tool	
	12.0.0		

	12.5.6 12.5.7	Loading and unloading tools Selecting a magazine	
	12.6 12.6.1	Tool wear Reactivating a tool	
	12.7	Tool data OEM	
	12.8 12.8.1 12.8.2	Magazine Positioning a magazine Relocating a tool	501
	12.9	Sorting tool management lists	504
	12.10	Filtering the tool management lists	505
	12.11	Specific search in the tool management lists	506
	12.12	Displaying tool details	
	12.13	Changing a tool type	
13	Program	n management	
	13.1 13.1.1 13.1.2 13.1.3	Overview NC memory Local drive USB drives	514 514
	13.2	Opening and closing the program	
	13.3	Executing a program	
	13.4 13.4.1 13.4.2 13.4.3 13.4.4 13.4.5 13.4.6 13.4.7	Creating a directory/program/job list/program list Creating a new directory Creating a new workpiece Creating a new G code program Creating a new ShopMill program Storing any new file. Creating a Joblist Creating a program list	
	13.5	Creating templates	
	13.6	Displaying the program in the Preview.	
	13.7	Selecting several directories/programs	531
	13.8	Copying and pasting a directory/program	533
	13.9 13.9.1	Deleting a program/directory Deleting a program/directory	
	13.10	Renaming file and directory properties	536
	13.11	EXTCALL	
	13.12 13.12.1 13.12.2 13.12.3	Backing up data Generating an archive in the Program Manager Generating the archive via series startup Reading in an archive	
	13.13 13.13.1 13.13.2	Setup data Backing up setup data Reading-in set-up data	

	13.14 13.14.1 13.14.2	V24 Reading-in and reading-out archives Setting V24 in the program manager	548
14	Setting ι	up drives	
	14.1	Overview	553
	14.2	Setting up drives	554
15	HT 8		557
	15.1	HT 8 overview	557
	15.2	Traversing keys	560
	15.3	Machine control panel menu	561
	15.4	Virtual keyboard	563
	15.5	Calibrating the touch panel	565
16	Easy Me	essage (828D only)	567
	16.1	Overview	567
	16.2	Activating Easy Message	569
	16.3	Creating/editing a user profile	570
	16.4	Setting-up events	572
	16.5	Logging an active user on and off	574
	16.6	Displaying SMS logs	575
	16.7	Making settings for Easy Message	576
17	Easy Ex	tend (828D only)	577
	17.1	Overview	577
	17.2	Enabling a device	578
	17.3	Activating and deactivating a device	579
	17.4	Commissioning Easy Extend	580
18	Service	Planner (828D only)	581
	18.1	Performing and monitoring maintenance tasks	581
	18.2	Set maintenance tasks	583
19	Ladder \	/iewer and Ladder add-on (828D only)	585
	19.1	PLC diagnostics	585
	19.2	Structure of the user interface	586
	19.3	Control options	588
	19.4	Displaying PLC properties	590
	19.5	Displaying and editing NC/PLC variables	591
	19.6	Displaying and editing PLC signals	592
	19.7	Displaying information on the program blocks	593
	19.8	Downloading a PLC user program	595

19.10       Creating a new block		19.9	Editing the local variable table	596
19.12       Inserting and editing networks       600         19.13       Editing network properties       602         19.14       Displaying and editing symbol tables       603         19.15       Inserting/deleting a symbol table       604         19.16       Searching for operands       605         19.17       Displaying the network symbol information table       607         19.18       Displaying/canceling the access protection       608         19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying alarms       611         20.2       Displaying an editing PLC and NC variables       615         20.3       Displaying messages       614         20.4       PLC and NC variables       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms       618         20.4.3       Loading PLC symbols       619         20.5       Version       621         20.5.1       Displaying and editing the logbook       624         20.5.1       Displaying and editing the logbook       624         20.5.2       S		19.10	Creating a new block	
19.13       Editing network properties.       602         19.14       Displaying and editing symbol tables.       603         19.15       Inserting/deleting a symbol table       604         19.15       Inserting/deleting a symbol table       604         19.16       Searching for operands.       605         19.17       Displaying the network symbol information table       607         19.18       Displaying/canceling the access protection       608         19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying an alarm log       613         20.2       Displaying an alarm log       613         20.3       Displaying and editing PLC and NC variables       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms       614         20.5       Version       621         20.5.1       Displaying version data       622         20.6       Logbook       624         20.5.1       Displaying and editing the logbook       624         20.5.2       Save information       625         20.5       Version		19.11	Editing block properties	599
19.14       Displaying and editing symbol tables       603         19.15       Inserting/deleting a symbol table       604         19.16       Searching for operands       605         19.17       Displaying the network symbol information table       607         19.18       Displaying/canceling the access protection       608         19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying alarms       611         20.2       Displaying an alarm log       613         20.3       Displaying messages       614         20.4       PLC and NC variables       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms       618         20.4.3       Loading PLC symbols       619         20.5       Version       622         20.6       Logbook       624         20.6.1       Logbook       624         20.6.2       Making/searching for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics       628         20.8.1		19.12	Inserting and editing networks	600
19.15       Inserting/deleting a symbol table       604         19.16       Searching for operands.       605         19.17       Displaying the network symbol information table       607         19.18       Displaying/canceling the access protection       608         19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying alarms       611         20.2       Displaying an alarm log.       613         20.3       Displaying messages       614         20.4       PLC and NC variables       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms.       618         20.4.3       Loading PLC symbols       619         20.5       Version       621         20.5.1       Displaying version data       622         20.6       Logbook       624         20.6.1       Displaying for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics       628         20.8.1       Setting remote access       628         20.8.2<		19.13	Editing network properties	
19.16Searching for operands.60519.17Displaying the network symbol information table.60719.18Displaying/canceling the access protection60819.19Displaying cross references60920Alarms, error messages, and system alarms.61120.1Displaying alarms61120.2Displaying an alarm log.61320.3Displaying messages61420.4PLC and NC variables.61520.4.1Displaying and editing PLC and NC variables61520.4.2Saving and loading screen forms.61820.4.3Loading PLC symbols61920.5Version62120.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry.62520.7Creating screenshots62720.8Remote diagnostics.62820.8.1Setting remote access.62820.8.2Permit modem.63020.8.3Request remote diagnostics.63120.8.4Exit remote diagnostics.63320.8.4Exit remote diagnostics.63320.8.4Exit remote diagnostics.63320.8.4Exit remote diagnostics.63320.8.4Exit remote diagnostics.63320.8.4Exit remote diagnostics.63320.8.4Exit rem		19.14	Displaying and editing symbol tables	603
19.17       Displaying the network symbol information table.       607         19.18       Displaying/canceling the access protection       608         19.19       Displaying cross references.       609         20       Alarms, error messages, and system alarms.       611         20.1       Displaying alarms       611         20.2       Displaying alarms       613         20.3       Displaying messages       614         20.4       PLC and NC variables.       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms.       618         20.4.3       Loading PLC symbols       619         20.5       Version       621         20.5.1       Displaying version data       622         20.6       Logbook.       624         20.6.2       Making/searching for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics.       628         20.8.1       Setting remote access       628         20.8.1       Setting remote access       628         20.8.1       Setting remote access       628         20.8.1		19.15	Inserting/deleting a symbol table	
19.18       Displaying/canceling the access protection       608         19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying alarms       611         20.2       Displaying an alarm log       613         20.3       Displaying messages       614         20.4       Displaying messages       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms       618         20.4.3       Loading PLC symbols       619         20.5       Version       621         20.5.1       Displaying version data       621         20.5.2       Save information       622         20.6       Logbook       624         20.6.1       Displaying and editing the logbook       624         20.6.2       Making/searching for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics       630         20.8.1       Setting remote access       628         20.8.2       Permit modem       630         20.8.3       Request remote diagn		19.16	Searching for operands	
19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying alarms       611         20.2       Displaying an alarm log       613         20.3       Displaying messages       614         20.4       PLC and NC variables       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms       618         20.4.3       Loading PLC symbols       619         20.5       Version       621         20.5.1       Displaying and editing the logbook       622         20.6       Logbook       624         20.6.2       Making/searching for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics       628         20.8.1       Setting remote access       628         20.8.2       Permit modem       630         20.8.3       Request remote diagnostics       631         20.8.4       Exit remote diagnostics       631         20.8.3       Request remote diagnostics       631         20.8.4       Exit remote diagnostics<		19.17	Displaying the network symbol information table	
19.19       Displaying cross references       609         20       Alarms, error messages, and system alarms       611         20.1       Displaying alarms       611         20.2       Displaying an alarm log       613         20.3       Displaying messages       614         20.4       PLC and NC variables       615         20.4.1       Displaying and editing PLC and NC variables       615         20.4.2       Saving and loading screen forms       618         20.4.3       Loading PLC symbols       619         20.5       Version       621         20.5.1       Displaying and editing the logbook       622         20.6       Logbook       624         20.6.2       Making/searching for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics       628         20.8.1       Setting remote access       628         20.8.2       Permit modem       630         20.8.3       Request remote diagnostics       631         20.8.4       Exit remote diagnostics       631         20.8.3       Request remote diagnostics       631         20.8.4       Exit remote diagnostics<		19.18	Displaying/canceling the access protection	
20Alarms, error messages, and system alarms61120.1Displaying alarms61120.2Displaying an alarm log61320.3Displaying messages61420.4PLC and NC variables61520.4.1Displaying and editing PLC and NC variables61520.4.2Saving and loading screen forms61820.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics63120.8.4Exit remote diagnostics63320.8.4Exit remote diagnostics63320.8.4Appendix633A.1Feedback on the documentation633A.2Overview635		19.19		
20.1Displaying alarms61120.2Displaying an alarm log61320.3Displaying messages61420.4PLC and NC variables61520.4.1Displaying and editing PLC and NC variables61520.4.2Saving and loading screen forms61820.4.3Loading PLC symbols61920.5Version62120.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics63120.8.4Exit remote diagnostics63320.8.4Exit remote diagnostics63520.8.5Exit remote d	20	Alarms,		
20.2Displaying an alarm log	_			
20.3Displaying messages61420.4PLC and NC variables61520.4.1Displaying and editing PLC and NC variables61520.4.2Saving and loading screen forms61820.4.3Loading PLC symbols61920.5Version62120.5.1Displaying version data62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics631AAppendix633A.1Feedback on the documentation633A.2Overview635				
20.4PLC and NC variables61520.4.1Displaying and editing PLC and NC variables61520.4.2Saving and loading screen forms61820.4.3Loading PLC symbols61920.5Version62120.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics631AAppendix633A.1Feedback on the documentation633A.2Overview635		-		
20.4.1Displaying and editing PLC and NC variables61520.4.2Saving and loading screen forms61820.4.3Loading PLC symbols61920.5Version62120.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics633AAppendix633A.1Feedback on the documentation633A.1Feedback on the documentation635				
20.4.2Saving and loading screen forms.61820.4.3Loading PLC symbols61920.5Version62120.5.1Displaying version data62120.5.2Save information62220.6Logbook.62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics.62820.8.1Setting remote access.62820.8.2Permit modem63020.8.3Request remote diagnostics.63020.8.4Exit remote diagnostics631AAppendix.633A.1Feedback on the documentation633A.2Overview635		-		
20.5Version62120.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics631AAppendix633A.1Feedback on the documentation633A.2Overview635			Saving and loading screen forms	
20.5.1Displaying version data62120.5.2Save information62220.6Logbook62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics631AAppendix633A.1Feedback on the documentation633A.2Overview635				
20.5.2Save information62220.6Logbook.62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics.62820.8.1Setting remote access.62820.8.2Permit modem63020.8.3Request remote diagnostics.631AAppendix.633A.1Feedback on the documentation.633A.2Overview635				
20.6Logbook.62420.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics.62820.8.1Setting remote access.62820.8.2Permit modem63020.8.3Request remote diagnostics631AAppendix.633A.1Feedback on the documentation633A.2Overview635				
20.6.1Displaying and editing the logbook62420.6.2Making/searching for a logbook entry62520.7Creating screenshots62720.8Remote diagnostics62820.8.1Setting remote access62820.8.2Permit modem63020.8.3Request remote diagnostics63120.8.4Exit remote diagnostics633AAppendix633A.1Feedback on the documentation633A.2Overview635				
20.6.2       Making/searching for a logbook entry       625         20.7       Creating screenshots       627         20.8       Remote diagnostics       628         20.8.1       Setting remote access       628         20.8.2       Permit modem       630         20.8.3       Request remote diagnostics       630         20.8.4       Exit remote diagnostics       631         A       Appendix       633         A.1       Feedback on the documentation       633         A.2       Overview       635				
20.8       Remote diagnostics				
20.8.1       Setting remote access		20.7	Creating screenshots	
20.8.1       Setting remote access		20.8	Remote diagnostics.	
20.8.3       Request remote diagnostics			•	
20.8.4       Exit remote diagnostics       631         A       Appendix       633         A.1       Feedback on the documentation       633         A.2       Overview       635				
A       Appendix				
A.1Feedback on the documentation		20.8.4	Exit remote diagnostics	
A.2 Overview	Α	Append	lix	
		A.1	Feedback on the documentation	633
Index		A.2	Overview	635
		Index		

### 1.1 Product overview

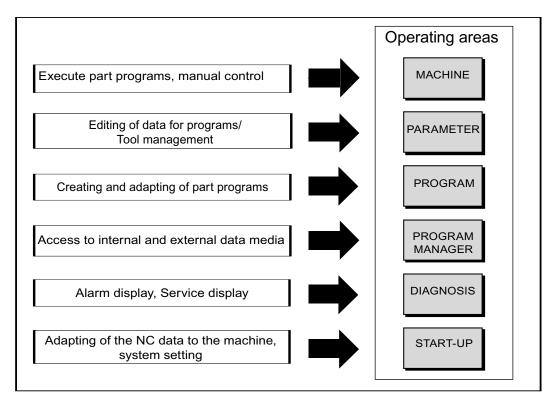
The SINUMERIK controller is a CNC (Computerized Numerical Controller) for machine tools. You can use the CNC to implement the following basic functions in conjunction with a machine tool:

- Creation and adaptation of part programs
- Execution of part programs
- Manual control
- Access to internal and external data media
- Editing of data for programs
- Management of tools, zero points and further user data required in programs
- Diagnostics of controller and machine

1.1 Product overview

#### **Operating areas**

The basic functions are grouped in the following operating areas in the controller:



# 1.2 Operator panel fronts

#### 1.2.1 Overview

#### Introduction

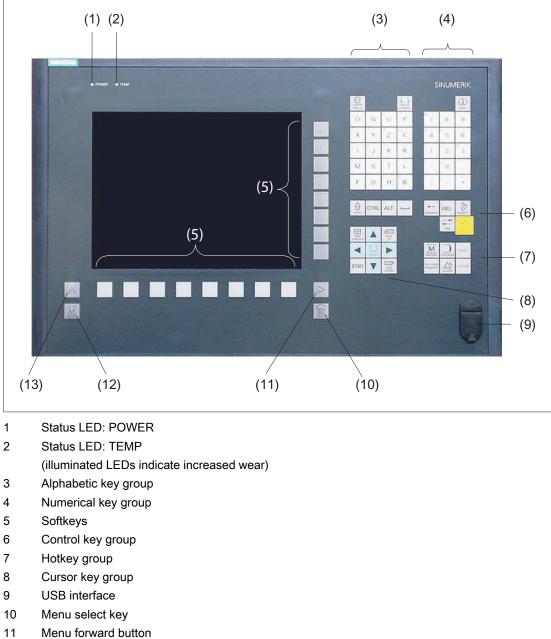
The display (screen) and operation (e.g. hardkeys and softkeys) of the SINUMERIK Operate user interface use the operator panel front.

In this example, the OP 010 operator panel front is used to illustrate the components that are available for operating the controller and machine tool.

Introduction

1.2 Operator panel fronts

#### Operator controls and indicators



- 12 Machine area button
- 13 Menu back key

Figure 1-1 View of OP 010 operator panel front

#### References

A more precise description as well as a view of the other operator panel fronts that can be used may be found in the following reference:

Operator Components and Networking Manual; SINUMERIK 840D sl/840Di sl

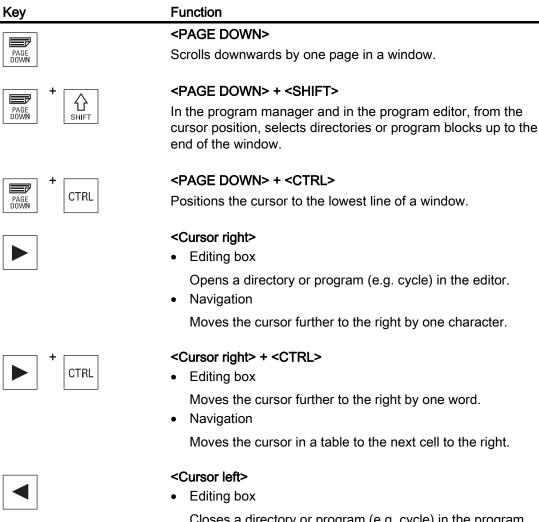
#### 1.2.2 Keys of the operator panel

The following keys and key combinations are available for operation of the control and the machine tool.

#### Keys and key combinations

Key	Function
ALARM CANCEL	<b>ALARM CANCEL&gt;</b> Cancels alarms and messages that are marked with this symbol.
	<channel> Advances for several channels.</channel>
(i) HELP	<help> Calls the context-sensitive online help for the selected window.</help>
NEXT WINDOW	<b>NEXT WINDOW&gt;</b> <ul> <li>Toggles between the windows.</li> <li>For a multi-channel view or for a multi-channel functionality, switches within a channel gap between the upper and lower window.</li> </ul>
PAGE UP	<page up=""> Scrolls upwards by one page in a window.</page>
PAGE UP + Ch SHIFT	<page up=""> + <shift> In the program manager and in the program editor from the cursor position, selects directories or program blocks up to the beginning of the window.</shift></page>
PAGE UP CTRL	<page up=""> + <ctrl> Positions the cursor to the topmost line of a window.</ctrl></page>

1.2 Operator panel fronts



Closes a directory or program (e.g. cycle) in the program editor. If you have made changed, then these are accepted.

Navigation

Moves the cursor further to the left by one character.

#### <Cursor left> + <CTRL>

• Editing box

Moves the cursor further to the left by one word.

Navigation

٠

Moves the cursor in a table to the next cell to the left.



1.2 Operator panel fronts

Key	Function
	<ul> <li><cursor up=""></cursor></li> <li>Editing box Moves the cursor into the next upper field.</li> <li>Navigation <ul> <li>Moves the cursor in a table to the next cell upwards.</li> <li>Moves the cursor upwards in a menu screen.</li> </ul> </li> </ul>
CTRL	<ul> <li><cursor up=""> + <ctrl></ctrl></cursor></li> <li>Moves the cursor in a table to the beginning of the table.</li> <li>Moves the cursor to the beginning of a window.</li> </ul>
+	<cursor up=""> + <shift> In the program manager and in the program editor, selects a</shift></cursor>

In the program manager and in the program editor, selects a contiguous selection of directories and program blocks.

#### <Cursor down>

Editing box

Moves the cursor downwards.

- Navigation
  - Moves the cursor in a table to the next cell downwards.
  - Moves the cursor in a window downwards. \_

#### <Cursor down> + <CTRL>

- Moves the cursor in a table to the end of the table.
- Moves the cursor to the end of a window.

#### <Cursor down> + <SHIFT>

In the program manager and in the program editor, selects a contiguous selection of directories and program blocks.

#### <SELECT>

CTRL

£

SHIFT

In selection drop down list boxes and in selection boxes, switches between several specified options.

Activates check boxes.

In the program editor and in the program manager, selects a program block or a program.

SELECT

1.2 Operator panel fronts

Key	Function
	<end></end>
END	Moves the cursor to the last entry field in a window or in a table.
+	<end> + <shift></shift></end>
END LI SHIFT	Moves the cursor to the last entry.
+	<end> + <ctrl></ctrl></end>
END	Moves the cursor to the last entry in the last line of the actual column.
<b></b>	<backspace></backspace>
BACKSPACE	Editing box
	<ul><li>Deletes a character selected to the left of the cursor.</li><li>Navigation</li></ul>
	Deletes all of the selected characters to the left of the cursor.
+	<backspace> + <ctrl></ctrl></backspace>
BACKSPACE	Deletes a word selected to the left of the cursor.
	<tab></tab>
ТАВ	<ul><li>In the program editor, indents the cursor by one character.</li><li>In the program manager, moves the cursor to the entry.</li></ul>
· · · · · · · · · · · · · · · · · · ·	<ctrl> + <a></a></ctrl>
CTRL	In the actual window, selects all entries (only in the program editor and program manager).
	<ctrl> + <c></c></ctrl>
CTRL C	Copies the selected content.
· · · · · · · · · · · · · · · · · · ·	<ctrl> + <l></l></ctrl>
CTRL	Scrolls the actual user interface through all installed languages one after the other.
	<pre><ctrl> + <shift> + <l></l></shift></ctrl></pre>
	Scrolls the actual operator interface through all installed

Scrolls the actual operator interface through all installed languages in the inverse sequence.

#### <CTRL> + <P>

Ρ

CTRL

Generates a screenshot from the actual operator interface and saves it as file.

1.2 Operator panel fronts

Key	Function
	<ctrl> + <x></x></ctrl>
CTRL	Cuts out the selected text. The text is located in the clipboard.
+	<ctrl> + <y></y></ctrl>
CTRL	Reactivates changes that were undone (only in the program editor).
	<ctrl> + <v></v></ctrl>
CTRL	Inserts text from the clipboard:
	<ul> <li>Pastes the text from the clipboard at the actual cursor position.</li> </ul>
	• Pastes text from the clipboard at the position of a selected text.
	<pre></pre>
CTRL ALT C	Creates a complete archive on an external data carrier (USB- FlashDrive).
	<pre> <ctrl> + <alt> + <s></s></alt></ctrl></pre>
CTRL ALT S	Creates a complete archive on an external data carrier (USB- FlashDrive).
	<pre></pre>
CTRL ALT D	Backs up the log files on the USB-FlashDrive. If a USB- FlashDrive is not inserted, then the files are backed-up in the manufacturer's area of the CF-Card.
	<alt> + <s></s></alt>
ALT S	Opens the Editor to enter Asian characters.
	<del></del>
DEL	Editing box
	Deletes the first character right of the cursor.
	Navigation
	Deletes all characters.
DEL CTRL	<pre><del> + <ctrl></ctrl></del></pre>
	Editing box
	<ul><li>Deletes the first word to the right of the cursor.</li><li>Navigation</li></ul>

Navigation

Deletes all characters.

1.2 Operator panel fronts

Кеу	Function
	<insert></insert>
INSERT	• Opens an editing window in the insert mode. Press the key again, exits the window and the entries are undone.
	Opens a selection box and shows the selection options.
	<input/>
	Completes input of a value in the entry field.
	Opens a director or a program.
	<alarm> - only OP 010 and OP 010C</alarm>
ALARM	Select the "Diagnosis" operating area.
	<program> - only OP 010 and OP 010C</program>
	-
PROGRAM	Calls the "Program Manager" operating area.
	<offset> - only OP 010 and OP 010C</offset>
OFFSET	Calls the "Parameter" operating area.
	<program manager=""> - only OP 010 and OP 010C</program>
PROGRAM MANAGER	Calls the "Program Manager" operating area.
	Menu forward key
	Advances in the extended horizontal softkey bar.
	Advances in the extended horizontal softkey bar.
	Menu back key
$\land$	Returns to the higher-level menu.
	<machine></machine>
MACHINE	Calls the "Machine" operating area.
MENU	<menu select=""></menu>
SELECT	Calls the main menu to select the operating area.

### 1.3 Machine control panels

#### 1.3.1 Overview

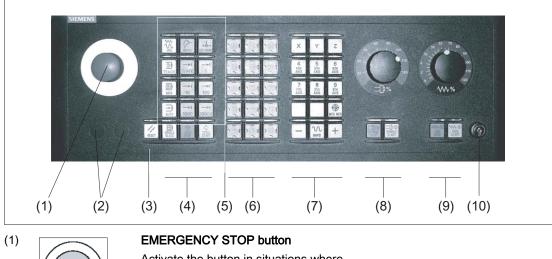
The machine tool can be equipped with a machine control panel by Siemens or with a specific machine control panel from the machine manufacturer.

You use the machine control panel to initiate actions on the machine tool such as traversing an axis or starting the machining of a workpiece.

#### 1.3.2 Controls on the machine control panel

In this example, the MCP 483C IE machine control panel is used to illustrate the operator controls and displays of a Siemens machine control panel.

#### Overview

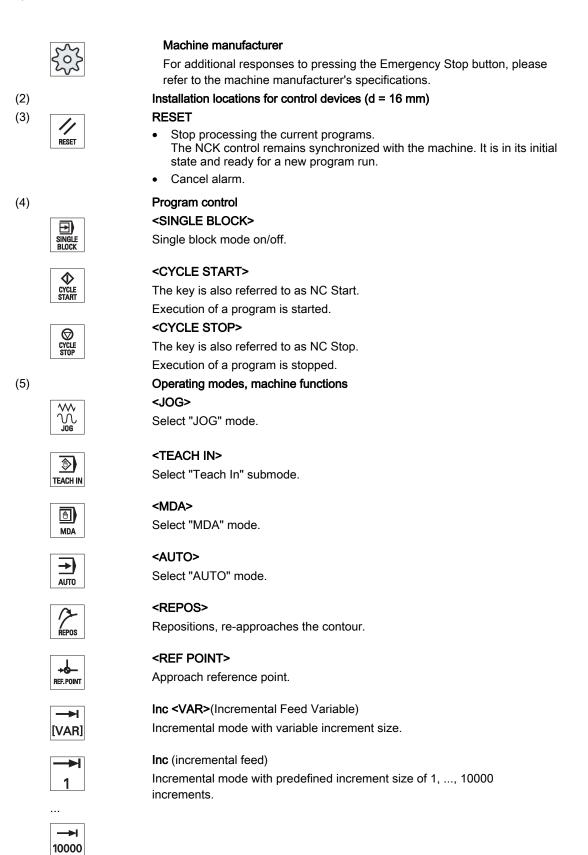


Activate the button in situations where

- life is at risk.
- there is the danger of a machine or workpiece being damaged.

All drives will be stopped with the greatest possible braking torque.

1.3 Machine control panels



		A machine data code defines how the increment value is interpreted.
(6)		Customer keys
		T1 to T15
(7)		Traversal axes with rapid traverse superposition and coordinate exchange
		Axis keys
	X	Selects an axis.
	Z	
		Direction keys
	+	Select the traversing direction.
	10.	<rapid></rapid>
	RAPID	Traverse axis in rapid traverse while pressing the direction key.
		<wcs mcs=""></wcs>
		Switches between the workpiece coordinate system (Work) and machine
(0)		coordinate system (Machine).
(8)		Spindle control with override switch <spindle stop=""></spindle>
		Stop spindle.
	STOP	otop apindie.
	⊐₽�	<spindle start=""></spindle>
	SPINDLE START	Spindle is enabled.
(9)		Feed control with override switch
(•)		<pre><feed stop=""></feed></pre>
		Stops execution of the running program and shuts down axis drives.
		<feed start=""></feed>
	FEED START	Enable for program execution in the current block and enable for ramp-up to
(10)		the feedrate value specified by the program.
(10)		Keyswitch (four positions)
Figu	re 1-2 Front view	w of machine control panel (milling version)

1.4 User interface

# 1.4 User interface

### 1.4.1 Screen layout

#### Overview

	300 🖉 📈 Em	ergency stop		ENTENC	0	
	WOE(3)OLD_AND_DIE Reset (4)	A Lisit. F	eedrate enat(5)mis		G functions	
Machine	Position [mm]	<u>va</u> wait. r	T,F,S	ssing	Auxiliary	
XM	0.000	<u>^</u>	Т		functions	
YM	⑥ 0.000		7		Basic	
ZM	0.000	=	F 0.000	W	blocks	
U1	0.000		0.000	mm/ min 80%	Times	
		¥	S1 v 0 Master 0		Time counter	
			<u>,0 , 5</u> 0	, <u>100, 120</u> ,	Program	
	10LD_AND_DIE [1, 1]=120  ; Schaftfj	r�ser Tm, Dn¶_	G functions 1: GO1	13: 6710	levels	
	[1,1]=60 ;Li;½nge¶		2:	14: 690		
· •	[1,1]=5 ;Radius¶		3: 6: 618	15: G94 16: CFC		
; N40 T1 [		=	7: 640 9	21: BRISK	Act. values	
	E(,,,"BOX",64,80,40 Kopf Zyl" D1¶	), 200, -190, -12;	8: G500 9:	22: CUT2D 29: DIAM90	Machine	
M6¶		~	10: G60	30: COMPOF		
10	1	Dia Drog		>	Prog.	
		NC Prog. N cntrl.	C Bloch Bloch Bloch	record.	Prog. corr.	
$\land$						>
,M,						MENU
MACHINE						SELECT

- 1 Active operating area and mode
- 2 Alarm/message line
- 3 Program name
- 4 Channel state and program control
- 5 Channel operational messages
- 6 Axis position display in actual value window

- 7 Display for
  - active tool T
  - current feedrate F
  - active spindle with current status (S)
  - Spindle utilization rate in percent
- 8 Operating window with program block display
- 9 Display of active G functions, all G functions, auxiliary functions and input window for different functions (for example, skip blocks, program control).
- 10 Dialog line to provide additional user notes.
- 11 Horizontal softkey bar
- 12 Vertical softkey bar

Figure 1-3 User interface

#### 1.4.2 Status display

The status display includes the most important information about the current machine status and the status of the NCK. It also shows alarms as well as NC and PLC messages.

Depending on your operating area, the status display is made up of several lines:

• Large status display

The status display is made up of three lines in the "Machine" operating area.

• Small status display

In the "Parameter", "Program", "Program Manager", "Diagnosis" and "Start-up" operating areas, the status display consists of the first line from the large display.

#### Status display of "Machine" operating area

#### **First line**

Display	isplay Description		
Active operating area			
M	"Machine" operating area With touch operation, you can change the operating area here.		
	"Parameter" operating area		
	"Program" operating area		

1.4 User interface

Display	Description
ſ	"Program manager" operating area
	"Diagnosis" operating area
2	"Start-up" operating area
Active mode or submode	
	"Jog" mode
MDA	"MDA" mode
	"Auto" mode
Teach In	"Teach In" submode
REPOS	"Repos" submode
REFPOINT	"Ref Point" submode
Alarms and messages	
10299 🕂 📄 Kanal 1 Funktion Auto-R	Alarm display The alarm numbers are displayed in white lettering on a red background. The associated alarm text is shown in red lettering.
	An arrow indicates that several alarms are active.
	An acknowledgment symbol indicates that the alarm can be acknowledged or canceled.
550125 Dies ist eine PLC-Meidung: Maschinentür geöffnet	NC or PLC message
Maschinentür geöffnet	Message numbers and texts are shown in black lettering.
	An arrow indicates that several messages are active.
READY TO START	Messages from NC programs do not have numbers and appear in green lettering.

#### Second line

Display	Description
TEST_TEACHEN	Program path and program name

The displays in the second line can be configured.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

#### Third line

Display	Description
	Display of channel status.
CHAN1 RESET	If several channels are present on the machine, the channel name is also displayed.
	If only one channel is available, only the "Reset" channel status is displayed.
	With touch operation, you can change the channel here.
	Display of channel status:
//	The program was aborted with "Reset".
	The program is started.
$\bigcirc$	The program has been interrupted with "Stop".
	Display of active program controls:
DRYPRT	PRT: no axis motion
	DRY: Dry run feedrate
	RG0: reduced rapid traverse
	M01: programmed stop 1
	M101: programmed stop 2 (name varies)
	SB1: Single block, coarse (program stops only after blocks which perform a machine function)
	SB2: Data block (program stops after each block)
	SB3: Single block, fine (program also only stops after blocks which perform a machine function in cycles)
	Channel operational messages:
🗥 Faulty NC block / user alarm	Stop: An operator action is usually required.
ORemaining dwell time:15 Sec.	Wait: No operator action is required.

The machine manufacturer settings determine which program controls are displayed.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

#### 1.4.3 Actual value window

The actual values of the axes and their positions are displayed.

1.4 User interface

#### Work/Machine

The displayed coordinates are based on either the machine coordinate system or the workpiece coordinate system. The machine coordinate system (Machine), in contrast to the workpiece coordinate system (Work), does not take any work offsets into consideration.

You can use the "Machine actual values" softkey to toggle between the machine coordinate system and the workpiece coordinate system.

The actual value display of the positions can also refer to the SZS coordinate system (settable zero system). However the positions are still output in the Work.

The ENS coordinate system corresponds to the Work coordinate system, reduced by certain components (\$P\_TRAFRAME, \$P\_PFRAME, \$P\_ISO4FRAME, \$P\_CYCFRAME), which are set by the system when machining and are then reset again. By using the ENS coordinate system, jumps into the actual value display are avoided, that would otherwise be caused by the additional components.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Maximize display



Press the ">>" and "Zoom act.val." softkeys.

#### Overview of display

Display	Meaning
Header columns	
Work/Machine	Display of axes in selected coordinate system.
Item	Position of displayed axes.
Display of distance-to-go	The distance-to-go for the current NC block is displayed while the program is running.
Feed/override	The feed acting on the axes, as well as the override, are displayed in the full-screen version.
Repos offset	The distances traversed in manual mode are displayed.
	This information is only displayed when you are in the "Repos" submode.
Footer	Display of active work offsets and transformations.
	The T, F, S values are also displayed in the full-screen version.

#### See also

Overview (Page 70) Work offsets (Page 101)

### 1.4.4 T,F,S window

The most important data concerning the current tool, the feedrate (path feed or axis feed in JOG) and the spindle are displayed in the T, F, and S windows.

#### Tool data

Display	Meaning
т	
Tool name	Name of current tool
Location	Location number of current tool
D	Cutting edge of the current tool
	The tool is displayed with the associated tool type symbol corresponding to the actual coordinate system in the selected cutting edge position.
	If the tool is swiveled, then this is taken into account in the display of the cutting edge position.
	In DIN-ISO mode the H number is displayed instead of the cutting edge number.
Н	H number (tool offset data record for DIN-ISO mode)
	If there is a valid D number, this is also displayed.
Ø	Diameter of current tool
R	Radius of the actual tool
Z	Z value of the actual tool
Х	X value of the actual tool

#### Feed data

Display	Meaning
F	
W	Feed disable
	Actual feed value
	If several axes traverse, is displayed for:
	"JOG" mode: Axis feed for the traversing axis
	"MDA" and "AUTO" mode: Programmed axis feed
Rapid traverse	G0 is active

1.4 User interface

Display	Meaning
0.000	No feed is active
Override	Display as a percentage

#### Spindle data

Display	Meaning
S	
S1	Spindle selection, identification with spindle number and main spindle
Speed	Actual value (when spindle turns, display increases)
	Setpoint (always displayed, also during positioning)
Symbol	Spindle status
	Spindle not enabled
$\bigcirc$	Spindle is turning clockwise
S	Spindle is turning counterclockwise
$\boxtimes$	Spindle is stationary
Override	Display as a percentage
Spindle utilization	Display between 0 and 100%
rate	The upper limit value can be greater than 100%.
	See machine manufacturer's specifications.

#### 1.4.5 Current block display

The window of the current block display shows you the program blocks currently being executed.

#### Display of current program

The following information is displayed in the running program:

- The workpiece name or program name is entered in the title row.
- The program block which is just being processed appears colored.

# Editing a program directly

In the Reset state, you can edit the current program directly.



- 1. Press the <INSERT> key.
- 2. Place the cursor at the relevant position and edit the program block. Direct editing is only possible for G code blocks in the NC memory, not for external execution.
- 3. Press the <INSERT> key to exit the program and the edit mode again.



#### 1.4.6 Operation via softkeys and buttons

#### Operating areas/operating modes

The user interface consists of different windows featuring eight horizontal and eight vertical softkeys.

You operate the softkeys with the keys next to the softkey bars.

You can display a new window or execute functions using the softkeys.

The operating software is sub-divided into six operating areas (machine, parameter, program, program manager, diagnosis, startup) and five operating modes or submodes (JOG, MDA, AUTO, TEACH IN, REF POINT, REPOS).

# Changing the operating area



Press the <MENU SELECT> key and select the desired operating area using the horizontal softkey bar.

You can call the "Machine" operating area directly using the key on the operator panel.



Press the <MACHINE> key to select the "machine" operating area.

#### Changing the operating mode

You can select a mode or submode directly using the keys on the machine control panel or using the vertical softkeys in the main menu.

1.4 User interface

#### General keys and softkeys



When the symbol appears to the right of the dialog line on the user interface, you can change the horizontal softkey bar within an operating area. To do so, press the menu forward key.

The **Symbol** indicates that you are in the expanded softkey bar. Pressing the key again will take you back to the original horizontal softkey bar.



Use the ">>" softkey to open a new vertical softkey bar.



Use the "<<" softkey to return to the previous vertical softkey bar.



Use the "Return" softkey to close an open window.



Use the "Cancel" softkey to exit a window without accepting the entered values and return to the next highest window.



When you have entered all the necessary parameters in the parameter screen form correctly, you can close the window and save the parameters using the "Accept" softkey. The values you entered are applied to a program.



Use the "OK" softkey to initiate an action immediately, e.g. to rename or delete a program.

# 1.4.7 Entering or selecting parameters

When setting up the machine and during programming, you must enter various parameter values in the entry fields. The background color of the fields provides information on the status of the input field.

Orange background	The input field is selected
Light orange background	The input field is in edit mode
Pink background	The entered value is incorrect

# Selecting parameters

Some parameters require you to select from a number of options in the input field. Fields of this type do not allow you to type in a value.

The selection symbol is displayed in the tooltip: U

#### Associated selection fields

There are selection fields for various parameters:

- Selection of units
- Changeover between absolute and incremental dimensions

# Procedure



 Keep pressing the <SELECT> key until the required setting or unit is selected.

The <SELECT> key only works if there are several selection options available.

- OR -



Press the <INSERT> key.

The selection options are displayed in a list.



- Select the required setting using the <Cursor down> and <Cursor up> keys.
- 3. If required, enter a value in the associated input field.
- 4. Press the <INPUT> key to complete the parameter input.

# INPUT

#### Changing or calculating parameters

If you only want to change individual characters in an input field rather than overwriting the entire entry, switch to insertion mode.

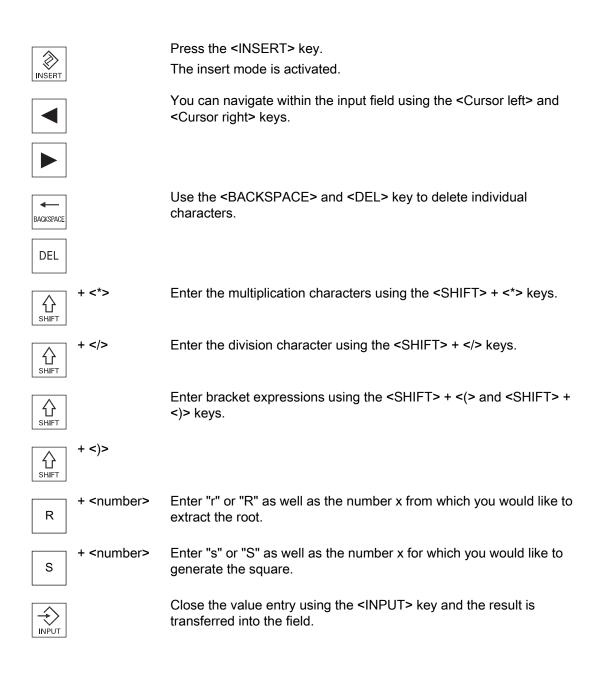
In this mode, you can also enter simple calculation expressions, without having to explicitly call the calculator. You can execute the four basic calculation types, work with expressions in brackets as well as generate square roots and squares.

#### Note

#### Generating square roots and squares

The extract roots and generate square functions is not available in the parameter screens of the cycles and functions in the "Program" operating area.

1.4 User interface



# Accepting parameters

When you have correctly entered all necessary parameters, you can close the window and save your settings.

You cannot accept the parameters if they are incomplete or obviously erroneous. In this case, you can see from the dialog line which parameters are missing or were entered incorrectly.



Press the "OK" softkey.

- OR -



Press the "Accept" softkey.

# 1.4.8 Pocket calculator

You can use the pocket calculator to quickly calculate parameter values during programming. If, for example, the diameter of a workpiece is only dimensioned indirectly in the workpiece drawing, i.e., the diameter must be derived from the sum of several other dimension specifications, you can calculate the diameter directly in the input field of this parameter.

# **Calculation methods**

The following arithmetic operations are available:

- Addition
- Subtraction
- Multiplication
- Division
- Calculation with parentheses
- Square root of x
- x squared

You can input a maximum of 256 characters in a field.

Pocket o	calculat	or			
85					
7	8	9	T	C	)
4	5	6	*	√x	R
1	2	3	Ŀ	<b>X</b> <sup>2</sup>	S
C	0				-

# Introduction

1.4 User interface

# Procedure

	1.	Position the cursor on the desired input field.
=	2.	Press the <=>.
		The pocket calculator is displayed.
	3.	Input the arithmetic statement.
		You can use arithmetic symbols, numbers, and commas.
=	4.	Press the equals symbol on the calculator.
		- OR -
Calculate		Press the "Calculate" softkey.
		- OR -
		Press the <input/> key.
		The new value is calculated and displayed in the input field of the pocket calculator.
$\checkmark$	5.	Press the "Accept" softkey.
Accept		The calculated value is accepted and displayed in the input field of the window.

# Note

# Input order for functions

When using the square root or squaring functions, make sure to press the "R" or "S" function keys, respectively, before entering a number.

# 1.4.9 Context menu

When you right-click, the context menu opens and provides the following functions:

- Cut
  - Cut Ctrl+X
- Сору

Copy Ctrl+C

Paste

Paste Ctrl+V

# **Program editor**

Additional functions are available in the editor

- Undo the last change
   Undo Ctrl+Z
- Redo the changes that were undone Redo Ctrl+Y

Up to 10 changes can be undone.

# 1.4.10 Touch operation

If you have an operator panel with a touch screen, you can perform the following functions with touch operation:

# Operating area switchover



You can display the operating area menu by touching the display symbol for the active operating area in the status display.

# **Channel switchover**

CHAN1 RESET

You can switch over to the next channel by touching the channel display in the status display.

# 1.4.11 Changing the user interface language

# Procedure

1. Select the "Startup" operating area.

- Start-up Change language
- Press the "Change language" softkey.
   The "Language selection" window opens. The language set last is selected.
- 3. Position the cursor on the desired language.

#### Introduction

# 1.4 User interface

ОК	4.	Press the "OK" softkey.
INPUT		- OR - Press the <input/> key.
		The user interface changes to the selected language.

#### Note

# Changing the language directly on the input screens

You can switch between the user interface languages available on the controller directly on the user interface by pressing the key combination <CTRL + L>.

# 1.4.12 Entering Asian characters

You have the possibility of entering Asian characters.

#### Note

#### Call the input editor with <Alt + S>

The input editor can only be called there where it is permissible to enter Asian characters.

You can select a character by using the Pinyin phonetic notation, which enables Chinese characters to be expressed by combining Latin letters.

The editor is available for the following Asian languages:

- Simplified Chinese
- Traditional Chinese
- Korean

#### Note

You require a special keyboard to enter Korean characters.

#### Structure of editor



# Functions

汉	Pinyin input
新词	Editing of the dictionary
A	Input of Latin letters

# Precondition

The control has been set to Chinese or Korean.

# Procedure

# **Editing characters**



 Open the screen form and position the cursor on the entry field and press the <Alt +S> keys.
 The editor is displayed.



- 2. Enter the desired phonetic notation.
- 3. Click the <Cursor down> key to access the dictionary.



- 4. By keeping the <Cursor down> key pressed, displays all the entered phonetic notations and the associated selection characters.
- BACKSPACE
- 5. Press the <BACKSPACE> softkey to delete entered phonetic notations.
- Press the number key to insert the associated character.
   When a character is selected, the editor records the frequency with which it is selected for a specific phonetic notation and offers this character at the top of the list when the editor is next opened.

# Editing the dictionary

1.



Select the dictionary editing function in the selection box. The editor provides a further line in which the combined characters and phonetic notations are displayed. 1.4 User interface

→I I← TAB	
-	
BACKSPACE	

()

SELECT

- Enter the desired phonetic notation in the phonetic input field. Various characters are displayed for this phonetic notation, from which you can select a character by entering either of the appropriate number (1 to 9). You can toggle the input cursor between the compound phonetic notations field and the phonetic input field by pressing the <TAB> key. Combined characters are cancelled via the <BACKSPACE> key.
- 3. Press the <SELECT> key to take a combined phonetic notation into the dictionary.

# 1.4.13 Protection levels

The input and modification of data in the control system is protected by passwords at sensitive places.

# Access protection via protection levels

The input or modification of data for the following functions depends on the protection level setting:

- Tool offsets
- Work offsets
- Setting data
- Program creation / program editing

# References

For additional information, please refer to the following documentation: Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

# Softkeys

Machine operating area	Protection level
SYNC Synchro	End user
n.	(protection level 3)

Introduction

1.4 User interface

Parameters operating area	Protection level
Tool management lists	
Details	Key switch 3 (protection level 4)

Diagnostics operating area	Protection level
Logbook	Keyswitch 3 (protection level 4)
Change	End user (protection level 3)
New	End user
entry	(protection level 3)
Startup	Manufacturer
complete	(protection level 1)
Machine	End user
installed	(protection level 3)
Add HW	Service
comp.	(protection level 2)

Startup operating area	Protection levels
System	End user
data	(protection level 3)
Series	Keyswitch 3
start-u	(protection level 4)
General Control	Keyswitch 3
MD unit MD	(protection level 4)
Lic-	Key switch 3
enses	(protection level 4)
Set MD	Keyswitch 3
active (cf)	(protection level 4)
NCK	Service (protection level 2)

#### Introduction

# 1.4 User interface

Startup operating area	Protection levels
Change	End user
password	(protection level 3)
Delete	End user
password	(protection level 3)

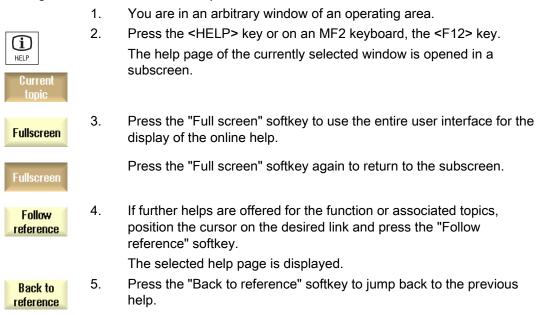
# 1.4.14 Online help in SINUMERIK Operate

A comprehensive context-sensitive online help is stored in the control system.

- A brief description is provided for each window and, if required, step-by-step instructions for the operating sequences.
- A detailed help is provided in the editor for every entered G code. You can also display all G functions and take over a selected command directly from the help into the editor.
- A help page with all parameters is provided on the input screen in the cycle programming.
- Lists of the machine data
- Lists of the setting data
- Lists of the drive parameters
- List of all alarms

# Procedure

# Calling context-sensitive online help



#### Calling a topic in the table of contents

1.

Table of contents Press the "Table of contents" softkey. Depending on which technology you are using, the Operating Manuals "Operator control Milling", "Operator control Turning" or "Operator control Universal" as well as the "Programming" Programming Manual are displayed.

2. Select the desired manual with the <Cursor down> and <Cursor up> keys.



3 Press the <Cursor right> or <INPUT> key or double-click to open the manual and the chapter.



4. Navigate to the desired topic with the "Cursor down" key.



Curren

Search

- 5. Press the <Follow reference> softkey or the <INPUT> key to display the help page for the selected topic.
- 6. Press the "Current topic" softkey to return to the original help.

#### Searching for a topic

1. Press the "Search" softkey.

The "Search in Help for: " window is opened.

 Activate the "Full text " checkbox to search in all help pages. If the checkbox is not activated, a search is performed in the table of contents and in the index.



Table

of contents

Enter the desired keyword in the "Text" field and press the "OK" softkey.
 If you enter the search term on the operator panel, replace an um

If you enter the search term on the operator panel, replace an umlaut (accented character) by an asterisk (\*) as dummy.

All entered terms and sentences are sought with an AND operation. In this way, only documents and entries that satisfy all the search criteria are displayed.

# 4. Press the "Keyword index" softkey if you only want to display the index of the operating and programming manual.

1.4 User interface

Displaying ala	arm de	scriptions and machine data
(i) HELP	1.	If messages or alarms are pending in the "Alarms", "Messages" or "Alarm Log" window, position the cursor at the appropriate display and press the <help> or the <f12> key.</f12></help>
		The associated alarm description is displayed.
HELP	2.	If you are in the "Startup" operating area in the windows for the display of the machine, setting and drive data, position the cursor on the desired machine data or drive parameter and press the <help> or the <f12> key.</f12></help>
		The associated data description is displayed.
Displaying an	nd inse	rting a G code command in the editor
LELP 1.	1.	A program is opened in the editor.
		Position the cursor on the desired G code command and press the <help> or the <f12> key.</f12></help>
		The associated G code description is displayed.
Display all G functions	2.	Press the "Display all G funct." softkey.
Search	3.	With the aid of the search function, select, for example, the desired G code command.
Transfer	4.	Press the "Transfer to editor" softkey.
to editor		The selected G function is taken into the program at the cursor position.
Exit Help	5.	Press the "Exit help" softkey again to close the help.

See also

Additional functions in the input screens (Page 220)

# Setting up the machine

# 2.1 Switching on and switching off

# Start-up

			02/17/09 2:36 PM
		SIEMENS	
🖉 DREHEN_K1 Rese			_
Machine	Position [mm]	Feed/override	
X1	0.000	0.000 mm/min 80%	
Y1	0.000	0.000 mm/min	
		80%	
Z1	0.000	0.000 mm/min 80%	
SP1	0.000°	0.000 °/min	
011	0.000	80%	
		[	
			_
		F 0.000	
		F=0.000	

When the control starts up, the main screen opens according to the operating mode specified by the machine manufacturer. In general, this is the main screen for the "REF POINT" submode.

# Machine manufacturer

Please also refer to the machine manufacturer's specifications.

2.2 Approaching a reference point

# 2.2 Approaching a reference point

# 2.2.1 Referencing axes

Your machine tool can be equipped with an absolute or incremental path measuring system. An axis with incremental path measuring system must be referenced after the control has been switched-on – however, an absolute path measuring system does not have to be referenced.

For the incremental path measuring system, all the machine axes must therefore first approach a reference point, the coordinates of which are known to be relative to the machine zero-point.

#### Sequence

Prior to the approach, the axes must be in a position from where they can approach the reference point without a collision.

The axes can also all approach the reference point simultaneously, depending on the manufacturer's settings.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### NOTICE

If the axes are not in a collision-free position, you must first traverse them to safe positions in "JOG" or "MDA" mode.

You must follow the axis motions directly on the machine!

Ignore the actual value display until the axes have been referenced!

The software limit switches are not active!

# Procedure



1. Press the <JOG> key.

1	
+0-	
REF. POINT	

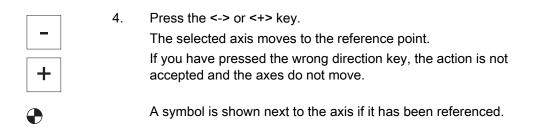
2. Press the <REF. POINT> key.



Ζ

3. Select the axis to be traversed.

2.2 Approaching a reference point



The axis is referenced as soon as the reference point is reached. The actual value display is set to the reference point value.

From now on, path limits, such as software limit switches, are active.

End the function via the machine control panel by selecting operating mode "AUTO" or "JOG".

# 2.2.2 User agreement

If you are using Safety Integrated (SI) on your machine, you will need to confirm that the current displayed position of an axis corresponds to its actual position on the machine when you reference an axis. Your confirmation is the precondition for the availability of other Safety Integrated functions.

You can only give your user acknowledgement for an axis after it has approached the reference point.

The displayed axis position always refers to the machine coordinate system (Machine).

#### Option

User acknowledgement with Safety Integrated is only possible with a software option.

# Procedure



1. Select the "Machine" operating area.

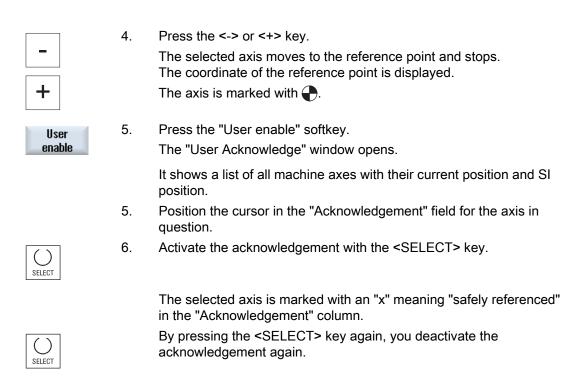


- 2. Press the <REF POINT> key.
- 3. Select the axis to be traversed.



#### Setting up the machine

#### 2.2 Approaching a reference point



# 2.3 Operating modes

# 2.3.1 General

You can work in three different operating modes.

# "JOG" mode

"JOG" mode is used for the following preparatory actions:

- Approach reference point, i.e. the machine axis is referenced
- Preparing a machine for executing a program in automatic mode, i.e. measuring tools, measuring the workpiece and, if necessary, defining the work offsets used in the program
- Traversing axes, e.g. during a program interruption
- Positioning axes

#### Select "JOG"



Press the <JOG> key.

# "Ref Point" submode

The "REF POINT" submode is used to synchronize the control and the machine. For this purpose, you approach the reference point in "JOG" mode.

# Selecting "REF POINT"



Press the <REF POINT> key.

# "REPOS" submode

The "REPOS" submode is used for repositioning to a defined position. After a program interruption (e.g. to correct tool wear values) move the tool away from the contour in "JOG" mode.

The distances traversed in "JOG" mode are displayed in the actual value window as the "Repos" offset.

"REPOS" offsets can be displayed in the machine coordinate system (MCS) or workpiece coordinate system (WCS).

2.3 Operating modes

# Selecting "Repos"



Press the <REPOS> key.

# "MDA" mode (Manual Data Automatic)

In "MDA" mode, you can enter and execute G code commands non-modally to set up the machine or to perform a single action.

# Selecting "MDA"



Press the <MDA> key.

# "AUTO" mode

In automatic mode, you can execute a program completely or only partially.

# Select "AUTO"



Press the <AUTO> key.

# "TEACH IN" submode

The "TEACH IN" submode is available in the "AUTO" and "MDA" modes.

There you may create, edit and execute part programs (main programs or subroutines) for motional sequences or simple workpieces by approaching and saving positions.

# Selecting "Teach In"



Press the <TEACH IN> key.

# 2.3.2 Modes groups and channels

Every channel behaves like an independent NC. A maximum of one part program can be processed per channel.

- Control with 1channel
  - One mode group exists.
- Control with several channels

Channels can be grouped to form several "mode groups."

# Example

Control with 4 channels, where machining is carried out in 2 channels and 2 other channels are used to control the transport of the new workpieces.

Mode group 1 channel 1 (machining)

Channel 2 (transport)

Mode group 2 channel 3 (machining)

Channel 4 (transport)

# Mode groups (MGs)

Technologically-related channels can be combined to form a mode group.

Axes and spindles of the same mode group can be controlled by one or more channels.

An operating mode group is in one of "Automatic", "JOG" or "MDI" operating modes, i.e., several channels of an operating mode group can never assume different operating modes.

# 2.3.3 Channel switchover

It is possible to switch between channels when several are in use. Since individual channels may be assigned to different mode groups, a channel switchover command is also an implicit mode switchover command.

When a channel menu is available, all of the channels are displayed on softkeys and can be switched over.

# Changing the channel



Press the <CHANNEL> key.

The channel changes over to the next channel.

- OR -

If the channel menu is available, a softkey bar is displayed. In this case, the active channel is displayed highlighted (emphasized). Another channel can be selected by pressing one of the other softkeys.

# References

Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

#### Channel switchover via touch operation

On the HT 8 and when using a touch screen operating panel, you can switch to the next channel via touch operation in the status display.

# 2.4 Settings for the machine

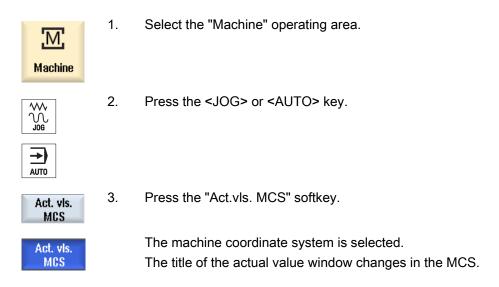
# 2.4.1 Switching over the coordinate system (MCS/WCS)

The coordinates in the actual value display are relative to either the machine coordinate system or the workpiece coordinate system.

By default, the workpiece coordinate system is set as a reference for the actual value display.

The machine coordinate system (MCS), in contrast to the workpiece coordinate system (WCS), does not take into account any work offsets, tool offsets and coordinate rotation.

# Proceed as follows



# 2.4.2 Switching the unit of measurement

You can set millimeters or inches as the unit of measurement. Switching the unit of measurement always applies to the entire machine. All required information is automatically converted to the new unit of measurement, for example:

- Positions
- Tool offsets
- Work offsets



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

2.4 Settings for the machine

# Proceed as follows

	1.	Select <jog> or <auto> mode in the "Machine" operating area.</auto></jog>
>	2.	Press the menu forward key and the "Settings" softkey. A new vertical softkey bar appears.
Changeover inch	3.	Press the "Switch to inch" softkey. A prompt asks you whether you really want to switch over the unit of measurement.
ОК	4.	Press the "OK" softkey.
Changeover metric	5.	The softkey label changes to "Switch to metric". The unit of measurement applies to the entire machine. Press the "Switch to metric" softkey to set the unit of measurement of the machine to metric again.

# 2.4.3 Setting the work offset

You can enter a new position value in the actual value display for individual axes when a settable work offset is active.

The difference between the position value in the machine coordinate system MCS and the new position value in the workpiece coordinate system WCS is saved permanently in the currently active work offset (e.g. G54).

# Precondition

The control is in the workpiece coordinate system.

The actual value is set in the reset state.

# Note

#### Setting the WO in the Stop state

If you enter the new actual value in the Stop state, the changes made are only visible and only take effect when the program is continued.

# Procedure

	1.	Select the "JOG" mode in the "Machine" operating area.
V20 Set WO	2.	Press the "Set WO" softkey.
INPUT X=0	3.	Enter the new position value for X, Y or Z directly in the actual value display (you can toggle between the axes with the cursor keys) and press the "Input" key to confirm the entries. - OR - Press softkeys "X=0","Y=0" or "Z=0" to set the relevant position to zero.
 Z=0		2010.
X=Y=Z=0		<ul> <li>OR - Press softkey "X=Y=Z=0" to set all axis positions to zero simultaneously.</li> </ul>

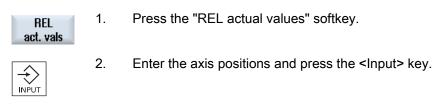
# Resetting the actual value

Delete	Press the "Delete active WO" softkey.
active WO	The offset is deleted permanently.

NOTICE
Irreversible active work offset
The current active work offset is irreversibly deleted by this action.

2.4 Settings for the machine

# Relative actual value



# Note

The new actual value is only displayed. The relative actual value has no effect on the axis positions and the active work offset.

The softkey is only available if the relevant machine data is set.



# Machine manufacturer

Please refer to the machine manufacturer's specifications.

# 2.5 Measuring the tool

The geometries of the machining tool must be taken into consideration when executing a part program. These are stored as tool offset data in the tool list. Each time the tool is called, the control considers the tool offset data.

When programming the part program, you only need to enter the workpiece dimensions from the production drawing. After this, the controller independently calculates the individual tool path.

You can determine the tool offset data, i.e. the length and radius or diameter, either manually or automatically with tool probes.

#### See also

Tool dimensioning (Page 478) Measuring the tool (Page 490)

# 2.5.1 Measuring a tool manually

For manual measurement, move the tool manually to a known reference point to determine the tool length and the radius or diameter. The control then calculates the tool offset data from the position of the tool carrier reference point and the reference point.

# **Reference** point

When measuring the tool length you can either use the workpiece or a fixed point in the machine coordinate system, e.g. a mechanical test socket or a fixed point in combination with a distance gauge as the reference point.

When determining the radius/diameter, the workpiece is always used as the reference point

In the machine data, you define whether the radius or the diameter of the tool is to be measured.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Note

You can enter the position of the workpiece during measurement.

However, you must declare the position of the fixed point before the measurement.

#### See also

Fixed point calibration (Page 65)

# 2.5.2 Measuring the tool length with the workpiece as reference point

# Procedure

Machine	1. 2.	Insert the tool you want to measure in the spindle. Select "JOG" mode in the "Machine" operating area.
Meas. tool Length manual	3.	Press the "Meas. tool" and "Length manual" softkeys. The "Length Manual" window opens.
SELECT	4.	Select the cutting edge number D and the number of the replacement tool ST of the tool.
	5.	Approach the workpiece in the Z direction, scratch it with a turning spindle and enter the set position Z0 of the workpiece edge.
Set length	6.	Press the "Set length" softkey. The tool length is calculated automatically and entered in the tool list.

Note

Tool measurement is only possible with an active tool.

# 2.5.3 Measuring radius or diameter

# Procedure

	1.	Insert the tool you want to measure in the spindle. Select "JOG" mode in the "Machine" operating area.
Meas. tool	2.	Press the "Meas. tool" softkey.
Radius manual Diameter manual	3.	Press the "Radius manual" or "Diam. manual" softkey.
SELECT	4.	Select the cutting edge number D and the the number of the replacement tool ST.
	5.	Approach the workpiece in the X or Y direction and perform scratching with the spindle rotating in the opposite direction.
	6.	Specify the setpoint position X0 or Y0 of the workpiece edge.
Set radius Set diamet.	7.	Press the "Set radius" or "Set diam." softkey. The tool radius or diameter is calculated automatically and entered in the tool list.

#### Note

Tool measurement is only possible with an active tool.

# 2.5.4 Fixed point calibration

If you want to use a fixed point as the reference point in manual measurement of the tool length, you must first determine the position of the fixed point relative to the machine zero.

#### Test socket

You can use a mechanical test socket as the fixed point, for example. Mount the test socket on the machine table in the machining space of the machine. Enter zero as the distance.

# 2.5 Measuring the tool

# Distance gauge

However, you can also use any fixed point on the machine in combination with a distance gauge. Enter the thickness of the plate as "DZ".

To calibrate the fixed point, use either a tool whose length is known (i.e. the tool length must be entered in the tool list) or the spindle directly.

The position of the fixed point may have already been determined by the machine manufacturer.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure

	1.	Traverse the tool or spindle to the fixed point.
	2.	Press the "Measure tool" softkey in the "JOG" mode.
Meas. tool		
Calibrate fixed pt.	3.	Press the "Calibrate fixed point" softkey.
	4.	Enter a correction value for "DZ".
		If you have used a distance gauge, enter the thickness of the plate used.
Cali- brate	5.	Press the "Calibrate" softkey.
	6.	The distance between machine zero and fixed point is calculated and entered in the machine data.

# 2.5.5 Measuring a tool with an electrical tool probe

For automatic measurement, you determine the length and radius or diameter of the tool with the aid of a tool probe (table contact system). The control uses the known positions of the toolholder reference point and tool probe to calculate the tool offset data.

Use the softkey to select whether you want to measure the length, the radius or the diameter of the tool.

The corresponding windows can be adapted to the measurement tasks in order to automatically measure tools.

# Adapting the user interface to the measurement functions

The following selection options can be switched-in or switched-out:

- Calibration plane, measurement plane
- Probe



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Preconditions

- No function-related settings are necessary after the measuring cycles have been installed.
- Before the actual measurement, enter approximate values for length and radius or diameter of the tool in the tool list.
- Calibrate the probe first.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

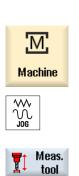
#### Lateral/longitudinal offset

You can consider a lateral or longitudinal offset V when measuring. If the maximum length of the tool is not at the outer edge of the tool or the maximum width is not at the bottom edge of the tool, you can store this difference in the offset.

If measuring shows that the length of the tool diameter is greater than the probe diameter, measurement is automatically performed with a turning spindle rotating in the opposite direction. The tool is then not moved over the probe center-to-center, but with the outside edge of the tool above the center of the probe.

# Procedure

- 1. Insert the tool that you want to measure.
- 2. Select "JOG" mode in the "Machine" operating area.



3. Press the "Meas. tool" softkey.



4. Press the "Length auto" softkey if you want to measure the length of the tool.

		- OR -
Radius auto		Press the "Radius Auto" or "Diam. Auto" softkey if you wish to measure the radius or diameter of the tool.
Diameter auto		
SELECT	5.	Select the cutting edge number D and the number of the replacement tool ST.
	6.	If necessary, enter the lateral offset V.
CYCLE START	7.	Press the <cycle start=""> key.</cycle>
		This starts the automatic measuring process. When you measure the tool radius or diameter, measurement is performed with a spindle rotating in the opposite direction.
		The tool length, radius, and diameter are calculated automatically and entered in the tool list.

#### Note

Tool measurement is only possible with an active tool.

# 2.5.6 Calibrating the electrical tool probe

If you want to measure your tools automatically, you must first determine the position of the tool probe on the machine table with reference to the machine zero.

Tool probes are typically shaped like a cube or a cylindrical disk. Install the tool probe in the working area of the machine (e.g on the machine table) and align it relative to the machining axes.

You must use a mill-type calibration tool to calibrate the tool probe. You must enter the length and radius/diameter of the calibration tool in the tool list beforehand.

#### Note

#### Setting the protection level

The "Calibrate probe" function is only available if an adequate level of protection is set.

Please refer to the machine manufacturer's specifications.

# Procedure

Μ Machine 1.

5.

measuring surface of the tool probe. 2. Select operating mode "JOG" in the "Machine" operating area and press the "Measure tool" softkey.

Move the calibration tool until it is approximately over the center of the





Press the "Probe calibration" softkey. 3.



Calibrate probe

- 4. Choose whether you want to calibrate the length or the length and the diameter.
- $\mathbf{0}$ CYCLE
- Press the <CYCLE START> key.

Calibration is automatically executed at the measuring feedrate. The distance measurements between the machine zero and tool probe are calculated and stored in an internal data area.

2.6 Measuring the workpiece zero

# 2.6 Measuring the workpiece zero

#### 2.6.1 Overview

The reference point for programming a workpiece is always the workpiece zero. You can determine the workpiece zero on the following workpiece elements:

- Edges, (Page 79)
- Corner (Page 81)
- Pocket and hole (Page 84)
- Spigot (Page 91)

#### Measuring methods

You can measure the workpiece zero either manually or automatically.

#### Manual measurement

To measure the zero point manually, you need to traverse your tool manually up to the workpiece. You can use edge probes, sensing probes, or dial gauges with known radii and lengths. You can also use any other tool of which you know the radius and length.

The tools used for measuring must not be electronic probes.

#### Automatic measurement

For automatic measurements, only use the electronic workpiece probe, tool type 710. You must first calibrate the electronic workpiece probe.

In the case of automatic measuring, first position the workpiece probe manually. After starting using the <CYCLE START> key, the workpiece probe is automatically extended to the workpiece with the measuring feedrate. Retraction motion from the measuring point is realized as a function of the setting data with the rapid traverse velocity or a user-specific positioning velocity.

#### Adapting the user interface to the measurement functions

Activate the following selection options using setting data:

- Calibration plane, measurement plane
- Work offset as basis for the measuring process
- Number of the probe calibration data set
- Offset target, adjustable work offset
- Offset target, basis reference

Setting up the machine

2.6 Measuring the workpiece zero

- Offset target, global basis work offset
- Offset target, channel-specific basis work offset



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Note

#### "Measuring only" for automatic measuring

If "Measuring only" is selected as offset target, then instead of the "Set WO" softkey, the "Calculate" softkey is displayed.

The measuring versions "Set edge", "Rectangular pocket", "Rectangular spigot", "1 circular spigot" and "1 hole" are an exception. For these single-point measurements, for "Measuring only" neither the "Set WO" softkey nor the "Calculate" softkey is listed.

#### Preconditions

- The automatic measurement in the JOG mode is completely installed and functional in the default setting of the control.
- When tool type 710 is active, the automatic measuring functions are always executed in the JOG mode.
- Define the user-specific settings (e.g. measuring velocity, length of the measuring distance) using the appropriate parameters.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### References

Information on user-specific settings is provided in the Chapter "Measuring in the JOG mode".

Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

#### Selecting the measuring plane

The measuring plane (G17,18,19) can be selected to flexibly adapt to measuring tasks. If the measuring plane selection is not activated, then the measurement is performed based on the currently active measuring plane.

2.6 Measuring the workpiece zero

# Selecting the probe number and the calibration data set number

Workpiece probe calibration data fields can be selected using this function. For different measuring situations, in order to guarantee a high measuring accuracy, it may be necessary to save the corresponding calibration data in different data fields, which can then be selected for the measuring tasks.

If the probe number selection is not activated, then probe number "one" is always used.

# Selecting the work offset as basis for the measurement

A work offset can be selected as measurement basis to flexibly adapt to the measuring tasks.

If the work offset selection as measurement basis is not activated, then the measurement refers to the currently active work offset.

# Measuring sequence

To obtain the desired measuring results, you must keep to the measuring point sequence shown in the help displays.

You can reject measuring points and then measure them again. This is done by pressing the softkey that is currently active (measured value).

# Measuring only

If you "only" want to measure the workpiece zero, the measured values are calculated and displayed without changing the coordinate system.

# Work offset

You usually store the measured workpiece zero in a work offset. The HMI allows rotations and offsets to be measured.

# Zero point

The measurement values for the offsets are stored in the coarse offset and the relevant fine offsets are deleted. If the zero point is stored in a non-active work offset, an activation window is displayed in which you can activate this work offset directly.



# Machine manufacturer

Please refer to the machine manufacturer's specifications.

## Aligning

Alignment can be performed either by rotating the coordinate system or by rotating the workpiece with a rotary axis. If your machine is equipped with two rotary axes and the "swivel" function is set up, you can also align an inclined plane.

### Rotary axes

If your machine has rotary axes, you can include these rotary axes in the measurement and setup procedure. If you store the workpiece zero in a work offset, rotary axis positioning may be necessary in the following cases.

- Correcting the work offset requires you to position the rotary axes to align the workpiece parallel with the coordinate system, e.g. with "Align edge".
- Correcting the work offset rotates the workpiece coordinate system, which should align the tool perpendicular to the plane, e.g. for "Align plane".

You are supported by one or two activation windows when you position the rotary axes (see Corrections after measuring the zero point (Page 99)").

You can only select "Rotary axis <name of rotary axis>" for the "Angle corr." parameter, if your machine has rotary axes.

They must also be assigned to geometry axes via the machine data.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# 2.6.2 Sequence of operations

To measure the workpiece zero, the workpiece probe must always be located or set perpendicular to the measuring plane (machining plane) (e.g. using "Align plane").

For the measuring versions "Set edge", "Distance 2 edges", "Rectangular pocket" and "Rectangular spigot", the workpiece must first be aligned parallel to the coordinate system.

To do this, it may be necessary to perform the measuring process in several steps.

#### Possible step sequences

- 1. "Align plane" (to align the workpiece probe perpendicular to the plane)
- 2. "Align edge" (to align the workpiece parallel to the coordinate system)
- 3. "Set edge" or "Distance 2 edges" of "Rectangular pocket" or

"Rectangular spigot", to define the workpiece zero.

- OR -

1. "Align plane" (to align the workpiece probe perpendicular to the plane)

2. "Corner" or "2 holes" or "2 spigots", to align the the coordinate system parallel to the workpiece and to determine the workpiece zero)

### **Pre-positioning**

If you want to preposition a rotary axis before measuring with "Align edge", move the rotary axis so that your workpiece is approximately parallel to the coordinate system.

Set the relevant rotary axis angle to zero with "Set WO". Measurement with "Align edge" will then correct the value for rotary axis offset or include it in the coordinate rotation and align the workpiece edge precisely.

If you want to preposition your workpiece with "Align plane" prior to measurement, you can set the required angular values under "Manual swivel". With "Set zero plane"you transfer the resulting rotations into the active work offset.

The measurement with "Align plane" will then correct the value for the coordinate rotations and precisely align the workpiece.

If the function "Swivel Manual" is set up on your machine, we recommend that you perform swivel to zero before starting measurement. In that way, you will ensure that the rotary axis positions match the actual coordinate system.

# 2.6.3 Examples with manual swivel

Two typical examples demonstrate the interaction and the use of "Measure workpiece" and "Manual swivel" when measuring and aligning workpieces.

## First example

The following steps are required when remachining a cylinder head with 2 holes on an inclined plane.

- 1. Clamp the workpiece
- 2. T,S,M

Load the probe and activate the desired work offset.

3. Pre-position the workpiece

Manually rotate the rotary axes until the inclined surface is almost perpendicular to the tool axis.

4. Manual swivel

Select "direct" swivel, press the "Teach rotary axes" softkey and press <CYCLE START> key.

5. Manual swivel

Apply "Set zero plane" to store the resulting rotations in the work zero.

6. Measure workpiece

Apply "Align plane" to correct the alignment of the workpiece.

7. Measure workpiece

Apply "2 holes" to define the rotation and offset in the XY plane.

8. Measure workpiece

Apply "Set edge Z" to define the offset in Z.

9. Start part program to remachine under AUTO.

Start the program with swivel zero.

### Second example

Measuring workpieces in swiveled states. The workpiece is to be probed in the X direction even though the probe cannot approach the workpiece in the X direction because of an obstructing edge (e.g. due to clamping elements). However, with a swivel movement, the measurement in the X direction can be replaced by a measurement in the Z direction.

- 1. Clamp the workpiece.
- 2. T,S,M

Load the probe and activate the desired work offset.

3. Manual swivel

With "direct" swiveling enter the required rotary axis positions or with "axis by axis" the required rotations (e.g. Y=-90) and <CYCLE START>.

4. Measure workpiece

Apply "Set edge Z": The measured offset in Z is converted and entered as an X value in the chosen work offset.

# 2.6.4 Calibrating the electronic workpiece probe

When the electronic probes are attached to the spindle, clamping tolerances usually occur. This can lead to measurement errors.

In addition, you need to determine the trigger points of the probe relative to the spindle center (trigger points).

Therefore, you need to calibrate the electronic probe. The radius is calibrated in a setting ring (calibration ring) or a hole, the length is calibrated on a surface. The diameter of the setting ring and the dimension of the surface in the Z direction (for G17) must be precisely known and this is entered into the corresponding entry field when calibrating the probe. The diameter of the workpiece probe ball and its length 1 must be stored in the tool list.

# Procedure

- 1. Load the workpiece probe into the spindle.
- 2. Move the workpiece probe into the hole and position it in the approximate center of the hole.
- 3. Select "JOG" mode in the "Machine" operating area.







4.

5.

- Press the "Workpiece Zero" and "Calibrate Probe" softkeys. The "Calibrate Probe" window opens.
- Length
- Press the "Length" or "Radius" softkey.

offset during calibration (G54...G57).



)

SELECT

CYCLE START

- 6. In PL, select the working plane (e.g. G17...G19) and the effective work
- 7. When calibrating the length of the workpiece probe in Z0, enter the reference point of the surface based on the active work offset (e.g. of the workpiece or the machine table).

When calibrating the probe ball radius, enter a  $\varnothing$  corresponding the diameter of the calibration bore.

8. Press the <CYCLE START> key.

The calibration starts.

When the length is calibrated, the length of the workpiece probe is calculated and entered in the tool list.

When calibrating the radius, the exact hole center point is determined first. Then the four trigger points on the inside wall of the hole are approached.

This procedure is carried out automatically twice: First with 180° (to the starting position of the working spindle) and then in its starting position.

# Note

# User-specific defaults

- "Setting ring diameter" For the entry field "Diameter setting ring" (diameter, reference piece), fixed values can be separately entered at parameters for each probe number (calibration data set number). If these parameters are assigned, the values saved there are displayed in the entry field "Diameter setting ring"; however, they can no longer be changed there.
- "Height of the reference surface in the infeed axis" For the entry field "Height of the reference surface" fixed values can be separately entered at parameters for each probe number (calibration data set number). If these parameters are assigned, the values saved there are displayed in the entry field "Height of the reference surface"; however, they can no longer be changed there.

Please refer to the machine manufacturer's specifications.

# 2.6.5 Setting the edge

The workpiece lies parallel to the coordinate system on the work table. You measure one reference point in one of the axes (X, Y, Z).

## Precondition

You can insert any tool in the spindle for scratching when measuring the workpiece zero manually.

- OR -

An electronic workpiece probe is inserted in the spindle and activated when measuring the workpiece zero automatically.

2.6 Measuring the workpiece zero

# Procedure

Machine	1.	Select the "Machine" operating area and press the <jog> key.</jog>
Meas. workp.	2.	Press the "Workpiece zero" and "Set edge" softkeys. The "Set edge" window opens.
SELECT	3.	Select "Measuring only" if you only want to display the measured values.
SELECT	4.	<ul> <li>OR -</li> <li>In the selection box, select the desired work offset in which you want to store the zero point.</li> </ul>
Select work offs. G54 G599		<ul> <li>- OR -</li> <li>Press the "Select WO" softkey to select an adjustable work offset.</li> <li>In the window "Work offset – G54 G599", select a work offset, in which the zero point should be saved and press the "In manual" softkey.</li> <li>You return to the measurement window.</li> </ul>
ln manual		
x  Z	5.	Use the softkeys to select in which axis direction you want to approach the workpiece first.
SELECT	6.	Select the measuring direction (+ or -) you want to approach the workpiece in.
	7.	For Z0, the workpiece is always approached in the Z minus direction. In X0, Y0, or Z0, specify the setpoint position of the workpiece edge. The setpoint position corresponds, e.g. to the dimension specifications of the workpiece edge from the workpiece drawing.
CYCLE START	8.	Traverse the workpiece probe close to the workpiece edge that you wish to measure and press the <cycle start=""> key in order to measure the workpiece zero automatically.</cycle>

#### Note

#### Settable work offsets

The labeling of the softkeys for the adjustable work offsets varies, i.e. the selectable work offsets configured at the machine are displayed (examples: G54...G57, G54...G505, G54...G599).

Please refer to the machine manufacturer's specifications.

## 2.6.6 Edge measurement

The following options are available to you when measuring an edge:

#### Aligning the edge

The workpiece lies in any direction, i.e. not parallel to the coordinate system on the work table. By measuring two points on the workpiece reference edge that you have selected, you determine the angle to the coordinate system.

#### Distance between 2 edges

The workpiece lies parallel to the coordinate system on the work table. You measure distance L of two parallel workpiece edges in one of the axes (X, Y, or Z) and determine its center.

#### Precondition

You can insert any tool in the spindle for scratching when measuring the workpiece zero manually.

- OR -

An electronic workpiece probe is inserted in the spindle and activated when measuring the workpiece zero automatically.

Select the "Machine" operating area and press the <JOG> key.

#### Procedure

М

1.

2.

3.

Machine





- Press the "Workpiece zero" softkey.
- Press the "Align edge" softkey.

		- OR -
		Press the "Distance between 2 edges" softkey.
		- OR -
SELECT		If these softkeys are not listed, press any vertical softkey (with the exception of "Set edge") and in the drop-down list, select the desired measurement version.
SELECT	4.	Select "Measuring only" if you only want to display the measured values.
		- OR -
SELECT	5.	In the selection box, select the desired work offset in which you want to store the zero point.
		- OR -
Select work offs. G54		Press the "Select WO" softkey to select an adjustable work offset. In the window "Work offset – G54 G599", select a work offset, in which the zero point should be saved and press the "In manual"
G599		softkey.
<b>In</b> manual		You return to the measurement window.
SELECT	6.	Under "Measuring axis", select the axis in which you want to approach the workpiece, and the measuring direction (+ or -).
	7.	Enter the setpoint angle between the workpiece edge and the reference axis.
	8.	Traverse the tool to the workpiece edge.
Store P1	9.	Press the "Save P1" softkey.
Store P2	10.	Reposition the tool and repeat the measuring procedure (step 7) to measure the second point, and then press the "Save P2" softkey.
0 alaulata	11.	Press the "Calculate" softkey.
Calculate		The angle between the workpiece edge and reference axis is calculated and displayed.
		- OR - Press the "Set WO" softkey.
Set WO		With "Set WO", the workpiece edge now corresponds to the setpoint angle.
		The calculated rotation is stored in the work offset.

# Note

### Settable work offsets

The labeling of the softkeys for the adjustable work offsets varies, i.e. the selectable work offsets configured at the machine are displayed (examples: G54...G57, G54...G505, G54...G599).

Please refer to the machine manufacturer's specifications.

## Automatic measurement

P1 stored	1. 2.	Prepare the measurement (see steps 1 to 5 above). Traverse the workpiece probe close to the workpiece edge on which you wish to measure and press the <cycle start=""> key. This starts the automatic measuring process. The position of measuring point 1 is measured and stored.</cycle>
	3.	The "P1 stored" softkey becomes active. Repeat the operation to measure and store P2.
P2 stored	0.	Repeat the operation to measure and store 12.
Calculate	4.	Press the "Calculate" softkey. The angle between the workpiece edge and reference axis is calculated and displayed. - OR -
Set WO		Press the "Set WO" softkey. With "Set WO", the workpiece edge now corresponds to the setpoint angle. The calculated rotation is stored in the correction target that you have selected.

# 2.6.7 Measuring a corner

You have the option to measure workpiece corners, which are defined by a right angle (90°) or any inner angle.

#### Measuring a right-angled corner

The workpiece corner to be measured has a 90° inner angle and is clamped to the worktable in any position. By measuring 3 points you can determine the corner point (point of intersection of the angle side) in the working plane and angle  $\alpha$  between the workpiece reference edge (line through P1 and P2) and the reference axis in the working plane (1st geometry axis of the working plane).

#### Measuring any corner

The workpiece corner to be measured has any (not right-angled) inner angle and is clamped at any position on the worktable. By measuring 4 points you can determine the corner point (point of intersection of the angle sides) in the working plane and angle  $\alpha$  between the workpiece reference edge (line through P1 and P2) and the reference axis in the working plane (1st geometry axis of the working plane) and inner angle  $\beta$  of the corner.

#### Note

The coordinate system shown in the help displays is always in relation to the currently set workpiece coordinate system.

Please be aware of this if you have swiveled or changed the WCS in any other form.

### Precondition

You can insert any tool in the spindle for scratching when measuring the workpiece zero manually.

- OR -

An electronic workpiece probe is inserted in the spindle and activated when measuring the workpiece zero automatically.

# Procedure

M

1.



۸۸۸,	
~~~	
'MA	
201	
000	

2. Press the "Workpiece zero" softkey.



🚺 Meas. — workp.

> 3. Press the "Right-angled corner" softkey if the workpiece has a rightangled corner.

Select the "Machine" operating area and press the <JOG> key.

- OR -

Press the "Any corner" softkey, if you want to measure a corner not equal to 90°.

- OR -



SELECT

If these softkeys are not listed, press any vertical softkey (with the exception of "Set edge") and in the drop-down list, select the desired measurement version.

4. Select "Measuring only" if you only want to display the measured values.

SELECT	5.	- OR - In the selection box, select the desired work offset in which you want to store the zero point.
Select work offs. G54 G599 In manual		<ul> <li>- OR -</li> <li>Press the "Select WO" softkey to select an adjustable work offset.</li> <li>In the window "Work offset – G54 G599", select a work offset, in which the zero point should be saved and press the "In manual" softkey.</li> <li>You return to the measurement window.</li> </ul>
SELECT	6.	Select the corner (inside corner or outside corner) that you wish to measure and its position (position 1 position 4). The position of the measuring points appear in the help display.
	7.	Specify the setpoint of the workpiece corner (Z0, X0) you want to measure.
	8.	Traverse the tool (acc. to help display) to the first measuring point P1 if you are measuring manually.
Store P1	9.	Press the "Save P1" softkey. The coordinates of the first measuring point are measured and stored.
Store P2 Store P3	10.	Reposition the spindle holding the tool each time, approach measuring points P2 and P3 and press the "Save P2" and "Save P3" softkeys.
Store P4	11.	Repeat the procedure to measure the fourth measuring point when you measure any corner.
Calculate	12.	Press the "Calculate" softkey. The corner point and angle $\alpha$ are calculated and displayed OR -
Set WO	13.	Press the "Set WO" softkey. The corner point now corresponds to the setpoint position. The calculated offset is stored in the work offset.

#### Note

#### Settable work offsets

The labeling of the softkeys for the adjustable work offsets varies, i.e. the selectable work offsets configured at the machine are displayed (examples: G54...G57, G54...G505, G54...G599).

Please refer to the machine manufacturer's specifications.

### Automatic measurement

	1.	Prepare the measurement (see steps 1 to 6 above).
CYCLE START	2.	Approach measuring point P1 with the workpiece probe and press the <cycle start=""> key.</cycle>
JAN		This starts the automatic measuring process. The position of measuring point 1 is measured and stored.
P1 stored		The "P1 stored" softkey becomes active.
P2 stored	3.	Repeat the operation to measure and store points P2 and P3.
P3 stored		
P4 stored		If you are measuring a corner not equal to 90°, repeat the procedure to measure and store point P4.
Calculate	4.	Press the "Calculate" softkey.
Udiculate		The corner point and angle $\alpha$ are calculated and displayed.
		- OR -
Set WO		Press the "Set WO" softkey.
		The corner point now corresponds to the setpoint position. The calculated offset is stored in the offset target that you have selected.

# 2.6.8 Measuring a pocket and hole

You can measure rectangular pockets and one or more holes and then align the workpiece.

#### Measuring a rectangular pocket

The rectangular pocket must be aligned at right-angles to the coordinate system. By automatically measuring 4 points inside the pocket, its length, width and center point can be determined.

### Measuring 1 hole

The workpiece with the hole to be measured is clamped to the work table in any position. In the hole, 4 points are automatically measured, and from this measurement, the diameter and center point of the hole are determined.

#### Measuring 2 holes

The workpiece with the two holes to be measured is clamped to the work table in any position. 4 points are automatically measured in both holes and the hole centers are calculated from them. Angle  $\alpha$  is calculated from the connecting line between both center points and the reference axis, and the new zero point that corresponds to the center point of the 1st hole is determined.

#### Measuring 3 holes

The workpiece with the three holes to be measured is clamped to the work table in any position. 4 points are automatically measured in the three holes and the hole centers are calculated from them. A circle is placed through the three center points. The center point and the diameter are determined from this circle. This center point represents the new workpiece zero to be determined. When an angular offset is selected, the base angle of rotation  $\alpha$  can also be determined.

#### Measuring 4 holes

The workpiece with the four holes to be measured is clamped to the work table in any position. 4 points are automatically measured in the four holes and the hole centers are calculated from them. Two hole center points are diagonally connected in each case. The point of intersection is determined from the two lines that are obtained. This point of intersection represents the new workpiece zero to be determined. When an angular offset is selected, the base angle of rotation  $\alpha$  can also be determined.

#### Note

#### "Measuring only" for automatic measuring

If "Measuring only" is selected as offset target, then instead of the "Set WO" softkey, the "Calculate" softkey is displayed.

The measuring versions "Rectangular pocket" and "1 hole" are an exception. For these single-point measurements, for "Measuring only" neither the "Set WO" softkey nor the "Calculate" softkey is listed.

#### Note

You can only measure 2, 3, and 4 holes automatically.

### Precondition

You can insert any tool in the spindle for scratching when measuring the workpiece zero manually.

- OR -

An electronic workpiece probe is inserted in the spindle and activated when measuring the workpiece zero automatically.

2.6 Measuring the workpiece zero

# Procedure

Machine	1.	Select the "Machine" operating area and press the <jog> key.</jog>
Meas.	2.	Press the "Workpiece zero" softkey.
030	3.	Press the "Rectangular pocket" softkey.
		- OR -
<b>®</b>		Press the "1 hole" softkey.
		- OR -
SELECT		If these softkeys are not listed, press any vertical softkey (with the exception of "Set edge") and in the drop-down list, select the desired measurement version.
SELECT	4.	Select "Measuring only" if you only want to display the measured values.
		- OR -
SELECT	5.	In the selection box, select the desired work offset in which you want to store the zero point.
		- OR -
Select		Press the "Select WO" softkey to select an adjustable work offset.
work offs. G54 G599		In the window "Work offset – G54 G599", select a work offset, in which the zero point should be saved and press the "In manual" softkey.
		You return to the measurement window.
In manual		
	6.	Specify the position setpoints (X0/Y0) of the pocket center point or hole center point.
	7.	Traverse the tool to the first/next measuring point if you are measuring manually.
Store	8.	Press the "Save P1" softkey.
P1		The point is measured and stored.

Store P2	9.	Repeat steps 6 and 7 to measure and store measuring points P2, P3 and P4.
Store P4		
Calculate	10.	Press the "Calculate" softkey.
		The length, width, and center point of the rectangular pocket or diameter and center point of the hole are calculated and displayed. - OR -
Set WO		Press the "Set WO" softkey.
		The setpoint position of the center point is stored as a new zero point with "Set WO". The tool radius is automatically included in the calculation.

#### Note

## Settable work offsets

The labeling of the softkeys for the adjustable work offsets varies, i.e. the selectable work offsets configured at the machine are displayed (examples: G54...G57, G54...G505, G54...G599).

Please refer to the machine manufacturer's specifications.

- OR -

- OR -

# Automatic measurement

- 1. Select the "Measure workpiece zero" function (see steps 1 and 2 above).
- 2. Press the "Rectangular pocket" softkey.

Press the "1 hole" softkey.

Press the "2 holes" softkey.



၀နိုစ



- OR -Press the "3 holes" softkey.



- OR -Press the "4 holes" softkey.

		- OR -
		If these softkeys are not listed, press any vertical softkey (with the exception of "Set edge") and in the drop-down list, select the desired measurement version.
	3.	Traverse the workpiece probe to approximately the center above the rectangular pocket or the hole or for several, above the first hole to be measured.
	4.	Specify whether you want "Measurement only" or in which work offset you want to store the zero point.
Rectangular pocket	5.	<ul> <li>If you do make any entry in the entry field "L" length (1st geometry axis of the working plane) or "W" width (2nd geometry axis of the working plane) of the pocket, then the axis moves with the measuring feedrate from the starting point.</li> <li>If the measuring stroke does not reach the edge, then this data must be approximately entered. However, the measuring sequence is then also shortened as part of the measuring distance is moved with rapid traverse.</li> </ul>
		- OR -
1 hole		<ul> <li>If you do not make any entry in the entry field "Øhole", then the axis moves with the measuring feedrate from the starting point. If the measuring stroke does not reach the edge of the hole, then the approximate diameter must be entered. However, the measuring sequence is then also shortened as part of the measuring distance is moved with rapid traverse.</li> <li>Enter an angle in "Probe angle". With the probe angle you can turn</li> </ul>
		the traversing direction of the probe through any angle.
		- OR -
2 holes		• If you do not make any entry in the entry field "Øhole", then the axis moves with the measuring feed from the starting point. If the measuring stroke does not reach the edge of the hole, then the approximate diameter must be entered. However, the measuring sequence is then also shortened as part of the measuring distance is moved with rapid traverse.
		<ul> <li>In "Angle offs.", select entry "Coord. rotation".</li> </ul>
		- OR -
		In "Angle offs.", select the "Rotary axis A, B, C" entry.
		Enter the setpoint angle.
		<ul> <li>Specify the position setpoints (X1/Y1) for the center point of the first hole.</li> </ul>
		V4 and V4 and ank active if the UC and instational entry is cale at a

X1 and Y1 are only active, if the "Coor. rotation" entry is selected. - OR -

3 holes		<ul> <li>If you do not make any entry in the entry field "Øhole", then the axis moves with the measuring feed from the starting point. If the measuring stroke does not reach the edge of the hole, then the approximate diameter must be entered. However, the measuring sequence is then also shortened as part of the measuring distance is moved with rapid traverse.</li> <li>In "Angle offs." select entry "No".</li> <li>OR -</li> <li>In "Angle offs." select entry "Yes" if you want alignment to be performed with coordinate rotation.</li> <li>Enter the setpoint angle.</li> <li>The angle entered here refers to the 1st axis of the working plane (X/Y plane). This input field only appears if you specified "Yes" for "Angle offs."</li> <li>Specify setpoint positions X0 and Y0.</li> <li>These determine the center point of the circle on which the center points of the three holes are to lie.</li> <li>OR -</li> </ul>
4 holes		<ul> <li>If you do not make any entry in the entry field "Øhole", then the axis moves with the measuring feed from the starting point. If the measuring stroke does not reach the edge of the hole, then the approximate diameter must be entered. However, the measuring sequence is then also shortened as part of the measuring distance is moved with rapid traverse.</li> <li>In "Angle offs." select entry "No".</li> </ul>
		- OR -
		<ul> <li>In "Angle offs." select entry "Yes" if you want alignment to be performed with coordinate rotation.</li> </ul>
		Enter the setpoint angle.
		The angle entered here refers to the 1st axis of the working plane (X/Y plane). This input field only appears if you specified "Yes" for "Angle offs."
		<ul> <li>Specify setpoint positions X0 and Y0.</li> </ul>
		These determine the point of intersection of the lines connecting the hole center points.
$\mathbf{r}$	7.	Press the <cycle start=""> key.</cycle>
CYCLE START		The tool automatically probes 4 points of the inner sides of the pocket or hole in succession.
		After the measurement has been successfully completed, the "P1 stored" softkey becomes active.
CYCLE START	8.	Then move the tool approximately to the center of the second, third, and fourth hole and press the <cycle start=""> key.</cycle>
		After measuring points P2, P3, and P4 have been successfully measured, the "P2 stored", "P3 stored", and "P4 stored" softkeys become active.

Calculate	9.	Press the "Calculate" or "Set WO" softkey.
Set WO		
Rectangular pocket		The length, width, and center point of the rectangular pocket are calculated and displayed.
		For "Set WO", the setpoint position of the center point is stored as new zero point.
1 hole		The diameter and center point of the hole are calculated and displayed.
		The tool automatically probes 4 points of the inside wall of the hole one after the other and the setpoint position of the center point is stored as the new zero point.
2 holes		The tool automatically probes 4 points of the inside wall of the first hole successively and after pressing <cycle start=""> again probes the 4 points of the inside wall of the second hole.</cycle>
		The angle between the line connecting the center points and the reference axis is calculated and displayed.
		With "Set WO", the center point of the first hole now corresponds to the position setpoint. The calculated rotation is stored in the work offset.
3 holes		The tool automatically probes 4 points of the inside wall of the first hole successively and after pressing <cycle start=""> again, then the 4 points of the inside wall of the second or third hole are successively probed.</cycle>
		The center point and the diameter of the circle on which the three hole center points lie are calculated and displayed. If you selected entry "Yes" for "Angle offs.", the angle $\alpha$ is additionally calculated and displayed.
		With "Set WO", the center point of the first hole now corresponds to the position setpoint. The calculated rotation is stored in the work offset.
4 holes		The tool automatically probes 4 points of the inside wall of the first hole successively. After pressing <cycle start=""> again, the tool automatically probes the 4 points of the inside wall of the second, third and fourth holes.</cycle>
		The hole center points are connected diagonally and the intersection point of the two connecting lines calculated and displayed. If you selected entry "Yes" for "Angle offs.", the angle $\alpha$ is additionally calculated and displayed.
		With "Set WO", the intersection point now corresponds to the position setpoint. The calculated rotation is stored in the work offset.

# 2.6.9 Measuring a spigot

You have the option to measure and align rectangular spigots, and one or more circular spigots.

#### Measuring a rectangular spigot

The rectangular spigot should be aligned at right-angles to the coordinate system. By measuring four points at the spigot you can determine the length, width, and center point of the spigot.

Please note that the straight lines between points P1 and P2 or P3 and P4 must intersect with one another, in order that a measurement result is displayed.

#### Measuring 1 circular spigot

The workpiece is located anywhere on the work table and has a circular spigot. You can determine the diameter and center point of the spigot with four measuring points.

#### Measuring 2 circular spigots

The workpiece is located anywhere on the work table and has 2 spigots. 4 points are automatically measured at the two spigots and the spigot centers are calculated from them. The angle  $\alpha$  is calculated from the connecting line between both center points and the reference axis, and the new zero point that corresponds to the center point of the first spigot is determined.

### Measuring 3 circular spigots

The workpiece is located anywhere on the work table and has three spigots. 4 points are automatically measured at the three spigots and the spigot centers are calculated from them. A circle is placed through the three center points and the circle center and circle diameter are determined.

When an angular offset is selected, the base angle of rotation  $\alpha$  can also be determined.

#### Measuring 4 circular spigots

The workpiece is located anywhere on the work table and has four spigots. 4 points are automatically measured at the four spigots and the spigot centers are calculated from them. Two spigot center points are each connected diagonally and the intersection point of the two lines is then determined. When an angular offset is selected, the base angle of rotation  $\alpha$  can also be determined.

#### Note

#### "Measuring only" for automatic measuring

If "Measuring only" is selected as offset target, then instead of the "Set WO" softkey, the "Calculate" softkey is displayed.

The measuring versions "Rectangular spigot" and "1 circular spigot" are an exception. For these single-point measurements, for "Measuring only" neither the "Set WO" softkey nor the "Calculate" softkey is listed.

### Note

You can only measure 2, 3, and 4 circular spigots automatically.

2.6 Measuring the workpiece zero

# Precondition

You can insert any tool in the spindle for scratching when measuring the workpiece zero manually.

An electronic workpiece probe is inserted in the spindle and activated when measuring the workpiece zero automatically.

## Procedure

Machine	1.	Select the "Machine" operating area and press the <jog> key.</jog>
workp.	2.	Press the "Workpiece zero" softkey.
÷	3.	Press the "Rectangular spigot" softkey.
		- OR -
ŵ		Press the "1 circular spigot" softkey.
		- OR -
SELECT		If these softkeys are not listed, press any vertical softkey (with the exception of "Set edge") and in the drop-down list, select the desired measurement version.
SELECT	4.	Select "Measuring only" if you only want to display the measured values.
		- OR -
SELECT		Select the desired work offset in which you want to store the zero point (e.g. basis reference).
		- OR -
Select work offs.		Press the "Select WO" softkey and select the work offset in which the zero point is to be saved in the "Work Offset – G54 G599" window and press the "In manual" softkey.
G599		You return to the "1 Circular Spigot" window.
		The selection of work offsets can differ.
<b>in</b> manual		Please refer to the machine manufacturer's specifications.
	5.	Specify the position setpoints (X0/Y0) of the spigot center point P0.
	6.	Traverse the tool to the first measuring point.

2.6 Measuring the workpiece zero

Store P1	7.	Press the "Save P1" softkey. The point is measured and stored.
Store P2	8.	Repeat steps 6 and 7 to measure and store measuring points P2, P3 and P4.
Store P4		
Calculate	9.	Press the "Calculate" softkey.
		The diameter and center point of the spigot are calculated and displayed.
		- OR -
Set WO		Press the "Set WO" softkey.
		The setpoint position of the center point is stored as a new zero point with "Set WO". The tool radius is automatically included in the calculation.

#### Note

### Settable work offsets

The labeling of the softkeys for the adjustable work offsets varies, i.e. the selectable work offsets configured at the machine are displayed (examples: G54...G57, G54...G505, G54...G599).

Please refer to the machine manufacturer's specifications.

### Automatic measurement

- 1. Select the "Measure workpiece zero" function (see steps 1 and 2 above).
- 2. Press the "Rectangular spigot" softkey.



•; O



- OR -Press the "2 circular spigots" softkey.

Press the "1 circular spigot" softkey.



- OR -Press the "3 circular spigots" softkey.

- OR -

- OR -

0.0 0.0		Press the "4 circular spigots" softkey.
		- OR -
SELECT		If these softkeys are not listed, press any vertical softkey (with the exception of "Set edge") and in the drop-down list, select the desired measurement version.
	3.	Traverse the workpiece probe to approximately the center above the rectangular or circular spigot, or for several, above the first spigot to be measured.
	4.	Specify whether you want "Measurement only" or in which work offset you want to store the zero point.
Rectangular	5.	• Enter the infeed value in "DY" to determine the measuring depth.
spigot		<ul> <li>In field "L" enter the length (1st geometry axis of the working plane) and in field "W" the width (2nd geometry axis of the working plane) of the spigot.</li> </ul>
		- OR -
1 circular		<ul> <li>Enter the approximate diameter of the spigot into "Øspigot".</li> </ul>
spigot		• Enter an angle in "Probe angle". With the probe angle you can turn the traversing direction of the probe through any angle.
		- OR -
2 circular		<ul> <li>Enter the approximate diameter of the spigot into "Øspigot".</li> </ul>
spigots		• Enter the infeed value in "DY" to determine the measuring depth.
		• In "Angle offs.", select entry "Coor. rotation" or "Rotary axis A, B, C".
		Enter the setpoint angle.
		<ul> <li>Enter the position setpoints (Z0/X0) for the center point of the first spigot.</li> </ul>
		The setpoint angle refers to the 1st axis of the working plane (X/Y plane).
		The input fields for the setpoint positions are only active if you selected the angle offset via coordinate rotation.
		- OR -

3 circular spigots		<ul> <li>Enter the approximate diameter of the spigot into "Øspigot".</li> <li>Enter the infeed value in "DY" to determine the measuring depth.</li> <li>In "Angle offs.", select entry "No", or in "Angle offs." select entry "Yes" if you want to align using coordinate rotation.</li> <li>Specify the setpoint angle if you selected entry "Yes" for "Angle offs."</li> <li>Enter the setpoint positions Z0 and X0 to determine the center point of the circuit on which the center points of three spigots lie.</li> <li>The setpoint angle refers to the 1st axis of the working plane (X/Y plane). This input field only appears if you specified "Yes" for "Angle offs."</li> <li>OR -</li> </ul>
4 circular spigots		<ul> <li>Enter the approximate diameter of the spigot into "Øspigot".</li> <li>Enter the infeed value in "DZ" to determine the measuring depth.</li> <li>In "Angle offs.", select entry "Yes" if you want to align using coordinate rotation or select in "Angle offs." the entry "No".</li> <li>Enter the setpoint angle.</li> <li>Enter the setpoint positions X0 and Y0 to determine the point of intersection of the connecting lines between the spigot center points.</li> <li>The setpoint angle refers to the 1st axis of the working plane (X/Y)</li> </ul>
	4.	plane). This input field only appears if you specified "Yes" for "Angle offs." Press the <cycle start=""> key.</cycle>
P1 stored		This starts the automatic measuring process. The tool automatically probes 4 points in succession of the rectangular or spigot outer wall or the outer wall of the first spigot if several spigots are to be measured. After the measurement has been successfully completed, the center of the spigot is determined and the "P1 stored" softkey becomes active.
CYCLE START	5	If you are measuring several spigots, then move the tool approximately to the center of the second, third, and fourth spigot and press the <cycle start=""> key.</cycle>



START

Milling Operating Manual, 07/2010, 6FC5398-7CP40-0BA0

P2 stored	After the measurement has been successfully completed, P2, P3 and P4 are stored and the softkeys "P2 stored", "P3 stored", and "P4 stored" become active.
P4 stored	
Calculate Set WO	Press the or "Calculate" or "Set WO"softkey.
Rectangular spigot	The length, width, and center point of the rectangular spigot are calculated and displayed.
	For "Set WO", the setpoint position of the center point is stored as new zero point. The tool radius is automatically included in the calculation.
1 spigot	The diameter and center point of the spigot are calculated and displayed.
	For "Set WO", the setpoint position of the center point is stored as new zero point. The tool radius is automatically included in the calculation.
2 spigots	The angle between the line connecting the center points and the reference axis is calculated and displayed.
	For "Set WO", the center point of the first spigot now corresponds to the position setpoint. The calculated rotation is stored in the work offset.
3 spigots	The center point and the diameter of the circle on which the three spigot center points lie are calculated and displayed. If you selected entry "Yes" in "Coor. rotation", then angle $\alpha$ is additionally calculated and displayed.
	For "Set WO", the center point of the circle now corresponds to the position setpoint. The calculated rotation is stored in the work offset.
4 spigots	The spigot center points are connected diagonally and the intersection point of the two connecting lines calculated and displayed. If you selected entry "Yes" in "Coor. rotation", then angle $\alpha$ is additionally calculated and displayed.
	For "Set WO", the intersection point now corresponds to the position setpoint. The calculated rotation is stored in the work offset.

# 2.6.10 Aligning the plane

You can measure an inclined plane of a workpiece in space and determine rotation angles  $\alpha$  and  $\beta$ . By subsequently performing coordinate rotation, you can align the tool axis perpendicular to the workpiece plane.

In order to determine the position of the plane in space, three different points are measured along the tool axis. To vertically align the tool axis, the "Swivel" function or the 5 axis transformation (TRAORI) must be set-up at the machine.

In order to be able to measure the plane, the surface must be flat.

### Precondition

You can insert any tool in the spindle for scratching when measuring the workpiece zero manually.

An electronic workpiece probe is inserted in the spindle and activated when measuring the workpiece zero automatically.

### Procedure



۰۰۰ الم 1.

Select the "Machine" operating area and press the <JOG> key.



SELECT

SELECT

- Press the "Workpiece zero" and "Align plane" softkeys.
   The "Align plane" window opens.
- 3. Select "Measuring only" if you only want to display the measured values.
  - OR -

Select the desired work offset in which you want to store the zero point (e.g. basis reference).

#### - OR -



Press the "Select WO" softkey and select the work offset in which the zero point is to be saved in the "Work Offset – G54  $\dots$  G599" window and press the "In manual" softkey.

You return to the appropriate measurement window.

You return to the "Align plane" window.

The selection of work offsets can differ.

Please refer to the machine manufacturer's specifications.

4. Traverse the tool to the first measuring point that you want to determine.

Store P1	5.	Press the "Save P1" softkey.
Store P2	6.	Then traverse the tool to the second and third measuring point and press the "Save P2" and "Save P3" softkeys.
Store P3		
Set	7.	Press the "Set WO" or "Calculate" softkey.
WO		Angles $\alpha$ and $\beta$ are calculated and displayed.
Calculate		For "Set WO" the angle offset is stored in the work offset.

# 2.6.11 Defining the measurement function selection

The measurement versions "Set edge", "Align edge", "Rightangled corner", "1 hole" and "1 circular spigot" are listed in the "Measure workpiece zero" in the associated vertical softkey bar.

You have the option of replacing these by softkeys with other measurement versions.



### "Set edge" softkey

The "Set edge" softkey cannot be assigned the softkey of another measurement version.



#### Software option

You require the "Extended operator function" option for the measurement function selection (only for 828D).

# Procedure

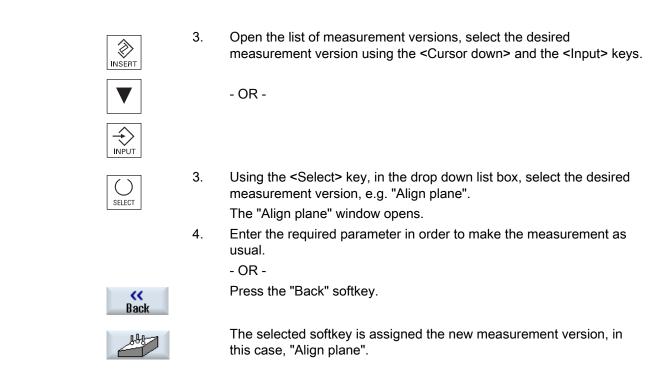


1. The "Measure workpiece zero" function is selected.



2. Press the softkey that you wish to assign to a new measurement version, e.g. "1 circular spigot".

The "1 Circular Spigot" window opens.



# 2.6.12 Corrections after measurement of the zero point

If you store the workpiece zero in a work offset, changes to the coordinate system or axis positions might be necessary in the following cases.

- Correcting the work offset causes the workpiece coordinate system to rotate, after which the tool can be aligned perpendicularly to the plane.
- Correcting the work offset necessitates positioning of the rotary axis in order to align the workpiece parallel with the coordinate system

Activation windows help you to adapt the coordinate system and the axis positions.

### Procedure

#### Activating work offset

You stored the workpiece zero in a work offset that was not active during measurement.

When you press the "Set WO" softkey, the activation window opens

asking whether you want to "Activate work offset Gxxx now?".

- Set 1. W0 2.
  - . Press the "OK" softkey to activate the corrected work offset.

1.

Rotating the workpiece coordinate system makes it necessary to realign the tool to the plane. The activation window asking whether you want to "Position

measuring probe perpendicular to plane?" is displayed.



The query "Positioning by swiveling! Retract?" is displayed.

Select "Yes" if you want to swivel into the plane.



2. Select the retraction method you want to use.



3. Press the <CYCLE START> key.

When the axis has been retracted the tool is realigned with the help of the swivel cycle.

You can now measure again.

### Positioning a rotary axis and entering a feedrate

Once you have measured the workpiece zero you must reposition the rotary axis.

Note:

Retract the probe to a safe position before the rotary axis should move.

The activation window asking whether you want to "Position rotary axis X to align?" is displayed.



- Select "Yes" if you want to position the rotary axis. An input field for the feedrate and the softkey "Rapid traverse" are displayed.
- Rapid
- 2. Press the "Rapid traverse" softkey to enter the feedrate in rapid traverse.

- OR -

3.

CYCLE START Press the <CYCLE START> key.

Enter the desired feedrate into input field "F".

The rotary axis is repositioned.

# 2.7 Work offsets

Following reference point approach, the actual value display for the axis coordinates is based on the machine zero (M) of the machine coordinate system (Machine). The program for machining the workpiece, however, is based on the workpiece zero (W) of the workpiece coordinate system (Work). The machine zero and workpiece zero are not necessarily identical. The distance between the machine zero and the workpiece zero depends on the workpiece type and how it is clamped. This work offset is taken into account during execution of the program and can be a combination of different offsets.

Following reference point approach, the actual value display for the axis coordinates is based on the machine zero of the machine coordinate system (Machine).

The actual value display of the positions can also refer to the SZS coordinate system (settable zero system). The position of the active tool relative to the workpiece zero is displayed.

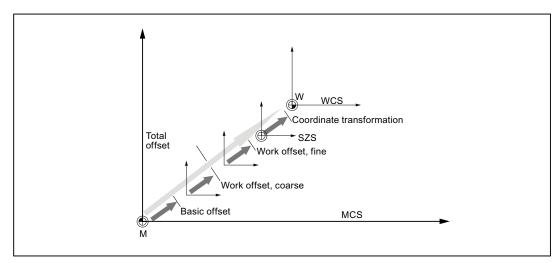


Figure 2-1 Work offsets

When the machine zero is not identical to the workpiece zero, at least one offset (base offset or work offset) exists in which the position of the workpiece zero is saved.

### Base offset

The base offset is a work offset that is always active. If you have not defined a base offset, its value will be zero. The base offset is specified in the "Work offset - Base" window.

### Coarse and fine offsets

Every work offset (G54 to G57, G505 to G599) consists of a coarse offset and a fine offset. You can call the work offsets from any program (coarse and fine offsets are added together).

2.7 Work offsets

You can save the workpiece zero, for example, in the coarse offset, and then store the offset that occurs when a new workpiece is clamped between the old and the new workpiece zero in the fine offset.

### Note

### Deselect fine offset

You have the option of deselecting the fine offset via machine data \$MN\_MM\_FRAM\_FINE\_TRANS.

### See also

Actual value window (Page 33)

# 2.7.1 Display active zero offset

The following work offsets are displayed in the "Work Offset - Active" window:

- Work offsets, for which active offsets are included, or for which values are entered.
- adjustable work offsets
- Total work offset

This window is generally used only for monitoring.

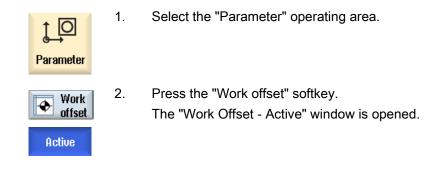
The availability of the offsets depends on the setting.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure



# Note

### Further details on work offsets

If you would like to see further details about the specified offsets or if you would like to change values for the rotation, scaling or mirroring, press the "Details" softkey.

# 2.7.2 Displaying the work offset "overview"

The active offsets or system offsets are displayed for all set-up axes in the "Work Offset - Overview" window.

In addition to the offset (course and fine), the rotation, scaling and mirroring defined using this are also displayed.

This window is generally used only for monitoring.

# Display of active work offsets

Work offsets	
DRF	Displays the handwheel axis offset.
Basic reference	Displays the additional work offsets programmed with \$P_SETFRAME. Access to the system offsets is protected via a keyswitch.
External WO frame	Displays the additional work offsets programmed with \$P_EXTFRAME.
Total base WO	Displays all effective basis offsets.
G500	Displays the work offsets activated with G54 - G599.
	Under certain circumstances, you can change the data using "Set WO", i.e. you can correct a zero point that has been set.

# 2.7 Work offsets

Work offsets	
Tool reference	Displays the additional work offsets programmed with \$P_TOOLFRAME.
Workpiece reference	Displays the additional work offsets programmed with \$P_WPFRAME.
Programmed WO	Displays the additional work offsets programmed with \$P_PFRAME.
Cycle reference	Displays the additional work offsets programmed with \$P_CYCFRAME.
Total WO	Displays the active work offset, resulting from the total of all work offsets.

## Procedure



- 1. Select the "Parameter" operating area.
- 2 Press the "Work offset" and "Overview" softkeys. The "Work Offsets - Overview" window opens.

# 2.7.3 Displaying and editing base zero offset

The defined channel-specific and global base offsets, divided into coarse and fine offsets, are displayed for all set-up axes in the "Work offset - Base" window.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure

1. Select the "Parameter" operating area.





2.

Press the "Work offset" softkey.

2.7 Work offsets

Dage
------

3.

Press the "Base" softkey. The "Work offset - Base" window is opened.

4. You can edit the values directly in the table.

# Note

Activate base offsets

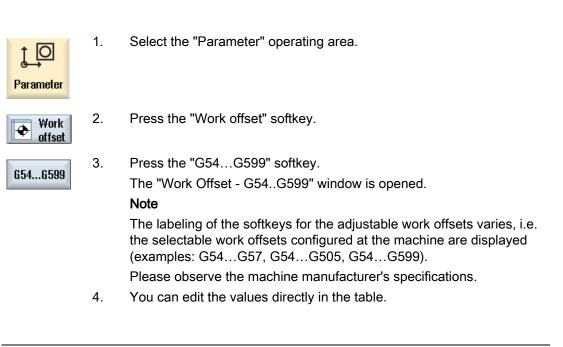
The offsets specified here are immediately active.

# 2.7.4 Displaying and editing settable zero offset

All settable offsets, divided into coarse and fine offsets, are displayed in the "Work Offset - G54..G599" window.

Rotation, scaling and mirroring are displayed.

Procedure



### Note

### Activate settable work offsets

The settable work offsets must first be selected in the program before they have an impact.

### 2.7 Work offsets

# 2.7.5 Displaying the zero offset details

For each work offset, you can display and edit all data for all axes. You can also delete work offsets.

For every axis, values for the following data will be displayed:

- Coarse and fine offsets
- Rotation
- Scaling
- Mirroring



Machine manufacturer

1.

3.

Please refer to the machine manufacturer's specifications.

#### Note

Settings for rotation, scaling and mirroring are specified here and can only be changed here.

### Procedure



Details

- Select the "Parameter" operating area.
- 2. Press the "Work offset" softkey.
  - Press the "Active", "Base" or "G54...G599" softkey. The corresponding window appears.
- 4. Place the cursor on the desired work offset to view its details.
- 5. Press the "Details" softkey.

A window opens, depending on the selected work offset, e.g. "Work Offset - Details: G54 to G599".

6. You can edit the values directly in the table.

OR Press the "Clear offset" softkey to reset all entered values.

W0 +

W0 +
W0 

6. You can edit the values directly in the table.

OR Press the "Clear offset" softkey to reset all entered values.

Press the "WO +" or "WO -" softkey to select the next or previous offset, respectively, within the selected area ("Active", "Base", "G54 to G599") without first having to switch to the overview window.

If you have reached the end of the range (e.g. G599), you will switch automatically to the beginning of the range (e.g. G54).

These value changes are available in the part program immediately or after "Reset".



# Machine manufacturer

Please refer to the machine manufacturer's specifications.



Press the "Back" softkey to close the window.

# 2.7.6 Deleting a work offset

You have the option of deleting zero offsets. This resets the entered values.

### Proceed as follows



1. Select the "Parameter" operating area.



- 2. Press the "Work offset" softkey.
- Active 654...6599
- 3. Press the "Active", "Base" or "G54...G599" softkey.

# 2.7 Work offsets

Details	4.	Press the "Details" softkey.
Clear	5.	Position the cursor on the zero offset you would like to delete.
Offset	6.	Press the "Clear Offset" soft key.

# 2.7.7 Measuring the workpiece zero

# Procedure

Parameter Work	1.	Select the "Parameter" operating area and press the "Work offset" softkey.
6546599	2.	Press the "G54G599" softkey and select the work offset in which the zero point is to be saved.
Work Measure	3.	Press the "Workpiece zero" softkey.
Ye Meas.		You change to the "Set Edge" window in the "JOG" mode.
<b>X</b>	4.	Use the softkeys to select in which axis direction you want to approach the workpiece first.
Z		
	5.	Select the measuring direction (+ or -) you want to approach the workpiece in.
	c	The measuring direction cannot be selected for Z0.
	6.	In X0, Y0, or Z0, specify the setpoint position of the workpiece edge you are approaching.
Set WO		Traverse the tool up to the workpiece edge and press the "Set WO" softkey to measure the workpiece zero.

#### Monitoring axis and spindle data 2.8

#### 2.8.1 Specify working area limitations

The "Working area limitation" function can be used to limit the range within which a tool can traverse in all channel axes. These commands allow you to set up protection zones in the working area which are out of bounds for tool movements.

In this way, you are able to restrict the traversing range of the axes in addition to the limit switches.

# **Preconditions**

You can only make changes in "AUTO" mode when in the RESET condition. These changes are then immediate.

You can make changes in "JOG" mode at any time. These changes, however, only become active at the start of a new motion.

# Procedure

Select the "Parameter" operating area. 1.



2. Press the "Setting data" softkey.



SD Setting

data

The "Working area limit." window appears.

3. Place the cursor in the required field and enter the new values via the numeric keyboard.

The upper or lower limit of the protection zone changes according to your inputs.

4. Click the checkbox to "active" to activate the protection zone.

## Note

You will find all of the setting data in the "Start-up" operating area under "Machine data" via the menu forward key.

2.8 Monitoring axis and spindle data

# 2.8.2 Editing spindle data

The speed limits set for the spindles that must not be under- or overshot are displayed in the "Spindles" window.

You can limit the spindle speeds in fields "Minimum" and "Maximum" within the limit values defined in the relevant machine data.

# Spindle speed limitation at constant cutting rate

In field "Spindle speed limitation at G96", the programmed spindle speed limitation at constant cutting speed is displayed together with the permanently active limitations.

This speed limitation, for example, prevents the spindle from accelerating to the max. spindle speed of the current gear stage (G96) when performing tapping operations or machining very small diameters.

### Note

The "Spindle data" softkey only appears if a spindle is configured.

# Procedure

Parameter





- Press softkeys "Setting data" and "Spindle data". The "Spindles" window opens.
- 3. If you want to change the spindle speed, place the cursor on the "Maximum", "Minimum", or "Spindle speed limitation at G96" and enter a new value.

Setting up the machine 2.9 Displaying setting data lists

# 2.9 Displaying setting data lists

You can display lists with configured setting data.



# Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure



- 1. Select the "Parameter" operating area.
- SD Setting data Data lists

Select

data list

- 2. Press "Setting data" and "Data lists" softkeys. The "Setting data list" window opens.
- 3. Press the "Select data list" softkey and in the "View" list, select the required list with setting data.

2.10 Handwheel assignment

# 2.10 Handwheel assignment

You can traverse the axes in the machine coordinate system (Machine) or in the workpiece coordinate system (Work) via the handwheel.



### Software option

You require the "Extended operator functions" option for the handwheel offset (only for 828D).

All axes are provided in the following order for handwheel assignment:

Geometry axes

When traversing, the geometry axes taken into account the actual machine status (e.g. rotations, transformations). All channel machine axes, which are currently assigned to the geometry axis, are in this case simultaneously traversed.

• Channel machine axes

Channel machine axes are assigned to the particular channel. They can only be individually traversed, i.e. the actual machine state has no influence.

The also applies to channel machine axes, that are declared as geometry axes.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure

1. Select the "Machine" operating area.





Press the <JOG>, <AUTO> or <MDA> key.



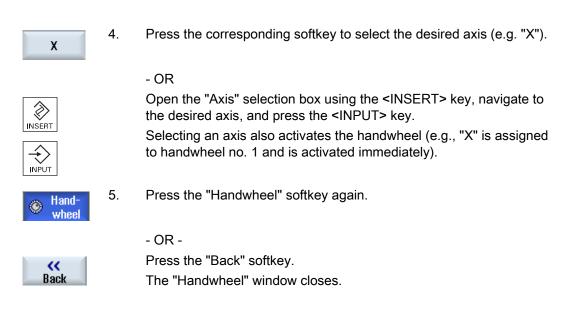
wheel

2.

Press the menu forward key and the "Handwheel" softkey. The "Handwheel" window appears.

A field for axis assignment will be offered for every connected handwheel.

3. Position the cursor in the field next to the handwheel with which you wish to assign the axis (e.g. No. 1).



# Deactivate handwheel



NSERT

INPU<sup>-</sup>

- 1. Position the cursor on the handwheel whose assignment you wish to cancel (e.g. No. 1).
- 2. Press the softkey for the assigned axis again (e.g. "X").

## - OR -

Open the "Axis" selection box using the <INSERT> key, navigate to the empty field, and press the <INPUT> key.

Clearing an axis selection also clears the handwheel selection (e.g., "X" is cleared for handwheel no. 1 and is no longer active).

2.11 MDA

# 2.11 MDA

In "MDA" mode (Manual Data Automatic mode), you can enter G-code commands block-byblock and immediately execute them for setting up the machine.

You can load an MDA program straight from the Program Manager into the MDA buffer. You may also store programs which were rendered or changed in the MDA operating window into any directory of the Program Manager.



## Software option

You require the "Extended operator functions" option to load and save MDA programs (for 828D).

# 2.11.1 Loading an MDA program from the Program Manager

# Proceed as follows

Machine	1.	Select the "Machine" operating area.
MDA	2.	Press the <mda> key.</mda>
		The MDI editor opens.
↑ Load MDI	3.	Press the "Load MDA" softkey.
		A changeover is made into the Program Manager.
		The "Load in MDA" window opens. The program manager is displayed in it.
	4.	Select the program that you would like to edit or execute in the MDA window.
$\checkmark$	5.	Press the "OK" softkey.
OK		The window closes and the program is ready for operation.

# 2.11.2 Saving an MDA program

# Proceed as follows

Machine	1.	Select the "Machine" operating area.
MDA	2.	Press the <mda> key.</mda>
		The MDA editor opens.
	3.	Create the MDA program by entering the G-code commands using the operator's keyboard.
_↓ Save	4.	Press the "Store MDA" softkey.
H MDI		The "Save from MDA : Select save location" window is opened. It shows you a view of the program manager.
	5.	Select the drive to which you want to save the MDA program you created, and place the cursor on the directory in which the program is to be stored.
ОК	6.	Press the "OK" softkey.
		When you place the cursor on a folder, a window opens which prompts you to assign a name. - OR -
		When you place the cursor on a program, you are asked whether the file should be overwritten.
	7.	Enter the name for the rendered program and press the "OK" softkey.
ОК		The program will be saved under the specified name in the selected

directory.

Milling Operating Manual, 07/2010, 6FC5398-7CP40-0BA0 2.11 MDA

# 2.11.3 Executing an MDA program

# Proceed as follows

Machine



- 2. Press the <MDA> key. The MDA editor opens.
- CYCLE START
- Input the desired G-code commands using the operator's keyboard.
   Press the <CYCLE START> key.

The control executes the input blocks.

Select the "Machine" operating area.

When executing the G-code commands, you can control the sequence as follows:

- Executing the program block-by-block
- Testing the program
   Settings under program control

1.

 Setting the test-run feedrate Settings under program control

# 2.11.4 Deleting an MDA program

# Precondition

The MDA editor contains a program that you created in the MDI window or loaded from the program manager.

# Procedure

Delete blocks Press the "Delete blocks" softkey.

The program displayed in the program window is deleted.

# 3.1 General

Always use "JOG" mode when you want to set up the machine for the execution of a program or to carry out simple traversing movements on the machine:

- Synchronize the measuring system of the controller with the machine (reference point approach)
- Set up the machine, i.e. activate manually-controlled motions on the machine using the keys and handwheels provided on the machine control panel.
- You can activate manually controlled motions on the machine using the keys and handwheels provided on the machine control panel while a part program is interrupted.

3.2 Selecting a tool and spindle

# 3.2 Selecting a tool and spindle

# 3.2.1 T, S, M windows

For the preparatory actions in manual mode, tool selection and spindle control are both performed centrally in a screen form.

In manual mode, you can select a tool either by its name or its location number. If you enter a number, a search is performed for a name first, followed by a location number. This means that if you enter "5", for example, and no tool with the name "5" exists, the tool is selected from location number "5".

### Note

Using the location number, you can thus swing around an empty space into the machining position and then comfortably install a new tool.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

Display	Meaning	
Т	Input of the tool (name or location number)	
	You can select a tool from the tool list using the "Select tool" softkey.	
D	Cutting edge number of the tool (1 - 9)	
Spindle	Spindle selection, identification with spindle number	
Spindle M function	∞	
	Q	
	ଦ	
	פ"ה	
Other M functions	Input of machine functions	
	Refer to the machine manufacturer's table for the correlation between the meaning and number of the function.	
G work offset	Selection of the work offset (basic reference, G54 - 57)	
	You can select work offsets from the tool list of settable work offsets via the "Work offset" softkey.	

3.2 Selecting a tool and spindle

Display	Meaning	
Unit of measurement	Selection of the unit of measurement (inch, mm)	
	The setting made here has an effect on the programming.	
Machining plane	Selection of the machining plane (G17(XY), G18 (ZX), G19 (YZ))	
Gear stage	Specification of the gear stage (auto, I - V)	
Stop position	Input of the spindle position in degrees	

### Note

### Spindle positioning

You can use this function to position the spindle at a specific angle, e.g. during a tool change.

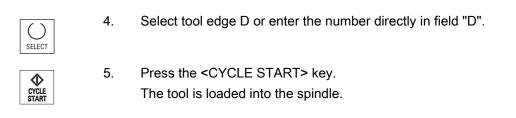
- A stationary spindle is positioned via the shortest possible route.
- A rotating spindle is positioned as it continues to turn in the same direction.

# 3.2.2 Selecting a tool

## Procedure

1. Select the "JOG" operating mode. Μ Machine ۰۰۰ الم 2. Press the "T, S, M" softkey. 📕 Т,S,M 3. Enter the name or the number of the tool T in the input field. - OR -Press the "Select tool" softkey to open the tool list, position the cursor Select on the desired tool and press the "In Manual" softkey. tool The tool is transferred to the "T, S, M... window" and displayed in the In field of tool parameter "T". manual

3.2 Selecting a tool and spindle



# 3.2.3 Starting and stopping a spindle manually

# Procedure

Machine	1.	Select the "JOG" operating mode.
J. T,S,M	2.	Press the "T, S, M" softkey.
	3.	Select the desired spindle (e.g. S1) and enter the desired spindle speed (rpm) in the adjacent input field. The spindle remains stationary.
SELECT	4.	If the machine has a gearbox for the spindle, set the gear stage (e.g. auto).
SELECT	5.	Select a spindle direction of rotation (clockwise or counterclockwise) in the "Spindle M function" field.
CYCLE START	6.	Press the <cycle start=""> key. The spindle rotates.</cycle>
SELECT	7.	Select the "Stop" setting in the "Spindle M function" field.
CYCLE START		Press the <cycle start=""> key. The spindle stops.</cycle>

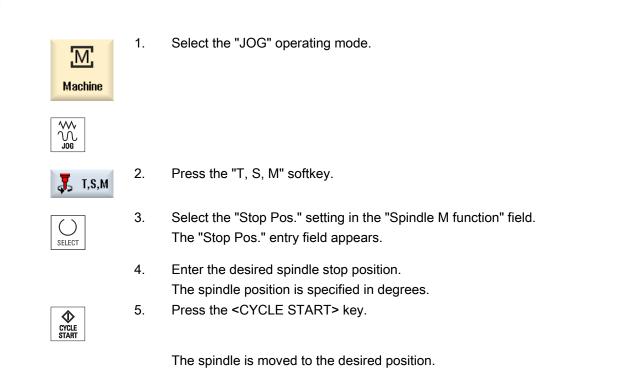
# Note

### Changing the spindle speed

If you enter the speed in the "Spindle" field while the spindle is rotating, the new speed is applied.

# 3.2.4 Position spindle

# Procedure



### Note

You can use this function to position the spindle at a specific angle, e.g. during a tool change.

- A stationary spindle is positioned via the shortest possible route.
- A rotating spindle is positioned as it continues to turn in the same direction.

3.3 Traversing axes

# 3.3 Traversing axes

You can traverse the axes in manual mode via the Increment or Axis keys or handwheels.

During a traverse initiated from the keyboard, the selected axis moves at the programmed setup feedrate. During an incremental traverse, the selected axis traverses a specified increment.

### Set the default feedrate

Specify the feedrate to be used for axis traversal in the set-up, in the "Settings for Manual Operation" window.

# 3.3.1 Traverse axes by a defined increment

You can traverse the axes in manual mode via the Increment and Axis keys or handwheels.

## Procedure





2. Press the <JOG> key.

<b>→</b> I 1	3.	Press keys 1, 10, etc. up to 10000 in order to move the axis in a defined increment.
		The numbers on the keys indicate the traverse path in micrometers or micro-inches.
		Example: Press the "100" button for a desired increment of 100 $\mu m$ (= 0.1 mm).
X	4.	Select the axis to be traversed.
+	5.	Press the <+> or <-> key. Each time you press the key the selected axis is traversed by the defined increment. Feedrate and rapid traverse override switches can be operative.

### Note

When the control is switched on, the axes can be traversed right up to the limits of the machine as the reference points have not yet been approached and the axes referenced. Emergency limit switches might be triggered as a result.

The software limit switches and the working area limitation are not yet operative!

The feed enable signal must be set.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# 3.3.2 Traversing axes by a variable increment

# Procedure

1. Select the "Machine" operating area.



М

Machine

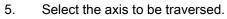
Press the <JOG> key.



Press the "Settings" softkey. The "Settings for manual operation" window is opened. 3.3 Traversing axes

3.	Enter the desired value for the "Variable increment" parameter.
	Example: Enter 500 for a desired increment of 500 µm (0.5 mm).
4.	Press the <inc var=""> key.</inc>

→I [VAR]



- +
- 6. Press the  $\rightarrow$  or  $\rightarrow$  key.

Each time you press the key the selected axis is traversed by the set increment.

Feedrate and rapid traverse override switches can be operative.

# 3.4 Positioning axes

In manual mode, you can traverse individual or several axes to certain positions in order to implement simple machining sequences.

The feedrate / rapid traverse override is active during traversing.

# Procedure



- 1. If required, select a tool.
- 2. Select the "JOG" operating mode.



3. Press the "Positions" softkey.

Specify the desired value for the feedrate F.
 - OR -

The rapid traverse is displayed in field "F".

Press the "Rapid traverse" softkey.

Rapid

5. Enter the target position or target angle for the axis or axes to be traversed.



6. Press the <CYCLE START> key.

The axis is traversed to the specified target position.

If target positions were specified for several axes, the axes are traversed simultaneously.

# 3.5 Swiveling

# 3.5 Swiveling

Manual swivel in the JOG mode provides functions that make it far easier to setup, measure, and machine workpieces with swiveled surfaces.

If you want to create or correct an inclined position, the required rotations of the workpiece coordinate system around the geometry axes (X, Y, Z) are automatically converted into suitable positions of the machine kinematics.

Alternatively, you can program the swivel axes of the machine "directly" and generate a matching workpiece coordinate system for those swivel axis positions. After swiveling, the tool axis (for G17 Z) is always perpendicular to the working plane (for G17 XY).

The swiveled coordinates are maintained in the Reset status and after Power On, if the machine manufacturer has correspondingly set the machine data. With these settings, after a program interrupt, e.g. as a result of a retraction in the +Z direction, you can retract from an inclined hole.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

### Important parameters

• TC - name of swivel data set

Here you can select the swivel data set.

Retraction

Before swiveling the axes you can move the tool to a safe retraction position. The retraction methods available to you are defined in the "Retraction position" parameter during set-up of the swivel data set.

"Retraction" corresponds to Parameter \_FR of CYCLE800.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# 

Select a retraction position so that no collision can occur between the tool and workpiece when swiveling.

## • Swivel plane

You can start the swivel plane as "new" or "additive" to a swivel plane that is already active.

### Swivel mode

Swiveling can be axis by axis or direct.

- Axis-by-axis swiveling is based on the coordinate system of the workpiece (X, Y, Z). The coordinate axis sequence can be selected freely. Rotations are applied in the selected sequence. The rotation of the two rotary axes (A, B or C) is calculated from this.
- For direct swiveling, the required positions of the rotary axes are specified. A suitable
  new coordinate system is calculated based on those values. The tool axis is aligned in
  the Z direction. You can derive the resulting direction of the X and Y axis by traversing
  the axes.

### Note

The positive direction of each rotation for the different swivel methods is shown in the help displays.

### • Direction

"Direction" corresponds to the parameter \_DIR of CYCLE800.

For swivel systems with 2 rotary axes, a particular plane can be reached in two different ways. You can choose between these two different positions in the "Direction" parameter. The +/- corresponds to the larger or smaller value of a rotary axis. This may affect the working area.

When the swivel data set is set up, the entries in the "Direction" parameter determine for which rotary axis you can select each of the two settings.

If one of the two positions cannot be reached for mechanical reasons, the alternative position is automatically selected irrespective of the setting of the "Direction" parameter.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

### Correcting tool

"Tool" corresponds to the Parameter \_ST=1x (correct tool tip) of CYCLE800.

To avoid collisions, you can use the 5-axis transformation (software option) to retain the position of the tool tip during swiveling.

When machine manufacturer commissions the function "Swivel Manual", "Track Tool" must be enabled.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# 3.5 Swiveling

## • Zero plane

The zero plane corresponds to the tool plane (G17, G18, G19) including the active work offset (G500, G54, ...). Rotations of the active work offset and the rotary axes are taken into account for manual swiveling.

The "Swivel Manual" function only writes rotations either in the workpiece reference (\$\_WPFRAME) or in the active work offset.

You can use the "Swivel Manual" function not only for machining, but also for setting-up.

 You can bring the machine into the initial position using the "Basic setting" softkey and the <CYCLE START> key. If the actual work offset does not include a rotation, then the rotary axes of the swivel data set are moved to zero. The tool is located vertically to the machining plane.

If you want to use the actual swiveled plane as the reference plane for setting up your workpiece, you must define this plane as the zero plane.

- With "Set zero plane" the actual swivel plane in the active work offset is stored as the zero plane. As a result, the rotations in the active work offset are overwritten.
- With "Delete zero plane", the rotations in the active work offset are set to zero.

## Note

The overall coordinate system does not change with "Set zero plane" or "Delete zero plane".



### Machine manufacturer

Basic setting of the machine kinematics for "Swivel Manual" and "5-axis transformation".

Please refer to the machine manufacturer's specifications.

## Procedure

1. Select the "Machine" operating area.



Μ

Machine

2. Press the <JOG> key



vel

3. Press the "Swivel" softkey.



 Enter the desired value for the parameter and press the <CYCLE START> key.
 The "Swivel" cycle is started

The "Swivel" cycle is started.

Initial setting	Press the "Basic setting" softkey and the <cycle start=""> key to move the machine into the initial position.</cycle>
	If the actual work offset does not include a rotation, then the rotary axes of the swivel data set are moved to zero. The tool is located vertically to the machining plane.
	This is done, for example, to swivel the coordinate system back to its original orientation.
Set zero plane	Press the "Set zero plane" softkey to set the actual swivel plane to the new zero plane.
Delete O-level	Press the "Delete zero plane" softkey to delete the actual swivel plane.

Parameter	Description	Unit
TC	Name of the swivel data set	
	0: Remove the swivel head, deselect the swivel data set	
	No entry: No change to the set swivel data set	
Retraction	No: No retraction before swiveling	
O	• Fixed point 1: Retraction in the direction of machine axis Z to the fixed point of machine axis Z defined by the machine manufacturer Z.	
	• Fixed point 2: Retraction in the direction of machine axis Z and then in X,Y to the fixed points defined by the machine manufacturer	
	Retraction, maximum in the tool direction up to the software end position	
	• Retraction, incremental in the tool direction up to a maximum of the software end position. The retraction path is entered into parameter ZR.	
Swivel plane	New: New swivel plane	
U	Additive: Additive swivel plane	
Swivel mode	Axis by axis: Rotate coordinate system axis-by-axis	
_	Direct: Directly position rotary axes	
	Positions the rotary axes of the active swivel data set	
	Angle of rotation in the plane around the tool axes	
Z	Angle of rotation in the plane (direct swivel)	Degrees
Axis sequence U	Sequence of the axes which are rotated around:	
	XYZ, XZY, YXZ, YZX, ZXY, ZYX	
Х	Rotation around X	Degrees
Y	Rotation around Y	Degrees
Z	Rotation around Z	Degrees
Name of rotary axis 1	Axis angle for swivel, direct	Degrees
Name of rotary axis 2	Axis angle for swivel, direct	Degrees

# 3.5 Swiveling

Parameter	Description	Unit
Direction	Preferred direction of rotation for 2 alternatives (swiveling axis-by-axis)	
	+: Larger angle of the axis on the scale of the swivel head / swivel table	
	-: Smaller angle of the axis on the scale of the swivel head / swivel table	
Tool	Correction: The position of the tool tip is maintained during swiveling	
	No correction: The position of the tool tip changes during swiveling	

3.6 Simple face milling of workpiece

# 3.6 Simple face milling of workpiece

You can use this cycle to face mill any workpiece. A rectangular surface is always machined.

## Selecting the machining direction

In the "Direction" field, using the select key, select the desired machining direction:

- Same direction of machining
- Alternating direction of machining

### Selecting limits

You can select the limits using the appropriate softkeys:

Left
Bottom
Тор
Right

### See also

Face milling (CYCLE61) (Page 298)

## Prerequisite

To carry out simple stock removal of a workpiece in manual mode, a measured tool must be in the machining position.

## Procedure

М
Machine

1. Select the "Machine" operating area.



2. Press the <JOG> key.



3.

Press the <Face milling> softkey.

3.6 Simple face milling of workpiece

	4.	Press the relevant softkey to specify the lateral limitations of the workpiece.
SELECT	5.	Select the machining type (e.g. roughing) in the "Machining" field.
SELECT	4.	Select the machining direction in the "Direction" field.
	5.	Enter all other parameters in the input screen.
ОК	6.	Press the "OK" softkey.
		The parameter screen is closed.
CYCLE START	7.	Press the <cycle start=""> key.</cycle>
		The face milling cycle is started.
		You can return to the parameter screen at any time to check and correct the inputs.

### Note

You cannot use the "Repos" function while face milling.

Parameter G code program			Parameter ShopMill program		
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting velocity	rpm m/min
F	Feedrate	mm/min			

3.6 Simple face milling of workpiece

Parameters	Description	Unit
Machining	The following machining operations can be selected: $\nabla (roughing)$	
U	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> </ul>	
Direction	Same direction of machining	
U	• <b>∉</b> • <del>Ш</del>	
	Alternating direction of machining	
	• <mark>田</mark> • <u></u>	
X0,	Corner point 1 of surface in X direction (abs. or inc.)	mm
Y0	Corner point 1 of surface in Y direction (abs. or inc.)	mm
Z0	Height of blank (abs. or inc.)	mm
X1 Ŭ	Corner point 2 of surface in X direction (abs. or inc.)	mm
Y1 Ŭ	Corner point 2 of surface in Y direction (abs. or inc.)	mm
Z1 Ŭ	Height of finished part (abs. or inc.)	mm
DXY	Max. infeed in the XY plane (dependent on milling cutter diameter)	mm
	Alternatively, you can specify the plane infeed as a %, as a ratio $\rightarrow$ plane infeed (mm) to milling cutter diameter (mm).	%
DZ	Max. infeed in Z direction - (only for roughing)	mm
UZ	Finishing allowance, depth	mm

## Note

The same finishing allowance must be entered for both roughing and finishing. The finishing allowance is used to position the tool for retraction.

See also

Tool, offset value, feed and spindle speed (T, D, F, S, V) (Page 236)

3.7 Default settings for manual mode

# 3.7 Default settings for manual mode

Specify the configurations for manual mode in the "Settings for manual operation" window.

# Presettings

Settings	Description	
Type of feedrate	Here, you select the type of feedrate.	
	<ul><li>G94: Axis feedrate/linear feedrate</li><li>G95: Rev. feedrate</li></ul>	
Default feedrate G94	Enter the desired feedrate in mm/min.	
Default feedrate G95	Enter the desired feedrate in mm/r.	
Variable increment	Enter the desired increment for axis traversal by variable increments.	
Spindle speed	Enter the desired spindle speed in rpm.	

# Proceed as follows

Machine	1.	Select the "Machine" operating area.
	2.	Press the <jog> key.</jog>
>	3.	Press the menu forward key and the "Settings" softkey. The "Settings for manual operation" window is opened.
K Settings		

# 4.1 Starting and stopping machining

During execution of a program, the workpiece is machined in accordance with the programming on the machine. After the program is started in automatic mode, workpiece machining is performed automatically.

# Requirements

The following requirements must be met before executing a program:

- The measuring system of the controller is referenced with the machine.
- The necessary tool offsets and work offsets have been entered.
- The necessary safety interlocks implemented by the machine manufacturer are activated.

# **General sequence**

Program manager	1.	Use the Program manager to select the desired program.
NC NC		Select the desired program under "NC", "Local drive", "USB" or set-up network drives.
∲ USB		
Select	3.	Press the "Select" softkey.
		The program is selected for execution and automatically switched to the "Machine" operating area.
CYCLE START	4.	Press the <cycle start=""> key.</cycle>
		The program is started and executed.

# Note

### Starting the program in any operating area

If the control is in "AUTO" mode, you can also start the selected program when you are in any operating area.

4.1 Starting and stopping machining

## Stopping machining



Press the <CYCLE STOP> key.

Machining stops immediately. Individual program blocks are not executed to the end. On the next start, machining is resumed from the point where it left off.

### Canceling machining



Press the <RESET> key.

Execution of the program is interrupted. On the next start, machining will start from the beginning.



## Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### 4.2 Selecting a program

# Procedure



- 1. Select the "Program manager" operating area. The directory overview is opened.
- 2. Place the cursor on the directory containing the program that you want to select.



3. Press the <INPUT> key



- OR -Press the <Cursor right> key.

The directory contents are displayed.

4. Place the cursor on the desired program. 5.



Press the "Select" softkey. The program is selected. When the program has been successfully selected, an automatic changeover to the "Machine" operating area occurs.

4.3 Testing a program

# 4.3 Testing a program

When testing a program, the system can interrupt the machining of the workpiece after each program block, which triggers a movement or auxiliary function on the machine. In this way, you can control the machining result block-by-block during the initial execution of a program on the machine.

### Note

# Settings for the automatic mode

Rapid traverse reduction and dry run feed rate are available to run-in or to test a program.

# Move by single block

In "Program control" you may select from among several types of block processing:

SB mode	Scope
SB1 Single block, coarse	The machining stops after every machine block (except for cycles)
SB2 Data block	The machining stops after every block, i.e. also for data blocks (except for cycles)
SB3 Single block, fine	The machining stops after every machine block (also in cycles)

# Precondition

A program must be selected for execution in "AUTO" or "MDA" mode.

# Procedure

- NC. Prog.
- 1. Press the "Prog. ctrl." softkey and select the desired variant in the "SBL" field.



2. Press the <SINGLE BLOCK> key.



3. Press the <CYCLE START> key.

Depending on the execution variant, the first block will be executed. Then the machining stops.

In the channel status line, the text "Stop: Block in single block ended" appears.

CYCLE START 4. Press the <CYCLE START> key.

Depending on the mode, the program will continue executing until the next stop.



Press the <SINGLE BLOCK> key again, if the machining is not supposed to run block-by-block.
The key is deselected again.
If you now press the <CYCLE START> key again, the program is executed to the end without interruption.

See also

Setting for automatic mode (Page 176)

5.

4.4 Displaying the current program block

# 4.4 Displaying the current program block

# 4.4.1 Current block display

The window of the current block display shows you the program blocks currently being executed.

# Display of current program

The following information is displayed in the running program:

- The workpiece name or program name is entered in the title row.
- The program block which is just being processed appears colored.

## Editing a program directly

In the Reset state, you can edit the current program directly.



- 1. Press the <INSERT> key.
- Place the cursor at the relevant position and edit the program block. Direct editing is only possible for G code blocks in the NC memory, not for external execution.



Press the <INSERT> key to exit the program and the edit mode again.

# 4.4.2 Displaying a basic block

If you want precise information about axis positions and important G functions during testing or program execution, you can call up the basic block display. This is how you can check, when using cycles, for example, whether the machine is actually traversing.

Positions programmed by means of variables or R parameters are resolved in the basic block display and replaced by the variable value.

You can use the basic block display both in test mode and when machining the workpiece on the machine. All G code commands that initiate a function on the machine are displayed in the "Basic Blocks" window for the currently active program block:

• Absolute axis positions

3.

- G functions for the first G group
- Other modal G functions
- Other programmed addresses
- M functions

### Machining the workpiece

4.4 Displaying the current program block



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure

Basic blocks	1. 2.	A program is selected for execution and has been opened in the "Machine" operating area. Press the "Basic blocks" softkey. The "Basic Blocks" window opens.
SINGLE BLOCK	3.	Press the <single block=""> key if you wish to execute the program block-by-block.</single>
CYCLE START	4.	Press the <cycle start=""> key to start the program execution. The axis positions to be approached, modal G functions, etc., are displayed in the "Basic Blocks" window for the currently active program block.</cycle>
Basic blocks	5.	Press the "Basic blocks" softkey once again to hide the window again.

# 4.4.3 Display program level

You can display the current program level during the execution of a large program with several subprograms.

### Several program run throughs

If you have programmed several program run throughs, i.e. subprograms are run through several times one after the other by specifying the additional parameter P, then during processing, the program runs still to be executed are displayed in the "Program Levels" window.

### Program example

N10 subprogram P25

If, in at least one program level, a program is run through several times, a horizontal scroll bar is displayed that allows the run through counter P to be viewed in the righthand window section. The scroll bar disappears if multiple run-through is no longer applicable.

4.4 Displaying the current program block

# Display of program level

The following information will be displayed:

- Level number
- Program name
- Block number, or line number
- Remain program run throughs (only for several program run throughs)

# Precondition

A program must be selected for execution in "AUTO" mode.

# Procedure

Program levels

Press the "Program levels" softkey. The "Program levels" window appears.

# 4.5 Correcting a program

As soon as a syntax error in the part program is detected by the controller, program execution is interrupted and the syntax error is displayed in the alarm line.

# **Correction possibilities**

Depending on the state of the control system, you can make the following corrections using the Program editing function.

Stop mode

Only program lines that have not yet been executed can be edited.

Reset mode

All program lines can be edited.

### Note

The "program correction" function is also available for execute from external; however, when making program changes, the NC channel must be brought into the reset state.

# Requirement

A program must be selected for execution in "AUTO" mode.

# Procedure



2.

4.

- 1. The program to be corrected is in the Stop or Reset mode.
  - Press the "Prog. corr." softkey
    The program is opened in the editor.
    The program preprocessing and the current block are displayed. The current block is also updated in the running program, but not the displayed program section, i.e. the current block moves out of the displayed program section.

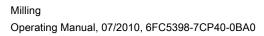
If a subprogram is executed, it is not opened automatically.

3. Make the necessary corrections.



CYCLE START

- Press the "NC Execute" softkey. The system switches back to the "Machine" operating area and selects "AUTO" mode.
- 5. Press the <CYCLE START> key to resume program execution.



4.5 Correcting a program

# Note

Exit the editor using the "Close" softkey to return to the "Program manager" operating area.

## 4.6 Repositioning axes

After a program interruption in automatic mode (e.g. after a tool breaks) you can move the tool away from the contour in manual mode.

The coordinates of the interrupt position will be saved. The distances traversed in manual mode are displayed in the actual value window. This path difference is called "Repos-offset".

### Resuming program execution

Using the "Repos" function, you can return the tool to the contour in order to continue executing the program.

You cannot traverse the interrupt position, because it is blocked by the control system.

The feedrate/rapid traverse override is in effect

## 

When repositioning, the axes move with the programmed feedrate and linear interpolation, i.e. in a straight line from the current position to the interrupt point. Therefore, you must first move the axes to a safe position in order to avoid collisions.

If you do not use the "Repos" function and subsequently move the axes in manual mode after a program interrupt, the control automatically moves the axes during the switch to automatic mode and the subsequent start of the machining process in a straight line back to the point of interruption.

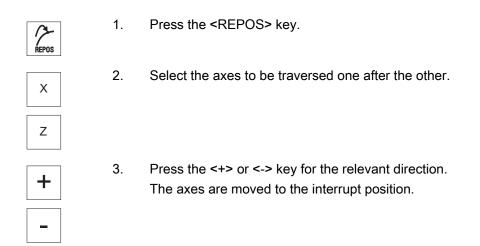
## Requirement

The following prerequisites must be met when repositioning the axes:

- The program execution was interrupted using <CYCLE STOP>.
- The axes were moved from the interrupt point to another position in manual mode.

4.6 Repositioning axes

## Proceed as follows



## 4.7 Starting machining at a specific point

## 4.7.1 Use block search

If you would only like to perform a certain section of a program on the machine, then you need not start the program from the beginning. You can also start the program from a specified program block.

## Applications

- Stopping or interrupting program execution
- Specify a target position, e.g. during remachining

### Determining a search target

- User-friendly search target definition (search positions)
  - Direct specification of the search target by positioning the cursor in the selected program (main program)
  - Search target via text search
  - The search target is the interruption point (main program and subprogram)

The function is only available if there is an interruption point. After a program interruption (CYCLE STOP or RESET), the controller saves the coordinates of the interruption point.

 The search target is the higher program level of the interruption point (main program and subprogram)

The level can only be changed if it was previously possible to select an interruption point in a subprogram. It is then possible to change the program level up to the main program level and back to the level of the interruption point.

- Search pointer
  - Direct entry of the program path

#### Note

### Searching for point in subprogram

You can search for a specific point in subprograms with the search pointer if there is no interruption point.



#### Software option

You require the "Extended operator functions" option for the "Search pointer" function (only for 828D).

### Cascaded search

You can start another search from the "Search target found" state. The cascading can be continued any number of times after every search target found.

#### Note

Another cascaded block search can be started from the stopped program execution only if the search target has been found.

#### References

Function Manual Basic Functions; Block Search

#### Preconditions

- 1. You have selected the desired program.
- 2. The control system is in the RESET condition.

- OR -

3. The desired search mode is selected.

#### NOTICE

### Collision-free start position

Pay attention to a collision-free start position and appropriate active tools and other technological values.

If necessary, manually approach a collision-free start position. Select the target block considering the selected block search type.

#### Toggling between search pointer and search positions



Press the "Search pointer" softkey again to exit the "Search Pointer" window and return to the "Program" window to define search positions.



Press the "Back" softkey. You have now exited the block search function.

See also

Selecting a program (Page 137)

## 4.7.2 Continuing program from search target

To continue the program at the desired position, press the <CYCLE START> key twice.

- The first CYCLE START outputs the auxiliary functions collected during the search. The program is then in the Stop state.
- Before the second CYCLE START, you can use the "Overstore" function to create states that are required, but not yet available, for the further program execution.

By changing to the JOG REPOS mode, you can also manually traverse the tool from the current position to the setpoint position, if the setpoint position is not to be automatically approached after the program start.

## 4.7.3 Simple search target definition

### Requirement

The program is selected and the controller is in Reset mode.

### Procedure

NC Block search	1.	Press the "Block search" softkey.
	2.	Place the cursor on a particular program block. - OR -
Search for text		Press the "Find text" softkey, select the search direction, enter the search text and confirm with "OK".
ОК		
Start search	3.	Press the "Start search" softkey.
		The search starts. Your specified search mode will be taken into account.
		The current block will be displayed in the "Program" window as soon as the target is found.
Start search	4.	If the located target (for example, when searching via text) does not correspond to the program block, press the "Start search" softkey again until you find your target.
		Press the <cycle start=""> key twice.</cycle>
		Processing is continued from the defined position.

## 4.7.4 Defining an interruption point as search target

## Precondition

A program was selected in "AUTO" mode and interrupted during execution through CYCLE STOP or RESET.



#### Software option

You require the "Extended operator functions" option (only for 828D).

## Procedure

NC Block search	1.	Press the "Block search" softkey.
Interrupt point	2.	Press the "Interrupt point" softkey. The interruption point is loaded.
Higher level	3.	If the "Higher level" and "Lower level" softkeys are available, use these to change the program level.
Lower level		
Start search	4.	Press the "Start search" softkey.
		The search starts. Your specified search mode will be taken into account.
		The search screen closes.
		The current block will be displayed in the "Program" window as soon as the target is found.
	5.	Press the <cycle start=""> key twice.</cycle>
CYCLE START		The execution will continue from the interruption point.

## 4.7.5 Entering the search target via search pointer

Enter the program point which you would like to proceed to in the "Search Pointer" window.



#### Software option

You require the "Extended operator functions" option for the "Search pointer" function (only for 828D).

### Precondition

The program is selected and the controller is in Reset mode.

### Screen form

Each line represents one program level. The actual number of levels in the program depends on the nesting depth of the program.

Level 1 always corresponds to the main program and all other levels correspond to subprograms.

You must enter the target in the line of the window corresponding to the program level in which the target is located.

For example, if the target is located in the subprogram called directly from the main program, you must enter the target in program level 2.

The specified target must always be unambiguous. This means, for example, that if the subprogram is called in the main program in two different places, you must also specify a target in program level 1 (main program).

## Procedure

NC Block search	1.	Press the "Block search" softkey.
Search pointer	2.	Press the "Search pointer" softkey.
	3.	Enter the full path of the program as well as the subprograms, if required, in the input fields.
Start search	4.	Press the "Start search" softkey.
		The search starts. Your specified search mode will be taken into account.
		The Search window closes. The current block will be displayed in the "Program" window as soon as the target is found.
	5.	Press the <cycle start=""> key twice.</cycle>
CYCLE START		Processing is continued from the defined location.

## Note Interruption point

You can load the interruption point in search pointer mode.

## 4.7.6 Parameters for block search in the search pointer

Parameter	Meaning		
Number of progra	Number of program level		
Program:	The name of the main program is automatically entered		
Ext:	File extension		
P:	Pass counter		
	If a program section is performed several times, you can enter the number of the pass here at which processing is to be continued		
Line:	Is automatically filled for an interruption point		
Туре	" " search target is ignored on this level		
	N no. Block number		
	Label Jump label		
	Text string		
	Subprg. Subprogram call		
	Line Line number		
Search target	Point in the program at which machining is to start		

## 4.7.7 Block search mode

Set the desired search variant in the "Search Mode" window.

The set mode is retained when the the controller is shut down. When you activate the "Search" function after restarting the controller, the current search mode is displayed in the title row.

### Search variants

Block search mode	Meaning
With calculation - without approach	It is used in order to be able to approach a target position in any circumstance (e.g. tool change position).
	The end position of the target block or the next programmed position is approached using the type of interpolation valid in the target block. Only the axes programmed in the target block are moved.
With calculation	It is used to be able to approach the contour in any circumstance.
- with approach	The end position of the block prior to the target block is found with <cycle start="">. The program runs in the same way as in normal program processing.</cycle>
With calculation - skip extcall	This is used to speed-up a search with calculation when using EXTCALL programs: EXTCALL programs are not taken into account.
	<b>Notice</b> : Important information, e.g. modal functions, which are located in the EXTCALL program, are not taken consideration. In this case, after the search target has been found, the program is not able to be executed. Information such as this should programmed in the main program.

Block search mode	Meaning
Without calculation	For a quick search in the main program.
	Calculations will not be performed during the block search, i.e. the calculation is skipped up to the target block.
	All settings required for execution have to be programmed from the target block (e.g. feedrate, spindle speed, etc.).
With program test	Multi-channel block search with calculation (SERUPRO).
	All blocks are calculated during the block search. Absolutely no axis motion is executed, however, all auxiliary functions are output.
	The NC starts the selected program in the program test mode. If the NC reaches the specified target block in the actual channel, it stops at the beginning of the target block and deselects program test mode again. After continuing the program with NC start (after REPOS motion) the auxiliary functions of the target block are output.
	For single-channel systems, the coordination is supported with events running in parallel, such as e.g. synchronized actions.
	Note
	The search speed depends on MD settings.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### References

For additional information, please refer to the following documentation: Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

## Procedure



1. Select the "Machine" operating area.





Block search

Blk sear. mode

- 2. Press the <AUTO> key.
- Press the "Block search" and "Block search mode" softkeys. 3. The "Search Mode" window will open.

4.8 Intervening in the program sequence

## 4.8 Intervening in the program sequence

## 4.8.1 Program control

You can change the program sequence in the "AUTO" and "MDA" modes.

Abbreviation/program control	Scope
PRT no axis motion	The program is started and executed with auxiliary function outputs and dwell times. In this mode, the axes are not traversed.
	The programmed axis positions and the auxiliary function outputs are controlled this way.
	Note: Program processing without axis motion can also be activated with the function "Dry run feedrate".
DRY Dry run feedrate	The traversing velocities programmed in conjunction with G1, G2, G3, CIP and CT are replaced by a defined dry run feedrate. The dry run feedrate also applies instead of the programmed revolutional feedrate.
	Caution: Workpieces must not be machined when "Dry run feedrate" is active because the altered feedrates might cause the permissible tool cutting rates to be exceeded and the workpiece or machine tool could be damaged.
RG0 Reduced rapid traverse	In the rapid traverse mode, the traversing speed of the axes is reduced to the percentage value entered in RG0.
	Note: You define the reduced rapid traverse in the settings for automatic operation.
M01 Programmed stop 1	The processing of the program stops at every block in which supplementary function M01 is programmed. In this way you can check the already obtained result during the processing of a workpiece.
	Note: In order to continue executing the program, press the <cycle start=""> key again.</cycle>
Programmed stop 2 (e.g. M101)	The processing of the program stops at every block in which the "Cycle end" is programmed (e.g. with M101).
	Note: In order to continue executing the program, press the <cycle start=""> key again.</cycle>
	Note: The display can be changed. Please refer to the machine manufacturer's specifications.
DRF Handwheel offset	Enables an additional incremental zero offset while processing in automatic operation mode with an electronic handwheel.
	This function can be used to compensate for tool wear within a programmed block.
	Note: You require the "Extended operator functions" option to use the handwheel offset (for 828D).
SB	Individual blocks are configured as follows.
	Single block, coarse: The program stops only after blocks which perform a machine function.
	Data block: The program stops after each block.
	Single block, fine: The program also only stops after blocks which perform a machine function in cycles.
	Select the desired setting using the <select> key.</select>
SKP	Skip blocks are skipped during machining.

4.8 Intervening in the program sequence

## Activating program control

You can control the program sequence however you wish by selecting and clearing the relevant check boxes.

#### Display / response of active program controls:

If a program control is activated, the abbreviation of the corresponding function appears in the status display as response.

## Procedure



1.

- Select the "Machine" operating area.
- 2. Press the <AUTO> or <MDA> key.



Press the "Prog. ctrl." softkey.
 The "Program control" window appears.

## See also

Setting for automatic mode (Page 176)

4.8 Intervening in the program sequence

## 4.8.2 Skip blocks

It is possible to skip program blocks, which are not to be executed every time the program runs.

The skip blocks are identified by placing a "/" (forward slash) or "/x (x = number of skip level) character in front of the block number. Several consecutive blocks can also be skipped.

The statements in the skipped blocks are not executed, i.e. the program continues with the next block, which is not skipped.

The number of skip levels that can be used depends on a machine datum.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Skip levels, activate

Check the corresponding checkbox in order to skip the required block level.

#### Note

The "Program control - skip blocks" window is only available when more than one skip level is set up.

### Procedure

- 1. Select the "Machine" operating area.
- Machine
- 2. Press the <AUTO> or <MDA> key.



NC Prog.

Skip blocks 3

> Press the "Prog. ctrl." and "Skip blocks" softkeys. The "Program control" window appears and shows a list of block levels.

## Machining the workpiece

4.8 Intervening in the program sequence

Program control
Skip blocks
Plane / Plane /4
Plane /1 Plane /5
Plane /2 Plane /6

#### 4.9 Overstore

## 4.9 Overstore

With overstore, you have the option of executing technological parameters (for example, auxiliary functions, axis feed, spindle speed, programmable instructions, etc.) before the program is actually started. The program instructions act as if they are located in a normal part program. These program instructions are, however, only valid for one program run. The part program is not permanently changed. When next started, the program will be executed as originally programmed.

After a block search, the machine can be brought into another state with overstore (e.g. M function, tool, feed, speed, axis positions etc.), in which the normal part program can be successfully continued.



#### Software option

You require the "Extended operator functions" option for the overstore function (for 828D).

## Precondition

The program to be corrected is in the Stop or Reset mode.

### Procedure

1. Open the program in the "AUTO" mode. Μ Machine → AUTO 2. Press the "Overstore" softkey. Overstore The "Overstore" window opens. 3. Enter the required data and NC block. 4. Press the <CYCLE START> key. CYCLE The blocks you have entered are stored. You can observe execution in the "Overstore" window. After the entered blocks have been executed, you can append blocks again. You cannot change the operating mode while you are in overstore mode. 5. Press the "Back" softkey. ~ Back The "Overstore" window closes. 6. Press the <CYCLE START> key again. CYCLE The program selected before overstoring continues to run.

4.9 Overstore

## Note

## Block-by-block execution

The <SINGLE BLOCK> key is also active in the overstore mode. If several blocks are entered in the overstore buffer, then these are executed block-by-block after each NC start

## **Deleting blocks**

Delete blocks Press the "Delete blocks" softkey to delete program blocks you have entered.

4.10 Editing a program

## 4.10 Editing a program

With the editor, you are able to render, supplement, or change part programs.

#### Note

The maximum block length is 512 characters.

#### Calling the editor

- The editor is started via the "Program correction" function in the "Machine" operating area.
- The editor is called via the "Open" softkey as well as with the <INPUT> or <Cursor right> key in the "Program manager" operating area.
- The editor opens in the "Program" operating area with the last executed part program, when this was not explicitly exited via the "Close" softkey.

#### Note

Please note that the changes to programs stored in the NC memory take immediate effect. You can exit the editor only after you have saved the changes.

If you are editing on a local drive or external drives, you can also exit the editor without saving, depending on the setting.

Exit the program correction mode using the "Close" softkey to return to the "Program manager" operating area.

### See also

Editor settings (Page 166) Opening and closing the program (Page 517) Correcting a program (Page 143) Generating a G code program (Page 208)

## 4.10.1 Searching in programs

You can use the search function to quickly arrive at points where you would like to make changes, e.g. in very large programs.

### Precondition

The desired program is opened in the editor.

## Machining the workpiece 4.10 Editing a program

## Procedure

Search	1.	Press the "Search" softkey. A new vertical softkey bar appears. The "Search" window opens at the same time.
	2.	Enter the desired search term in the "Text" field.
	3.	Select "Whole words" if you want to search for whole words only.
SELECT	4.	Position the cursor in the "Direction" field and choose the search direction (forward, backward) with the <select> key.</select>
ОК	5.	Press the "OK" softkey to start the search.
		If the text you are searching for is found, the corresponding line is highlighted.
Continue search	6.	Press the "Continue search" softkey if the text located during the search does not correspond to the point you are looking for.
		- OR -
<b>X</b> Cancel		Press the "Cancel" softkey when you want to cancel the search.

## Further search options

Softkey	Function
Go to start	The cursor is set to the first character in the program.
Go to end	The cursor is set to the last character in the program.

## 4.10.2 Replacing program text

You can find and replace text in one step.

## Requirement

The desired program is opened in the editor.

4.10 Editing a program

## Proceed as follows

Search	1.	Press the "Search" softkey. A new vertical softkey bar appears.
Find + replace	2.	Press the "Find + replace" softkey. The "Find and replace" window appears.
	3.	In the "Text" field, enter the term you are looking for and in the "Replace with" field, enter the text you would like to insert automatically during the search.
SELECT	4.	Position the cursor in the "Direction" field and choose the search direction (forward, backward) with the <select> key.</select>
ОК	5.	Press the "OK" softkey to start the search.
		If the text you are searching for is found, the corresponding line is highlighted.
Replace	6.	Press the "Replace" softkey to replace the text.
		- OR -
Replace all		Press the "Replace all" softkey to replace all text in the file that corresponds to the search term.
		- OR -
Continue search		Press the "Continue search" softkey if the text located during the search should not be replaced.
		- OR -
X Cancel		Press the "Cancel" softkey when you want to cancel the search.

## 4.10.3 Copying/pasting/deleting a program block

## Precondition

The program is opened in the editor.

## Procedure

Mark	1.	Press the "Mark" softkey.
$\bigcirc$		- OR - Press the <select> key.</select>
SELECT Copy	2. 3.	Select the desired program blocks with the cursor or mouse. Press the "Copy" softkey in order to copy the selection to the buffer memory.
Paste	4.	Place the cursor on the desired insertion point in the program and press the "Paste" softkey.
		The content of the buffer memory is pasted.

## Deleting program blocks



Use the "Cut" softkey to delete selected program blocks.

### Note

The buffer memory contents are retained even after the editor is closed, enabling you to paste the contents in another program, as well.

### See also

Opening a second program (Page 164)

4.10 Editing a program

## 4.10.4 Renumber program

You can modify the block numbering of programs opened in the editor at a later point in time.

## Requirement

The program is opened in the editor.

## Procedure

	1.	Press the ">>" softkey. A new vertical softkey bar appears.
Renumbering	2.	Press the "Renumber" softkey. The "Renumbering" window appears.
	3.	Enter the values for the first block number and the increment to be used for numbering.
ок	4.	Press the "OK" softkey. The program is renumbered.

#### Note

If you only want to renumber a section, select the program blocks whose block numbering you want to edit.

## 4.10.5 Opening a second program

You have the option of viewing and editing two programs simultaneously in the editor.

For instance, you can copy program blocks or machining steps of a program and paste them into another program.

### Opening several programs

You have the option of opening up to 10 program blocks.

Open	1.	In the Program Manager, select the programs that you wish to open and view in the dual editor and then press on the "Open" softkey.
		The dual editor is opened and the first two programs are displayed.
NEXT WINDOW	2.	Press the <next window=""> key to change to the next opened program.</next>
Exit	3.	Press the "Close" softkey to close the actual program.

## Note Pasting program blocks

Jobshop machining steps cannot be copied into a G code program.

## Precondition

You have opened a program in the Editor.

## Procedure



1. Press the ">>" and "Open 2nd program" softkeys.



- The "Select 2nd program" window opens.
- 2. Select the required program that you wish to display in addition to the program that is already open.



3. Press the "OK" softkey.

> The dual editor opens and displays both of the programs next to one another.

## See also

Copying/pasting/deleting a program block (Page 163)

4.10 Editing a program

## 4.10.6 Editor settings

Enter the default settings in the "Settings" window that are to take effect automatically when the editor is opened.

## Presettings

Settings	Meaning
Number automatically	Yes: A new block number will automatically be assigned after every line change. In this case, the specifications provided under "First block number" and "Increment" are applicable.
	No: No automatic numbering.
First block number	Specifies the starting block number of a newly created program.
	The field is only editable when "Yes" is available under "Number automatically".
Increment	Defines the increment used for the block numbers.
	The field is only editable when "Yes" is available under "Number automatically".
Display hidden lines	Hidden lines marked with "*HD" (hidden) will be displayed.
Display block end as an icon	The "CFLF" (line feed) symbol $\P$ is displayed at the block end.
Scroll horizontally	A horizontal scrollbar is displayed. In this way, you can scroll horizontally to the end of long lines that would otherwise wrap.
Automatic save (only local and external	Yes: The changes are saved automatically when you change to another operating area.
drives)	No: You are prompted to save when changing to another operating area.
	Save or reject the changes with the "Yes" or "No" softkeys.

### Note

All entries that you make here are effective immediately.

## Machining the workpiece 4.10 Editing a program

## Procedure



1. Select the "Program" operating area



Edit

- You have activated the editor.
- 2. Press the ">>" and "Settings" softkeys. The "Settings" window appears.



0K

3. Make the desired changes here and press the "OK" softkey to confirm your settings.

## 4.11 Displaying G functions and auxiliary functions

## 4.11.1 Selected G functions

16 selected G groups are displayed in the "G Function" window.

Within a G group, the G function currently active in the controller is displayed.

Some G codes (e.g. G17, G18, G19) are immediately active after switching the machine control on.

Which G codes are always active depends on the settings.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

## G groups displayed by default

Group	Meaning
G group 1	Modally active motion commands (e.g. G0, G1, G2, G3)
G group 2	Non-modally active motion commands, dwell time (e.g. G4, G74, G75)
G group 3	Programmable offsets, working area limitations and pole programming (e.g. TRANS, ROT, G25, G110)
G group 6	Plane selection (e.g. G17, G18)
G group 7	Tool radius compensation (e.g. G40, G42)
G group 8	Settable work offset (e.g. G54, G57, G500)
G group 9	Offset suppression (e.g. SUPA, G53)
G group 10	Exact stop - continuous-path mode (e.g. G60, G641)
G group 13	Workpiece dimensioning inches/metric (e.g. G70, G700)
G group 14	Workpiece dimensioning absolute/incremental (G90)
G group 15	Feedrate type (e.g. G93, G961, G972)
G group 16	Feedrate override on inside and outside curvature (e.g. CFC)
G group 21	Acceleration profile (e.g. SOFT, DRIVE)
G group 22	Tool offset types (e.g. CUT2D, CUT2DF)
G group 29	Radius/diameter programming (e.g. DIAMOF, DIAMCYCOF)
G group 30	Compressor ON/OFF (e.g. COMPOF)

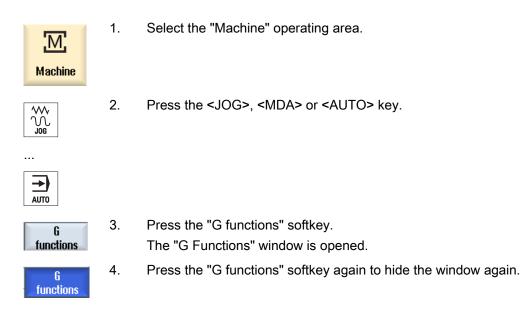
#### Machining the workpiece

4.11 Displaying G functions and auxiliary functions

Group	Meaning	
G group 1	Modally active motion commands (e.g. G0, G1, G2, G3)	
G group 2	Non-modally active motion commands, dwell time (e.g. G4, G74, G75)	
G group 3 Programmable offsets, working area limitations and pole progra TRANS, ROT, G25, G110)		
G group 6	Plane selection (e.g. G17, G18)	
G group 7	Tool radius compensation (e.g. G40, G42)	
G group 8	Settable work offset (e.g. G54, G57, G500)	
G group 9	Offset suppression (e.g. SUPA, G53)	
G group 10	Exact stop - continuous-path mode (e.g. G60, G641)	
G group 13	Workpiece dimensioning inches/metric (e.g. G70, G700)	
G group 14	Workpiece dimensioning absolute/incremental (G90)	
G group 15	Feedrate type (e.g. G93, G961, G972)	
G group 16	Feedrate override on inside and outside curvature (e.g. CFC)	
G group 21	Acceleration profile (e.g. SOFT, DRIVE)	
G group 22	Tool offset types (e.g. CUT2D, CUT2DF)	
G group 29	Radius/diameter programming (e.g. DIAMOF, DIAMCYCOF)	
G group 30	Compressor ON/OFF (e.g. COMPOF)	

## G groups displayed by default (ISO code)

## Procedure



The G groups selection displayed in the "G Functions" window may differ.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

## References

For more information about configuring the displayed G groups, refer to the following document:

Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

## 4.11.2 All G functions

All G groups and their group numbers are listed in the "G Functions" window. Within a G group, only the G function currently active in the controller is displayed.

#### Additional information in the footer

The following additional information is displayed in the footer:

• Current transformations

Display	Meaning
TRANSMIT	Polar transformation active
TRACYL	Cylinder surface transformation active
TRAORI	Orientation transformation active
TRAANG	Inclined axis transformation active
TRACON	Cascaded transformation active
	For TRACON, two transformations (TRAANG and TRACYL or TRAANG and TRANSMIT) are activated in succession.

- Current zero offsets
- Spindle speed
- Path feedrate
- Active tool

## Procedure

Machine	1.	Select the "Machine" operating area.
	2.	Press the <jog>, <mda> or <auto> key.</auto></mda></jog>
	3.	Press the ">>" and "All G functions" softkeys. The "G Functions" window is opened.
All G functions		

#### 4.11.3 Auxiliary functions

Auxiliary functions include M and H functions preprogrammed by the machine manufacturer, which transfer parameters to the PLC to trigger reactions defined by the manufacturer.

## **Displayed auxiliary functions**

Up to five current M functions and three H functions are displayed in the "Auxiliary Functions" window.

### Procedure



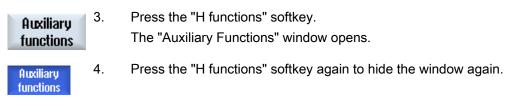
Select the "Machine" operating area. 1.



2. Press the <JOG>, <MDA> or <AUTO> key.



. . .



You can display status information for diagnosing synchronized actions in the "Synchronized Actions" window.

You get a list with all currently active synchronized actions.

In this list, the synchronized action programming is displayed in the same form as in the part program.

#### References

Programming Guide Job Planning (PGA) Chapter: Motion-synchronous actions

#### Status of synchronized actions

You can see the status of the synchronized actions in the "Status" column.

- Waiting
- Active
- Blocked

Non-modal synchronized actions can only be identified by their status display. They are only displayed during execution.

#### Synchronization types

Synchronization types	Meaning
ID=n	Modal synchronized actions in the automatic mode up to the end of program, local to program; $n = 1254$
IDS=n	Static synchronized actions, modally effective in every operating type, also beyond the end of program; $n = 1254$
Without ID/IDS	Non-modal synchronized actions in automatic mode

#### Note

Numbers ranging from 1 to 254 can only be assigned once, irrespective of the identification number.

### Display of synchronized actions

Using softkeys, you have the option of restricting the display to activated synchronized actions.

## Machining the workpiece

4.11 Displaying G functions and auxiliary functions

## Procedure

Machine	1.	Select the "Machine" operating area.
	2.	Press the <auto>, <mda> or <jog> key.</jog></mda></auto>
SYNC Synchro n.	3.	Press the menu forward key and the "Synchron." softkey. The "Synchronized Actions" window appears. You obtain a display of all activated synchronized actions.
D	4.	Press the "ID" softkey if you wish to hide the modal synchronized actions in the automatic mode.
		- AND / OR -
IDS		Press the "IDS" softkey if you wish to hide static synchronized actions.
		- AND / OR -
Blockwise		Press the "Blockwise" softkey if you wish to hide the non-modal synchronized actions in the automatic mode.
D	5.	Press the "ID", "IDS" or "Blockwise" softkeys to re-display the corresponding synchronized actions.
Blockwise		

4.12 Displaying the program runtime and counting workpieces

## 4.12 Displaying the program runtime and counting workpieces

To gain an overview of the program runtime and the number of machined workpieces, open the "Times, Counter" window.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

## **Displayed times**

• Program

Pressing the softkey the first time shows how long the program has already been running.

At every further start of the program, the time required to run the entire program the first time is displayed.

If the program or the feedrate is changed, the new program runtime is corrected after the first run.

• Program remainder

Here you can see how long the current program still has to run. In addition, you can

track how much of the current program has been completed as a percentage by using the progress bar.

The display only appears when the program is run a second time.

If you are executing the program from an external location, the program loading progress is displayed here.

Influencing the time measurement

The time measurement is started with the start of the program and ends with the end of the program (M30) or with an agreed M function.

When the program is running, the time measurement is interrupted with CYCLE STOP and continued with CYCLE START.

The time measurement starts at the beginning with RESET and subsequent CYCLE START.

The time measurement stops with CYCLE STOP or a feedrate override = 0.

### **Counting workpieces**

You can also display program repetitions and the number of completed workpieces. For the worpiece count, enter the actual and planned workpiece numbers.

## Workpiece count

Completed workpieces can be counted via the end of program command (M30) or an M command.

## Machining the workpiece

4.12 Displaying the program runtime and counting workpieces

## Procedure

Machine	1.	Select the "Machine" operating area.
	2.	Press the <auto> key.</auto>
Time counter	3.	Press the "Times, Counter" softkey. The "Times, Counter" window opens.
SELECT	4.	Select "Yes" under "Count workpieces" if you want to count completed workpieces.
	5.	Enter the number of workpieces needed in the "Desired workpieces" field. The number of workpieces already finished is displayed in "Actual workpieces". This value can be corrected if necessary. After the defined number of workpieces is reached, the current workpieces display is automatically reset to zero.
		, , , , ,

### See also

Specifying the number of workpieces (Page 243)

4.13 Setting for automatic mode

## 4.13 Setting for automatic mode

Before machining a workpiece, you can test the program in order to identify programming errors early on. Use the dry run feedrate for this purpose.

In addition, you have the option of additionally limiting the traversing speed for rapid traverse so that when running-in a new program with rapid traverse, no undesirable high traversing speeds occur.

### Dry run feedrate

The feedrate defined here replaces the programmed feedrate during execution if you have selected "DRY dry run feedrate" under program control.

#### **Reduced rapid traverse**

This value entered here reduces the rapid traverse to the entered percentage value if you selected "RG0 reduced rapid traverse" under program control.

#### **Displaying measurement results**

Using an MMC command, you can display measurement results in a part program:

You set

 whether, when the control reaches the command, it automatically jumps into the "Machine" operating area and the window with the measurement results is displayed,

or

• whether the window with the measurement results is opened by pressing the "Measurement result" softkey.

### Procedure

1. Select the "Machine" operating area.

→)

Machine

Μ

2. Press the <AUTO> key.



- Press the menu forward key and the "Settings" softkey.
   The "Settings for Automatic Operation" window is opened.
- Settings
- 4. In "DRY run feedrate," enter the desired dry run speed.

4.13 Setting for automatic mode

5. Enter the desired percentage in the "Reduced rapid traverse RG0" field.

RG0 has not effect if you do not change the specified amount of 100%.



6. Enter "Automatic" in the "Display measurement result" box if the measurement result window should be automatically opened, or "Manual", if the measurement result window should be opened by pressing the "Measurement result" softkey.

## References

840D sl Programming Manual Measuring Cycles

#### Note

The feedrate can be changed while the operation is running.

## See also

Program control (Page 154)

Machining the workpiece

4.13 Setting for automatic mode

# Simulating machining

## 5.1 Overview

During simulation, the current program is calculated in its entirety and the result displayed in graphic form. The result of programming is verified without traversing the machine axes. Incorrectly programmed machining steps are detected at an early stage and incorrect machining on the workpiece prevented.

#### Graphic display

The simulation represented on the screen uses the correct workpiece and tool proportions.

For simulation at milling machines, the workpiece is located, fixed in space. Only the tool moves, independent of the machine type.

#### **Definition of blank**

The blank dimensions that are entered in the program editor are used for the workpiece.

The blank is clamped with reference to the coordinate system, which is valid at the time that the blank was defined. This means that before defining the blank in G code programs, the required output conditions must be established, e.g. by selecting a suitable work offset.

### Programming a blank (example)

```
G54 G17 G90
CYCLE800(0,"TISCH", 100000,57,0,0,0,0,0,0,0,0,0,-1,100,1)
WORKPIECE(,,,"Box",112,0,-50,-80,00,155,100)
T="NC-SPOTDRILL D16
```

#### Note

#### Blank offset for a changed work offset

The blank is always created in the work offset, which is presently active.

If you select another work offset, then the coordinate system is converted, however, the display of the blank is not changed.

### Display of the traversing paths

The traversing paths are displayed in color. Rapid traverse is red and the feedrate is green.

#### 5.1 Overview

#### Machine references

The simulation is implemented as workpiece simulation. This means that it is not assumed that the work offset has already been precisely scratched or is known.

In spite of this, unavoidable Machine references are in the programming, such as for example, the tool change point in the Machine, the retraction position when swiveling and the table components of a swivel kinematic. Depending on the actual work offset - in the worst case - these Machine references can mean that collisions are shown in the simulation that would not occur for a realistic work offset - or vice versa, collisions are not shown, which could occur for a realistic work offset.

CYCLE800 does not cause any motion and is not shown in the simulation.

#### Simulation display

You can choose one of the following types of display:

Material removal simulation

During simulation or simultaneous recording you can follow stock removal from the defined blank.

Path display

You have the option of including the display of the path. The programmed tool path is displayed.

#### Note

#### Tool display in the simulation and for simultaneous recording

In order that workpiece simulation is also possible for tools that have either not been measured or have been incompletely entered, certain assumptions are made regarding the tool geometry.

For instance, the length of a miller or drill is set to a value proportional to the tool radius so that cutting can be simulated.

#### **Display variants**

You can choose between three variants of graphical display:

Simulation before machining of the workpiece

Before machining the workpiece on the machine, you can perform a quick run-through in order to graphically display how the program will be executed.

• Simultaneous recording before machining of the workpiece

Before machining the workpiece on the machine, you can graphically display how the program will be executed during the program test and dry run feedrate. The machine axes do not move if you have selected "no axis motion".

• Simultaneous recording during machining of the workpiece

You can follow machining of the workpiece on the screen while the program is being executed on the machine.

#### Views

The following views are available for all three variants:

- Top view
- 3D view
- Side views

#### Status display

The current axis coordinates, the override, the current tool with cutting edge, the current program block, the feedrate and the machining time are displayed.

In all views, a clock is displayed during graphical processing. The machining time is displayed in hours, minutes and seconds. It is approximately equal to the time that the program requires for processing including the tool change.



#### Software options

You require the option "3D simulation of the finished part" for the 3D view. You require the option "Simultaneous recording (real-time simulation)" for the "Simultaneous recording" function.

#### Determining the program run time

The program runtime is determined when executing the simulation. The program runtime is temporarily displayed in the editor at the end of the program.

#### Properties of simultaneous recording and simulation

#### Traversing paths

For the simulation, the displayed traversing paths are saved in a ring buffer. If this buffer is full, then the oldest traversing path is deleted with each new traversing path.

#### Working zone limiting

No working zone limits and software limit switches are effective in the tool simulation.

#### Constraint

- Traori: 5-axis motion is linearly interpolated. More complex motion cannot be displayed.
- Spines and polynomials are not supported.
- Referencing: G74 from a program run does not function.
- Alarm 15110 "REORG block not possible" is not displayed.
- Compile cycles are not supported.
- No PLC support.
- Axis containers are not supported.

#### **General conditions**

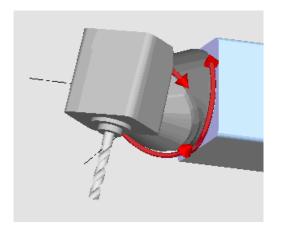
- All of the existing data records (Toolcarrier / TRAORI, TRACYL) are evaluated and must be correctly commissioned for correct simulation.
- Transformations with swiveled linear axis (TRAORI 64 69) as well as OEM transformations (TRAORI 4096 4098) are not supported.
- Changes to the toolcarrier or transformation data only become effective after Power On.
- Transformation change and swivel data record change are supported. However, a real kinematic change is not supported, where a swivel head is physically changed out.
- The simulation of mold building programs with extremely short block change times can take longer than machining, as the computation time distribution for this application is dimensioned in favor of the machining and to the detriment of simulation.

#### Examples

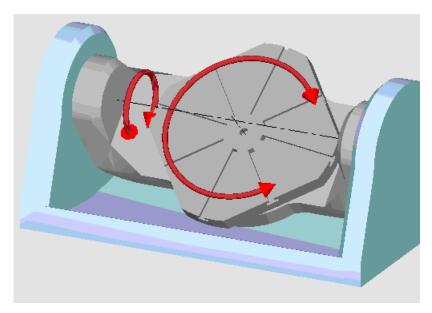
Several examples for machine types that are supported:



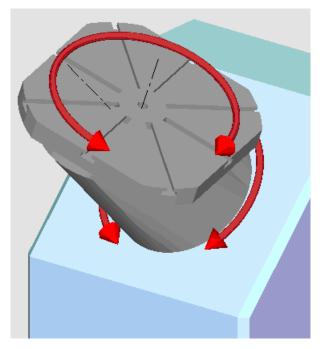
Swivel head 90°/90°



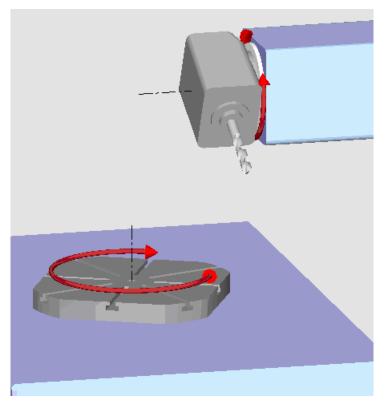
Swivel head 90°/45°



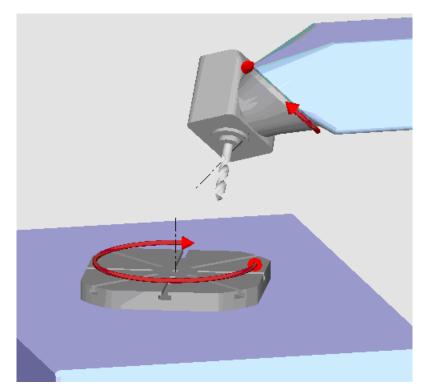
Swivel table 90°/90°



Swivel table 90°/45°



Swivel combination 90°/90°



Swivel combination 45°/90°

5.2 Simulation before machining of the workpiece

# 5.2 Simulation before machining of the workpiece

Before machining the workpiece on the machine, you have the option of performing a quick run-through in order to graphically display how the program will be executed. This provides a simple way of checking the result of the programming.

#### Feedrate override

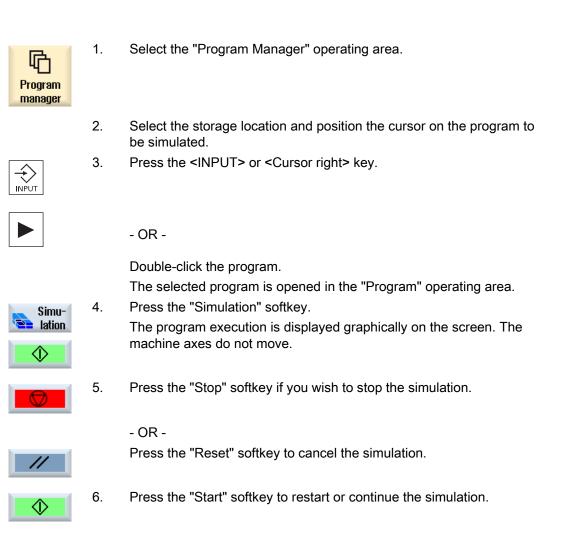
Feedrate override is also active during simulation.

You can change the feedrate during the simulation via the user interface.

0 %: The simulation stops.

100 %: The program is executed as quickly as possible.

#### Procedure



5.2 Simulation before machining of the workpiece

#### Note

#### Operating area switchover

The simulation is exited if you switch into another operating area. If you restart the simulation, then this starts again at the beginning of the program.

5.3 Simultaneous recording before machining of the workpiece

# 5.3 Simultaneous recording before machining of the workpiece

Before machining the workpiece on the machine, you can graphically display the execution of the program on the screen to monitor the result of the programming.



#### Software option

You require the option "Simultaneous recording (real-time simulation)" for the simultaneous recording.

You can replace the programmed feedrate with a dry run feedrate to influence the speed of execution and select the program test to disable axis motion.

If you would like to view the current program blocks again instead of the graphical display, you can switch to the program view.

#### Procedure

	1.	Load a program in the "AUTO" mode.
NC Prog. cntrl.	2.	Press the "Prog. ctrl." softkey and activate the checkboxes "PRT no axis movement" and "DRY run feedrate".
		The program is executed without axis movement. The programmed feedrate is replaced by a dry run feedrate.
Simult. record.	3.	Press the "Sim. rec." softkey.
	4.	Press the <cycle start=""> key.</cycle>
CYCLE START		The program execution is displayed graphically on the screen.
Simult. record.	5.	Press the "Sim. rec." softkey again to stop the recording.

5.4 Simultaneous recording during machining of the workpiece

# 5.4 Simultaneous recording during machining of the workpiece

If the view of the work space is blocked by coolant, for example, while the workpiece is being machined, you can also track the program execution on the screen.



#### Software option

You require the option "Simultaneous recording (real-time simulation)" for the simultaneous recording.

#### Procedure

1. Load a program in the "AUTO" mode.



- 2. Press the "Sim. rec." softkey.
- CYCLE START
- Press the <CYCLE START> key. The machining of the workpiece is started and graphically displayed on the screen.
- Simult. 4.
- Press the "Sim. rec." softkey again to stop the recording.

#### Note

- If you switch-on simultaneous recording after the unmachined part information has already been processed in the program, only traversing paths and tool are displayed.
- If you switch-off simultaneous recording during machining and then switch-on the function again at a later time, then the traversing paths generated in the intermediate time will not be displayed.

5.5 Different views of a workpiece

# 5.5 Different views of a workpiece

In the graphical display, you can choose between different views so that you constantly have the best view of the current workpiece machining, or in order to display details or the overall view of the finished workpiece.

The following views are available:

- Top view
- 3D view
- Side views

5.5.1 Plan view

	1.	Start the simulation.
Top view	2.	Press the "Top view" softkey.
		The workpiece is shown from above in the top view.

#### Changing the display

You can increase or decrease the size of the simulation graphic and move it, as well as change the segment.

#### 5.5.2 3D view

Further views	
3D view	

- 1. Starting the simulation.
- 2. Press the "Other views" and "3D view" softkeys.



#### Software option

You require the option "3D simulation (finished part)" for the simulation.

#### Changing the display

You can increase or decrease the size of the simulation graphic, move it, turn it, or change the segment.

5.5 Different views of a workpiece

#### Displaying and moving cutting planes

You can display and move cutting planes X, Y, and Z.

#### See also

Defining cutting planes (Page 198)

#### 5.5.3 Side views

Further views	1. 2.	Starting the simulation. Press the "Other views" softkey.
From front	3.	Press the "From front" softkey if you wish to view the workpiece from the front.
From rear		- OR - Press the "From rear" softkey if you wish to view the workpiece from the rear.
From left		- OR - Press the "From left" softkey if you wish to view the workpiece from the left.
From right		- OR - Press the "From right" softkey if you wish to view the workpiece from the right.

#### Changing the display

You can increase or decrease the size of the simulation graphic and move it, as well as change the segment.

5.6 Editing the simulation display

# 5.6 Editing the simulation display

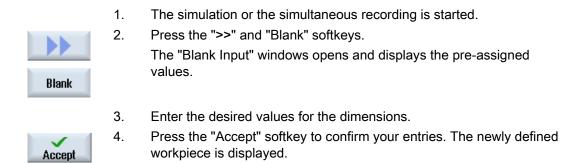
## 5.6.1 Entering blank details

You have the option of replacing the blank defined in the program or to define a blank for programs in which a blank definition cannot be inserted.

#### Note

The unmachined part can only be entered if simulation or simultaneous recording is in the reset state.

#### Procedure



# 5.6.2 Showing and hiding the tool path

1.

The path display follows the programmed tool path of the selected program. The path is continuously updated as a function of the tool movement. The tool paths can be shown or hidden as required.

The simulation or the simultaneous recording is started.

#### Procedure

		••	g i contration de la co
	2.	Press the ">>" softkey.	
			The tool paths are displayed in the active view.
	Show	3.	Press the softkey to hide the tool paths.
tool path		The tool paths are still generated in the background and can be shown again by pressing the softkey again.	
	Delete	4.	Press the "Delete tool path" softkey.
tool path		All of the tool paths recorded up until now are deleted.	

5.7 Program control during the simulation

# 5.7 Program control during the simulation

## 5.7.1 Changing the feedrate

You can change the feedrate at any time during the simulation.

You can track the changes in the status line.

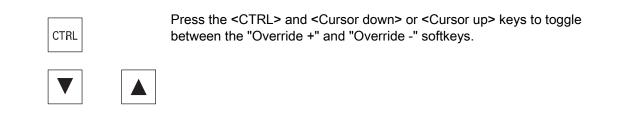
#### Note

If you are working with the "Simultaneous recording" function, the rotary switch (override) on the control panel is used.

#### Procedure

	1.	Simulation is started.
Program control	2.	Press the "Program control" softkey.
Override +	3.	Press the "Override +" or "Override -" softkey to increase or decrease the feedrate by 5%.
Override -		
		- OR -
100% override		Press the "Override 100%" softkey to set the feedrate to the maximum value.
		- OR -
		Press the "<<" softkey to return to the main screen and perform the simulation with changed feedrate.
Note		

Note Toggling between "Override +" and "Override -"

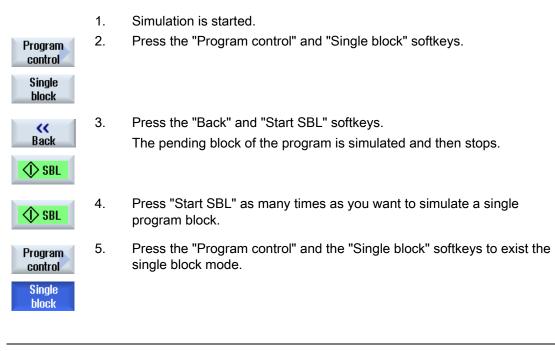


5.7 Program control during the simulation

#### 5.7.2 Simulating the program block by block

You can control the program execution during simulation, i.e. execute a program block by block, as when executing a program.

#### Procedure



## Note

#### Enabling/disabling single block



Press the <CTRL> and <S> keys simultaneously to enable and disable the single block mode.

5.8 Changing and adapting a simulation graphic

# 5.8 Changing and adapting a simulation graphic

# 5.8.1 Enlarging or reducing the graphical representation

#### Precondition

The simulation or the simultaneous recording is started.

#### Procedure

+	1.	Press the <+> and <-> keys if you wish to enlarge or reduce the graphic display. The graphic display enlarged or reduced from the center.
-		
		- OR -
Details		Press the "Details" and "Zoom +" softkeys if you wish to increase the size of the segment.
Zoom +		
		- OR -
Details		Press the "Details" and "Zoom -" softkeys if you wish to decrease the size of the segment.
Zoom -		
		- OR -
Details		Press the "Details" and "Auto zoom" softkeys if you wish to automatically adapt the segment to the size of the window.
Autozoom		The automatic scaling function "Fit to size" takes account of the largest expansion of the workpiece in the individual axes.

# Note Selected section

The selected sections and size changes are kept as long as the program is selected.

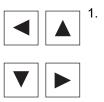
5.8 Changing and adapting a simulation graphic

# 5.8.2 Panning a graphical representation

#### Precondition

The simulation or the simultaneous recording is started.

#### Procedure



Press a cursor key if you wish to move the graphic up, down, left, or right.

#### 5.8.3 Rotating the graphical representation

In the 3D view you can rotate the position of the workpiece to view it from all sides.

#### Precondition

Simulation has been started and the 3D view is selected.

#### Procedure



1.

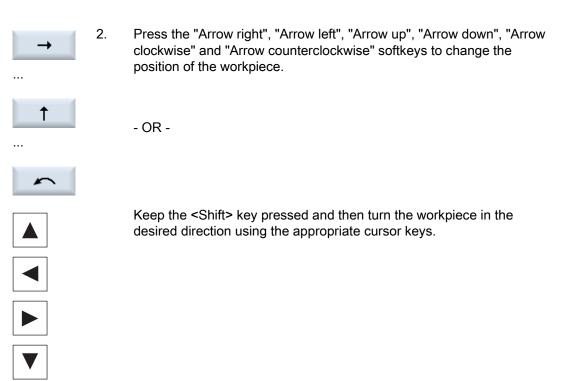
2.

Press the "Details" softkey.



Press the "Rotate view" softkey.

5.8 Changing and adapting a simulation graphic



#### 5.8.4 Modifying the viewport

If you would like to move, enlarge or decrease the size of the segment of the graphical display, e.g. to view details or display the complete workpiece, use the magnifying glass.

Using the magnifying glass, you can define your own segment and then increase or decrease its size.

#### Precondition

The simulation or the simultaneous recording is started.

#### Procedure

Details	1.	Press the "Details" softkey.
Zoom	2.	Press the "Magnifying glass" softkey. A magnifying glass in the shape of a rectangular frame appears.
Zoom +	3.	Press the "Magnify +" or <+> softkey to enlarge the frame.

- OR -

#### Simulating machining

5.8 Changing and adapting a simulation graphic

Zoom -	Press the '
	- OR - Press one
4.	Press the '

ress the "Magnify -" or <-> softkey to reduce the frame.

Press one of the cursor keys to move the frame up, down, left or right.

Press the "Accept" softkey to accept the section.

## 5.8.5 Defining cutting planes

In the 3D view, you have the option of "cutting" the workpiece and therefore displaying certain views in order to show hidden contours.

#### Precondition

The simulation or the simultaneous recording is started.

#### Procedure

Details Cut

> Cut active

> > X +

Z -

1.

2. Press the "Cut" softkey.

Press the "Details" softkey.

- The workpiece is displayed in the cut state.
- 3. Press the corresponding softkey to shift the cutting plane in the required direction.

5.9 Displaying simulation alarms

# 5.9 Displaying simulation alarms

Alarms might occur during simulation. If an alarm occurs during a simulation run, a window opens in the operating window to display it.

The alarm overview contains the following information:

- Date and time
- Deletion criterion

Specifies with which softkey the alarm is acknowledged

- Alarm number
- Alarm text

#### Precondition

Simulation is running and an alarm is active.

#### Procedure

Program control Alarm	1.	Press the "Program control" and "Alarm" softkeys. The "Simulation Alarms" window is opened and a list of all pending alarms is displayed.
Acknowl. alarm		Press the "Acknowledge alarm" softkey to reset the simulation alarms indicated by the Reset or Cancel symbol. The simulation can be continued. - OR -
Simulation Power On		Press the "Simulation Power On" softkey to reset a simulation alarm indicated by the Power On symbol.

Simulating machining

5.9 Displaying simulation alarms

# Creating G code program

# 6.1 Graphical programming

#### Functions

The following functionality is available:

- Technology-oriented program step selection (cycles) using softkeys
- · Input windows for parameter assignment with animated help screens
- Context-sensitive online help for every input window
- Support with contour input (geometry processor)

#### Call and return conditions

- The G functions active before the cycle call and the programmable frame remain active beyond the cycle.
- The starting position must be approached in the higher-level program before the cycle is called. The coordinates are programmed in a clockwise coordinate system.

6.2 Program views

# 6.2 Program views

You can display a G code program in various ways.

- Program view
- Parameter screen, either with help screen or graphic view

#### Program view

The program view in the editor provides an overview of the individual machining steps of a program.

NC/SIM_ZYK_T_26/AUS_IN 10	Select
g, Jourrenten II	tool
CYCLE76(100, 0, 1, , 4, 156, 156, 10, 0, 0, 0, 5, 0.2, 0.2, 800, 500, 0, 2, 160, 160, 1,	
N5 CYCLE76 (100, 0, 1, , 3, 138, 138, 5, 9, 9, 0, 4, 0, 0.2, 800, 500, 0, 2, 156, 156, 1, 2, 2	
CYCLE72("", 100, 0, 1, 3, 4, 0.2, 0.2, 800, 500, 102, 41, 3, 20, 1000, 3, 20, 0, 1, 2, 1 GO Z200 T	
N10 T="SCHAFTFRAESER D6" M6¶	
N15D1 F700 S10000 M03¶	Search
N2Q:Innenbearbeitung¶	
N25; Schruppen¶	Mark
CYU POCKET3 (100, 0, 1, 1.5, 60, 35, 8, 78, 50, 15, 2.5, 0.2, 0.2, 700, 300, 0, 21, 66, 🖃	TIGIN
N30 SLOT2(100, 0, 1, , 3, 3, 45, 10, 78, 115, 35, 180, 67.5, 250, 700, 4, 0, 0.2, 1, 0, 0, 0,	
C SLOT1(100, -1.5, 1, , 1.5, 1, 30, 10, 78, 50, , 15, 0, 300, 700, 2.5, 0, 0.2, 31, , , , 0.	Сору
¶ MCALL SLOT1(100, 0, 1, −3, , 1, 20, 10, 78, 125, , 0, 0, 300, 700, 4, 0, 0.2, 31, , , , 0.	
N35POS1: HOLES2(78, 125, 7.5, 0, -90, 3, 2, 0, , , 1)¶	
MO¶HCALL¶	Paste
N40; Schlichten¶	
N45 POCKET3(100, 0, 1, 1.5, 60, 35, 8, 78, 50, 15, 4, 0.2, 0.2, 600, 300, 0, 12, 66, 15, 10	
N5(SLOT2(100, 0, 1, , 3, 3, 45, 10, 78, 115, 35, 180, 67.5, 300, 700, 3, 0, 0.2, 2002, 4, 6 N5(SLOT1(100, -1.5, 1, , 1.5, 1, 30, 10, 78, 50, , 15, 0, 200, 600, 5, 0, 0.2, 12, 5, 600, 1	Cut
N5350011(100, -1.3, 1, 1.3, 1, 30, 10, 78, 50, 13, 0, 200, 000, 3, 0, 0.2, 12, 3, 000, 1 N60MCALL SLOT1(100, 0, 1, -3, , 1, 20, 10, 78, 125, , 0, 0, 200, 600, 4, 0, 0.2, 12, 5, 600_	
NDUNCHEL SECTED, 5, 1, 3, 1, 20, 10, 70, 123, , 0, 0, 200, 000, 4, 0, 0.2, 12, 3, 000	
Edit = Drill. I Turn- Cont. T Mill. E Vari- ing turn. Turn. I Mill. E Vari- ous lation	NC Ex-

Figure 6-1 Program view of a G code program



In the program view, you can move between the program blocks using the <Cursor up> and <Cursor down> keys.

#### Parameter screen with help display



Press the <Cursor right> or the <Input> key to open a selected program block or cycle in the program view.

The associated parameter screen with help screen is then displayed.

NC/NC/NC	Rectar	ngular pocket			
	PL	617 (XY)	Down-cut	$\sim$	
	RP	100.000		Π.	
	SC	1.000			Graphic
	F	700.000			view
	Ref. p		· •		
	Machi				Rectang.
		Single p	osition		pocket
	XO	78.000			
	YO	50.000		≣	
	20	0.000			
	W	35.000			
	L	60.000			
Land Y	R	8.000	•		
	α0	15.000			i
	Z1	1.500			
	DXY	66.000	mm		
	DZ	2.500		H.	
	UXY UZ	0.200 0.200			×
	uz Inserti		Helical		Cancel
	mser u	UII	nelical		
	FP	2.000	/reu >	-	Accept
Cont.		📕 💻 Vari	-		
Edit 🦾 Drill. 📥 Mill. 🛃 Cont. 🗾		Uari ous		n	ecute

Figure 6-2 Parameter screen with help display

The animated help displays are always displayed with the correct orientation to the selected coordinate system. The parameters are dynamically displayed in the graphic. The selected parameter is displayed highlighted in the graphic.

#### The color symbols

Red arrow = tool traverses in rapid traverse

Green arrow = tool moves with the machining feedrate

#### Parameter screen with graphic view



Using the "Graphic view" softkey, you can toggle between the help screen and the graphic view in the screen.

6.2 Program views

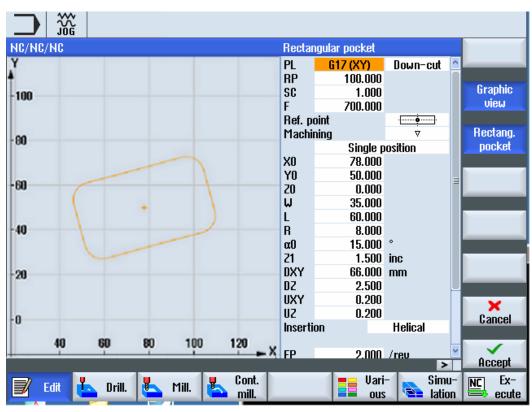


Figure 6-3 Parameter screen with a graphical view of a G code program block

# 6.3 Program structure

G\_code programs can always be freely programmed. The most important commands that are included in the rule:

- Set a machining plane
- Call a tool (T and D)
- Call a work offset
- Technology values such as feedrate (F), speed and direction of rotation of the spindle (S and M)
- Positions and calls, technology functions (cycles)
- End of program

For G code programs, before calling cycles, a tool must be selected and the required technology values F, S programmed.

A blank can be specified for simulation.

#### See also

Blank input (Page 210)

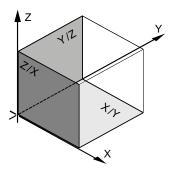
6.4 Basics

# 6.4 Basics

#### 6.4.1 Machining planes

A plane is defined by means of two coordinate axes. The third coordinate axis (tool axis) is perpendicular to this plane and determines the infeed direction of the tool (e.g. for 2½-D machining).

When programming, it is necessary to specify the working plane so that the control system can calculate the tool offset values correctly. The plane is also relevant to certain types of circular programming and polar coordinates.



#### Working planes

Working planes are defined as follows:

Plane		Tool axis
X/Y	G17	Z
Z/X	G18	Y
Y/Z	G19	Х

## 6.4.2 Current planes in cycles and input screens

Each input screen has a selection box for the planes, if the planes have not been specified by NC machine data.

- Empty (for compatibility reasons to screen forms without plane)
- G17 (XY)
- G18 (ZX)
- G19 (YZ)

There are parameters in the cycle screens that have names dependent on this plane setting and that are displayed accordingly, e.g. Z0, Z1 or X0, Y0.

If the entry field remains empty, the parameters, the help screens and the broken-line graphics are displayed in the default plane (can be set via machine data):

• Milling: G17 (XY)

The plane is transferred to the cycles as new parameter. The plane is output in the cycle, i.e. the cycle runs in the entered plane. It is also possible to leave the plane fields empty and thus create a plane-independent program.

The entered plane only applies for this cycle (not modal)! At the end of the cycle, the plane from the main program applies again. In this way, a new cycle can be inserted in a program without having to change the plane for the remaining program.

#### 6.4.3 Programming a tool (T)

#### Calling a tool

- 1. You are in a part program 2. Press the "Select tool" softkey. Select tool The "Tool selection" window is opened. 3. Position the cursor on the desired tool and press the "To program" To softkey. program The selected tool is loaded into the G code editor. Text such as the following is displayed at the current cursor position in the G code editor: T="ROUGHINGTOOL100" - OR -4. Press the "Tool list" and "New tool" softkeys. Tool list New tool 5. Then select the required tool using the softkeys on the vertical softkey To bar, parameterize it and then press the softkey "To program". program
  - The selected tool is loaded into the G code editor.
  - 6. Then program the tool change (M6), the spindle direction (M3/M4), the spindle speed (S...), the feedrate (F), the feedrate type (G94, G95,...), the coolant (M7/M8) and, if required, further tool-specific functions.

6.5 Generating a G code program

#### 6.5 Generating a G code program

Create a separate program for each new workpiece that you would like to produce. The program contains the individual machining steps that must be performed to produce the workpiece.

Part programs in the G code can be created under the "Workpiece" folder or under the "Part programs" folder.

#### Procedure

Program manager	1.	Select the "Program Manager" operating area.				
NC NC	2.	Select the required archiving location.				
Creating a ne	Creating a new part program					
New	3.	Position the cursor on the folder "Part programs" and press the "New" softkey.				
programGUIDE <b>G code</b>		The "New G Code Program" window opens.				
OK	4.	Enter the required name and press the "OK" softkey. The name can contain up to 28 characters (name + dot + 3-character extension). You can use all letters (except accented characters), digits and underscores (_). The program type (MPF) is set by default.				
		The project is created and opened in the Editor.				
Creating a ne	ew par	t program for a workpiece				
New	5.	Position the cursor on the folder "Workpieces" and press the "New" softkey.				
programGUIDE <b>G code</b>		The "New G Code Program" window opens.				
ОК	6.	Select the file type (MPF or SPF), enter the desired name of the program and press the "OK" softkey.				
		The project is created and opened in the Editor.				
	7.	Enter the desired G code commands.				

See also

Changing a cycle call (Page 219) Creating a new workpiece (Page 522) Selection of the cycles via softkey (Page 213) 6.6 Blank input

# 6.6 Blank input

#### Function

The blank is used for the simulation and the simultaneous recording. A useful simulation can only be achieved with a blank that is as close as possible to the real blank.

Create a separate program for each new workpiece that you would like to produce. The program contains the individual machining steps that are performed to produce the workpiece.

For the blank of the workpiece, define the shape (cuboid, tube, cylinder, polygon or centered cuboid) and your dimensions.

#### Manually reclamping the blank

If the blank is to be manually reclamped from the main spindle to the counterspindle for example, then delete the blank.

#### Example

- Blank, main spindle, cylinder
- Machining
- M0; Manually reclamping the blank
- Blank, main spindle, delete
- Blank, counterspindle, cylinder
- Machining

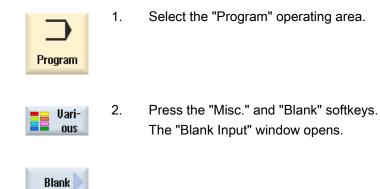
The blank entry always refers to the work offset currently effective at the position in the program.

#### Note

#### Swiveling

For programs that use "Swiveling", a 0 swivel must first be made and then the blank defined.

#### Procedure



Parameter	Description	Unit
Data for	Selection of the spindle for blank	
Data IOI	Main spindle	
	Counterspindle	
	Note:	
	If the machine does not have a counterspindle, then the entry field "Data for" is not applicable.	
Blank	Selecting the blank	
U	Cuboid	
-	• Tube	
	Cylinder	
	• Polygon	
	Centered cuboid	
	• Delete	
X0	1st rectangular point X - (only for cuboid)	
Y0	1st rectangular point Y - (only for cuboid)	
X1 🖸	2nd rectangular point X (abs) or 2nd rectangular point X referred to X0 (inc) - (only for cuboid)	
Y1 🖸	2nd rectangular point Y (abs) or 2nd rectangular point Y referred to Y0 (inc) - (only for cuboid)	
ZA	Initial dimension	
ZI Ŭ	Final dimension (abs) or final dimension in relation to ZA (inc)	
ZB 🔾	Machining dimension (abs) or machining dimension in relation to ZA (inc)	
ХА	Outside diameter – (only for tube and cylinder)	mm
XI Ŭ	Inside diameter (abs) or wall thickness (inc) – (only for tube)	mm
Ν	Number of edges – (only for polygon)	
SW or L U	Width across flats or edge length – (only for polygon)	
W	Width of the blank - (only for centered cuboid)	mm
L	Length of the blank - (only for centered cuboid)	mm

6.7 Machining plane, milling direction, retraction plane, safe clearance and feedrate (PL, RP, SC, F)

# 6.7 Machining plane, milling direction, retraction plane, safe clearance and feedrate (PL, RP, SC, F)

In the program header, cycle input screens have general parameters that are always repeated. You will find the following parameters in every input screen for a cycle in a G code program.

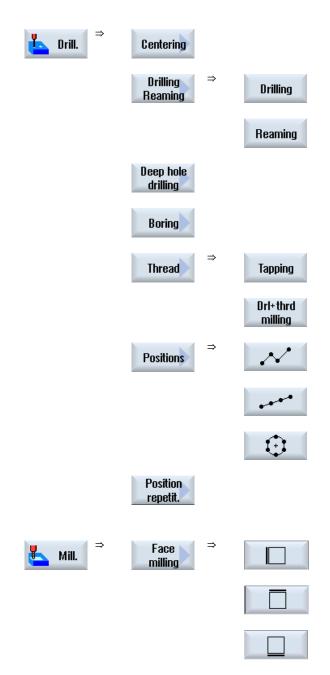
Parameter	Description	Unit
PL O	<ul> <li>Each input screen has a selection box for the planes, if the planes have not been specified by NC machine data.</li> <li>Machining plane:</li> <li>G17 (XY)</li> <li>G18 (ZX)</li> <li>G19 (YZ)</li> </ul>	
Milling direction	When milling, the machining direction of rotation ( <b>climbing</b> or <b>conventional</b> ) and the spindle direction of rotation in the tool list are taken into consideration. The pocket is then machined in a clockwise or counterclockwise direction. During path milling, the programmed contour direction determines the machining direction.	
RP	Retraction plane (abs) During machining the tool travels in rapid traverse from the tool change point to the return plane and then to the safety clearance. The machining feedrate is activated at this level. When the machining operation is finished, the tool travels at the machining feedrate away from the workpiece to the safety clearance level. It travels from the safety clearance to the retraction plane and then to the tool change point in rapid traverse. The retraction plane is entered as an absolute value. Normally, reference point Z0 and retraction plane RP have different values. The cycle assumes that the retraction plane is in front of the reference point.	mm
sc O	Safety clearance (inc) Acts in relation to the reference point. The direction in which the safety clearance is effective is automatically determined by the cycle. The safety clearance must be entered as an incremental value (without sign).	mm
F	Feedrate The feedrate F (also referred to as the machining feedrate) specifies the speed at which the axes move during machining of the workpiece. The machining feedrate is entered in mm/min, mm/rev or in mm/tooth before programming a cycle. The maximum feedrate is determined via machine data.	mm/min mm/rev mm/tooth

# 6.8 Selection of the cycles via softkey

#### Overview of machining steps

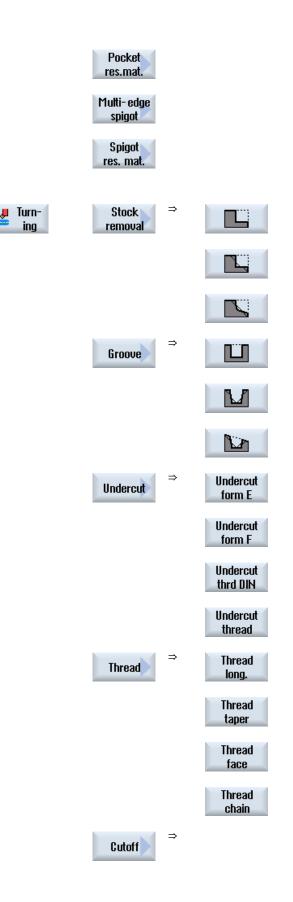
The following softkey bars are available to insert machining steps.

All of the cycles/functions available in the control are shown in this display. However, at a specific system, only the steps possible corresponding to the selected technology can be selected.

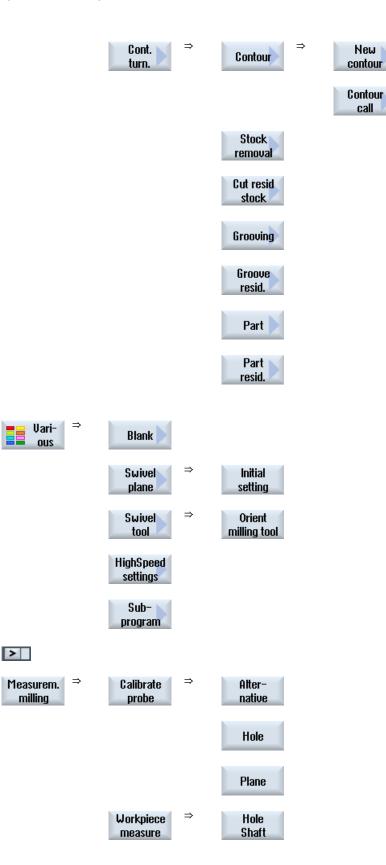


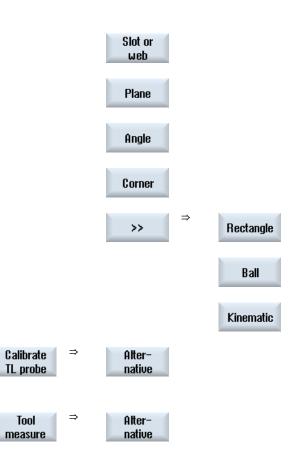
6.8 Selection of the cycles via softkey





6.8 Selection of the cycles via softkey





# See also

General (Page 273) Generating a G code program (Page 208)

# 6.9 Calling technology functions

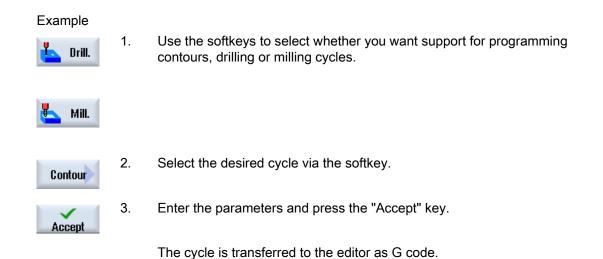
# 6.9.1 Hiding cycle parameters

The documentation describes all the possible input parameters for each cycle. Depending on the settings of the machine manufacturer, certain parameters can be hidden in the screens, i.e. not displayed. These are then generated with the appropriate default values when the cycles are called.

For additional information, please refer to the following documentation:

Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

# Cycle support



# 6.9.2 Setting data for cycles

Cycle functions can be influenced and configured using machine and setting data. For additional information, please refer to the following documentation: Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

# 6.9.3 Checking cycle parameters

The entered parameters are already checked during the program creation in order to avoid faulty entries.

If a parameter is assigned an illegal value, this is indicated in the input screen and is designated as follows:

- The entry field has a colored background (background color, pink).
- A note is displayed in the comment line.
- If the parameter input field is selected using the cursor, the not is also displayed as tooltip.

The programming can only be completed after the incorrect value has been corrected.

Faulty parameter values are also monitored with alarms during the cycle runtime.

# 6.9.4 Changing a cycle call

You have called the desired cycle via softkey in the program editor, entered the parameters and confirmed with "Accept".

# Procedure



分

SHIFT

 Select the desired cycle call and press the <Cursor right> key. The associated input screen of the selected cycle call is opened.

- OR -

Press the <SHIFT + INSERT> key combination.

This starts the edit mode for this cycle call and you can edit it like a normal NC block. In this way, it is possible to create an empty block before the cycle call.

Note: In edit mode, the cycle call can be changed in such a way that it can no longer be recompiled in the parameter screen.



 $\langle \rangle$ 

INSERT

You exit the edit mode by pressing the <SHIFT + INSERT> key combination.

- OR -

You are in the edit mode and press the <INPUT> key. A new line is inserted before the selected cycle call.

### See also

Generating a G code program (Page 208)

6.9 Calling technology functions

# 6.9.5 Additional functions in the input screens

# Selection of units

If, for example, the unit can be switched in a field, this is highlighted as soon as the cursor is positioned on the element. In this way, the operator recognizes the dependency.

The selection symbol is also displayed in the tooltip.

# Display of abs or inc

The abbreviations "abs" and "inc" for absolute and incremental values are displayed behind the entry fields when a switchover is possible for the field.

## Help screens

2D and 3D graphics or sectional views are displayed for the parameterization of the cycles.

# **Online help**

If you wish to obtain more detailed information about certain G code commands or cycle parameters, then you can call a context-sensitive online help.

# 6.10 Measuring cycle support

Measuring cycles are general subroutines designed to solve specific measurement tasks. They can be adapted to specific problems via parameter settings.



### Software option

You require the "Measuring cycles" option to use "Measuring cycles".

### Note

## Using measuring cycles

The program measuring cycles, which are in the editor at the menu forward bar, cannot be handled using the usual functions, such as display tooltips, animated help, close screen with <Cursor left> key.

For measuring generally, a distinction is made between:

- Workpiece measurement
- Tool measurement

### Workpiece measurement

For the measurement, a workpiece probe is brought to the workpiece to be measured (just like a tool) and the measuring positions are acquired. As a result of the flexible structure of measuring cycles, almost all measuring tasks that have to be realized in a milling machine can be handled. An automatic tool offset or WO can be applied to the workpiece measurement result.

### **Tool measurement**

For the tool measurement, the loaded tool to be measured is moved up to the probe and the measured values of the geometry are acquired. The probe is either in a fixed in position or is swung into the working area with a mechanism. The tool geometry that is acquired is entered in the appropriate tool offset data set.

### References

You will find a more detailed description on how to use measuring cycles in:

HMI sl / SINUMERIK 840D sl Programming Manual Measuring Cycles

6.10 Measuring cycle support

# Procedure

>	1.	Press the menu forward key.
Measurem. milling	2.	Press the horizontal "Measure mill" softkey.
Calibrate probe	3.	Using a vertical softkey, select the desired measurement function group, e.g. "Calibrate probe".
		- OR -
Workpiece measure		Measure workpiece
		- OR -
Calibrate TL probe		Calibrate workpiece probe
		- OR -
Tool measure		Measure tool
	4.	Using a vertical softkey, select a measurement task.
	5.	Enter the parameters into the measuring cycle screen.
<b>~</b>	6.	Press the "OK" softkey.
ОК		The measuring cycle is transferred into the editor as G code. The measuring cycle parameterized in the G code is color coded.
	7.	Position the cursor on a measuring cycle in the G code editor, if you want to display the associated parameter screen form again.
	8.	Press the <cursor right=""> key.</cursor>
		The parameter screen for the selected measuring cycle appears.
		- OR -
INSERT	9.	Press the <shift> + <insert> keys to remove the measuring cycle selection in the editor and to be able to directly change the parameters in the editor.</insert></shift>

# Creating a ShopMill program

The program editor offers graphic programming to generate machining step programs that you can directly generate at the machine.



### Software option

You require the "ShopMill/ShopTurn" option to generate ShopMill machining step programs.

# **Functions**

The following functionality is available:

- Technology-oriented program step selection (cycles) using softkeys
- · Input windows for parameter assignment with animated help screens
- Context-sensitive online help for every input window
- Support with contour input (geometry processor)

7.1 Program views

# 7.1 Program views

You can display a ShopMill program in various views:

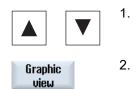
- Machining schedule
- Programming graphics
- Parameter screen, either with help display or programming graphics

### Machining schedule

The work plan in the editor provides an overview of the individual machining steps of a program.

NC/MANN/PGM_MAN	3	Select
P N5 Programmkopf	Nullpunktversch. G54 📃	tool
∼1H100 Kontur	PLANEN 3	Creatia
M105 Zapten Fräsen	T-D6R08 F0.15/2 S10000U 2F9	Graphic view
A N210 Einstellungen	Gegenlauf Rohteil	VIEW
G H405 E_CON("OBEN_LINKS", 1, "E_LAB_A	_OBEN_LINKS", "E_LAB_E_OBEN_LIN	
KS" ); *R0*¶		Search
M15 Tasche Fräsen	T-D6R08 F0.06/2 S10000U 2FS-1	
🕸 H290 Einstellungen	Gleichlauf Rohteil	Mark
G N410 E_CON("OBEN_HITTE", 1, "E_LAB_A	_OBEN_MITTE", "E_LAB_E_OBEN_MIT	Пак
TE"); *R0*¶		
M25 Tasche Fräsen	T=D6R08 F0.06/2 S10000U 2FS=1	Сору
G N415 E_CON("OBEN_RECHTS", 1, "E_LAB_	A_OBEN_RECHTS", "E_LAB_E_OBEN_R	
ECHTS"); *R0*¶		
😭 H45 Tasche Fräsen	T=D6R08 F0.06/2 S10000U 2FS=1	Paste
G H420 E_COH("UNTEN_LINKS", 1, "E_LAB_	A_UNTEN_LINKS", "E_LAB_E_UNTEN_	
LINKS"); *R0*¶		
🕼 N340 Tasche Fräsen	T=D6R08 F0.06/2 S10000U ZFS=1	Cut
G H425 E_CON("UNTEN_MITTE", 1, "E_LAB_	A_UNTEN_MITTE", "E_LAB_E_UNTEN_	
HITTE"); *R0*¶	T-DEDOG FO 08/7 C100000 7FC-1	
Toppho France		
Edit 🖌 Drill, 🖳 Mill, 🖳 Con	t. 🗧 🗾 Vari- 📉 Simu-	NC Ex-
	I. 🛛 📲 ous 🛸 lation	🚔 ecute

Figure 7-1 Machining schedule of a ShopMill program



- You can move between the program blocks in the machining schedule using the <Cursor up> and <Cursor down> keys.
- Press the "Graphics view" softkey to display the programming graphics.

# **Programming graphics**

The programming graphics show the contour of the workpiece as a dynamic graphic with dotted lines. The program block selected in the machining schedule is highlighted in color in the programming graphics.

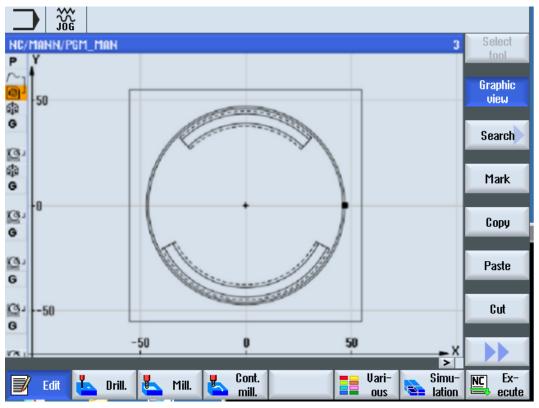


Figure 7-2 Programming graphics of a ShopMill program

### Parameter screen with help display



Press the <Cursor right> or <Input> key to open a selected program block or cycle in the work plan.

The associated parameter screen with help screen is then displayed.

7.1 Program views

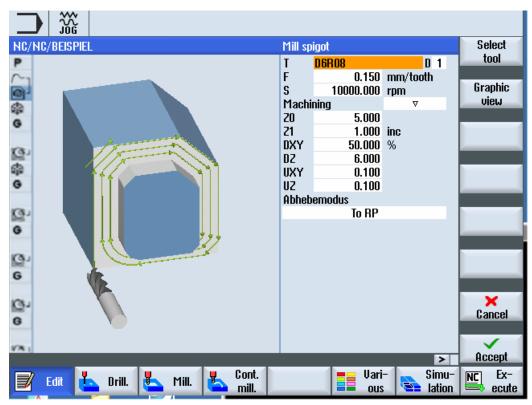


Figure 7-3 Parameter screen with help display

The animated help displays are always displayed with the correct orientation to the selected coordinate system. The parameters are dynamically displayed in the graphic. The selected parameter is displayed highlighted in the graphic.

### The color symbols

Red arrow = tool traverses in rapid traverse

Green arrow = tool moves with the machining feedrate

### Parameter screen with programming graphics



In the screen, you can toggle between the help display and the program graphics using the "Graphic view".

7.1 Program views

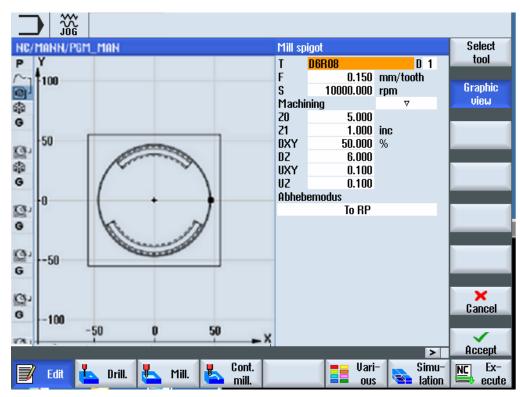


Figure 7-4 Parameter screen with programming graphics

7.2 Program structure

# 7.2 Program structure

A machining step program is divided into three sub-areas:

- Program header
- Program blocks
- End of program

These sub-areas form a work plan.

### Program header

The program header contains parameters that affect the entire program, such as blank dimensions or retraction planes.

### **Program blocks**

You determine the individual machining steps in the program blocks. In doing this, you specify the technology data and positions, among other things.

### Linked blocks

For the "Contour milling", "Milling", and "Drilling" functions, program the technology blocks and contours or positioning blocks separately. These program blocks are automatically linked by the control and connected by brackets in the work plan.

In the technology blocks, you specify how and in what form the machining should take place, e.g. centering first, and then drilling. In the positioning blocks, you define the positions for drilling or milling operations.

### End of program

End of program signals to the machine that the machining of the workpiece has ended. Further, here you set whether program execute should be repeated.

### Note

#### Number of workpieces

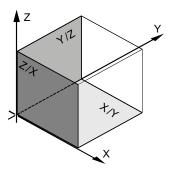
You can enter the number of required workpieces using the "Times, counters" window.

# 7.3 Basic information

# 7.3.1 Machining planes

A plane is defined by means of two coordinate axes. The third coordinate axis (tool axis) is perpendicular to this plane and determines the infeed direction of the tool (e.g. for 2½-D machining).

When programming, it is necessary to specify the working plane so that the control system can calculate the tool offset values correctly. The plane is also relevant to certain types of circular programming and polar coordinates.



### Working planes

Working planes are defined as follows:

Plane		Tool axis	
X/Y	G17	Z	
Z/X	G18	Y	
Y/Z	G19	Х	

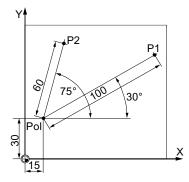
# 7.3.2 Polar coordinates

The rectangular coordinate system is suitable in cases where dimensions in the production drawing are orthogonal. For workpieces dimensioned with arcs or angles, it is better to define positions using polar coordinates. This is possible if you are programming a straight line or a circle.

Polar coordinates have their zero point at the "pole".

7.3 Basic information

## Example



Points P1 and P2 can then be described – with reference to the pole – as follows:

P1:Radius =100 / angle =30°

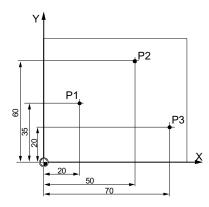
P2:Radius =60 / angle =75°

# 7.3.3 Absolute and incremental dimensions

### Absolute dimensions

With absolute dimensions, all the position specifications refer to the currently valid zero point. Applied to tool movement this means: The absolute dimension data defines the position, to which the tool is to travel.

# Example



The position data points P1 to P3 in absolute dimensions relative to the zero point are the following:

P1: X20 Y35 P2: X50 Y60

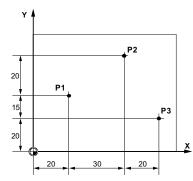
P3: X70 Y20

### Incremental dimensions

In the case of production drawings in which dimensions refer to some other point on the workpiece rather than the zero point, it is possible to enter an incremental dimension.

When incremental dimensions are entered, each item of position data refers to a point programmed beforehand.

## Example



The position data for points P1 to P3 in incremental dimensions are:

P1: X20 Y35 ;(referred to the zero point)

P2: X30 Y20 ;(referred to P1)

P3: X20 Y-35 ;(referred to P2)

# 7.4 Creating a ShopMill program

#### 7.4 Creating a ShopMill program

Create a separate program for each new workpiece that you would like to produce. The program contains the individual machining steps that must be performed to produce the workpiece.

If you create a new program, a program header and program end are automatically generated.

ShopMill programs can be created in a new workpiece or under the folder "Part programs".

# Procedure



- 1. Select the "Program Manager" operating area.
- 2. Select the desired storage location and position the cursor on the folder "Part programs" or under the folder "Workpieces" on the workpiece for which you wish to create a program.
- 3. Press the "New" and "ShopMill" softkeys. The "New machining step programming" window opens.

Enter the required name and press the "OK" softkey. The name can contain up to 28 characters (name + dot + 3-character extension). You can use all letters (except accented characters), digits and underscores (\_). The "ShopMill" program type is selected. The editor is opened and the "Program header" parameter screen is displayed.

# Filling-out the program header

6.

4.



Select a work offset and enter the dimensions of the blank and the 5. parameters, which are effective over the complete program, e.g. dimension units in mm or inch, tool axis, retraction plane, safety clearance and machining direction.



Press the "Accept" softkey. The work plan is displayed. Program header and end of program are created as program blocks.

The end of program is automatically defined.

# See also

Changing program settings (Page 245) Creating a new workpiece (Page 522)

# 7.5 Program header

In the program header, set the following parameters, which are effective for the complete program.

Parameter	Description	Unit	
Measurement unit U	The dimension unit ( <b>mm</b> or <b>inch</b> ) set in the program header only refers to the position data in the actual program. All other data, such as feedrate or tool offsets, are entered in the dimension unit that you have set for the entire machine.		
Work offset 🚺	The work offset in which the workpiece zero is saved.		
	You can also delete the pre-setting of the parameter if you do not want to specify a work offset.		
Blank U	Define the form and dimensions of the workpiece		
	Cylinder		
ХА	Outer diameter $\varnothing$	mm	
	Polygon		
Ν	Number of edges		
SW/L	Width across flats Edge length		
U	Centered cuboid		
W	Width of blank	mm	
L	Length of blank	mm	
	Cuboid		
X0	1st corner point X	mm	
Y0	1st corner point Y	mm	
X1 Ŭ	2nd corner point X (abs) or 2nd corner point X referred to X0 (inc)	mm	
Y1 Ŭ	2nd corner point Y (abs) or 2nd corner point Y referred to Y0 (inc)	mm	
	• Tube		
ХА	Outer diameter $\varnothing$	mm	
XI 🖸	Inner diameter $\varnothing$ (abs) or wall thickness (inc)	mm	
ZA	Initial dimension		
ZI Ŭ	Final dimension (abs) or final dimension in relation to ZA (inc)		
PL Ŭ	Machining plane		
	G17 (XY)		
	G18 (ZX)		
	G19 (YZ)		
	Note: The plane settings can already be defined. Ask the machine manufacturer in order that the selection box is available.		

# Creating a ShopMill program

# 7.5 Program header

Parameter	Description	Unit
Retraction plane RP	Planes above the workpiece.	
Safety clearance SC:	During machining the tool travels in rapid traverse from the tool change point to the return plane (RP) and then to the safety clearance (SC). The machining feedrate is activated at this level. When the machining operation is finished, the tool travels at the machining feedrate away from the workpiece to the safety clearance level. It travels from the safety clearance to the retraction plane and then to the tool change point in rapid traverse. The retraction plane is entered as an absolute value.	
	The safety clearance must be entered as an incremental value (without sign).	
Machining direction 🧿	When machining a pocket, a longitudinal slot or a spigot, ShopMill takes the machining direction ( <b>climbing</b> or <b>conventional</b> ) and the spindle direction in the tool list into account. The pocket is then machined in a clockwise or counterclockwise direction.	
	During path milling, the programmed contour direction determines the machining direction.	
Retraction position	optimized	
pattern 💟	When machining with optimized retraction, the tool travels across the workpiece at the machining feedrate depending on the contour and with a safety clearance (SC).	
	• to RP	
	When retracting to RP, the tool is retracted to the retraction plane when the machining step is complete and infeeds at the new position. Collisions with workpiece obstacles are thus prevented when the tool is retracted and fed in, e.g. when holes in pockets or grooves are machined at different levels and positions.	

#### 7.6 Generating program blocks

After a new program is created and the program header is filled out, define the individual machining steps in program blocks that are necessary to produce the workpiece.

You can only generate program blocks between the program header and the end of the program.

# Procedure

### Selecting a technological function

1. Position the cursor in the work plan on the line behind which a new program block is to be inserted.



2. Using the softkeys, select the desired function. The associated parameter screen is displayed.



...

3. First, program the tool, offset value, feedrate and spindle speed (T, D, F, S, V) and then enter the values for the other parameters.

# Selecting a tool from the tool list

selecting a		
Select tool	4.	Press the "Select tools" softkey if you wish to select the tool for parameter "T".
		The "Tool selection" window is opened.
To program	5.	Position the cursor on the tool that you wish to use for machining and press the "To program" softkey.
		The selected tool is accepted into the parameter screen form. - OR -
Tool list		Press the "Tool list" and "New tool" softkeys.
New tool		
		Using the softkeys on the vertical softkey bar, select the required tool with the data and press the "To program" softkey

with the data and press the "To program" softkey.

The selected tool is accepted into the parameter screen form.

The process plan is displayed and the newly generated program block is marked.

7.7 Tool, offset value, feed and spindle speed (T, D, F, S, V)

# 7.7 Tool, offset value, feed and spindle speed (T, D, F, S, V)

Generally, the following parameters are entered for a program block.

## Tool (T)

Each time a workpiece is machined, you must program a tool. Tools are selected by name, and the selection is integrated in all parameter screen forms of the machining cycles (with the exception of the straight line/circle).

The tool length offsets become active as soon as the tool is changed.

Tool selection is modal for the straight line/circle, i.e. if the same tool is used to perform several machining steps occur in succession, you only have to program one tool for the first straight line/circle.

### Cutting edge (D)

In the case of tools with several cutting edges, there is a separate set of individual tool offset data for each edge. For these tools, you must select or specify the number of the cutting edge that you would like to use for machining.

### CAUTION

Collisions may occur if you specify the wrong cutting edge number for some tools (e.g. a flat chamfering drill with guide spigot or step drill) and then traverse the tool. Always ensure that you enter the correct cutting edge number.

### Tool length compensation

Tool length compensation takes effect as soon as the tool is loaded into the spindle. Different tool offsets can be assigned to each tool with multiple cutting edges.

The tool length compensation of the spindle tool remains active even after the program has been executed (RESET).

### **Radius compensation**

The tool radius compensation is automatically included in the machining cycles except for path milling.

For path milling and straight line/circle, you have the option of programming the machining with or without radius compensation. The tool radius compensation is modal for straight lines/circles, i.e. you have to deselect the radius compensation if you want to traverse without radius compensation.

### Creating a ShopMill program

7.7 Tool, offset value, feed and spindle speed (T, D, F, S, V)

- Radius compensation to right of contour
- Radius compensation to left of contour
- Radius compensation off
  - Radius compensation remains as previously set

### Feedrate (F)

The feedrate F (also referred to as the machining feedrate) specifies the speed at which the tool moves when machining the workpiece. The machining feedrate is entered in mm/min, mm/rev or in mm/tooth. The feedrate for milling cycles is automatically converted when switching from mm/min to mm/rev and vice versa.

It is only possible to enter the feedrate in mm/tooth during milling; this ensures that each cutting edge of the milling cutter is cutting under the best possible conditions. The feedrate per tooth corresponds to the linear path traversed by the milling cutter when a tooth is engaged.

With milling cycles, the feedrate for rough cutting is relative to the milling tool center point. This also applies to finish cutting, with the exception of concave curves where the feedrate is relative to the contact point between the tool and workpiece.

The maximum feedrate is determined via machine data.

### Spindle speed (S) / cutting rate (V)

You have the option of either programming the spindle speed (S) or the cutting rate (V). You can toggle between them using the <SELECT> key.

In the milling cycles, the spindle speed is automatically converted to the cutting rate and vice versa.

- Spindle speed and cutting rate remain valid until you program a new tool.
- Spindle speeds are programmed in rev/min.
- Cutting rates are programmed in m/min
- You can set the direction of rotation of a tool in the tool list.

7.8 Defining machine functions

# 7.8 Defining machine functions

You can switch-on the coolant or stop machining between the individual machining steps.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

You have the option of defining machine functions as well as your own texts in the "Machine functions" window.

# References

A description of the configuration options is provided in Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

## Procedure

	1.	The ShopMill program to be edited has been created and you are in the editor.
>	2.	Press the menu forward key and the "Straight Circle" softkey.
Strght Circle		
Machine functions	3.	Press the "Machine functions" softkey. The "Machine functions" window opens.
	4.	Enter the desired parameters.
Accept	5.	Press the "Accept" softkey.

### See also

Starting and stopping a spindle manually (Page 120)

7.8 Defining machine functions

Parameter	Description	Unit
O	<ul> <li>Spindle M function, defines the spindle direction of rotation or spindle position</li> <li>Spindle off</li> <li>Spindle rotates clockwise</li> <li>Spindle rotates counterclockwise</li> <li>T Spindle positions</li> </ul>	
Stop position	Spindle stop position - (only for spindle M function SPOS)	Degrees
Other M function	Machine functions, e.g. "Close door" that are additionally provided by the machine manufacturer.	
Coolant 1 🚺	Selects coolant (switches coolant 1 on or off) <ul> <li>with</li> <li>without</li> </ul>	
Coolant 2 U	Selects coolant (switches coolant 2 on or off) <ul> <li>with</li> <li>without</li> </ul>	
Tool-spec. function 1 🕖	User machine functions on/off	
Tool-spec. function 2 U	User machine functions on/off	
Tool-spec. function 3 U	User machine functions on/off	
Tool-spec. function 4 Ŭ	User machine functions on/off	
DT	Dwell time in seconds Time after which machining is continued.	s
Programmed stop Ŭ	Programmed stop on Stops machining at the machine if, under Machine in the "Program control" window, the check box "Programmed stop" was activated.	
Stop 🖸	Stop on Stops machining at the machine.	

# 7.9 Call work offsets

You can call work offsets (G54, etc.) from any program.

You define work offsets in work offset lists. You can also view the coordinates of the selected offset here.

# Procedure



- Press the "Various", "Transformations" and "Work offset" softkeys. The "Work offset" window opens.
- SELECT
- Select the desired work offset (e.g. G54).
- Accept

3.

Press the "Accept" softkey. The work offset is transferred into the work plan.

# 7.10 Repeating program blocks

If certain steps when machining a workpiece have to be executed more than once, it is only necessary to program these steps once. You have the option of repeating program blocks.

### Start and end marker

You must mark the program blocks that you want to repeat with a start and end marker. You can then call these program blocks up to 9999 times within a program. The markers must be unique, i.e. they must have different names. No names used in the NCK can be used.

You can also set markers and repeats after creating the program, but not within linked program blocks.

### Note

You can use one and the same marker as end marker for preceding program blocks and as start marker for following program blocks.

## Procedure

	1.	Position the cursor at the program block, behind which a program block that will be repeated should follow.
Uari- ous	2.	Press the "Various" softkey.
	3.	Press the ">>" and "Repeat progr." softkeys.
Repeat program		
Set	3.	Press the "Set marker" and "Accept" softkeys.
mark		A start marker is inserted behind the actual block.
Accept		
	4.	Enter the program blocks that you want to repeat later.
Set 🔪	5.	Press the "Set marker" and "Accept" softkeys again.
mark		An end marker is inserted after the actual block.
Accept		
	6.	Continue programming up to the point where you want to repeat the program blocks.

## 7.10 Repeating program blocks



7.

Press the "Various" and "Repeat progr." softkeys.

8. Enter the names of the start and end markers and the number of times the blocks are to be repeated.



Press the "Accept" softkey.
 The marked program blocks are repeated.

# 7.11 Specifying the number of workpieces

If you wish to produce a certain quantity of the same workpiece, then at the end of the program, specify that you wish to repeat the program.

Control the numbers of times that the program is repeated using the "Times, counters" window. Enter the number of required workpieces using the target number. You can track the number of machined and completed workpieces in the actual counter window.

### Controlling program repetition

End of program: Repeat	Times, counter: Counts the workpieces	
No	No	A CYCLE START is required for each workpiece.
No	Yes	A CYCLE START is required for each workpiece.
		The workpieces are counted.
Yes	Yes	The program is repeated without a new CYCLE START until the required number of workpieces have been machined.
Yes	No	Without a new CYCLE START, the program is repeated an infinite number of times.
		You can interrupt program execution with <reset>.</reset>

## Procedure

- 1. Open the "Program end" program block, if you want to machine more than one workpiece.
- 2. In the "Repeat" field, enter "Yes".



3. Press the "Accept" softkey.

If you start the program later, program execution is repeated. Depending on the settings in the "Times, counters" window, the program is repeated until the set number of workpieces has been machined.

### See also

Displaying the program runtime and counting workpieces (Page 174)

### 7.12 Changing program blocks

# 7.12 Changing program blocks

You can subsequently optimize the parameters in the programmed blocks or adapt them to new situations, e.g. if you want to increase the feedrate or shift a position. In this case, you can directly change all the parameters in every program block in the associated parameter screen form.

# Procedure



- 1. Select the program that you wish to change in the "Program Manager" operating area.
- Press the <Cursor right> or <INPUT> key.
   The work plan of the program is displayed.



3. Position the cursor in the work plan at the desired program block and press the <Cursor right> key.

The parameter screen for the selected program block is displayed.

- 4. Make the desired changes.
- 5. Press the "Accept" softkey.



Accept

- OR -

Press the <Cursor left> key.

The changes are accepted in the program.

Creating a ShopMill program 7.13 Changing program settings

# 7.13 Changing program settings

## Function

All parameters defined in the program header, with the exception of the dimension unit, can be changed at any location in the program.

The settings in the program header are modal, i.e. they remain active until they are changed.

Define a new blank, e.g. in the machining step program, if you want to change the visible section during simulation.

This is useful for the work offset, coordinate transformation, cylinder peripheral surface transformation and swiveling functions. First program the functions listed above and then define a new blank.

## Procedure



Various

Settings

1.

Select the "Program" operating area.

Press the "Various" and "Settings" softkeys.
 The "Settings" input window opens.

Parameter	Description	Unit
PL Ŭ	Machining plane	
	G17 (XY)	
	G18 (ZX)	
	G19 (YZ)	
RP	Retraction plane (abs)	mm
SC	Safety clearance (inc)	mm
	Acts in relation to the reference point. The direction in which the safety clearance is effective is automatically determined by the cycle.	
Machining	Milling direction:	
direction	Climbing	
U	Conventional	
Retraction position	Lift mode before new infeed	mm
pattern	to RP	
U	optimized	

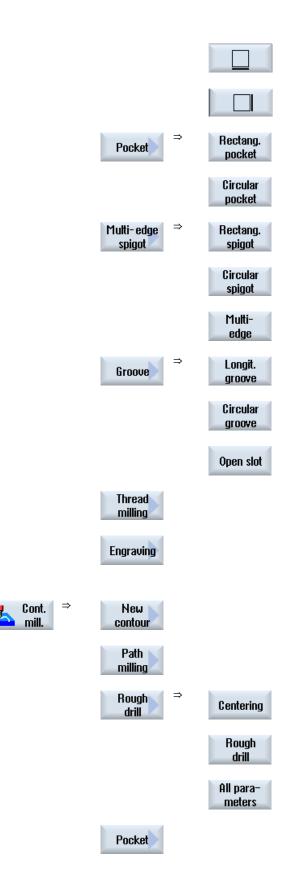
# 7.14 Selection of the cycles via softkey

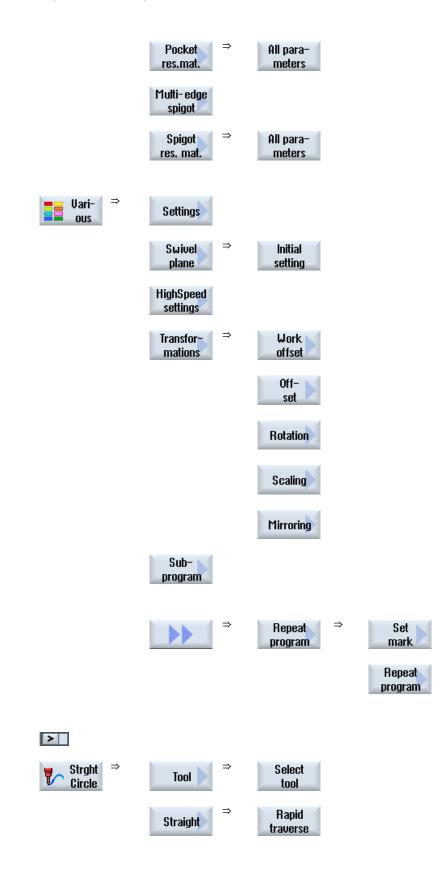
## Overview of machining steps

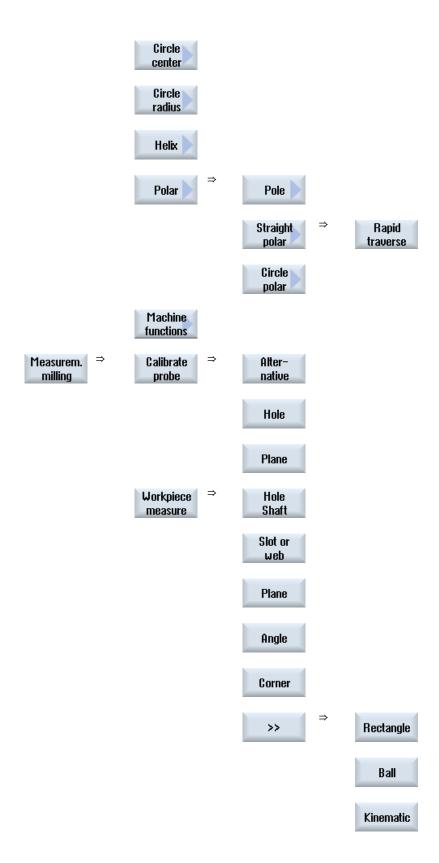
The following machining steps are available for insertion.

All of the cycles/functions available in the control are shown in this display. However, at a specific system, only the steps possible corresponding to the selected technology can be selected.

⇒ Drill. →	Centering	
	Drilling ⇒ Reaming	Drilling
		Reaming
	Deep hole drilling	
	Boring	
	$\stackrel{\Rightarrow}{}$ Thread	Tapping
		Drl+thrd milling
	⇒ Positions	$\sim$
		$\odot$
		Obstacle
	Position repetit.	
⇒ Mill. ⇒	Face ⇒ milling	







Creating a ShopMill program



# 7.15 Calling technology functions

# 7.15.1 Additional functions in the input screens

### Selection of units

If, for example, the unit can be switched in a field, this is highlighted as soon as the cursor is positioned on the element. In this way, the operator recognizes the dependency.

The selection symbol is also displayed in the tooltip.

### Display of abs or inc

The abbreviations "abs" and "inc" for absolute and incremental values are displayed behind the entry fields when a switchover is possible for the field.

### Help screens

2D and 3D graphics or sectional views are displayed for the parameterization of the cycles.

### **Online help**

If you wish to obtain more detailed information about certain G code commands or cycle parameters, then you can call a context-sensitive online help.

# 7.15.2 Checking input parameters

When generating the program, the parameters that are entered are already checked in order to avoid making incorrect entries.

If a parameter is assigned an illegal value, this is indicated in the input screen and is designated as follows:

- The entry field has a colored background (background color, pink).
- A note is displayed in the comment line.
- If the parameter input field is selected using the cursor, the note is also displayed as tooltip.

The programming can only be completed after the incorrect value has been corrected.

Incorrect parameter values are also monitored with alarms during the cycle runtime.

7.15 Calling technology functions

# 7.15.3 Setting data for technological functions

Technological functions can be influenced and corrected using machine or setting data. For additional information, please refer to the following documentation: Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

# 7.15.4 Changing a cycle call

You have called the desired cycle via softkey in the program editor, entered the parameters and confirmed with "Accept".

# Procedure



分

SHIFT

INPUT

 Select the desired cycle call and press the <Cursor right> key. The associated input screen of the selected cycle call is opened.

- OR -

Press the <SHIFT + INSERT> key combination.

This starts the edit mode for this cycle call and you can edit it like a normal NC block. In this way, it is possible to create an empty block before the cycle call.

Note: In edit mode, the cycle call can be changed in such a way that it can no longer be recompiled in the parameter screen.



 $\otimes$ 

INSERT

You exit the edit mode by pressing the <SHIFT + INSERT> key combination.

- OR -

You are in the edit mode and press the <INPUT> key.

A new line is inserted before the selected cycle call.

# 7.16 Measuring cycle support

Measuring cycles are general subroutines designed to solve specific measurement tasks. They can be adapted to specific problems via parameter settings.



#### Software option

You require the "Measuring cycles" option to use "Measuring cycles".

#### Note

#### Using measuring cycles

The program measuring cycles, which are in the editor at the menu forward bar, cannot be handled using the usual functions, such as display tooltips, animated help, close screen with <Cursor left> key.

For measuring generally, a distinction is made between:

- Workpiece measurement
- Tool measurement

#### Workpiece measurement

For the measurement, a workpiece probe is brought to the workpiece to be measured (just like a tool) and the measuring positions are acquired. As a result of the flexible structure of measuring cycles, almost all measuring tasks that have to be realized in a milling machine can be handled. An automatic tool offset or WO can be applied to the workpiece measurement result.

#### **Tool measurement**

For the tool measurement, the loaded tool to be measured is moved up to the probe and the measured values of the geometry are acquired. The probe is either in a fixed in position or is swung into the working area with a mechanism. The tool geometry that is acquired is entered in the appropriate tool offset data set.

#### References

You will find a more detailed description on how to use measuring cycles in:

HMI sl / SINUMERIK 840D sl Programming Manual Measuring Cycles

7.16 Measuring cycle support

## Procedure

>	1.	Press the menu forward key.
Measurem. milling	2.	Press the horizontal "Measure mill" softkey.
Calibrate probe	3.	Using a vertical softkey, select the desired measurement function group, e.g. "Calibrate probe".
		- OR -
Workpiece measure		Measure workpiece
		- OR -
Calibrate TL probe		Calibrate workpiece probe
		- OR -
Tool measure		Measure tool
	4.	Using a vertical softkey, select a measurement task.
	5.	Enter the parameters into the measuring cycle screen.
$\checkmark$	6.	Press the "OK" softkey.
OK		The measuring cycle is transferred into the editor as G code. The measuring cycle parameterized in the G code is color coded.
	7.	Position the cursor on a measuring cycle in the G code editor, if you want to display the associated parameter screen form again.
	8.	Press the <cursor right=""> key.</cursor>
		The parameter screen for the selected measuring cycle appears.
		- OR -
INSERT	9.	Press the <shift> + <insert> keys to remove the measuring cycle selection in the editor and to be able to directly change the parameters in the editor.</insert></shift>

#### General

The following example is described in detail as ShopMill program. A G code program is generated in the same way; however, some differences must be observed.

If you copy the G code program listed below, read it into the control and open it in the editor, then you can track the individual program steps.



Machine manufacturer

Under all circumstances, observe the machine manufacturer's specifications.

#### Tools

The following tools are saved in the tool manager:

Tool name	Tool diameter	Cutting materials	Number of teeth
Face miller	D80 mm	НМ	Z = 8
End mill	D20 mm	HM	Z = 3
End mill	D10 mm	HM	Z = 3
End mill	D8 mm	HM	Z = 3
Centering tool (NC spotdrill)	D10 mm	НМ	-
Twist drill	D10 mm	HSS	-

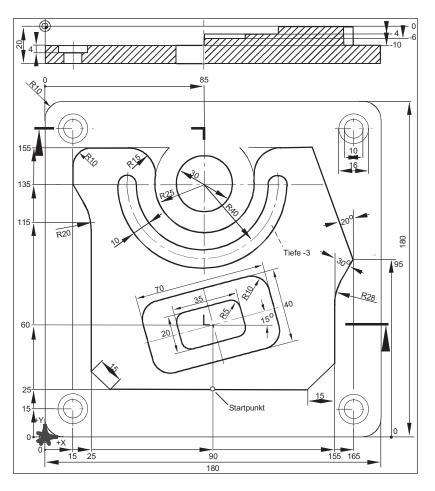
The correction (compensation) values for length and radius as well as the tip angle for drills and number of teeth for milling tools should be entered into the tool list. If you are working with ShopMill, in addition, enter the spindle direction of rotation and coolant.

Adapt the cutting data to the tools used and the specific application conditions.

#### Blank

Dimensions: 185 x 185 x 50 Material: Aluminum

# 7.17.1 Workpiece drawing



## 7.17.2 Programming

## 1. Program header

1.	Specify the blank.		
	Measurement unit mm		
	Work offset	G54	
	Blank	Cuboid	
	X0	-2.5	abs
	Y0	-2.5	abs
	X1	182.5	abs
	Y1	182.5	abs
	ZA	1	abs

		ZI	-20	abs			
		RP	100				
		SC	1				
		Machining direction	Climbing				
		Retraction position pattern	Optimized				
$\checkmark$	2.	Press the "Accept" softkey.					
Accept		The work plan is displayed. Program header and end of program are created as program blocks.					
		The end of program is automatically defined.					

## 2. Rectangular spigots, face milling



3.

4.

1. Press the "Milling" and "Face milling" softkeys.

- Enter the following technology parameters: T FACING TOOL
   D1
   F 0.1 mm/tooth
   V 750 m/min
  - Enter the following parameters: Machining Roughing  $(\nabla)$ Direction \$ -2.5 abs X0 Y0 -2.5 abs **Z**0 1 abs X1 185 abs **Y1** 185 abs Z1 0 abs DXY 80 % DZ 2.0 UΖ 0



Press the "Accept" softkey.

#### 3. Outside contour of the workpiece

Mill. Multi-edge spigot Rectang.	1.	Press the "Milling", "I softkeys.	Multi-e	edge s	pigot" and "Rec	ctangular spigot"				
spigot										
	2.	Enter the following te	chno	logy pa	arameters:					
		T MILLER20	D1	<b>F</b> 0	.14 mm/tooth	<b>V</b> 240 m/min				
	3.	Enter the following pa	arame	eters:						
		Position of reference point	Position of reference Bottom left point							
		Machining		Roug	hing (∇)					
		Type of position		Single	e position					
		X0		0	abs					
		Y0		0	abs					
		Z0		0	abs					
		W1		185	(fictitious blan	k dimension)				
		L1		185	(fictitious blan	k dimension)				
		W		180	abs					
		L		180	abs					
		R		10	abs					
		α0		0	degrees					
		Z1		20	inc					
		DZ		5						
		UXY		0						
		UZ		0						
Accept	4.	Press the "Accept" so	oftkey	'.						

## 4. Outside contour islands

To simply machine the entire surface outside the island, define a contour pocket around the blank and then program the island. In this way, the entire surface area is machined and no residual material is left behind.

Contour		
New contour		
	2.	Enter the contour name (in this case: Part_4_pocket).
		The contour calculated as NC code is written as internal subprogram between a start and an end marker containing the entered name.
	3.	Press the "Accept" softkey.
Accept		The "Starting point" input window opens.
	4.	Enter the starting point of the contour.
		X -10 abs Y -10 abs
Accept	5.	Press the "Accept" softkey.
Accept	6.	Enter the following contour elements and acknowledge using the "Accept" softkey.
<b>←•→</b>	6.1.	X 190 abs
ŧ	6.2.	Y 190 abs
<b>←</b> ∎→	6.3.	X -10 abs
	6.4.	Press the ">>" and "Close contour" softkeys, to close the contour.
Accept	7.	Press the "Accept" softkey.
Outside conto	our of t	he island

The "New Contour" input window opens.

Press the "Contour milling", "Contour" and "New contour" softkeys.

#### Outside contour of the pocket

1.

Cont. mill.



- 1. Press the "Contour milling", "Contour" and "New contour" softkeys. The "New Contour" input window opens.
- Enter the contour name (in this case: Part\_4\_island).
   The contour calculated as NC code is written as internal subprogram between a start and an end marker containing the entered name.

Accept	3.	Press the "Accept" softkey. The "Starting point" input window opens.										
	4.		Enter the starting point of the contour. <b>X</b> 90 abs <b>Y</b> 25 abs									
Accept	5.		Press the "Accept" softkey.									
Accept	6.		Enter the following contour elements and acknowledge using the Accept" softkey.									
<b>←∎→</b>	6.1.	х	25	abs	FS	15						
ŧ	6.2.	Y	115	abs	R	20						
X	6.3.	х	15	abs	Y	135	abs					
ŧ	6.4.	Y	155	abs	R	10						
<b>←</b> ∎→	6.5.	Х	60	abs	R	15						
<b>‡</b>	6.6.	Y	135	abs								
$\langle \uparrow \rangle$	7.	Directior	of ro	tation ្ន								
Tangent. trans.	8.	R	25		х	110	abs					
ŧ	9.1	Y	155	abs	R	15						
Tangent. trans.												
←•→	9.2	R	0									
X	9.3	Х	165	abs	Y	95	abs	α1	290 degr.	R	0	
X	9.4	Х	155	abs	α1	240	degr.	R	28			
<b>‡</b>	9.5	FS	0									
X	9.6	x	140	abs	Y	25	abs	α1	225 degr.	R	0	



Accept

- 10. Press the ">>" and "Close contour" softkeys, to close the contour.
- 11. Press the "Accept" softkey.

#### Contour milling/solid machining

1. Press the "Contour milling" and "Pocket" softkeys.



 Enter the following technology parameters: T MILLER20 D1 F 0.1 mm/tooth V 240 m/min
 Enter the following parameters:

5.	Enter the following parameters.							
	Machining ∇							
	<b>Z</b> 0	0	abs					
	Z1	10	inc					
	DXY	40	%					
	DZ	3.5						
	UXY	0	mm					
	UZ	0						
	Starting point		Auto					
	Insertion		Helical					
	EP	1.0						
	ER	2.0						
	Lift mode	•	Select, e.g. to the retraction plane					
4.	Press the	e "Ac	cept" softkey.					



#### Note

- When selecting the milling tool, please make sure that the tool diameter is large enough to cut the intended pocket. A message will be displayed if you make a mistake.
- If you want to finish cut the pocket, you must assign parameters UXY and UZ accordingly and add a second solid machining cycle for finishing.

## 5. Milling a rectangular pocket (large)

Kill.	1.	Press the "Milling", "Pocket" and "Rectangular pocket" softkeys. The "Rectangular Pocket" input window opens.							
Pocket									
Rectang.									
pocket									
	2.	Enter the following teo	chnology pa	arameters:					
		T MILLER10	D1 F	0.04 mm/tooth	<b>V</b> 260 m/min				
	3.	Enter the following pa	rameters:						
		Reference point	ence point Center						
		Machining	Roug	hing (∇)					
		Machining position	Singl	e position					
		X0	90	abs					
		Y0	60	abs					
		Z0	0	abs					
		W	40						
		L	70						
		R	10						
		α0	15	degrees					
		Z1		inc					
		DXY	40	%					
		DZ	4						
		UXY	0						
		UZ	0						
			Insertion Helical						
		EP	1						
		ER	2						
		Solid machining		plete machining					
$\checkmark$	4.	Press the "Accept" so	ftkey.						



Creating a ShopMill program 7.17 Example, standard machining

#### 6. Milling a rectangular pocket (small)



- Press the "Milling", "Pocket" and "Rectangular pocket" softkeys. The "Rectangular Pocket" input window opens.
- Enter the following technology parameters: T MILLER10 D1 F 0.04 mm/tooth V 260 m/min
- 3. Enter the following parameters:

	Reference point	Center
	Machining	Roughing ( $\nabla$ )
	Machining position	Single position
	X0	90 abs
	YO	60 abs
	ZO	-4 abs
	W	20
	L	35
	R	5
	α0	15 degrees
	Z1	2 inc
	DXY	40 %
	DZ	2
	UXY	0
	UZ	0
	Insertion	Oscillation
	Solid machining	Complete machining
4.	Press the "Accept" softkey	



## 7. Milling a circumferential slot

Mill. Groove Circular groove	1.	Press the "Milling", "Groove" and "Circ. groove" softkeys. The "Circumferential Groove" input window opens.					
	2.	Enter the following tech	nology param	neters:			
	۷.	-		18 mm/tooth	FZ 0.01 mm/tooth		
		V 230 m/min					
	3.	Enter the following para	ameters:				
	•	Machining	Roughing	a (V)			
		Circular pattern	Pitch circ				
		X0	85 ab				
		YO	135 ab				
		ZO	0 ab				
		Ν	1				
		R	40				
		α0	180 de	egrees			
		α1	180 de	egrees			
		W	10				
		Z1	3 inc	с			
		DZ	3				
		UXY	0 mi	m			
Accept	4.	Press the "Accept" soft	key.				
8. Drilling/centering							
L. Drill.	1.	Press the "Drilling" and	Centering" s	oftkeys.			
		The "Centering" input v	vindow opens.				
Centering							
	2.	Enter the following tech	nology param	eters:			
		<b>T</b> CENTERING TOOL10	<b>D1 F</b> 100	00 mm/min	<b>S</b> 12000 rev/min		
	3.	Enter the following para	ameters:				
		Diameter/tip	Diameter	r			
		Ø	5				
Accept	4.	Press the "Accept" soft	key.				

## 9. Drilling/reaming

L Drill.	1.	Press the "Drilling", "Drilling reaming" and "Drilling" softkeys. The "Drilling" input window opens.						
Drilling Reaming								
Drilling								
	2.	Enter the following technology parameters:						
		T DRILL10	D1	<b>F</b> 500 r	nm/min	<b>S</b> 1600 rev/min		
	3.	Enter the following p	barame	eters:				
		Diameter/tip		Tip				
		Z1		-25 a	abs			
		DT		0				
Accept	4.	Press the "Accept" s	softkey.					

## 10. Positions



 Press the "Drilling", "Positions" and "Drilling Positions" softkeys. The "Any positions" input window opens.

2.	Enter the following parameters:
----	---------------------------------

			Recta	ngular
<b>Z</b> 0			-10	abs
X0			15	abs
Y0			15	abs
X1			165	abs
Y1			15	abs
_	 	 <i>c</i>		



3.

Press the "Accept" softkey.

#### 11. Obstacle

🣥 Drill.	1.	Press the "Drilling", "Position The "obstacle" input window	•
Positions			
Obstacle			
	2.	Enter the following paramete	rs:
		Z	2 abs
Accept	3.	Press the "Accept" softkey.	

#### Note

If this obstacle cycle is not inserted, the drill will violate the right-hand corner of the island contour. Alternately, you could increase the safety clearance.

#### 12. Positions

- Drill. Positions
- Press the "Drilling", "Positions" and "Drilling Positions" softkeys. 1. The "Any positions" input window opens.



2.

3.

Enter the following parame	ters:	
	Recta	ngular
Z0	-10	abs
X2	165	abs
Y2	165	abs
X3	15	abs
Y3	165	abs
Press the "Accept" softkey.		

Accept

Creating a ShopMill program 7.17 Example, standard machining

## 13. Milling the circular pocket

Mill.	1.	Press the "Milling", "			•	t" softkeys.
		The "Circular Pocket	t" inpu	t windo	w opens.	
Pocket						
Circular pocket						
	2.	Enter the following te	echnol	ogy pa	rameters:	
		T MILLER8	D1	<b>F</b> 0.	018 mm/tooth	<b>V</b> 230 m/min
	3.	Enter the following p	arame	eters:		
		Machining		Rough	ning (∇)	
		Machining type		Plane	by plane	
		Machining position		Single	position	
		X0		85	abs	
		Y0		135	abs	
		Z0		-10	abs	
		Diameter		30		
		Z1		12	inc	
		DXY		40	%	
		DZ		5		
		UXY		0	mm	
		UZ		0		
		Insertion		Helica	I	
		EP		1.0		
		ER		2.0		
		Solid machining		Comp	lete machining	
Angent	4.	Press the "Accept" s	oftkey			

Accept

You also program the 4 countersinks  $\varnothing$ 16 and 4 deep using a circular pocket and repeating positions 1, 2 and 4.

## 7.17.3 Results/simulation test

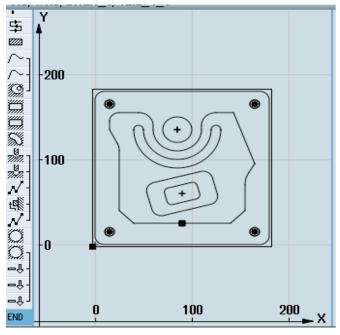


Figure 7-5 Programming graphics

P	Program header		Work offset G54 🖂	<u></u> ^
₽₽	Face milling	V	T=PLANFRAESER F0.1/t U=750m X0=-2.5 Y0=-2.5	
	Rectang.spigot	V	T=FRAESER20 F0.14/t V=240m X0=0 Y0=0 Z0=0	
$\sim$	l Contour		TEIL_4_TASCHE	
$\sim$	Contour		TEIL_4_INSEL	
Ø.	<sup>1</sup> Mill pocket	V	T=FRAESER20 F0.1/t V=240m 20=0 21=10inc	
ģ,	Rectang.pocket	V	T=FRAESER10 F0.04/t V=260m X0=90 Y0=60 Z0=0	
<u>شار</u>	Rectang.pocket	V	T=FRAESER10 F0.04/t U=260m X0=90 Y0=60 Z0=-4	
53	Circumfer. slot	V	T=FRAESER8 F0.018/t U=230m X0=85 Y0=135 Z0=0	
Z -	l Centering		T=ZENTRIERER10 F1000/min S=12000rev Ø5	=
Zez -	Drilling		T=B0HRER10 F500/min S=1600rev 21=-25	
N	001: Positions		Z0=-10 X0=15 Y0=15 X1=165 Y1=15	
<u> </u>	002: Obstacle		2=2	
N	003: Positions		Z0=-10 X2=165 Y2=165 X3=15 Y3=165	
Ő	Circular pocket	V	T=FRAESER8 F0.018/t V=230m X0=85 Y0=135	
Õ	Circular pocket	V	T=FRAESER8 F0.018/t U=230m X0=85 Y0=135	
-Û-	Repeat position		001: Positionen	
-Û-	Repeat position		002: Hindernis	
-Û-	Repeat position		003: Positionen	
CKID	End of program			~

Figure 7-6 Machining schedule

#### Program test by means of simulation

During simulation, the current program is calculated in its entirety and the result displayed in graphic form.

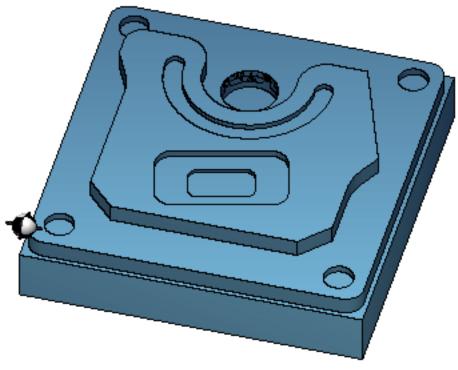


Figure 7-7 3D view

## 7.17.4 G code machining program

```
G17 G54 G71
WORKPIECE(,,"","BOX",112,1,-20,-100,-2.5,-2.5,182.5,182.5)
;*******************Tool change***************
T="FACING TOOL" D1 M6
G95 FZ=0.1 S3000 M3 M8
CYCLE61(50,1,1,0,-2.5,-2.5,185,185,2,80,0,0.1,31,0,1,10)
G0 Z200 M9
;*******************Tool change****************
T="MILLER20" D1 M6
G95 FZ=0.14 S3900 M3 M8
CYCLE76(50,0,1,,20,180,180,10,0,0,0,5,0,0,0.14,0.14,0,1,185,185,1,2,2100,1,101)
;CYCLE62(,2,"MA1","MA0")
CYCLE62(,2,"E LAB A PART 4 POCKET","E LAB E PART 4 POCKET")
CYCLE62(,2,"E_LAB_A_PART_4_ISLAND","E_LAB_E_PART_4_ISLAND")
CYCLE63("PART 4 GEN 01",11,50,0,1,10,0.1,0.3,40,3.5,0,0,0,0,0,0,2,1,15,1,2,,,,0,101,111)
G0 Z200 M9
T="MILLER10" D1 M6
G95 FZ=0.04 S8500 M3 M8
```

```
POCKET3 (50, 0, 1, 4, 70, 40, 10, 90, 60, 15, 4, 0, 0, 0.04, 0.2, 0, 21, 40, 8, 3, 15, 2, 1, 0, 1, 2, 11100, 11, 111)
POCKET3 (50, -4, 1, 2, 35, 20, 6, 90, 60, 15, 2, 0, 0, 0.04, 0.2, 0, 31, 40, 8, 3, 15, 10, 2, 0, 1, 2, 11100, 11, 111)
G0 Z200 M9
;******************Tool change***************
T="MILLER8" D1 M6
G95 FZ=0.018 S9000 M3 M8
SLOT2 (50,0,1,,3,1,180,10,85,135,40,180,90,0.01,0.018,3,0,0,2001,0,0,0,0,1,2,100,1001,101)
G0 7200 M9
T="CENTERING TOOL10" D1 M6
G94 F1000 S12000 M3 M8
MCALL CYCLE81 (50, -10, 1, 5, , 0, 10, 1, 11)
MCALL
GO 7200 M9
T="DRILL10" D1 M6
G94 F500 S1600 M3 M8
MCALL CYCLE82(50,-10,1,-25,,0,0,1,12)
REPEATB POS_1 ;#SM
MCALL
G0 Z200 M9
T="MILLER8" D1 M06
G95 FZ=0.018 S12000 M3 M8
POCKET4 (50, -10, 1, 12, 30, 85, 135, 5, 0, 0, 0.018, 0.01, 0, 21, 40, 9, 15, 2, 1, 0, 1, 2, 10100, 111, 111)
MCALL POCKET4 (50, -10, 1, 4, 16, 0, 0, 5, 0, 0, 0.018, 0.018, 0, 11, 40, 9, 15, 0, 2, 0, 1, 2, 10100, 111, 111)
REPEATB POS 1 ;#SM
MCALL
G0 Z200 M9
;Contour chamfering
T="CENTERING TOOL10" D1 M6
G94 F500 S8000 M3 M8
CYCLE62(,2,"E LAB A PART 4 ISLAND","E LAB E PART 4 ISLAND")
CYCLE72("",100,0,1,20,2,0.5,0.5,500,100,305,41,1,0,0.1,1,0,0,0.3,2,101,1011,101)
POCKET3 (50, 0, 1, 4, 70, 40, 10, 90, 60, 15, 4, 0, 0, 500, 0.2, 0, 25, 40, 8, 3, 15, 2, 1, 0, 0.3, 2, 11100, 11, 111)
POCKET3 (50, -4, 1, 2, 35, 20, 6, 90, 60, 15, 2, 0, 0, 500, 0.2, 0, 35, 40, 8, 3, 15, 10, 2, 0, 0.3, 2, 11100, 11, 111)
SLOT2 (50,0,1,,3,1,180,10,85,135,40,180,90,0.01,500,3,0,0,2005,0,0,0,0,0,0,3,2,100,1001,101)
POCKET4 (50, -10, 1, 12, 30, 85, 135, 5, 0, 0, 500, 0.01, 0, 15, 40, 9, 15, 0, 2, 0, 0.3, 2, 10100, 111, 111)
MCALL POCKET4 (50, -10, 1, 4, 16, 0, 0, 5, 0, 0, 500, 0.025, 0, 15, 40, 9, 15, 0, 2, 0, 0.3, 4, 10100, 111, 111)
REPEATB POS 1 ;#SM
MCALL
G0 Z200 M9
M30
```

#### Creating a ShopMill program

7.17 Example, standard machining

E\_LAB\_A\_PART\_4\_POCKET: ;#SM Z:5 ;#7\_\_DlgK contour definition begin - Don't change!;\*GP\*;\*RO\*;\*HD\* G17 G90 DIAMOF;\*GP\* G0 X-10 Y-10 ;\*GP\* G1 X190 ;\*GP\* Y190 ;\*GP\* X-10 ;\*GP\* Y-10 ;\*GP\* ;CON,0,0.0000,4,4,MST:0,0,AX:X,Y,I,J;\*GP\*;\*RO\*;\*HD\* ;S,EX:-10,EY:-10;\*GP\*;\*RO\*;\*HD\* ;LR,EX:190;\*GP\*;\*RO\*;\*HD\* ;LU,EY:190;\*GP\*;\*RO\*;\*HD\* ;LL,EX:-10;\*GP\*;\*RO\*;\*HD\* ;LA,EX:-10,EY:-10;\*GP\*;\*RO\*;\*HD\* ;#End contour definition end - Don't change!;\*GP\*;\*RO\*;\*HD\* E\_LAB\_E\_PART\_4\_POCKET: ; E\_LAB\_A\_PART\_4\_ISLAND: ;#SM Z:2 ;#7 DlgK contour definition begin - Don't change!;\*GP\*;\*RO\*;\*HD\* G17 G90 DIAMOF;\*GP\* G0 X90 Y25 ;\*GP\* G1 X25 CHR=15 ;\*GP\* Y115 RND=20 ;\*GP\* X15 Y135 ;\*GP\* Y155 RND=10 ;\*GP\* X60 RND=15 ;\*GP\* Y135 ;\*GP\* G3 X110 I=AC(85) J=AC(135) ;\*GP\* G1 Y155 RND=15 ;\*GP\* X143.162 ;\*GP\* X165 Y95 ;\*GP\* X155 Y77.679 RND=28 ;\*GP\* Y40 ;\*GP\* X140 Y25 ;\*GP\* X90 ;\*GP\* ;CON,0,0.0000,14,14,MST:0,0,AX:X,Y,I,J;\*GP\*;\*RO\*;\*HD\* ;S,EX:90,EY:25;\*GP\*;\*RO\*;\*HD\* ;LL,EX:25;\*GP\*;\*RO\*;\*HD\* ;F,LFASE:15;\*GP\*;\*RO\*;\*HD\* ;LU,EY:115;\*GP\*;\*RO\*;\*HD\* ;R,RROUND:20;\*GP\*;\*RO\*;\*HD\* ;LA,EX:15,EY:135;\*GP\*;\*RO\*;\*HD\* ;LU,EY:155;\*GP\*;\*RO\*;\*HD\* ;R,RROUND:10;\*GP\*;\*RO\*;\*HD\*

#### Creating a ShopMill program

7.17 Example, standard machining

;LR,EX:60;\*GP\*;\*RO\*;\*HD\* ;R,RROUND:15;\*GP\*;\*RO\*;\*HD\* ;LD,EY:135;\*GP\*;\*RO\*;\*HD\* ;ACCW,EX:110,RAD:25;\*GP\*;\*RO\*;\*HD\* ;LU,EY:155,AT:0;\*GP\*;\*RO\*;\*HD\* ;R,RROUND:15;\*GP\*;\*RO\*;\*HD\* ;LR;\*GP\*;\*RO\*;\*HD\* ;LA,EX:165,EY:95,ASE:290;\*GP\*;\*RO\*;\*HD\* ;LA,EX:155,ASE:240;\*GP\*;\*RO\*;\*HD\* ;LA,EX:155,ASE:240;\*GP\*;\*RO\*;\*HD\* ;LD;\*GP\*;\*RO\*;\*HD\* ;LA,EX:140,EY:25,ASE:225;\*GP\*;\*RO\*;\*HD\* ;LA,EX:90,EY:25;\*GP\*;\*RO\*;\*HD\* ;#End contour definition end - Don't change!;\*GP\*;\*RO\*;\*HD\* E\_LAB\_E\_PART\_4\_ISLAND:

# Programming technological functions (cycles)

## 8.1 Drilling

#### 8.1.1 General

#### General geometry parameters

• Retraction plane RP and reference point Z0

Normally, reference point Z0 and retraction plane RP have different values. The cycle assumes that the retraction plane is in front of the reference point.

#### Note

If the values for reference point and retraction planes are identical, a relative depth specification is not permitted. Error message "Reference plane defined incorrectly" is output and the cycle is not executed.

This error message is also output if the retraction plane is located after the reference point, i.e. its distance to the final drilling depth is smaller.

• Safety clearance SC

Acts in relation to the reference point. The direction in which the safety clearance is active is automatically determined by the cycle.

Drilling depth

Depending on the selection of the drill shank or drill tip or the centering diameter, the programmed drilling depth refers to the following for cycles with a selection field:

- Tip (drilling depth in relation to the tip)

The drill is inserted into the workpiece until the drill tip reaches the value programmed for Z1.

- Shank (drilling depth in relation to the shank)

The drill is inserted into the workpiece until the drill shank reaches the value programmed for Z1. The angle entered in the tool list is taken into account.

Diameter (centering in relation to the diameter, only for CYCLE81)

The diameter of the centering hole is programmed at Z1. In this case, the tip angle of the tool must be specified in the tool list. The drill is inserted into the workpiece until the specified diameter is reached.

#### **Drilling positions**

The cycle assumes the tested hole coordinates of the plane.

The hole centers should therefore be programmed before or after the cycle call as follows (see also Section, Cycles on single position or position pattern (MCALL)):

- A single position should be programmed before the cycle call
- Position patterns (MCALL) should be programmed after the cycle call
  - as drilling pattern cycle (line, circle, etc.) or
  - as a sequence of positioning blocks for the hole centers

## 8.1.2 Centering (CYCLE81)

#### Function

With the "Centering" function, the tool drills with the programmed spindle speed and feedrate either:

- Down to the programmed final drilling depth or
- So deep until the programmed diameter of the centering is reached

The tool is retracted after a programmed dwell time has elapsed.

#### Approach/retraction

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. Inserted into the workpiece with G1 and the programmed feedrate F until the depth or the centering diameter is reached.
- 3. On expiry of a dwell time DT, the tool is retracted at rapid traverse G0 to the retraction plane.

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.

2. Press the "Drilling" softkey.



Drill.

 Press the "Center" softkey. The "Centering" input window opens.

Parameters, G code program			Param	eters, ShopMill program	
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
			S / V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining position 🧿 (only for G code)	<ul> <li>Single position Drill hole at programmed position</li> <li>Position pattern Position with MCALL</li> </ul>	
Z0 (only for G code)	Reference point Z	mm
Centering	Diameter (centered with reference to the diameter)	mm
O	<ul> <li>The angle for the center drill entered in the tool list is applied.</li> <li>Tip (centered with reference to the depth)</li> <li>The drill is inserted into the workpiece until the programmed insertion depth is</li> </ul>	
	reached.	
Ø	It is inserted into the workpiece until the diameter is correct (for diameter centering only)	mm
Z1	Drilling depth (abs) or drilling depth in relation to Z0 (inc)	mm
U	It is inserted into the workpiece until it reaches Z1 - (for tip centering only)	
DT	Dwell time (at final drilling depth) in seconds	s
O	Dwell time (at final drilling depth) in revolutions	rev

## 8.1.3 Drilling (CYCLE82)

#### Function

With the "Drilling" function, the tool drills with the programmed spindle speed and feedrate down to the specified final drilling depth (shank or tip).

The tool is retracted after a programmed dwell time has elapsed.

#### Approach/retraction

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. The tool is inserted into the workpiece with G1 and the programmed feedrate F until it reaches the programmed final depth Z1.
- 3. When a dwell time DT expires, the tool is retracted at rapid traverse G0 to the retraction plane.

#### Procedure

1.	The part program or ShopMill program to be processed has been
	created and you are in the editor.

- 2. Press the "Drilling" softkey.
- Drilling Reaming

Drill.

- 3. Press the "Drilling Reaming" softkey.
- Drilling 4.
- Press the "Drilling" softkey. The "Drilling" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
			S/V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining	Single position	
position <b>()</b> (only for G code)	<ul><li>Drill hole at programmed position</li><li>Position pattern</li></ul>	
	Position with MCALL	
Z0 (only for G code)	Reference point Z	mm

Parameter	Description	Unit
Drilling depth	Shank (drilling depth in relation to the shank)	
U	<ul><li>The drill is inserted into the workpiece until the drill shank reaches the value programmed for Z1. The angle entered in the tool list is taken into account.</li><li>Tip (drilling depth in relation to the tip)</li></ul>	
	The drill is inserted into the workpiece until the drill tip reaches the value programmed for Z1.	
Z1	Drilling depth (abs) or drilling depth in relation to Z0 (inc)	mm
U	It is inserted into the workpiece until it reaches Z1.	
DT	Dwell time (at final drilling depth) in seconds	s
C	Dwell time (at final drilling depth) in revolutions	rev

## 8.1.4 Reaming (CYCLE85)

#### Function

With the "Reaming" cycle, the tool is inserted in the workpiece with the programmed spindle speed and the feedrate programmed at F.

If Z1 has been reached and the dwell time expired, the reamer is retracted at the programmed retraction feedrate to the retraction plane.

#### Approach/retraction

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. The tool is inserted into the workpiece with the programmed feedrate F until it reaches the final depth Z1.
- 3. Dwell time DT at final drilling depth.
- 4. Retraction to retraction plane with programmed retraction feedrate FR.

### Procedure

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Drilling" softkey.
- 3. Press the "Drilling Reaming" softkey.



Reaming

Drill.

Press the "Reaming" softkey
 The "Reaming" input window opens.

#### Programming technological functions (cycles)

8.1 Drilling

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
F	Feedrate	mm/min	S/V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining	Single position	
position 🕐 (only for G code)	Drill hole at programmed position	
	Position pattern	
	Position with MCALL	
Z0 (only for	Reference point Z	mm
G code)		
FR	Feedrate during retraction	mm/min
Z1	Drilling depth (abs) or drilling depth in relation to Z0 (inc)	mm
U	It is inserted into the workpiece until it reaches Z1 (for tip centering only)	
DT	Dwell time (at final drilling depth) in seconds	s
U	Dwell time (at final drilling depth) in revolutions	rev

## 8.1.5 Deep-hole drilling (CYCLE83)

#### Function

With the "Deep-hole drilling" cycle, the tool is inserted in the workpiece with the programmed spindle speed and feedrate in several infeed steps until the depth Z1 is reached. The following can be specified:

- Number of infeed steps constant or decreasing (via programmable degression factor)
- Chip breaking without lifting or swarth removal with tool retraction
- Feedrate factor for 1st infeed to reduce the feedrate or increase the feedrate (e.g. if a hole has already be predrilled)
- Dwell times
- Depth in relation to drill shank of drill tip

#### Approach/retraction during chipbreaking

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. The tool drills with the programmed spindle speed and feedrate F = F · FD1 [%] up to the 1st infeed depth.
- 3. Dwell time at drilling depth DTB.
- 4. The tool is retracted by retraction distance V2 for chipbreaking and drills up to the next infeed depth with programmed feedrate F.
- 5. Step 4 is repeated until the final drilling depth Z1 is reached.
- 6. Dwell time at final drilling depth DT.
- 7. The tool retracts to the retraction plane at rapid traverse.

#### Approach/retraction during stock removal

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. The tool drills with the programmed spindle speed and feedrate F = F · FD1 [%] up to the 1st infeed depth.
- 3. Dwell time at drilling depth DTB.
- 4. The tool retracts from the workpiece for the stock removal with rapid traverse to the safety clearance.
- 5. Dwell time at starting point DTS.
- 6. Approach of the last drilling depth with G0, reduced by the clearance distance V3.
- 7. Drilling is then continued to the next drilling depth.
- 8. Steps 4 to 7 are repeated until the programmed final drilling depth Z1 is reached.
- 9. The tool retracts to the retraction plane at rapid traverse.

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



2. Press the "Drilling" softkey.



Press the "Deep-hole drilling" softkey.
 The "Deep-hole Drilling" input window opens.

#### Programming technological functions (cycles)

8.1 Drilling

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining position O (only for G code)	<ul> <li>Single position Drill hole at programmed position.</li> <li>Position pattern Position with MCALL</li> </ul>	
Z0 (only for G code)	Reference point Z	mm
Machining O	<ul> <li>Stock removal The drill is retracted from the workpiece for stock removal.</li> <li>Chipbreaking The drill is retracted by the retraction distance V2 for chipbreaking.</li> </ul>	
Drilling depth	<ul> <li>Shank (drilling depth in relation to the shank) The drill is inserted into the workpiece until the drill shank reaches the value programmed for Z1. The angle entered in the tool list is taken into account. </li> <li>Tip (drilling depth in relation to the tip) The drill is inserted into the workpiece until the drill tip reaches the value programmed for Z1.</li></ul>	
Z1	Drilling depth (abs) or drilling depth in relation to Z0 (inc)	mm
D - (only for G code)	It is inserted into the workpiece until it reaches Z1.         1. Drilling depth (abs) or 1st drilling depth in relation to Z0 (inc)	
D - (only for ShopMill)	Maximum depth infeed	
FD1	Percentage for the feedrate for the first infeed	%
DF O	<ul> <li>Infeed:</li> <li>Amount for each additional infeed</li> <li>Percentage for each additional infeed</li> <li>DF = 100%: Infeed increment remains constant</li> <li>DF &lt; 100%: Infeed increment is reduced in direction of final drilling depth.</li> <li>Example: Last infeed was 4 mm; DF is 80%</li> </ul>	mm %
	next infeed = $4 \times 80\%$ = $3.2 \text{ mm}$ next infeed = $3.2 \times 80\%$ = $2.56 \text{ mm}$ etc.	

Parameter	Description	Unit
V1	Minimum infeed - (only for DF in %)	
	Parameter V1 is provided only if DF< 100 has been programmed.	
	If the infeed increment becomes minimal, a minimum infeed can be programmed in parameter "V1".	
	V1 < Infeed increment: The tool is inserted by the infeed increment.	
	V1 < Infeed increment: The tool is inserted by the infeed value programmed under V1.	
V2	Retraction distance after each machining step – (for chipbreaking only)	mm
	Distance by which the drill is retracted for chipbreaking.	
	V2 = 0: The tool is not retracted but is left in place for one revolution.	
V3	Clearance distance – (for stock removal only and manual clearance distance)	mm
	Distance to the last infeed depth that the drill approaches in rapid traverse after stock removal.	
DTB - (only for	Dwell time at drilling depth in seconds	s
G code) U	Dwell time at drilling depth in revolutions	rev
DT	Dwell time at final drilling depth in seconds	s
U	Dwell time at final drilling depth in revolutions	rev
DTS - (only for	Dwell time for stock removal in seconds	s
G code) U	Dwell time for stock removal in revolutions	rev

## 8.1.6 Boring (CYCLE86)

#### Function

With the "Boring" cycle, the tool approaches the programmed position in rapid traverse, allowing for the retraction plane and safety clearance. It is then inserted into the workpiece at the feedrate programmed under F until it reaches the programmed depth (Z1). There is an oriented spindle stop with the SPOS command. After the dwell time has elapsed, the tool is retracted either with or without lift of the tool.

For "lift off contour", the retraction distance D and the tool orientation angle  $\alpha$  can either be defined via machine data or in the parameter screen. If both parameters are pre-assigned via machine data, they do not appear in the parameter screen.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

#### NOTICE

The "Boring" cycle can be used if the spindle to be used for the boring operation is technically able to go into position-controlled spindle operation.

#### Approach/retraction

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. Travel to the final drilling depth with G1 and the speed and feedrate programmed before the cycle call.
- 3. Dwell time at final drilling depth.

2.

3.

- 4. Oriented spindle hold at the spindle position programmed under SPOS.
- 5. With the "Lift" selection, the cutting edge retracts from the hole edge with G0 in up to three axes.
- 6. Retraction with G0 to the safety clearance of the reference point.
- 7. Retraction to retraction plane with G0 to drilling position in the two axes of the plane (coordinates of the hole center point).

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



Press the "Drilling" softkey.

Press the "Boring" softkey. The "Boring" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
			S/V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining position 🧿 (only for G code)	<ul> <li>Single position <ul> <li>Drill hole at programmed position</li> </ul> </li> <li>Position pattern <ul> <li>Position with MCALL</li> </ul> </li> </ul>	
Z0 (only for G code)	Reference point Z	mm
DIR	Direction of rotation	
O (only for G code)	• ଦ • ହ	
Z1 Ŭ	Drilling depth (abs) or drilling depth in relation to Z0 (inc)	mm
DT	Dwell time at final drilling depth in seconds	S
U	Dwell time at final drilling depth in revolutions	rev
SPOS	Spindle stop position	Degrees
Lift mode	Do not lift off contour	
U	<ul> <li>The cutting edge is not fully retracted, but traverses back to the retraction plane.</li> <li>Lift off contour</li> <li>The cutting edge retracts from the edge of the hole and then retracts to the safety</li> </ul>	
	clearance from the reference point and then positions at the retraction plane and hole center point.	
DX	Retraction distance in the X direction (incremental) - (for lift-off only, standard)	
DY	Retraction distance in the Y direction (incremental) - (for lift-off only, standard)	
DZ	Retraction distance in the Z direction (incremental) - (for lift-off only, standard)	
D	Retraction distance (incremental) - (for lift-off only, ShopMill)	

## 8.1.7 Tapping (CYCLE84, 840)

#### Function

You can machine an internal thread with the "tapping" cycle.

The tool moves to the safety clearance with the active speed and rapid traverse. The spindle stops, spindle and feedrate are synchronized. The tool is then inserted in the workpiece with the programmed speed (dependent on %S).

You can choose between drilling in one cut, chipbreaking or retraction from the workpiece for stock removal.

Depending on the selection in the "Compensating chuck mode" field, alternatively the following cycle calls are generated:

- With compensating chuck: CYCLE840
- Without compensating chuck: CYCLE84

When tapping with compensating chuck, the thread is produced in one cut. CYCLE84 enables tapping to be performed in several cuts, when the spindle is equipped with a measuring system.

#### Approach/retraction - CYCLE840 - with compensating chuck

- 1. The tool moves with G0 to safety clearance of the reference point.
- 2. The tool drills with G1 and the programmed spindle speed and direction of rotation to depth Z1. The feedrate F is calculated internally in the cycle from the speed and pitch.
- 3. The direction of rotation is reversed.
- 4. Dwell time at final drilling depth.
- 5. Retraction to safety clearance with G1.
- 6. Reversal of direction of rotation or spindle stop.
- 7. Retraction to retraction plane with G0.

#### Approach/retraction - CYCLE84 - without compensating chuck

One cut:

- 1. Travel with G0 to the safety clearance of the reference point.
- 2. Spindle is synchronized and started with the programmed speed (dependent on %S).
- 3. Tapping with spindle-feedrate synchronization to Z1.
- 4. Spindle stop and dwell time at drilling depth.
- 5. Spindle reverse after dwell time has elapsed.
- 6. Retraction with active spindle retraction speed (dependent on %S) to safety clearance
- 7. Spindle stop.
- 8. Retraction to retraction plane with G0.

#### Approach/retraction during stock removal

- 1. The tool drills at the programmed spindle speed S (dependent on %S) as far as the first infeed depth (maximum infeed depth D).
- 2. Spindle stop and dwell time DT.
- 3. The tool retracts from the workpiece for the stock removal with spindle speed SR to the safety clearance.
- 4. Spindle stop and dwell time DT.
- 5. The tool then drills with spindle speed S as far as the next infeed depth.
- 6. Steps 2 to 5 are repeated until the programmed final drilling depth Z1 is reached.
- 7. On expiry of dwell time DT, the tool is retracted with spindle speed SR to the safety clearance. The spindle stops and retracts to the retraction plane.

#### Approach/retraction during chipbreaking

- 1. The tool drills at the programmed spindle speed S (dependent on %S) as far as the first infeed depth (maximum infeed depth D).
- 2. Spindle stop and dwell time DT.
- 3. The tool retracts by the retraction distance V2 for chipbreaking.
- 4. The tool then drills to the next infeed depth at spindle speed S (dependent on %S).
- 5. Steps 2 to 4 are repeated until the programmed final drilling depth Z1 is reached.
- 6. On expiry of dwell time DT, the tool is retracted with spindle speed SR to the safety clearance. The spindle stops and retracts to the retraction plane.



Drill.

Thread

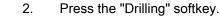
Tapping

#### Machine manufacturer

 $\langle \rangle$  Please refer to the machine manufacturer's specifications.

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



3. Press the "Thread" and "Tap" softkeys. The "tapping" input window opens.

#### Programming technological functions (cycles)

8.1 Drilling

Parameters, G code program		Parame	Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
			S / V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Compensating chuck mode	<ul><li>With compensating chuck</li><li>Without compensating chuck</li></ul>	
Machining position () (only for G code)	<ul> <li>Single position</li> <li>Drill hole at programmed position</li> <li>Position pattern</li> <li>Position with MCALL</li> </ul>	
Z0 (only for G code)	Reference point Z	mm
Z1 🖸	End point of the thread (abs) or thread length (inc) It is inserted into the workpiece until it reaches Z1.	mm
Machining - (with compensating chuck)	<ul> <li>You can select the following technologies for tapping: (only for G code)</li> <li>With encoder Tapping with spindle encoder</li> <li>Without encoder Tapping without spindle encoder; selection: - Define "Pitch" parameter</li> </ul>	
SR (only for ShopMill)	Spindle speed for retraction - (only for S)	rev/min
VR (only for ShopMill)	Constant cutting rate for retraction (only for V)	m/min
Pitch - (only machining without encoder)	<ul> <li>User input <ul> <li>Pitch results from the input</li> </ul> </li> <li>Active feedrate <ul> <li>Pitch results from the feedrate</li> <li>(only for G code)</li> </ul> </li> </ul>	
Table O	Thread table selection: <ul> <li>Without</li> <li>ISO metric</li> <li>Whitworth BSW</li> <li>Whitworth BSP</li> <li>UNC</li> </ul>	

8.	1	Drilling
----	---	----------

Parameter	Description	Unit
Selection	Selection of table value: e.g.	
U	M3; M10; etc. (ISO metric)	
	W3/4"; etc. (Whitworth BSW)	
	• G3/4"; etc. (Whitworth BSP)	
	• 1" - 8 UNC; etc. (UNC)	
Р	Pitch	
U - (selection	• in MODULUS: MODULUS = Pitch/ $\pi$	MODULE
option only for	• in turns per inch: Used with pipe threads, for example.	Turns/"
table selection "without")	When entered per inch, enter the integer number in front of the decimal point in the first parameter field and the figures after the decimal point as a fraction in the second and third field.	mm/rev
	• in mm/rev	
	in inch/rev	in/rev
	The pitch is determined by the tool used.	
αS	Starting angle offset - (for rigid tapping only)	Degrees
S	Spindle speed - (for rigid tapping only)	rev/min
Machining (rigid	The following machining operations can be selected:	
tapping)	• 1 cut	
U	The thread is drilled in one cut without stopping	
	Chipbreaking	
	The drill is retracted by the retraction amount V2 for chipbreaking.	
	Stock removal	
	The drill is retracted from the workpiece for stock removal.	
D	Maximum depth infeed - (only when used without compensating chuck, stock removal	mm
D	or chipbreaking)	
Retraction	Retraction distance - (only without compensating chuck, chipbreaking)	
U	Manual	
-	Retraction distance after each machining step (V2)	
	Automatic	
	Without retraction distance after each machining step	
V2	Retraction distance after each machining step – (only without compensating chuck,	mm
V L	chipbreaking and manual retraction)	
	Distance by which the drill is retracted for chipbreaking.	
	V2 = automatic: The tool is retracted by one revolution.	
DT (only for G code)	Dwell time at final drilling depth in seconds	S
SR (only for G code)	Spindle speed for retraction - (only for when a compensating chuck is not used)	rev/min
SDE (only for G code)	Direction of rotation after end of cycle:	

Parameter	Description	Unit
Technology 🔾	<ul> <li>Yes</li> <li>Exact stop</li> <li>Precontrol</li> <li>Acceleration</li> <li>Spindle</li> <li>No</li> </ul>	
Exact stop (only for technology, yes)	<ul> <li>Behavior the same as it was before the cycle was called</li> <li>G601: Block advance for exact stop fine</li> <li>G602: Block advance for exact stop coarse</li> <li>G603: Block advance if the setpoint has been reached</li> </ul>	
Precontrol (only for technology, yes) O	<ul> <li>Behavior the same as it was before the cycle was called</li> <li>FFWON: with precontrol</li> <li>FFWOF: without precontrol</li> </ul>	
Acceleration (only for technology, yes)	<ul> <li>Behavior the same as it was before the cycle was called</li> <li>SOFT: Jerk-limited (soft) acceleration of the axes</li> <li>BRISK: Abrupt acceleration of the axes</li> <li>DRIVE: Reduced axis acceleration</li> </ul>	
Spindle (only for technology, yes)	<ul> <li>Speed controlled: Spindle for MCAL; speed controlled operation</li> <li>Position controlled: Spindle for MCALL; position controlled operation</li> </ul>	

## 8.1.8 Drill and thread milling (CYCLE78)

#### Function

You can use a drill and thread milling cutter to manufacture an internal thread with a specific depth and pitch in one operation. This means that you can use the same tool for drilling and thread milling, a change of tool is superfluous.

The thread can be machined as a right- or left-hand thread.

#### Approach/retraction

- 1. The tool traverses with rapid traverse to the safety clearance.
- 2. If pre-drilling is required, the tool traverses at a reduced drilling feedrate to the predrilling depth defined in a setting data (ShopMill/ShopTurn). When programming in G code, the predrilling depth can be programmed using an input parameter.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

- The tool bores at drilling feedrate F1 to the first drilling depth D. If the final drilling depth Z1 is not reached, the tool will travel back to the workpiece surface in rapid traverse for stock removal. Then the tool will traverse with rapid traverse to a position 1 mm above the drilling depth previously achieved - allowing it to continue drilling at drill feedrate F1 at the next infeed. Parameter "DF" is taken into account from the 2nd infeed and higher (refer to the table "Parameters").
- 2. If another feedrate FR is required for through-boring, the residual drilling depth ZR is drilled with this feedrate.
- 3. If required, the tool traverses back to the workpiece surface for stock removal before thread milling with rapid traverse.
- 4. The tool traverses to the starting position for thread milling.
- 5. The thread milling is carried out (climbing, conventional or conventional + climbing) with milling feedrate F2. The thread milling acceleration path and deceleration path is traversed in a semicircle with concurrent infeed in the tool axis.

#### Procedure

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Drilling" softkey.



 Press the "Thread" and "Drill and thread mill" softkeys. The "Drilling and thread milling" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
			S/V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining position () (only for G code)	<ul> <li>Single position</li> <li>Drill hole at programmed position</li> <li>Position pattern</li> <li>Position with MCALL</li> </ul>	
F1	Drilling feedrate	
Z0 (only for G code)	Reference point Z	mm
Z1 Ŭ	Thread length (inc) or end point of the thread (abs)	

Parameter	Description	Unit
D	<ul> <li>Maximum depth infeed</li> <li>D ≥ Z1: Infeed to the final drilling depth</li> <li>D &lt; Z1: Several infeeds with stock removal</li> </ul>	
DF O	Percentage for each additional infeed     DF=100: Amount of infeed remains constant     DF<100: Amount of infeed is reduced in direction of final drilling depth Z1     Example: last infeed 4 mm; DE 20%	%
	<ul> <li>Example: last infeed 4 mm; DF 80%</li> <li>next infeed = 4 x 80% = 3.2 mm</li> <li>next but one infeed = 3.2 x 80% = 2.56 mm etc.</li> <li>Amount for each additional infeed</li> </ul>	mm
V1	<ul> <li>Minimum infeed - (only for DF, percentage for each additional infeed)</li> <li>Parameter V1 is only provided if DF&lt; 100 has been programmed.</li> <li>If the amount of infeed becomes very small, a minimum infeed can be programmed in parameter "V1".</li> <li>V1 &lt; amount of infeed: The tool is inserted by the infeed amount</li> <li>V1 &gt; amount of infeed: The tool is inserted by the infeed value programmed under V1.</li> </ul>	mm
Predrilling O	<ul> <li>Predrilling with reduced feedrate</li> <li>Yes</li> <li>No</li> <li>The reduced drilling feedrate is obtained as follows:</li> <li>Drilling feedrate F1 &lt; 0.15 mm/rev: Predrilling feedrate = 30% of F1</li> <li>Drilling feedrate F1 ≥ 0.15 mm/rev: Predrilling feedrate = 0.1 mm/rev</li> </ul>	
AZ (only for G code)	Predrilling depth with reduced drilling feedrate (inc) - ("yes", only for pre-drilling)	
Through boring	Remaining drilling depth with drilling feedrate <ul> <li>Yes</li> <li>No</li> </ul>	
ZR FR O	Residual drilling depth for through boring - ("yes", only for through boring)Drilling feedrate for remaining drilling depth - ("yes", only for through boring)	mm mm/min mm/rev
Stock removal	<ul> <li>Stock removal before thread milling</li> <li>Yes</li> <li>No</li> <li>Return to workpiece surface for stock removal before thread milling.</li> </ul>	
Thread O	Direction of rotation of the thread <ul> <li>Right-hand thread</li> <li>Left-hand thread</li> </ul>	
F2 U	Feedrate for thread milling	mm/min mm/tooth

Parameter	Description	Unit
Table O	Thread table selection: <ul> <li>without</li> <li>ISO metric</li> <li>Whitworth BSW</li> <li>Whitworth BSP</li> <li>UNC</li> </ul>	
Selection - (not for table "Without") O	<ul> <li>Selection of table value: e.g.</li> <li>M3; M10; etc. (ISO metric)</li> <li>W3/4"; etc. (Whitworth BSW)</li> <li>G3/4"; etc. (Whitworth BSP)</li> <li>N1" - 8 UNC; etc. (UNC)</li> </ul>	
P O - (selection option only for table selection "without")	<ul> <li>Pitch</li> <li>in MODULUS: MODULUS = Pitch/π</li> <li>in turns per inch: Used with pipe threads, for example. When entered per inch, enter the integer in front of the decimal point in the first parameter field and the figures after the decimal point as a fraction in the second and third field.</li> <li>in mm/rev</li> <li>in inch/rev</li> <li>The pitch is determined by the tool used.</li> </ul>	MODULUS Turns/" mm/rev in/rev
Z2	Retraction amount before thread milling The thread depth in the direction of the tool axis is defined using Z2. Z2 is relative to the tool tip.	mm
Ø	Nominal diameter	mm
Milling direction	<ul> <li>Climb milling: Mill thread in one cycle.</li> <li>Conventional milling: Mill thread in one cycle.</li> <li>Climbing - conventional: Mill thread in two cycles: rough cutting is performed by conventional milling with defined allowances, then finish cutting is performed by climb milling with milling feedrate FS.</li> </ul>	
FS O	Finishing feedrate - (only for climbing - conventional milling)	mm/min mm/tooth

8.1.9 Positioning and position patterns

### Function

After you have programmed the technology (cycle call), you must program the positions. Several position patterns are available:

- Arbitrary positions
- Position on a line, on a grid or frame
- Position on a full or pitch circle

Several position patterns can be programmed in succession. They are traversed in the order in which you program them.

#### Note

The number of positions that can be programmed in the one "Positions" step is limited to a maximum of 400!

#### Programming a position pattern in ShopMill

Several position patterns can be programmed in succession (up to 20 technologies and position patterns in total). They are executed in the order in which you program them.

The programmed technologies and subsequently programmed positions are automatically linked by the control.

#### Approach/retraction

- 1. Within a position pattern, or while approaching the next position pattern, the tool is retracted to the retraction plane and the new position or position pattern is then approached at rapid traverse.
- 2. With technological follow-up operations (e.g. centering drilling tapping), the respective drilling cycle must programmed after calling the next tool (e.g. drill) and immediately afterwards the call of the position pattern to be machined.

#### Tool traverse path

ShopMill

The programmed positions are machined with the previously programmed tool (e.g. center drill). Machining of the positions always starts at the reference point. In the case of a grid, machining is performed first in the direction of the 1st axis and then meandering back and forth. The frame and hole circle are machined counterclockwise.

• G codes

For G code, for lines/frames/grids, a start is always made at the next corner of the frame or grid or the end of the row. The frame and hole circle are machined counterclockwise.

#### 8.1.10 Arbitrary positions (CYCLE802)

#### **Function**

The "Arbitrary positions" cycle allows you to program positions freely, i.e. rectangular or polar. Individual positions are approached in the order in which you program them. Press softkey "Delete all" to delete all positions programmed in X/Y.

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



 $\sim$ 

2.

- Press the "Drilling" softkey. 3. Press the "Positions" softkey.
- The "Positions" input window opens.

Parameter	Description	Unit
LAB - (only for G code)	Repeat jump label for position	
PL 💟 - (only for G code)	Machining plane	
Selection <b>O</b> - (only for ShopMill)	Coordinate system <ul> <li>Rectangular</li> <li>Polar</li> </ul>	
- (only for ShopMill)	Polar coordinates of the 1st position for "polar" selection	
LO	Length (abs.)	mm
C0	Angle (abs.)	Degrees
X0	X coordinate for 1st position (abs.)	mm
Y0	Y coordinate for 1st position (abs.)	mm
- (only for ShopMill)	Polar coordinates, additional. Positions, when selecting "polar"	
L1 🖸 L7 🖸	Length (abs.)	mm
C1 🕖 C7 🚺	Angle (abs.)	Degrees
X1 🖸 X7 🖸	X coordinate for further positions (abs. or inc.)	mm
Y1 🚺 Y8 🚺	Y coordinate for further positions (abs. or inc.)	mm

# 8.1.11 Position pattern Line (HOLES1), Grid or Frame (CYCLE801)

#### Function

You can program the following pattern using the "Position pattern" cycle:

• Line (HOLES1)

In the "Line" selection option you can program any number of positions at equal distances along a line.

• Grid (CYCLE801)

You can use the "Grid" selection option to program any number of positions spaced at an equal distance along one or several parallel lines.

If you want to program a rhombus-shaped grid, enter angle  $\alpha X$  or  $\alpha Y$ .

• Frame (CYCLE801)

You can use the "Frame" selection option to program any number of positions spaced at an equal distance on a frame. The spacing may be different on both axes.

If you want to program a rhombus-shaped frame, enter angle  $\alpha X$  or  $\alpha Y$ .

#### Procedure

1.	The part program or ShopMill program to be processed has been
	created and you are in the editor.



2. Press the "Drilling" softkey.

Press the "Positions" and "Line" softkeys.
 The "Position pattern" input window opens.

Parameter	Description	Unit
LAB (only for G code)	Repeat jump label for position	
PL O (only for G code)	Machining plane	
Position pattern (only for G code)	<ul><li>Selection option for the following patterns:</li><li>Line</li><li>Grid</li><li>Frame</li></ul>	
Z0 (only for ShopMill)	Z coordinate of the reference point Z	mm

8.1 Driiling	8.	1	Drilling
--------------	----	---	----------

Parameter	Description	Unit
X0	X coordinate of the reference point X (abs) This position must be programmed absolutely in the 1st call.	mm
Y0	Y coordinate of the reference point Y (abs) mm This position must be programmed absolutely in the 1st call.	
αΟ	Angle of rotation of the line referred to the X axis Positive angle: Line is rotated counterclockwise. Negative angle: Line is rotated clockwise.	Degrees
L0	Distance of 1st position to reference point - (for line position pattern only)	mm
L	Distance between positions - (for line position pattern only)	mm
Ν	Number of positions - (for line position pattern only)	
αX	Shear angle X - (for grid or frame position pattern only)	Degrees
αY	Shear angle Y - (for grid or frame position pattern only)	Degrees
L1	Distance between columns - (for grid or frame position pattern only)	mm
L2	Distance between lines - (for grid or frame position pattern only)	mm
N1	Number of columns - (for grid or frame position pattern only)	
N2	Number of lines - (for grid or frame position pattern only)	

#### 8.1.12 Circle position pattern (HOLES2)

#### **Function**

You can program holes on a full circle or pitch circle with defined radius with the "Circle position pattern" cycle. The basic angle of rotation ( $\alpha$ 0) for the 1st position is relative to the X axis. The control calculates the angle of the next hole position as a function of the total number of holes. The angle it calculates is identical for all positions.

The tool can approach the next position along a linear or circular path.

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



- 2. Press the "Drilling" softkey.
- Positions



Press the "Positions" and "Circle" softkeys. 3. The "Position circle" input window opens.

Parameter	Description	Unit
LAB (only for G code)	Repeat jump label for position	
PL Ŭ	Machining plane	
Circular pattern O (only for G code)	<ul><li>Selection option for the following patterns:</li><li>Pitch circle</li><li>Full circle</li></ul>	
Z0 (only for ShopMill)	Z coordinate of the reference point Z	mm
X0	X coordinate of the reference point X (abs)	mm
Y0	Y coordinate of the reference point Y (abs)	mm
α0	Starting angle for first position. Positive angle: Full circle is rotated counterclockwise. Negative angle: Full circle is rotated in clockwise direction.	Degrees
α1	Advance angle - (for pitch circle pattern only)       Deg         After the first hole has been drilled, all further positions are advanced by this angle.       Deg         Positive angle: Further positions are rotated counterclockwise.       Negative angle: Further positions are rotated clockwise.	
R	Radius	mm
N	Number of positions	
Positioning	<ul> <li>Positioning motion between the positions</li> <li>Straight line Next position is approached linearly at rapid traverse.</li> <li>Circle Next position is approached at the programmed feedrate (FP) along a circular path.</li> </ul>	

# 8.1.13 Repeating positions

#### Function

If you want to approach positions that you have already programmed again, you can do this quickly with the function "Repeat position".

You must specify the number of the position pattern. This cycle automatically assigns this number. You will find this position pattern number in the work plan (program view) after the block number.

# Procedure



- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- Press the "Drilling", and "Repeat position" softkeys.
   The "Repeat positions" input window opens.

3. After you have entered the label or the position pattern number, e.g. 1, press the "Accept" softkey. The position pattern you have selected is then approached again.

Parameter	Description	Unit
LAB	Repeat jump label for position	
PL <b>(</b> (only for G code)	Machining plane	
Position (only for ShopMill)	Enter the number of the position pattern	

# 8.2.1 Face milling (CYCLE61)

#### Function

You can face mill any workpiece with the "Face milling" cycle.

A rectangular surface is always machined. The rectangle results from corner points 1 and 2 that are pre-assigned with the values of the blank part dimensions from the program header.

Workpieces with and without limits can be face-milled.

#### Note

If face milling is opened using a softkey, then the corner points X and Y from the program header are transferred. Further, Z0 and the abs/inc selection from X1, Y1 are also transferred.

#### Approach/retraction

1. For vertical machining, the starting point is always at the top or bottom. For horizontal machining, it is at the left or right.

The starting point is marked in the help display.

2. Machining is performed from the outside to the inside.

### Machining type

The cycle makes a distinction between roughing and finishing:

• Roughing:

Milling the surface

Tool turns above the workpiece edge

Finishing:

Milling the surface once

Tool turns at safety distance in the X/Y plane

Retraction of milling cutter

Depth infeed always takes place outside the workpiece.

For a workpiece with edge breaking, select the rectangular spigot cycle.

In face milling, the effective tool diameter for a tool of type "Milling cutter" is stored in a machine data item.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Selecting the machining direction

Toggle the machining direction in the "Direction" field until the symbol for the required machining direction appears.

- Same direction of machining
- Alternating direction of machining

#### **Selecting limits**

Press the respective softkey for the required limit.

Left
Тор
Bottom
Right

The selected limits are shown in the help screen and in the broken-line graphics.

#### Procedure



1. The part program or ShopMill program to be processed has been created and you are in the editor.

2. Press the "Milling" softkey.



Press the "Face milling" softkey.
 The "Face Milling" input window opens.

Parameters, G code program				Parameters, ShopMill program		
PL	Machining plane			Т	Tool name	
	Milling direction			D	Cutting edge number	
RP	Retraction plane	mm		F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm		S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min	]			

Parameter	Description	Unit
Machining	<ul> <li>The following machining operations can be selected:</li> <li>∇ (roughing)</li> </ul>	
9	• VVV (finishing)	
Direction	Same direction of machining	
U	• <mark>E</mark> • <del>U</del>	
	Alternating direction of machining	
	• <mark>5</mark> • <del>11</del>	
	The positions refer to the reference point:	
X0	Corner point 1X	mm
Y0	Corner point 1Y	mm
Z0	Height of blank	mm
X1 Ŭ	Corner point 2X (abs) or corner point 2X in relation to X0 (inc)	
Y1 🔼	Corner point 2Y (abs) or corner point 2Y in relation to Y0 (inc)	
Z1 Ŭ	Height of blank (abs) or height of blank in relation to Z0 (inc)	
DXY 🚺	Maximum plane infeed	mm
	Alternately, you can specify the plane infeed in %, as a ratio $\rightarrow$ plane infeed (mm) to the milling cutter diameter (mm).	%
DZ	Maximum depth infeed – (for roughing only)	mm
UZ	Finishing allowance, depth	mm

#### Note

The same finishing allowance must be entered for both roughing and finishing. The finishing allowance is used to position the tool for retraction.

# 8.2.2 Rectangular pocket (POCKET3)

#### Function

You can mill any rectangular pocket with the "rectangular pocket milling" function.

The following machining variants are available:

- Mill rectangular pocket from solid material.
- Pre-drill rectangular pocket in the center first if, for example, the milling cutter does not cut in the center (program the drilling, rectangular pocket and position program blocks in succession).
- Machine pre-machined rectangular pocket (see "Solid machining" parameter).

Depending on the dimensions of the rectangular pocket in the workpiece drawing, you can select a corresponding reference point for the rectangular pocket.

#### Approach/retraction

- 1. The tool approaches the center point of the rectangular pocket in rapid traverse at the height of the retraction plane and adjusts to the safety clearance.
- 2. The tool is inserted into the material according to the chosen strategy.
- 3. The rectangular pocket is always machined with the chosen machining type from inside out.
- 4. The tool moves back to the safety clearance at rapid traverse.

### Machining type

Roughing

During roughing, the individual planes of the rectangular pocket are machined one after the other from center point until depth Z1 is reached.

• Finishing

During finishing, the edge is always machined first. The rectangular pocket edge is approached on the quadrant that joins the corner radius. In the last infeed, the base is finished from the center out.

• Finishing of edge

Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted.

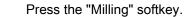
• Chamfering

Chamfering involves edge breaking at the upper edge of the rectangular pocket.

## Procedure



1. The part program or ShopMill program to be processed has been created and you are in the editor.



# Press the "Pocket" and "Rectangular pocket" softkeys. The "Rectangular pocket" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S / V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min			

Parameter	Description	Unit
Reference point	The following different reference point positions can be selected:	
U	• (center)	
	• (bottom left)	
	• (bottom right)	
	• top left)	
	• (top right)	
	The reference point (highlighted in blue) is displayed in the Help screen.	
Machining	The following machining operations can be selected:	
O	• $\nabla$ (roughing)	
	• $\nabla \nabla \nabla$ (finishing)	
	Chamfering	
Machining	Single position	
position	Mill rectangular pocket to the programmed position (X0, Y0, Z0).	
U	Position pattern	
	Position with MCALL	
	The positions refer to the reference point:	
X0	Reference point X – (single position only)	mm
Y0	Reference point Y – (single position only)	mm
Z0	Reference point Z – (single position only)	mm
W	Pocket width	mm
L	Pocket length	mm

Parameter	Description	Unit
R	Corner radius	mm
α0	Angle of rotation	Degrees
Z1	Depth referred to Z0 (inc) or pocket depth (abs) - (only for $\nabla$ , $\nabla\nabla\nabla$ or $\nabla\nabla\nabla$ edge)	mm
U		
DXY	Maximum plane infeed	mm
U	Maximum plane infeed as a percentage of the milling cutter diameter	%
	- (only for $\nabla$ and $\nabla\nabla\nabla$ )	
DZ	Maximum depth infeed – (only for $\nabla$ , $\nabla\nabla\nabla$ or $\nabla\nabla\nabla$ edge)	mm
UXY	Plane finishing allowance – (only for $\nabla$ , $\nabla\nabla\nabla$ or $\nabla\nabla\nabla$ edge)	mm
UZ	Depth finishing allowance – (only for $\nabla$ , $\nabla\nabla\nabla$ or $\nabla\nabla\nabla$ edge)	mm
Insertion	The following insertion modes can be selected – (only for $\nabla$ , $\nabla\nabla\nabla$ or $\nabla\nabla\nabla$ edge)	
U	Predrilled: (only for G code)	
	With G0, the pocket center point is approached at the retraction level, and then, from this position, the reference point brought forward by the safety clearance is approached also with G0. The machining of the rectangular pocket is then performed according to the selected insertion strategy, taking into account the programmed blank dimensions.	
	Perpendicular: Insert perpendicular to the center of pocket	
	The tool executes the calculated actual depth infeed at the pocket center in a single block. This setting can be used only if the cutter can cut across center or if the pocket has been predrilled.	
	Helical: Insert along helical path	
	The cutter center point traverses along the helical path determined by the radius and depth per revolution (helical path). If the depth for one infeed has been reached, a full circle motion is executed to eliminate the inclined insertion path.	
	Oscillating: Insert with oscillation along center axis of rectangular pocket	
	The cutter center point oscillates back and forth along a linear path until it reaches the depth infeed. When the depth has been reached, the path is traversed again without depth infeed in order to eliminate the inclined insertion path.	
FZ <mark>U</mark>	Depth infeed rate - (only for insertion, predrilled and perpendicular)	mm/min mm/tooth
EP	Maximum pitch of helix – (for helical insertion only)	mm/rev
ER	Radius of helix – (for helical insertion only)	mm
	The radius cannot be any larger than the cutter radius; otherwise, material will remain.	
EW	Maximum insertion angle – (for insertion with oscillation only)	Degrees
Solid machining	Complete machining	
(for roughing only)	The rectangular pocket is milled from the solid material.	
U	Editing	
	A rectangular pocket or hole has already been machined in the workpiece. This needs to be enlarged in one or several axes. You must program parameters AZ, W1 and L1 for this purpose.	

W1 and L1 for this purpose.

Depth of premachining - (for remachining only)

Width of premachining – (for remachining only)

Length of premachining - (for remachining only)

Chamfer width for chamfering - (for chamfering only)

Insertion depth of tool tip (abs or inc) - (for chamfer only)

ΑZ

W1

L1

FS

ZFS 🚺

mm

mm

mm

mm

mm

# 8.2.3 Circular pocket (POCKET4)

#### Function

You can mill any circular pocket with the "Circular pocket" cycle.

The following machining methods are available:

- Mill circular pocket from solid material.
- Pre-drill circular pocket in the center first if, for example, the milling cutter does not cut in the center (program the drilling, circular pocket and position program blocks in succession).
- Machine pre-machined circular pocket (see "Solid machining" parameter).
  - Complete machining
  - Remachining

The following machining types are available for milling using the "Circular pocket" function:

- Plane-by-plane
- Helical

#### Approach/retraction for plane-by-plane solid machining

In plane-by-plane machining of the circular pocket, the material is removed horizontally, one layer at a time.

- 1. The tool approaches the center point of the pocket at rapid traverse at the height of the retraction plane and adjusts to the safety clearance.
- 2. The tool is inserted into the material according to the chosen strategy.
- 3. The circular pocket is always machined from inside out using the selected machining method.
- 4. The tool moves back to the safety clearance at rapid traverse.

#### Approach/retraction for helical solid machining

In helical reaming, the material is removed down to pocket depth in a helical movement.

- 1. The tool approaches the center point of the pocket at rapid traverse at the height of the retraction plane and adjusts to the safety clearance.
- 2. Infeed to the first machining diameter.
- 3. The circular pocket is machined with the chosen machining type up to pocket depth or up to pocket depth with finishing allowance.
- 4. The tool moves back to the safety clearance at rapid traverse.
- 5. Lateral infeed to the next machining diameter.

#### Machining type: Plane-by-plane

When milling circular pockets, you can select the following machining types:

Roughing

During roughing, the individual planes of the circular pocket are machined one after the other from center point until depth Z1 is reached.

• Finishing

During finishing, the edge is always machined first. The pocket edge is approached on the quadrant, which joins the pocket radius. In the last infeed, the base is finished from the center out.

• Finishing of edge

Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted.

#### Machining type: Helical

When milling circular pockets, you can select the following machining types:

• Roughing

During roughing, the circular pocket is machined downward with helical movements.

A full circle is effected down to pocket depth to remove the residual material.

The tool is retracted from the edge and base of the pocket in a quadrant and retracted with rapid traverse to a safety clearance.

This process is repeated layer-by-layer, from inside out, until the circular pocket has been completely machined.

• Finishing

In finishing mode, the edge is machined first with a helical movement down to the bottom.

A full circle is effected down to pocket depth to remove the residual material.

The base is milled from outside in a spiral movement.

The tool is retracted from the center of the pocket to a safety clearance.

• Finishing of edge

In edge finishing, the edge is machined first with a helical movement down to the bottom.

A full circle is effected down to pocket depth to remove the residual material.

The tool is retracted from the edge and base of the pocket in a quadrant and retracted with rapid traverse to a safety clearance.

#### Procedure

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Milling" softkey.



Mill.

 Press the "Pocket" and "Circular pocket" softkeys. The "Circular Pocket" input window opens.

Parameters, G code program		Parameters, ShopMill program			
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rev/min m/min
F	Feedrate	mm/min			

Parameters	Description	Unit
Machining O	<ul> <li>∇ (roughing, plane-by-plane or helical)</li> <li>∇∇∇ (finishing, plane-by-plane or helical)</li> <li>∇∇∇ edge (edge finishing, plane-by-plane or helical)</li> <li>Chamfering</li> </ul>	
Machining type	<ul> <li>Plane-by-plane Machine circular pocket plane-by-plane</li> <li>Helical Machine circular pocket using helical type</li> </ul>	
Machining position O	<ul> <li>Single position <ul> <li>A circular pocket is machined at the programmed position (X0, Y0, Z0).</li> </ul> </li> <li>Position pattern <ul> <li>Several circular pockets are machined in a position pattern (e.g. full circle, pitch circle, grid, etc.).</li> </ul> </li> </ul>	
	The reference points refer to the center point of the circular pocket:	
X0	Reference point X – (for single position only)	mm
Y0	Reference point Y – (for single position only)	mm
Z0	Reference point Z – (for single position only)	mm
Ø	Diameter of pocket	mm
Z1	Pocket depth (abs) or depth relative to Z0 (inc) – (only for $\nabla,  \nabla \nabla \nabla$ and $\nabla \nabla \nabla$ edge)	mm
DXY O	<ul> <li>Maximum plane infeed</li> <li>Maximum plane infeed as a percentage of the cutting tool diameter</li> <li>- (only for ∇ and ∇∇∇)</li> </ul>	in %
DZ	Maximum depth infeed - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ Rand)	mm
UXY	Plane finishing allowance - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ edge)	mm
UZ	Depth finishing allowance – (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm

Parameters	Description	Unit
Insertion	<ul> <li>Various insertion modes can be selected – (only for plane-by-plane machining method and for ∇, ∇∇∇ or ∇∇∇ edge)</li> <li>Predrilled (only for G code)</li> <li>Perpendicular: Insert vertically in center of pocket The tool executes the calculated depth infeed vertically in the center of the pocket. Feedrate: Infeed rate as programmed under FZ</li> <li>Helical: Insert along helical path The cutter center point traverses along the helical path determined by</li> </ul>	
	<ul> <li>the radius and depth per revolution. If the depth for one infeed has been reached, a full circle motion is executed to eliminate the inclined insertion path.</li> <li>Feedrate: Machining feedrate</li> <li>Note: The vertical insertion into pocket center method can be used only</li> </ul>	
	if the tool can cut across center or if the workpiece has been predrilled.	
FZ	Depth infeed rate - (only for insertion, predrilled and perpendicular)	mm/min
FZ <mark>U</mark>	Depth infeed rate - (only for insertion, predrilled and perpendicular)	mm/min mm/tooth
EP	Maximum pitch of helix - (for helical insertion only) The helix pitch may be lower due to the geometric conditions.	mm/rev
ER	Radius of helix - (only for helical insertion) The radius must not be larger than the cutter radius, otherwise material will remain. Also make sure the circular pocket is not violated	mm
Solid machining	Complete machining	
O	The circular pocket must be milled from a solid workpiece (e.g. casting). <ul> <li>Editing</li> </ul>	
	A small pocket or hole has already been machined in the workpiece. This needs to be enlarged. Parameters AZ, and $\emptyset$ 1 must be programmed.	
FS	Chamfer width for chamfering - (for chamfering only)	mm
ZFS O	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm
AZ	Depth of premachining - (for remachining only)	mm
Ø1	Diameter of premachining - (for remachining only)	mm

# 8.2.4 Rectangular spigot (CYCLE76)

#### Function

You can mill various rectangular spigots with the "Rectangular spigot" cycle.

You can select from the following shapes with or without a corner radius:



Depending on the dimensions of the rectangular spigot in the workpiece drawing, you can select a corresponding reference point for the rectangular spigot.

In addition to the required rectangular spigot, you must also define a blank spigot, i.e. the outer limits of the material. The tool moves at rapid traverse outside this area. The blank spigot must not overlap adjacent blank spigots and is automatically placed by the cycle in a central position on the finished spigot.

The rectangular spigot is machined using only one infeed. If you want to machine the spigot using multiple infeeds, you must program the "Rectangular spigot" cycle several times with a reducing finishing allowance.

#### Sequence

- 1. The tool approaches the starting point at rapid traverse at the height of the retraction plane and is fed in to the safety clearance. The starting point is on the positive X axis rotated through α0.
- 2. The tool approaches the spigot contour sideways in a semicircle at machining feedrate. The tool first executes infeed at machining depth and then moves in the plane. The rectangular spigot is machined depending on the programmed machining direction (upcut/down-cut) in a clockwise or counterclockwise direction.
- 3. When the rectangular spigot has been traversed once, the tool retracts from the contour in a semicircle and then infeed to the next machining depth is performed.
- 4. The rectangular spigot is approached again in a semicircle and traversed once. This process is repeated until the programmed spigot depth is reached.
- 5. The tool moves back to the safety clearance at rapid traverse.

#### Machining type

Roughing

Roughing involves moving around the rectangular spigot until the programmed finishing allowance has been reached.

• Finishing

If you have programmed a finishing allowance, the rectangular spigot is moved around until depth Z1 is reached.

Chamfering

Chamfering involves edge breaking at the upper edge of the rectangular spigot.

### Procedure



1.

2.

3.

created and you are in the editor. Press the "Milling" softkey.

#### Multi-edge spigot Rectang. spigot

Press the "Multi-edge spigot" and "Rectangular spigot" softkeys. The "Rectangular Spigot" input window opens.

The part program or ShopMill program to be processed has been

Parameters, G code program		Parameters, ShopMill program			
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm (in)	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min			

Parameter	Description	Unit
FZ (only for G code)	Depth infeed rate	mm/min
Reference point	The following different reference point positions can be selected:	
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> <li>Chamfering</li> </ul>	
Machining position	<ul> <li>Single position <ul> <li>A rectangular spigot is machined at the programmed position (X0, Y0, Z0).</li> </ul> </li> <li>Position pattern <ul> <li>Several rectangular spigots are machined in a position pattern (e.g. full circle, pitch circle, grid, etc.).</li> </ul> </li> </ul>	
X0 Y0 Z0	The positions refer to the reference point: Reference point X – (for single position only) Reference point Y – (for single position only) Reference point Z – (for single position only)	mm mm mm
W L	Width of spigot Length of spigot	mm mm

Parameter	Description	Unit
R	Corner radius	mm
α0	Angle of rotation	Degrees
Z1 Ŭ	Spigot depth (abs) or depth relative to Z0 (inc) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
DZ	Maximum depth infeed - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
UXY	Plane finishing allowance for the length (L) and width (W) of the rectangular spigot.	mm
	Smaller rectangular spigot dimensions are obtained by calling the cycle again and programming it with a lower finishing allowance (only for $\nabla$ and $\nabla\nabla\nabla$ )	
UZ	Depth finishing allowance (tool axis) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
W1	Width of blank spigot (important for determining approach position) - (only for $\nabla$ and $\nabla \nabla \nabla$ )	mm
L1	Length of blank spigot (important for determining approach position) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
FS	Chamfer width for chamfering - (for chamfering only)	mm
ZFS 🜔	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm

# 8.2.5 Circular spigot (CYCLE77)

#### Function

You can mill various circular spigots with the "Circular spigot" function.

In addition to the required circular spigot, you must also define a blank spigot, i.e. the outer limits of the material. The tool moves at rapid traverse outside this area. The blank spigot must not overlap adjacent blank spigots and is automatically placed on the finished spigot in a centered position.

The circular spigot is machined using only one infeed. If you want to machine the spigot using multiple infeeds, you must program the "Circular spigot" function several times with a reducing finishing allowance.

#### Approach/retraction

- 1. The tool approaches the starting point at rapid traverse at the height of the retraction plane and is fed in to the safety clearance. The starting point is always on the positive X axis.
- 2. The tool approaches the spigot contour sideways in a semicircle at machining feedrate. The tool first executes infeed at machining depth and then moves in the plane. The circular spigot is machined depending on the programmed machining direction (upcut/down-cut) in a clockwise or counterclockwise direction.
- 3. When the circular spigot has been traversed once, the tool retracts from the contour in a semicircle and then infeed to the next machining depth is performed.
- 4. The circular spigot is approached again in a semicircle and traversed once. This process is repeated until the programmed spigot depth is reached.
- 5. The tool moves back to the safety clearance at rapid traverse.

#### Machining type

You can select the machining mode for milling the circular spigot as follows:

• Roughing

Roughing involves moving round the circular spigot until the programmed finishing allowance has been reached.

• Finishing

If you have programmed a finishing allowance, the circular spigot is moved around until depth Z1 is reached.

• Chamfering

Chamfering involves edge breaking at the upper edge of the circular spigot.

#### Procedure



- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Milling" softkey.



 Press the "Multi-edge spigot" and "Circular spigot" softkeys. The "Circular Spigot" input window opens.

Parameters, G code program			Parame	Parameters, ShopMill program		
PL	Machining plane		Т	Tool name		
	Milling direction		D	Cutting edge number		
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev	
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min	
F	Feedrate	mm/min				

Parameter	Description	Unit
FZ (only for G code)	Depth infeed rate	mm/min
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> <li>Chamfering</li> </ul>	

Parameter	Description	Unit			
Machining position	<ul> <li>Single position <ul> <li>A circular spigot is machined at the programmed position (X0, Y0, Z0).</li> </ul> </li> <li>Position pattern <ul> <li>Several circular spigots are machined in a position pattern</li> </ul> </li> </ul>				
	(e.g. full circle, pitch circle, grid, etc.).				
X0 Y0	The positions refer to the reference point: Reference point X – (for single position only) Reference point Y – (for single position only)	mm mm			
Z0	Reference point Z – (for single position only)	mm			
Ø	Diameter of spigot	mm			
L	Length of spigot	mm			
R	Corner radius n				
α0	Angle of rotation	Degrees			
Z1 U	Spigot depth (abs) or depth relative to Z0 (inc) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm			
DZ	Maximum depth infeed - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm			
UXY	Plane finishing allowance for the length (L) and width (W) of the circular spigot. Smaller circular spigot dimensions are obtained by calling the cycle again and programming it with a lower finishing allowance (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm			
UZ	Depth finishing allowance (tool axis) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm			
Ø1	Diameter of blank spigot (important for determining approach position) - (only for $\nabla$ and $\nabla\nabla\nabla$ )				
FS	Chamfer width for chamfering - (for chamfering only)	mm			
ZFS U	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm			

# 8.2.6 Multi-edge (CYCLE79)

#### Function

You can mill a multi-edge with any number of edges with the "Multi-edge" cycle. You can select from the following shapes with or without a corner radius or chamfer:



#### Approach/retraction

- 1. The tool approaches the starting point at rapid traverse at the height of the retraction plane and is fed in to the safety clearance.
- 2. The tool traverses the multi-edge in a quadrant at machining feedrate. The tool first executes infeed at machining depth and then moves in the plane. The multi-edge is machined depending on the programmed machining direction (up-cut/down-cut) in a clockwise or counterclockwise direction.
- 3. When the first plane has been machined, the tool retracts from the contour in a quadrant and then infeed to the next machining depth is performed.
- 4. The multi-edge is traversed again in a quadrant. This process is repeated until the depth of the multi-edge has been reached.
- 5. The tool retracts to the safety clearance at rapid traverse.

#### Note

A multi-edge with more than two edges is traversed helically; with a single or double edge, each edge is machined separately.

#### Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



3.

Press the "Milling" softkey.



Press the "Multi-edge spigot" and "Multi-edge" softkeys.
 The "Multi-edge" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min			

Parameter	Description	Unit
FZ (only for G code)	Depth infeed rate	mm/min
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> <li>∇∇∇ edge (edge finishing)</li> <li>Chamfering</li> </ul>	
Machining position	<ul> <li>Single position <ul> <li>A polygon is milled at the programmed position (X0, Y0, Z0).</li> </ul> </li> <li>Position pattern <ul> <li>Several polygons are milled at the programmed position pattern (e.g. pitch circle, grid, line).</li> </ul> </li> </ul>	
X0 Y0	The positions refer to the reference point: Reference point X – (for single position only) Reference point Y – (for single position only)	mm mm
<b>Z0</b>	Reference point Z – (for single position only)         Diameter of blank spigot	mm mm
N SW or L 🚺	Number of edges           Width across flats or edge length	
α0 R1 or FS1 <b>O</b>	Angle of rotation Rounding radius or chamfer width	Degrees
Z1 O DXY O	<ul> <li>Multi-edge depth (abs) or depth in relation to Z0 (inc) - (only for ∇, ∇∇∇ and ∇∇∇ edge)</li> <li>Maximum plane infeed</li> <li>Maximum plane infeed as a percentage of the cutting tool diameter</li> <li>- (only for ∇ and ∇∇∇)</li> </ul>	mm mm %
DZ	Maximum depth infeed - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
UXY	Plane finishing allowance - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ edge)	mm
UZ	Depth finishing allowance – (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
FS	Chamfer width for chamfering - (for chamfering only)	mm
ZFS 🚺	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm %

# 8.2.7 Longitudinal groove (SLOT1)

#### Function

You can mill any longitudinal groove with the "longitudinal groove" milling function.

The following machining methods are available:

- Mill longitudinal groove from solid material.
- Pre-drill longitudinal groove in the center first if, for example, the milling cutter does not cut in the center (program the drilling, rectangular pocket and position program blocks in succession).

Depending on the dimensions of the longitudinal groove in the workpiece drawing, you can select a corresponding reference point for the longitudinal groove.

#### Approach/retraction

- 1. The tool moves at rapid traverse to the retraction plane and infeeds at safety clearance.
- 2. The tool is inserted into the material according to the chosen strategy.
- 3. The longitudinal slot is always machined with the chosen machining type from inside out.
- 4. The tool moves back to the safety clearance at rapid traverse.

#### Machining type

You can select the machining mode for milling the longitudinal slot as follows:

Roughing

During roughing, the individual planes of the slot are machined one after the other until depth Z1 is reached.

• Finishing

During finishing, the edge is always machined first. The slot edge is approached on the quadrant, which joins the corner radius. In the last infeed, the base is finished from the center out.

• Finishing of edge

Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted.

Chamfer

Chamfering involves edge breaking at the upper edge of the longitudinal slot.

# Procedure



3.

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Milling" softkey.

Press the "Groove" and "Longitudinal groove" softkeys. The "Longitudinal Groove (SLOT1)" input window opens.

Parameters, G code program		Param			
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min			

Parameter	Description	Unit
Parameter Reference point	Description         Position of the reference point:         • (lefthand edge)         • (inside left)         • (center)         • (inside right)         • (righthand edge)	Unit
Machining O Machining position	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> <li>∇∇∇ edge (edge finishing)</li> <li>Chamfering</li> <li>Single position</li> </ul>	
O	<ul> <li>A slot is milled at the programmed position (X0, Y0, Z0).</li> <li>Position pattern Several slots are milled at the programmed position pattern (e.g. pitch circle, grid, line).</li> </ul>	

Parameter	Description	Unit
	The positions refer to the reference point:	
X0	Reference point X – (for single position only)	mm
Y0	Reference point Y – (for single position only)	mm
Z0	Reference point Z	mm
W	Groove width	mm
L	Groove length	mm
α0	Angle of rotation	Degrees
Z1 U	Slot depth (abs) or depth relative to Z0 (inc) – (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ edge)	mm
DXY	<ul> <li>Maximum plane infeed</li> <li>Maximum plane infeed as a percentage of the milling cutter diameter</li> <li>- (only for ∇ and ∇∇∇)</li> </ul>	mm %
DZ	Maximum depth infeed - (only for $\nabla$ , $\nabla \nabla \nabla$ and $\nabla \nabla \nabla$ Rand)	mm
UXY	Plane finishing allowance - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ edge)	mm
UZ	Depth finishing allowance (slot base) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
Insertion O	<ul> <li>The following insertion modes can be selected:</li> <li>Predrilled: (only for G code) Approach of reference point shifted by the amount of the safety clearance with G0. </li> <li>Perpendicular: Insert vertically in longitudinal groove center: The tool is inserted to infeed depth in the pocket center. Note: This setting can be used only if the cutter can cut across center. </li> <li>Helical: Insert along helical path The cutter center point traverses along the helical path determined by the radius and depth per revolution (helical path). If the depth for one infeed has been reached, a full longitudinal slot is machined to eliminate the inclined insertion path. </li> <li>Oscillating: Insert with oscillation along center axis of longitudinal groove: The cutter center point oscillates along a linear path until it reaches the depth infeed. When the depth has been reached, the path is traversed again without</li></ul>	mm
FZ	depth infeed in order to eliminate the inclined insertion path. Depth infeed rate	mm/min
FZ <mark>U</mark>	Depth infeed rate - (for perpendicular insertion only)	mm/min mm/tooth
EW	Maximum insertion angle - (for insertion with oscillation only)	Degrees
FS	Chamfer width for chamfering (inc) - (for chamfering only),	mm
ZFS 🚺	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm

# 8.2.8 Circumferential groove (SLOT2)

#### Function

You can mill one or several circumferential grooves of equal size on a full or pitch circle with the "circumferential groove" cycle.

#### **Tool size**

Please note that there is a minimum size for the milling cutter used to machine the circumferential groove:

• Roughing:

1/2 groove width W – finishing allowance UXY ≤ milling cutter diameter

• Finishing:

1/2 groove width W  $\leq$  milling cutter diameter

• Edge finishing:

Finishing allowance UXY ≤ milling cutter diameter

#### Annular groove

To create an annular groove, you must enter the following values for the "Number N" and "Aperture angle  $\alpha$ 1" parameters:

N = 1

α1 = 360°

#### Approach/retraction

- 1. The tool approaches the center point of the semicircle at the end of the slot at rapid traverse at the height of the retraction plane and adjusts to the safety clearance.
- 2. Then, the tool enters the workpiece at machining infeed (taking into consideration the maximum infeed in the Z direction and the finishing allowance). The circumferential slot is machined in the programmed machining direction (up-cut or down-cut) in a clockwise or counterclockwise direction.
- 3. When the first circumferential slot is finished, the tool moves to the retraction plane at rapid traverse.
- 4. The next circumferential slot is approached along a straight line or circular path and then machined.
- 5. The tool moves back to the safety clearance at rapid traverse.

#### Machining type

You can select the machining mode for milling the circumferential slot as follows:

Roughing

During roughing, the individual planes of the slot are machined one after the other from center point of the semicircle at the end of the slot until depth Z1 is reached.

Finishing •

> In "Finishing" mode, the edge is always machined first until depth Z1 is reached. The slot edge is approached on the quadrant, which joins the radius. In the last infeed, the base is finished from the center point of the semicircle to the end of the slot.

Finishing of edge

Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted.

• Chamfer

Chamfering involves edge breaking at the upper edge of the circumferential groove.

#### Procedure

- The part program or ShopMill program to be processed has been 1. created and you are in the editor.
- Mill. Groove

2.

3.

00000
Circular
groove

Press the "Groove" and "Circumferential groove" softkeys. The "Circumferential Groove" input window opens.

Parameters, G code program		Parameters, ShopMill program			
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min			

Press the "Milling" softkey.

Parameter	Description	Unit
FZ	Depth infeed rate	mm/min
(only for G code)		in/tooth
Machining	• $\nabla$ (roughing)	
U		
	<ul> <li>∇ + ∇∇∇ (roughing and finishing) - (only for ShopMill)</li> </ul>	
	Chamfering	
FZ	Depth infeed rate - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm/min
Circular pattern	Full circle	
U	<ul><li>The circumferential grooves are positioned around a full circle. The groove spacing is uniform and is calculated by the controller.</li><li>Pitch circle</li></ul>	
	The circumferential grooves are positioned around a pitch circle. The groove spacing can be determined on the basis of angle $\alpha 2$ .	
	The positions refer to the center point:	
X0	Reference point X	mm
Y0	Reference point Y	mm
Z0	Reference point Z	mm
N	Number of grooves	
R	Radius of circumferential groove	mm
α0	Starting angle	Degrees
α1	Opening angle of the groove	Degrees
α2	Advance angle - (for pitch circle only)	Degrees
W	Groove width	mm
Z1 <b>O</b> (only for G code)	Slot depth (abs) or depth relative to Z0 (inc) – (only for $\nabla, \nabla \nabla \nabla$ and $\nabla \nabla \nabla$ edge)	mm
Z1 (Only for ShopMill)	Slot depth (abs) or depth relative to Z0 (inc) - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
DZ	Maximum depth infeed - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ Rand)	mm
DZ	Maximum depth infeed - (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
FS	Chamfer width for chamfering (inc) - (for chamfering only),	mm
ZFS 🚺	Insertion depth of tool tip (abs or inc) - (for chamfering only),	mm
UXY (only for G code)	Plane finishing allowance - (only for $\nabla,\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ edge)	mm
UXY (only for ShopMill)	Plane finishing allowance – (only for $\nabla$ , $\nabla\nabla\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
Positioning	Positioning motion between the grooves:	
U	Straight line:	
	<ul><li>Next position is approached linearly at rapid traverse.</li><li>Circular:</li></ul>	
	Next position is approached at the programmed feedrate FP along a circular path.	
	i i i i i i i i i i i i i i i i i i i	L

# 8.2.9 Open groove (CYCLE899)

#### Function.

Use the "Open slot" function if you want to machine open slots.

For roughing, you can choose between the following machining strategies, depending on your workpiece and machine properties.

- Vortex milling
- Plunge cutting

The following machining types are available to completely machine the slot:

- Roughing
- Rough-finishing
- Finishing
- Base finishing
- Edge finishing
- Chamfering

#### Vortex milling

Particularly where hardened materials are concerned, this process is used for roughing and contour machining using coated VHM milling cutters.

Vortex milling is the preferred technique for HSC roughing, as it ensures that the tool is never completely inserted. This means that the set overlap is precisely maintained.

#### Plunge cutting

Plunge cutting is the preferred method of machining slots for "unstable" machines and workpiece geometries. This method generally only exerts forces along the tool axis, i.e. perpendicular to the surface of the pocket/slot to be machined (with the XY plane in Z direction). Therefore, the tool is subject to virtually no deformation. As a result of the axial loading of the tool, there is hardly any danger of vibration occurring for unstable workpieces.

The cutting depth can be considerably increased. The plunge cutter, as it is known, ensures a longer service life due to less vibration for long overhangs.

#### Approach/retraction for vortex milling

- 1. The tool approaches the starting point in front of the slot in rapid traverse and maintains the safety clearance.
- 2. The tool goes to the cutting depth.
- 3. The open slot is always machined along its entire length using the selected machining method.
- 4. The tool retracts to the safety clearance in rapid traverse.

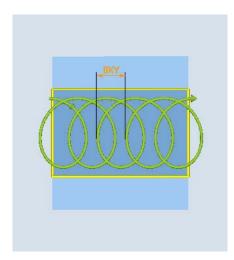
#### Approach/retraction for plunge cutting

- 1. The tool moves in rapid traverse to the starting point in front of the slot at the safety clearance.
- 2. The open slot is always machined along its entire length using the selected machining method.
- 3. The tool retracts to the safety clearance in rapid traverse.

#### Machining type, roughing vortex milling

Roughing is performed by moving the milling cutter along a circular path.

While performing this motion, the milling cutter is continuously fed into the plane. Once the milling cutter has traveled along the entire slot, it returns to its starting point, while continuing to move in a circular fashion. By doing this, it removes the next layer (infeed depth) in the Z direction. This process is repeated until the set slot depth plus the finishing allowance has been reached.



Vortex milling: Climbing or conventional milling

Vortex milling: Climbing - conventional milling

### Supplementary conditions for vortex milling

- Roughing
  - 1/2 slot width W finishing allowance UXY ≤ milling cutter diameter
- Slot width minimum 1.15 x milling cutter diameter + finishing allowance maximum, 2 x milling cutter diameter + 2 x finishing allowance
- Radial infeed minimum, 0.02 x milling cutter diameter maximum, 0.25 x milling cutter diameter
  - Maximum infeed depth ≤ cutting height of milling cutter

Please note that the cutting height of the milling cutter cannot be checked.

The maximum radial infeed depends on the milling cutter.

For hard materials, use a lower infeed.

#### Machining type, roughing plunge cutting

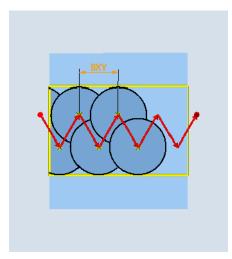
Roughing of the slot takes place sequentially along the length of the groove, with the milling cutter performing vertical insertions at the machining feedrate. The milling cutter is then retracted and repositioned at the next insertion point.

The milling cutter moves along the length of the slot, at half the infeed rate, and inserts alternately at the left-hand and right-hand walls.

The first insertion motion takes place at the slot edge, with the milling cutter inserted at half the infeed, less the safety clearance. (if the safety clearance is greater than the infeed, this will be on the outside). For this cycle, the maximum width of the slot must be less than double the width of the milling cutter + the finishing allowance.

Following each insertion, the milling cutter is lifted by the height of the safety clearance at the machining feedrate. As far as possible, this occurs during what is known as the retraction process, i.e. if the milling cutter's wrap angle is less than 180°, it is lifted at a 45- angle from the base in the opposite direction to the bisector of the wrap area.

The milling cutter then traverses over the material in rapid traverse.



#### Supplementary conditions for plunge cutting

• Roughing

1/2 slot width W - finishing allowance UXY ≤ milling cutter diameter

Maximum radial infeed

The maximum infeed depends on the width of the cutting edge of the milling cutter.

Increment

The lateral increment is calculated on the basis of the required slot width, milling cutter diameter and finishing allowance.

Retraction

Retraction involves the milling cutter being retracted at a  $45^{\circ}$  angle if the wrap angle is less than  $180^{\circ}$ .

Otherwise, retraction is perpendicular, as is the case with drilling.

Retraction

Retraction is performed perpendicular to the wrapped surface.

• Safety clearance

Traverse through the safety clearance beyond the end of the

workpiece in order to avoid rounding-off the

slot walls at the ends.

Please note that the milling cutter's cutting edge cannot be checked for the maximum radial infeed.

## Machining type, rough finishing

If there is too much residual material on the slot walls, unwanted corners are removed to the finishing dimension.

## Machining type, finishing

When finishing walls, the milling cutter travels along the slot walls, whereby just like for roughing, it is again fed in the Z direction, increment by increment. During this process, the milling cutter travels through the safety clearance beyond the beginning and end of the slot, so that an even slot wall surface can be guaranteed across the entire length of the slot.

## Machining type, edge finishing

Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted.

## Machining type, finishing base

When finishing the base, the milling cutter moves backwards and forwards once in the finished slot.

## Machining type, chamfering

Chamfering involves breaking the edge at the upper slot edge.

## Additional supplementary conditions

• Finishing

1/2 slot width W  $\leq$  milling cutter diameter

• Edge finishing

Finishing allowance UXY ≤ milling cutter diameter

• Chamfering

The tip angle must be entered into the tool table.

## Procedure



3.

1. The part program or ShopMill program to be processed has been created and you are in the editor.

Press the "Milling" softkey. 2.



Press the "Slot" and "Open slot" softkeys. The "Open slot" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
	Milling direction		D	Cutting edge number	
RP	Retraction plane	mm	F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm	S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min			

8.2	Mill	ling
-----	------	------

Parameters	Description	Unit
Reference point	Position of the reference point:	
U	(lefthand edge)	
	<b>g</b>	
	• (center)	
	(righthand edge)	
	- <u></u>	
Machining	• $\nabla$ (roughing)	
U	<ul> <li>∇∇ (pre-finishing)</li> </ul>	
U U	● ∇∇∇ (finishing)	
	• $\nabla \nabla \nabla$ edge (edge finishing)	
	Chamfering	
Technology	Vortex milling	
U	The milling cutter performs circular motions along the length of the slot and back	
	again.	
	Plunge cutting     Sequential drilling motion along the tool axis.	
U	Milling direction: - (except plunge cutting).	
_	Climbing	
	Conventional	
Machining	Single position	
position	Mill a slot at the programmed position (X0, Y0, Z0).	
C	Position pattern	
	Mill slots at a programmed position pattern (e.g. full circle or grid).	
	The positions refer to the reference point:	
X0	Reference point X – (for single position only)	mm
Y0	Reference point Y – (for single position only)	mm
Z0	Reference point Z – (for single position only)	mm
W	Slot width	mm
L	Slot length	mm
α0	Angle of rotation of slot	Degrees
Z1 🖸	Slot depth (abs) or depth relative to Z0 (abs) – (only for $\nabla$ , $\nabla\nabla\nabla$ , $\nabla\nabla\nabla$ base and $\nabla\nabla\nabla$ rough finishing)	mm
DXY	Maximum plane infeed	mm
O	Maximum plane infeed as a percentage of the milling cutter diameter	%
	- (only for $\nabla$ )	
DZ	Maximum depth infeed - (only for $\nabla$ , $\nabla\nabla\nabla$ rough finishing, $\nabla\nabla\nabla$ and $\nabla\nabla\nabla$ edge) - (only for vortex milling)	mm
UXY	Plane finishing allowance (slot edge) - (only for $\nabla$ , $\nabla\nabla\nabla$ rough finishing and $\nabla\nabla\nabla$ base)	mm
UZ	Depth finishing allowance (slot base) - (only for $\nabla$ , $\nabla\nabla\nabla$ rough finishing and $\nabla\nabla\nabla$ edge )	mm

Parameters	Description	Unit
FS	Chamfer width for chamfering (inc) - (for chamfering only)	mm
ZFS	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm

## 8.2.10 Long hole (LONGHOLE) - only for G code programs

## Function

Use the "Elongated hole" cycle to machine elongated holes arranged on a circle. The longitudinal axis of the elongated hole is aligned radially.

In contrast to the groove, the width of the elongated hole is determined by the tool diameter.

Internally in the cycle, an optimum traversing path of the tool is determined, ruling out unnecessary idle passes. If several depth infeeds are required to machine an elongated hole, the infeed is carried out alternately at the end points. The path to be traversed in the plane along the longitudinal axis of the elongated hole changes its direction after each infeed. The cycle searches for the shortest path when changing to the next elongated hole.

## NOTICE

The cycle requires a milling cutter with a "face tooth cutting over center" (DIN 844).

## Approach/retraction

- 1. Using G0, the starting position for the cycle is approached. In both axes of the current plane, the closest end point of the first elongated hole to be machined is approached at the level of the retraction plane in the tool axis and then lowered to the reference point shifted by the amount of the safety clearance.
- 2. Each elongated hole is milled in a reciprocating motion. The machining in the plane is performed using G1 and the programmed feedrate. At each reversal point, the infeed to the next machining depth calculated internally in the cycle is performed with G1 and the feedrate, until the final depth is reached.
- 3. Retraction to the retraction plane using G0 and approach to the next elongated hole on the shortest path.
- 4. After the last elongated hole has been machined, the tool at the position reached last in the machining plane is moved with G0 to the retraction plane, and the cycle terminated.

## Procedure



- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Milling" softkey.
- Press the "Groove" and "Elongated hole" softkeys.
   The "Elongated Hole" input window opens.

Parameters	Description	Unit			
PL Ŭ	Machining plane				
RP	Retraction plane (abs)				
SC	Safety clearance (inc)				
F	Feedrate	mm/min			
Machining type	Plane by plane	mm			
U	The tool is inserted to infeed depth in the pocket center.				
	<ul> <li>Note: This setting can be used only if the cutter can cut across center.</li> <li>Oscillating Insert with oscillation along center axis of longitudinal slot:</li> </ul>				
	The cutter center point oscillates along a linear path until it reaches the depth infeed. When the depth has been reached, the path is traversed again without depth infeed in order to eliminate the inclined insertion path.				
Reference point	Position of the reference point:				
O					
Machining	Single position				
position	An elongated hole is machined at the programmed position (X0, Y0, Z0).				
U	Position pattern				
	Several elongated holes are machined in the programmed position pattern (e.g. pitch circle, grid, line).				
	The positions refer to the reference point:				
X0	Reference point X – (for single position only)	mm			
Y0	Reference point Y – (for single position only)	mm			
Z0	Reference point Z	mm			
L	Elongated hole length mm				
α0	Angle of rotation Deg				
Z1 🚺	Elongated hole depth (abs) or depth in relation to Z0 (inc)	mm			

Parameters	Description	Unit
DZ	Maximum depth infeed	mm
FZ	Depth infeed rate	mm/min

## 8.2.11 Thread milling (CYCLE70)

## Function

Using a thread cutter, internal or external threads can be machined with the same pitch. Threads can be machined as right-hand or left-hand threads and from top to bottom or vice versa.

For metric threads (thread pitch P in mm/rev), the cycle assigns a value (calculated on the basis of the thread pitch) to the thread depth H1 parameter. You can change this value. The default selection must be activated via a machine data code.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

The entered feedrate refers to the machining. However the feedrate of the cutter center point is displayed. That is why a smaller value is displayed for internal threads and a larger value is displayed for external threads than was entered.

## Approach/retraction when milling internal threads

- 1. Positioning on retraction plane with rapid traverse.
- 2. Approach of starting point of the approach circle in the current plane with rapid traverse.
- 3. Infeed to a starting point in the tool axis calculated internally in the controller with rapid traverse.
- 4. Approach motion to thread diameter on an approach circle calculated internally in the controller with the programmed feedrate, taking into account the finishing allowance and maximum plane infeed.
- Thread cutting along a spiral path in clockwise or counterclockwise direction (depending on whether it is left-hand/right-hand thread, for number of cutting teeth of a milling plate (NT) ≥ 2 only 1 rotation, offset in the Z direction).
- 6. Exit motion along a circular path in the same rotational direction at programmed feedrate.
- With a programmed number of threads per cutting edge NT > 2, the tool is fed in (offset) by the amount NT-1 in the Z direction. Points 4 to 7 are repeated until the programmed thread depth is reached.
- 8. If the plane infeed is less than the thread depth, points 3 to 7 are repeated until the thread depth + programmed allowance is reached.
- 9. Retract on the thread center point and then to retraction plane in the tool axis in rapid traverse.

Please note that when milling an internal thread the tool must not exceed the following value: Milling cutter diameter < (nominal diameter -  $2 \cdot$  thread depth H1)

## Approach/retraction when milling external threads

- 1. Positioning on retraction plane with rapid traverse.
- 2. Approach of starting point of the approach circle in the current plane with rapid traverse.
- 3. Infeed to a starting point in the tool axis calculated internally in the controller with rapid traverse.
- 4. Approach motion to thread core diameter on an approach circle calculated internally in the controller with the programmed feedrate, taking into account the finishing allowance and maximum plane infeed.
- 5. Cut thread along a spiral path in clockwise or counterclockwise direction (depending on whether it is left-hand/right-hand thread, with NT ≥ 2 only one rotation, offset in Z direction).
- 6. Exit motion along a circular path in opposite rotational direction at programmed feedrate.
- With a programmed number of threads per cutting edge NT > 2, the tool is fed in (offset) by the amount NT-1 in the Z direction. Points 4 to 7 are repeated until the programmed thread depth is reached.
- 8. If the plane infeed is less than the thread depth, points 3 to 7 are repeated until the thread depth + programmed allowance is reached.
- 9. Retraction on the retraction plane in the tool axis with rapid traverse.

## Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



2.

Press the "Milling" softkey.

Thread<br/>milling3.Press the "Thread milling" softkey.The "thread milling" input window opens.

Parameters, G code program				Parameters, ShopMill program		
PL	Machining plane			Т	Tool name	
	Milling direction			D	Cutting edge number	
RP	Retraction plane	mm		F	Feedrate	mm/min mm/rev
SC	Safety clearance	mm		S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	mm/min	]			

Parameters	Description	Unit
Machining	∇ (roughing)	
C	Machining direction:	
	<ul> <li>Z0 → Z1</li> </ul>	
	Machining from top to bottom	
	<ul> <li>Z1 → Z0</li> </ul>	
	Machining from bottom to top	
U	Direction of rotation of the thread:	
	Right-hand thread	
	A right-hand thread is cut.	
	Left-hand thread	
	A left-hand thread is cut.	
O	Position of the thread:	
	Internal thread	
	An internal thread is cut.	
	External thread	
	An external thread is cut.	
NT	Number of teeth per cutting edge	
	Single or multiple toothed milling inserts can be used. The motions required are	
	executed by the cycle internally, so that the tip of the bottom tooth on the milling insert corresponds to the programmed end position when the thread end position is reached.	
	Depending on the cutting edge geometry of the milling insert, the retraction path must	
	be taken into account at the base of the workpiece.	
O (only for G code)	Machining position:	
	Single position	
	Position pattern (MCALL)	
O	The positions refer to the center point:	
X0	Reference point $X - ($ for single position only $)$	mm
Y0 Z0	Reference point Y – (for single position only) Reference point Z	mm
(only for G code)		mm
Z1	End point of the thread (abs) or thread length (inc)	mm
U		
Table	Thread table selection:	
	Without	
	ISO metric	
	<ul><li>Whitworth BSW</li><li>Whitworth BSP</li></ul>	
	Whitworth BSP     UNC	

8.2	Milling
-----	---------

Parameters	Description	Unit
Selection - (not for table "Without")	<ul> <li>Selection of table value: e.g.</li> <li>M3; M10; etc. (ISO metric)</li> <li>W3/4"; etc. (Whitworth BSW)</li> <li>G3/4"; etc. (Whitworth BSP)</li> <li>N1" - 8 UNC; etc. (UNC)</li> </ul>	
Ρ	Display of the thread pitch for the parameter input in the input field "Table" and "Selection".	MODULE Turns/" mm/rev inch/rev
P O - (selection option only for table selection "without")	<ul> <li>Pitch</li> <li>in MODULUS: For instance, used for worms that mesh with a gearwheel.</li> <li>per inch: Used with pipe threads, for example.</li> <li>When entered per inch, enter the integer number in front of the decimal point in the</li> </ul>	
	<ul> <li>first parameter field and the figures after the decimal point as a fraction in the second and third field.</li> <li>in mm/rev</li> <li>in inch/rev</li> <li>The tool used depends on the thread pitch.</li> </ul>	mm/rev in/rev
Ø	Nominal diameter Example: Nominal diameter of M12 = 12 mm	
H1	Thread depth	mm
αS	Starting angle	Degrees
rev	Finishing allowance in X and Y - (only for $\nabla$ )	mm

#### 8.2.12 Engraving (CYCLE60)

## Function

The "Engraving" function is used to engrave a text on a workpiece along a line or arc.

You can enter the text directly in the text field as "fixed text" or assign it via a variable as "variable text".

Engraving uses a proportional font, i.e., the individual characters are of different widths.

## Approach/retraction

- 1. The tool approaches the starting point at rapid traverse at the height of the retraction plane and adjusts to the safety clearance.
- 2. The tool moves to the machining depth FZ at the infeed feedrate Z1 and mills the characters.
- 3. The tool retracts to the safety clearance at rapid traverse and moves along a straight line to the next character.

- 4. Steps 2 and 3 are repeated until the entire text has been milled.
- 5. The tool moves to the retraction plane in rapid traverse.

## Procedure



- The part program or ShopMill program to be processed has been 1. created and you are in the editor.
- 2. Press the "Milling" softkey.



- 3. Press the "Engraving" softkey. The "Engraving" input window opens.

## Entering the engraving text

Special character OK	4.	<ul> <li>Press the "Special characters" softkey if you need a character that does not appear on the input keys.</li> <li>The "Special characters" window appears.</li> <li>Position the cursor on the desired character.</li> <li>Press the "OK" softkey.</li> <li>The selected character is inserted into the text at the cursor position.</li> </ul>
Delete text	5.	If you wish to delete the complete text, press the "Delete text" and "Delete" softkeys one after the other.
Delete		
Lower-case letters	6.	Press the "Lowercase" softkey to enter lowercase letters. Press it again to enter uppercase letters.
Variable	7.	Press the "Variable" and "Date" softkeys if you want to engrave the current date.
Date		The data is inserted in the European date format ( <dd>.<mm>.<yyyy>).</yyyy></mm></dd>
		To obtain a different date format, you must adapt the format specified in the text field. For example, to engrave the date in the American date format (month/day/year => $8/16/04$ ), change the format to <m>/<d>/<yy>.</yy></d></m>
Variable	7.	Press the "Variable" and "Time" softkeys if you want to engrave the current time.

## Programming technological functions (cycles) 8.2 Milling

335

Time		The time is inserted in the To have the time in the A		an format ( <time24>). format, change the format to</time24>
		<time12>.</time12>		
		Example: Text entry: Time: <time< th=""><th>245 Exec</th><th>ita: Tima: 16 25</th></time<>	245 Exec	ita: Tima: 16 25
		Time: <time12> Execut</time12>		
	7.			piece count 000123" softkeys to
Variable				a fixed number of digits and
				_ACTUAL_PARTS> is inserted and d with the softkey bar.
Quantity 000123		Define the number of holders (#) in the eng		adjusting the number of place d.
		If the specified numb	er of positi	ons (e.g. ##) is not sufficient to
		represent the unit qu	antity, ther	n the cycle automatically increases
		the number of require	ed position	S.
		- OR		
Variable	7.			piece count 123" softkeys if you ount without lead zeroes.
		The format text <#,_9 return to the engravir		JAL_PARTS> is inserted and you h the softkey bar.
Quantity 123		• Define the number of holders in the engrav		adjusting the number of place
				is not enough to display the cycle will automatically increase
Variable	7.	•		per 123.456" softkeys if you want to ain format.
		The format text <#.## the engraving field w		NUM> is inserted and you return to key bar.
Number 123.456		• The place holders #.# number defined in _V		the digit format in which the will be engraved.
		For example, if you h format the variable as		12.35 in _VAR_NUM, you can
		Entry	Release	Meaning
		<#,_VAR_NUM>	12	Places before decimal point unformatted, no places after the decimal point
		<####,_VAR_NUM>	0012	4 places before decimal point, leading zeros, no places after the decimal point

		< #,_VAR_NUM>	12	4 places before decimal point, leading blanks, no places after the decimal point
		<#.,_VAR_NUM>	12.35	Integer and fractional digits not formatted.
		<#.#,_VAR_NUM>	12.4	Places before decimal point unformatted, 1 place after the decimal point (rounded)
		<#.##,_VAR_NUM>	12.35	Places before decimal point unformatted, 2 places after the decimal point (rounded)
		<#.####,_VAR_NUM>	12.3500	Places before decimal point unformatted, 4 places after the decimal point (rounded)
		number entered, it is aut of digits is larger than th	omatically e number	t of the decimal point to display the extended. If the specified number to be engraved, the output format is riate number of leading and trailing
		Instead of the decimal p	oint you ca	an also use a blank.
		Instead of _VAR_NUM y R0).	ou can us	e any other numerical variable (e.g.
Variable	7.			text" softkeys if you want to take characters) from a variable.
Variable text		The format text <text, _'<br="">engraving field with the s</text,>		T> is inserted and you return to the r.
		You can use any other to	ext variabl	e instead of _VAR_TEXT.

## Note

## Entering the engraving text

Only single-line entries without line break are permissible!

## Variable texts

There are various ways of defining variable text:

• Date and time

For example, you can engrave the time and date of manufacture on a workpiece. The values for date and time are read from the NCK.

• Quantity

Using the workpiece variables you can assign a consecutive number to the workpieces.

You can define the format (number of digits, leading zeroes).

The place holder (#) is used to format the number of digits at which the workpiece counts output will begin.

If you do not want to output a count of 1 for the first workpiece, you can specify an additive value (e.g., <#,\$AC\_ACTUAL\_PARTS + 100>). The workpiece count output is then incremented by this value (e. g. 101, 102, 103,...).

• Numbers

When outputting number (e. g. measurement results), you can select the output format (digits either side of the point) of the number to be engraved.

• Text

Instead of entering a fixed text in the engraving text field, you can specify the text to be engraved via a text variable (e. g., \_VAR\_TEXT="ABC123").

## **Full circle**

If you want to distribute the characters evenly around a full circle, enter the arc angle  $\alpha 2=360^{\circ}$ . The cycle then distributes the characters evenly around the full circle.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
F	Feedrate	mm/min	S/V	Spindle speed or constant cutting rate	rpm m/min

Parameters	Description	Unit	
FZ (only for G code)	Depth infeed rate	mm/min	
FZ O (only for ShopMill)	Depth infeed rate		
Alignment O	<ul> <li>ABC (linear alignment)</li> <li>ABc (curved alignment)</li> <li>ABc (curved alignment)</li> </ul>		

Parameters	Description	Unit
Reference point	Position of the reference point	
U	• bottom left	
	• bottom center	
	• bottom right	
	• top left	
	• top center	
	• top right	
	• left-hand edge	
	• center	
	• right-hand edge	
Engraving text	maximum 100 characters	
X0 or R 🚺	Reference point X (abs) or reference point length polar	mm
	– (for curved alignment only)	
Y0 or α0 U	Reference point Y (abs) or reference point angle polar	mm or
	<ul> <li>– (for curved alignment only)</li> </ul>	degrees
Z0	Reference point Z (abs)	mm
Z1 Ŭ	Engraving depth (abs) or depth referred to Z0 (inc)	mm
W	Character height	mm
DX1 or α2 🔱	Distance between characters or angle of opening – (for curved alignment only)	mm or
		degrees
DX1 or DX2 Ŭ	Distance between characters or total width – (for linear alignment only)	mm
α1	Text direction (for linear alignment only)	
XM or LM 💟	Center point X (abs) or center point length polar mm	
	– (for curved alignment only)	
YM or aM 💟	Center point X (abs) or center point angle polar	mm
	– (for curved alignment only)	

Programming technological functions (cycles) 8.3 Contour milling

## 8.3 Contour milling

## 8.3.1 General

#### Function

You can mill simple or complex contours with the "Contour milling" cycle. You can define open contours or closed contours (pockets, islands, spigots).

A contour comprises separate contour elements, whereby at least two and up to 250 elements result in a defined contour. Radii, chamfers and tangential transitions are available as contour transition elements.

The integrated contour calculator calculates the intersection points of the individual contour elements taking into account the geometrical relationships, which allows you to enter incompletely dimensioned elements.

With contour milling, you must always program the geometry of the contour before you program the technology.

## 8.3.2 Representation of the contour

## G Code program

In the editor, the contour is represented in a program section using individual program blocks. If you open an individual block, then the contour is opened.

#### ShopMill program

The cycle represents a contour as a program block in the program. If you open this block, the individual contour elements are listed symbolically and displayed in broken-line graphics.

## Symbolic representation

The individual contour elements are represented by symbols adjacent to the graphics window. They appear in the order in which they were entered.

Contour element	Symbol	Meaning
Starting point	$\oplus$	Starting point of the contour
Straight line up Straight line down	<pre>\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$</pre>	
Straight line left Straight line right	$ \begin{array}{c} \leftarrow \\ \rightarrow \end{array} $	Straight line in 90° grid Straight line in 90° grid

## Programming technological functions (cycles)

## 8.3 Contour milling

Contour element	Symbol	Meaning	
Straight line in any direction	2	Straight line with any gradient	
Arc right Arc left	$\sim$	Circle Circle	
Pole	Ľ	Straight diagonal or circle in polar coordinates	
Finish contour	END	End of contour definition	

The different colors of the symbols indicate their status:

Foreground	Background	Meaning
Black	Blue	Cursor on new element
Black	Orange Cursor on current element	
Black	White	Normal element
Red	White	Element not currently evaluated (element will only be evaluated when it is selected with the cursor)

## Graphical display

The progress of contour programming is shown in broken-line graphics while the contour elements are being entered.

When the contour element has been created, it can be displayed in different line styles and colors:

- Black: Programmed contour
- Orange: Current contour element
- Green dashed: Alternative element
- Blue dotted: Partially defined element

The scaling of the coordinate system is adjusted automatically to match the complete contour.

The position of the coordinate system is displayed in the graphics window.

## 8.3.3 Creating a new contour

## Function

For each contour that you want to mill, you must create a new contour.

The contours are stored at the end of the program.

#### Note

When programming in the G code, it must be ensured that the contours are located after the end of program identifier!

The first step in creating a contour is to specify a starting point. Enter the contour element. The contour processor then automatically defines the end of the contour.

If you alter the tool axis, the cycle will automatically adjust the associated starting point axes. You can enter any additional commands (up to 40 characters) in G code format for the starting point.

## Additional commands

You can program feedrates and M commands, for example, using additional G code commands. You can enter the additional commands (max. 40 characters) in the extended parameter screens ("All parameters" softkey). However, make sure that the additional commands do not collide with the generated G code of the contour. Therefore, do not use any G code commands of group 1 (G0, G1, G2, G3), no coordinates in the plane and no G code commands that have to be programmed in a separate block.

## Procedure



- The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Contour milling" and "New contour" softkeys. The "New Contour" input window opens.



4.

- 3. Enter a contour name.
  - Press the "Accept" softkey. The input screen for the starting point of the contour appears. You can enter Cartesian or polar coordinates.

## Cartesian starting point



- 1. Enter the starting point for the contour.
- 2. Enter any additional commands in G code format, as required.
- 3. Press the "Accept" softkey.
- 4. Enter the individual contour elements.

## Polar starting point

Pole	1.
	2.
	3.
	4.
Accept	5.

- . Press the "Pole" softkey.
- 2. Enter the pole position in Cartesian coordinates.
- 3. Enter the starting point for the contour in polar coordinates.
- Enter any additional commands in G code format, as required.
- 5. Press the "Accept" softkey.
- 6. Enter the individual contour elements.

Parameter	Description	Unit
PL	Machining plane	
	Cartesian:	
Х	Starting point X (abs)	mm
Y	Starting point Y (abs)	mm
	Polar:	
х	Position pole (abs)	mm
Y	Position pole (abs)	Degrees
Starting point		
L1	Distance to pole, end point (abs)	mm
φ1	Polar angle to the pole, end point (abs)	Degrees
Additional commands	The contour is finished in continuous-path mode (G64). As a result, contour transitions such as corners, chamfers or radii may not be machined precisely.	
	If you wish to avoid this, there is a possibility to use additional commands when programming.	
	Example: For a contour, first program the X parallel straight line and then enter "G9" (non-modal exact stop) for the additional command parameter. Then program the Y-parallel straight line. The corner will be machined exactly, as the feedrate at the end of the X-parallel straight line is briefly zero.	
	Note:	
	The additional commands are only effective for path milling!	

## 8.3.4 Creating contour elements

After you have created a new contour and specified the starting point, you can define the individual elements that make up the contour.

The following contour elements are available for the definition of a contour:

- Straight vertical line
- Straight horizontal line
- Diagonal line

- Circle/arc
- Pole

For each contour element, you must parameterize a separate parameter screen.

The coordinates for a horizontal or vertical line are entered in Cartesian format; however, for the contour elements Diagonal line and Circle/arc you can choose between Cartesian and polar coordinates. If you wish to enter polar coordinates you must first define a pole. If you have already defined a pole for the starting point, you can also refer the polar coordinates to this pole. Therefore, in this case, you do not have to define an additional pole.

Parameter entry is supported by various help screens that explain the parameters.

If you leave certain fields blank, the geometry processor assumes that the values are unknown and attempts to calculate them from other parameters.

Conflicts may result if you enter more parameters than are absolutely necessary for a contour. In such a case, try to enter fewer parameters and allow the geometry processor to calculate as many parameters as possible.

#### Contour transition elements

As a transition between two contour elements, you can choose a radius or a chamfer. The transition element is always attached at the end of a contour element. The contour transition element is selected in the parameter screen of the respective contour element.

You can use a contour transition element whenever there is an intersection between two successive elements which can be calculated from the input values. Otherwise you must use the straight/circle contour elements.

The contour end is an exception. Although there is no intersection to another element, you can still define a radius or a chamfer as a transition element for the blank.

## Additional functions

The following additional functions are available for programming a contour:

Tangent to preceding element

You can program the transition to the preceding element as tangent.

Dialog box selection

If two different possible contours result from the parameters entered thus far, one of the options must be selected.

Close contour

From the actual position, you can close the contour with a straight line to the starting point.

## Procedure for entering contour elements

	1.	The part program or the machining schedule is opened. Position the cursor at the desired entry position.
	2.	Contour input using contour support:
Cont. mill.	2.1	Press the "Contour milling", "Contour" and "New contour" softkeys.
Contour		
New contour		
Accept	2.2	In the opened input window, enter a name for the contour, e.g. contour_1.
		Press the "Accept" softkey.
Accept	2.3	The input screen to enter the contour opens, in which you initially enter a starting point for the contour. This is marked in the lefthand navigation bar using the "+" symbol.
		Press the "Accept" softkey.
	3.	Enter the individual contour elements of the machining direction.
		Select a contour element via softkey.
<b>‡</b>		The "Straight (e.g. X)" input window opens.
		- OR
←•→		The "Straight (e.g. Y)" input window opens.
		- OR
		The "Straight (e.g. XY)" input window opens.
		- OR
		The "Circle" input window opens.
$( \uparrow \uparrow )$		The Circle linput window opens.
		- OR
		The "Pole Input" input window opens.
Pole		
	4	Enter all the data available from the workpiece drawing in the input

. Enter all the data available from the workpiece drawing in the input screen (e.g. length of straight line, target position, transition to next element, angle of lead, etc.).

Accept	5.	Press the "Accept" softkey. The contour element is added to the contour.
Tangent. trans.	6.	When entering data for a contour element, you can program the transition to the preceding element as a tangent.
		Press the "Tangent to prec. elem." softkey. The "tangential" selection appears in the parameter $\alpha 2$ entry field.
	7.	Repeat the procedure until the contour is complete.
	8.	Press the "Accept" softkey.
Accept		The programmed contour is transferred into the process plan (program view).
All para- meters	9.	If you want to display further parameters for certain contour elements, e.g. to enter additional commands, press the "All parameters" softkey.

# Contour element "Straight line, e.g. X"

Parameter	Descr	Description		
XU	End p	ooint X (abs or inc)	mm	
α1	Startin	ng angle e.g. to the X axis	Degrees	
α2	Angle	Angle to the preceding element		
Transition to next element O	• Ra	Type of transition <ul> <li>Radius</li> <li>Chamfer</li> </ul>		
Radius	R	R Transition to following element - radius		
Chamfer	FS Transition to following element - chamfer		mm	
Additional commands	Additi	Additional G code commands		

## Contour element "straight line, e.g. Y"

Parameter	Desc	Description				
YU	End p	End point Y (abs or inc)				
α1	Starti	arting angle to X axis				
Transition to next element O	• R	Type of transition <ul> <li>Radius</li> <li>Chamfer</li> </ul>				
Radius	R	Transition to following element - radius	mm			
Chamfer	FS Transition to following element - chamfer					
Additional commands	Addit	ional G code commands				

## Contour element "Straight line, e.g. XY"

Parameter	Descr	Description					
ΧU	End p	oint X (abs or inc)	mm				
YU	End p	oint Y (abs or inc)	mm				
L	Lengt	h	mm				
α1	Startin	ng angle e.g. to the X axis	Degrees				
α2	Angle	Angle to the preceding element					
Transition to next element O	· · · · · · · · · · · · · · · · · · ·						
Radius	R	Transition to following element - radius	mm				
Chamfer	FS	FS Transition to following element - chamfer					
Additional commands	Additi	onal G code commands					

## Contour element "Circle"

Parameter	Description	Unit		
Direction of rotation	<ul> <li>Clockwise direction of rotation</li> <li>Counterclockwise direction of rotation</li> </ul>			
R	Radius	mm		
e.g. X Ŭ	End point X (abs or inc)	mm		
e.g. Y Ŭ	End point Y (abs or inc)	mm		
e.g. l Ŭ	Circle center point I (abs or inc)	mm		
e.g. J Ŭ	Circle center point J (abs or inc)	mm		
α1	Starting angle to X axis	Degrees		
α2	Angle to the preceding element	Degrees		
β1	End angle to Z axis	Degrees		
β2	Angle of opening	Degrees		
Transition to next element O	on to next Type of transition			
Radius	R Transition to following element - radius	mm		
Chamfer	FS Transition to following element - chamfer	mm		
Additional commands	Additional G code commands			

## Contour element "Pole"

Parameter	Description	Unit
Х	Position pole (abs)	mm
Y	Position pole (abs)	mm

## Contour element "End"

The data for the transition at the contour end of the previous contour element is displayed in the "End" parameter screen.

The values cannot be edited.

#### 8.3.5 Changing the contour

## **Function**

You can change a previously created contour later.

If you want to create a contour that is similar to an existing contour, you can copy the existing one, rename it and just alter selected contour elements.

Individual contour elements can be

- added,
- changed, •
- inserted or
- deleted.

## Procedure for changing a contour element

- 1. Open the part program or ShopMill program to be executed.
- 2. With the cursor, select the program block where you want to change the contour. Open the geometry processor.

The individual contour elements are listed.

- 3. Position the cursor at the position where a contour element is to be inserted or changed.
- 4. Select the desired contour element with the cursor.
- 5. Enter the parameters in the input screen or delete the element and select a new element.



6. Press the "Accept" softkey.

The desired contour element is inserted in the contour or changed.

## Procedure for deleting a contour element

- 1. Open the part program or ShopMill program to be executed.
- 2. Position the cursor on the contour element that you want to delete.



- 3. Press the "Delete element" softkey.
- 4. Press the "Delete" softkey.

## 8.3.6 Contour call (CYCLE62) - only for G code program

#### Function

The input creates a reference to the selected contour.

There are four ways to call the contour:

1. Contour name

The contour is in the calling main program.

2. Labels

The contour is in the calling main program and is limited by the labels that have been entered.

3. Subprogram

The contour is located in a subprogram in the same workpiece.

4. Labels in the subprogram

The contour is in a subprogram and is limited by the labels that have been entered.

## Procedure

1. The subprogram to be edited has been created and you are in the editor.



- 2. Press the "Contour milling" softkey.
- 3. Press the "Contour" and "Contour call" softkeys. The "Contour Call" input window opens.
- 4. Assign parameters to the contour selection.

Parameter	Description	Unit
Contour selection	<ul> <li>Contour name</li> <li>Labels</li> <li>Subprogram</li> <li>Labels in the subprogram</li> </ul>	
Contour name	CON: Contour name	
Labels	<ul><li>LAB1: Label 1</li><li>LAB2: Label 2</li></ul>	
Subprogram	PRG: Subprogram	
Labels in the subprogram	<ul> <li>PRG: Subprogram</li> <li>LAB1: Label 1</li> <li>LAB2: Label 2</li> </ul>	

## 8.3.7 Path milling (CYCLE72)

## Function

You can mill along any programmed contour with the "Path milling" cycle. The function operates with cutter radius compensation. Machining can be performed in either direction, i.e. in the direction of the programmed contour or in the opposite direction.

It is not imperative that the contour is closed. You can perform any of the following operations:

- Inside or outside machining (on left or right of the contour).
- Machining along center-point path.

For machining in the opposite direction, contours must not consist of more than 170 contour elements (incl. chamfers/radii). Special aspects (except for feed values) of free G code input are ignored during path milling in the opposite direction to the contour.

## Programming of arbitrary contours

The machining of arbitrary open or closed contours is generally programmed as follows:

1. Enter contour

You build up the contour gradually from a series of different contour elements.

2. Contour call (CYCLE62)

You select the contour to be machined.

3. Path milling (roughing)

The contour is machined taking into account various approach and retract strategies.

4. Path milling (finishing)

If you programmed a finishing allowance for roughing, the contour is machined again.

5. Path milling (chamfering)

If you have planned edge breaking, chamfer the workpiece with a special tool.

## Path milling on right or left of the contour

A programmed contour can be machined with the cutter radius compensation to the right or left. You can also select various modes and strategies of approach and retraction from the contour.

## Approach/retraction mode

The tool can approach or retract from the contour along a quadrant, semi-circle or straight line.

- With a quadrant or semi-circle, you must specify the radius of the cutter center point path.
- With a straight line, you must specify the distance between the cutter outer edge and the contour starting or end point.

You can also program a mixture of modes, e.g. approach along quadrant, retract along semicircle.

## Approach/retraction strategy

You can choose between planar approach/retraction and spatial approach/retraction:

• Planar approach:

Approach is first at depth and then in the machining plane.

• Spatial approach:

Approach is at depth and in machining plane simultaneously.

• Retraction is performed in reverse order.

Mixed programming is possible, for example, approach in the machining plane, retract spatially.

## Path milling along center-point path.

A programmed contour can also be machined along the center-point path if the radius correction was switched-out. In this case, approaching and retraction is only possible along a straight line or vertical. Vertical approach/retraction can be used for closed contours, for example.

## Procedure



- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
  - Press the "Contour milling" and "Path milling" softkeys. The "Path Milling" input window opens.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
RP	Retraction plane	mm	D	Cutting edge number	
SC	Safety clearance	mm	F	Feedrate	mm/min mm/rev
F	Feedrate	mm/min	S / V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> <li>Chamfering</li> </ul>	
Machining direction	<ul> <li>Machining in the programmed contour direction</li> <li>Forward: Machining is performed in the programmed contour direction</li> <li>Backward: Machining is performed in the opposite direction to the programmed contour</li> </ul>	
Radius compensation	<ul> <li>Left (machining to the left of the contour)</li> <li>Right (machining to the right of the contour)</li> <li>Image: a contour contained on the center-point path. In this case, approaching and retraction is only possible along a straight line or vertical. Vertical approach/retraction can be used for closed contours, for example.</li> </ul>	
Z0	Reference point Z (abs or inc)	
Z1 Ŭ	Final depth (abs) or final depth referred to Z0 (inc) - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
DZ	Maximum depth infeed - (only for $\nabla$ and $\nabla\nabla\nabla$ )	mm
UZ	Depth finishing allowance - (only for $\nabla$ )	mm
FS	Chamfer width for chamfering (inc) - (for chamfering only)	mm

Parameter	Description	Unit
ZFS	Insertion depth of tool tip (abs or inc) - (for chamfering only)	mm
UXY	Plane finishing allowance - (only for $ abla$ and G code)	mm
Approach	Planar approach mode:	
U	Straight line:	
	Slope in space	
	Quadrant:	
	Part of a spiral (only with path milling left and right of the contour)	
	Semi-circle:	
	Part of a spiral (only with path milling left and right of the contour)	
	Perpendicular:	
	Perpendicular to the path (only with path milling on the center-point path)	
Approach strategy	Axis by axis	
O		
	Spatial (only for "quadrant, semi-circle or straight line" approach)	
D1	Approach radius - (only for "quadrant or semi-circle" approach)	
R1 L1	Approach distance - (only for "straight line" approach)	mm mm
Retraction	Planar retraction mode:	
O	Straight line	
U III	Quadrant:	
	Part of a spiral (only with path milling left and right of the contour)	
	Semi-circle:	
	Part of a spiral (only with path milling left and right of the contour)	
Retraction	Axis by axis	
strategy		
U		
	Spatial (not with perpendicular approach mode)	
R2	Retraction radius - (only for "quadrant or semi-circle" retraction)	mm
L2	Retraction distance - (only for "straight line" retraction)	mm
Lift mode	If more than one depth infeed is necessary, specify the retraction height to which the	
O	tool retracts between the individual infeeds (at the transition from the end of the contour to the start).	
	Lift mode before new infeed	
	• Z0 + safety clearance	
	By the safety clearance	
	to RP	
	No retraction	
FZ	Depth infeed rate - (only for G code)	

Parameter	Description	Unit
FR	Retraction feedrate for intermediate positioning - (not with "No retraction" lift mode)	
FS	Chamfer width for chamfering - (only for chamfering machining)	mm
ZFS 🕖	Insertion depth of tool tip (abs or inc) - (for machining only)	mm

## 8.3.8 Contour pocket/contour spigot (CYCLE63/64)

## Contours for pockets or islands

Contours for pockets or islands must be closed, i.e. the starting point and end point of the contour are identical. You can also mill pockets that contain one or more islands. The islands can also be located partially outside the pocket or overlap each other. The first contour you specify is interpreted as the pocket contour and all the others as islands.

## Automatically calculating/Manually entering the starting point

Using "Automatic starting point" you have the option of calculating the optimum plunge point.

By selecting "Manual starting point", you define the plunge point in the parameter screen.

If the islands and the miller diameter, which must be plunged at various locations, are obtained from the pocket contour, then the manual entry only defines the first plunge point; the remaining plunge points are automatically calculated.

## Contours for spigots

Contours for spigots must be closed, i.e. the starting point and end point of the contour are identical. You can define multiple spigots, which can also overlap. The first contour specified is interpreted as a blank contour and all others as spigots.

## Machining

You program the machining of contour pockets with islands/blank contour with spigots e.g. as follows:

- 1. Enter the pocket contour/blank contour
- 2. Enter the island/spigot contour
- 3. Call the contour for pocket contour/blank contour or island/spigot contour (only for G code program)
- 4. Center (this is only possible for pocket contour)
- 5. Predrill (this is only possible for pocket contour)
- 6. Solid machine/machine pocket / spigot roughing
- 7. Solid machine/machine remaining material roughing

- 8. Finishing (base/edge)
- 9. Chamfering



## Software option

For solid machining residual material, you require the option "residual material detection and machining".

## Name convention

For multi-channel systems, cycles attach a "\_C" and a two-digit number of the specific channel to the names of the programs to be generated, e.g. for channel 1 "\_C01". This is the reason that the name of the main program must not end with "\_C" and a two-digit number. This is monitored by the cycles.

For single-channel systems, cycles do not extend the name for the programs to be generated.

## Note

## G code programs

For G code programs, the programs to be generated, which do not include any path data, are saved in the directory in which the main program is located. In this case, it must be ensured that programs, which already exist in the directory and which have the same name as the programs to be generated, are overwritten.

## 8.3.9 Predrilling contour pocket (CYCLE64)

## Function

In addition to predrilling, the cycle can be used for centering. The centering or predrilling program generated by the cycle is called for this purpose.

If a milling cutter cannot be inserted at the center to remove stock from contour pockets, then it is necessary to predrill first. The number and positions of the required predrilled holes depends on the specific conditions, e.g. type of contour, tool, plane infeed, finishing allowances.

If you mill several pockets and want to avoid unnecessary tool changes, predrill all the pockets first and then remove the stock. In this case, for centering/predrilling, you also have to enter the parameters that appear when you press the "All parameters" softkey. These parameters must correspond to the parameters from the previous stock removal step.

Programming technological functions (cycles)

8.3 Contour milling

## Programming

When programming, proceed as follows:

- 1. Contour pocket 1
- 2. Centering
- 3. Contour pocket 2
- 4. Centering
- 5. Contour pocket 1
- 6. Predrilling
- 7. Contour pocket 2
- 8. Predrilling
- 9. Contour pocket 1
- 10.Stock removal
- 11.Contour pocket 2
- 12.Stock removal

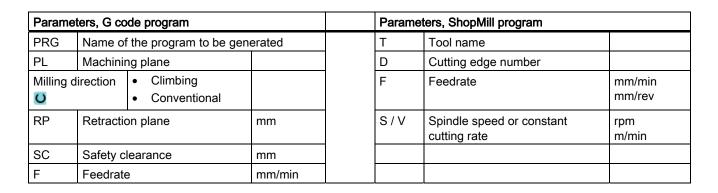
If you are doing all the machining for the pocket at once, i.e. centering, rough-drilling and removing stock directly in sequence, and do not set the additional parameters for centering/rough-drilling, the cycle will take these parameter values from the stock removal (roughing) machining step. When programming in G code, these values must be specifically re-entered.

## Procedure when centering

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- Cont. mill. Rough drill



- created and you are in the editor.
   Press the "Cont. mill.", "Predrilling", and "Centering" softkeys.
  - The "Centering" input window opens.



Parameter	Description	Unit
TR	Reference tool Tool, which is used in the "solid machining" machining step. This is used to determine the plunge position.	
Z0	Reference point Z	mm
Z1 Ŭ	Depth with reference to Z0 (inc.)	mm
DXY O	<ul><li>Maximum plane infeed</li><li>Maximum plane infeed as a percentage of the milling cutter diameter</li></ul>	in %
UXY	Finishing allowance, plane	mm
UZ	Depth finishing allowance - (only for predrilling)	mm
Lift mode	Lift mode before new infeed	
U	If the machining operation requires several points of insertion, the retraction height can be programmed:	
	To retraction plane	mm
	Z0 + safety clearance	mm
	When making the transition to the next insertion point, the tool returns to this height. If there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the lift mode.	

## Predrilling procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



2.

Press the "Cont. mill.", "Predrilling", and "Predrilling" softkeys. The "Predrilling" input window opens.



Rough drill

Param	Parameters, G code program			Parameters, ShopMill program		
PRG	Name of the	ne program to be ge	nerated	Т	Tool name	
PL	Machining	Machining plane		D	Cutting edge number	
Milling	Milling direction <b>O</b> • Climbing • Conventional			F	Feedrate	mm/min mm/rev
RP	Retraction	Retraction plane		S / V	Spindle speed or constant cutting rate	rpm m/min
SC	Safety clea	arance	mm			
F	Feedrate		mm/min			

Parameter	Description	Unit
TR	Reference tool Tool, which is used in the "solid machining" machining step. This is used to determine the plunge position.	
Z0	Reference point Z	mm
Z1 U	Pocket depth (abs) or depth referred to Z0 (inc)	mm
DXY O	<ul><li>Maximum plane infeed</li><li>Maximum plane infeed as a percentage of the milling cutter diameter</li></ul>	in %
UXY	Finishing allowance, plane	mm
UZ	Finishing allowance, depth	mm
Lift mode	Lift mode before new infeed	
U	If the machining operation requires several points of insertion, the retraction height can be programmed:	
	To retraction plane	mm
	Z0 + safety clearance	mm
	When making the transition to the next insertion point, the tool returns to this height. If there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the lift mode.	

#### 8.3.10 Milling contour pocket (CYCLE63)

## Function

Before you can machine a pocket with islands, you must enter the contour of the pocket and islands. The first contour you specify is interpreted as the pocket contour and all the others as islands.

From the programmed contours and the input screen form for stock removal, the cycle generates a program that removes the pockets with islands from inside to outside in parallel to the contour.

The islands can also be located partially outside the pocket or overlap each other.

## Procedure

- 2. Cont. mill.
- 1. The part program or ShopMill program to be processed has been created and you are in the editor. Press the "Contour milling" and "Pocket" softkeys.
- The "Mill pocket" input window opens. Pocket

Parameters, G code program				Parameters, ShopMill program		
PRG	Name of the	Name of the program to be generated		Т	Tool name	
PL	Machining plane			D	Cutting edge number	
Milling direction U		<ul><li>Climbing</li><li>Conventional</li></ul>		F	Feedrate	mm/min mm/rev
RP	Retraction	Retraction plane		S/V	Spindle speed or constant cutting rate	rpm m/min
SC	Safety clearance		mm			
F	Feedrate		mm/min			

Parameter	Description	Unit	
Machining O	<ul> <li>The following machining operations can be selected:</li> <li>∇ (roughing)</li> <li>∇V∇ base (base finishing)</li> <li>∇V∇ edge (edge finishing)</li> <li>Chamfering</li> </ul>		
Z0	Reference point Z	mm	
Z1 💟	Pocket depth (abs) or depth relative to Z0 (inc) - (only for ∇, ∇∇∇ base or ∇∇∇ edge)	mm	
DXY O	<ul> <li>Maximum plane infeed</li> <li>Maximum plane infeed as a percentage of the milling cutter diameter</li> <li>- (only for ∇ or ∇∇∇ base)</li> </ul>	mm %	
DZ	Maximum depth infeed – (only for $\nabla$ or $\nabla\nabla\nabla$ edge)	mm	
UXY	Plane finishing allowance – (only for $\nabla$ , $\nabla\nabla\nabla$ base or $\nabla\nabla\nabla$ edge)	mm	
UZ	Depth finishing allowance – (only for $\nabla$ or $\nabla\nabla\nabla$ base)	mm	
Starting point 🥥	<ul> <li>Manual Starting point is manually entered</li> <li>Automatic Starting point is automatically calculated</li> <li>- (only for ∇ or ∇∇∇ base)</li> </ul>		
XS	Starting point X - (only for "manual" starting point)		
YS	Starting point Y - (only for "manual" starting point)		

Parameter	Description	Unit
Insertion	The following insertion modes can be selected – (only for $\nabla$ or $\nabla\nabla\nabla$ base)	
U	Perpendicular: Insert perpendicular to the center of pocket	
	<ul> <li>The tool executes the calculated actual depth infeed at the pocket center in a single block. This setting can be used only if the cutter can cut across center or if the pocket has been predrilled.</li> <li>Helical: Insert along helical path</li> </ul>	
	<ul> <li>The cutter center point traverses along the helical path determined by the radius and depth per revolution (helical path). If the depth for one infeed has been reached, a full circle motion is executed to eliminate the inclined insertion path.</li> <li>Oscillating: Insert with oscillation along center axis of rectangular pocket</li> </ul>	
	The cutter center point oscillates back and forth along a linear path until it reaches the depth infeed. When the depth has been reached, the path is traversed again without depth infeed in order to eliminate the inclined insertion path.	
FZ <u>(</u> (only for ShopMill)	Depth infeed rate - (only for perpendicular insertion and $ abla$ )	mm/min mm/tooth
FZ (only for G code)	Depth infeed rate - (only for perpendicular insertion and $ abla$ )	mm/min
EP	Maximum pitch of helix – (for helical insertion only)	mm/rev
ER	Radius of helix – (for helical insertion only)	mm
	The radius cannot be any larger than the cutter radius; otherwise, material will remain.	
EW	Maximum insertion angle – (for insertion with oscillation only)	Degrees
Lift mode	Lift mode before new infeed - (only for $\nabla$ , $\nabla\nabla\nabla$ base or $\nabla\nabla\nabla$ edge)	
O	If the machining operation requires several points of insertion, the retraction height can be programmed: • to RP	
	<ul> <li>Z0 + safety clearance</li> </ul>	mm
	When making the transition to the next insertion point, the tool returns to this height. If there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the lift mode.	mm
FS	Chamfer width for chamfering - (only for chamfering machining)	mm
ZFS U	Insertion depth of tool tip (abs or inc) - (for machining only)	mm

#### Note

When input manually, the starting point can also be located outside the pocket. This can be useful, for example, when machining a pocket which is open on one side. The machining operation then begins without insertion with a linear movement into the open side of the pocket.

## 8.3.11 Residual material contour pocket (CYCLE63)

## Function

When you have removed stock from a pocket (with/without islands) and there is residual material, then this is automatically detected. You can use a suitable tool to remove this residual material without having to machine the whole pocket again, i.e. avoiding unnecessary non-productive motion. Material that remains as part of the finishing allowance is not residual material.

The residual material is calculated on the basis of the milling cutter used for stock removal.

If you mill several pockets and want to avoid unnecessary tool changes, remove stock from all the pockets first and then remove the residual material. In this case, for removing the residual material, you also have to enter a value for the reference tool TR parameter, which, for the ShopMill program, additionally appears when you press the "All parameters" softkey. When programming, you must then proceed as follows:

- 1. Contour pocket 1
- 2. Solid machining
- 3. Contour pocket 2
- 4. Solid machining
- 5. Contour pocket 1
- 6. Remove residual material
- 7. Contour pocket 2
- 8. Remove residual material



#### Software option

For solid machining residual material, you require the option "residual material detection and machining".

## Procedure

1. The part program or ShopMill program to be processed has been created and you are in the editor.



Press the "Contour milling" and "Pocket Res. Mat." softkeys.
 The "Pocket Res. Mat." input window opens.



All para-

meters

3. For the ShopMill program, press the "All parameters" softkey if you want to enter additional parameters.

Param	Parameters, G code program				Parameters, ShopMill program		
PRG	Name of the program to be generated			٦	Т	Tool name	
PL	Machining plane			F	F	Feedrate	mm/min mm/rev
Milling	direction U	<ul><li>Climbing</li><li>Conventional</li></ul>		S	S / V	Spindle speed or constant cutting rate	rpm m/min
RP	Retraction	plane	mm				
SC	Safety clearance		mm				
F	Feedrate		mm/min				

Parameter	Description	Unit
Machining	The following machining operations can be selected:	
	∇ (roughing)	
TR	Reference tool Tool, which is used in the "solid machining" machining step. This is used to determine the residual corners.	
D 🚺	Cutting edge number	
Z0	Reference point	mm
Z1 Ŭ	Pocket depth (abs) or depth referred to Z0 (inc)	mm
DXY U	Maximum plane infeed	mm
	Maximum plane infeed as a percentage of the milling cutter diameter	%
DZ	Maximum depth infeed	mm
UXY	Finishing allowance, plane	mm
UZ	Finishing allowance, depth	mm
Lift mode	Lift mode before new infeed	
U	If the machining operation requires several points of insertion, the retraction height can	
	be programmed:	mm
	• to RP	mm
	• Z0 + safety clearance	
	When making the transition to the next insertion point, the tool returns to this height. If there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the lift mode.	

### 8.3.12 Milling contour spigot (CYCLE63)

### Function

You can mill any spigot using the "Mill spigot" cycle.

Before you mill the spigot, you must first enter a blank contour and then one or more spigot contours. The blank contour defines the area, outside of which there is no material, i.e. the tool moves with rapid traverse there. Material is then removed between the blank contour and spigot contour.

### Machining type

You can select the machining mode (roughing, base finishing, edge finishing, chamfer) for milling. If you want to rough and then finish, you have to call the machining cycle twice (Block 1 = roughing, Block 2 = finishing). The programmed parameters are retained when the cycle is called for the second time.

### Approach/retraction

- 1. The tool approaches the starting point in rapid traverse at the height of the retraction plane and goes to the safety clearance. The cycle calculates the starting point.
- 2. The tool first infeeds to the machining depth and then approaches the spigot contour from the side in a quadrant at machining feedrate.
- 3. The spigot is machined in parallel with the contours from the outside in. The direction is determined by the machining direction (climbing or conventional).
- 4. When the first plane of the spigot has been machined, the tool retracts from the contour in a quadrant and then infeeds to the next machining depth.
- 5. The spigot is again approached in a quadrant and machine in parallel with the contours from outside in.
- 6. Steps 4 and 5 are repeated until the programmed spigot depth is reached.
- 7. The tool moves back to the safety clearance in rapid traverse.

### Procedure



- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- Press the "Contour milling" and "Spigot" softkeys.
   The "Mill spigot" input window opens.
  - 3. Select the "Roughing" machining type.

Param	Parameters, G code program				Parameters, ShopMill program		
PRG	Name of the	Name of the program to be generated			Т	Tool name	
PL	Machining plane				F	Feedrate	mm/min mm/rev
Milling	Milling direction () • Climbing • Conventional				D	Cutting edge number	D
RP	Retraction	Retraction plane			F	Feedrate	mm/min mm/rev
SC	Safety clearance		mm		S/V	Spindle speed or constant cutting rate	rpm m/min
F	Feedrate	Feedrate					

Parameter	Description	Unit
Machining	<ul> <li>The following machining operations can be selected:</li> <li>∇ (roughing)</li> <li>∇∇∇ base (base finishing)</li> <li>∇∇∇ edge (edge finishing)</li> <li>Chamfering</li> </ul>	
Z0	Reference point Z	mm
Z1 Ŭ	Pocket depth (abs) or depth relative to Z0 (inc) - (only for ∇, ∇∇∇ base or ∇∇∇ edge)	mm
DXY	Maximum plane infeed	mm
U	<ul> <li>Maximum plane infeed as a percentage of the milling cutter diameter</li> <li>- (only for ∇ and ∇∇∇ base)</li> </ul>	%
DZ	Maximum depth infeed – (only for $\nabla$ or $\nabla\nabla\nabla$ edge)	mm
UXY	Plane finishing allowance – (only for $\nabla$ , $\nabla\nabla\nabla$ base or $\nabla\nabla\nabla$ edge)	mm
UZ	Depth finishing allowance – (only for $\nabla$ or $\nabla\nabla\nabla$ base)	mm
Lift mode	Lift mode before new infeed	
U	If the machining operation requires several points of insertion, the retraction height can be programmed:	
	to RP	mm
	Z0 + safety clearance	mm
	When making the transition to the next insertion point, the tool returns to this height. If there are no elements larger than Z0 (X0) in the pocket area, then Z0 (X0) + safety clearance can be programmed as the lift mode.	mm
FS	Chamfer width for chamfering - (only for chamfering machining)	mm
ZFS 😈	Insertion depth of tool tip (abs or inc) - (for machining only)	mm

### 8.3.13 Residual material contour spigot (CYCLE63)

### Function

When you have milled a contour spigot and residual material remains, then this is automatically detected. You can use a suitable tool to remove this residual material without having to machine the whole spigot again, i.e. avoiding unnecessary non-productive motion. Material that remains as part of the finishing allowance is not residual material.

The residual material is calculated on the basis of the milling cutter used for clearing.

If you mill several spigots and want to avoid unnecessary tool changes, clear all the spigots first and then remove the residual material. In this case, for removing the residual material, you also have to enter a value for the reference tool TR parameter, which, for the ShopMill program, additionally appears when you press the "All parameters" softkey. When programming, you must then proceed as follows:

- 1. Contour blank 1
- 2. Contour spigot 1
- 3. Clear spigot 1
- 4. Contour blank 2
- 5. Contour spigot 2
- 6. Clear spigot 2
- 7. Contour blank 1
- 8. Contour spigot 1
- 9. Clear residual material spigot 1
- 10.Contour blank 2
- 11.Contour spigot 2
- 12.Clear residual material spigot 2



#### Software option

For solid machining residual material, you require the option "residual material detection and machining".

### Procedure



meters

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- 2. Press the "Contour milling" and "Spigot Res. Mat." softkeys. The "Spigot Res. Mat." input window opens.
- 3. For the ShopMill program, press the "All parameters" softkey if you want to enter additional parameters.

Parame	Parameters, G code program				Parameters, ShopMill program		
PRG	Name of the program to be generated				Т	Tool name	
PL	Machining plane				F	Feedrate	mm/min mm/rev
Milling d	Milling direction () • Climbing • Conventional				S / V	Spindle speed or constant cutting rate	rpm m/min
RP	Retraction	plane	mm				
SC	Safety clearance		mm				
F	Feedrate		mm/min				

Parameter	Description	Unit
TR	Reference tool Tool, which is used in the "solid machining" machining step. This is used to determine the residual corners.	
D	Cutting edge number	
Z0	Reference point Z	mm
Z1 Ŭ	Pocket depth (abs) or depth referred to Z0 (inc)	mm
DXY U	<ul><li>Maximum plane infeed</li><li>Maximum plane infeed as a percentage of the milling cutter diameter</li></ul>	mm %
DZ	Maximum depth infeed	mm
Lift mode	Lift mode before new infeed	
U	If the machining operation requires several points of insertion, the retraction height can be programmed:	
	To retraction plane	mm
	Z0 + safety clearance	mm
	When making the transition to the next insertion point, the tool returns to this height. If there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the lift mode.	

# 8.4 Turning - only for G code programs

### 8.4.1 General

In all turning cycles apart from contour turning (CYCLE95), in the combined roughing and finishing mode, when finishing it is possible to reduce the feedrate as a percentage.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

### 8.4.2 Stock removal (CYCLE951)

### Function

You can use the "Stock removal" cycle for longitudinal or transverse stock removal of corners at outer or inner contours.

#### Note

#### Removing stock from corners

For this cycle, the safety clearance is additionally limited using setting data. The lower value is taken for machining.

Please refer to the machine manufacturer's specifications.

### Machining method

Roughing

In roughing applications, paraxial cuts are machined to the finishing allowance that has been programmed. If no finishing allowance has been programmed, the workpiece is roughed down to the final contour.

During roughing, the cycle reduces the programmed infeed depth D if necessary so that it is possible for cuts of an equal size to be made. For example, if the overall infeed depth is 10 and you have specified an infeed depth of 3, this would result in cuts of 3, 3, 3 and 1. The cycle would reduce the infeed depth to 2.5 to create 4 equally sized cuts.

The angle between the contour and the tool cutting edge determines whether the tool rounds the contour at the end of each cut by the infeed depth D, in order to remove residual corners, or is raised immediately. The angle beyond which rounding is performed is stored in a machine data element.



### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

If the tool does not round the corner at the end of the cut, it is raised by the safety distance or a value specified in the machine data at rapid traverse. The cycle always observes the lower value; otherwise, stock removal at inner contours, for example, could cause the contour to be damaged.



### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

• Finishing

Finishing is performed in the same direction as roughing. The cycle automatically selects and deselects tool radius compensation during finishing.

### Procedure

1.	The part program to be executed has been created and you are in the
	editor.

2. Press the "Turning" softkey.



Turning

Press the "Stock removal" softkey.
 The "Stock Removal" input window opens.



4. Select one of the three stock removal cycles via the softkeys: Simple straight stock removal cycle.

The "Stock removal 1" input window opens.

- OR

Straight stock removal cycle with radii or chamfers.

The "Stock removal 2" input window opens.

- OR

Stock removal cycle with oblique lines, radii, or chamfers. The "Stock Removal 3" input window opens.

Parame	Parameters, G code program			
PL	Machining plane			
SC	Safety clearance	mm		
F	Feedrate	mm/min		

### Programming technological functions (cycles)

Parameter	Description	Unit						
Machining								
U	• $\nabla \nabla \nabla$ (finishing)							
Position	Stock removal position:							
O								
	<u></u>							
Machining	Stock removal direction (longitudinal or transverse) in the coordinate system							
direction	Parallel to the Z axis (longitudinal) Parallel to the X axis (transverse)							
O	External Internal External internal							
X0	Reference point in X $\varnothing$ (abs, always diameter)	mm						
Z0	Reference point in Z (abs)	mm						
X1 Ŭ	End point X (abs) or end point X in relation to X0 (inc)							
Z1 Ŭ	End point Z $\varnothing$ (abs) or end point Z in relation to Z0 (inc)							
D	Maximum depth infeed – (not for finishing)	mm						
UX	Finishing allowance in X – (not for finishing)	mm						
UZ	Finishing allowance in Z – (not for finishing)	mm						
FS1FS3 or R1R3	Chamfer width (FS1FS3) or rounding radius (R1R3) - (not for stock removal 1)	mm						
U	<ul> <li>Parameter selection of intermediate point</li> <li>The intermediate point can be determined through position specification or angle.</li> <li>The following combinations are possible - (not for stock removal 1 and 2)</li> <li>XM ZM</li> <li>XM α1</li> <li>XM α2</li> <li>α1 ZM</li> <li>α2 ZM</li> <li>α1 α2</li> </ul>							
XM 🖸	Intermediate point X $\varnothing$ (abs) or intermediate point X in relation to X0 (inc)							
ZMO	Intermediate point Z (abs or inc)							
α1	Angle of the 1st edge	Degrees						
α2	Angle of the 2nd edge	Degrees						

# 8.4.3 Groove (CYCLE930)

### Function

You can use the "Groove" cycle to manufacture symmetrical and asymmetrical grooves on any straight contour elements.

You can machine outer or inner grooves in the longitudinal or transverse directions. Use the "Groove width" and "Groove depth" parameters to determine the shape of the groove. If a groove is wider than the active tool, it is machined in several cuts. The tool is moved by a maximum of 80% of the tool width for each groove.

You can specify a finishing allowance for the groove base and the flanks; roughing is then performed down to this point.

The dwell time between recessing and retraction is stored in a setting data element.



#### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

### Approach/retraction during roughing

Infeed depth D > 0

- 1. The tool first moves to the starting point calculated internally in the cycle at rapid traverse.
- 2. The tool cuts a groove in the center of infeed depth D.
- 3. The tool moves back by D + safety clearance with rapid traverse.
- 4. The tool cuts a groove next to the first groove with infeed depth  $2 \cdot D$ .
- 5. The tool moves back by D + safety clearance with rapid traverse.
- 6. The tool cuts alternating in the first and second groove with the infeed depth 2 · D, until the final depth T1 is reached.

Between the individual grooves, the tool moves back by D + safety clearance with rapid traverse. After the last groove, the tool is retracted at rapid traverse to the safety distance.

 All subsequent groove cuts are made alternating and directly down to the final depth T1. Between the individual grooves, the tool moves back to the safety distance at rapid traverse.

### Approach/retraction during finishing

- 1. The tool first moves to the starting point calculated internally in the cycle at rapid traverse.
- 2. The tool moves at the machining feedrate down one flank and then along the bottom to the center.
- 3. The tool moves back to the safety distance at rapid traverse.
- 4. The tool moves at the machining feedrate along the other flank and then along the bottom to the center.
- 5. The tool moves back to the safety distance at rapid traverse.

# Procedure

	1.	The part program to be executed has been created and you are in the editor.
Jurn- ing	2.	Press the "Turning" softkey.
Groove	3.	Press the "Groove" softkey.
GLOOAG		The "Groove" input window opens.
	4.	Select one of the three groove cycles with the softkey:
		Simple groove cycle
		The "Groove 1" input window opens.
		- OR
M		Groove cycle with inclines, radii, or chamfers.
		The "Groove 2" input window opens.
		- OR
N° P		Groove cycle on an incline with inclines, radii or chamfers.
		The "Groove 3" input window opens.

Parame	Parameters, G code program			
PL	Machining plane			
SC	Safety clearance	mm		
F	Feedrate	mm/min		

Parameters	Description	Unit
Machining	• $\nabla$ (roughing)	
U	• $\nabla \nabla \nabla$ (finishing)	
	• $\nabla$ + $\nabla\nabla\nabla$ (roughing and finishing)	
Position	Groove position/reference point:	
U		
X0	Reference point in X $\varnothing$	mm
Z0	Reference point in Z	mm
B1	Groove width	mm
T1	Groove depth $\varnothing$ (abs) or groove depth referred to X0 (inc)	

Parameters	Description	Unit
α1, α2	Flank angle 1 or flank angle 2 - (only for grooves 2 and 3)	Degrees
	Asymmetric grooves can be described by separate angles. The angles can be between 0 and < $90^{\circ}$ .	
FS1FS4 or R1R4	Chamfer width (FS1FS4) or rounding radius (R1R4) - (only for grooves 2 and 3)	mm
D	• Maximum depth infeed for insertion – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
	• For zero: Insertion in a cut – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	
	D = 0: 1. cut is made directly to final depth T1	
	D > 0: 1st and 2nd cuts are made alternately to infeed depth D, in order to achieve a better chip flow and prevent the tool from breaking, refer to approaching/retraction when roughing.	
	Alternate cutting is not possible if the tool can only reach the groove base at one position.	
UX or U U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
UZ	Finishing allowance in Z – (for UX, only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
N	Number of grooves (N = 165535)	
DP	Distance between grooves (inc)	mm
	DP is not displayed when $N = 1$	

# 8.4.4 Undercut form E and F (CYCLE940)

### Function

You can use the "Undercut form E" or "Undercut form F" cycle to turn form E or F undercuts in accordance with DIN 509.

### Approach/retraction

- 1. The tool first moves to the starting point calculated internally in the cycle at rapid traverse.
- 2. The undercut is made in one cut at the machining feedrate, starting from the flank through to the cross-feed VX.
- 3. The tool moves back to the starting point at rapid traverse.

### Procedure

1. The part program to be executed has been created and you are in the editor.



2. Press the "Turning" softkey.

### Programming technological functions (cycles)

Undercut	3.	Press the "Undercut" softkey. The "Undercut" input window opens.
Undercut form E	4.	Select one of the following undercut cycles via the softkeys: Press the "Undercut form E" softkey. The "Undercut form E (DIN 509)" input window opens.
Undercut form F		- OR Press the "Undercut form F" softkey. The "Undercut form F (DIN 509)" input window opens.

Parameters, G code program (undercut, form E)				
PL Machining plane				
SC	Safety clearance	mm		
F	Feedrate	mm/min		

Parameters	Description	Unit
Position	Form E machining position:	
O	¥≪	
	¥≪	
	2 2 2	
	₩.	
U	Undercut size according to DIN table:	
	E.g.: E1.0 x 0.4 (undercut form E)	
X0	Reference point X Ø	mm
Z0	Reference point Z	mm
X1	Allowance in X $\varnothing$ (abs) or allowance in X (inc)	mm
U		
UX	Cross feed $\varnothing$ (abs) or cross feed (inc)	mm
U		

Parameters, G code program (undercut, form F)						
PL	Machining plane					
SC	Safety clearance	mm				
F	Feedrate	mm/min				

Parameters	Description	Unit
Position	Form F machining position:	
U	Ka	
	<u>5</u>	
	》 》	
	20 <del>1</del>	
U	Undercut size according to DIN table:	
_	e.g.: F0.6 x 0.3 (undercut form F)	
X0	Reference point X Ø	mm
Z0	Reference point Z	mm
X1 Ŭ	Allowance in X $\varnothing$ (abs) or allowance in X (inc)	mm
Z1 Ŭ	Allowance in Z (abs) or allowance in Z (inc) – (for undercut form F only)	mm
VX U	Cross feed $\varnothing$ (abs) or cross feed (inc)	mm

### 8.4.5 Thread undercut (CYCLE940)

#### **Function**

You can use the "Thread undercut DIN" or "Thread undercut" cycle to program thread undercuts to DIN 76 for workpieces with a metric ISO thread, or freely definable thread undercuts.

### Approach/retraction

- 1. The tool first moves to the starting point calculated internally in the cycle at rapid traverse.
- 2. The first cut is made at the machining feedrate, starting from the flank and traveling along the shape of the thread undercut as far as the safety distance.
- 3. The tool moves to the next starting position at rapid traverse.
- 4. Steps 2 and 3 are repeated until the thread undercut is finished.
- 5. The tool moves back to the starting point at rapid traverse.

During finishing, the tool travels as far as cross-feed VX.

### Procedure

	1.	The part program to be executed has been created and you are in the editor.
Jurn- ing	2.	Press the "Turning" softkey.
Undercut	3.	Press the "Undercut" softkey.
Undercut thrd DIN	4.	Press the "Thread undercut DIN" softkey. The "Thread Undercut (DIN 76)" input window opens.
		- OR -
Undercut thread		Press the "Thread undercut" softkey. The "Thread Undercut" input window opens.

Parameters, G code program (undercut, thread DIN)					
PL Machining plane					
SC	Safety clearance	mm			
F	Feedrate	mm/min			

Parameters	Description	Unit
Machining	• $\nabla$ (roughing)	
U	• VVV (finishing)	
	• $\nabla$ + $\nabla\nabla\nabla$ (roughing and finishing)	
Position	Machining position:	
O		
	<u>199</u>	
	2014 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 101 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 -	
	wł.	
Machining	Longitudinal	
direction O	Parallel to the contour	
Form Ŭ	Normal (form A)	
-	Short (form B)	
PU	Thread pitch (select from the preset DIN table or enter)	mm/rev
X0	Reference point X Ø	mm
ZO	Reference point Z	mm
α	Insertion angle	Degrees

# Programming technological functions (cycles)

Parameters	Description	Unit
VX U	Cross feed $\emptyset$ (abs) or cross feed (inc) - (only for $\nabla\nabla\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
D	Maximum depth infeed – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
U or UX U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
UZ	Finishing allowance in Z – (only for UX, $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm

Parame	Parameters, G code program (undercut, thread)			
PL	Machining plane			
SC	Safety clearance	mm		
F	Feedrate	mm/min		

Parameters	Description	Unit
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> <li>∇ + ∇∇∇ (roughing and finishing)</li> </ul>	
Machining direction O	<ul><li>Longitudinal</li><li>Parallel to the contour</li></ul>	
Position O	Machining position:	
X0	Reference point X Ø	mm
Z0	Reference point Z	mm
X1 Ŭ	Undercut depth referred to X $\varnothing$ (abs) or undercut depth referred to X (inc)	
Z1 Ŭ	Allowance Z (abs or inc)	
R1	Rounding radius 1	mm
R2	Rounding radius 2	mm
α	Insertion angle	Degrees
VX 🕐	Cross feed $\emptyset$ (abs) or cross feed (inc) - (only for $\nabla \nabla \nabla$ and $\nabla$ + $\nabla \nabla \nabla$ )	
D	Maximum depth infeed – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
U or UX 😈	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla)$	mm
UZ	Finishing allowance in Z – (only for UZ, $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm

### 8.4.6 Thread turning (CYCLE99)

### Function

You can use the "Longitudinal thread", "Tapered thread" or "Face thread" cycle to turn external or internal threads with a constant or variable pitch.

There may be single or multiple threads.

For metric threads (thread pitch P in mm/rev), the cycle assigns a value (calculated on the basis of the thread pitch) to the thread depth H1 parameter. You can change this value.

The default must be activated via setting data SD 55212 \$SCS\_FUNCTION\_MASK\_TECH\_SET.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

The cycle requires a speed-controlled spindle with a position measuring system.

#### Thread re-machining

You have the option of subsequently machining threads. To do this, change into the "JOG" operating mode and carry out a thread synchronization.

#### Approach/retraction

- 1. The tool moves to the starting point calculated internally in the cycle at rapid traverse.
- 2. Thread with advance:

The tool moves at rapid traverse to the first starting position displaced by the thread advance LW.

Thread with run-in:

The tool moves at rapid traverse to the starting position displaced by the thread run-in LW2.

- 3. The first cut is made with thread pitch P as far as the thread run-out LR.
- 4. Thread with advance:

The tool moves at rapid traverse to the return distance VR and then to the next starting position.

Thread with run-in:

The tool moves at rapid traverse to the return distance VR and then back to the starting position.

- 5. Steps 3 and 4 are repeated until the thread is finished.
- 6. The tool moves back to the retraction plane at rapid traverse.

Thread machining can be stopped at any time with the "Rapid lift" function. It ensures that the tool does not damage the thread when it is raised.

### Procedure for longitudinal thread, tapered thread, or face thread

	1.	The part program to be executed has been created and you are in the editor.
Jurn- ing	2.	Press the "Turning" softkey.
Thursd	3.	Press the "Thread" softkey.
Thread		The "Thread" input window opens.
Thread	4.	Press the "Longitudinal thread" softkey.
long.		The "Longitudinal Thread" input window opens.
		- OR -
Thread		Press the "Tapered thread" softkey.
taper		The "Tapered Thread" input window opens.
		- OR -
Thread		Press the "Face thread" softkey.
face		The "Face Thread" input window opens.

Parameters, G code program (thread, longitudinal)		
PL	Machining plane	
SC	Safety clearance	mm
F	Feedrate	mm/min

Parameters	Description	Unit
Table O	Thread table selection: <ul> <li>without</li> <li>ISO metric</li> <li>Whitworth BSW</li> <li>Whitworth BSP</li> <li>UNC</li> </ul>	
Selection - (not for table "Without")	Data, table value, e.g. M10, M12, M14,	
P O	<ul> <li>Select the thread pitch / turns for table "without" or specify the thread pitch/turns corresponding to the selection in the thread table:</li> <li>Thread pitch in mm/revolution</li> <li>Thread pitch in inch/revolution</li> <li>Thread turns per inch</li> <li>Thread pitch in MODULUS</li> </ul>	mm/rev in/rev turns/" MODULUS

Parameters	Description	Unit
G	Change in thread pitch per revolution - (only for P = mm/rev or in/rev)	
	G = 0: The thread pitch P does not change.	
	G > 0: The thread pitch P increases by the value G per revolution.	
	G < 0: The thread pitch P decreases by the value G per revolution.	
	If the start and end pitch of the thread are known, the pitch change to be programmed can be calculated as follows:	
	$ P_e^2 - P^2 $ G = [mm/rev <sup>2</sup> ] 2 * Z <sub>1</sub>	
	The meanings are as follows:	
	P <sub>e</sub> : End pitch of thread [mm/rev]	
	P: Start pitch of thread [mm/rev]	
	Z <sub>1</sub> : Thread length [mm]	
	A larger pitch results in a larger distance between the thread turns on the workpiece.	
Machining	<ul> <li>∇ (roughing)</li> </ul>	
U	● ∇∇∇ (finishing)	
-	• $\nabla + \nabla \nabla \nabla$ (roughing and finishing)	
Infeed (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	Linear:	
U	Infeed with constant cutting depth	
U III	Degressive:	
	Infeed with constant cutting cross-section	
Thread	Internal thread	
U	External thread	
X0	Reference point X from thread table $\varnothing$ (abs)	mm
Z0	Reference point Z (abs)	mm
Z1 U	End point of the thread (abs) or thread length (inc) Incremental dimensions: The sign is also evaluated.	mm
LW	Thread advance (inc)	mm
O	The starting point for the thread is the reference point (X0, Z0) brought forward by the thread advance W. The thread advance can be used if you wish to begin the individual cuts slightly earlier in order to also produce a precise start of thread.	
or	Thread run-in (inc)	
LW2	The thread run-in can be used if you cannot approach the thread from the side and instead have to insert the tool into the material (e.g. lubrication groove on a	mm
<b>a</b> r	shaft).	
or LW2 = LR	Thread run-in = thread run-out (inc)	mm
LVV2 = LR		mm
LR	Thread run-out (inc)	mm
	The thread run-out can be used if you wish to retract the tool obliquely at the end of the thread (e.g. lubrication groove on a shaft).	
H1	Thread depth from thread table (inc)	mm
DP	Infeed slope as flank (inc) – (alternative to infeed slope as angle)	
U	DP > 0: Infeed along the rear flank	
		1

Parameters	Description		Unit			
αP	Infeed slope as	s angle – (alternative to infeed slope as flank)	Degrees			
	$\alpha$ > 0: Infeed a	$\alpha$ > 0: Infeed along the rear flank				
	α < 0: Infeed a	$\alpha$ < 0: Infeed along the front flank				
	$\alpha$ = 0: Infeed a	t right angle to cutting direction				
		nfeed along the flanks, the maximum absolute value of this / be half the flank angle of the tool.				
V U	Infeed along th	e flank				
**	Infeed with alte	ernating flanks (alternative)				
	always loading the tool life.	t at the rear flank				
D1 or ND 🚺			mm			
(only for $\nabla$ and $\nabla + \nabla \nabla \nabla$ )	The respective	First infeed depth or number of roughing cuts The respective value is displayed when you switch between the number of roughing cuts and the first infeed.				
rev		rance in X and Z – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm			
NN		Number of noncuts - (only for $\nabla\nabla\nabla$ and $\nabla + \nabla\nabla\nabla$ )				
VR		Return distance (inc)				
Multiple threads	No					
U	α0	Starting angle offset				
-	Yes	Yes				
	N	Number of threads The threads are distributed evenly across the periphery of the turned part; the 1st thread is always placed at 0°.				
	DA	Thread changeover depth (inc) First machine all thread turns sequentially to thread changeover depth DA, then machine all thread turns sequentially to depth 2 DA, etc. until the final depth is reached.				
		DA = 0: Thread changeover depth is not taken into account, i.e. finish machining each thread before starting the next thread.				
	Machining:	<ul><li>Complete, or</li><li>from turn N1</li></ul>				
		N1 (14) start thread N1 = 1N <b>○</b> or • only thread NX				
		NX (14) 1 from N threads O				

Param	Parameters, G code program (thread, face)		
PL	Machining plane		
SC	Safety clearance	mm	
F	Feedrate	mm/min	

Parameters	Description	Unit
Р	Thread pitch in mm/revolution	mm/rev
U	Thread pitch in inch/revolution	in/rev
	Thread turns per inch	turns/" MODULUS
	Thread pitch in MODULUS	MODOLOG
G	Change in thread pitch per revolution - (only for P = mm/rev or in/rev)	
	G = 0: The thread pitch P does not change.	
	G > 0: The thread pitch P increases by the value G per revolution.	
	G < 0: The thread pitch P decreases by the value G per revolution.	
	If the start and end pitch of the thread are known, the pitch change to be	
	programmed can be calculated as follows:	
	Pe <sup>2</sup> - P <sup>2</sup>   G =[mm/rev <sup>2</sup> ]	
	2 * Z <sub>1</sub>	
	The meanings are as follows:	
	P <sub>e</sub> : End pitch of thread [mm/rev]	
	P: Start pitch of thread [mm/rev]	
	Z <sub>1</sub> : Thread length [mm]	
	A larger pitch results in a larger distance between the thread turns on the workpiece.	
Machining	∇ (roughing)	
U		
-	• $\nabla + \nabla \nabla \nabla$ (roughing and finishing)	
Infeed (only for $\nabla$ and $\nabla$	Linear:	
+ $\nabla \nabla \nabla$ )	Infeed with constant cutting depth	
C	Degressive:	
	Infeed with constant cutting cross-section	
Thread 🚺	Internal thread	
_	External thread	
X0	Reference point X $\varnothing$ (abs, always diameter)	mm
ZO	Reference point Z (abs)	mm
X1 🖸	End point of the thread $\varnothing$ (abs) or thread length (inc) Incremental dimensions: The sign is also evaluated.	mm
LW	Thread advance (inc)	mm
O	The starting point for the thread is the reference point (X0, Z0) brought forward by the thread advance W. The thread advance can be used if you wish to begin the individual cuts slightly earlier in order to also produce a precise start of thread.	
or	Thread run-in (inc)	
LW2	The thread run-in can be used if you cannot approach the thread from the side	mm
O	and instead have to insert the tool into the material (e.g. lubrication groove on a shaft).	
or	Thread run-in = thread run-out (inc)	
LW2 = LR		mm
U		

Parameters	Description		Unit	
LR	Thread run-out	t (inc)	mm	
	The thread run-out can be used if you wish to retract the tool obliquely at the end			
		e.g. lubrication groove on a shaft).		
H1	Thread depth (	inc)	mm	
DP	Infeed slope as	s flank (inc) – (alternative to infeed slope as angle)		
U	DP > 0: Infeed	along the rear flank		
or	DP < 0: Infeed	DP < 0: Infeed along the front flank		
αP	Infeed slope as	s angle – (alternative to infeed slope as flank)	Degrees	
	α > 0: Infeed a	long the rear flank		
	α < 0: Infeed a	long the front flank		
	$\alpha$ = 0: Infeed a	t right angle to cutting direction		
		nfeed along the flanks, the maximum absolute value of this / be half the flank angle of the tool.		
<b>V</b>	Infeed along th	e flank		
**	Infeed with alte	ernating flanks (alternative)		
U	Instead of infee always loading the tool life.			
	α > 0: Start at t			
	α < 0: Start at t			
D1 or ND 🚺	First infeed de	First infeed depth or number of roughing cuts		
(only for $\nabla$ and $\nabla + \nabla \nabla \nabla$ )	The respective	The respective value is displayed when you switch between the number of roughing cuts and the first infeed.		
rev	Finishing allow	ance in X and Z – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm	
NN	-	icuts - (only for $\nabla\nabla\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )		
VR	Return distanc		mm	
Multiple threads 🕖	Νο			
·····	α0	Starting angle offset		
	Yes			
	N	Number of threads The threads are distributed evenly across the periphery of the turned part; the 1st thread is always placed at 0°.		
	DA	Thread changeover depth (inc) First machine all thread turns sequentially to thread changeover depth DA, then machine all thread turns sequentially to depth 2 DA, etc. until the final depth is reached.		
		DA = 0: Thread changeover depth is not taken into account, i.e. finish machining each thread before starting the next thread.		
	Machining:	<ul> <li>Complete, or</li> <li>from turn N1</li> <li>N1 (1 4) start throad N1 = 1 N (2) or</li> </ul>		
		<ul> <li>N1 (14) start thread N1 = 1N O or</li> <li>only thread NX</li> </ul>		
		NX (14) 1 from N threads 💟		

### Programming technological functions (cycles)

Parameters, G code program (thread, conical)		
PL	Machining plane	
SC	Safety clearance	mm
F	Feedrate	mm/min

Parameters	Description	Unit
Р	Thread pitch in mm/revolution	mm/rev
U	Thread pitch in inch/revolution	in/rev
_	Thread turns per inch	turns/" MODULUS
	Thread pitch in MODULUS	MODOLOG
G	Change in thread pitch per revolution - (only for P = mm/rev or in/rev)	
	G = 0: The thread pitch P does not change.	
	G > 0: The thread pitch P increases by the value G per revolution.	
	G < 0: The thread pitch P decreases by the value G per revolution.	
	If the start and end pitch of the thread are known, the pitch change to be programmed can be calculated as follows:	
	Pe <sup>2</sup> - P <sup>2</sup>	
	G =[mm/rev <sup>2</sup> ]	
	The meanings are as follows:	
	Pe: End pitch of thread [mm/rev]	
	P: Start pitch of thread [mm/rev]	
	Z1: Thread length [mm]	
	A larger pitch results in a larger distance between the thread turns on the workpiece.	
Machining	• $\nabla$ (roughing)	
U	• $\nabla \nabla \nabla$ (finishing)	
	∇ + ∇∇∇ (roughing and finishing)	
Infeed (only for $\nabla$ and $\nabla$	Linear:	
+ $\nabla\nabla\nabla$ )	Infeed with constant cutting depth	
O	Degressive:	
	Infeed with constant cutting cross-section	
Thread	Internal thread	
U	External thread	
X0	Reference point X $\varnothing$ (abs, always diameter)	mm
Z0	Reference point Z (abs)	mm
X1 or	End point X $\varnothing$ (abs) or end point in relation to X0 (inc) or	mm or
Χ1α	Thread taper	degrees
U	Incremental dimensions: The sign is also evaluated.	
Z1 🕖	End point Z (abs) or end point in relation to Z0 (inc) Incremental dimension: The sign is also evaluated.	mm

Parameters	Description	Unit
LW	Thread advance (inc)	mm
U	The starting point for the thread is the reference point (X0, Z0) brought forward by the thread advance W. The thread advance can be used if you wish to begin the individual cuts slightly earlier in order to also produce a precise start of thread.	
or	Thread run-in (inc)	mm
LW2	The thread run-in can be used if you cannot approach the thread from the side and instead have to insert the tool into the material (e.g. lubrication groove on a shaft).	
or	Thread run-in = thread run-out (inc)	mm
or LW2 = LR		
UVZ - LR		
LR	Thread run-out (inc)	mm
	The thread run-out can be used if you wish to retract the tool obliquely at the end of the thread (e.g. lubrication groove on a shaft).	
H1	Thread depth (inc)	mm
DP	Infeed slope as flank (inc) – (alternative to infeed slope as angle)	
U	DP > 0: Infeed along the rear flank	
or	DP < 0: Infeed along the front flank	
αP	Infeed slope as angle – (alternative to infeed slope as flank)	Degrees
	$\alpha$ > 0: Infeed along the rear flank	
	$\alpha$ < 0: Infeed along the front flank	
	$\alpha$ = 0: Infeed at right angle to cutting direction	
	If you wish to infeed along the flanks, the maximum absolute value of this parameter may be half the flank angle of the tool.	
1	Infeed along the flank	
*	Infeed with alternating flanks (alternative)	
U	Instead of infeed along one flank, you can infeed along alternating flanks to avoid always loading the same tool cutting edge. As a consequence you can increase the tool life.	
	$\alpha$ > 0: Start at the rear flank	
	$\alpha$ < 0: Start at the front flank	
D1 or ND 🚺	First infeed depth or number of roughing cuts	mm
(only for $\nabla$ and $\nabla + \nabla \nabla \nabla$ )	The respective value is displayed when you switch between the number of roughing cuts and the first infeed.	
rev	Finishing allowance in X and Z – (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )	mm
NN	Number of noncuts - (only for $\nabla \nabla \nabla$ and $\nabla + \nabla \nabla \nabla$ )	
VR	Return distance (inc)	mm
Multiple threads	No	
U	α0 Starting angle offset	
	Yes	
	N Number of threads The threads are distributed evenly across the periphery of the turned part; the 1st thread is always placed at 0°.	

Parameters	Description		Unit
	DA	Thread changeover depth (inc) First machine all thread turns sequentially to thread changeover depth DA, then machine all thread turns sequentially to depth 2 · DA, etc. until the final depth is reached.	
		DA = 0: Thread changeover depth is not taken into account, i.e. finish machining each thread before starting the next thread.	
	Machining:	<ul><li>Complete, or</li><li>from turn N1</li></ul>	
		N1 (14) start thread N1 = 1N O or • only thread NX	
		NX (14) 1 from N threads 🕖	

### 8.4.7 Thread chain (CYCLE98)

#### Function

With this cycle, you can produce several concatenated cylindrical or tapered threads with a constant pitch in longitudinal and face machining, all of which can have different thread pitches.

There may be single or multiple threads. With multiple threads, the individual thread turns are machined one after the other.

You define a right or left-hand thread by the direction of spindle rotation and the feed direction.

The infeed is performed automatically with a constant infeed depth or constant cutting crosssection.

• With a constant infeed depth, the cutting cross-section increases from cut to cut. The finishing allowance is machined in one cut after roughing.

A constant infeed depth can produce better cutting conditions at small thread depths.

 With a constant cutting cross-section, the cutting pressure remains constant over all roughing cuts and the infeed depth is reduced.

The feedrate override has no effect during traversing blocks with thread. The spindle override must not be changed during the thread machining.

### Approach/retraction

- 1. Approach of the starting point determined in the cycle at the beginning of the run-in path for the first thread with G0.
- 2. Infeed for roughing according to the defined infeed type.
- 3. Thread cutting is repeated according to the programmed number of roughing cuts.

- 4. The finishing allowance is removed in the following step with G33.
- 5. This cut is repeated according to the number of noncuts.
- 6. The whole sequence of motions is repeated for each further thread.

### Procedure for thread chain

	1.	The part program to be executed has been created and you are in the editor.
Jurn- ing	2.	Press the "Turning" softkey.
Thread	3.	Press the "Thread" softkey. The "Thread" input window opens.
Thread chain	4.	Press the "Thread chain" softkey. The "Thread Chain" input window opens.

Parame	Parameters, G code program		
PL	Machining plane		
SC	Safety clearance	mm	
F	Feedrate	mm/min	

Parameters	Description	Unit
Machining	<ul> <li>∇ (roughing)</li> </ul>	
U		
_	• $\nabla + \nabla \nabla \nabla$ (roughing and finishing)	
Infeed (only for $\nabla$ and $\nabla$	Linear:	
$+ \nabla \nabla \nabla$ )	Constant cutting depth infeed	
U	Degressive:	
	Constant cutting cross-section infeed	
Thread	Internal thread	
U	External thread	
X0	Reference point X $\varnothing$ (abs, always diameter)	mm
ZO	Reference point Z (abs)	mm
P0 Ŭ	Thread pitch 1	mm/rev
		in/rev
		turns/" MODULUS
X1 or X1α	● Intermediate point 1 X Ø (abs) or	mm
U	Intermediate point 1 in relation to X0 (inc) or	
	Thread taper 1	Degrees
	Incremental dimensions: The sign is also evaluated.	

Parameters	Description	Unit	
Z1 Ŭ	Intermediate point 1 Z (abs) or		
	Intermediate point 1 in relation to Z0 (inc)		
P1	Thread pitch 2 (unit as parameterized for P0)	mm/rev in/rev turns/" MODULUS	
X2 or X2α	<ul> <li>Intermediate point 2 X Ø (abs) or</li> </ul>	mm	
U	Intermediate point 2 in relation to X1 (inc) or	Degrees	
	Thread taper 2 (abs or inc)	Degrees	
	Incremental dimensions: The sign is also evaluated.		
Z2	Intermediate point 2 Z (abs) or		
U	Intermediate point 2 in relation to Z1 (inc)		
P2	Thread pitch 3 (unit as parameterized for P0)	mm/rev in/rev turns/" MODULUS	
ХЗ 🖸	• End point X $\varnothing$ (abs) or		
	End point 3 in relation to X2 (inc) or		
	Thread taper 3		
Z3 🚺	• End point Z $\varnothing$ (abs) or		
	End point with reference to Z2 (inc)		
LW	Thread run-in		
LR	Thread run-out		
H1	Thread depth		
DP or αP Ŭ	Infeed slope (flank) or infeed slope (angle)		
1	Infeed along a flank		
<b>*</b> *	Infeed with alternating flanks		
U			
D1 or ND Ŭ	First infeed depth or number of roughing cuts - (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )		
rev	Finishing allowance in X and Z - (only for $\nabla$ and $\nabla$ + $\nabla\nabla\nabla$ )		
NN	Number of noncuts - (only for $\nabla \nabla \nabla$ and $\nabla + \nabla \nabla \nabla$ )		
VR	Return distance		
Multiple threads	No		
O	α0 Starting angle offset		
	Yes		
	N Number of threads		
	DA Thread changeover depth (inc)		

### 8.4.8 Cut-off (CYCLE92)

### Function

The "Cut-off" cycle is used when you want to cut off dynamically balanced parts (e.g. screws, bolts, or pipes).

You can program a chamfer or rounding on the edge of the machined part. You can machine at a constant cutting rate V or speed S up to a depth X1, from which point the workpiece is machined at a constant speed. As of depth X1, you can also program a reduced feedrate FR or a reduced speed SR, in order to adapt the velocity to the smaller diameter.

Use parameter X2 to enter the final depth that you wish to reach with the cut-off. With pipes, for example, you do not need to cut-off until you reach the center; cutting off slightly more than the wall thickness of the pipe is sufficient.

### Approach/retraction

- 1. The tool first moves to the starting point calculated internally in the cycle at rapid traverse.
- 2. The chamfer or radius is machined at the machining feedrate.
- 3. Cut-off down to depth X1 is performed at the machining feedrate.
- 4. Cut-off is continued down to depth X2 at reduced feedrate FR and reduced speed SR.
- 5. The tool moves back to the safety distance at rapid traverse.

If your turning machine is appropriately set up, you can extend a workpiece drawer (part catcher) to accept the cut-off workpiece. Extension of the workpiece drawer must be enabled in a machine data element.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

### Procedure

1. The part program to be executed has been created and you are in the editor.



2. Press the "Turning" softkey.



Press the "Cut-off" softkey.
 The "Cut-off" input window opens.

### Programming technological functions (cycles)

Param	Parameters, G code program		
PL	Machining plane		
SC	Safety clearance	mm	
F	Feedrate	mm/min	

Parameters	Description	Unit
DIR 🖸	Direction of spindle rotation	
	$\sim$	
	$\sim$	
SV	Maximum speed limit - (only for constant cutting rate V)	rev/min
X0	Reference point in X $\varnothing$ (abs, always diameter)	mm
Z0	Reference point in Z (abs)	mm
FS or R 🚺	Chamfer width or rounding radius	mm
X1 🖸	Depth for speed reduction $\varnothing$ (abs) or depth for speed reduction in relation to X0 (inc)	mm
FR	Reduced feedrate	in/rev
SR	Reduced speed	rev/min
X2 Ŭ	Final depth $\varnothing$ (abs) or final depth in relation to X1 (inc)	mm

# 8.5 Contour turning - only for G code programs

### 8.5.1 General information

### Function

You can machine simple or complex contours with the "Contour turning" cycle. A contour comprises separate contour elements, whereby at least two and up to 250 elements result in a defined contour.

You can program chamfers, radii, undercuts or tangential transitions between the contour elements.

The integrated contour calculator calculates the intersection points of the individual contour elements taking into account the geometrical relationships, which allows you to enter incompletely dimensioned elements.

When you machine the contour, you can make allowance for a blank contour which must be entered before the finished-part contour. You then choose one of the following machining technologies:

- Stock removal
- Grooving
- Plunge-turning

You can rough, remove residual material and finish for each of the three technologies above.

### Programming

For example, the programming procedure for stock removal is as follows:

#### Note

When programming in the G code, it must be ensured that the contours are located after the end of program identifier!

1. Enter the unmachined-part contour

If, when removing stock along the contour, you want to take into account an unmachined part contour (and no cylinder or no allowance) as unmachined part shape, then you must define the contour of the unmachined part before you define the finished-part contour. Compile the unmachined-part contour step-by-step from various contour elements.

2. Enter finished-part contour

You build up the finished-part contour gradually from a series of different contour elements.

- 3. Contour call
- 4. Stock removal along the contour (roughing)

The contour is machined longitudinally, transversely or parallel to the contour.

5. Remove residual material (roughing)

For G code programming, when removing stock, it must first be decided whether to rough (machine) with residual material detection or not. A suitable tool will allow you to remove this without having to machine the contour again.

6. Stock removal along the contour (finishing)

If you programmed a finishing allowance for roughing, the contour is machined again.

### 8.5.2 Representation of the contour

### G code program

In the editor, the contour is represented in a program section using individual program blocks. If you open an individual block, then the contour is opened.

### Symbolic representation

The individual contour elements are represented by symbols adjacent to the graphics window. They appear in the order in which they were entered.

Contour element	Symbol	Meaning
Starting point	$\oplus$	Starting point of the contour
Straight line up	1	Straight line in 90° grid
Straight line down	Ļ	Straight line in 90° grid
Straight line left	←	Straight line in 90° grid
Straight line right	$\rightarrow$	Straight line in 90° grid
Straight line in any direction	2	Straight line with any gradient
Arc right	$\sim$	Circle
Arc left	<u>^</u>	Circle
Pole	Ľ	Straight diagonal or circle in polar coordinates
Finish contour	END	End of contour definition

The different colors of the symbols indicate their status:

Foreground	Background	Meaning
Black	Blue	Cursor on new element
Black	Orange	Cursor on current element

Foreground	Background	Meaning
Black	White	Normal element
Red	White	Element not currently evaluated (element will only be evaluated when it is selected with the cursor)

### Graphical display

The progress of contour programming is shown in broken-line graphics while the contour elements are being entered.

When the contour element has been created, it can be displayed in different line styles and colors:

- Black: Programmed contour
- Orange: Current contour element
- Green dashed: Alternative element
- Blue dotted: Partially defined element

The scaling of the coordinate system is adjusted automatically to match the complete contour.

The position of the coordinate system is displayed in the graphics window.

### 8.5.3 Creating a new contour

#### Function

For each contour that you want to cut, you must create a new contour.

The first step in creating a contour is to specify a starting point. Enter the contour element. The contour processor then automatically defines the end of the contour.

### Procedure

- 1. The part program to be executed has been created and you are in the editor.
- 2. Press the "Turning" and "Contour turning" softkeys.



New contour  Press the "Contour" and "New contour" softkeys. The "New Contour" input window opens.

4. Enter a name for the new contour. The contour name must be unique.



5.

The input window for the starting point of the contour appears.

Enter the individual contour elements (see Section "Creating contour elements").

Parameter	Description	Unit
Z	Starting point Z (abs)	mm
х	Starting point X Ø (abs)	mm
Additional commands	You can enter additional commands in the form of G code for each contour element. You can enter the additional commands (max. 40 characters) in the extended parameter screens ("All parameters" softkey). The softkey is always available at the starting point, it only has to be pressed when entering additional contour elements.	
	You can program feedrates and M commands, for example, using additional G code commands. However, carefully ensure that the additional commands do not collide with the generated G code of the contour and are compatible with the machining type required. Therefore, do not use any G code commands of group 1 (G0, G1, G2, G3), no coordinates in the plane and no G code commands that have to be programmed in a separate block.	
	The contour is finished in continuous-path mode (G64). As a result, contour transitions such as corners, chamfers or radii may not be machined precisely.	
	If you wish to avoid this, then it is possible to use additional commands when programming.	
	Example: For a contour, first program the straight X parallel and then enter "G9" (non- modal exact stop) for the additional command parameter. Then program the Z-parallel straight line. The corner will be machined exactly, as the feedrate at the end of the X- parallel straight line is briefly zero.	
	Note:	
	The additional commands are only effective for finishing!	

Press the "Accept" softkey.

### 8.5.4 Creating contour elements

### Creating contour elements

After you have created a new contour and specified the starting point, you can define the individual elements that make up the contour.

The following contour elements are available for the definition of a contour:

- Straight vertical line
- Straight horizontal line
- Diagonal line
- Circle/arc

For each contour element, you must parameterize a separate parameter screen. Parameter entry is supported by various help screens that explain the parameters.

If you leave certain fields blank, the cycle assumes that the values are unknown and attempts to calculate them from other parameters.

Conflicts may result if you enter more parameters than are absolutely necessary for a contour. In such a case, try entering less parameters and allowing the cycle to calculate as many parameters as possible.

#### Contour transition elements

As transition element between two contour elements, you can select a radius or a chamfer or, in the case of linear contour elements, an undercut. The transition element is always attached at the end of a contour element. The contour transition element is selected in the parameter screen of the respective contour element.

You can use a contour transition element whenever there is an intersection between two successive elements which can be calculated from the input values. Otherwise you must use the straight/circle contour elements.

#### Additional commands

You can enter additional commands in the form of G code for each contour element. You can enter the additional commands (max. 40 characters) in the extended parameter screens ("All parameters" softkey).

You can program feedrates and M commands, for example, using additional G code commands. However, make sure that the additional commands do not collide with the generated G code of the contour. Therefore, do not use any G code commands of group 1 (G0, G1, G2, G3), no coordinates in the plane and no G code commands that have to be programmed in a separate block.

#### Additional functions

The following additional functions are available for programming a contour:

Tangent to preceding element

You can program the transition to the preceding element as tangent.

• Selecting a dialog box

If two different possible contours result from the parameters entered thus far, one of the options must be selected.

Close contour

From the actual position, you can close the contour with a straight line to the starting point.

### Producing exact contour transitions

The axis moves in the continuous path mode (G64). As a result, contour transitions such as corners, chamfers or radii may not be machined precisely.

If you wish to avoid this, there are two different options when programming. Use the additional programs or program the special feedrate for the transition element.

Additional command

For a contour, first program the vertical straight line and then enter "G9" (non-modal exact stop) for the additional command parameter. Then program the horizontal straight line. The corner will be machined exactly, since the feedrate at the end of the vertical straight line is briefly zero.

• Feedrate, transition element

If you have chosen a chamfer or a radius as the transition element, enter a reduced feedrate in the "FRC" parameter. The slower machining rate means that the transition element is machined more accurately.

### Procedure for entering contour elements

	1.	The part program is opened. Position the cursor at the required input position, this is generally at the physical end of the program after M02 or M30.
	2.	Contour input using contour support:
Cont.	2.1	Press the "Contour turning", "Contour" and "New contour" softkeys.
Contour		
New contour		
Accept	2.2	In the opened input window, enter a name for the contour, e.g. contour_1.
		Press the "Accept" softkey.
Accept	2.3	The input screen to enter the contour opens, in which you initially enter a starting point for the contour. This is marked in the lefthand navigation bar using the "+" symbol.
		Press the "Accept" softkey.
	3.	Enter the individual contour elements of the machining direction.
		Select a contour element via softkey.
←•→		The "Straight (e.g. Z)" input window opens.
		- OR
ŧ		The "Straight (e.g. X)" input window opens.

### Programming technological functions (cycles)

8.5 Contour turning - only for G code programs

		- OR
		The "Straight (e.g. ZX)" input window opens.
		- OR
		The "Circle" input window opens.
	4.	Enter all the data available from the workpiece drawing in the input screen (e.g. length of straight line, target position, transition to next element, angle of lead, etc.).
$\checkmark$	5.	Press the "Accept" softkey.
Accept		The contour element is added to the contour.
Tangent. trans.	6.	When entering data for a contour element, you can program the transition to the preceding element as a tangent.
		Press the "Tangent to prec. elem." softkey. The "tangential" selection appears in the parameter $\alpha 2$ entry field.
	7.	Repeat the procedure until the contour is complete.
	8.	Press the "Accept" softkey.
Accept		The programmed contour is transferred into the process plan (program view).
All para- meters	9.	If you want to display further parameters for certain contour elements, e.g. to enter additional commands, press the "All parameters" softkey.

### Contour element "Straight line e.g. Z"

Parameters	Description	Unit				
Z 🖸	End point Z (a	mm				
α1	Starting angle	Degrees				
α2	Angle to the p	Angle to the preceding element				
Transition to next element O	Type of transit Radius Undercut Chamfer					
Radius	R Transit	on to following element - radius	mm			
Undercut 🧿	Form E	Undercut size O e.g. E1.0x0.4 Undercut size O				
		e.g. F0.6x0.3				
	DIN thread	PThread pitchαInsertion angle	mm/rev Degrees			

Parameters	Desci	Description					
	Threa	d	Z1 Z2 R1 R2 T	Length Z1 Length Z2 Radius R1 Radius R2 Insertion depth	mm mm mm mm mm		
Chamfer	FS	Transitio	on to fo	llowing element - chamfer	mm		
CA	• 1	Grinding allowance O       mm         Image: Continue of Contour       Image: Contour         Image: Contour       Image: Contour         Image: Contour       Image: Contour					
Additional commands	Additi	Additional G code commands					

# Contour element "Straight line e.g. X"

Parameters	Descri	ption		Unit				
XO	End po	pint X $\varnothing$ (a	pr end point X (inc)	mm				
α1	Startin	g angle to	is	Degrees				
α2	Angle	to the pre	g element	Degrees				
Transition to next element <b>O</b>	<ul><li>Rad</li><li>Und</li></ul>	Undercut						
Radius	R	Transitio	n to fo	mm				
Undercut 🕗	Form E			ercut size 💟 E1.0x0.4				
	Form F		Undercut size O e.g. F0.6x0.3					
	DIN thread		Ρ α	Thread pitch Insertion angle	mm/rev Degrees			
	Thread		Z1 Z2 R1 R2 T	Length Z1 Length Z2 Radius R1 Radius R2 Insertion depth	mm mm mm mm mm			
Chamfer	FS	Transitio	n to fo	ollowing element - chamfer	mm			
CA	•							
Additional commands	Additio	Additional G code commands						

8.5 Contour turning - only for G code programs

Parameters	Description				
ZU	End	End point Z (abs or inc)			
XU	End	point X $\varnothing$ (abs) or end point X (inc)	mm		
α1	Start	ing angle to Z axis	Degrees		
α2	Angle	e to the preceding element	Degrees		
Transition to next element O	• R	Type of transition <ul> <li>Radius</li> <li>Chamfer</li> </ul>			
Radius	R	Transition to following element - radius			
Chamfer	FS	Transition to following element - chamfer			
CA		<ul> <li>Grinding allowance O</li> <li>Grinding allowance to right of contour</li> <li>Grinding allowance to left of contour</li> </ul>			
Additional commands	Addit	Additional G code commands			

# Contour element "Straight line e.g. ZX"

# Contour element "Circle"

Parameters	Description	Unit			
Direction of rotation	Clockwise direction of rotation				
O	$\sim$				
	Counterclockwise direction of rotation				
	$\sim$				
ZU	End point Z (abs or inc)	mm			
X O X	End point X $\varnothing$ (abs) or end point X (inc)	mm			
К <mark>О</mark>	Circle center point K (abs or inc)	mm			
C	Circle center point I $\varnothing$ (abs or circle center point I (inc)	mm			
α1	Starting angle to Z axis	Degrees			
β1	End angle to Z axis	Degrees			
β2	Opening angle	Degrees			
Transition to next	Type of transition				
element U	Radius				
	Chamfer				
Radius	R Transition to following element - radius	mm			
Chamfer	FS Transition to following element - chamfer	mm			
CA	Grinding allowance U				
	Grinding allowance to right of contour				
	Grinding allowance to left of contour				
Additional commands	commands Additional G code commands				

# Contour element "End"

The data for the transition at the contour end of the previous contour element is displayed in the "End" parameter screen.

The values cannot be edited.

# 8.5.5 Changing the contour

#### Function

You can change a previously created contour later.

Individual contour elements can be

- added,
- changed,
- inserted or
- deleted.

# Procedure for changing a contour element

- 1. Open the part program to be executed.
- With the cursor, select the program block where you want to change the contour. Open the geometry processor.
   The individual contour elements are listed.
- 3. Position the cursor at the position where a contour element is to be inserted or changed.
- 4. Select the desired contour element with the cursor.
- 5. Enter the parameters in the input screen or delete the element and select a new element.

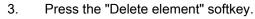


6. Press the "Accept" softkey.

The desired contour element is inserted in the contour or changed.

# Procedure for deleting a contour element

- 1. Open the part program to be executed.
- 2. Position the cursor on the contour element that you want to delete.





Delete

4. Press the "Delete" softkey.

8.5 Contour turning - only for G code programs

# 8.5.6 Contour call (CYCLE62)

## Function

The input creates a reference to the selected contour.

There are four ways to call the contour:

1. Contour name

The contour is in the calling main program.

2. Labels

The contour is in the calling main program and is limited by the labels that have been entered.

3. Subprogram

The contour is located in a subprogram in the same workpiece.

4. Labels in the subprogram

The contour is in a subprogram and is limited by the labels that have been entered.

Procedure

- 1. The part program to be executed has been created and you are in the editor.
- 2. Press the "Turning" and "Contour turning" softkeys.



Contour

Contour call

- Press the "Contour" and "Contour call" softkeys.
   The "Contour Call" input window opens.
- 4. Assign parameters to the contour selection.

Parameter	Description	
Contour selection	<ul> <li>Contour name</li> <li>Labels</li> <li>Subprogram</li> <li>Labels in the subprogram</li> </ul>	
Contour name	CON: Contour name	
Labels	LAB1: Label 1     LAB2: Label 2	

Parameter	Description	
Subprogram	PRG: Subprogram	
Labels in the subprogram	<ul> <li>PRG: Subprogram</li> <li>LAB1: Label 1</li> <li>LAB2: Label 2</li> </ul>	

# 8.5.7 Stock removal (CYCLE952)

#### Function

For stock removal, the cycle takes into account a blank that can comprise a cylinder, an allowance on the finished-part contour or any unmachined-part contour. You must define an unmachined-part contour as a separate closed contour in advance of the finished-part contour.

#### Rounding the contour

In order to avoid residual corners during roughing, you can enable the "Always round the contour" function. This will remove the protrusions that are always left at the end with each cut (due to the cut geometry). The "Round to the previous intersection" setting accelerates machining of the contour. However, any resulting residual corners will not be recognized or machined. Thus, it is imperative that you check the behavior before machining using the simulation.

When set to "automatic", rounding is always performed if the angle between the cutting edge and the contour exceeds a certain value. The angle is set in a machine data element.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Alternating cutting depth

Instead of working with constant cutting depth D, you can use an alternating cutting depth to vary the load on the tool edge, As a consequence you can increase the tool life.

The percentage for the alternating cutting depth is saved in a machine data element.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Cut segmentation

To avoid the occurrence of very thin cuts in cut segmentation due to contour edges, you can align the cut segmentation to the contour edges. During machining the contour is then divided by the edges into individual sections and cut segmentation is performed separately for each section.

#### Set machining area limits

If, for example, you want to machine a certain area of the contour with a different tool, you can set machining area limits so that machining only takes place in the area of the contour you have selected. You can define between 1 and 4 limit lines.

#### Feedrate interruption

To prevent the occurrence of excessively long chips during machining, you can program a feedrate interruption. Parameter DI specifies the distance after which the feedrate interruption should occur.

#### Name convention

For multi-channel systems, cycles attach a "\_C" and a two-digit number of the specific channel to the names of the programs to be generated, e.g. for channel 1 "\_C01".

This is the reason that the name of the main program must not end with "\_C" and a two-digit number. This is monitored by the cycles.

For G code programs with residual machining, when specifying the name for the file, which includes the updated blank contour, it must be ensured that this does not have the attached characters ("\_C" and double-digit number).

For single-channel systems, cycles do not extend the name for the programs to be generated.

#### Note

#### G code programs

For G code programs, the programs to be generated, which do not include any path data, are saved in the directory in which the main program is located. In this case, it must be ensured that programs, which already exist in the directory and which have the same name as the programs to be generated, are overwritten.

## Machining type

You can select the machining mode (roughing or finishing). During contour roughing, parallel cuts of maximum programmed infeed depth are created. Roughing is performed to the programmed allowance.

You can also specify a compensation allowance U1 for finishing operations, which allows you to either finish several times (positive allowance) or to shrink the contour (negative allowance). Finishing is performed in the same direction as roughing.

#### Procedure

1. The part program to be executed has been created and you are in the editor.



3.

2. Press the "Turning" and "Contour turning" softkeys.

Press the "Stock removal" softkey. The "Stock Removal" input window opens.

Parameter	Parameters, G code program		
PRG	Name of the program to be generated		
PL	Machining plane		
RP	Retraction plane	mm	
SC	Safety clearance	mm	
F	Feedrate	mm/min	
Residual	With subsequent residual material removal		
material	• Yes		
0	• No		
CONR	Name to save the updated ur contour for residual material		

Parameters	Description	Unit
Machining	∇ (roughing)	
O	• $\nabla \nabla \nabla$ (finishing)	
Machining	Face U     From inside to outside	
direction	Longitudinal O	
U	Parallel to the contour	
	From outside to inside	
	Ţ	
	<ul> <li>From end face to rear side</li> </ul>	
	<b>←</b>	
	From rear side to end face	
	$\rightarrow$	
	The machining direction depends on the stock removal direction and choice of tool.	
Position	• front	
O	<ul> <li>back</li> <li>internal</li> </ul>	
	external	
D		
D	Maximum depth infeed - (only for $\nabla$ )	mm
DX	Maximum depth infeed - (only for parallel to the contour, as an alternative to D)	mm
	Do not round contour at end of cut. Always round contour at end of cut.	
lt_		
U		
	Uniform cut segmentation	
Ľ.	Round cut segmentation at the edge	
'\$∓ '\$∓		
_		
0	Constant cutting depth	
Ħ	Alternating cutting depth - (only with align cut segmentation to edge)	
Ħ		
DZ	Maximum depth infeed - (only for position parallel to the contour and UX)	mm
UX or U U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ )	mm
UZ	Finishing allowance in Z – (only for UX)	mm
DI	For zero: Continuous cut - (only for $\nabla$ )	mm
BL 🖸	Description of unmachined part	
	Cylinder	
	Allowance	
	Contour	

8.5 Contour turning - only for G code programs

Parameters	Description	Unit
XD	<ul> <li>(only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder <ul> <li>Allowance or cylinder dimension Ø (abs)</li> <li>Allowance or cylinder dimension (inc)</li> </ul> </li> <li>For unmachined part description, allowance <ul> <li>Allowance on the contour Ø (abs)</li> <li>Allowance on the contour (inc)</li> </ul> </li> </ul>	mm
ZD	<ul> <li>(only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder</li> <li>Allowance or cylinder dimension (abs or inc)</li> <li>For unmachined part description, allowance</li> <li>Allowance on the contour (abs or inc)</li> </ul>	mm
Allowance 🔾	<ul> <li>Allowance for pre-finishing - (only for ∇∇∇)</li> <li>Yes <ul> <li>U1 contour allowance</li> <li>No</li> </ul> </li> </ul>	
U1	<ul> <li>Compensation allowance in X and Z direction (inc) – (only for allowance)</li> <li>Positive value: Compensation allowance is kept</li> <li>Negative value: Compensation allowance is removed in addition to finishing allowance</li> </ul>	mm
Set machining area limits O	<ul> <li>Set machining area limits</li> <li>Yes <ul> <li>XA: 1st limit XA Ø</li> <li>XB: <b>○</b> 2nd limit XB Ø (abs) or 2nd limit referred to XA (inc)</li> <li>ZA: 1st limit ZA</li> <li>ZB: <b>○</b> 2nd limit ZB (abs) or 2nd limit referred to ZA</li> </ul> </li> <li>No</li> </ul>	
Relief cuts U	Machine relief cuts <ul> <li>Yes</li> <li>No</li> </ul>	
FR	Insertion feedrate, relief cuts	

# 8.5.8 Stock removal residual (CYCLE952)

# Function

Using the "Stock removal residual" function, you can remove material that has remained for stock removal along the contour.

During stock removal along the contour, the cycle automatically detects any residual material and generates an updated blank contour. For a G code program, for stock removal residual material, "Yes" must be programmed. Material that remains as part of the finishing allowance is not residual material. Using the "Stock removal residual material" function, you can remove unwanted material with a suitable tool.

The "Stock removal residual material" function is a software option.

# Procedure



- 1. The part program to be executed has been created and you are in the editor.
- 2. Press the "Turning" and "Contour turning" softkeys.
- 3. Press the "Stock removal residual material" softkey. The "Stock removal residual material" input window opens.

Parameter	Parameters, G code program		
PRG	Name of the program to be generated		
PL	Machining plane		
RP	Retraction plane	mm	
SC	Safety clearance	mm	
F	Feedrate	mm/min	
Residual	With subsequent residual material removal		
material	• Yes		
O	• No		
CONR	Name to save the updated contour for residual mater		

Parameters	Description					
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> </ul>					
Machining direction	<ul> <li>Face O</li> <li>Longitudinal O</li> <li>Parallel to the contour</li> <li>From end face to rear side</li> <li>From rear side to end face</li> </ul>					
	The machining direction depends on the stock removal direction and choice of tool.					
Position	<ul> <li>front</li> <li>back</li> <li>internal</li> <li>external</li> </ul>					
D	Maximum depth infeed - (only for $\nabla$ )	mm				
XDA	1st grooving limit tool (abs) – (only for face machining direction)	mm				
XDB	2nd grooving limit tool (abs) – (only for face machining direction)	mm				
DX	Maximum depth infeed - (only for parallel to the contour, as an alternative to D)	mm				
U	Do not round contour at end of cut. Always round contour at end of cut.					
U	Uniform cut segmentation Round cut segmentation at the edge					
O	Constant cutting depth Alternating cutting depth - (only with align cut segmentation to edge)					
Allowance 😈	<ul> <li>Allowance for pre-finishing - (only for ∇∇∇)</li> <li>Yes</li> <li>U1 contour allowance</li> <li>No</li> </ul>					
U1	<ul> <li>Compensation allowance in X and Z direction (inc) – (only for allowance)</li> <li>Positive value: Compensation allowance is kept</li> <li>Negative value: Compensation allowance is removed in addition to finishing allowance</li> </ul>					
Set machining area limits O	<ul> <li>Set machining area limits</li> <li>Yes <ul> <li>XA: 1st limit XA Ø</li> <li>XB: Q 2nd limit XB Ø (abs) or 2nd limit referred to XA (inc)</li> <li>ZA: 1st limit ZA</li> <li>ZB: Q 2nd limit ZB (abs) or 2nd limit referred to ZA</li> </ul> </li> <li>No</li> </ul>					
Relief cuts U	Machine relief cuts <ul> <li>Yes</li> <li>No</li> </ul>					
FR	Insertion feedrate, relief cuts					

8.5 Contour turning - only for G code programs

# 8.5.9 Grooving (CYCLE952)

#### Function

The "Grooving" function is used to machine grooves of any shape.

Before you program the groove, you must define the groove contour.

If a groove is wider than the active tool, it is machined in several cuts. The tool is moved by a maximum of 80% of the tool width for each groove.

#### Blank

When grooving, the cycle takes into account a blank that can consist of a cylinder, an allowance on the finished-part contour or any other blank contour.

#### Set machining area limits

If, for example, you want to machine a certain area of the contour with a different tool, you can set machining area limits so that machining only takes place in the area of the contour you have selected.

#### Feedrate interruption

To prevent the occurrence of excessively long chips during machining, you can program a feedrate interruption.

#### Machining type

You can freely select the machining type (roughing or finishing).

For more detailed information, please refer to section "Stock removal".

#### Procedure

1. The part program to be executed has been created and you are in the editor.



- 2. Press the "Turning" and "Contour turning" softkeys.
- Press the "Grooving" softkey.
   The "Grooving" input window opens.

Parameter	rs, G code program		
PRG	Name of the program to be g	enerated	
PL	Machining plane		
RP	Retraction plane - (only for machining direction, longitudinal, internal)	mm	
SC	Safety clearance	mm	
F	Feedrate	mm/min	
Residual material	With subsequent residual ma • Yes • No	aterial removal	
CONR	Name to save the updated un contour for residual material "Yes" for residual material re	removal - (only	

Parameters	Description	Unit
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> </ul>	
Machining direction	<ul><li>Face</li><li>Longitudinal</li></ul>	
Position	<ul> <li>front</li> <li>back</li> <li>internal</li> <li>external</li> </ul>	
D	Maximum depth infeed - (only for $\nabla$ )	mm
XDA	1st grooving limit tool (abs) – (only for face machining direction)	mm
XDB	2nd grooving limit tool (abs) – (only for face machining direction)	mm
UX or U U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ )	mm
UZ	Finishing allowance in Z – (only for UX)	mm
DI	For zero: Continuous cut - (only for $\nabla$ )	mm
BL 💟	Description of unmachined part <ul> <li>Cylinder</li> <li>Allowance</li> <li>Contour</li> </ul>	
XD	<ul> <li>Contour</li> <li>(only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder         <ul> <li>Allowance or cylinder dimension Ø (abs)</li> <li>Allowance or cylinder dimension (inc)</li> </ul> </li> <li>For unmachined part description, allowance         <ul> <li>Allowance on the contour Ø (abs)</li> <li>Allowance on the contour (inc)</li> </ul> </li> </ul>	

8.5 Contour turning - only for G code programs

Parameters	arameters Description		
ZD	<ul><li> (only for unmachined part description, cylinder and allowance)</li><li> For unmachined part description, cylinder</li></ul>	mm	
	<ul><li>Allowance or cylinder dimension (abs or inc)</li><li>For unmachined part description, allowance</li></ul>		
	Allowance on the contour (abs or inc)		
Allowance U	<ul> <li>Allowance for pre-finishing - (only for ∇∇∇)</li> <li>Yes <ul> <li>U1 contour allowance</li> <li>No</li> </ul> </li> </ul>	mm	
U1	<ul> <li>Compensation allowance in X and Z direction (inc) – (only for allowance)</li> <li>Positive value: Compensation allowance is kept</li> <li>Negative value: Compensation allowance is removed in addition to finishing allowance</li> </ul>	mm	
Set machining area limits O	<ul> <li>Set machining area limits</li> <li>Yes <ul> <li>XA: 1st limit XA Ø</li> <li>XB: ○ 2nd limit XB Ø (abs) or 2nd limit referred to XA (inc)</li> <li>ZA: 1st limit ZA</li> <li>ZB: ○ 2nd limit ZB (abs) or 2nd limit referred to ZA</li> </ul> </li> <li>No</li> </ul>		
N	Number of grooves		
DP	Distance between grooves (inc)	mm	

# 8.5.10 Grooving residual material (CYCLE952)

#### Function

The "Grooving residual material" function is used when you want to machine the material that remained after grooving along the contour.

For a G code program, first select the "Grooving residual material" function. Material that remains as part of the finishing allowance is not residual material. The "Grooving residual material" function allows you to remove unwanted material with a suitable tool.

The "Grooving residual material" function is a software option.

# Procedure

1. The part program to be executed has been created and you are in the editor.



- 2. Press the "Turning" and "Contour turning" softkeys.
- Press the "Grooving residual material" softkey.
   The "Grooving residual material" input window is opened.

Parameter	Parameters, G code program			
PRG	Name of the program to be generated			
PL	PL Machining plane			
RP	Retraction plane - (only for longitudinal machining direction)	mm		
SC	Safety clearance	mm		
F	Feedrate	mm/min		
Residual	With subsequent residual material removal			
material	• Yes			
C	• No			
CONR	Name to save the updated unmachined-part contour for residual material removal - (only "Yes" for residual material removal)			

Parameters	Description	Unit
Machining	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> </ul>	
Machining direction	<ul><li>Face</li><li>Longitudinal</li></ul>	
Position	<ul> <li>front</li> <li>back</li> <li>internal</li> <li>external</li> </ul>	
D	Maximum depth infeed - (only for $\nabla$ )	mm
XDA	1st grooving limit tool (abs) – (only for face machining direction)	mm
XDB	2nd grooving limit tool (abs) – (only for face machining direction)	
UX or U U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ )	
UZ	Finishing allowance in Z – (only for UX)	mm
DI	For zero: Continuous cut - (only for $\nabla$ )	mm

8.5 Contour turning - only for G code programs

Parameters	Description	Unit
Allowance O	<ul> <li>Allowance for pre-finishing - (only for ∇∇∇)</li> <li>Yes <ul> <li>U1 contour allowance</li> <li>No</li> </ul> </li> </ul>	mm
U1	<ul> <li>Compensation allowance in X and Z direction (inc) – (only for allowance)</li> <li>Positive value: Compensation allowance is kept</li> <li>Negative value: Compensation allowance is removed in addition to finishing allowance</li> </ul>	mm
Set machining area limits O	<ul> <li>Set machining area limits</li> <li>Yes <ul> <li>XA: 1st limit XA Ø</li> <li>XB: ○ 2nd limit XB Ø (abs) or 2nd limit referred to XB (inc)</li> <li>ZA: 1st limit ZA</li> <li>ZB: ○ 2nd limit ZB (abs) or 2nd limit referred to ZB</li> </ul> </li> <li>No</li> </ul>	
Ν	Number of grooves	
DP	Distance between grooves (inc)	mm

# 8.5.11 Plunge turning (CYCLE952)

#### Function

Using the "Plunge turning" function, you can machine any shape of groove.

Contrary to grooving, the plunge turning function removes material on the sides after the groove has been machined in order to reduce machining time. Contrary to stock removal, the plunge turning function allows you to machine contours that the tool must enter vertically.

You will need a special tool for plunge turning. Before you program the "Plunge turning" cycle, you must define the contour.

#### Set machining area limits

If, for example, you want to machine a certain area of the contour with a different tool, you can set machining area limits so that machining only takes place in the area of the contour you have selected.

#### Feedrate interruption

To prevent the occurrence of excessively long chips during machining, you can program a feedrate interruption.

8.5 Contour turning - only for G code programs

# Machining type

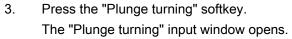
You can freely select the machining type (roughing or finishing). For more detailed information, please refer to section "Stock removal".

# Procedure

1. The part program to be executed has been created and you are in the editor.



2. Press the "Turning" and "Contour turning" softkeys.



Parameter	Parameters, G code program		
PRG	Name of the program to be generated		
PL	Machining plane		
RP	Retraction plane - (only for longitudinal machining direction)	mm	
SC	Safety clearance	mm	
F	Feedrate	mm/min	
Residual material			
U	• No		
CONR	Name to save the updated ur contour for residual material r "Yes" for residual material rer	emoval - (only	

Parameters	Description	Unit
FX	Feedrate in X direction	mm/rev
FZ	Feedrate in Z direction	mm/rev
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> </ul>	
Machining direction	<ul><li>Face</li><li>Longitudinal</li></ul>	
Position O	<ul> <li>front</li> <li>back</li> <li>internal</li> <li>external</li> </ul>	
D	Maximum depth infeed - (only for $\nabla$ )	mm

8.5 Contour turning - only for G code programs

Parameters	Description	Unit			
XDA	1st grooving limit tool (abs) – (only for face machining direction)	mm			
XDB	2nd grooving limit tool (abs) – (only for face machining direction)	mm			
UX or U U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ )	mm			
UZ	Finishing allowance in Z – (only for UX)				
DI	For zero: Continuous cut - (only for ∇)	mm			
BL Ŭ	<ul> <li>Description of unmachined part</li> <li>Cylinder</li> <li>Allowance</li> <li>Contour</li> </ul>				
XD U	<ul> <li>(only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder <ul> <li>Allowance or cylinder dimension Ø (abs)</li> <li>Allowance or cylinder dimension (inc)</li> </ul> </li> <li>For unmachined part description, allowance <ul> <li>Allowance on the contour Ø (abs)</li> <li>Allowance on the contour (inc)</li> </ul> </li> </ul>	mm			
ZD 😈	<ul> <li>- (only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder Allowance or cylinder dimension (abs or inc)</li> <li>For unmachined part description, allowance Allowance on the contour (abs or inc)</li> </ul>	mm			
Allowance 😈	<ul> <li>Allowance for pre-finishing - (only for ∇∇∇)</li> <li>Yes</li> <li>U1 contour allowance</li> <li>No</li> </ul>	mm			
U1	<ul> <li>Compensation allowance in X and Z direction (inc) – (only for allowance)</li> <li>Positive value: Compensation allowance is kept</li> <li>Negative value: Compensation allowance is removed in addition to finishing allowance</li> </ul>	mm			
Set machining area limits O	<ul> <li>Set machining area limits</li> <li>Yes <ul> <li>XA: 1st limit XA Ø</li> <li>XB: 2nd limit XB Ø (abs) or 2nd limit referred to XB (inc)</li> <li>ZA: 1st limit ZA</li> <li>ZB: 2nd limit ZB (abs) or 2nd limit referred to ZB</li> </ul> </li> <li>No</li> </ul>				
Ν	Number of grooves				
DP	Distance between grooves	mm			

# 8.5.12 Plunge turning residual material (CYCLE952)

# Function

The "Plunge turning residual material" function is used when you want to machine the material that remained after plunge turning.

For a G code program, select the function in the screen. Material that remains as part of the finishing allowance is not residual material. The "Plunge turning residual material" function allows you to remove unwanted material with a suitable tool.

The "Plunge turning residual material" function is a software option.

#### Procedure



- 1. The part program to be executed has been created and you are in the editor.
- 2. Press the "Turning" and "Contour turning" softkeys.
- Press the "Plunge turning residual material" softkey.
   The "Plunge turning residual material" input window opens.

Parameter	rs, G code program		
PRG	Name of the program to be generated		
PL	Machining plane		
RP	Retraction plane - (only for longitudinal machining direction)	mm	
SC	Safety clearance	mm	
F	Feedrate	mm/min	
Residual material	With subsequent residual ma • Yes • No	iterial removal	
CONR	Name to save the updated unmachined-part contour for residual material removal - (only "Yes" for residual material removal)		

Parameters	Description	Unit
FX	Feedrate in X direction m	
FZ	Z Feedrate in Z direction	
Machining O	<ul> <li>∇ (roughing)</li> <li>∇∇∇ (finishing)</li> </ul>	

Parameters	Description	Unit
Machining direction	<ul><li>Face</li><li>Longitudinal</li></ul>	
Position O	<ul> <li>front</li> <li>back</li> <li>internal</li> <li>external</li> </ul>	
D	Maximum depth infeed - (only for $\nabla$ )	mm
UX or U U	Finishing allowance in X or finishing allowance in X and Z – (only for $\nabla$ )	mm
UZ	Finishing allowance in Z – (only for UX)	mm
XDA	1st grooving limit tool $\varnothing$ (abs) – (end face or rear face only)	mm
XDB Allowance O	2nd grooving limit tool Ø (abs) – (end face or rear face only)         Allowance for prefinishing         • Yes         U1 contour allowance         • No	mm
DI	For zero: Continuous cut - (only for $\nabla$ )	mm
XD	<ul> <li>(only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder <ul> <li>Allowance or cylinder dimension Ø (abs)</li> <li>Allowance or cylinder dimension (inc)</li> </ul> </li> <li>For unmachined part description, allowance <ul> <li>Allowance on the contour Ø (abs)</li> <li>Allowance on the contour (inc)</li> </ul> </li> </ul>	mm
ZD	<ul> <li>(only for unmachined part description, cylinder and allowance)</li> <li>For unmachined part description, cylinder</li> <li>Allowance or cylinder dimension (abs or inc)</li> <li>For unmachined part description, allowance</li> <li>Allowance on the contour (abs or inc)</li> </ul>	mm
U1	<ul> <li>Compensation allowance in X and Z direction (inc) – (only for allowance)</li> <li>Positive value: Compensation allowance is kept</li> <li>Negative value: Compensation allowance is removed in addition to finishing allowance</li> </ul>	mm
Set machining area limits U	<ul> <li>Set machining area limits</li> <li>Yes <ul> <li>XA: 1st limit XA Ø</li> <li>XB: 2nd limit XB Ø (abs) or 2nd limit referred to XB (inc)</li> <li>ZA: 1st limit ZA</li> <li>ZB: 2nd limit ZB (abs) or 2nd limit referred to ZB</li> </ul> </li> <li>No</li> </ul>	
N	Number of grooves	
DP	Distance between grooves (inc)	mm

# 8.6 Further cycles and functions

# 8.6.1 Swiveling plane/tool (CYCLE800)

The CYCLE800 swivel cycle is used to swivel to any surface in order to either machine or measure it. In this cycle, the active workpiece zeros and the work offsets are converted to the inclined surface taking into account the kinematic chain of the machine by calling the appropriate NC functions - and rotary axes (optionally) are positioned.

Swiveling can be realized:

- axis by axis
- via solid angle
- via projection angle
- directly

Before the rotary axes are positioned, the linear axes can be retracted if desired.

Swiveling always means three geometry axes.

In the basic version, the following functions

- 3 + 2 axes, inclined machining and
- toolholder with orientation capability

are available.

#### Setting/aligning tools for a G code program

The swivel function also includes the "Setting tool" and "Aligning milling tool" functions. Contrary to swiveling, when setting and aligning, the coordinate system (WCS) is not rotated at the same time.

# Prerequisites before calling the swivel cycle

A tool (tool cutting edge D > 0) and the work offset (WO), with which the workpiece was scratched or measured, must be programmed before the swivel cycle is first called in the main program.

#### Example:

N1 N2	T1D1 M6	
	G17 G54	
N4	CYCLE800(1,"",0,57,0,0,0,0,0,0,0,0,0,0,1,0,1))	;swivel ZERO to ;initial position of the ;machine kinematics
N5	WORKPIECE(,,,,"BOX",0,0,50,0,0,0,100,100)	;blank agreement for ;simulation and ;recording
_		

For machines where swivel is set-up, each main program with a swivel should start in the basic setting of the machine.

The definition of the blank (WORKPIECE) always refers to the currently effective work offset. For programs that use "swivel", a swivel to zero must be made before the blank is defined. For ShopMill programs, the blank in the program header is automatically referred to the unswiveled state.

In the swivel cycle, the work offset (WO) as well as the shifts and rotations of the parameters of the CYCLE800 are converted to the corresponding machining plane. The work offset is kept. Shifts and rotations are saved in system frames - the swivel frames - (displayed under parameter/work offsets):

- Tool reference (\$P\_TOOLFRAME)
- Rotary table reference (\$P\_PARTFRAME)
- Workpiece reference (\$P\_WPFRAME)

The swivel cycle takes into account the actual machining plane (G17, G18, G19).

Swiveling on a machining or auxiliary surface always involves 3 steps:

- Shifting the WCS before rotation
- Rotating the WCS (axis-by-axis, ...)
- Shifting the WCS after rotation

# The shifts and rotations refer to the coordinate system X, Y, Z of the workpiece and are therefore independent of the machine (with the exception of swivel "rotary axis direct").

No programmable frames are used in the swivel cycle. The frames programmed by the user are taken into account for additive swiveling.

On the other hand, when swiveling to a new swivel plane the programmable frames are deleted. Any type of machining operation can be performed on the swivel plane, e.g. by calling standard or measuring cycles.

The last swivel plane remains active after a program reset or when the power fails. The behavior at reset and power on can be set using machine data.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Block search when swiveling the plane / swiveling the tool

For block search with calculation, after NC start, initially, the automatic rotary axes of the active swivel data set are pre-positioned and then the remaining machine axes are positioned. This does not apply if a type TRACYL or TRANSMIT transformation is active after the block search. In this case, all axes simultaneously move to the accumulated positions.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Aligning tools

In contrast to "Swivel plane", no rotation is operative in the active frame chain (WCS) in the case of "Swivel tool" or "Align milling tool". Only the offsets calculated by the NC and the corresponding tool orientation are effective.

The maximum angular range for "Align milling tool" is limited by the traversing range of the participating rotary axes.

#### Name of the swivel data set

Selecting the swivel data set or deselecting the swivel data set.

The selection can be hidden by the machine data.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Approaching a machining operation

When approaching the programmed machining operation in the swiveled plane, under worst case conditions, the software limit switches could be violated. In this case, the system travels along the software limit switches above the retraction plane. In the event of violation below the retraction plane, for safety reasons, the program is interrupted with an alarm. To avoid this, before swiveling, e.g. move the tool in the X/Y plane and position it as close as possible to the starting point of the machining operation or define the retraction plane closer to the workpiece.

#### Retraction

Before swiveling the axes you can move the tool to a safe retraction position. The retraction versions available are defined when starting up the system (commissioning).

The retraction mode is modal. When a tool is changed or after a block search, the retraction mode last set is used.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# 

#### **Risk of collision**

You must select a retraction position that avoids a collision between the tool and workpiece when swiveling.

## Swivel plane (only for G code programming)

New

Previous swivel frames and programmed frames are deleted and a new swivel frame is formed according to the values specified in the input screen.

Every main program must begin with a swivel cycle with the new swivel plane, in order to ensure that a swivel frame from another program is not active.

• Additive

The swivel frame is added to the swivel frame from the last swivel cycle.

If several swivel cycles are programmed in a program and programmable frames are also active between them (e.g., AROT ATRANS), these are taken into account in the swivel frame.

If the currently active WO contains rotations, e.g., due to previous workpiece measuring operations, they will be taken into account in the swivel cycle.

#### Swivel mode

Swiveling can either be realized axis-by-axis, using the angle in space, using the projection angle or directly. The machine manufacturer determines when setting up the "Swivel plane/swivel tool" function which swivel methods are available.



#### Machine manufacturer

 $\mathcal{S}$  Please refer to the machine manufacturer's specifications.

#### • Axis by axis

In the case of axis-by-axis swiveling, the coordinate system is rotated about each axis in turn, with each rotation starting from the previous rotation. The axis sequence can be freely selected.

• Solid angle

With the solid angle swiveling option, the tool is first rotated about the Z axis and then about the Y axis. The second rotation starts from the first.

• Projection angle

When swiveling using the projection angle, the angle value of the swiveled surface is projected onto the first two axes of the right-angle coordinate system. The user can freely select the axis rotation sequence.

The 3rd rotation is based on the previous rotation. The active plane and the tool orientation must be taken into consideration when the projection angle is used:

- For G17 projection angle XY, 3rd rotation around Z
- For G18 projection angle ZX, 3rd rotation around Y
- For G19 projection angle YZ, 3rd rotation around X

When projection angles around XY and YX are programmed, the new X-axis of the swiveled coordinate system lies in the old ZX plane.

When projection angles around XZ and ZX are programmed, the new Z-axis of the swiveled coordinate system lies in the old Y-Z plane.

When projection angles around YZ and ZY are programmed, the new Y-axis of the swiveled coordinate system lies in the old X-Y plane.

#### • directly

For direct swiveling, the required positions of the rotary axes are specified. The HMI calculates a suitable new coordinate system based on these values. The tool axis is aligned in the Z direction. You can derive the resulting direction of the X and Y axis by traversing the axes.

#### Note

#### Direction of rotation

The positive direction of each rotation for the different swivel versions is shown in the help displays.

#### Axis sequence

Sequence of the axes which are rotated around:

XYZ or XZY or YXZ or YZX or ZXY or ZYX

#### **Direction (minus/plus)**

Direction reference of traversing direction of rotary axis 1 or 2 of the active swivel data set (machine kinematics). The NC calculates two possible solutions of the rotation / offset programmed in CYCLE800 using the angle traversing range of the rotary axes of the machine kinematics. Usually, only one of these solutions is technologically suitable. The solutions differ by 180 degrees in each case. Selecting the "minus" or "plus" direction determines which of the two possible solutions is to be applied.

- "Minus" → Lower rotary axis value
- "Plus" → Higher rotary axis value

Also in the basic setting (pole setting) of the machine kinematics, the NC calculates two solutions and these are approached by CYCLE800. The reference is the rotary axis that was set as direction reference when commissioning the "swivel" function.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

If one of the two positions cannot be reached for mechanical reasons, the alternative position is automatically selected irrespective of the setting of the "Direction" parameter.

Example:

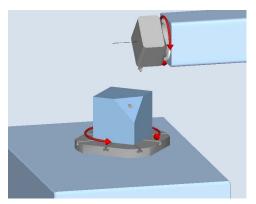
• Machine kinematics with swivel head and swivel table.

Swivel head with rotary axis 1 (B) rotates around machine axis Y.

- Angular traversing range of rotary axis B from -90 to +90 degrees.
- Swivel table with rotary axis 2 (C) rotates around machine axis Z.
- Angle traversing range of rotary axis 2 (C) from 0 to 360 degrees (modulo 360).

- Machine manufacturer has set the direction reference to rotary axis 1 (B) when he commissioned the swivel function.
- A rotation around X (WCS) of 10 degrees is programmed in the swivel cycle.

The machine in the basic setting (pole setting) of the kinematics (B = 0 C = 0) is shown in the following diagram.



- Direction "-" (minus)
  - Rotary axis B moves to -10 degrees in the negative direction (red arrow).
  - Rotary axis C moves to 90 degrees (rotation around X!).
- Direction "+" (plus)
  - Rotary axis B moves to +10 degrees in the positive direction (red arrow).
  - Rotary axis C moves to 270 degrees.

The two "Minus" or "Plus" direction settings enable a workpiece to be machined with swiveled planes. The two solutions calculated by the NC differ by 180 degrees (see rotary axis C).

#### Tool

To avoid collisions, you can use the 5-axis transformation (software option) to define the position of the tool tip during swiveling.

Correct

The position of the tool tip is corrected during swiveling (tracking function).

No correction

The position of the tool tip is not corrected during swiveling.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure

- 1. The part program or ShopMill program to be processed has been created and you are in the editor.
- Swivel

Vari-

2.

Press the "Swivel plane" softkey.
 The "Swivel plane" input window opens.

Press the "Various" softkey.

Initial setting Press the "Basic setting" softkey if you wish to reestablish the initial state, i.e. you wish to set the values back to 0.
 You use this, for example, to swivel the coordinate system back into its original orientation.

Parameters, G code program			Parameters, ShopMill program		
PL	Machining plane		Т	Tool name	
			D	Cutting edge number	
			F	Feedrate	mm/min mm/rev
			S/V	Spindle speed or constant cutting rate	rpm m/min

Parameter	Description	Unit			
TC U	Name of the swivel data set				
Retraction	No: No retraction before swiveling				
U	• Z: Retraction in the direction of machine axis Z				
	• Z, X, Y: Move machining axis to retraction position before swiveling				
	• Tool direction, max.: Maximum retraction (up to the software end position) in the tool direction				
	• Tool direction, inc.: Retraction, incremental (up to the software end position) in the tool direction				
	When retracting in the tool direction, in the swiveled machine state, several axes can move (travel).				
ZR	Retraction path - (only for incremental retraction in the tool direction)				
Swivel plane	wivel plane   • New: New swivel plane				
O	Additive: Additive swivel plane				
X0	Reference point for rotation X				
Y0	Reference point for rotation Y				
Z0	Reference point for rotation Z				
Swivel mode 🚺	Axis by axis: Rotate coordinate system axis-by-axis				
	Solid angle: Swivel via solid angle				
	Proj. angle: Swiveling via projection angle				
	Direct: Directly position rotary axes				

Parameter	Description			
Axis sequence U	Sequence of the axes which are rotated around: - (only for axis-by-axis swivel mode) XYZ or XZY or YXZ or YZX or ZXY or ZYX			
х	Rotation around X	- (only for axis sequence)	Degrees	
Y	Rotation around Y		Degrees	
Z	Rotation around Z		Degrees	
Projection position U	Position of the projection in space - (only for swivel mode, projection angle) Xα, Yα, Zβ or Yα, Zα, Zβ or Zα, Xα, Zβ			
Χα	Projection angle	- (only for projection position)	Degrees	
Υα	Projection angle		Degrees	
Ζβ	Angle of rotation in the plane		Degrees	
Name of rotary axis 1	Angle of rotation of rotary axis 1	- (only for direct swivel mode)	Degrees	
Name of rotary axis 2	Angle of rotation of rotary axis 2		Degrees	
Z	Angle of rotation in the plane		Degrees	
X1	Zero point of rotated surface X	Zero point of rotated surface X		
Y1	Zero point of rotated surface Y			
Z1	Zero point of rotated surface Z			
Direction 💟	Preferred direction, rotary axis 1 - (not for swivel mode direct)  +			
Tool 🧿	<ul> <li>Tool tip when swiveling</li> <li>Correct <ul> <li>The position of the tool tip is maintained during swiveling.</li> </ul> </li> <li>No correction <ul> <li>The position of the tool tip is not maintained during swiveling.</li> </ul> </li> </ul>			

# 8.6.2 Swiveling tool (CYCLE800)

# 8.6.2.1 Swiveling tool/preloading milling tools - only for G code program (CYCLE800)

After "Swivel plane", the tool orientation is always perpendicular on the machining plane. When milling with radial cutters, it can make technological sense to set the tool at an angle to the normal surface vector. In the swivel cycle, the setting angle is generated by an axis rotation (max. +/- 90 degrees) to the active swivel plane. When setting, the swivel plane is always "additive". With "Setting tool", only rotations are displayed on the swivel cycle input screen form. The user can freely select the rotation sequence.

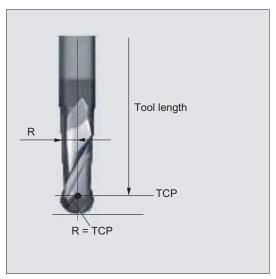


Figure 8-1 The length up to the TCP (Tool Center Point) must be entered as tool length of the radial cutter.

# Procedure

1. The part program to be executed has been created and you are in the editor.



2.

Press the "Various" softkey.



 Press the "Swivel tool" and "Setting milling tool" softkeys. The "Setting tool" input window opens.

Parameter	Description	Unit	
TC 🕐	Name of the swivel data set		
Retraction	<ul> <li>No: No retraction before swiveling</li> <li>Z: Retraction in the direction of machine axis Z</li> <li>Z, X, Y: Move machining axis to retraction position before swiveling</li> <li>Tool direction, max.: Maximum retraction in tool direction</li> <li>Tool direction, inc.: Incremental retraction in tool direction</li> </ul>		
ZR	Retraction path - (only for incremental retraction in the tool direction)		
Axis sequence U	Sequence of the axes which are rotated around XY or XZ or YX or YZ or ZX or ZY		
Х	Rotation around X Degrees		
Y	Rotation around Y Degrees		
Tool 🖸	<ul> <li>Tool tip when swiveling</li> <li>Correct <ul> <li>The position of the tool tip is maintained during swiveling.</li> </ul> </li> <li>No correction <ul> <li>The position of the tool tip is not maintained during swiveling.</li> </ul> </li> </ul>		

## 8.6.2.2 Swiveling tool/orienting milling tools - only for G code program (CYCLE800)

#### Function

The purpose of the "Aligning milling tool" or "Aligning turning tool" function is to support lathes with a B axis that can be swiveled. This functionality is designed for use with a specific configuration of lathes or milling machines on which the tool orientation is implemented by a swivel axis B (around Y) with associated milling spindle (C1). It is designed to be compatible with both turning and milling tools.

In contrast to "Swivel plane", no rotation is effective in the active frame chain (WCS) in the case of "Swivel tool" or "Align tool". Only the offsets calculated by the NC and the corresponding tool orientation are effective.

The maximum angular range for "Align tool" is + 360 degrees or it is limited by the traversing range of the participating rotary axes. Technological limits are also placed on the angular range depending on the tool used.

The use of the "Align milling tool" function is restricted to milling operations in parallel with the axis (face, peripheral machining) at a machine with a B axis that can be swiveled. If milling is to be possible on any swiveled machining plane, then the "swivel plane" function must be used.

# Procedure



- 1. The part program to be executed has been created and you are in the editor.
  - Press the "Various" softkey.
- Press the "Swivel tool" and "Align milling tool" softkeys. The "Align milling tool" input window opens.

Parameter	Description		
TC 🚺	Name of the swivel data set		
Retract O	<ul> <li>No: No retraction before swiveling</li> <li>Z: Retraction in the direction of machine axis Z</li> <li>Tool direction, max.: Maximum retraction in tool direction</li> <li>Tool direction, inc.: Incremental retraction in tool direction</li> </ul>		
ZR	Retraction path - (only for incremental retraction in the tool direction)		
β	Rotation around the 3rd geometry axis (for G18 Y) Degrees		
Tool 😈	<ul> <li>Tool tip when swiveling</li> <li>Correct</li> <li>The position of the tool tip is maintained during swiveling.</li> <li>No correction</li> <li>The position of the tool tip is not maintained during swiveling.</li> </ul>		

# 8.6.3 High-speed settings (CYCLE832)

# Function

Machining of free-form surfaces involves high requirements regarding velocity, precision and surface quality.

You can achieve optimum velocity control depending on the type of processing (roughing, rough-finishing, finishing) very simply with the "High Speed Settings" cycle.

Program the cycle in the technology program before the geometry program is called.

The "High Speed Settings" cycle is also in conjunction with the "Advanced Surface" function.



#### Software option

You require the software option in order to use this function: "Advanced Surface"

## Machining methods

With the "High Speed Settings" function, you can select between four technological machining types:

- "Finishing"
- "Rough-finishing"
- "Roughing"
- "Deselected" (default setting)

For CAM programs in the HSC range, the four machining types directly relate to the accuracy and speed of the path contour (see help screen).

The operator/programmer uses the tolerance value to give a corresponding weighting.

Corresponding to the appropriate G commands, the four machining types are assigned to technology G group 59:

Machining type	Technology G group 59
Deselection	DYNNORM
Finishing	DYNFINISH
Rough-finishing	DYNSEMIFIN
Roughing	DYNROUGH

Additional G commands that are available in conjunction with machining free-form surfaces, are also activated in the High Speed Settings cycle.

When deselecting CYCLE832, the G groups are programmed to the settings - during the program run time - that are declared in the machine data for the reset state.

#### References

For additional information, please refer to the following documentation:

Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Procedure

	1.	The part program or ShopMill program to be processed has been created and you are in the editor.
Uari- ous	2.	Press the "Various" softkey.
HighSpeed settings	3.	Press the "High Speed Settings" softkey. The "High Speed Settings" input window is opened.

Parameter	Description Unit			
Tolerance	Tolerance of the machining axis			
Machining	∇ (roughing)			
U	<ul> <li>∇∇ (pre-finishing)</li> </ul>			
-	• $\nabla \nabla \nabla$ (finishing)			
	Deselection			

#### 8.6.4 Subroutines

If you require the same machining steps when programming different workpieces, you can define these machining steps in a separate subprogram. You can then call this subprogram in any programs.

Identical machining steps therefore only have to be programmed once.

ShopMill does not differentiate between main programs and subprograms. This means that you can call a "standard" machining step or G code program as subprogram in another machining step program.

You can also call another subprogram in the subprogram. The maximum nesting depth is 8 subprograms.

You cannot insert subprograms into linked blocks.

If you want to call machining step program as subprogram, the program must already have been calculated once (load or simulate program in Machine Auto mode). This is not necessary for G code subprograms.

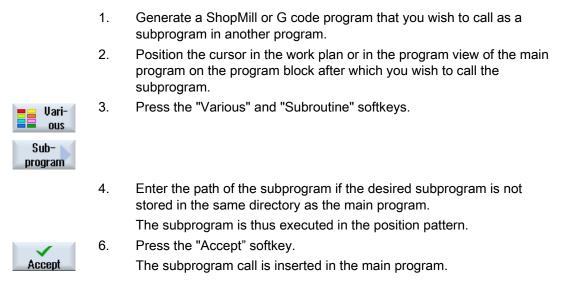
The subprogram must always be stored in the NCK work memory (in a separate directory "XYZ" or in the "ShopMill", "Part programs", "Subprograms" directories).

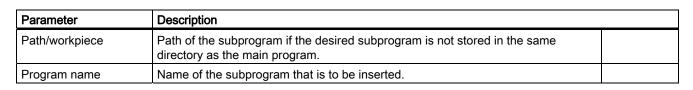
If you want to call a subprogram located on another drive, you can use G code command "EXTCALL".

Please note that, when a subprogram is called, ShopMill evaluates the settings in the program header of the subprogram. These settings also remain active even after the subprogram has ended.

If you wish to activate the settings from the program header for the main program again, you can make the settings again in the main program after calling the subprogram.

# Procedure





# Programming example

N10 T1 D1	;Load tool
N11 M6	
N20 G54 G710	;Select work offset
N30 M3 S12000	;Switch-on spindle
N40 CYCLE832(0.05,3,1)	;Tolerance value 0.05 mm, machining type, roughing
N50 EXTCALL"CAM_SCHRUPP"	Externally call subprogram CAM_SCHRUPP
N60 T2 D1	;Load tool
N61 M6	
N70 CYCLE832(0.005,1,1)	;Tolerance value 0.005 mm, machining type, finishing
N80 EXTCALL"CAM_SCHLICHT"	;Call subprogram CAM_SCHLICHT
N90 M30	;End of program

The subprograms CAM\_SCHRUPP.SPF, CAM\_SCHLICHT.SPF contain the workpiece geometry and the technological values (feedrates). These are externally called due to the program size.

8.7 Further cycles and functions ShopMill

# 8.7 Further cycles and functions ShopMill

# 8.7.1 Transformations

To make programming easier, you can transform the coordinate system. Use this possibility, for example, to rotate the coordinate system.

Coordinate transformations only apply in the actual program. You can define shift, rotation, scaling or mirroring. You can select between a new or an additive coordinate transformation.

In the case of a new coordinate transformation, all previously defined coordinate transformations are deselected. An additive coordinate transformation acts in addition to the currently selected coordinate transformations.

#### Note

#### Transformations with virtual axes

Please note that when selecting TRANSMIT or TRACYL offsets, scaling and mirroring, the real Y axis is not transferred into the virtual Y axis.

Offsets, scalings and mirroring of the virtual Y axis are deleted for TRAFOOF.

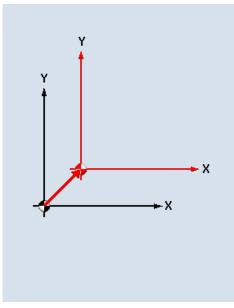
# Procedure for work offset, offset, rotation, scaling or mirroring

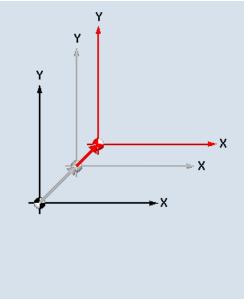
	1.	The ShopMill program has been created and you are in the
Vari- ous	2.	Press the "Various" and "Transformation" softkeys.
Transfor- mations		
Work	3.	Press the "Work offsets" softkey.
offset		The "Work offsets" input window opens.
		- OR -
Off-		Press the "Offset" softkey.
set 🖊		The "Offset" input window opens.
		- OR -
<b>D L U</b>		Press the "Rotation" softkey.
Rotation		The "Rotate" input window opens.
		- OR -
		Press the "Scaling" softkey.
Scaling		The "Scaling" input window opens.
		- OR -
		Press the "Mirroring" softkey.
Mirroring		The "Mirroring" input window opens.

editor.

# 8.7.2 Translation

For each axis, you can program an offset of the zero point.





New offset

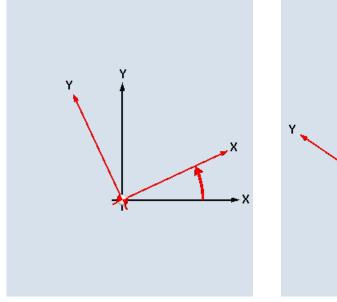
Additive offset

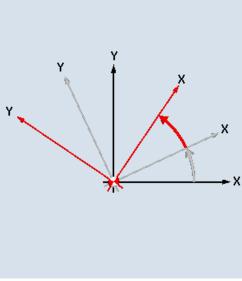
Parameter	Description	Unit
Offset	• New	
U	New offset <ul> <li>Additive</li> <li>Additive offset</li> </ul>	
х	Offset X	mm
Y	Offset Y	mm
Z	Offset Z	mm

8.7 Further cycles and functions ShopMill

# 8.7.3 Rotation

You can rotate every axis through a specific angle. A positive angle corresponds to counterclockwise rotation.





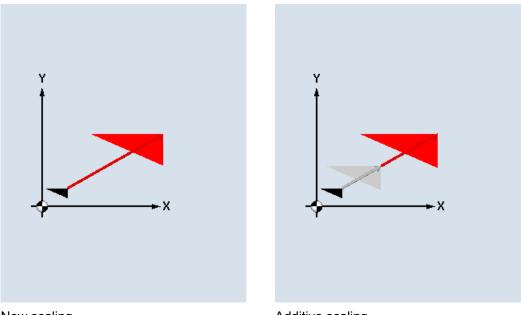
New rotation

Additive rotation

Parameter	Description	Unit
Rotation	• New	
	New rotation <ul> <li>Additive</li> </ul>	
	Additive rotation	
Х	Rotation around X	Degrees
Υ	Rotation around Y	Degrees
Z	Rotation around Z	Degrees

# 8.7.4 Scaling

You can specify a scale factor for the active machining plane as well as for the tool axis. The programmed coordinates are then multiplied by this factor.



New scaling

Additive scaling

Parameter	Description	Unit
Scaling	• New	
U	<ul><li>New scaling</li><li>Additive</li><li>Additive scaling</li></ul>	
XY	Scale factor XY	
Z	cale factor Z	

# 8.7.5 Mirroring

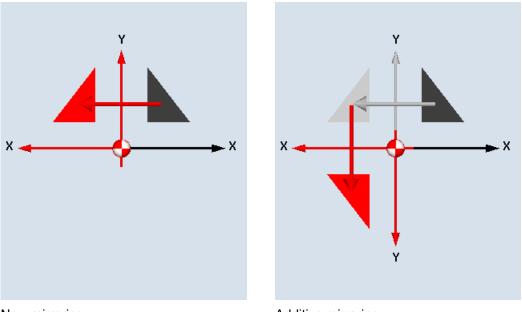
Furthermore, you can mirror all axes. Enter the axis to be mirrored in each case.

### Note

### Travel direction of the milling cutter

Note that with mirroring, the travel direction of the cutting tool (conventional/climbing) is also mirrored.

8.7 Further cycles and functions ShopMill



New mirroring

Additive mirroring

Parameter	Description	Unit
Mirroring	• New	
O	New mirroring <ul> <li>Additive</li> </ul>	
	Additive mirroring	
XU	Mirroring of the X axis, on/off	
YU	Mirroring of the Y axis, on/off	
ZU	Mirroring of the Z axis, on/off	

# 8.7.6 Straight or circular machining

When you want to perform straight or circular path movements or machining without defining a complete contour, you can use the functions "Straight line" or "Circle" respectively.

### General sequence

To program simple machining operations, proceed as follows:

- Specify the tool and the spindle speed
- Program the machining operation

### Machining options

The following machining options are available:

Programming technological functions (cycles) 8.7 Further cycles and functions ShopMill

- Straight line
- Circle with known center point
- Circle with known radius
- Helix
- Straight line with polar coordinates
- Circle with polar coordinates

If you want to program a straight line or a circle using polar coordinates, you must define the pole first.

# 

If you use a straight or circular path movement to move the tool into the retraction zone specified in the program header, you must also move the tool out again. Otherwise a collision could occur as a result of the traversing movements in a subsequently programmed cycle.

Before you can program a straight line or circle, you have to select the tool, spindle speed and machining plane.

If you program a sequence of different straight or circular path movements, the settings for the tool and spindle speed remain active until you change these again.

# Procedure

- Edit

   Edit

   >

   Stright

   Circle
- 1. The ShopMill program to be edited has been created and you are in the editor.
- 2. Press the menu forward key and the "Straight Circle" softkey.
- Press the "Tool" softkey. 3. Tool The parameter screen "Tool" is opened. 4. Enter a tool in parameter field "T". - OR -Press the "Select tool" softkey. Select tool The "Tool selection" window is opened. Position the cursor on the tool that you wish to use for machining and To press the "To program" softkey. program The tool is copied into the "T" parameter field. - OR -Press the "Tool list" and "New tool" softkeys.

8.7 Further cycles and functions ShopMill

Using the softkeys on the vertical softkey bar, select the required tool and press the "To program" softkey.

The tool is copied into the "T" parameter field.

- 5. Select the tool cutting edge number D if the tool has several cutting edges.
- 6. Enter the spindle speed or cutting rate.
- 7. Enter an allowance in the "DR" field.

Accept

Press the "Accept" softkey. The values are saved and the parameterization screen form is closed. The process plan is displayed and the newly generated program block is marked.

Parameter	Description	Unit
Т	Tool name	
D Ŭ	Cutting edge number	
S / V 🚺	Spindle speed or	rev/min
	Constant cutting rate	m/min
DR	Allowance, tool radius	mm

# 8.7.7 Programming a straight line

The tool moves at the programmed feedrate or with rapid traverse from its actual position to the programmed end position.

### Radius compensation

Alternatively, you can implement the straight line with radius compensation. The radius compensation acts modally, therefore you must deactivate the radius compensation again when you want to traverse without radius compensation. Where several straight line blocks with radius compensation are programmed sequentially, you may only select radius compensation in the first program block.

When executing the first path motion with radius compensation, the tool traverses without compensation at the starting point and with compensation at the end point. This means that if a vertical path is programmed, the tool traverses an oblique path. The compensation is not applied over the entire traversing path until the second programmed path motion with radius compensation is executed. The reverse effect occurs when radius compensation is deactivated.

# Procedure

- 1. The ShopMill program to be edited has been created and you are in the editor.
- Straight

Rapid

- 2. Press the menu forward key and the "Straight Circle" softkey.
- 3. Press the "Straight line" softkey.

4. Press the "Rapid traverse" softkey to enter the feedrate in rapid traverse.

Parameter	Descriptio	n	Unit
X U	Target position X (abs) or target position X referred to the last programmed position (inc)		mm
Y U	Target position Y (abs) or target position Y referred to the last programmed position (inc)		mm
Z	Target position Z (abs) or target position Z referred to the last programmed position (inc)		mm
	Note Incremental dimensions: The sign is also evaluated.		
F	Machining feedrate		mm/rev mm/min mm/tooth
Radius compensation	Input defir direction:	ning which side of the contour the cutter travels in the programmed	
	38 <mark>8</mark>	Radius compensation to right of contour	
	<u>8</u>	Radius compensation to left of contour	
	×	Radius compensation off	
		The previously programmed setting for radius compensation is used.	

# 8.7.8 Programming a circle with known center point

The tool travels along a circular path from its actual position to the programmed circle end point. You must know the position of the circle center point. The control calculates the radius of the circle/arc on the basis of your interpolation parameter settings.

The circle can only be traversed at machining feedrate. You must program a tool before the circle can be traversed.

8.7 Further cycles and functions ShopMill

# Procedure

1. The ShopMill program to be edited has been created and you are in the editor.



center

- 2. Press the menu forward key and the "Straight Circle" softkey.
- 3. Press the "Circle center point" softkey.

Parameter	Descrip	otion	Unit
Direction of rotation		The tool travels in the programmed direction from the circle starting point to its end point. You can program this direction as clockwise or counterclockwise.	
	2	Clockwise direction of rotation	
	s	Counterclockwise direction of rotation	
X U	Target positior	position X (abs) or target position X referred to the last programmed n (inc)	mm
Y U	Target position Y (abs) or target position Y referred to the last programmed position (inc)		mm
1	Distance between circle starting point and center point in X direction (inc.)		mm
J	Distance between circle starting point and center point in Y direction (inc.)		mm
F	Machining feedrate		mm/rev
U			mm/min
			mm/tooth
PL	Plane: The circle is traversed in the set plane with the relevant interpolation parameters:		
	XYIJ: X	Y plane with interpolation parameters I and J	mm
	ZXKI: Z	X plane with interpolation parameters K and I	mm
	YZJK: `	YZ plane with interpolation parameters J and K	mm

# 8.7.9 Programming a circle with known radius

The tool traverses a circular path with the programmed radius from its actual position to the programmed circle end point. The control system calculates the circle center point. You do not need to program interpolation parameters.

The circle can only be traversed at machining feedrate.

# Procedure

1. The ShopMill program to be edited has been created and you are in the editor.



2. Press the menu forward key and the "Straight Circle" softkey.



Circle radius 3. Press the "Circle radius" softkey.

Parameter	Descrip	Description		
Direction of rotation		I travels in the programmed direction from the circle starting point to its end ou can program this direction as clockwise or counterclockwise.		
_	Q	Clockwise direction of rotation		
	Ω	Counterclockwise direction of rotation		
X U		Target position X (abs) or target position X referred to the last programmed position (inc)		
Y U	Target position Y (abs) or target position Y referred to the last programmed position (inc)		mm	
R	Radius of arc. You can select the arc of your choice by entering a positive or a negative sign.		mm	
F			mm/rev mm/min mm/tooth	

# 8.7.10 Helix

With helical interpolation, a circular movement is overlaid in the plane with a linear motion in the tool axis, i.e. a spiral is created.

8.7 Further cycles and functions ShopMill

# Procedure

1. The ShopMill program to be edited has been created and you are in the editor.



2. Press the menu forward key and the "Straight Circle" softkey.



Helix

3. Press the "Helix" softkey.

Parameter	Descript	Description	
Direction of rotation		travels in the programmed direction from the circle starting point to its end ou can program this direction as clockwise or counterclockwise.	
	Q	Clockwise direction of rotation	
	ۍ	Counterclockwise direction of rotation	]
	Center p	Center point of the helix in the X direction (abs or inc)	
J	Center point of the helix in the Y direction (abs or inc)		mm
Р	Helix pitch The pitch is programmed in mm per revolution.		mm/rev
Z U	Target position of the helical end point (abs or inc)		mm
F	Machining feedrate		mm/rev
O			mm/min
			mm/tooth

# 8.7.11 Polar coordinates

If a workpiece has been dimensioned from a central point (pole) with radius and angles, you will find it helpful to program these as polar coordinates.

You can program straight lines and circles as polar coordinates.

### Defining a pole

You must define the pole before you can program a straight line or circle in polar coordinates. This pole acts as the reference point of the polar coordinate system.

The angle for the first line or circle then needs to be programmed in absolute coordinates. You can program the angles for any additional straight lines and circles as either absolute or incremental coordinates.

# Procedure

1. The ShopMill program to be edited has been created and you are in the editor.



2. Press the menu forward key and the "Polar" softkey.





3. Press the "Pole" softkey.

Parameter	Description	Unit
XU	Pole X (abs) or pole X referred to the last programmed position (inc)	mm
YU	Pole Y (abs) or pole Y referred to the last programmed position (inc)	mm

#### 8.7.12 Straight polar

A straight line in the polar coordinate system is defined by a radius (L) and an angle ( $\alpha$ ). The angle refers to the X axis.

The tool moves from its actual position along a straight line to the programmed end point at the machining feedrate or in rapid traverse.

The 1st straight line in polar coordinates entered after the pole must be programmed with an absolute angle. You can program any additional straight lines or circles with incremental coordinates.

### Procedure

1. The ShopMill program to be edited has been created and you are in the editor.



2. Press the menu forward key and the "Straight Circle" softkey.



# Programming technological functions (cycles)

8.7 Further cycles and functions ShopMill

Polar	3.	Press the "Polar" and "Straight polar" softkeys.
Straight polar		
Rapid	4.	Press the "Rapid traverse" softkey to enter the feedrate in rapid traverse.

Parameter	Description		Unit
L	Distance to the p	ole, end point	mm
α 🖸		e pole, end point (abs) or angle to the pole, end point (inc)	Degrees
F	Machining feedrate		mm/rev mm/min mm/tooth
Radius compensation	Input defining which side of the contour the cutter travels in the programmed direction:		
	<del>8</del>	Radius compensation to left of contour	
	35	Radius compensation to right of contour	
	×	Radius compensation off	
		The set radius compensation remains as previously set	

# 8.7.13 Circle polar

A circle in the polar coordinate system is defined by an angle ( $\alpha$ ). The angle refers to the X axis.

The tool moves from its actual position on a circular path to the programmed end point (angle) at the machining feedrate. The radius corresponds to the distance from the actual tool position to the defined pole, i.e. the circle starting and end point positions are at the same distance from the defined pole.

The 1st arc in polar coordinates entered after the pole must be programmed with an absolute angle. You can program any additional straight lines or circles with incremental coordinates.

# Procedure

- 1. The ShopMill program to be edited has been created and you are in the editor.
- 2. Press the menu forward key and the "Straight Circle" softkey.



3. Press the "Polar" and "Circle polar" softkeys.



Polar

Parameter	Description		Unit
Direction of rotation		avels in the programmed direction from the circle starting point to its end can program this direction as clockwise (right) or counterclockwise	
	Q	Clockwise direction of rotation	
	۵	Counterclockwise direction of rotation	
U	Polar angle to the pole, end point (abs) or change in polar angle to the pole, end point (inc)		Degrees
F	Machining feedrate		mm/rev mm/min mm/tooth

#### 8.7.14 Obstacle

# Function

If there is an obstacle between 2 position patterns, it can be crossed. The height of the obstacle can be programmed absolutely or incrementally.

If all positions in the 1st pattern have been machined, the tool axis travels with rapid traverse to a height corresponding to the obstacle height + safety clearance. The new position is approached with rapid traverse at this height. The tool axis then approaches a position according to Z0 of the position pattern + safety clearance with rapid traverse.

8.7 Further cycles and functions ShopMill

# Procedure

	1.	The ShopMill program to be edited has been created and you are in the editor.
⊾ Drill.	2.	Press the "Drilling" softkey.
Positions	3.	Press the "Positions" and "Obstacle" softkeys. The "obstacle" input window opens.
Obstacle		

### Note

Obstacles are only taken into consideration if they lie between 2 position patterns. If the tool change point and the programmed retraction plane are positioned below the obstacle, the tool travels to the retraction plane height and on to the new position without taking the obstacle into account. The obstacle must not be higher than the retraction plane.

Parameter	Description	
Z0 🖸	Obstacle height (abs or inc)	

Multi-channel view

# 9.1 Multi-channel view

The multi-channel view allows you to simultaneously view two channels in the following operating areas:

- "Machine" operating area
- "Program" operating area

9.2 Multi-channel view in the "Machine" operating area

# 9.2 Multi-channel view in the "Machine" operating area

When a multi-channel machine, you have the option of simultaneously monitoring and influencing the execution of several programs.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

### Displaying the channels in the "Machine" operating area

In the "Machine" operating area, you can display 2 channels simultaneously.

Using the appropriate settings, you can define the sequence in which channels are displayed. Here, you can also select if you wish to hide a channel.

### Note

The sub operating mode "REF POINT" is only shown in the single channel view.

#### Multi-channel view

2 channels are simultaneously displayed in channel columns on the user interface.

- 2 windows are displayed one above the other for each channel.
- The actual value display is always in the upper window.
- The same window is displayed for both channels in the lower window.
- You can select the display in the lower window using the vertical softkey bar.

The following exceptions apply when making a selection using the vertical softkeys:

- The "Actual values Machine" softkey switches over the coordinate systems of both channels.
- The "Zoom actual value" and "All G functions" softkeys switch into the single-channel view.

#### Single channel view

If, for your multi-channel machine, you always only wish to monitor one channel, then you can set a permanent single-channel view.

#### Horizontal softkeys

Block search

When selecting the block search, the multi-channel view is kept. The block display is displayed as search window.

Program control

The "Program control" window is displayed for the channels configured in the multichannel view. The data entered here apply for these channels together.

 If you press an additional horizontal softkey in the "Machine" operating area (e.g. "Overstore", "Synchronized actions"), then you change into a temporary single-channel view. If you close the window again, then you return to the multi-channel view.

9.2 Multi-channel view in the "Machine" operating area

### Switching between single and multi-channel view



Press the <MACHINE> key in order to briefly switch between the single and multi-channel display in the machine area.



Press the <NEXT WINDOW> key in order to switch between the upper and lower window within a channel column.

### Editing a program in the block display

You can perform simple editing operations as usual in the actual block display. If there is not sufficient space, you switch over into the single-channel view.

### Running-in a program

You select individual channels to run-in the program at the machine.

### Precondition

- Several channels have been set-up.
- The "2 channels" setting has been selected.

# Displaying/hiding a multi-channel view

Machine	1.	Select the "Machine" operating area
	2.	Select the operating mode "JOG", "MDA" or "AUTO".
	3.	Press the menu forward key and the "Settings" softkey.
₽ <sup>™</sup> Settings		
Miti-chan. view	4.	Press the "Multi-channel view" softkey.

9.2 Multi-channel view in the "Machine" operating area

5.	In the window "Settings for multi-channel view" in the selection box "View", select the entry "2 channels" and define the channels as well as the sequence in which they are displayed.
	In the basic screen for the "AUTO", "MDA" and JOG" operating modes, the upper window of the lefthand and righthand channel columns are occupied by the actual value window.
6.	Press the "T,S,F" softkey if you wish to view the "T,F,S"

T,F,S

Press the "T,S,F" softkey if you wish to view the "T,F,S" window.

The "T,F,S" window is displayed in the lower window of the lefthand and righthand channel column.

# 9.3 Setting the multi-channel view

Setting	Meaning
View	<ul><li>Here, you define whether one or two channels are displayed.</li><li>1 channel</li><li>2 channels</li></ul>
Channel selection and sequence	Here, you create the channel group, i.e. you specify which channels and in which sequence are displayed in the multi-channel view.
(for "2 channels" view)	
Visible	Here, you specify which channels are displayed in the two-channel view.
(for "2 channels" view)	

### Example

Your machine has 6 channels.

You configure channels 1 - 4 for the multi-channel view and define the display sequence (e.g. 1,3,4,2).

In the multi-channel view, for a channel switchover, you can only switch between the channels configured for the multi-channel view; all others are not taken into consideration. Using the <CHANNEL> key, advance the channel in the "Machine" operating area - you obtain the following views: Channels "1" and "3", channels "3" and "4", channels "4" and "2". Channels "5" and "6" are not displayed in the multi-channel view.

In the single-channel view, toggle between all of the channels (1...6) without taking into account the configured sequence for the multi-channel view.

Using the channel menu, you can always select all channels, also those not configured for multi-channel view. If you switch to another channel, which is not configured for the multiview, then the system automatically switches into the single-channel view. There is no automatic switchback into the multi-channel view, even if a channel is again selected, which has been configured for multi-channel view.

# Procedure



1. Select the "Machine" operating area.

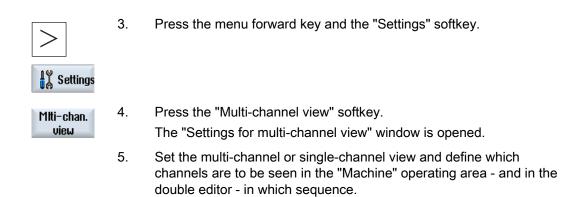


AUTO

2. Select the operating mode "JOG", "MDA" or "AUTO".

### Multi-channel view

9.3 Setting the multi-channel view



# User variables

# 10

# 10.1 Overview

The defined user data may be displayed in lists.

The following variables can be defined:

- Data parameters (R parameters)
- Global user data (GUD) is valid in all programs
- Local user data (LUD) is valid in one program
- Program-global user data (PUD) is valid in one program and the called subroutines.

Channel-specific user data can be defined with a different value for each channel.

### Entering and displaying parameter values

Up to 15 positions (including decimal places) are evaluated. If you enter a number with more than 15 places, it will be written in exponential notation (15 places + EXXX).

### LUD or PUD

Only local or program-global user data can be displayed at one time.

Whether the user data are available as LUD or PUD depends on the current control configuration.



### Machine manufacturer

Please also refer to the machine manufacturer's specifications.

#### Note

#### Reading and writing variables protected

Reading and writing of user data are protected via a keyswitch and protection levels.

#### Searching for user data

You may search for user data within the lists using any character string.

Refer to the "Defining and activating user data" section to learn how to edit displayed user data.

10.2 R parameters

# 10.2 R parameters

R parameters (arithmetic parameters) are channel-specific variables that you can use within a G code program. G code programs can read and write R parameters.

These values are retained after the control is switched off.

### Number of channel-specific R parameters

The number of channel-specific R parameters is defined in a machine data element.

Range: R0-R999 (dependent on machine data).

There are no gaps in the numbering within the range.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

# Procedure

Parameter	1.	Select the "Parameter" operating area.
R User variable	2.	Press the "User variable" softkey.
R variables	3.	Press the "R variables" softkey. The "R parameters" window appears.

### **Delete R variables**

1.



Press the ">>" and "Delete" softkeys. The "Delete R parameters" window appears.



 Enter the R parameter(s) whose channel-specific values you would like to delete and press the "OK" softkey.

A value of 0 is assigned to the selected R parameters or to all R parameters.

#### 10.3 **Global GUD**

# Global user data

Global GUDs are NC global user data (Global User Data) that remains available after switching the machine off.

GUDs apply in all programs.

### Definition

A GUD variable is defined with the following:

- Keyword DEF
- Range of validity NCK
- Data type (INT, REAL, ....)
- Variable names
- Value assignment (optional)

# Example

### DEF NCK INT ZAEHLER1 = 10

GUDs are defined in files with the ending DEF. The following file names are reserved for this purpose:

File name	Meaning
MGUD.DEF	Definitions for global machine manufacturer data
UGUD.DEF	Definitions for global user data
GUD4.DEF	User-definable data
GUD8.DEF, GUD9.DEF	User-definable data

# Procedure



1. Select the "Parameter" operating area.





variable

- 2. Press the "User variable" softkey.
- Global GUD
- 3. Press the "Global GUD" softkeys.

The "Global user data" window is displayed. A list of the defined UGUD variables will be displayed. - OR -

# 10.3 Global GUD

GUD selection GUD6	Press the "GUD selection" softkey and the "SGUD" to "GUD6" softkeys if you wish to display SGUD, MGUD, UGUD as well as GUD4 to GUD 6 of the global user variables.
GUD selection GUD9	- OR - Press the "GUD selection" and ">>" softkeys as well as the "GUD7" to "GUD9" softkeys if you want to display GUD 7 to GUD 9 of the global user data.

### Note

After each start-up, a list with the defined UGUD variables is displayed in the "Global user data" window.

# 10.4 Channel GUD

### Channel-specific user data

Like the GUDs, channel-specific user data are applicable in all programs for each channel. However, unlike GUDs, they have specific values.

### Definition

A channel-specific GUD variable is defined with the following:

- Keyword DEF
- Range of validity CHAN
- Data type
- Variable names
- Value assignment (optional)

## Example

DEF CHAN REAL X\_POS = 100.5

## Procedure

<b>↓</b> Parameter	1.	Select the "Parameter" operating area.
R User variable	2.	Press the "User variable" softkey.
Channel GUD	3.	Press the "Channel GUD" and "GUD selection" softkeys.
GUD selection		
SGUD GUD6	4.	A new vertical softkey bar appears. Press the "SGUD" "GUD6" softkeys if you want to display the SGUD, MGUD, UGUD as well as GUD4 to GUD 6 of the channel- specific user variables.
Continue GVD9		- OR - Press the "Continue" softkey and the "GUD7" to "GUD9" softkeys if you want to display GUD 7 to GUD 9 of the channel-specific user data.

10.5 Local LUD

# 10.5 Local LUD

# Local user data

LUDs are only valid in the program or subroutine in which they were defined.

The control displays the LUDs after the start of program processing. The display is available until the end of program processing.

# Definition

A local user variable is defined with the following:

- Keyword DEF
- Data type
- Variable names
- Value assignment (optional)

# Proceed as follows

ţ O	1.	Select the "Parameter" operating area.
Parameter		
R User variable	2.	Press the "User variable" softkey.
Local LUD	3.	Press the "Local LUD" softkey.

# 10.6 Program PUD

# Program-global user data

PUDs are global part program variables (**P**rogram **U**ser **D**ata). PUDs are valid in all main programs and subroutines, where they can also be written and read.



### Machine manufacturer

Please refer to the machine manufacturer's specifications.

### Procedure



1. Select the "Parameter" operating area.





2. Press the "User variable" softkey.



3.

Press the "Program PUD" softkey.

### User variables

10.7 Searching for user data

# 10.7 Searching for user data

You can search for R parameters and user data.

# Procedure

Parameter	1.	Select the "Parameter" operating area.
R variables Local LUD	2.	Press the "R parameters", "Global GUD", "Channel GUD", "Local GUD" or "Program PUD" softkeys to select the list in which you would like to search for user data.
Search	3.	Press the "Search" softkey. The "Search for R Parameters" or "Search for User Data" window opens.
ОК	4.	Enter the desired search term and press "OK".

The cursor is automatically positioned on the the R parameter or user data you are searching for, if they exist.

User variables

10.8 Defining and activating user variables

# 10.8 Defining and activating user variables

By editing a DEF/MAC file, you can alter or delete existing definition/macro files or add new ones.

# Proceed as follows

Start-up	1.	Select the "Startup" operating area.
⊨B System data	2.	Press the "System data" softkey.
	3.	In the data tree, select the "NC data" folder and then open the "Definitions" folder.
	4.	Select the file you want to edit.
	5.	Double-click the file.
		- OR -
Open		Press the "Open" softkey.
		- OR -
		Press the <input/> key.
		- OR -
		Press the <cursor right=""> key.</cursor>
		The selected file is opened in the editor and can be edited there.
	6.	Define the desired user data.
Exit	7.	Press the "Exit" softkey to close the editor.
Activating user data		

1. Press the "Activate" softkey.

A prompt is displayed.

2. Select whether the current values in the definition files should be retained

- OR -

Activate

10.8 Defining and activating user variables

Select whether the current values in the definition files should be deleted.

This will overwrite the definition files with the initial values.

Press the "OK" softkey to continue the process.



3.

# Teaching in a program

# 11.1 Overview

The "Teach in" function can be used to edit programs in the "AUTO" and "MDA" modes. You can create and modify simple traversing blocks.

You traverse the axes manually to specific positions in order to implement simple machining sequences and make them reproducible. The positions you approach are applied.

In "AUTO" teach-in mode, the selected program is "taught".

In "MDA" teach-in mode, you teach to the MDA buffer.

External programs, which may have been rendered offline, can therefore be adjusted and modified according to need.

# 11.2 General sequence

### General sequence

Select the desired program block, press the relevant softkey "Teach position", "Rap. tra. G01", "Straight line G1" or "Circ. interm. pos. CIP", and "Circ. end pos. CIP" and traverse the axes to change the program block.

You can only overwrite a block with a block of the same type.

- OR -

Position the cursor at the desired point in the program, press the relevant softkey "Teach position", "Rap. tra. G01", "Straight line G1" or "Circ. interp. pos. CIP", and "Circ. end pos. CIP" and traverse the axes to insert a new program block.

In order for the block to be inserted, the cursor must be positioned in an empty line using the cursor key and input key.

Press the "Accept" softkey to teach-in the modified or new program block.

### Note

All defined axes are "taught in" in the first teach-in block. In all additional teach-in blocks, only axes modified by axis traversing or manual input are "taught in".

If you exit teach-in mode, this sequence begins again.

### Operating mode or operating area switchover

If you switch to another operating mode or operating area in teach-in mode, the position changes will be canceled and teach-in mode will be cleared.

# 11.3 Inserting a block

You have the option of traversing the axes and writing the current actual values directly to a new position block.

# Requirement

"AUTO" mode: The program to be edited is selected.

# Proceed as follows

Machine	1.	Select the "Machine" operating area.
AUTO	2.	Press the <auto> or <mda> key.</mda></auto>
MDA		
TEACH IN	3.	Press the <teach in=""> key.</teach>
treach prog.	4.	Press the "Teach prog." softkey.
	5.	Traverse the axes to the relevant position.
Teach	6.	Press the "Teach position" softkey.
position		A new program block with the current actual position values will be created.

# 11.3.1 Input parameters for teach-in blocks

# Parameters for teach-in of position and teach-in of G0, G1, and circle end position CIP

Parameter	Description
х	Approach position in X direction
Υ	Approach position in Y direction
Z	Approach position in Z direction
F	Feedrate (mm/r; mm/min) - only for teach-in of G1 and circle end position CIP
U	

11.3 Inserting a block

# Parameters for teach-in of circle intermediate position CIP

Parameter	Description
I	Coordinate of the circle center point in the X direction
J	Coordinate of the circle center point in the Y direction
К	Coordinate of the circle center point in the Z direction

# Transition types for teach-in of position and teach-in of G0 and G1, and ASPLINE

The following parameters are offered for the transition:

Parameter	Description
G60	Exact stop
G64	Corner rounding
G641	Programmable corner rounding
G642	Axis-specific corner rounding
G643	Block-internal corner rounding
G644	Axis dynamics corner rounding

# Motion types for teach-in of position and teach-in of G0 and G1

The following motion parameters are offered:

Parameter	Description
CP	Path-synchronous
PTP	Point-to-point
PTPG0	Only G0 point-to-point

## Transition behavior at the beginning and end of the spline curve

The following motion parameters are offered:

Parameter	eter Description		
Start			
BAUTO	Automatic calculation		
BNAT	Curvature is zero or natural	-	
BTAN	Tangential		
End			
EAUTO	Automatic calculation		
ENAT	Curvature is zero or natural		
ETAN	Tangential		

# 11.4 Teach-in via window

### 11.4.1 General

The cursor must be positioned on an empty line.

The windows for pasting program blocks contain input and output fields for the actual values in the WCS. Depending on the default setting, selection fields with parameters for motion behavior and motion transition are available.

When first selected, the input fields are empty unless axes were already traversed before the window was selected.

All data from the input/output fields are transferred to the program via the "Accept" softkey.

# Precondition

"AUTO" mode: The program to be edited is selected.

### Procedure

Machine	1	Select the "Machine" operating area.
AUTO	2.	Press the <auto> or <mda> key.</mda></auto>
MDA		
TEACH IN	3.	Press the <teach in=""> key.</teach>
V Teach prog.	4.	Press the "Teach prog." softkey.
	5.	Use the cursor and input keys to position the cursor at the desired point in the program.
		If an empty row is not available, insert one.
Rap. tra. GO	6.	Press the softkeys "Rap. tra. G0", "Straight line G1", or Circ. interm. pos. CIP" and "Circ. end pos. CIP".
Circ. end pos. CIP		The relevant windows with the input fields are displayed.
	7.	Traverse the axes to the relevant position.

### Teaching in a program

### 11.4 Teach-in via window

Accept	8.	Press the "Accept" softkey. A new program block will be inserted at the cursor position.
X Cancel		- OR - Press the "Cancel" softkey to cancel your input.

# 11.4.2 Teach in rapid traverse G0

You traverse the axes and teach-in a rapid traverse block with the approached positions.

### Note

### Selection of axes and parameters for teach-in

You can select the axes to be included in the teach-in block in the "Settings" window. You also specify here whether motion and transition parameters are offered for teach-in.

# 11.4.3 Teach in straight G1

You traverse the axes and teach-in a machining block (G1) with the approached positions.

#### Note

### Selection of axes and parameters for teach-in

You can select the axes to be included in the teach-in block in the "Settings" window. You also specify here whether motion and transition parameters are offered for teach-in.

# 11.4.4 Teaching in circle intermediate and circle end point CIP

Enter the intermediate and end positions for the circle interpolation CIP. You teach-in each of these separately in a separate block. The order in which you program these two points is not specified.

### Note

Make sure that the cursor position does not change during teach-in of the two positions.

You teach-in the intermediate position in the "Circle intermediate position CIP" window.

You teach-in the end position in the "Circle end position CIP" window.

The intermediate or interpolation point is only taught-in with geometry axes. For this reason, at least 2 geometry axes must be set up for the transfer.

#### Note

### Selection of axes for teach in

You can select the axes to be included in the teach-in block in the "Settings" window.

# 11.4.5 Teach-in A spline

For Akima-spline interpolation, you enter interpolation points that are connected by a smooth curve.

Enter a starting point and specify a transition at the beginning and end.

You teach-in each interpolation point via "Teach in of position".



#### Software option

You require the "Spline-Interpolation" option for A Spline interpolation.

#### Note

The relevant option bit must be set to enable you to program a spline interpolation.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

11.4 Teach-in via window

# Procedure

Machine	1.	Select the "Machine" operating area.
AUTO	2.	Press the <auto> or <mda> key.</mda></auto>
TEACH IN	3.	Press the <teach in=""> key.</teach>
teach prog.	4.	Press the "Teach prog." softkey.
ASPLINE	5.	Press the ">>" and "ASPLINE" softkeys. The "Akima-spline" window opens with the input fields.
	6.	Traverse the axes to the required position and if necessary, set the transition type for the starting point and end point.
Accept	7.	Press the "Accept" softkey. A new program block will be inserted at the cursor position. - OR -
Cancel		Press the "Cancel" softkey to cancel your input.

### Note

### Selection of axes and parameters for teach-in

You can select the axes to be included in the teach-in block in the "Settings" window.

You also specify here whether motion and transition parameters are offered for teach-in.

## 11.5 Editing a block

You can only overwrite a program block with a teach-in block of the same type.

The axis values displayed in the relevant window are actual values, not the values to be overwritten in the block.

#### Note

If you wish to change any variable in a block in the program block window other than the position and its parameters, then we recommend alphanumerical input.

## Requirement

The program to be edited is selected.

## Proceed as follows

Machine	1.	Select the "Machine" operating area.
	2.	Press the <auto> or <mda> key.</mda></auto>
TEACH IN	3.	Press the <teach in=""> key.</teach>
teach prog.	4.	Press the "Teach prog." softkey.
	5.	Click the program block to be edited.
Teach position	6.	Press the relevant softkey "Teach position, "Rap. tra. G0", "Straight line G1", or "Circ. interm. pos. CIP", and "Circ. end pos. CIP".
		The relevant windows with the input fields are displayed.
Accept	7.	Traverse the axes to the desired position and press the "Accept" softkey.
		The program block is taught with the modified values. - OR -
X Cancel		Press the "Cancel" softkey to cancel the changes.

#### 11.6 Selecting a block

You have the option of setting the interrupt pointer to the current cursor position. The next time the program is started, processing will resume from this point.

With teach-in, you can also change program areas that have already been executed. This automatically disables program processing.

You must press reset or select a block to resume the program.

## Requirement

The program to be processed is selected.

1.

6.

## Proceed as follows



- Select the "Machine" operating area.
- 2. Press the <AUTO> key.



- 3. Press the <TEACH IN> key.
- 4. NC proa.
- Press the "Teach prog." softkey.
- 5. Place the cursor on the desired program block.
- Block selection
- Press the "Block selection" softkey.

## 11.7 Deleting a block

You have the option of deleting a program block entirely.

### Requirement

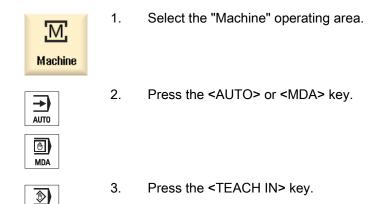
"AUTO" mode: The program to be processed is selected.

## Proceed as follows

Machine	1.	Select the "Machine" operating area.
AUTO	2.	Press the <auto> or <mda> key.</mda></auto>
TEACH IN	3.	Press the <teach in=""> key.</teach>
teach prog.	4.	Press the "Teach prog." softkey.
	5.	Click the program block to be deleted.
	6.	Press the ">>" and "Delete block" softkeys. The program block on which the cursor is positioned is deleted.

In the "Settings" window, you define which axes are to be included in the teach-in block and whether motion-type and continuous-path mode parameters are to be provided.

## Proceed as follows



TEACH IN

teach prog.	4.	Press the "Teach prog." softkey.
	5.	Press the ">>" and "Settings" softkeys. The "Settings" window appears.
Settings		
Accept	6.	Under "Axes to be taught" and "Parameters to be taught", select the check boxes for the relevant settings and press the "Accept" softkey to confirm the settings.

# **Tool management**

## 12.1 Lists for the tool management

All tools and also all magazine locations that have been created or configured in the NC are displayed in the lists in the Tool area.

All lists display the same tools in the same order. When switching between the lists, the cursor remains on the same tool in the same screen segment.

The lists have different parameters and softkey assignments. Switching between lists is a specific change from one topic to the next.

• Tool list

All parameters and functions required to create and set up tools are displayed.

• Tool wear

All parameters and functions that are required during operation, e.g. wear and monitoring functions, are listed here.

• Magazine

You will find the magazine and magazine location-related parameters and functions for the tools/magazine locations here.

Tool data OEM

This list can be freely defined by the OEM.

#### Sorting the lists

You can change the sorting within the lists:

- according to the magazine
- according to the name (tool identifier, alphabetic)
- according to the tool type
- according to the T number (tool identifier, numerical)

12.1 Lists for the tool management

## Filtering the lists

You can filter the lists according to the following criteria:

- only display the first cutting edge
- only tools that are ready to use
- only tools that have reached the pre-alarm limit
- only locked tools

## Search functions

You have the option of searching through the lists according to the following objects:

- Tool
- Magazine location
- Empty location

## 12.2 Magazine management

Depending on the configuration, the tool lists support a magazine management.

#### Magazine management functions

- Press the "Magazine" horizontal softkey to obtain a list that displays tools with magazinerelated data.
- The Magazine / Magazine location column is displayed in the lists.
- In the default setting, the lists are displayed sorted according to magazine location.
- The magazine selected via the cursor is displayed in the title line of each list.
- The "Magazine selection" vertical softkey is displayed in the tool list.
- You can load and unload tools to and from a magazine via the tool list.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

12.3 Tool types

## 12.3 Tool types

A number of tool types are available when you create a new tool. The tool type determines which geometry data are required and how they will be computed.

## **Tool types**

Тур	Identifier	Tool position
<b>120</b> ·	End mill	₩
140 ·	Facing tool	
<b>200</b> ·	Twist drill	8
<b>220</b> ·	Center drill	V
<b>240</b> ·	· Tap	
710 ·	3D milling probe	
711 ·	Edge tracer	ę
110 ·	Cylindr. ball end	U
111 ·	Conical ball end	U
121 ·	End mill corner round.	U
155 ·	Bevelled cutter	
156 ·	Beveled cutter corner	U
157 ·	Tap. die-sink. cutter	$\square$

Figure 12-1 Example of Favorites list

New to	00	I - milling cutter	
Тур		Identifier Too	l position
100	-	Milling tool	₩
110	-	Cylindr. ball end	U
111	-	Conical ball end	U
120	-	End mill	
121	-	End mill corner round.	U
130	-	Angle head cutter	5
131	-	Corn.round.ang.hd.cut	5
140	-	Facing tool	
145	-	Thread cutter	D
150	-	Side mill	⋣
151	-	Saw	
155	-	Bevelled cutter	
156	-	Beveled cutter corner	$\mathbb{U}$
157	-	Tap. die-sink. cutter	$\mathbb{U}$
160	-	Drill&thread cut.	罪

Figure 12-2 Available tools in the "New tool - milling cutter" window

12.3 Tool types

New tool - drill				
Тур	Identifier	Tool position		
200	- Twist drill	8		
205	- Solid drill	8		
210	- Boring bar	<b>.</b>		
220	- Center drill	V		
230	- Countersink	₩		
231	- Counterbore	Ŵ		
240	- Тар	*		
241	- Fine tap	*		
242	- Tap, Whitworth	*		
250	- Reamer	<b>b</b>		

Figure 12-3 Available tools in the "New tool - drill" window

New tool - special tools				
Тур		Identifier	Tool position	
700	-	Groove saw	Ш.	
710	-	3D milling probe	6	
711	-	Edge tracer	÷	
730	-	Stop	•	
900	-	Auxiliary tools	Û	

Figure 12-4 Available tools in the "New tool - special tools" window

## See also

Changing a tool type (Page 510)

# 12.4 Tool dimensioning

This section provides an overview of the dimensioning of tools.

## **Tool types**

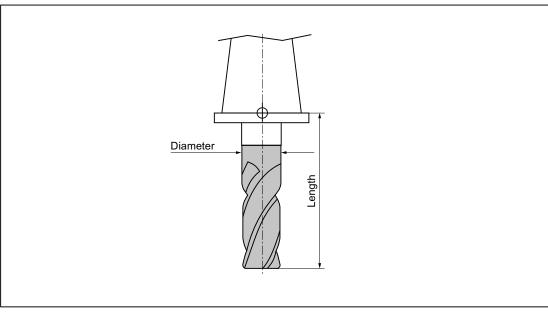


Figure 12-5 End mill (Type 120)

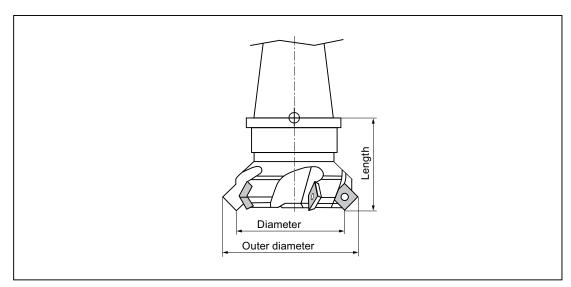


Figure 12-6 Face mill (Type 140)

Tool management 12.4 Tool dimensioning

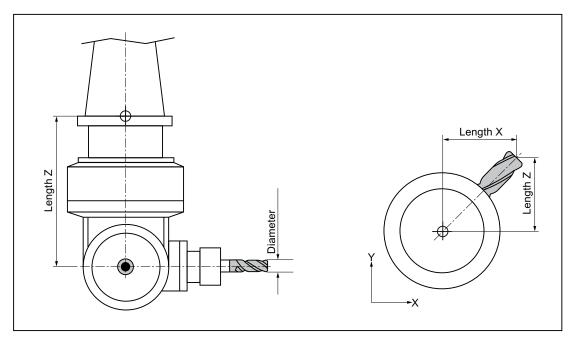


Figure 12-7 Angle head cutter (Type 130)

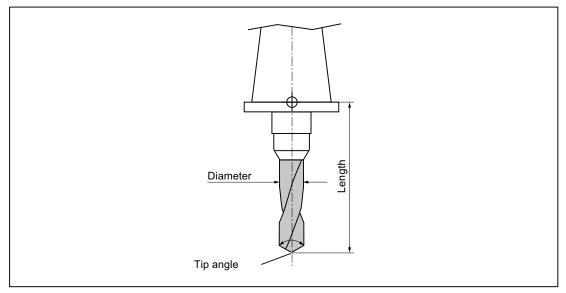


Figure 12-8 Drill (Type 200)

12.4 Tool dimensioning

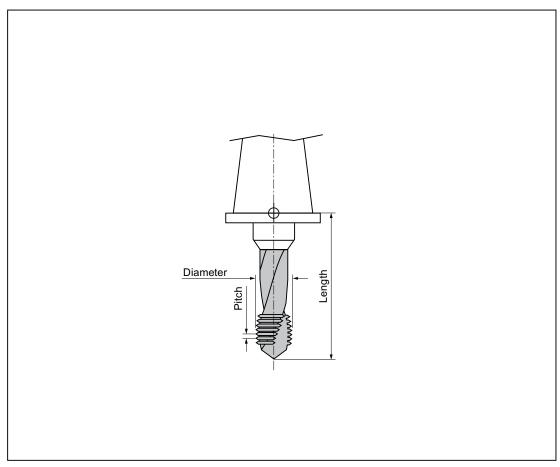


Figure 12-9 Tap (Type 240)

## Tool management 12.4 Tool dimensioning

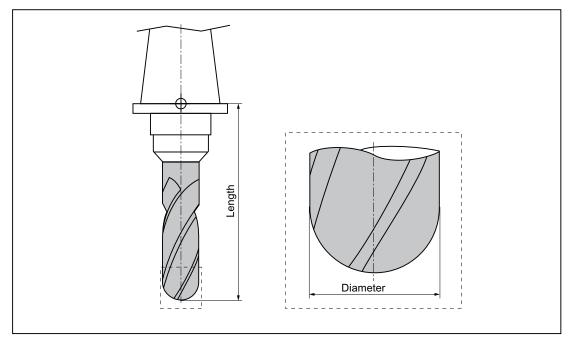


Figure 12-10 3D tool with an example of a cylindrical die-sinking cutter (Type 110)

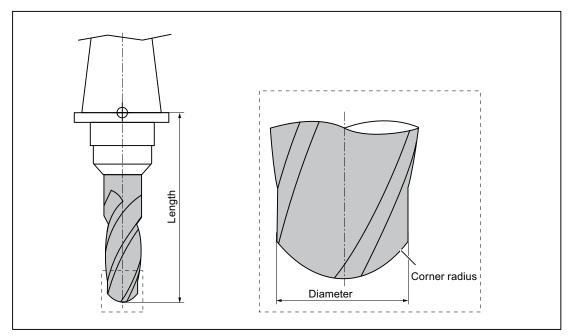


Figure 12-11 3D tool type with an example of a ballhead cutter (Type 111)

12.4 Tool dimensioning

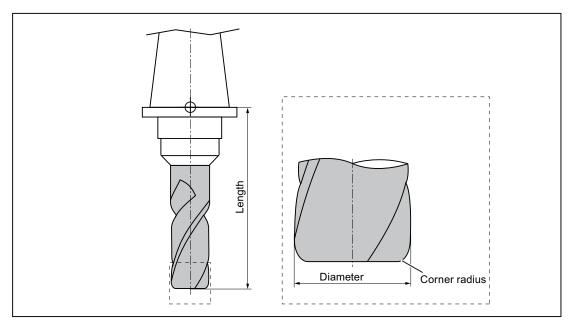


Figure 12-12 3D tool with an example of an end mill with corner rounding (Type 121)

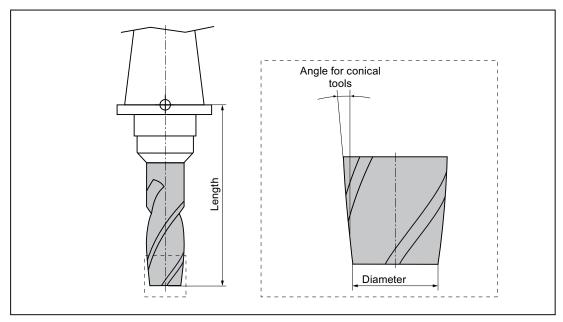


Figure 12-13 3D tool type with an example of a bevel cutter (Type 155)

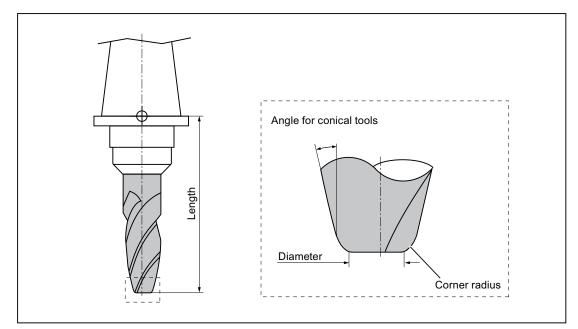


Figure 12-14 3D tool with an example of a bevel cutter with corner rounding (Type 156)

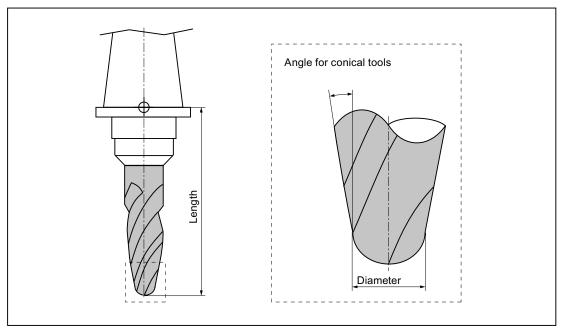


Figure 12-15 3D tool with an example of a tapered die-sinking cutter (Type 157)

12.4 Tool dimensioning

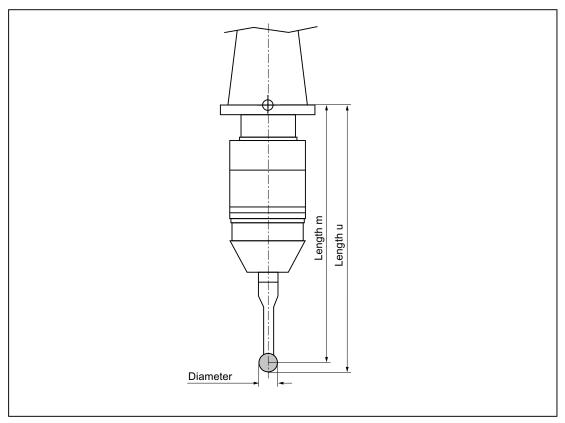


Figure 12-16 Electronic workpiece probe



#### Machine manufacturer

The tool length of the workpiece probe is measured to the center of the ball (length m) or to the ball circumference (length u). Please refer to the machine manufacturer's specifications.

#### Note

An electronic workpiece probe must be calibrated before use.

## 12.5 Tool list

All parameters and functions that are required to create and set up the tools are displayed in the tool list.

Each tool is uniquely identified by the tool identifier and the replacement tool number.

## **Tool parameters**

Column heading	Meaning
Location	Magazine/location number
	The magazine location numbers
	The magazine number is specified first, followed by the location number in the magazine.
	If there is only one magazine, only the location number is displayed.
BS	
	Load position in the load magazine
ц.	The following icons can also be displayed for other magazine types (e.g. for a chain):
	Spindle location as an icon.
	<ul> <li>Locations for gripper 1 and gripper 2 (applies only when a spindle with dual gripper is used) as icons.</li> </ul>
* If activated in magazine selection	dual gripper is used) as icons.
Туре	Tool type
	Specific tool offset data is displayed depending on the tool type
	(represented as an icon).
SELECT	You have the option of changing the tool type using the <select> key.</select>
Tool name	The tool is identified by the name and the replacement tool number. You may enter the names as text or numbers.
ST	Replacement tool number (for replacement tool strategy)
D	Cutting edge number
Length	Tool length
	Geometry data, length
Radius	Tool radius
Tip angle or Pitch	Tip angle for Type 200 - twist drill and Type 220 - centering tool and Type 230 countersink
	Pitch for Type 240 - tap

#### Tool management

12.5 Tool list

Column heading	Meaning
N	Number of teeth for Type 100 - milling tool, Type 110 - ball end mill for cylindrical die-sinking cutter, Type 111 - ball end mill or tapered die- sinking cutter, Type 120 - end mill, Type 121 - end mill with corner rounding, Type 130 - angle head cutter, Type 131 - angle head cutter with corner rounding, Type 140 - facing tool, Type 150 - side mill, Type 155 - bevel cutter, Type 156 - bevel cutter with corner rounding and Type 157 - tapered die-sinking cutter.
U	Direction of spindle rotation
స	Coolant supply 1 and 2 (e.g. internal and external cooling) can be switched on and switched off. The coolant supply at the machine does not necessarily have to be set- up.
M1 - M4	Other tool-specific functions such as additional coolant supply, monitoring functions for speed, tool breakage, etc.

You use the configuration file to specify the selection of parameters in the list.



#### Software option

In order to be able to manage the parameter spindle direction of rotation, coolant and tool-specific functions (M1-M4), you require the "ShopMill/ShopTurn" option.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

## Icons in the tool list

Icon/ Designation		Meaning
Tool type		
Red "X"	×	The tool is disabled.
Yellow triangle pointing downward	▽	The prewarning limit has been reached.
Yellow triangle pointing	Δ	The tool is in a special state.
upward		Place the cursor on the marked tool. A tooltip provides a short description.
Green border		The tool is preselected.

12.5 Tool list

Icon/ Designation		Meaning
Magazine/location number		
Green double arrow	4	The magazine location is positioned at the change position.
Gray double arrow (configurable)	÷	The magazine location is positioned at the loading position.
Red "X"	×	The magazine location is disabled.

## Procedure



1. Select the "Parameter" operating area.

Parameter



Press the "Tool list" softkey. The "Tool list" window is opened.

## See also

Displaying tool details (Page 508) Changing a tool type (Page 510)

2.

## 12.5.1 Additional data

The following tool types require geometry data that is not included in the tool list display.

## Tools with additional geometry data

Tool type	Additional parameters
111 Conical ballhead cutter	Corner radius
121 End mill with corner rounding	Corner radius
130 Angle head cutter	Geometry length (length X, length Y, length Z)
	Wear length ( $\Delta$ length X, $\Delta$ length Y, $\Delta$ length Z)
	Adapter length (length X, length Y, length Z)
	V (direction vector 1 - 6)
	Vector X, vector Y, vector Z

12.5 Tool list

Tool type	Additional parameters	
131 Angle head cutter with	Geometry length (length X, length Y, length Z)	
corner rounding	Corner radius	
	Wear length ( $\Delta$ length X, $\Delta$ length Y, $\Delta$ length Z)	
	Adapter length (length X, length Y, length Z)	
	V (direction vector 1 - 6)	
	Vector X, vector Y, vector Z	
140 Face milling	External radius	
	Tool angle	
155 Bevel cutter	Taper angle	
156 Bevel cutter with corner	Corner radius	
rounding	Taper angle	
157 Conical die-milling cutter	Taper angle	

You can use the configuration file to specify the data to be displayed for specific tool types in the "Additional Data" window.



#### Machine manufacturer

The tool list is opened.

Please refer to the machine manufacturer's specifications.

#### Procedure

Tool list	

Further data 1.

2.

3.

In the list, select an appropriate tool, e.g. an angle head cutter.
Press the "Additional data" softkey.
The "Additional data - ..." window is opened.
The "Additional data" softkey is only active if a tool for which the "Additional Data" window is configured is selected.

## 12.5.2 Creating a new tool

When creating a new tool, the "New Tool - Favorites" window offers you a number of selected tool types, known as "favorites".

If you do not find the desired tool type in the favorites list, then select the milling, drilling or special tool via the corresponding softkeys.

## Procedure

Tool list	1.	The tool list is opened.
	2.	Place the cursor in the tool list at the position where the new tool should be stored.
		For this, you can select an empty magazine location or the NC tool memory outside of the magazine.
		You may also place the cursor on an existing tool in the NC tool memory region. Data from the displayed tool will not be overwritten.
New tool	3.	Press the "New tool" softkey.
Favorites		The "New Tool - Favorites" window appears on the screen.
		- OR -
Cutters 100-199		If you want to create a tool that is not in the "Favorites" list, press the "Cutters 100-199", "Drills 200-299" or "Sp. tools 700-900" softkey.
		The "New Tool - Milling Cutter", "New Tool - Drill", or "New Tool -
Spec.tool 700-900		Special Tools" window opens.
	4.	Select the tool by placing the cursor on the corresponding icon.
$\checkmark$	5.	Press the "OK" softkey.
ОК		The tool is added to the tool list with a predefined name. If the cursor is located on an empty magazine location in the tool list, then the tool is loaded to this magazine location.

The tool creation sequence can be defined differently.

### Multiple load points

If you have configured several loading points for a magazine, then the "Loading Point Selection" window appears when a tool is created directly in an empty magazine location or when the "Load" softkey is pressed.

Select the required load point and confirm with the "OK" softkey.

### 12.5 Tool list

#### Additional data

If configured accordingly, the "New Tool" window opens after the required tool has been selected and confirmed with "OK".

You can define the following data in this window:

- Names
- Tool location type
- Size of tool

#### References

For a description of configuration options, refer to the Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

### 12.5.3 Measuring the tool

You can measure the tool offset data for the individual tools directly from the tool list.

Note

Tool measurement is only possible with an active tool.

## Procedure

- Tool 1. list
  - 1. The tool list is opened.
- Tool measure
- 2. Select the tool that you want to measure in the tool list and press the "Measure tool" softkey.

You jump to the "JOG" operating area and the tool to be measured is



entered in the "T" field in the "Length Manual" screen.3. Select the cutting edge number D and the number of t



- Select the cutting edge number D and the number of the replacement tool ST of the tool.
- 4. Approach the workpiece in the Z direction, scratch it with a turning spindle and enter the set position Z0 of the workpiece edge.



Press the "Set length" softkey.
 The tool length is calculated automatically and entered in the tool list.

## 12.5.4 Managing several cutting edges

In the case of tools with more than one cutting edge, a separate set of offset data is assigned to each cutting edge. The number of possible cutting edges depends on the controller configuration.

Tool cutting edges that are not required can be deleted.

## Procedure

iv Tool list	1.	The tool list is opened.		
	2.	Position the cursor on the tool for which you would like to store more cutting edges.		
Edges	3.	Press the "Edges" softkey in the "Tool list".		
New	4.	Press the "New cutting edge" softkey.		
cuttgEdge		A new data set is stored in the list.		
		The cutting edge number is incremented by one and the offset data is assigned the values of the cutting edge on which the cursor is positioned.		
	5.	Enter the offset data for the second cutting edge.		
	6.	Repeat this process if you wish to create more tool edge offset data.		
Delete cut. edge	7.	Position the cursor on the cutting edge that you want to delete and press the "Delete cutting edge" softkey.		
		The data set is deleted from the list. The first tool cutting edge cannot be deleted.		

## 12.5.5 Delete tool

Tools that are no longer in use can be deleted from the tool list for a clearer overview.

## Procedure



- 1. The tool list is opened.
- 2. Place the cursor on the tool that you would like to delete.



Use this softkey to delete the tool. If the tool is in a magazine location, it is unloaded and then deleted.

#### Multiple load points - tool in magazine location

If you have configured several loading points for a magazine, then the "Loading Point Selection" window appears after pressing the "Delete tool" softkey.

Select the required load point and press the "OK" softkey to unload and delete the tool.

## 12.5.6 Loading and unloading tools

You can load and unload tools to and from a magazine via the tool list. When a tool is loaded, it is taken to a magazine location. When it is unloaded, it is removed from the magazine and stored in the NC memory.

When you are loading a tool, the application automatically suggests an empty location. You may also directly specify an empty magazine location.

You can unload tools from the magazine that you are not using at present. HMI then automatically saves the tool data in the NC memory.

Should you want to use the tool again later, simply load the tool with the tool data into the corresponding magazine location again. Then the same tool data does not have to be entered more than once.

#### Procedure



- The tool list is opened.
- 2. Place the cursor on the tool that you want to load into the magazine (if the tools are sorted according to magazine location number you will find it at the end of the tool list).



1.

Press the "Load" softkey.

The "Load to..." window opens. The "... location" field is initialized with the number of the first empty magazine location.



4.

Press the "OK" softkey to load the tool into the suggested location.

- OR -

Enter the location number you require and press the "OK" softkey.

- OR -

Spindle

0K

Press the "Spindle" softkey.

The tool is loaded into the specified magazine location or spindle.

#### Several magazines

If you have configured several magazines, the "Load to ..." window appears after pressing the "Load" softkey.

If you do not want to use the suggested empty location, then enter your desired magazine and magazine location. Confirm your selection with "OK".

#### Multiple load points

If you have configured several loading points for a magazine, then the "Loading Point Selection" window appears after pressing the "Load" softkey.

Select the required loading point and confirm with "OK".

#### Unloading tools

1. Place the cursor on the tool that you would like to unload from the magazine and press the "Unload" softkey.



2.

3.

Select the required load point in the "Loading Point Selection" window. Confirm your selection with "OK".



× Cancel

Unload

- OR -Undo your selection with "Cancel".

#### 12.5.7 Selecting a magazine

You can directly select the buffer memory, the magazine, or the NC memory.

12.5 Tool list

## Procedure

iv Tool list	1.	The tool list is opened.	
Magazine selection	2.	Press the "Magazine selection" softkey.	
		If there is only one magazine, you will move from one area to the next (i.e. from the buffer memory to the magazine, from the magazine to the NC memory, and from the NC memory back to the buffer memory) each time you press the softkey. The cursor is positioned at the beginning of the magazine each time. - OR -	
Go to		If there is more than one magazine, the "Magazine Selection" window opens. Position the cursor on the desired magazine in this window and press the "Go to" softkey.	
		The cursor jumps directly to the beginning of the specified magazine.	

## **Hiding magazines**

Magaa	Magazine selection		
ش	Machine		
<b>T</b>	WZ-Zwischenspeicher		
- 17	revolver10		
打	revolver20		
- 77	kette10		
<u>NC</u>	NC memory		



Deactivate the checkbox next to the magazines that you do not want to appear in the magazine list.

The magazine selection behavior with multiple magazines can be configured in different ways.

203
V

## Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### References

For a description of configuration options, refer to the Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sI

## 12.6 Tool wear

All parameters and functions that are required during operation are contained in the tool wear list.

Tools that are in use for long periods are subject to wear. You can measure this wear and enter it in the tool wear list. The controller then takes this information into account when calculating the tool length or radius compensation. This ensures a consistent level of accuracy during workpiece machining.

You can automatically monitor the tools' working times via the workpiece count, tool life or wear.

In addition, you can disable tools when you no longer wish to use them.

## **Tool parameters**

Column heading	Meaning	
Location	Magazine/location number	
	<ul> <li>The magazine location numbers. The magazine number is specified first, followed by the location number in the magazine.</li> <li>If there is only one magazine, only the location number is displayed.</li> </ul>	
BS	Load position in the load magazine	
	The following icons can also be displayed for other magazine types (e.g. for a chain):	
#	Spindle location as an icon.	
> <	<ul> <li>Locations for gripper 1 and gripper 2 (applies only when a spindle with dual gripper is used) as icons.</li> </ul>	
* If activated in magazine selection		
Туре	Tool type	
	Depending on the tool type (represented by an icon), certain tool offset data is enabled.	
Tool name	The tool is identified by the name and the replacement tool number. You can enter the name as text or number.	
ST	Replacement tool number (for replacement tool strategy).	
D	Cutting edge number	
Δ Length	Length wear	
Δ Radius	Radius wear	

## 12.6 Tool wear

Column heading	Meaning	
ТС	Selection of tool monitoring - by tool life (T)	
	- by count (C)	
	- by wear (W)	
	The wear monitoring is configured via a machine data item.	
	Please refer to the machine manufacturer's specifications.	
Tool life	Tool life	
Workpiece count	Number of workpieces	
Wear *	Tool wear	
*Parameter depends on selection in TC		
Setpoint	Setpoint for tool life, workpiece count, or wear.	
Prewarning limit	Specification of the tool life, workpiece count or wear at which a warning is displayed.	
G	The tool is disabled when the checkbox is selected.	

## Icons in the wear list

Icon/ Marking		Meaning	
Tool type			
Red "X"	X	The tool is disabled.	
Yellow triangle pointing downward	▽	The prewarning limit has been reached.	
Yellow triangle pointing	Δ	The tool is in a special state.	
upward		Place the cursor on the marked tool. A tooltip provides a short description.	
Green border		The tool is preselected.	
Magazine/location number	Magazine/location number		
Green double arrow	<b></b>	The magazine location is positioned at the change position.	
Gray double arrow (configurable)	÷.	The magazine location is positioned at the loading position.	
Red "X"	×	The magazine location is disabled.	

## Procedure



wear

- 1. Select the "Parameter" operating area.
- 2. Press the "Tool wear" softkey.

#### See also

Displaying tool details (Page 508) Changing a tool type (Page 510)

## 12.6.1 Reactivating a tool

You can replace disabled tools or make them ready for use again.

#### Preconditions

In order to reactivate a tool, the monitoring function must be activated and a setpoint must be stored.

#### Procedure



- 1. The tool wear list is opened.
- 2. Position the cursor on the disabled tool which you would like to reuse.



Press the "Reactivate" softkey.
 The value entered as the setpoint is entered as the new tool life or workpiece count.

The disabling of the tool is canceled.

#### Reactivating and positioning

When the "Reactivate with positioning" function is configured, the selected tool's magazine location will also be positioned at a loading point. You can exchange the tool.

### Reactivation of all monitoring types

When the "Reactivation of all monitoring types" function is configured, all the monitoring types set in the NC for a tool are reset during reactivation.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

### References

Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

#### Multiple load points

If you have configured several loading points for a magazine, then the "Loading Point Selection" window appears after pressing the "Load" softkey.

Select the required load point and confirm with the "OK" softkey.

## 12.7 Tool data OEM

You have the option of configuring the list according to your requirements:

### References

For more information, see the following references: Commissioning Manual SINUMERIK Operate / SINUMERIK 840D sl

## Procedure



1.

2.

Select the "Parameter" operating area.



Press the "OEM Tool" soft key.

12.8 Magazine

## 12.8 Magazine

Tools are displayed with their magazine-related data in the magazine list. Here, you can take specific actions relating to the magazines and the magazine locations.

Individual magazine locations can be location-coded or disabled for existing tools.

## **Tool parameters**

Column heading	Meaning	
Location	Magazine/location number	
BS	<ul> <li>The magazine location numbers. The magazine number is specified first, followed by the location number in the magazine. If there is only one magazine, only the location number is displayed.</li> <li>Load position in the load magazine</li> </ul>	
	The following additional icons can also be displayed for other magazine types (e.g. for a chain):	
₩	Spindle location as an icon.	
> <	<ul> <li>Locations for gripper 1 and gripper 2 (applies only when a spindle with dual gripper is used) as icons.</li> </ul>	
* If activated in magazine selection		
Туре	Tool type	
	Depending on the tool type (represented by an icon), certain tool offset data is enabled.	
Tool name	The tool is identified by the name and the replacement tool number. You can enter the name as text or number.	
ST	Replacement tool number (for replacement tool strategy).	
D	Cutting edge number.	
G	Disabling of the magazine location.	
Mag.loctype	Display of magazine location type.	
Tool.loctype	Display of tool location type of tool.	
Ü	Marking of a tool as oversized. The tool occupies two half locations left, two half locations right, one half location top and one half location bottom in a magazine.	
Р	Fixed location coding.	
	The tool is permanently assigned to this magazine location.	

12.8 Magazine

## Magazine list icons

Icon/		Meaning
Designation		
Tool type		
Red "X"	×	The tool is disabled.
Yellow triangle pointing downward	▽	The prewarning limit has been reached.
Yellow triangle pointing	Δ	The tool is in a special state.
upward		Place the cursor on the marked tool. A tooltip provides a short description.
Green border		The tool is preselected.
Magazine/location number		
Green double arrow		The magazine location is positioned at the change position.
Gray double arrow (configurable)	÷	The magazine location is positioned at the loading position.
Red "X"	×	The magazine location is disabled.

## Procedure



Select the "Parameter" operating area.





Press the "Magazine" softkey.

#### See also

Displaying tool details (Page 508) Changing a tool type (Page 510)

1.

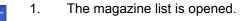
2.

#### 12.8.1 Positioning a magazine

You can position magazine locations directly on the loading point.

12.8 Magazine

### Procedure



2. Place the cursor on the magazine location that you want to position onto the load point.



Maga<sup>.</sup> zine

Press the "Position magazine" softkey.
 The magazine location is positioned on the loading point.

#### Multiple load points

If you have configured several loading points for a magazine, then the "Loading Point Selection" window appears after pressing the "Position magazine" softkey.

Select the desired loading point in this window and confirm your selection with "OK" to position the magazine location at the loading point.

## 12.8.2 Relocating a tool

Tools can be directly relocated within magazines to another magazine location, which means that you do not have to unload tools from the magazine in order to load them into a different location.

When you are relocating a tool, the application automatically suggests an empty location. You may also directly specify an empty magazine location.

#### Buffer

You have the option of relocating the tool to buffer locations.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Procedure

ह हु	Maga- zine	

- 1. The magazine list is opened.
- 2. Position the cursor on the tool that you wish to relocate to a different magazine location.



3.

Press the "Relocate" softkey.

The "... relocate from location ... to location ..." window is displayed. The "Location" field is pre-assigned with the number of the first empty magazine location.



ŌК

Press the "OK" softkey to relocate the tool to the recommended magazine location.



4.

Enter the required magazine, enter the location number and press the "OK" softkey.

- OR -

Enter the number "9998" or the number "9999" into the "... magazine" field in order to select the buffer as well as the required buffer location in the "Location" field.

- OR -

Spindle OK Press the "Spindle" softkey to load a tool into the spindle and press the "OK" softkey.

The tool is relocated to the specified magazine location, in the spindle or in the buffer.

### Several magazines

If you have set up several magazines, then the "...relocate from magazine... location... to..." window appears after pressing the "Relocate" softkey.

Select the desired magazine and location, and confirm your selection with "OK" to load the tool.

12.9 Sorting tool management lists

# 12.9 Sorting tool management lists

When you are working with many tools, with large magazines or several magazines, it is useful to display the tools sorted according to different criteria. Then you will be able to find a specific tool more quickly in the lists.

## Procedure

<b>↓</b> Parameter	1.	Select the "Parameter" operating area.
Tool list	2.	Press the "Tool list", "Tool wear" or "Magazine" softkey.
Maga- zine	3.	Press the ">>" and "Sort" softkeys.
Acc. to magazine		The lists are displayed sorted numerically according to magazine location. Tool types are used to sort tools with the same magazine location. Identical types (e.g. milling cutters), in turn, are sorted according to their radius value.
Acc. to type	4.	Press the "Acc. to type" softkey to display the tools arranged by tool type. Identical types (e.g. milling cutters) are sorted according to their radius value. - OR -
Surname		Press the "Acc. to name" softkey to display the tool names in alphabetical order. The replacement tool numbers are used to sort tools with the same
Acc. to T number		names. - OR - Press the "Acc. to T number" softkey to display the tools names sorted numerically. The list is sorted according to the specified criteria.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

Tool management

12.10 Filtering the tool management lists

## 12.10 Filtering the tool management lists

The filter function allows you to filter-out tools with specific properties in the tool management lists.

For instance, you have the option of displaying tools during machining that have already reached the pre-alarm limit in order to prepare the corresponding tools to be loaded.

#### Filter criteria

- only display the first cutting edge
- only tools that are ready to use
- only tools that have reached the pre-alarm limit
- only locked tools

#### Note

#### Multiple selection

You have the option of selecting several criteria. You will receive an appropriate message if conflicting filter options are selected.

#### Procedure

1. Select the "Parameter" operating area.





2. Press the "Tool list", "Tool wear" or "Magazine" softkey.



Press the ">>" and "Filter" softkeys.
 The "Filter" window is opened.



**OK** 

Activate the required filter criterion and press the "OK" softkey.

The tools that correspond to the selection criteria are displayed in the list.

The active filter is displayed in the window header.

12.11 Specific search in the tool management lists

## 12.11 Specific search in the tool management lists

There is a search function in all tool management lists, where you can search for the following objects:

Tools

You enter a tool name. You can narrow down your search by entering a replacement tool number.

You have the option of only entering a part of the name as search term.

#### • Magazine locations or magazines

If only one magazine is configured, then the search is only made for the magazine location.

If several magazines are configured, then it is possible to search a specific magazine location in a specific magazine or just to search in a specific magazine.

Empty locations

If the lists with the location type are used, then the empty location search is made using the location type and location size.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

Tool management

12.11 Specific search in the tool management lists

## Procedure

Parameter	1.	Select the "Parameter" operating area.
Tool list	2.	Press the "Tool list", "Tool wear" or "Magazine" softkey.
Maga- zine		
	3.	Press the ">>" and "Search" softkeys.
Search		
Tool	4.	Press the "Tool" softkey if you wish to search for a specific tool.
Magazine location		<ul> <li>OR -</li> <li>Press the "Magazine location" softkey if you wish to search for a specific magazine location or a specific magazine.</li> <li>OR -</li> </ul>
Empty location		Press the "Empty location" softkey if you wish to search for a specific empty location.

## 12.12 Displaying tool details

All of the parameters of the selected tool are listed in the "Tool details - all parameters" window.

The parameters are displayed, sorted according to the following criteria

- Tool data
- Cutting edge data
- Monitoring data

#### **Protection level**

You require access level, keyswitch 3 (protection level 4) in order to edit the parameters in the detail window.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

### Procedure

i <mark>Vienne Tool</mark> list	1.	The tool list, the wear list, the OEM tool list or the magazine is opened.
Maga- zine		
••	2. 3.	Position the cursor to the desired tool. If you are in the tool list or in the magazine, press the ">>" softkey and "Details".
Details		
		- OR -
Details		If you are in the wear list or OEM tool list, press the "Details" softkey.
		The "Tool details - all parameters" window is displayed.
		All of the available tool, cutting edge and monitoring data of the selected tool are displayed in the list.
		You can view all of the window contents using the horizontal scroll bar.
Tool data	4.	Press the "Tool data" softkey to return to the "Tool data" column.



5.

- Press the "Cutting edge data" softkey to directly go to the "Cutting edge data" column.
- 6. Press the "Monitoring data" softkey to go directly to the "Monitoring data" column.

# 12.13 Changing a tool type

## Procedure

iv Tool list	1.	The tool list, the wear list, the OEM tool list or the magazine is opened.
Maga- zine		
	2.	Position the cursor in the column "Type" of the tool that you wish to change.
$\left( \right)$	3.	Press the <select> key.</select>
SELECT		The "Tool types - Favorites" window opens.
	4.	Select the desired tool type in the list of favorites or select using the softkeys "Cutters 100-199", "Drills 200-299" or "Special tools 700-900".
	5.	Press the "OK" softkey.
OK		The new tool type is accepted and the corresponding icon is displayed in the "Type" column.

# Program management

## 13.1 Overview

You can access programs at any time via the Program Manager for execution, editing, copying, or renaming. Programs that you no longer require can be deleted to release their storage space.

#### NOTICE

#### **Execution from USB FlashDrive**

Direct execution from a USB FlashDrive is not recommended.

There is no protection against contact problems, falling out, breakage through knocking or unintentional removal of the USB FlashDrive during operation.

Disconnecting it during operation will result in the stopping of the machining and thus to the workpiece being damaged.

#### Storage for programs

Possible storage locations are:

- NC
- Local drive
- Network drives
- USB drives
- V24



#### Software options

To display the "Local drive" softkey, you require the option "Additional 256 MB HMI user memory on CF Card of the NCU" (not for SINUMERIK Operate on PCU50 or PC/PG).

#### Data exchange with other workstations

You have the following options for exchanging programs and data with other workstations:

- USB drives (e.g. USB FlashDrive)
- Network drives

#### Choosing storage locations

In the horizontal softkey bar, you can select the storage location that contains the directories and programs that you want to display. In addition to the "NC" softkey, via which the passive file system data can be displayed, additional softkeys can be displayed.

The "USB" softkey is only operational when an external storage medium is connected (e.g. USB FlashDrive on the USB port of the operator panel).

#### Structure of the directories

In the overview, the symbols in the left-hand column have the following meaning:

Directory

Program

B

All directories have a plus sign when the program manager is called for the first time.

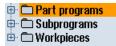


Figure 13-1 Program directory in the program manager

The plus sign in front of empty directories is removed after they have been read for the first time.

The directories and programs are always listed complete with the following information:

Name

The name may be a maximum of 24 characters long

Permissible characters include all upper-case letters (without accents), numbers, and underscores.

- Туре
  - Directory: WPD
  - Program: MPF
  - Subprogram: SPF
  - Initialization programs: INI
  - Job lists: JOB
  - Tool data: TOA
  - Magazine assignment: TMA
  - Zero points: UFR
  - R parameters: RPA
  - Global user data/definitions: GUD
  - Setting data: SEA
  - Protection zones: PRO
  - Sag: CEC
- Size (in bytes)
- Date/time (of creation or last change)

#### Active programs

Selected, i.e. active programs are identified using a green symbol.

CHAN1 Na	me Type	Length	Date	Time
🗄 🖻 Part programs	DIR		11/30/09	3:49:09 PM
🖶 🗂 Subprograms	DIR		12/02/09	11:24:33 AM
🖻 🗁 Workpieces	DIR		12/02/09	2:53:07 PM
🖶 🖻 DREHEN1	WPD		12/02/09	8:40:58 AM
🖶 🗖 666	WPD		12/01/09	12:03:39 PM
🖶 🖻 JOBSHOP_MEHRK	WPD		12/03/09	9:18:27 AM
🖶 🖻 MEHR	WPD		11/30/09	3:49:23 PM
🖶 🖻 MEHRKANAL	WPD		12/02/09	12:47:20 PM
🖶 💼 SIM_CHESS_KING	WPD		11/30/09	3:49:14 PM
🐵 🖻 SIM_CHESS_LADY	_26 WPD		11/30/09	3:49:14 PM
🖶 🖻 SIM_CHESS_TOWE	R WPD		11/30/09	3:49:15 PM
🖶 🖻 SIM_ZYK_T_26	WPD		11/30/09	3:49:17 PM
🖨 🗁 SWOB	WPD		12/03/09	8:39:49 AM
💷 🖻 UT	MPF	205	12/03/09	3:22:48 PM
🖶 🗂 TEMP	WPD		11/30/09	3:49:33 PM

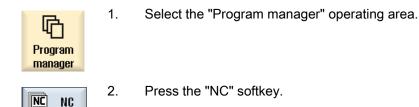
Figure 13-2 Active program shown in green

## 13.1.1 NC memory

The complete NC working memory is displayed along with all tools and the main programs and subroutines.

You can create further subdirectories here.

#### Proceed as follows



### 13.1.2 Local drive

Workpieces, main and subprograms are displayed that are saved in the user memory of the CF-Card or on the local hard disk.

For archiving, you have the option of mapping the structure of the NC memory system or to create your own archiving system.

You can create any number of subdirectories here, in which to store any files (e.g. text files with notes).



#### Software options

To display the "Local drive" softkey, you require the option "Additional 256 MB HMI user memory on CF Card of the NCU" (not for SINUMERIK Operate on PCU50 or PC/PG).

#### Procedure



- 1. Select the "Program manager" operating area.
- Local 2. Pres drive
  - Press the "Local drive" software key.

On the local drive, you have the option of mapping the directory structure of the NC memory. This also simplifies the search sequence.

## Procedure



The local drive is selected.

- CHAN1 CHAN1 S New Directory
- . Position the cursor on the main directory.
- Press the "New" and "Directory" softkeys. The "New Directory" window opens.



 In the "Name" entry field, enter "mpf.dir", "spf.dir" and "wks.dir" and press the "OK" softkey.
 The directories "Part programs", "Subprograms" and "Workpieces" are created below the main directory.

### 13.1.3 USB drives

USB drives enable you to exchange data. For example, you can copy to the NC and execute programs that were created externally.

#### NOTICE

#### **Execution from USB FlashDrive**

Direct execution from the USB FlashDrive is not recommended.

### Procedure



1. Select the "Program manager" operating area.



2. Press the "USB" softkey.

#### Note

The "USB" softkey can only be operated when a USB FlashDrive is inserted in the front interface of the operator panel.

13.2 Opening and closing the program

#### 13.2 Opening and closing the program

To view a program in more detail or modify it, open the program in the editor.

With programs that are in the NCK memory, navigation is already possible when opening. The program blocks can only be edited when the program has been opened completely. You can follow the opening of the program in the dialog line.

With programs that are opened via local network, USB FlashDrive or network connections, navigation is only possible when the program has been opened completely. A progress message box is displayed when opening the program.

### Procedure



- 1. Select the "Program manager" operating area.
- 2. Select the desired storage location and position the cursor on the program that you would like to edit.



3.

Press the "Open" softkey.





Press the <INPUT> key.

- OR -

- OR -

Press the <Cursor right> key.



- OR -

Double-click the program.

The selected program is opened in the "Editor" operating area.



NC Select

4.

Press the "NC Select" softkey to switch to the "Machine" operating area and begin execution.

When the program is running, the softkey is deactivated.

Now make the necessary program changes.

13.2 Opening and closing the program

#### Closing the program

Exit	

Press the ">>" and "Exit" softkeys to close the program and editor again.

- OR -



If you are at the start of the first line of the program, press the <Cursor left> key to close the program and the editor.



To reopen a program you have exited with "Close", press the "Program" key.

#### Note

A program does not have to be closed in order for it to be executed.

## 13.3 Executing a program

When you select a program for execution, the controller automatically switches to the "Machine" operating area.

#### **Program selection**

Select the workpieces (WPD), main programs (MPF) or subprograms (SPF) by placing the cursor on the desired program or workpiece.

For workpieces, the workpiece directory must contain a program with the same name. This program is automatically selected for execution (e.g. when you select the workpiece SHAFT.WPD, the main program SHAFT.MPF is automatically selected).

If an INI file of the same name exists (e.g. SHAFT.INI), it will be executed once at the first part program start after selection of the part program. Any additional INI files are executed in accordance with machine data MD11280 \$MN\_WPD\_INI\_MODE.

MD11280 \$MN\_WPD\_INI\_MODE=0:

The INI file with the same name as the selected workpiece is executed. For example, when you select SHAFT1.MPF, the SHAFT1.INI file is executed upon <CYCLE START>.

MD11280 \$MN\_WPD\_INI\_MODE=1:

All files of type SEA, GUD, RPA, UFR, PRO, TOA, TMA and CEC which have the same name as the selected main program are executed in the specified sequence. The main programs stored in a workpiece directory can be selected and processed by several channels.



#### Machine manufacturer

 $\mathcal{S}$  Please refer to the machine manufacturer's specifications.

#### Procedure



- 1. Select the "Program Manager" operating area.
- 2. Select the desired storage location and position the cursor on the workpiece/program that you would like to execute.

Select

3.

Press the "Select" softkey.

The controller switches automatically into the "Machine" operating area.

- OR -

#### 13.3 Executing a program

Ex-	If the selected program is already opened in the "Program" operating area, press the "Execute NC" softkey.
	Press the <cycle start=""> key.</cycle>
CYCLE START	Execution of the workpiece is started.

#### Note

Only workpieces/programs that are located in the NCK memory, local drive or USB drive can be selected for execution.

## 13.4 Creating a directory/program/job list/program list

### 13.4.1 Creating a new directory

Directory structures help you to manage your program and data transparently. You can create subdirectories in a directory on the local drive and on USB/network drives.

In a subdirectory, in turn, you can create programs and then create program blocks for them.

#### Note

Directory names must end in .DIR or .WPD. The maximum name length is 49 characters including the extension.

All letters (except accented characters), numbers, and underscores are permitted for name assignment. These names are automatically converted to upper-case letters.

This limitation does not apply for work on USB/network drives.

#### Procedure

Program manager	1.	Select the "Program manager" operating area.
Local drive	2.	Select your chosen storage medium, i.e. a local or USB drive.
New Directory	3.	If you want to create a new directory in the local network, place the cursor on the topmost folder and press the "New" and "Directory" softkeys. The "New Directory" window opens.
OK	4.	Enter the desired directory name and press the "OK" softkey.

## 13.4.2 Creating a new workpiece

You can set up various types of files such as main programs, initialization files, tool offsets, etc. in a workpiece.

#### Note

Additional workpiece directories cannot be created within a workpiece directory (WPD).

#### Proceed as follows

Program manager	1.	Select the "Program manager" operating area.
	2.	Select the desired storage location and position the cursor on the folder, in which you would like to create a workpiece.
New	3.	Press the "New" and "Workpiece" softkeys. The "New workpiece" window appears.
Workpiece		
ок	4. 5.	If necessary, select a template if any are available. Enter the desired workpiece name, select a template, if necessary, and press the "OK" softkey.
	6.	The name may be a maximum of 24 characters long. You can use any letters (except umlauts), digits or the underscore symbol (_). The directory type (WPD) is set by default. A new folder with the workpiece name will be created. The "New G code program" window will open. Press the "OK" softkey again if you want to create the program.
ок	0.	ress the ort sourcey again if you want to create the program.

The program will open in the editor.

Program management

13.4 Creating a directory/program/job list/program list

## 13.4.3 Creating a new G code program

You can create G code programs and then render G code blocks for them in a directory/workpiece.

### Procedure



- 1. Select the "Program Manager" operating area.
- 2. Select the desired storage location and position the cursor on the folder, in which you would like to store the program.



3. Press the "New" softkey.

programGUIDE **G code** 

The "New G Code Program" window opens.

4. If necessary, select a template if any are available.

subprogram (SPF) or one main program (MPF).

 Select the file type (MPF or SPF).
 If you are in the NC memory and have selected either the "Subprograms" or "Part Programs" folder, you can only create one



6. Enter the desired program name and press the "OK" softkey.

Program names may be a maximum of 24 characters in length. You can use all letters (with the exception of special characters, language-specific special characters, Asian or Cyrillic characters), numbers and underscores (\_).

## 13.4.4 Creating a new ShopMill program

In the part program and workpiece directories, you can create ShopMill programs and then subsequently generate the machining steps for them.

## Procedure

Program manager	1.	Select the "Program Manager" operating area.
	2.	Select the desired storage location and position the cursor on the folder, in which you would like to store the program.
New	3.	Press the "New" softkey.
ShopMill	4.	Press the "ShopMill" softkey. The "New step sequence program" window opens. The "ShopMill" type is specified.
OK	5.	Enter the desired program name and press the "OK" softkey.
		Program names may be a maximum of 24 characters in length.

You can use all letters (with the exception of special characters, language-specific special characters, Asian or Cyrillic characters), numbers and underscores (\_).

## 13.4.5 Storing any new file

In each directory or subdirectory you can create a file in any format that you specify.

This does not apply to the NC memory. Here you can create the following file types under a workpiece using the "Any" softkey.

	Any new program	
Template	JOBLIST.JOB	$\sim$
1		
Type	Job list JOB	~
Nama	Job list JOB	_
Name	Tool data TOA	
	TMA magazine assignment	
	UFR zero points	
	R variable RPA	
	Definitions GUD	
	Setting data SEA	
	Protection zones PRO	
	CEC sag compensation	
	Initialization program INI	

#### Procedure



1.

- Select the "Program manager" operating area.
- 2. Select the desired storage location and position the cursor on the folder, in which you would like to create the file.
- Press the "New" and "Any" softkeys.
   The "Any new program" window appears



New

 Select a file type from the "Type" selection field (for example, "Definitions GUD") and enter the name of the file to be created when you have selected a workpiece directory in the NC memory.

The file automatically has the selected file format.

- OR -

Enter a name and file format for the file to be created (e.g. My\_Text.txt).

The name may be a maximum of 24 characters long. You can use any letters (except umlauts), digits or the underscore symbol (\_).



5. Press the "OK" softkey.

### 13.4.6 Creating a Joblist

For every workpiece, you can create a job list for extended workpiece selection. In the job list, you specify instructions for program selection in different channels.

#### Syntax

The job list contains the SELECT select instructions.

SELECT <program> CH=<channel number> [DISK]

The SELECT instruction selects a program for execution in a specific NC channel. The selected program must be loaded into the working memory of the NC. The DISK parameter enables the selection of external execution (CF card, USB data carrier, network drive).

<Program>

Absolute or relative path specification of the program to be selected.

Examples:

- //NC/WCS.DIR/SHAFT.WPD/SHAFT1.MPF
- SHAFT2.MPF
- <Channel number>

Number of the NC channel in which the program is to be selected.

Example:

CH=2

• [DISK]

Optional parameter for programs that are not in the NC memory and are to be executed "externally".

Example:

SELECT //remote/myshare/shaft3.mpf CH=1 DISK

#### Comment

Comments are identified in the job list by ";" at the start of the line or by round brackets.

### Template

You can select a template from Siemens or the machine manufacturer when creating a new job list.

#### Executing a workpiece

If the "Select" softkey is selected for a workpiece, the syntax of the associated job list is checked and then executed. The cursor can also be placed on the job list for selection.

### Procedure



NC

- 1. Select the "Program Manager" operating area.
- 2. Press the "NC" softkey, and in directory "Workpieces" place the cursor on the program for which you wish to create a job list.



**OK** 

NC

3. Press the "New" and "Any" softkeys.

The "Any New Program" window opens.

4. Select entry "Job list JOB" from the "Type" selection field and enter a name and press the "OK" softkey.

## 13.4.7 Creating a program list

You can also enter programs in a program list that are then selected and executed from the PLC.

The program list may contain up to 100 entries.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

## Procedure

1. Select the "Program manager" operating area. 咛 Program manager 2. Press the menu forward key and the "Program list" softkey. The "Prog.-list" window opens. Prog.-PLC list 3. Place the cursor in the desired line (program number). 4. Press the "Select program" softkey. Select program The "Programs" window opens. The data tree of the NC memory with workpiece, part program and subprogram directory is displayed. 5. Place the cursor on the desired program and press the "OK" softkey. **OK** The selected program is inserted in the first line of the list together with its path. - OR -Enter the program name directly in the list. If you are making entries manually, check that the path is correct (e.g. //NC/WKS.DIR/MEINPROGRAMM.WPD/MEINPROGRAMM.MPF). //NC and the extension (.MPF) may be added automatically. With multi-channel machines, you can specify in which channel the program is to be selected. 6. To remove a program from the list, place the cursor on the appropriate Delete line and press the "Delete" softkey. - OR -To delete all programs from the program list, press the "Delete all" Delete softkey. all

## 13.5 Creating templates

You can store your own templates to be used for creating part programs and workpieces. These templates provide the basic framework for further editing.

You can use them for any part programs or workpieces you have created.

#### Storage location for templates

The templates used to create part programs or workpieces are stored in the following directories:

HMI Data/Templates/Manufacturer/Part programs or Workpieces

HMI Data/Templates/User/Part programs or Workpieces

#### Procedure



1.

- Select the "Startup" operating area.
- 2. Press the "System data" softkey.
- Сору
- 3. Position the cursor on the file that you wish to store as a template and press the "Copy" softkey.
- Paste
- 4. Select the directory in which you want to store the data "Part programs" or "Workpieces" and press the "Paste" softkey.

Stored templates can be selected when a part program or a workpiece is being created.

13.6 Displaying the program in the Preview

# 13.6 Displaying the program in the Preview

1.

You can show the content on a program in a preview before you start editing.

## Procedure



- Select the "Program manager" operating area.
- 2. Select a storage location and place the cursor on the relevant program.
- Preview window Preview

window

- Press the ">>" and "Preview window" softkeys.
   The "Preview: ..." window opens.
- 4. Press the "Preview window" softkey again to close the window.

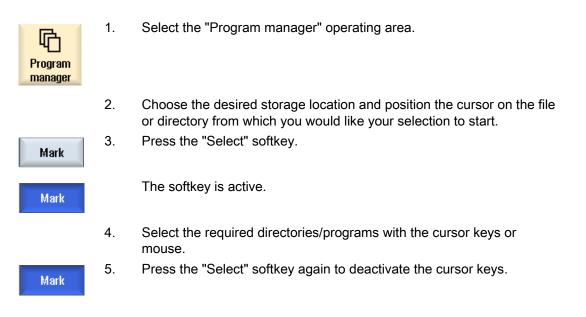
## 13.7 Selecting several directories/programs

You can select several files and directories for further processing. When you select a directory, all directories and files located beneath it are also selected.

#### Note

If you have selected several directories and one of them closes, then selection of the directory and all of the files contained therein is canceled.

### Procedure



#### Canceling a selection

By reselecting an element, the existing selection is canceled.

13.7 Selecting several directories/programs

### Selecting via keys

Key combination	Meaning
SELECT	Renders or expands a selection. You can only select individual elements.
SHIFT	Renders a consecutive selection.
INSERT	A previously existing selection is canceled.

#### Selecting with the mouse

Key combination	Meaning
Left mouse	Click on element: The element is selected.
	A previously existing selection is canceled.
Left mouse +	Expand selection consecutively up to the next click.
SHIFT	
Pressed	
Left mouse +	Expand selection to individual elements by clicking.
	An existing selection will expand to include the element you clicked.
CTRL	
Pressed	

13.8 Copying and pasting a directory/program

## 13.8 Copying and pasting a directory/program

To create a new directory or program that is similar to an existing program, you can save time by copying the old directory or program and only changing selected programs or program blocks.

The capability of copying and pasting directories and programs can also be used to exchange data with other systems via USB/network drives (e.g. USB FlashDrive).

Copied files or directories can be pasted in a different location.

#### Note

You can only paste directories on local drives and on USB or network drives.

#### Note

#### Write protection

If the current directory is write-protected for the user, then the function is not offered.

#### Note

When you copy directories, any missing endings are added automatically.

All letters (except accented characters), numbers, and underscores are permitted for name assignment. The names are automatically converted to upper-case letters, and extra dots are converted to underscores.

#### Example

If the name is not changed during the copy procedure, a copy is created automatically:

MYPROGRAM.MPF is copied to MYPROGRAM\_1.MPF. The next time it is copied, it is changed to MYPROGRAM\_2.MPF, etc.

If the files MYPROGRAM.MPF, MYPROGRAM\_1.MPF, and MYPROGRAM\_3.MPF already exist in a directory, MYPROGRAM\_2.MPF is created as the next copy of MYPROGRAM.MPF.

#### Procedure



- 1. Select the "Program manager" operating area.
- 2. Choose the desired storage location and position the cursor on the file or directory which you would like to copy.

13.8 Copying and pasting a directory/program

ĺ

Сору	3.	Press the "Copy" softkey.
	4.	Select the directory in which you want to paste your copied directory/program.
Paste	5.	Press the "Paste" softkey.
		If a directory/program of the same name already exists in this directory, you are are informed. You are requested to assign a new name, otherwise the directory/program is assigned a name by the system.
		If the name contains illegal characters or is too long, a prompt will appear for you to enter a permissible name.
ОК	6.	Press the "OK" or "Overwrite all" softkey if you want to overwrite existing directories/programs.
Overwrite all		
		- OR -
No overwriting		Press the "No overwriting" softkey if you do not want to overwrite already existing directories/programs.
		- OR -
Skip		Press the "Skip" softkey if the copy operation is to be continued with the next file.
		- OR -
ОК		Enter another name if you want to paste the directory/program under another name and press the "OK" softkey.

#### Note

#### Copying files in the same directory

You cannot copy files to the same directory. You must copy the file under a new name.

## 13.9 Deleting a program/directory

## 13.9.1 Deleting a program/directory

Delete programs or directories from time to time that you are no longer using to maintain a clearer overview of your data management. Back up the data beforehand, if necessary, on an external data medium (e.g. USB FlashDrive) or on a network drive.

Please note that when you delete a directory, all programs, tool data and zero point data and subdirectories that this directory contains are deleted.

#### Temp directory for ShopMill

If you want to free up space in the NCK memory, delete the contents of the "TEMP" directory. ShopMill stores the programs that are created internally for calculating the stock removal processes in this directory.

#### Procedure

Program manager	1.	Select the "Program manager" operating area.
	2.	Choose the desired storage location and position the cursor on the file or directory that you would like to delete.
	3.	Press the ">>" and "Delete" softkeys.
		A prompt appears as to whether you really want to delete the file or
Delete		directory.
ок	4.	Press the "OK" softkey to delete the program/directory.
		- OR
×		Press the "Cancel" softkey to cancel the process.
~		

Cancel

13.10 Renaming file and directory properties

## 13.10 Renaming file and directory properties

Information on directories and files can be displayed in the "Properties for ..." window. Information on the creation date is displayed near the file's path and name. You can change names.

## Changing access rights for NC data

Access rights for execution, writing, listing and reading are displayed in the "Properties" window.

- Execute: This is used for the selection
- Write: Controls the changing and deletion of a file or a directory

You can set the access rights from keyswitch 0 to the current access level. If an access level is higher than the current access level, it cannot be changed.

Note

Access rights cannot be defined for files outside the NC memory (e.g. local drive).

Procedure



1.

- Select the Program manager.
- 2. Choose the desired storage location and position the cursor on the file or directory whose properties you want to display or change.



Press the ">>" and "Properties" softkeys.
 The "Properties from ..." window appears.

Properties



- 4. Enter any necessary changes.
- 5. Press the "OK" softkey to save the changes.

## 13.11 EXTCALL

The EXTCALL command can be used to access files on a local drive, USB data carriers or network drives from a part program.

The programmer can set the source directory with the setting data SD \$SC42700 EXT\_PROG\_PATH and then specify the file name of the subprogram to be loaded with the EXTCALL command.

#### **General conditions**

The following supplementary conditions must be taken into account with EXTCALL calls:

- You can only call files with the MPF or SPF extension via EXTCALL from a network drive.
- The files and paths must comply with the NCK naming conventions (max. 25 characters for the name, 3 characters for the identifier).
- A program is found on a network drive with the EXTCALL command if
  - with SD \$SC42700 EXT\_PROG\_PATH, the search path refers to the network drive or a directory contained on the network drive. The program must be stored directly on that level, no subdirectories are searched.
  - without SD \$SC42700: The correct location of the program is specified in the EXTCALL call itself by means of a fully qualified path that can also point to a subdirectory of the network drive.

#### Note

#### Maximum path length for EXTCALL

The path length must not exceed 112 characters. The path comprises the contents of the setting data (SD \$SC42700) and the path data for EXTCALL call from the part program.

### Examples of EXTCALL calls

The setting data can be used to perform a targeted search for the program.

 Call of USB drive on TCU (USB storage device on interface X203), if SD42700 is empty: e.g. EXTCALL "//TCU/TCU1 /X203 ,1/TEST.SPF"

- OR -

Call of USB drive on TCU (USB storage device on interface X203), if SD42700 "//TCU/TCU1 /X203 ,1" contains: EXTCALL "TEST.SPF"

- Calls the USB front connection (USB FlashDrive), if SD \$SC 42700 is empty: e.g. EXTCALL "//ACTTCU/FRONT,1/TEST.SPF"
  - OR -

Call of USB front connection (USB FlashDrive), if SD42700 "//ACTTCU/FRONT,1" contains: EXTCALL "TEST.SPF"

 Call of network drive, if SD42700 is empty: e.g. EXTCALL "//computer name/enabled drive/TEST.SPF"

- OR -

Calls the network drive, if SD \$SC42700 "//Computer name/enabled drive" contains: EXTCALL "TEST.SPF"

- Use of the HMI user memory (local drive):
  - On the local drive, you have created the directories part programs (mpf.dir), subprograms (spf.dir) and workpieces (wks.dir) with the respective workpiece directories (.wpd):

SD42700 is empty: EXTCALL "TEST.SPF"

The same search sequence is used on the CompactFlash card as in the NCK part program memory.

On the local drive, you have created your own directory (e.g. my.dir):

Specification of the complete path: e.g. EXTCALL "/card/user/sinumerik/data/prog/my.dir/TEST.SPF"

A search is performed for the specified file.

#### Note

#### Abbreviations for local drive, CompactFlash Card and USB front connection

As abbreviation for the local drive, the CompactFlash Card and the USB front connection you can use the abbreviation LOCAL\_DRIVE:, CF\_CARD: and USB: (e.g. EXTCALL "LOCAL\_DRIVE:/spf.dir/TEST.SPF").

Alternatively, you can also use the abbreviations CF\_Card and LOCAL\_DRIVE.



#### Software options

To display the "Local drive" softkey, you require the option "Additional 256 MB HMI user memory on CF Card of the NCU" (not for SINUMERIK Operate on PCU50 / PC).

#### NOTICE

#### Execution from USB FlashDrive

Direct execution from a USB FlashDrive is not recommended.

There is no protection against contact problems, falling out, breakage through knocking or unintentional removal of the USB FlashDrive during operation.

Disconnecting it during operation will result in immediate stopping of the machining and, thus, to the workpiece being damaged.



### Machine manufacturer

Processing EXTCALL calls can be enabled and disabled. Please refer to the machine manufacturer's specifications.

#### 13.12 Backing up data

#### 13.12.1 Generating an archive in the Program Manager

You have the option of archiving individual files from the NC memory and the local drive.

#### Archive formats

You have the option of saving your archive in the binary and punched tape format.

#### Save target

The archive folder of the system data in the "Startup" operating area as well as USB and network drives are available as save target.

### Procedure

Program manager	1.	Select the "Program Manager" operating area.
NC NC	2.	Select the storage location for the file/files to be archived.
	3.	In the directories, select the required file from which you want to create an archive. - OR -
Mark		If you want to back up several files or directories, press the "Select" softkey and, using the cursor keys or the mouse, select the required directories or files.
Archive	4.	Press the ">>" and "Archive" softkeys.
Generate archive	5.	Press the "Generate archive" softkey. The "Generate archive: Select archiving" window opens.
New directory OK	6.	Select the required folder or the memory medium and press the "New directory" softkey to create a subdirectory and then press the "OK" softkey. The "New Directory" window opens.
OK	7.	Enter the directory name and press "OK". The sub-directory is created in the selected directory.



Press "OK".

The "Generate Archive: Name" window opens.



Select the format (e.g. archive ARC (binary format)), enter the desired 9. name and press the "OK" softkey.

A message informs you if archiving was successful.

#### 13.12.2 Generating the archive via series startup

If you only want to backup specific data, then you can select the desired files directly from the data tree and generate an archive.

#### Archive formats

You have the option of saving your archive in the binary and punched tape format.

You can display the contents of the selected files (XML, ini, hsp, syf files, programs) in a preview.

You can display information about the file, such as path, name, date of creation and change, in a Properties window.

#### Precondition

The access rights depend on the relevant areas and range from protection level 7 (key switch position 0) to protection level 2 (password: Service).

#### Storage locations

- CompactFlash Card under • /user/sinumerik/data/archive, or /oem/sinumerik/data/archive
- All configured logical drives (USB, network drives)



Software option

In order to save archives on the CompactFlash Card in the user area you require the "Additional 256 MB HMI user memory on CF card of NCU" option.

#### NOTICE

## **USB** FlashDrive

USB FlashDrives are not suitable as persistent memory media.

13.12 Backing up data

I

## Procedure

*	1.	Select the "Start-up" operating area.
Start-up		
System	2.	Press the "System data" softkey.
-🖻 data		The data tree opens.
	3.	In the data tree, select the required files from which you want to generate an archive. - OR -
Mark		If you want to back up several files or directories, press the "Select" softkey and, using the cursor keys or the mouse, select the required directories or files.
	4.	If you press the ">>" softkey, further softkeys are displayed on the vertical bar.
Preview	5.	Press the "Preview window" softkey.
window		The contents of the selected file are displayed in a small window. Press the "Preview window" softkey again to close the window.
Properties	6.	Press the "Properties" softkey.
		Information about the selected file is displayed in a small window. Press the "OK" softkey to close the window.
Archive	7.	Press the "Archive" and "Generate archive" softkeys.
		The "Generate Archive: Select Archiving" window opens.
Generate archive		All the files to be archived and the storage path are displayed.
New	8.	Select the required location for archiving and press the "New directory" softkey to create a suitable subdirectory.
directory		The "New Directory" window opens.
	9.	Enter the required name and press the "OK" softkey.
ок		The directory is created subordinate to the selected folder.
	10.	Press the "OK" softkey.
ок		The "Generate Archive: Name" window opens.
ок	11.	Select the format (e.g. archive ARC (binary format)), enter the desired name and press the "OK" softkey to archive the file/files.
		A message informs you if archiving was successful. An archive file in .arc format is created in the selected directory.

# 13.12.3 Reading in an archive

If you want to read in a specific archive, you can select this directly from the data tree.

## Procedure

	4	Coloct the "Otort up" energing area
2	1.	Select the "Start-up" operating area.
Start-up		
FB System data	2.	Press the "System data" softkey.
	3.	Below the "Archive" directory in the data tree, select the file you want to read in.
Read in	4.	Press the "Read in" softkey.
ОК	5.	Press the "OK" or "Overwrite all" softkey to overwrite existing files.
Overwrite all		
		- OR -
No overwriting		Press the "Do not overwrite" softkey if you do not want to overwrite already existing files.
		- OR -
Skip		Press the "Skip" softkey if the read-in operation is to be continued with the next file.
		The "Read In Archive" window opens and a progress message box appears for the read-in process.
		You will then obtain a "Read error log for archive" in which the skipped or overwritten files are listed.
X Cancel	6.	Press the "Cancel" softkey to cancel the read-in process.

13.13 Setup data

## 13.13 Setup data

## 13.13.1 Backing up setup data

Apart from programs, you can also save tool data and zero point settings.

You can use this option, for example, to back up tools and zero point data for a specific machining step program. If you want to execute this program at a later point in time, you will then have quick access to the relevant settings.

Even tool data that you have measured on an external tool setting station can be copied easily into the tool management system using this option.

#### Backing-up job lists

If you wish to backup a job list, which contains ShopMill and G code programs, you obtain dedicated selection boxes to backup the tool data and zero points.

#### Backing up data

Data	
Tool data	<ul> <li>No</li> <li>All used in the program (only for ShopMill program and job list with ShopMill programs)</li> <li>Complete tool list</li> </ul>
Tool data for ShopMill programs only available for job list with ShopMill and G code programs	<ul><li>No</li><li>All used in the program</li><li>Complete tool list</li></ul>
Tool data for G code programs only available for job list with ShopMill and G code programs	<ul><li>No</li><li>Complete tool list</li></ul>
Magazine assignment	<ul><li>Yes</li><li>No</li></ul>
Zero points	<ul> <li>No The selection box "Basis zero point" is hidden</li> <li>All used in the program (only for ShopMill program and job list with ShopMill programs)</li> <li>All</li> </ul>
Zero points for ShopMill programs only available for job list with ShopMill and G code programs	<ul> <li>No</li> <li>The selection box "Basis zero point" is hidden</li> <li>All used in the program</li> <li>Complete tool list</li> </ul>

13.13 Setup data

Data	
Zero points for G code programs only available for job list with ShopMill and G code programs	<ul> <li>No The selection box "Basis zero point" is hidden</li> <li>All</li> </ul>
Basic zero points	<ul><li>No</li><li>Yes</li></ul>
Directory	The directory is displayed, in which the selected program is located.
File name	Here you have the option of changing the suggested file names.

#### Note

#### Magazine assignment

You can only read out the magazine assignments if your system provides support for loading and unloading tool data to and from the magazine.

#### Procedure



- 1. Select the "Program Manager" operating area.
- 2. Position the cursor on the program whose tool and zero point data you wish to back up.



...



3.



Save setup data

- Press the ">>" and "Archive" softkeys.
- 4. Press the "Setup data" softkey. The "Backup setup data" window opens.
- 5. Select the data you want to back up.

OK	6.	When required, change the specified name of the originally selected program here in the "File name" field.
	7.	Press the "OK" softkey.
		The setup data will be set up in the same directory in which the selected program is stored.

The file is automatically saved as INI file.

## Note

#### **Program selection**

If a main program as well as an INI file with the same name are in a directory, when selecting the main program, initially, the INI file is automatically started. In this way, unwanted tool data can be changed.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

## 13.13.2 Reading-in set-up data

When reading-in, you can select which of the backed-up data you wish to read-in:

- Tool data
- Magazine assignment
- Zero points
- Basic zero point

#### Tool data

Depending on which data you have selected, the system behaves as follows:

Complete tool list

First, all tool management data are deleted and then the saved data are imported.

• All tool data used in the program

If at least one of the tools to be read in already exists in the tool management system, you can choose between the following options.

Overwrite all	Select the "Replace all" softkey to import all tool data. Any existing tools will now be overwritten without a warning prompt.
	- OR -
No overwriting	Press the "Do not overwrite" softkey if existing tools must not be overwritten.
	Already existing tools are skipped, without you receiving any queries. - OR -
Skip	Press the "Skip" softkey if already existing tools are not to be overwritten.
	For an already existing tool, you receive a query.

## Selecting loading point

For a magazine, if more than one loading point was set-up, using the "Select loading point" softkey, you have the option of opening a window in which you can assign a loading point to a magazine.

#### Procedure

哈
Program
manager

1. Select the "Program Manager" operating area.



2. Position the cursor on the file with the backed-up tool and zero point data (\*.INI) that you wish to re-import.



3. Press the <Cursor right> key



- OR -Double-click the file.

Press the "OK" softkey.

The "Read-in setup data" window opens.



ŌК

5.

4. Select the data (e.g. magazine assignment) that you wish to read-in.

13.14 V24

# 13.14 V24

## 13.14.1 Reading-in and reading-out archives

You have the option of reading-out and reading-in archives in the "Program Manager" operating area as well as in the "Start-up" operating area via the serial V24 interface.

#### Availability of the serial V24 interface

• SINUMERIK Operate in the NCU

The softkeys for the V24 interface are available as soon as option module is connected and the slot is occupied.

• SINUMERIK Operate on PCU 50.3

The softkeys for the V24 interface are always available.

#### **Reading-out archives**

The files to be sent (directories or individual files) are zipped in an archive (\*.ARC).

If you send an archive (\*.arc), this is sent directly without being additionally zipped. If you have selected an archive (\*.arc) together with an additional file (e.g. directory), then these are zipped into a new archive and are then sent.

#### **Reading-in archives**

Only archives can be read-in via the V24 interface. These are transferred and then subsequently unzipped.

#### Note

#### Series commissioning archive

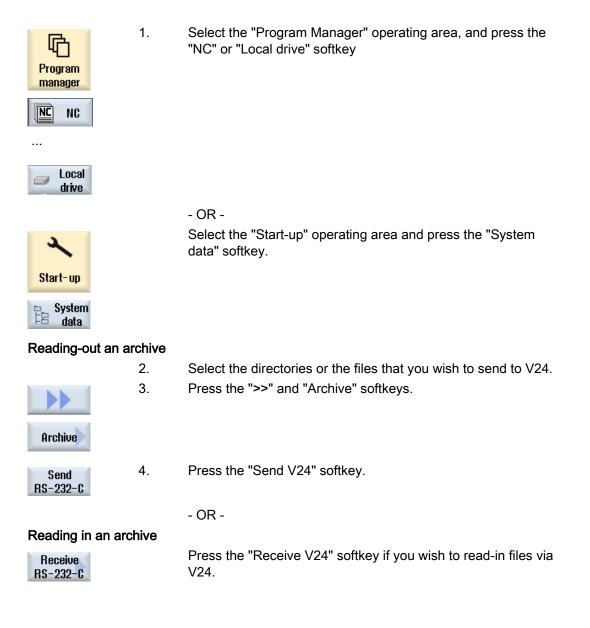
If you read-in a series commissioning archive via the V24 interface, then this is immediately activated.

#### Externally processing the punched tape format

If you wish to externally process an archive, then generate this in the punch tape format. Using the SinuCom commissioning and Servicetool SinuCom ARC, you can process the archive in the binary format and in the series commissioning archive.

#### Program management 13.14 V24

## Procedure



13.14 V24

# 13.14.2 Setting V24 in the program manager

V24 setting	Meaning
Protocol	The following protocols are supported for transfer via the V24 interface:
	RTS/CTS (default setting)
	Xon/Xoff
Transfer	It is also possible to use a secure protocol for data transfer (ZMODEM protocol).
	Normal (default setting)
	• secure
	For the selected interface, secure data transfer is set in conjunction with handshake RTS/CTS.
Baud rate	Transfer rate: Transfer rates of up to 115 kbaud can be selected. The baud rate that can be used depends on the connected device, the cable length and the general electrical conditions.
	• 110
	•
	• 19200 (default)
	•
	• 115200
Archive format	Punched tape format (default setting)
	Binary format (PC format)
V24 settings (details)	
Interface	• COM1
Parity	<ul> <li>Parity bits are used for error detection: The parity bits are added to the coded characters to make the number of positions set to "1" an uneven number (uneven parity) or to an even number (even parity).</li> <li>None (default setting)</li> <li>Odd</li> <li>Even</li> </ul>
Stop bits	Number of stop bits for asynchronous data transfer.
	• 1 (default)
	• 2
Data bits	Number of data bits for asynchronous data transfer.
	• 5 bits
	•
	-8 bits (default setting)
XON (hex)	Only for punched tape format
XOFF (hex)	Only for punched tape format

13.14 V24

V24 setting	Meaning
End of data transfer (hex)	Only for punched tape format
	Stop with end of data transfer character
	The default setting for the end of data transfer character is (HEX) 1A
Time monitoring (sec)	Time monitoring
	For data transfer problems or at the end of data transfer (without end of data transfer character) data transfer is interrupted after the specified number of seconds.
	The time monitoring is controlled by a time generator (clock) that is started with the first character and is reset with each transferred character. The time monitoring can be set (seconds).

## Procedure

Program manager	1.	Select the "Program Manager" operating area.
Local drive	2.	Press the "NC" or "Local drive" softkey.
Archive	3.	Press the ">>" and "Archive" softkeys.
RS-232-C settings	4.	Select the "V24 settings" softkey. The "Interface: V24" window is opened.
Details	5. 6.	The interface settings are displayed. Press the "Details" softkey if you wish to view and process additional settings for the interface.

Program management

13.14 V24

# Setting up drives

## 14.1 Overview

#### Set up connections

Up to 8 connections to so-called logical drives (data carriers) can be configured. These drives can be accessed in the "Program manager" and "Startup" operating areas.

The following logical drives can be set up:

- USB interface
- CompactFlash Card of the NCU, only for SINUMERIK Operate in the NCU
- Network drives
- Local hard disk of the PCU 50.3, only for SINUMERIK Operate on the PCU



#### Software option

In order to use the CompactFlash Card as data carrier, you require the option "Additional 256 MB HMI user memory on CF card of NCU" (not for SINUMERIK Operate of PCU50 / PC).

## Note

The USB interfaces of the NCU are not available for SINUMERIK Operate and therefore cannot be configured.

# 14.2 Setting up drives

The "Set-up drives" window is available in the "Startup" operating area for configuration.

#### File

The created configuration data is stored in the "logdrive.ini" file. This file is located in the /user/sinumerik/hmi/cfg directory.

## **General information**

Entry		Meaning
Туре	No drive	No drive defined.
	USB local	Access to the USB memory medium is only realized via the TCU to which it is connected. USB drives are automatically identified if the memory medium is inserted when SINUMERIK Operate powers-up.
	USB global	All of the TCUs in the plant network can access the USB memory medium. - USB global is not possible under Windows!
	NW Windows	Network drive
	Local drive	Local drive Hard disk or user memory on the CompactFlash Card
Connection	Front	USB interface that is located at the front of the operator panel.
	X203/X204	USB interface X203/X204 that is located at the rear of the operator panel.
	X204	For SIMATIC Thin Client the USB interface is X204.
Device		Names of the TCU to which the USB storage medium is connected, e.g. tcu1. The NCU must already know the TCU name.
Partition		Partition number on the USB memory medium, e.g. 1. If a USB hub is used, specify the USB port of the hub.
Path		• Start direct directory of the data carrier that is connected via the local drive.
		<ul> <li>Network path to a directory that has been released in the network. This path must always start with "//", e.g. //Server01/share3.</li> </ul>
Access level		Assign access rights to the connections: From protection level 7 (key switch position 0) to protection level 1 (password: Manufacturer).
		The particular assigned protection level applies to all operating areas.

Setting up drives

14.2 Setting up drives

Entry		Meaning
Softkey text		Two lines are available as labeling text for the softkey. %n is accepted as a line separator.
		If the first line is too long, then it is automatically separated into several lines. If a blank is present, then this is used as line separator.
Softkey icon	No icon	No icon is displayed on the softkey.
	sk_usb_front.png	Icon file name. Is displayed on the softkey.
	$\Psi$	
	sk_local_drive.png	Icon file name. Is displayed on the softkey.
Text file	slpmdialog	File for softkey dependent on the language. If nothing is
Text context	SIPmDialog	specified in the input fields, the text appears on the softkey as was specified in the input field "Softkey text".
		If your own text files are saved, then the text ID, which is used to search for the text file, is specified in the "Softkey text" input field.
User name		Enter the user name and the corresponding password for
Password		which the directory is enabled on the server. The password is displayed in encoded form as as string of "*" characters and is stored in the "logdrive.ini" file.

## Error messages

Error message	Meaning
Error occurred when closing a connection	An existing drive was not able to be deactivated.
Error occurred when establishing a connection.	Drive connection was not able to be established.
Error occurred while establishing a connection: Incorrect entry or no authorization.	Drive connection was not able to be established.
Incorrect data	The entered data are either incorrect or inconsistent.
Function not available	The function is not supported with the current software release.
Unknown error - error code:%1	Error was not able to be assigned.

14.2 Setting up drives

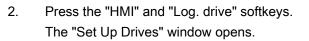
## Procedure



1.

4.

Select the "Start-up" operating area.



3. Select the data for the corresponding drive or enter the necessary data.

Activate drive Press the "Activate drive" softkey. The drive is activated.

The operating system now checks the entered data and whether the connection is established. An OK message is output in the dialog line if an error is not identified.

The drive can be accessed.

Press the "OK" softkey.

your entries and re-activate the drive.

- OR -

If the operating system identifies an error, then you receive an error message.

You then return to the "Configure drives" window. Check and correct





If you press the "OK" softkey, the modified data are accepted without any feedback message. You do not receive any message about a successful or unsuccessful connection.



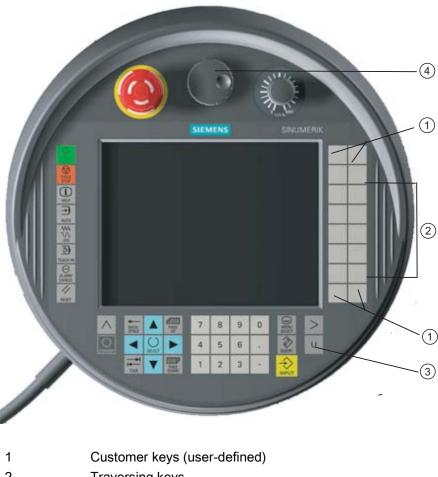
If you press the "Cancel" softkey, then all of the data that has not been activated is rejected.

# 15

# HT 8

# 15.1 HT 8 overview

The mobile SINUMERIK HT 8 handheld terminal combines the functions of an operator panel and a machine control panel. It is therefore suitable for visualization, operation, teach in, and programming at the machine.



- 2 Traversing keys
- 3 User menu key
- 4 Handwheel (optional)

15.1 HT 8 overview

## Operation

The 7.5 TFT color display provides touch operation.

It also has membrane keys for traversing the axes, for numeric input, for cursor control, and for machine control panel functions like start and stop.

It is equipped with an emergency stop button and two 3-position enabling buttons. You can also connect an external keyboard.

#### References

For more information about connection and startup of the HT 8, see the following references: Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

#### Customer keys

The four customer keys are freely assignable and can be set up customer-specifically by the machine manufacturer.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Integrated machine control panel

The HT 8 has an integrated machine control panel consisting of keys (e.g. start, stop, traversing keys, etc.), and keys reproduced as softkeys (see machine control panel menu).

See chapter "Controls on the machine control panel" for a description of the individual keys.

#### Note

PLC interface signals that are triggered via the softkeys of the machine control panel menus are edge triggered.

#### **Enabling button**

The HT 8 has two enabling buttons. Thus, you can initiate enabling functions for operations that require enabling (e.g. displaying and operating of traversing keys) with either your right hand or your left hand.

Enabling buttons are available for the following key positions:

- Released (no activation)
- Enabling (center position) enabling for channel 1 and 2 is on the same switch.
- Panic (completely pushed through)

## **Traversing keys**

To traverse the axes of your machine using the traversing keys of the HT 8, you must select "JOG" mode or either the "Teach In" or "Ref.Point" submode. Depending on the setting, the enabling button must be activated.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Virtual keyboard

A virtual keyboard is available for the easy entry of values.

#### Changing the channel

- You are able to switch the channel by touch in the status display:
  - In the Machine operating area (large status display), by touch operation of the channel display in the status display.
  - In the other operating areas (no status display), by touch operation of the channel display in the screen headers (yellow field).
- The "1... n CHANNEL" softkey is available in the machine control panel menu that can be reached via the user menu key "U".

#### Operating-area switchover

You can display the operating area menu by touching the display symbol for the active operating area.

#### Handwheel

The HT 8 is available with a hand wheel.

#### References

For information about connecting the hand wheel, refer to: Operator Components and Networking Manual; SINUMERIK 840D sl/840Di sl HT 8 15.2 Traversing keys

# 15.2 Traversing keys

The traversing keys are not labeled. However, you can display a label for the keys in place of the vertical softkey bar.

Labeling of the traversing keys is displayed for up to six axes on the touch panel by default.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Showing and hiding

You can link the showing and hiding of the label to activation of the enabling button, for example. In this case, the traversing keys are displayed when you press the enabling button.

If you release the enabling button, the traversing keys are hidden again.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.



All existing vertical and horizontal softkeys are covered or hidden, i.e. other softkeys cannot be used.

# 15.3 Machine control panel menu

Here you select keys from the machine control panel which are reproduced by the software by touch operation of the relevant softkeys.

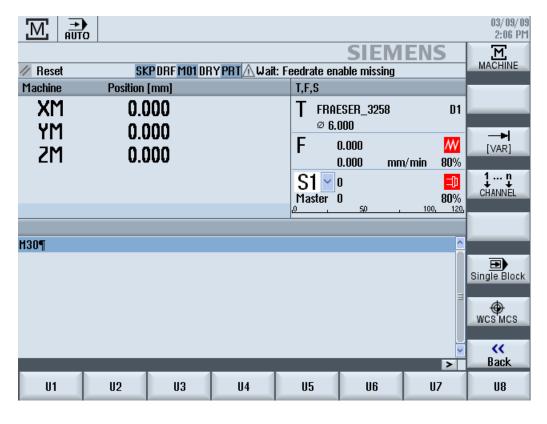
See chapter "Controls on the machine control panel" for a description of the individual keys.

#### Note

PLC interface signals that are triggered via the softkeys of the machine control panel menus are edge triggered.

#### Showing and hiding

The user menu key "U" displays the CPF softkey bar (vertical softkey bar) and the user softkey bar (horizontal softkey bar).





You can expand the user softkey bar to display eight additional softkeys via the menu forward key.



You use the "Back" softkey to hide the menu bar again.

15.3 Machine control panel menu

## Softkeys on the machine control panel menu

Available softkeys:

"Machine" softkey	Select the "Machine" operating area
"[VAR]" softkey	Select the axis feedrate in the variable increment
"1 n CHANNEL" softkey	Change the channel
"Single Block" softkey	Switch single block execution on/off
"WCS MCS" softkey	Switch between WCS and MCS
"Back" softkey	Close the window.

#### Note

The window will automatically disappear when changing regions areas with the "Menu Select" key.

# 15.4 Virtual keyboard

The virtual keyboard is used as the input device for touch operator panels.

It opens when you double-click an operator element with input capability (editor, edit field). The virtual keyboard can be positioned anywhere on the operator interface. In addition, you can toggle between a full keyboard and a reduced keyboard that only includes the number block. Moreover, with the full keyboard, you can toggle between English key assignments and the keyboard assignment for the current language setting.

## Procedure

- 1. Click in the required input field in order to place the cursor there.
- Click the input field.
   The virtual keyboard is displayed.
- 3 Enter your values via the virtual keyboard.



4. Press the <INPUT> key.

- OR -

Position the cursor on an another operator element. The value is accepted and the virtual keyboard is closed.

## Positioning of the virtual keyboard

You can position the virtual keyboard anywhere in the window by pressing the empty bar next to the "Close window" icon with your finger or a stylus and moving it back and forth.

## Special keys on the virtual keyboard



1 Num:

Reduces the virtual keyboard to the number block.

2 Eng:

Toggles the keyboard assignment between the English keyboard assignment and the keyboard assignment for the current language setting.

#### Number block of the virtual keyboard

7	8	9	-		$\left[X\right]$
4	5	6		Del	Ins
1	2	3		Eng	Deu
0	-	·	8		

Use the "Deu" or "Eng" keys to return to the full keyboard with the English keyboard assignment or the keyboard assignment of the current language setting.

# 15.5 Calibrating the touch panel

It is necessary to calibrate the touch panel upon first connection to the controller.

#### Note

#### Recalibration

If the operation is not exact, then redo the calibration.



## Procedure



- 1. Press the back key and the <MENU SELECT> key at the same time to start the TCU service screen.
- 2. Touch the "Calibrate TouchPanel" button. The calibration process will be started.
- 3. Follow the instructions on the screen and touch the three calibration points one after the other.
  - The calibration process has terminated.
- 4. Touch the horizontal softkey "1" or the key with the number "1" to close the TCU service screen.

## *HT 8 15.5 Calibrating the touch panel*

# Easy Message (828D only)

## 16.1 Overview

Easy Message enables you to be informed about certain machine states by means of SMS messages via a connected modem:

- · For example, you would like to be informed about emergency stop states
- · You would like to know when a batch has been completed

#### **Control commands**

HMI commands are used to activate or deactivate a user.

Syntax: [User ID] deactivate, [User ID] activate

 A special area is reserved in the PLC to which you can send commands in the form of PLC bytes using SMS commands.

Syntax: [User ID] PLC DataByte

The user ID is optional and required only if a corresponding ID has been specified in the user profile. The string PLC indicates that a PLC byte is to be written. It is followed by the data byte to be written in the following format: Base#Value. Base can take the values 2, 10 and 16 and defines the number base. Then follows the separator # and the value of the byte. Only positive values are allowed to be sent.

Examples:

2#11101101

10#34

16#AF



## Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Active users

In order to receive an SMS message for certain events, you must be activated as user.

#### User logon

As registered user, you can log on via SMS to inquire about messages.

#### Action log

You can obtain precise information about incoming and outgoing messages via SMS logs.

#### Easy Message (828D only)

16.1 Overview

## References

Information on the GSM modem can be found in the PPU SINUMERIK 828D Manual

## Calling the SMS Messenger



1. Select the "Diagnostics" operating area.



2. Press the "Easy Msg." softkey.

Easy Message (828D only) 16.2 Activating Easy Message

# 16.2 Activating Easy Message

To commission the connection to the modem for the SMS Messenger, activate the SIM card at the initial start-up.

## Requirement

The modem is connected.

## Procedure

#### Activating the SIM card

1.

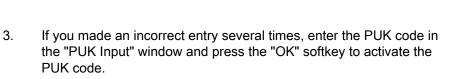
2.



Press the "Easy Msg." softkey. The "SMS Messenger" window appears. "Status" shows that the SIM card has not been activated with a PIN. Enter the PIN, repeat the PIN and press the "OK" softkey.



0K



The "PIN input" window is opened and you can enter the PIN number as usual.

## Activating a new SIM card

Easy	1.	Press the "Easy Msg." softkey.
Msg.		The "SMS Messenger" window appears.
		"Status" shows that the connection to the modem has been activated.
	2.	Press the "Settings" softkey.



 $\square$ 



Press the "Delete PIN" softkey to delete the stored PIN.
 Enter the new PIN in the "PIN Input" window at the next power up.

16.3 Creating/editing a user profile

# 16.3 Creating/editing a user profile

#### User identification

Display	Meaning
User name	Name of the user to be created or logged on.
Telephone number	Telephone number of the user to which the messages are to be sent. The telephone number must include the country code in order that control commands can identify the sender (e.g. +491729999999)
User ID	The user ID has 5 digits (e.g. 12345)
	<ul> <li>It is used to activate and deactivate the user via SMS. (e.g. "12345 activate")</li> </ul>
	• The ID is used to additionally verify the incoming and outgoing messages and to activate the control commands.

#### Events that can be selected

You must set-up the events for which you receive notification.

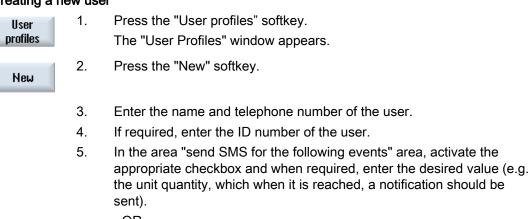
#### Requirement

The modem is connected.

#### Procedure

#### Creating a new user

Standard



- OR -

Press the "Default" softkey.

The appropriate window is opened and displays the default values.

## Easy Message (828D only)

16.3 Creating/editing a user profile

Send	6.	Press the "Send test message" softkey.
test SMS		An SMS message with predefined text is sent to the specified telephone number.

## Editing user data and events

Edit	1.	Select the user whose data you want to edit and press the "Edit" softkey.
		The input fields can be edited.
	2.	Enter new data and activate the desired settings.
		- OR -
Standard		Press the "Default" softkey to accept the default values.

## 16.4 Setting-up events

## 16.4 Setting-up events

In the "Send SMS for the following events" area, select the events using the check box, which when they occur, an SMS is sent to the user.

Programmed messages from the part program (MSG)

In the part program, program an MSG command via which you receive an SMS.

Example: MSG ("SMS: An SMS from a part program")

- Select the following events using the <SELECT> key
  - The workpiece counter reaches the following value

An SMS is sent if the workpiece counter reaches the set value.

- The following program progress is reached (percent)

An SMS is sent if, when executing a part program, the set progress is reached.

- Actual NC program reaches runtime (minutes)

An SMS is sent after the set runtime has been reached when executing an NC program.

- Tool usage time reaches the following value (minutes)

An SMS is sent if the usage time of the tool reaches the set time when executing a part program (derived from \$AC\_CUTTING\_TIME).

• Messages/alarms from the Tool Manager

An SMS is sent if messages or alarms are output to the Tool Manager.

Measuring cycle messages for tools

An SMS is sent if measuring cycle messages are output that involve tools.

• Measuring cycle messages for workpieces

An SMS is sent if measuring cycle messages are output that involve workpieces.

• Sinumerik messages/alarms (error when executing)

An SMS is sent if NCK alarms or messages are output that cause the machine to come to a standstill.

Machine faults

An SMS is sent if PLC alarms or messages are output that cause the machine to come to a standstill (i.e. PLC alarms with Emergency Off response).

• Maintenance intervals

An SMS is sent if the service planner registers pending maintenance work.

• Additional alarm numbers:

Here, specify additional alarms where you should be notified if they occur. You can enter individual alarms, several alarms or alarm number ranges. Examples: 1234,400

- 1000-2000
- 100,200-300

#### Requirement

- The user profile window is opened.
- You selected the event "Measuring cycle messages for tools", "Measuring cycle messages for workpieces", "Sinumerik messages/alarms (errors when executing)", "Machine faults" or "Maintenance intervals".

#### **Editing events**

Details Delete	1. 2.	Activate the required check box and press the "Details" softkey. The appropriate window opens (e.g. "Measuring cycle messages for workpieces") and shows a list of the defined alarm numbers. Select the corresponding entry and press the "Delete" softkey to remove the alarm number from the list.
Неш		- OR - Then press the "New" softkey if you wish to create a new entry. The "Create new entry" window opens.
ок		Enter the data and press the "OK" softkey to add the entry to the list.
Save		Press the "Save" softkey to save the settings for the result.
Standard	3.	Press the "Standard" softkey to return to the standard settings for the events.

16.5 Logging an active user on and off

# 16.5 Logging an active user on and off

Only active users receive an SMS message for the specified events.

You can activate users, already created for Easy Message, with certain control commands via the user interface or via SMS.



The connection has been established to the modem.

#### Procedure



1.

2.

3.

- Press the "User profiles" softkey.
- User active

User ac<u>tive</u>

#### Note

active" softkey

Repeat step 2 to activate further users.

- OR -

Send an SMS with the User ID and the "activate" text to the control (e.g. "12345 activate")

If the telephone number and the user ID match the stored data, the

Select the desired user in the User name field and press the "User



user profile is activated. You receive a message of success or failure per SMS.

Proce the "User active" coffkey to lea off an activated use



- Press the "User active" softkey to log off an activated user.
  - OR -

Send an SMS with the "deactivate" text (e.g. "12345 deactivate") to log off from the Messenger.

An SMS message is not sent to the deactivated user for the events specified in the user profile.

# 16.6 Displaying SMS logs

The SMS data traffic is recorded in the "SMS Log" window. In this way, it is possible to see the chronological sequence of activates when a fault occurs.

Symbols	Description
Ŷ	Incoming SMS message for the Messenger.
횟	Message that has reached the Messenger, but which has not been processed (e.g. incorrect user ID or unknown account).
î	SMS message sent to a user.
6	Message that has not reached the user because of an error.

## Requirement



The connection has been established to the modem.

## Procedure



Incoming

1. Press the "SMS log" softkey.

The "SMS Log" window appears. All the messages that have been sent or received by the Messenger

are listed.

## Note

Press the "Incoming" or "Outgoing" softkey to restrict the list.

16.7 Making settings for Easy Message

# 16.7 Making settings for Easy Message

You can change the following Messenger configuration in the "Settings" window:

- Name of the controller that is part of an SMS message
- Number of sent messages
  - The SMS counter provides information on all sent messages.
  - Limit the number of sent messages in order to receive an overview of the costs through SMS messages, for example.

#### Setting the SMS counter to zero



When a set limit is reached, no further SMS messages are sent. Press the "Reset SMS counter" softkey to reset the counter to zero.

## Requirement



The connection has been established to the modem.

## Procedure

## Settings

1. Press the "Settings" softkey.

Press the "Default" softkey.

- SELECT
- 2. Enter an arbitrary name for the controller in the "Machine name" field.
- If you want to limit the number of sent SMS messages then select the "Specify limit for SMS counter" entry and enter the desired number. When the maximum number of messages is reached, you obtain a corresponding error message.

#### Note

Check the SMS log to see the exact time when the limit was reached. - OR -

Standard

3.

If you have freely selected a machine name, this is replaced by a default name (e.g. 828D).

# Easy Extend (828D only)

#### 17.1 Overview

Easy Extend enables machines to be retrofitted with additional units, which are controlled by the PLC or that require additional NC axes (such as bar loaders, swiveling tables or milling heads), at a later point in time. These additional devices are easily commissioned, activated, deactivated or tested with Easy Extend.

The communication between the operator component and the PLC is performed via a PLC user program. The sequences to be executed for the installation, activation, deactivation and testing of a device are stored in a statement script.

Available devices and device states are displayed in a list. The view of the available devices can be controlled for users according to their access rights.

The subsequent chapters are selected for example only and are not available in every statement list.

Machine manufacturer

Please refer to the machine manufacturer's specifications.

Up to 64 devices can be managed.

#### References

SINUMERIK 828D Turning and Milling Commissioning Manual

## 17.2 Enabling a device

The available device options are protected by a password.



Machine manufacturer

Please refer to the machine manufacturer's specifications.

<b>↓</b> Parameter	1.	Select the "Parameter" operating area.
>	2.	Press the menu forward key and then the "Easy Extend" softkey. A list of the connected devices is displayed.
Easy Extend		
Enable function	3.	Press the "Enable function" softkey. The "Enabling of the Devices Option" window is opened.
ОК	4.	Enter the option code and press the "OK" softkey. A tick appears in the appropriate checkbox in the "Function" column and the function is enabled.

## 17.3 Activating and deactivating a device

Status	Meaning
0	Device activated
6	System waiting for PLC checkback signal
0	Device faulty
▲	Interface error in the communication module

#### Procedure

Easy Extend	1.
▼	2
Activate	3.

4.

. Easy Extend is opened.

You can select the desired device in the list with the <Cursor up> and <Cursor down> keys.

 Position the cursor on the device option for which the function has been unlocked and press the "Activate" softkey.
 The device is marked as activated and can now be used.

#### Deactivate

Select the desired activated device and press the "Deactivate" softkey to switch the device off again.

17.4 Commissioning Easy Extend

## 17.4 Commissioning Easy Extend

As a rule, the "Easy Extend" function has already been commissioned by the machine manufacturer. If a first commissioning has not been performed or if, for example, function tests are to be performed again (e.g. when retrofitting additional devices), this is possible at any time.

The "Start-up" softkey has been declared as Manufacturer data class (M).

Parameter	1.	Select the "Parameter" operating area.
Easy Extend	2.	Press the menu forward key and then the "Easy Extend" softkey.
Start-up	3.	Press the "Start-up" softkey. A new vertical softkey bar appears.
IBN StartUp	4.	Press the "Comm. startup" softkey to start the commissioning. Before starting, a complete data backup is generated which you can then use in an emergency.
	5.	Press the "Cancel" softkey if you want to abort the commissioning prematurely.
恢复	6.	Press the "Restore" softkey to load the original data.
Function test device	7.	Press the "Device function test" softkey to test the machine manufacturer's intended function.

# Service Planner (828D only)

## 18.1 Performing and monitoring maintenance tasks

With the "Service Planner", maintenance tasks have been set up that have to be performed at certain intervals (e.g. top up oil, change coolant).

A list is displayed of all the maintenance tasks that have been set up together with the time remaining until the end of the specified maintenance interval.

The current status can be seen in the status display.

Messages and alarms indicate when a task has to be performed.

#### Acknowledging a maintenance task

Acknowledge the message when a maintenance task has been completed.

#### Note

#### **Protection level**

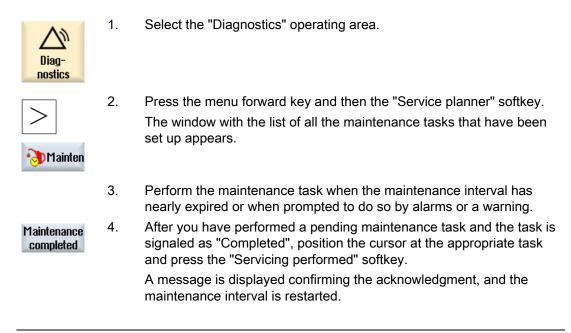
You require protection level 2 (service) to acknowledge completed maintenance tasks.

#### Service Planner

Display	Meaning	
Pos	Position	n of the maintenance task in the PLC interface.
Maintenance task	Name c	of the maintenance task.
Interval [h]	Maximum time until next servicing in hours.	
Remaining time [h]	Time until the interval expires in hours.	
Status		Display of the current status of a maintenance task.
	✓ ● ×	The maintenance task has been started. The maintenance task is completed. The maintenance task is deactivated.

18.1 Performing and monitoring maintenance tasks

#### Procedure



#### Note

You can perform the maintenance tasks before the interval expires. The maintenance interval is restarted.

## 18.2 Set maintenance tasks

You can make the following changes in the list of maintenance tasks in the configuration mode:

- Set up a maximum of 32 maintenance tasks with interval, initial warning and number of warnings to be acknowledged
- Change the interval, time of the initial warning and the number of warnings to be output
- Delete a maintenance task
- Reset the times of the maintenance tasks

#### Acknowledging a maintenance task

You can acknowledge the maintenance tasks with the "Servicing performed" softkey.

#### Note

#### Protection level

You require protection level 1 (manufacturer) to set up and edit maintenance tasks.

#### Service Planner

Display	Meaning		
Pos	Position of the maintenance task in the PLC interface.		
Maintenance task	Name o	of the maintenance task.	
Interval [h]	Maximu	um time until next servicing in hours.	
1st warning [h]	Time in	hours at which an initial warning is displayed.	
Number of warnings	Number of warnings that can be acknowledged by the operator before an alarm message is output for the last time.		
Remaining time [h]	Time until the interval expires in hours.		
	The rer	naining time cannot be edited.	
Status		Display of the current status of a maintenance task.	
	$\checkmark$	The maintenance task has been started.	
	•	The maintenance task is completed.	
	×	The maintenance task is deactivated, i.e. the time has been stopped.	
	The sta	tus cannot be edited.	

18.2 Set maintenance tasks

Diag- nostics	1.	Select the "Diagnostics" operating area.
> Mainten	2.	Press the menu forward key and then the "Service planner" softkey. The window opens and displays a list of all the tasks that have been set up. The values cannot be edited.
New task	3.	Press the "New maintenance task" softkey to set up a new maintenance task.
ОК		A message informs you that a new maintenance task will be set up at the next free position. Enter the required data in the columns and press the "OK" softkey. - OR -
Change task		Position the cursor on the desired maintenance task and press the "Change task" softkey to change the associated times. All columns except Remaining time and Status can be edited. - OR -
Reset all		Press the "Reset all" softkey to reset all the times.
		- OR -
Delete task		Position the cursor on the desired maintenance task and press the "Delete task" softkey to remove the maintenance task from the list.

# Ladder Viewer and Ladder add-on (828D only)

## 19.1 PLC diagnostics

A PLC user program consists to a large degree of logical operations to implement safety functions and to support process sequences. These logical operations include the linking of various contacts and relays. These logic operations are displayed in a ladder diagram.

#### Ladder add-on tool

As a rule, the failure of a single contact or relay results in a failure of the whole system.

Using the Ladder add-on tool, you can perform a PLC diagnosis in order to find fault causes or program errors.

#### Editing of interrupt routines

You can edit the following interrupt programs:

- INT\_100 interrupt program, (is executed before the main program)
- INT\_101 interrupt program, (is executed after the main program)

#### Marshalling data

Using the Ladder add-on tool, you can "re-wire" inputs (via INT\_100) or outputs (via INT\_101) for service purposes.

#### Generating INT\_100 / INT\_101 block

If one or several INT\_100 or INT\_101 blocks are missing, they can be added via the vertical softkey bar. If these INT blocks exist in a project, they can be deleted via the vertical softkey bar. You also have the opportunity to change the networks of a program on the control as well as to save and load these changes.

#### Note

#### Saving the PLC project when changing the operating area

If you have created INT\_100/INT\_101 blocks or inserted, removed or edited networks in an INT block, you must save the project before you change from the PLC area into another operating area. Transfer the project into the PLC using the "Download to CPU" softkey. If this is not done, all of the changes will be lost and must be re-entered.

19.2 Structure of the user interface

## 19.2 Structure of the user interface

HMI	_ 🗆 ×
	05/13/09 <mark>2</mark> 11:00 AM
SIMATIC LAD         MCP_310 (SBR1)         Run         Sym         ♦         ♥           Network 1         2         SET J06         3         ④         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ●         ● <td>Program block</td>	Program block
	Program stat. OFF
	Absolute address
Network 2 Jog Active	Zoom+
Network 3 SET MDA	
	Search
Network 4 MDA Active	_
Network 3 Line 2, Column 1	Symbol info
PLC - CPU         NC/PLC status         Status list         Window 1 SBR1         Window 2 SBR3         Symbol table	Cross refs.

Figure 19-1 Screen structure

Table 19- 1	Key to screen	lavout
-------------	---------------	--------

Screen element	Display	Meaning
1	Application area	
2	Supported PLC prog	ram language
3	Name of the active p	program block
	Representation: Syn	nbolic name (absolute name)
4	Program status	
	Run Abs	
	Run	Program is running
	Stop	Program is stopped
Status of the application area		tion area
	Sym	Symbolic representation
	Abs	Absolute representation
5	Display of the active keys ( <input/> , <select>)</select>	

19.2 Structure of the user interface

Screen element	Display	Meaning
6	Focus	
	Performs the tasks of the cursor	
7	Information line	
	Displays information, e.g. for searching	

19.3 Control options

## 19.3 Control options

In addition to the softkeys and the navigation keys, there are further shortcuts in this area.

#### Shortcuts

The cursor keys move the focus over the PLC user program. When the window borders are reached, scrolling is performed automatically.

Shortcuts	Action
	To the first column of the row
END	To the last column of the row
CTRL	
PAGE	Up a screen
PAGE	Down a screen
	One field to the left, right, up or down
	To the first field of the first network
-or-	
CTRL	
CTRL END	To the last field of the last network
-or-	

19.3 Control options

Shortcuts		Action
CTRL		
CTRL	PAGE UP	Open the next program block in the same window
CTRL	PAGE DOWN	Open the previous program block in the same window
SELECT		<ul> <li>The function of the Select key depends on the position of the input focus.</li> <li>Table line: Displays the complete text line</li> <li>Network title: Displays the network comment</li> <li>Command: Displays all operands</li> </ul>
INPUT		If the input focus is positioned on a command, all operands including the comments are displayed.

19.4 Displaying PLC properties

## 19.4 Displaying PLC properties

The following PLC properties can be displayed in the "SIMATIC LAD" window:

- Operating mode
- Name of the PLC project

1.

- PLC system version
- Cycle time
- Machining time of the PLC user program

#### Procedure



Reset pro. time

- Select the "Start-up" operating area.
- 2. Press the "PLC" softkey. The ladder diagram display opens and displays the PLC information.
- Press the "Reset mach.time" softkey.
   The data of the machining time is reset.

#### 19.5 Displaying and editing NC/PLC variables

The "NC/PLC Variables" window enables the monitoring and modification of NC system variables and PLC variables.

You receive the following list in which you enter the desired NC and PLC variables in order to display the actual values.

Variable

Address for NC/PLC variable.

Faulty variables have a red background and # is displayed in the Value column.

Comment •

Arbitrary comment on the variables.

The column can be shown or hidden.

Format

Specification of the format in which the variable is to be displayed. The format can be permanently defined (e.g. floating-point).

Value •

Display of the current value of the NC/PLC variable.

#### Procedure



1.

2.

Ladder add-on tool is opened.

- status
- Press the "NC/PLC variables" softkey. The "NC/PLC Variables" window appears.

19.6 Displaying and editing PLC signals

## 19.6 Displaying and editing PLC signals

PLC signals are displayed and can be changed here in the "PLC status list" window.

### The following lists are shown

Inputs (IB) Bit memories (MB) Outputs (QB) Variables (VB) Data (DB)

#### Setting the address

You can go directly to the desired PLC address to monitor the signals.

#### Editing

You can edit the data.

PLC - CPU	1.	Ladder add-on tool is opened.
Status list	2.	Press the "Status list" softkey. The "Status List" window appears.
Set address	3.	Press the "Set address" softkey. The "Set Address" window appears.
OK	4.	Activate the desired address type (e.g. DB), enter the value and press the "OK" softkey.
Change	5.	The cursor jumps to the specified address. Press the "Change" softkey. The "RW" input field can be edited.
ок	6.	Enter the desired value and press the "OK" softkey.

## 19.7 Displaying information on the program blocks

You can display all the logic and graphic information of a program block.

#### Display program block

In the "Program block" list, select the program block that you want to display.

#### Logic information

The following logic information is displayed in a ladder diagram (LAD):

- Networks with program parts and current paths
- Electrical current flow through a number of logical operations

#### **Further information**

Properties

Name of the block, author, number of the subprogram, data class, date it was generated, date of the last change and comment.

Local variable

Name of the variable, variable type, data type and comment.

#### Access protection



If a program block is password-protected. The ladder diagram display can be enabled using the "Protection" softkey.

#### Displaying the program status

Program<br/>stat. OFF1.Press the "Program stat. OFF" softkey to hide the program status in<br/>the status display.



2. Press the "Program stat. ON" softkey to unhide the program status in the status display.

#### Enlarging/reducing the display of the ladder diagram



Zoom -

1. Press the "Zoom +" softkey to enlarge the section of the ladder diagram.

After enlarging, the "Zoom -" softkey is available.

2. Press the "Zoom -" softkey to reduce the section of the ladder diagram again.

Ladder Viewer and Ladder add-on (828D only)

19.7 Displaying information on the program blocks

PLC – CPU	1.	Ladder add-on tool is opened.
Window 1 OB1	2.	Press the "Window 1" or "Window 2" softkey.
Program	3.	Press the "Program block" softkey.
block		The "Program block" list is displayed.
Proper- ties	4.	Press the "Properties" softkey if you wish to display additional information.
		- OR -
Local variables		Press the "Local variables" softkey if you wish to display data of a variable.

## 19.8 Downloading a PLC user program

Download the project data into the PLC if some changes have been made to the project data and a new PLC user program is available.

When the project data is loaded, the data classes are saved and loaded to the PLC.

#### Requirement

Check whether the PLC is in Stop mode.

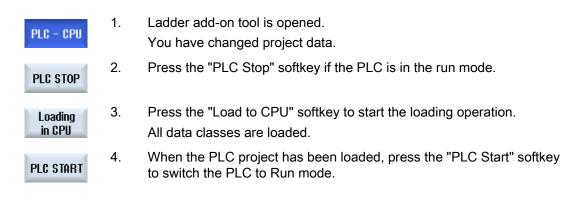
#### Note

#### PLC in RUN mode

If the PLC is in RUN mode, a corresponding message is displayed and the "Load in Stop" and "Load in Run" softkeys appear.

With "Load in Stop", the PLC is set to Stop mode and the project is stored and loaded to the CPU.

With "Load in Run", the loading operation is continued and the PLC project loaded to the PLC. Only those data classes that have really been changed are loaded, i.e. generally INDIVIDUAL data classes.



19.9 Editing the local variable table

## 19.9 Editing the local variable table

You have the option of editing the local variable table of an INT block.

#### Insert local variable

If you have inserted new networks or operands, it may be necessary to insert new variables in the local variable table of an INT block.

Name	Freely assign.
Variable type	Selection:
	• IN
	<ul> <li>IN_OUT</li> </ul>
	• OUT
	TEMP
Data type	Selection:
	BOOL
	<ul> <li>BYTE</li> </ul>
	WORD
	• INT
	DWORD
	DINT
	REAL
Comment	Freely assign.

Window 1 OB1	1.	The ladder diagram display (LAD) is opened.
Window 2 SBR0		
Program block	2.	Press the "Program block" softkey.
Local variables	3.	Press the "Local variables" softkey. The "Local Variables" window appears and lists the created variables.
Edit	4.	Press the "Edit" softkey. The fields can be edited.
SELECT	5.	Enter a name, select the variable and data type and, if required, enter a comment.



6.

Press the "Attach line" softkey if you want to add a further variable and enter the data.

- OR -

Delete line Select the relevant variable and press the "Delete line" softkey to remove the variable from the list.

19.10 Creating a new block

## 19.10 Creating a new block

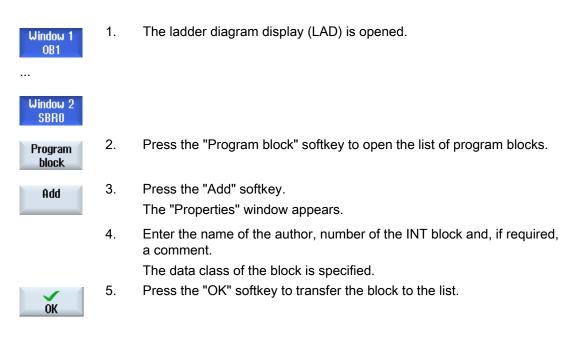
Create INT blocks i you wish to make changes with the PLC user program.

Name	INT _100, INT_101 The number from the selection field "Number, interrupt program" is
	taken for the name of the INT block.
Author	A maximum of 48 characters is permitted.
Number of the	100
interrupt program	101
Data class	Individual
Comment	A maximum of 100 lines and 4096 characters are permitted.

#### Note

#### Access protection

You have the option of protecting blocks that have been newly created against being accessed.

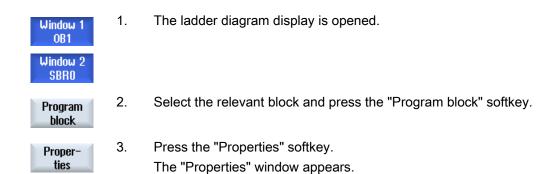


## 19.11 Editing block properties

You can edit the title, author and comments of an INT block.

#### Note

You cannot edit the block name, interrupt number and data class assignment.



19.12 Inserting and editing networks

## 19.12 Inserting and editing networks

You can create a new network and then insert operations (bit operation, assignment, etc.) at the selected cursor position.

Only empty networks can be edited. Networks, that already include statements, can only be deleted.

A simple, single line can be edited for each network. You can create a maximum of 3 columns per network.

Column	Operation	
Column 1	NO contact	-   -
	NC contact	- / -
Column 2	NOT	- NOT -
(optional)	Rising edge	- P -
	Falling edge	- N -
	Assign	-( )
	Set	-(S)
	Reset	-(R)
Column 3	Assign	-( )
(only possible if no assign, set or reset	Set	-(S)
operations were specified in the second column)	Reset	-(R)

#### Note

Logical AND (serial contact) and logical OR (parallel contact) are not possible.

The bit combinations comprise one or several logical operations and the assignment to an output / bit memory.

If the cursor is moved further to the left with the arrow key, the type of assignment or a logic operation can be selected. A further logic operation cannot be placed to the right of an assignment. A network must always be terminated with an assignment.

#### References

For further information about PLC programming, please refer to: Function Manual, Basic Functions, Basic PLC Program SINUMERIK 828D (P3-828D)

# Ladder Viewer and Ladder add-on (828D only)

19.12 Inserting and editing networks

#### Procedure

Window 1 INT101	1.	An interrupt routine has been selected.
Edit	2.	Press the "Edit" softkey.
	3.	Position the cursor on a network.
Insert network	4.	Press the "Insert network" softkey.
		- OR -
INSERT		Press the <insert> key.</insert>
		A new, empty network is inserted behind the network in which the cursor is positioned.
Insert operation	5.	Position the cursor on the desired element below the network title and press the "Insert operation" softkey.
		The "Insert Operation" window appears.
ОК	6.	Select the desired bit operation (NC contact or NO contact) or assignment and press the "OK" softkey.
Insert operand	7.	Press the "Insert operand" softkey.
INPUT	8.	Enter the logic operation or the command and press the <input/> key to complete the entry.
Delete operation	9.	Position the cursor on the operation that you want to delete and press the "Delete operation" softkey.
		- OR -
Delete network		Position the cursor on the title of the network that you want to delete and press the "Delete network" softkey.
		- OR -
DEL		Press the <del> key.</del>

The network, including all the logic operations and operands, or the selected operation is deleted.

19.13 Editing network properties

## 19.13 Editing network properties

You can edit the network properties of an INT block.

#### Network title and network comment

The title can have a maximum of three lines and 128 characters. The comment can have a maximum of 100 lines and 4096 characters.

Window 1 OB1	1.	The ladder diagram display (LAD) is opened.
Window 2 SBR0		
	2.	Use the cursor keys to select the network that you want to edit.
$\left( \right)$	3.	Press the <select> key.</select>
SELECT		The "Network title / comment" window opens and shows the title and a possibly assigned comment for the selected network.
Change	5.	Press the "Change" softkey.
		The fields can be edited.
ОК	6.	Enter the changes and press the "OK" softkey to transfer the data to the user program.

## 19.14 Displaying and editing symbol tables

You can display the symbol tables that are used to obtain an overview of the global operands available in the project - which you can then edit.

The name, address and possibly also a comment is displayed for each entry.

PLC - CPU	1.	Ladder add-on tool is opened.
Symbol table	2.	Press the "Symbol table" softkey. The list with the symbol table entries is displayed.
Edit	3.	Press the "Edit" softkey if you want to change entries. The display fields can be edited.
	4.	Use the cursor keys to select the desired entry and the field to be changed.
	5.	Enter the value to be changed. - OR -
Add line		Press the "Attach line" softkey to insert an empty line after the selected entry.
		- OR - Drace the "Delete line" eafliers to remove the celected entry from the
Delete line		Press the "Delete line" softkey to remove the selected entry from the list.
		- OR -
		Enter a new value in the selected field.
OK	7.	Press the "OK" softkey to confirm your action.

19.15 Inserting/deleting a symbol table

## 19.15 Inserting/deleting a symbol table

New user symbol tables can be generated and changed. Tables that are no longer used can be deleted.

#### Note

#### Delete symbol table

The "Delete" softkey is only available if a user symbol table has been selected.

Symbol table	1.	The symbol table is opened.
Select sym table	2.	Press the "Select sym. table" softkey. The "Symbol Table - Selection" window appears.
Insert sym table	3.	Position the cursor at the desired position and press the "Insert sym. table" softkey.
		The "Create Symbol Table" window appears.
ОК	4	Enter a symbolic name and press the "OK" softkey. The new user symbol table is inserted in the line after the cursor position. - OR -
Change sym table		Select a symbol table and press the "Change symbol table" softkey if you wish to change the properties of the symbol table.
Delete	5.	Position the cursor on the symbol table that you want to delete and press the "Delete" softkey.

## 19.16 Searching for operands

You can use the search function to quickly reach points in very large programs where you would like, for example, to make changes.

#### Restricting the search

• "Window 1" / "Window 2","Symbol table"

With "Go to", you can jump directly to the desired network.

• "Cross references"

With "Go to", you can jump directly to the desired line.

#### Requirement

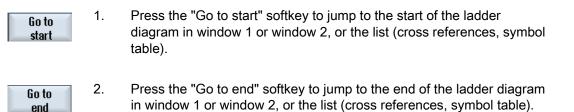
Window 1/window 2, the symbol tables or the list of cross references is opened.

Search	1.	Press the "Find" softkey.
		A new vertical softkey bar appears. The "Find / Go To" window opens at the same time.
SELECT	2.	Select the "Find operand" entry in the first input field if you are searching for a specific operand and enter the search term in the "Find" input field.
SELECT	3.	Select the search range (e.g. Find all).
SELECT	4.	Select the "In this program unit" or "In all program units" entry if you are in "Window 1" or "Window 2" or in the symbol table in order to restrict the search.
	5.	Press the "OK" softkey to start the search.
ОК		If the operand you are searching for is found, the corresponding line is highlighted.
Continue search		Press the "Continue search" softkey if the operand found during the search does not correspond to the element you are looking for.
		- OR -
X Cancel		Press the "Cancel" softkey if you want to cancel the search.

end

19.16 Searching for operands

#### Further search options



19.17 Displaying the network symbol information table

## 19.17 Displaying the network symbol information table

All of the symbolic identifiers used in the selected network are displayed in the "Network symbol information table" window.

The following information is listed:

1.

- Names
- Absolute addresses
- Comments

The symbol information table remains empty for networks that do not contain any global symbols.

#### Procedure



The ladder diagram display (LAD) is opened.



- Symbol 2. info
- Select the desired network and press the "Symbol info" softkey. The "Network Symbol Information Table" window appears.
  - 3. Use the cursor keys to move within the table.

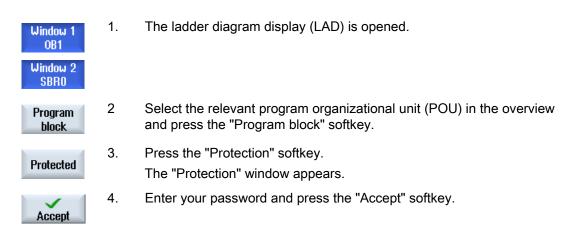


19.18 Displaying/canceling the access protection

## 19.18 Displaying/canceling the access protection

You can password protect your program organizational units (POUs) in the PLC 828 programming tool. This prevents other users from accessing this part of the program. This means that it is invisible to other users and is encrypted when it is downloaded.

A lock symbol is used to show a password-protected POU in the block overview and in the ladder diagram.



#### 19.19 **Displaying cross references**

You can display all the operands used in the PLC user project and their use in the list of cross references.

This list indicates in which networks an input, output, bit memory etc. is used.

The list of cross references contains the following information:

- Block
- Address in the network
- Context (command ID)

#### Symbolic and absolute address

You can choose between specification in absolute or symbolic address.

Elements for which there are no symbolic identifiers are automatically displayed with absolute identifiers.

#### Opening program blocks in the ladder diagram

From the cross references, you have the option of going directly to the location in the program where the operand is used. The corresponding block is opened in window 1 or 2 and the cursor is set to the corresponding element.

#### Searching

Using a specific search, you can go directly to the location that you wish to view in more detail:

- Search for operand •
- Jump to sought line •

PLC - CPU	1.	Ladder add-on tool is opened.
Cross refs.	2.	Press the "Cross refs." softkey.
		The list of cross references appears and the operands are displayed sorted according to absolute address.
Symbolic address	3.	Press the "Symbol. address" softkey.
		The list of operands is displayed sorted according to symbolic address.
Absolute address	4.	Press the "Absolute address" softkey to return to the display showing the absolute addresses.

Ladder Viewer and Ladder add-on (828D only)

19.19 Displaying cross references

Open in window 1 Open in window 2	5.	Select the desired cross reference and press the "Open in window 1" or "Open in window 2" softkey. The ladder diagram is opened, and the selected operand is marked.
Search	6.	Press the "Find" softkey. The "Find / Go To" window appears.
SELECT	7.	Select "Find operand" or "Go to" and enter the sought element or the desired line and select the search order (e.g. search up).
ОК	8.	Press the "OK" softkey to start the search.
Continue search	9.	If an an element is found that corresponds to the sought element, but is not at the appropriate position, press the "Continue search" softkey to find where the search term occurs next.

# 20

## Alarms, error messages, and system alarms

## 20.1 Displaying alarms

If faulty conditions are recognized in the operation of the machine, then an alarm will be generated and, if necessary, the machining will be interrupted.

The error text that is displayed together with the alarm number gives you more detailed information on the error cause.

#### 

Please check the situation in the plant on the basis of the description of the active alarm(s). Eliminate the cause/s of the alarm/s and acknowledge it/them as instructed.

Failure to observe this warning will place your machine, workpiece, stored settings and possibly even your own safety at risk.

#### Alarm overview

You can display all upcoming alarms and acknowledge them.

The alarm overview contains the following information:

- Date and time
- Deletion criterion

specifies the key or softkey used to acknowledge the alarm

- Alarm number
- Alarm text

#### Procedure



1. Select the "Diagnostics" operating area.



Press the "Alarm list" softkey.
 The "Alarms" window appears.
 All pending alarms are displayed.
 The "Hide SI alarms" softkey is displayed if safety alarms are pending.

20.1 Displaying alarms

3.	Press the "Hide SI alarms" softkey if you do not wish to display SI alarms.
3.	Position the cursor on an alarm.
4.	Press the key that is specified as acknowledgement symbol to delete the alarm. - OR -
	Press the "Delete HMI alarm" softkey to cancel an HMI alarm.
	- OR -
	Press the "Acknowledge alarm" softkey to delete a PLC alarm of the SQ type (alarm number as of 800000). The softkeys are activated when the cursor is on the corresponding alarm.
	3.

#### Acknowledgement symbols

Symbol	Meaning
	Turn the unit off and back on (main switch), or press NCK POWER ON.
//	Press the <reset> key.</reset>
	Press the <alarm cancel=""> key. - OR - Press the "Acknowl. HMI alarm" softkey.</alarm>
PLC	Press the key provided by the manufacturer.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

Alarms, error messages, and system alarms 20.2 Displaying an alarm log

# 20.2 Displaying an alarm log

A list of all the alarms and messages that have occurred so far are listed in the "Alarm Log" window.

Up to 500 administered, incoming and outgoing events are displayed in chronological order.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

#### Procedure



- 1. Select the "Diagnostics" operating area.
- Alarm protoc.
- 2. Press the "Alarm log" softkey.

The "Alarm Log" window opens. All of the coming and going events - that have occurred since the HMI

Display new 3.

#### was started - are listed. Press the "Display new" softkey to update the list of displayed alarms/messages.

Store Ioa  Press the "Save Log" softkey.
 The log that is currently displayed is stored as text file alarmlog.txt in the system data in directory card/user/sinumerik/hmi/log/alarm\_log. 20.3 Displaying messages

# 20.3 Displaying messages

PLC and part program messages may be issued during machining.

These message will not interrupt the program execution. Messages provide information with regard to a certain behavior of the cycles and with regard to the progress of machining and are usually kept beyond a machining step or until the end of the cycle.

#### Overview of messages

You can display all issued messages.

The message overview contains the following information:

- Date
- Message number is only displayed for PLC messages
- Message text

#### Proceed as follows



٧١)

- Select the "Diagnosis" operating area.
- Mes- 2. Pres sages The

1.

Press the "Messages" softkey. The "Messages" window appears.

# 20.4 PLC and NC variables

### 20.4.1 Displaying and editing PLC and NC variables

The "NC/PLC variables" window allows NC system variables and PLC variables to be monitored and changed.

You receive the following list in which you can enter the desired NC/PLC variables in order to display the actual values.

Variable

Address for NC/PLC variable

Incorrect variables have a red background and are displayed with a # character in the value column.

• Comment

Any comment on the variable.

The columns can be displayed and hidden.

• Format

Specify the format in which the variable is to be displayed.

The format can be specified (e.g. floating point)

• Value

Displays the actual value of the NC/PLC variables

PLC variables		
Inputs	Input bit (Ex), input byte (EBx), input word (EWx), input double word (EDx)	
Outputs	Output bit (Ax), output byte (ABx), output word (AWx), output double word (ADx)	
Bit memory	Memory bit (Mx), memory byte (MBx), memory word (MWx), memory double word (MDx)	
Times	Time (Tx)	
Meters	Counter (Cx)	
Data	Data block (DBx), data bit (DBXx), data byte (DBBx), data word (DBWx), data double word (DBDx)	

Formats	
В	Binary
Н	Hexadecimal
D	Decimal without sign
+/-D	Decimal with sign
F	Floating point (for double words)
A	ASCII characters

20.4 PLC and NC variables

#### Notation for variables

PLC variables

EB2

A1.2

DB2.DBW2

- NC variables
  - NC system variables notation
     \$AA\_IM[1]
  - User variables/GUDs notation
     GUD/MyVariable[1,3]
  - OPI notation

/CHANNEL/PARAMETER/R[u1,2]

### Note

### NC system variables and PLC variables

- System variables can be dependent on the channel. When the channel is switched over, the values from the corresponding channel are displayed.
- For user variables (GUDs) it is not necessary to make a specification according to global or channel-specific GUDs. The indices of GUD arrays are, just like NC variables in the system variable syntax, 0-based; this means that the first element starts with the index 0.
- Using the tooltip, for NC system variables, you can display the OPI notation (with the exception of GUDs).

#### **Changing PLC variables**

Changes can only be made to the PLC variables with the appropriate password.

## 

Changes in the states of NC/PLC variables have a major impact on the machine. Incorrect configuration of the parameters can endanger human life and cause damage to the machine.

Alarms, error messages, and system alarms

20.4 PLC and NC variables

### Changing and deleting values

Diag- nostics	1.	Select the "Diagnostics" operating area.
V NC/PLC variab.	2.	Press the "NC/PLC variab." softkey.
		The "NC/PLC variables" window opens.
	3.	Position the cursor in the "Variable" column and enter the required variable.
	4.	Press the <input/> key.
INPUT		The operand is displayed with the value.
	5.	Press the "Details" softkey.
Details		The "NC/PLC variables: Details" window opens. The information for "Variable", "Comment" and "Value" are displayed in the full length.
SELECT	6.	Position the cursor in the "Format" field and choose the required format with <select>.</select>
Display	7.	Press the "Display comments" softkey.
comments		The "Comments" column is displayed. You have the option of creating comments or editing existing comments.
Display comments		Press the "Display comments" softkey once again to hide the column again.
Change	8.	Press the "Change" softkey if you would like to edit the value. The "Value" column can be edited.
Insert variable	9.	Press the "Insert variable" softkey if you wish to select a variable from a list of all of the existing variables and insert this.
		The "Select variable" window opens.
Filter/ search	10.	Press the "Filter/search" softkey to restrict the display of variables (e.g. to mode groups-variables) using the "Filter" selection box and/or select the desired variable using the "Search" input box.
Delete all		Press the "Delete all" softkey if you would like to delete the entries for the operands.
ок	11.	Press the "OK" softkey to confirm the changes or the deletion.
		- OR -
X Cancel		Press the "Cancel" softkey to cancel the changes.

20.4 PLC and NC variables

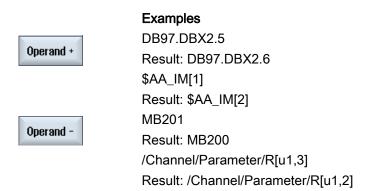
#### Changing operands

Depending on the type of operand, you can increment or decrtement the address by 1 place at a time using the "Operand +" and "Operand -" softkeys.

#### Note

#### Axis names as index

For axis names, the softkeys "Operand +" and "Operand -" do not act as index, e.g. for \$AA\_IM[X1].



#### 20.4.2 Saving and loading screen forms

You have the option of saving the configurations of the variables made in the "NC/PLC variables" window in a screen form that you reload again when required.

#### Editing screen forms

If you change a screen form that has been loaded, then this is marked using with \* after the screen form name.

The name of a screen form is kept in the display after switching-off.

#### Procedure

1. You have entered values for the desired variables in the "NC/PLC variables" window.



2. Press the ">>" softkey.

Save screen	3.	Press the "Save screen" softkey. The "Save screen: Select archiving" window opens.
ок	4.	Position the cursor on the template folder for variable screen forms in which your actual screen form should be saved and press the "OK" softkey.
		The "Save screen: Name" window opens.
ОК	5.	Enter the name for the file and press the "OK" softkey.
		A message in the status line informs you that the screen form was saved in the specified folder.
		If a file with the same name already exists, they you will receive a prompt.
Load mask	6.	Press the "Load screen" softkey.
		The "Load screen" window opens and displays the sample folder for the variable screen forms.
	7.	Select the desired file and press the "OK" softkey.
		You return to the variable view. The list of all of the predefined NC and PLC variables is displayed.

### 20.4.3 Loading PLC symbols

PLC data can also be edited via symbols.

To do this, the symbol tables and texts for the symbols in the PLC project must have been suitably prepared (STEP7) and made available in SINUMERIK Operate.

#### Preparing PLC data

Save the generated files in the /oem/sinumerik/plc/symbols directory.

### Procedure



- 1. The variable view is opened.
- Press the ">>" and "Load icons" softkeys.
   The "Import PLC symbols: \*.snh" window opens.





3. In the folder "/oem/sinumerik/plc/symbols", select the "PlcSym.snh" file to import the symbols and then click on "OK".

 In the folder "/oem/sinumerik/plc/symbols", select the "PlcSym.snt" file to import the symbols and then press the "OK" softkey. You will obtain an appropriate note if the tables were successfully imported.
 Press the "OK" softkey. You return to the "NC/PLC variables" window.
 Restart the SINUMERIK Operate in order to activate the files.

#### 20.5 Version

#### 20.5 Version

#### 20.5.1**Displaying version data**

The following components with the associated version data are specified in the "Version data" window:

- System software
- Basic PLC program
- PLC user program
- System extensions •
- OEM applications
- Hardware

Information is provided in the "Nominal version" column as to whether the versions of the components deviate from the version supplied on the CompactFlash Card.



The version displayed in the "Actual version" column matches the version of the CF card.



The version displayed in the "Actual version" column does not match the version of the CF card.

You may save the version data. Version displays saved as text files can be further processed as required or sent to the hotline in the event of an error.

#### Procedure



1. Select the "Diagnosis" operating area.



2.

3.

4.

Press the "Version" softkey. The "Version Data" window appears. Data from the available components are displayed.



Select the component for which you would like more information.



Details

Press the "Details" softkey, in order to receive more exact information on the components displayed.

20.5 Version

### 20.5.2 Save information

All the machine-specific information of the controller is combined in a configuration via the user interface. You can save machine-specific information on the drives that have been setup.

#### Procedure



1.

2.

3.

Select the "Diagnostics" operating area.



Press the "Version" softkey. It takes some time to call the version display. While the version data is being determined a progress message box and the appropriate text are displayed in the dialog line.



Press the "Save" softkey.

The "Save version information: Select archive" window opens. The following storage locations are offered depending on the configuration:

- Local drive
- Network drives
- USB
- Version data (archive: Data tree in the "HMI data" directory)



Then press the "New directory" softkey if you wish to create your own directory.



0K

Press the "OK" softkey. The directory is created.

4. Press the "OK" softkey again to confirm the storage location.

The "Save version information: Name" window opens. The following options are available:

- In the "Name:" text field, The file name is pre-assigned with <Machine name/no.>+<CF-card number>. "\_config.xml" or "\_version.txt" is automatically attached to the file names.
- In text field "Comment", you can add a comment, which is stored with the configuration data.

Select the following via a checkbox:

- Version data (.TXT): Output of pure version data in text format.
- Configuration data (.XML): Output of configuration data in XML format. The configuration file contains the data you entered under Machine identity, the license requirements, the version information and the logbook entries.



5. Press the "OK" softkey to start the data transfer.

#### 20.6 Logbook

# 20.6 Logbook

The logbook provides you with the machine history in an electronic form.

If service is carried out on the machine, this can be electronically saved. This means that it is possible to obtain a picture about the "History" of the control and to optimize service.

#### Editing the logbook

You can edit the following information:

- Editing information on the machine identity
  - Machine name/No.
  - Machine type
  - Address data
- Make logbook entries (e.g. "filter replaced")

#### Output of the logbook

You have the possibility of exporting the logbook by generating a file using the "Save version" function in which the logbook is contained as section.

### 20.6.1 Displaying and editing the logbook

#### Procedure

- 1.
   Select the "Diagnostics" operating area.

   Diagnostics
   2.

   Version
   2.
  - Logbook
     3.
     Press the "Logbook" softkey.

     The "Machine logbook" window opens.

#### Editing end customer data

Change You have the option of changing the address data of the end customer using the "Change" softkey.

20.6 Logbook

#### 20.6.2 Making/searching for a logbook entry

Using the "New logbook entry" window to make a new entry into the logbook.

Enter your name, company and department and a brief description of the measure taken or a description of the fault.

#### Note

If you wish to make line breaks in the "fault diagnostics/measure" field, use the key combination <ALT> + <INPUT>.

The date and entry number are automatically added.

### Sorting the entries

The logbook entries are displayed numbered in the "machine logbook" window.

More recent entries are always added at the top in the display.

### Procedure

	1.	The logbook is opened.
New entry	2.	Press the "New entry" softkey.
		The "New logbook entry" window opens.
<b>ок</b> 3.	Enter the required data and press the "OK" softkey.	
		You return to the "Machine logbook" window and the entry is displayed below the machine identity data.

#### Note

Once you have stored an entry this can no longer be changed or deleted.

### Searching for a logbook entry

You have the option for searching for specific entries using the search function.

Search	
Search	

- The "Machine logbook" window is opened. 1.
- 2. Press the "Search..." softkey and enter the desired term in the search form. You can make a search according to date/time, company name/department or according to fault diagnostics/measure. The cursor is positioned on the first entry that corresponds to the search term.



Press the "Continue search" softkey if the entry found is not the one that you are looking for.

20.6 Logbook

### Additional search option



Press the "Go to Beginning" softkey to start the search at the latest entry.

Press the "Go to End" softkey to start the search at the oldest entry.

Alarms, error messages, and system alarms 20.7 Creating screenshots

# 20.7 Creating screenshots

You can create screenshots of the current user interface. Each screenshot is saved as a file and stored in the following folder: /**user**/sinumerik/hmi/log/screenshot

### Procedure

Ctrl + P Press the <Ctrl+P> key combination. A screenshot of the current user interface is created in .png format. The file names assigned by the system run in ascending order from "SCR\_SAVE\_0001.png" to "SCR\_SAVE\_9999". You can create up to 9,999 screenshots.

### Copy file



- 1. Select the "Start-up" operating area.
- P System data
- 2. Press the "System data" softkey and open the specified folder.

As you cannot open screenshots in SINUMERIK Operate, you must copy the files to a Windows PC either via "WinSCP" or via a USB FlashDrive.

You can open the files using a graphics program, e.g. "Office Picture Manager".

# 20.8 Remote diagnostics

#### 20.8.1 Setting remote access

You can influence the remote access to your control in the "Remote diagnostics (RCS)" window.

Here, rights for all types of remote control are set. The selected rights are defined from the PLC and using the setting at the HMI.

The HMI can restrict the rights specified from the PLC, but however, cannot extend the rights beyond the PLC rights.

If the settings made permit access from outside, then this is still dependent on a manual or automatic confirmation.

#### **Rights for remote access**

The "Specified from PLC" field shows the access rights for remote access or remote monitoring specified from the PLC.

#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

In the "Selected in the HMI" selection box, you have the possibility of setting rights for remote control:

- Do not permit remote access
- Permit remote monitoring
- Permit remote control

The combination of the settings in the HMI and in the PLC show the valid status as to whether access is permitted or not. This is displayed in the "Resulting from" line.

#### Settings for the confirmation dialog box

If the settings made for "Specified from the PLC" and "Selected in the HMI" permit access from outside, then this is however, still dependent on either a manual or automatic confirmation.

As soon as a remote access is permitted, at all of the active operating stations, a query dialog box is displayed for the operator at the active operating station to either confirm or reject an access.

For the case that there is no local operation, then the control behavior can be set for this particular scenario. You define how long this window is displayed and whether, after the confirmation has expired, the remote access is automatically rejected or accepted.

Alarms, error messages, and system alarms 20.8 Remote diagnostics

Display of the state



Remote monitoring active



Remote control active

If remote access is active, using these icons you will be informed in the status line as to whether a remote access is presently active or whether only monitoring is permitted.

#### Procedure

Diag- nostics	1.	Select the "Diagnostics" operating area.
RCS diag.	2.	Press the "Remote diag." softkey. The "Remote diagnostics (RCS)" window is opened.
Change	3.	Press the "Change" softkey. The "Selected in the HMI" is activated.
>	4.	If you desire remote control, select the entry "Permit remote control".
		In order that remote control is possible, the entry "Permit remote control" must be specified in the fields "Specified from the PLC" and "Selected in the HMI".
	5.	Enter new values in the group "Behavior for confirming remote access" if you wish to change the behavior for confirming remote access.
ОК	6.	Press the "OK" softkey. The settings are accepted and saved.

#### References

For a description of configuration options, refer to the Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sI 20.8 Remote diagnostics

### 20.8.2 Permit modem

You can permit remote access to your control via a teleservice adapter IE connected at X127.

202	
-----	--

#### Machine manufacturer

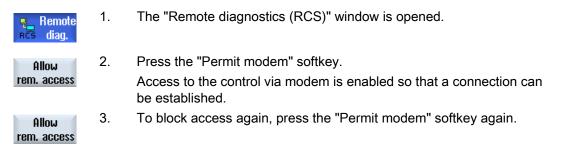
Please refer to the machine manufacturer's specifications.



#### Software option

You need the "MC Information System RCS Host" option to display the "Permit modem" softkey.

#### Procedure



#### 20.8.3 Request remote diagnostics

Using the "Request remote diagnostics" softkey, from your control you have the option of actively requesting remote diagnostics with your machinery construction OEM.

The access via modem must be enabled if the access is to be made via modem.



#### Machine manufacturer

Please refer to the machine manufacturer's specifications.

When requesting remote diagnostics, you obtain a window with the corresponding preassigned data and values of the ping service. If required, you can ask your machine manufacturer for this data.

Data	Meaning	
IP address	IP address of the remote PC	
Port	Standard port that is intended for remote diagnostics	
Send duration	Duration of the request in minutes	

# Alarms, error messages, and system alarms

20.8 Remote diagnostics

Data	Meaning			
Send interval	cle in which the message is sent to the remote PC in seconds			
Ping send data	Message for the remote PC			

### Procedure

Remote RCS diag.	1.	The "Remote diagnostics (RCS)" window is opened.
Request rem.diagn.	2.	Press the "Request remote diagnostics" softkey. The "Request remote diagnostics" window is displayed.
Change	3.	Press the "Change" softkey if you would like to edit the values.
ОК	4.	Press the "OK" softkey. The request is sent to the remote PC.

#### References

Commissioning Manual SINUMERIK Operate (IM9) / SINUMERIK 840D sl

### 20.8.4 Exit remote diagnostics

### Procedure



- 1. The "Remote diagnostics (RCS)" is opened and it is possible that remote monitoring or remote access is active.
- Block modem access if access via modem is to be blocked .
   OR In the "Remote diagnostics (RCS)" window, reset the access right

In the "Remote diagnostics (RCS)" window, reset the access rights to "Permit no remote access" .

Alarms, error messages, and system alarms

20.8 Remote diagnostics

# Appendix



# A.1 Feedback on the documentation

This document will be continuously improved with regard to its quality and ease of use. Please help us with this task by sending your comments and suggestions for improvement via e-mail or fax to:

E-mail: mailto:docu.motioncontrol@siemens.com

Fax: +49 9131 - 98 2176

Please use the fax form on the back of this page.

#### Appendix

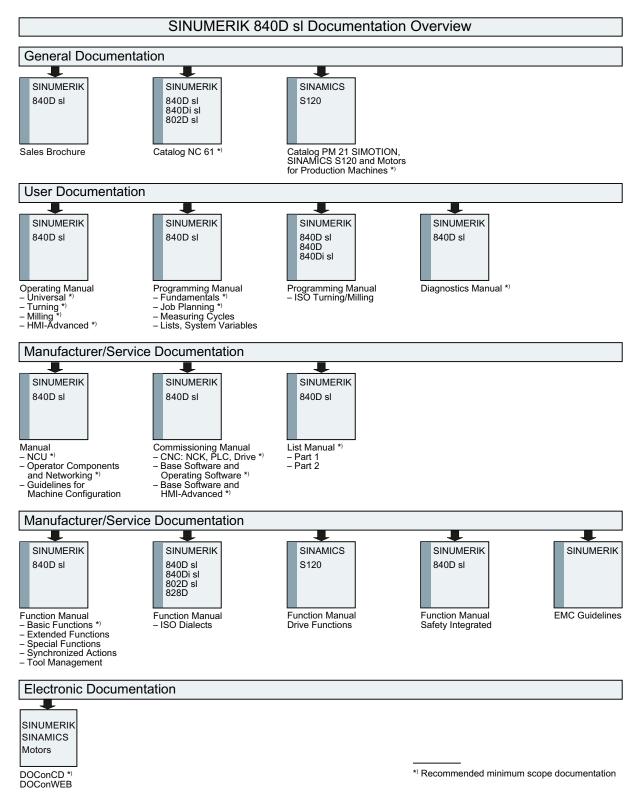
A.1 Feedback on the documentation

То	From
SIEMENS AG I DT MC MS1	Name:
P.O. Box 3180	Address of your company/department
D-91050 Erlangen / Germany	Street:
	Zip code: City:
	Phone: /
Fax: +49 9131 - 98 2176 (Documentation)	Fax: /

Suggestions and/or corrections

A.2 Overview

# A.2 Overview



Appendix

A.2 Overview

# Index

## Α

Actual-value display, 33 Alarm log Display, 613 Alarms, 611 Align milling tool - CYCLE800 Function, 425 Parameter, 426 Any file Create, 525 Arbitrary positions - CYCLE802 Function, 293 Parameter, 293 Archive Generate in the program manager, 540 Generate in the start-up area, 541 Reading in, 543 Asian characters, 44 Auxiliary functions H functions, 171 M functions, 171 Axes Defined increment, 122 Direct positioning, 125 Referencing, 52 Repositioning, 145 Traversing, 122 Variable increment, 123

## В

Backing up Data, 540, 541 Setup data, 544 Base offset, 101 Basic blocks, 140 Binary format, 540 Blank input Function, 210 Parameter, 211 Block Search, 112, 147, 150 Block search, 147 Mode, 152 Program interruption, 112, 150 Search pointer, 112, 147, 150 Search target parameters, 152 Search target specification, 149 Boring - CYCLE86 Function, 281 Parameter, 283

## С

Centering - CYCLE81 Function, 274 Parameter, 275 Changing a program block, 244 Channel switchover, 57 Circle Polar, 442 Circle position pattern - HOLES2 Function, 295 Parameter, 296 Circle with known center point, 437 Circle with known radius, 438 Circular pocket - POCKET4 Function, 304 Parameter, 308 Circular spigot - CYCLE77 Function, 311 Parameter, 313 Circumferential groove - SLOT2 Function, 319 Parameter, 321 Coarse and fine offsets, 101 Context-sensitive online help, 48 Continuous-path mode, 464 Contour call - CYCLE62 Function, 348, 399 Parameter, 349, 400 Contour milling - CYCLE63 Function, contour pocket, 357 Function, contour spigot, 362 Function, residual material contour pocket, 360 Function, residual material contour spigot, 364 Parameter, contour spigot, 363 Parameters, contour pocket, 359 Parameters, residual material contour pocket, 361 Parameters, residual material contour spigot, 365 Contour milling - CYCLE64 Function, predrilling, 354 Parameters, centering, 355 Parameters, predrilling, 356

Contour turning - CYCLE952 Function, grooving, 407 Function, grooving residual material, 409 Function, plunge turning, 411 Function, plunge turning residual material, 414 Function, stock removal, 400 Function, stock removal residual, 405 Parameters, grooving, 409 Parameters, grooving residual material, 411 Parameters, plunge turning, 413 Parameters, plunge turning residual material, 415 Parameters, stock removal, 404 Parameters, stock removal residual material, 406 Coordinate system Switching over, 59 Coordinate transformation, 430 Copying Directory, 533 Program, 533 Creating Any file, 525 Directory, 521 G Code program, 523 Job list, 526 NC directory on the local drive, 514 Program list, 527 Workpiece, 522 Cut-off - CYCLE92 Function, 387 Parameter, 388 Cutting edge, 236 Cutting rated, 237 CYCLE61- face milling Function, 298 Parameter, 300 CYCLE62 - new contour Function, 340, 391 Parameter, 342 CYCLE62- contour call Function, 348, 399 Parameter, 349, 400 CYCLE63 - contour milling Function, contour pocket, 357 Function, contour spigot, 362 Function, residual material contour pocket, 360 Function, residual material contour spigot, 364 Parameter, contour spigot, 363 Parameters, contour pocket, 359 Parameters, residual material contour pocket, 361 Parameters, residual material contour spigot, 365 CYCLE64 - contour milling Function, predrilling, 354

Parameters, centering, 356 Parameters, predrilling, 357 CYCLE70 - engraving Function, 333 Parameters, 338 CYCLE70 - thread milling Function, 330 Parameter, 333 CYCLE72 - Path milling Function, 349 Parameter, 353 CYCLE76 - rectangular spigot Function, 309 Parameter, 311 CYCLE77 - circular spigot Function, 311 Parameter, 313 CYCLE78 - Drilling and thread milling Function, 288 Parameter, 291 CYCLE79 - multi-edge Function, 313 Parameter, 315 CYCLE801 - grid/frame position pattern Function, 294 Parameter, 295 CYCLE802 - arbitrary positions Function, 293 Parameter, 293 CYCLE81 - centering Function, 274 Parameter, 275 CYCLE82 - drilling Function, 276 Parameter, 277 CYCLE83 - deep-hole drilling Function, 278 Parameter, 281 CYCLE832 - High Speed Settings Function, 426 Parameter, 428 CYCLE84 - rigid tapping Function, 284 Parameter, 288 CYCLE840 - tapping with compensating chuck Function, 284 Parameter, 288 CYCLE85 - reaming Function, 277 Parameter, 278 CYCLE86 - borina Function, 281 Parameter, 283

CYCLE899 - open slot Function, 322 Parameters, 328 CYCLE92 - cut-off Function, 387 Parameter, 388 CYCLE930 - groove Function, 369 Parameter, 371 CYCLE940 - undercut Function, DIN thread, 373 Function, form E, 371 Function, form F, 371 Function, thread, 373 Parameters, DIN thread, 375 Parameters, form E, 372 Parameters, form F, 373 Parameters, thread, 375 CYCLE951 - stock removal Function, 366 CYCLE952 - contour turning Function, grooving, 407 Function, grooving residual material, 409 Function, plunge turning, 411 Function, plunge turning residual material, 414 Function, stock removal, 400 Function, stock removal residual, 405 Parameters, grooving, 409 Parameters, grooving residual material, 411 Parameters, plunge turning, 413 Parameters, plunge turning residual material, 415 Parameters, stock removal, 404 Parameters, stock removal residual material, 406 CYCLE98 - thread turning Parameters, thread chain, 386 CYCLE99 - thread turning Function, face thread, 376 Function, longitudinal thread, 376 Function, tapered thread, 376 Function, thread chain, 384 Parameters, face thread, 381 Parameters, tapered thread, 384 Cvcles Current levels, 206 Hiding cycle parameters, 218 Screen forms, 206

### D

Data block (SB2), 138 Deep-hole drilling - CYCLE83 Function, 278 Parameter, 281 Deleting Directory, 535 Program, 535 Device Activate/deactivate, 579 Enabling, 578 Directory Copying, 533 Creating, 521 Deleting, 535 Highlight, 531 Pasting, 533 Properties, 536 Selecting, 531 Displaying Program level, 141 DRF (handwheel offset), 154 Drilling - CYCLE82 Function, 276 Parameter, 277 Drilling and thread milling - CYCLE78 Function, 288 Parameter, 291 Drive Error messages, 555 Logical drive, 553 Setting up, 554 DRY (dry run feed), 154 Dual editor, 164 Duplo number, 485

### Ε

Easy Extend, 579 Activate/deactivate device, 579 Enabling a device, 578 First commissioning, 580 Easy Message, 567 Commissioning, 569 Settings, 576 User log on/off, 574 Edges, 491 Editor Calling, 160 Settings, 166 Elongated hole - LONGHOLE Function. 328 Parameter, 330 Enabling button, 558 Engraving - CYCLE60 Function, 333 Parameters, 338

Executing Program, 519 EXTCALL, 537

### F

Face milling in JOG, 131 Face milling - CYCLE61 Function, 298 Parameter, 300 Feed data Actual value window, 35 Feedrate, 237 Function Align milling tool - CYCLE800, 425 Setting milling tool - CYCLE800, 424 Subprograms, 428

### G

G code program Blank input, 210 G Code program Creating, 523 G functions Display all G groups, 170 Displaying selected G groups, 168 Global user data, 453 Grid/frame position pattern - CYCLE801 Function, 294 Parameter, 295 Groove - CYCLE930 Function, 369 Parameter, 371

### Η

Handheld terminal 8, 557 Handwheel Assigning, 112 Helix, 439 High Speed Settings - CYCLE832 Function, 426 Parameter, 428 Highlight Directory, 531 Program, 531 HOLES1 - line position pattern Function, 294 Parameter, 295 HOLES2 - circle position pattern Function, 295 Parameter, 296 HT 8, 557 Enabling button, 558 Touch Panel, 565 Traversing keys, 560 User menu, 561 Virtual keyboard, 563

# I

Interruption point Approaching, 112, 150

### J

Job list Creating, 526

### L

Ladder viewer, 585 Line position pattern - HOLES1 Function, 294 Parameter, 295 Logbook, 624 Display, 624 Edit the address data, 624 Entry search, 625 Making an entry, 625 Output, 622 LONGHOLE - elongated hole Function, 328 Parameter, 330 Longitudinal groove - SLOT1 Function, 316 Parameter, 318

### Μ

M functions, 171 Machine control panel Operator controls, 27 Machine functions, 238 Machine-specific information Save, 622 Machining Canceling, 136 Starting, 135 Stopping, 135 Machining schedule ShopMill, 224 Machining step program, 223 Magazine Open, 500 Positioning, 501 Selecting, 493 Magazine management, 475 Maintenance tasks Monitoring/performing, 581 Setting up, 583 Manual mode, 117, 118 Positioning axes, 125 Settings, 134 Spindle, 120 T, S, M windows, 118 Tool, 119 Traversing axes, 122 Unit of measurement, 118 MDA Deleting a program, 116 Executing a program, 116 Loading a program, 114 Saving a program, 115 Measuring Tool, 63 Tool automatically, 66 Tool manually, 63 Workpiece zero, 70 Measuring cycle support, 221, 253 Measuring cycles Inserting, 222, 254 Messages, 614 Mode groups, 57 Multi-channel view, 445 "Machine" operating area, Settings, 449 Multi-edge - CYCLE79 Function, 313 Parameter, 315

#### Ν

NC directory Creating on local drive, 514 NC variables, 615 NC/PLC variables Changing, 617 Load symbols, 619 New contour - CYCLE62 Function, 340, 391 Parameter, 342 Number of teeth, 486

# 0

Obstacle, 443 Offset, 431 Online help Context-sensitive, 48 Open Program, 517 Second program, 164 **Open slot - CYCLE899** Function, 322 Parameter, 328 Operating area Changing, 37 Operating mode AUTO, 56 Changing, 37 JOG, 55, 117 MDA, 56 Operator panel fronts, 19

## Ρ

Parameter Align milling tool - CYCLE800, 426 Calculating, 39 Changing, 39 Entering, 38 Setting milling tool - CYCLE800, 425 Swivel plane - CYCLE800, 422 Pasting Directories, 533 Program, 533 Path milling - CYCLE72 Function, 349 Parameter, 353 Pinvin Input editor, 44 Pitch, 485 PLC diagnostics Ladder add-on tool, 585 PLC symbols Loading, 619 PLC variables, 617 Pocket calculator, 41 POCKET3 - rectangular pocket Function, 301 POCKET4 - circular pocket Function, 304 Parameter, 308 Polar coordinates, 440

Positions Parameter, obstacle, 444 Parameter, repeat, 297 Preview Program, 530 Probe, 68 Electronic, 75 Program Closing, 517 Copying, 533 Creating with cycle support, 208 Deleting, 535 Executing, 519 Highlight, 531 Open, 517 Opening a second program, 164 Pasting, 533 Preview, 530 Properties, 536 Selecting, 531 Program block, 228 Changing, 160 Copying and inserting, 163 Delete, 163 Generating, 235 Linked, 228 Numbering, 164 Repeat, 241 Search, 160 Selecting, 163 Program block display, 36, 140 Program control, 154 Activate, 155 Program editing, 143 Program header, 233 Important parameters, 236 Program level Displaying, 141 Program list Creating, 527 Program Manager, 511 Program runtime, 174 Program settings Changing, 245 Program views ShopMill, 224 Programmed stop 1, 154 Programmed stop 2, 154 Programming graphics ShopMill, 224 Programs Correcting, 36, 140, 143

Editing, 160 Managing, 511 Renumbering blocks, 164 Replacing text, 161 Running-in, 138 Searching for a program position, 160 Selecting, 137 Teach-in, 461 Properties Directory, 536 Program, 536 Protection levels, 46 PRT (no axis motion), 154 Punched tape format, 540

### Q

Quantity, 496

### R

R parameters, 452 Radius compensation, 236 Reading in Setup data, 546 Reaming - CYCLE85 Function, 277 Parameter, 278 Rectangular pocket - POCKET3 Function, 301 Rectangular spigot - CYCLE76 Function, 309 Parameter, 311 Reference point approach, 52 Remote access Permit, 630 Setting, 628 Remote diagnostics, 628 Exit, 631 Requesting, 630 Repeat positions Function, 296 Replacement tool number, 485 Repositioning, 145 RG0 (reduced rapid traverse), 154 Rigid tapping - CYCLE84 Function, 284 Parameter, 288 Rotation, 432

# S

Save Setup data, 544 SB (single blocks), 154 SB1, 138 SB2, 138 SB3, 138 Screenshots Copy, 627 Creating, 627 Open, 627 Search Logbook entry, 625 Search mode, 152 Search pointer, 112, 147, 150 Selecting Directory, 531 Program, 531 Service Planner, 581 Setting actual values, 60 Setting milling tool - CYCLE800 Function, 424 Parameter, 425 Settings Editor, 166 For automatic operation, 176 For manual operation, 134 Multi-channel view, 449 Teach-in, 471 Setup data Backing up, 544 Reading in, 546 ShopMill program Creating, 232 Machine functions, 238 Program blocks, 235 Program header, 233 Program settings, 245 Program structure, 228 Straight line/Circle, 434 ShopTurn program Mirroring, 433 Scaling, 433 Simulation, 179 Alarm display, 199 Blank, 192 Changing a graphic, 195 Program control, 193 Showing and hiding the path display, 192 Views, 190 Simultaneous recording, 180 Before machining, 188

Single block Coarse (SB1), 138 Fine (SB3), 138 Skip blocks, 156 SKP (skip blocks), 154 SLOT1- longitudinal groove Function, 316 Parameter, 318 SLOT2 - circumferential groove Function, 319 Parameter, 321 SMS messages, 567 Log, 575 Spindle data Actual value window, 36 Spindle speed, 237 Spindle speed limitation, 110 Status display, 31 Stock removal - CYCLE951 Function, 366 Straight line, 434 Polar, 441 Straight line/Circle, 434 Submode **REF POINT, 55** REPOS, 55 TEACH IN, 56 Subprograms, 428 Switching off, 51 Switching on, 51 Switching over Channel, 57 Coordinate system, 59 Unit of measurement, 59 Swivel plane - CYCLE800 Parameter, 422 Swiveling Parameter, swivel plane, 130 Symbol tables, 603 Synchronized actions Displaying status, 172

## Т

Tapping with compensating chuck - CYCLE840 Function, 284 Parameter, 288 Teach-in, 461 Changing blocks, 469 Circle intermediate position CIP, 467 Deleting blocks, 471 General sequence, 462

Inserting a position, 463 Inserting blocks, 465 Motion type, 464 Parameter, 463 Rapid traverse G0, 466 Selecting a block, 470 Settings, 471 Traversing block G1, 466 Templates Creating, 529 Storage locations, 529 Thread milling - CYCLE70 Function, 330 Parameter, 333 Thread turning - CYCLE98 Function, thread chain, 384 Parameters, thread chain, 386 Thread turning - CYCLE99 Function, face thread, 376 Function, longitudinal thread, 376 Function, tapered thread, 376 Parameters, face thread, 381 Parameters, longitudinal thread, 379 Parameters, tapered thread, 384 Tip angle, 485 Tool, 119 Automatic measurement, 66 Changing type, 510 Creating, 488 Deleting, 491 Details, 508 Dimensioning, 478 Loading, 492 Manual measurement, 63 Measuring, 63 Multiple edges, 491 Reactivating, 497 Relocating, 502 Unloading, 492 Tool data Actual value window, 35 Backing up, 544 Reading in. 546 Tool data OEM, 499 Tool life, 496 Tool list, 485 Tool management, 473 List filtering, 505 Sorting lists, 504 Tool parameters, 478 Tool probe, 68 Tool types, 476

Tool wear, 495 Tool wear list Open, 495 Touch Panel Calibrating, 565

### U

Undercut - CYCLE940 Function, DIN thread, 373 Function, form E, 371 Function, form F, 371 Function, thread, 373 Parameters, DIN thread, 375 Parameters, form E, 372 Parameters, form F, 373 Parameters, thread, 375 Unit of measurement Switching over, 59 User acknowledgement, 53 User data, 451 Channel GUD, 455 Definition, 459 Global GUD, 453 Local LUD, 456 Program PUD, 457 R parameters, 452 Search, 458 User variables Activate, 459 Global GUD, 459

## V

Variable screen forms, 618 Virtual keyboard, 563

### W

Wear, 496 Work offsets, 101 Active WO, 102 Calling, 240 Delete, 107 Displaying details, 106 Overview, 103 Settable WO, 105 Setting, 60 Working area limitation, 109 Workpiece Create, 522

Index

Workpiece counter, 174 Workpiece zero Aligning the edge, 79 Aligning the plane, 96 Automatic measurement, 70 Changing the user interface, 98 Corrections after measurement, 99 Manual measurement, 70 Measuring, 70 Measuring a hole, 84 Measuring a rectangular pocket, 84 Measuring a rectangular spigot, 91 Measuring a right-angled corner, 81 Measuring any corner, 81 Measuring circular spigot, 91 Measuring the distance between two edges, 79

# Ζ

Zero point settings Backing up, 544 Reading in, 546 Index