Operating Instructions

Safety information

General

Installation

Setting parameters with the BOP20

Technical specifications

Control version V4.6

03/2013
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Legal information

Warning notice system

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

⚠️ DANGER
indicates that death or severe personal injury will result if proper precautions are not taken.

⚠️ WARNING
indicates that death or severe personal injury may result if proper precautions are not taken.

⚠️ CAUTION
indicates that minor personal injury can result if proper precautions are not taken.

NOTICE
indicates that property damage can result if proper precautions are not taken.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

Qualified Personnel

The product/system described in this documentation may be operated only by personnel qualified for the specific task in accordance with the relevant documentation, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

Proper use of Siemens products

Note the following:

⚠️ WARNING
Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be complied with. The information in the relevant documentation must be observed.

Trademarks

All names identified by ® are registered trademarks of Siemens AG. The remaining trademarks in this publication may be trademarks whose use by third parties for their own purposes could violate the rights of the owner.

Disclaimer of Liability

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.
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Safety information

1.1 Warnings

**WARNING**

**Dangerous electrical voltage**

Hazardous voltages are present when electrical equipment is in operation. Severe personal injury or substantial material damage may result if these warnings are not observed.

Only qualified personnel are permitted to work on or around the equipment. These personnel must be thoroughly familiar with all the warnings and maintenance procedures described in these operating instructions.

The successful and safe operation of this device is dependent on correct transport, proper storage and installation, as well as careful operation and maintenance.

National safety guidelines must be observed.

**DANGER**

**Five safety rules**

When carrying out any kind of work on electrical devices, the "five safety rules" according to EN 50110 must always be observed:

1. Disconnect the system.
2. Protect against reconnection.
3. Make sure that the equipment is de-energized.
4. Ground and short-circuit.
5. Cover or enclose adjacent components that are still live.

---

**Note**

**Use of copper cables for a UL-approved system**

For a UL-approved system use 60/75°C copper conductors only.
1.2 Safety and application instructions

**DANGER**

**Dangerous electrical voltage**

This equipment is used in industrial high-voltage installations. During operation, this equipment contains live, bare parts. For this reason, they could cause severe injury or significant material damage if the required covers are removed, if they are used or operated incorrectly, or have not been properly maintained.

When the machines are used in non-industrial areas, the installation location must be protected against unauthorized access (protective fencing, appropriate signs).

**Preconditions**

The persons responsible for the safety of the plant must ensure that the following conditions are met:

- Basic planning work for the system and all work relating to transportation, assembly, installation, commissioning, maintenance and repairs is carried out by qualified personnel and checked by responsible, suitably skilled personnel.
- The Operating Instructions and machine documentation are always available.
- The technical specifications regarding the applicable installation, connection, environmental, and operating conditions are always observed.
- The plant-specific assembly and safety guidelines are observed and personal protection equipment is used.
- Unqualified personnel are forbidden from using these machines and working near them.

These Operating Instructions are intended for qualified personnel and only contain information and notes relating to the intended purpose of the machines.

The Operating Instructions and machine documentation are written in different languages as specified in the delivery contracts.

**Note**

**Support by SIEMENS service centers**

We recommend engaging the support and services of your local Siemens service center for all planning, installation, commissioning and maintenance work.
1.3 Components that can be destroyed by electrostatic discharge (ESD)

![Diagram of ESD protective measures]

- a = conductive floor surface
- b = ESD table
- c = ESD shoes
- d = ESD overall
- e = ESD wristband
- f = cabinet ground connection
- g = contact with conductive flooring

The necessary ESD protective measures are clearly illustrated in the following diagram:
Safety information

1.3 Components that can be destroyed by electrostatic discharge (ESD)
General

Description

The Basic Operator Panel 20 (BOP20) contains six keys and a backlit display unit. The BOP20 can be plugged into and operated from the SINAMICS Control Unit. The blanking cover must be removed for this purpose.

The BOP20 supports the following functions:

- Entering parameters and activating functions
- Displaying operating modes, parameters, alarms, and faults
- Switch on/off during commissioning
- Acknowledging faults

Figure 2-1  BOP20
The following photos and captions explain how to assemble the Basic Operator Panel 20 (BOP20) on the Control Unit.

Control Unit and BOP20

Remove the cover by pressing the latching cams together

Insert the CompactFlash card before inserting the BOP20

Carefully insert the BOP20 until you hear it latch into position
3.1 Removal

Please note the following information when removing the BOP20 from the Control Unit:

1. The latching cams on the BOP20 must be pressed together simultaneously.

2. The BOP20 must be pulled out straight (i.e. not at an angle). The bottom edge of the BOP20 must never be pulled forwards to remove the device, as this could damage the interface on the rear.

Figure 3-1 Incorrect mounting of the BOP20
Setting parameters with the BOP20

4.1 BOP20 overview

Overview of displays/indicators and keys

![Figure 4-1 Overview of displays/indicators and keys](image)

Table 4-1 Displays/indicators

<table>
<thead>
<tr>
<th>Display</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Top left, 2 chars.</td>
<td>The active drive object of the BOP is displayed here.</td>
</tr>
<tr>
<td></td>
<td>The displays and key operations always refer to this drive object.</td>
</tr>
<tr>
<td>RUN</td>
<td>Lit if at least one drive in the drive line-up is in the RUN state (in operation). RUN is also displayed via bit r0999.2 of the drive.</td>
</tr>
<tr>
<td>Top right, 2 chars.</td>
<td>The following is displayed in this field:</td>
</tr>
<tr>
<td></td>
<td>• More than 6 digits: Characters that are present but cannot be seen (e.g. &quot;r2&quot; → 2 characters to the right are invisible, &quot;L1&quot; → 1 character to the left is invisible)</td>
</tr>
<tr>
<td></td>
<td>• Faults: Selects/displays other drives with faults</td>
</tr>
<tr>
<td></td>
<td>• Designation of BICO inputs (bi, ci)</td>
</tr>
<tr>
<td></td>
<td>• Designation of BICO outputs (bo, co)</td>
</tr>
<tr>
<td></td>
<td>• Source object of a BICO interconnection to a drive object other than the active one.</td>
</tr>
<tr>
<td>S</td>
<td>Lit if at least one parameter was changed and the value was not transferred to the non-volatile memory.</td>
</tr>
<tr>
<td>P</td>
<td>Lit if the parameter value does not become effective until the P key is pressed.</td>
</tr>
<tr>
<td>C</td>
<td>Lit if at least one parameter was changed and the calculation for consistent data management has not been initiated.</td>
</tr>
<tr>
<td>Bottom, 6 chars.</td>
<td>Displays parameters, indices, faults, and alarms.</td>
</tr>
</tbody>
</table>
### 4.1 BOP20 overview

#### Table 4-2  Keys

<table>
<thead>
<tr>
<th>Key</th>
<th>Name</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>Switches on the drives for which the command &quot;ON/OFF1&quot; is to be issued from the BOP. Binector output r0019.0 is set using this key.</td>
<td></td>
</tr>
<tr>
<td>OFF</td>
<td>Switches off the drives for which the commands &quot;ON/OFF1&quot;, &quot;OFF2&quot;, and &quot;OFF3&quot; are to be issued from the BOP. The binector outputs r0019.0, .1 and .2 are reset simultaneously when this key is pressed. After the key has been released, binector outputs r0019.0, .1 and .2 are again set to a &quot;1&quot; signal.</td>
<td></td>
</tr>
<tr>
<td>FN</td>
<td>Functions The significance of this key depends on the current display. Note: The effectiveness of this key for acknowledging faults can be defined by parameterizing the BiCo accordingly.</td>
<td></td>
</tr>
<tr>
<td>P</td>
<td>Parameters The significance of this key depends on the current display. If this key is pressed for 3 s, the &quot;Copy RAM to ROM&quot; function is executed. The &quot;S&quot; displayed on the BOP disappears.</td>
<td></td>
</tr>
<tr>
<td>Δ</td>
<td>Raise     The keys depend on the current display and are used to either raise or lower values.</td>
<td></td>
</tr>
<tr>
<td>▽</td>
<td>Lower</td>
<td></td>
</tr>
</tbody>
</table>
BOP20 functions

<table>
<thead>
<tr>
<th>Name</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>Backlighting</td>
<td>The backlighting can be set using p0007 in such a way that it switches itself off automatically after the set time if no actions are carried out.</td>
</tr>
<tr>
<td>Changeover active drive</td>
<td>From the point of view of the BOP, the active drive is defined using p0008 or using the keys “Fn” and ”Arrow up”.</td>
</tr>
<tr>
<td>Units</td>
<td>The units are not displayed on the BOP.</td>
</tr>
<tr>
<td>Access level</td>
<td>The access level for the BOP is defined using p0003.</td>
</tr>
<tr>
<td>Parameter filter</td>
<td>The parameter filter in p0004 can be used to filter the available parameters in accordance with their particular function.</td>
</tr>
<tr>
<td>Selecting the status display</td>
<td>Actual values and setpoints are displayed on the status display.</td>
</tr>
<tr>
<td>User parameter list</td>
<td>The user parameter list in p0013 can be used to select access parameters.</td>
</tr>
<tr>
<td>Unplug while voltage is present</td>
<td>The BOP can be unplugged and plugged in again while the device is live.</td>
</tr>
<tr>
<td></td>
<td>The ON and OFF buttons function here.</td>
</tr>
<tr>
<td></td>
<td>Unplugging the BOP causes the drives to coast to a standstill.</td>
</tr>
<tr>
<td></td>
<td>When the BOP is plugged in again, the drives must be switched on again.</td>
</tr>
<tr>
<td></td>
<td>The ON and OFF buttons have no function.</td>
</tr>
<tr>
<td></td>
<td>Unplugging and plugging the BOP in again has no effect on the drives.</td>
</tr>
<tr>
<td>Actuating keys</td>
<td>The following applies to the &quot;P&quot; and &quot;Fn&quot; keys:</td>
</tr>
<tr>
<td></td>
<td>When used in combination with another key, &quot;P&quot; or &quot;Fn&quot; must be pressed first and then the other key.</td>
</tr>
</tbody>
</table>
Parameters

All drive objects
- p0005 BOP status display selection
- p0006 BOP status display mode
- p0013 BOP user-defined list
- p0971 Save drive object parameters

Drive object, Control Unit
- r0000 BOP status display
- p0003 BOP access level
- p0004 BOP parameter menu
- p0007 Backlighting display delay time
- p0008 BOP drive object selection
- p0009 Device commissioning parameter filter
- p0011 BOP password input (p0013)
- p0012 BOP password confirmation (p0013)
- r0019 CO/BO: Control word, BOP
- p0977 Save all parameters

Other drive objects (e.g. VECTOR, TM31, …)
- p0010 Commissioning parameter filter
4.2 Displays/indicators and using the BOP20

Status display

The status display for each drive object can be set using p0005 and p0006. Using the status display, you can switch to the parameter display or to a different drive object. The following functions are supported:

- **Changing the active drive object**
  - Press the "Fn" key and "Arrow up" -> the drive object number at the top left flashes.
  - Select the required drive object using the arrow keys.
  - Confirm with the "P" key.

- **Parameter display**
  - Press the "P" key.
  - The required parameter can be selected using the arrow keys.
  - Press the "Fn" key -> parameter r0000 is displayed.
  - Press the "P" key -> returns to the status display.
Parameter display

The parameters are selected in the BOP using their respective numbers. To call up the parameter display from the status display, press the "P" key. You can search for the parameters you require using the arrow keys. To display the parameter value, press the "P" key again. You can switch between the drive objects by simultaneously pressing the "Fn" key and the arrow keys. You can switch between r0000 and the parameter that was last displayed by pressing the "Fn" key in the parameter display.

Figure 4-2 Parameter display
Value display

To switch from the parameter display to the value display, press the "P" key. In the value display, the values of the setting parameters can be increased and decreased using the arrow keys. The cursor can be selected using the "Fn" key.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value display</th>
</tr>
</thead>
<tbody>
<tr>
<td>Decimal number</td>
<td>02</td>
</tr>
<tr>
<td>Integer number</td>
<td>20</td>
</tr>
<tr>
<td>Decimal number</td>
<td>02 123.45678</td>
</tr>
<tr>
<td>Timer</td>
<td>02 09h:32m:12s</td>
</tr>
<tr>
<td>H: Hexadecimal</td>
<td>02 0x0A0FB001</td>
</tr>
</tbody>
</table>

![Figure 4-3 Value display](image)

- Changing the entire number
- Changing an individual digit
- Displaying the original value
Examples

Example 1: Changing a parameter
Prerequisite: The appropriate access level is set (for this particular example, p0003 = 3).

![Parameter display](image1)

Figure 4-4 Example: Change p0013[4] from "0000" to "0300".

Example 2: Changing binector and connector input parameters
Binector output r0019.0 of the Control Unit (drive object 1) is connected to binector input p0840[0] (OFF1) of drive object 2.

![Parameter display](image2)

Figure 4-5 Example: Changing the indexed binector parameters
4.3 Fault and alarm displays

Displaying faults

<table>
<thead>
<tr>
<th>Condition</th>
<th>Display</th>
</tr>
</thead>
<tbody>
<tr>
<td>F: Fault A fault from the drive object</td>
<td>![Diagram of fault display]</td>
</tr>
<tr>
<td>More than one fault from the drive object</td>
<td>![Diagram of fault display]</td>
</tr>
<tr>
<td>A fault from a different drive object than the one that is active</td>
<td>![Diagram of fault display]</td>
</tr>
<tr>
<td>More than one fault from an active drive object and from a different drive object</td>
<td>![Diagram of fault display]</td>
</tr>
</tbody>
</table>

Figure 4-6 Displaying faults

Displaying alarms

<table>
<thead>
<tr>
<th>Condition</th>
<th>Display</th>
</tr>
</thead>
<tbody>
<tr>
<td>A: Warning</td>
<td>![Diagram of alarm display]</td>
</tr>
<tr>
<td>New alarms or alarms present and a button has not been pressed for approx. 20 seconds</td>
<td>![Diagram of alarm display]</td>
</tr>
<tr>
<td>Alarms are clocked through automatically</td>
<td>![Diagram of alarm display]</td>
</tr>
</tbody>
</table>

Figure 4-7 Displaying alarms
4.4 Controlling the drive using the BOP20

Description

When the drive is commissioned, it can be controlled via the BOP20. A control word is available on the Control Unit drive object (r0019) for this purpose, which can be interconnected with the appropriate binector inputs of the drive.

The interconnections do not function if a standard PROFIdrive telegram was selected as its interconnection cannot be disconnected.

Table 4-3 BOP control word (r0019)

<table>
<thead>
<tr>
<th>Bit (r0019)</th>
<th>Signal name</th>
<th>1 signal</th>
<th>0 signal</th>
<th>Example, interconnection parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>ON / OFF (OFF1)</td>
<td>ON</td>
<td>OFF</td>
<td>p0840</td>
</tr>
<tr>
<td>01</td>
<td>No coast down/coast down (OFF2)</td>
<td>No coast down</td>
<td>Coast down (OFF2)</td>
<td>p0844</td>
</tr>
<tr>
<td>02</td>
<td>No fast stop/fast stop (OFF3)</td>
<td>No fast stop</td>
<td>Fast stop (OFF3)</td>
<td>p0848</td>
</tr>
<tr>
<td>07</td>
<td>Acknowledge fault (0 -&gt; 1)</td>
<td>Yes</td>
<td>No</td>
<td>p2102</td>
</tr>
<tr>
<td>13</td>
<td>Motorized potentiometer, raise</td>
<td>Yes</td>
<td>No</td>
<td>p1035</td>
</tr>
<tr>
<td>14</td>
<td>Motorized potentiometer, lower</td>
<td>Yes</td>
<td>No</td>
<td>p1036</td>
</tr>
</tbody>
</table>

Note

Simple commissioning

For simple commissioning, only bit 0 should be interconnected. When bits 0 ... 2 are interconnected, the system is switched off according to the following priority: OFF2, OFF3, OFF1.
4.5 Important functions via BOP20

Description

The BOP20 can be used to execute the following functions (via parameters) that help you handle your projects more efficiently:

- Restore the factory settings
- Copy from RAM to ROM
- Identification via LED
- Acknowledge error

Restore the factory settings

The factory setting of the complete device can be restored in the CU drive object.

- p0009 = 30
- p0976 = 1

Copy from RAM to ROM

In the CU drive object, you can save all your parameters to the non-volatile memory (CompactFlash card):

- Press the "P" key for 3 seconds or
- p0977 = 1

Note

Parameter rejection with active identification

This parameter is not accepted if an identification routine (e.g. motor identification routine) has been selected on a drive.
Identification via LED

The main component of a drive object (e.g. Motor Module) can be identified using the index of p0124. The ready LED on the module starts to flash. The index corresponds to the index in p0107; the drive object type can be identified using this parameter.

On the drive objects, the components can also be identified using the following parameters:

- p0124 power unit detection via LED
- p0144 Voltage Sensing Module detection via LED
- p0144 Sensor Module detection via LED
- p0154 DRIVE-CLiQ hub identification using LED
- p0154 Terminal Module detection via LED

Acknowledge error

All errors whose cause has been rectified can be acknowledged by pressing the Fn key.
### Technical specifications

<table>
<thead>
<tr>
<th></th>
<th>Basic Operator Panel 20 (BOP20)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Electronics power supply</td>
<td>3.3 V DC (provided by CU320)</td>
</tr>
<tr>
<td>Weight</td>
<td>0.02 kg</td>
</tr>
</tbody>
</table>