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NEWS

Using the 2nd-Generation Mobile Panel in a Safety-Related Application

WinCC V14, KTP400F, KTP700F, KTP900F, STEP 7 Safety Advanced

https://support.industry.siemens.com/cs/ww/en/view/103497649

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# **Table of Contents**

Wai	rranty and	d Liability	2
1	Task		4
	1.1 1.2 1.3	Introduction	4 4 5
2	Solutio	on	6
	2.1 2.2 2.2.1 2.2.2 2.2.3 2.2.4 2.3 2.3.1 2.3.2	Overview.6Hardware configuration8Hardware configuration overview.8Hardware components used9Software components used.9Sample files and projects10Design of the control elements and contactors10Mobile Panel, connection box advanced.11ET 200SP, 8 F-DI electronic module.12	6 8 9 9 0 1 2
3	Basics		3
	3.1 3.2 3.3 3.4	Safety notices       13         Operating modes       13         Mobile Panel       14         Logging out of the safety program       14	3 3 4 4
4	Config	uration Guide	5
	4.1 4.2 4.3 4.3.1 4.3.2 4.3.3 4.3.4 4.4 4.4.1 4.4.2	General information15Circuit diagram16WinCC TIA Portal project21Hardware configuration21STEP 7 user program26STEP 7 safety program26Mobile Panel configuration36Device settings37Connection box37Mobile Panel36	5611696778
5	Operat	ion of the Application Example41	1
	5.1 5.2	HMI user interface    41      Controlling the plant    42	1 2
6	Debug	ging44	4
7	Links &	& Literature	6
8	History	۷	6

# 1 Task

## 1.1 Introduction

The KTP400F, KTP700F and KTP900F Mobile are suitable for a wide range of applications in the industrial environment. Its mobility and robustness allows it to be used even in applications where other HMI operator panels cannot be used at all or only with considerable effort.

Using a specific example, the application example describes how to integrate the

- emergency stop button
- enabling button

of the KTP400F, KTP700F and KTP900F Mobile into a safety-related application.

**Note** When this document uses the term 'Mobile Panel', this always refers to the KTP400F, KTP700F and KTP900F Mobile.

## **1.2** Overview of the automation task

A robot to be operated is located in an area protected by a safety fence. For adjustment and maintenance work, this area can be entered through a safety door.

- The robot is operated using a mobile HMI operator panel.
- "Service mode":
  - Safety door open. When the safety door is open, an enabling button **must** be additionally pressed to operate the robot. The operating mode is selected using a key-operated switch.
- Manual/Automatic mode:
  - When the safety door is closed, the robot is operated in Manual/Automatic mode.
    - The "Manual mode" selection is password protected.
- Emergency stop command device:
  - An emergency stop command device must be available during operation in the protected area.
  - Another emergency stop command device must be available outside the safety fence.
- The risk analysis for the safety function requires PL e according to ISO 13849-1 / SIL 3 according to IEC 62061.

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# 1.3 Safety notices

Unauthorized	restart	of	the	plant
Unautionzeu	restart	U.	unc.	plain

**Necessary F-FBs** 

When the EMERGENCY stop button was activated, the plant must not be restarted until it is acknowledged by the operator. In your safety program, use FB 215 ESTOP1 to ensure acknowledgment by the operator.

#### Unauthorized automatic restart of the plant

The safety program must ensure that an automatic restart of the plant is not possible after setting the RESET. The operator is required to perform a separate action in order to restart the plant.

You have to integrate the following fail-safe blocks into your safety program:

- One FB198 F\_FB\_KTP\_Mobile for each operator panel. The assigned operator panel is monitored using this F-FB.
- One FB199 F\_FB\_KTP\_RNG for each connection box.
   F\_FB\_KTP\_RNG provides the safety-related signals for the machine part assigned to a connection box.
   FB 215: ESTOP1.
- With this block, you make sure that, following an EMERGENCY stop, operator acknowledgment must be made before the plant restarts. You will find this block in the "Safety Advanced" F-library in the following block container: "Communication > Fail-safe HMI Mobile Panels > -- KTP Mobile --".



WARNING

WARNING

# 2 Solution

## 2.1 Overview

#### Plant overview

The following figure shows the plant overview with the most important components.

- Drive to control the robot
- KTP900F Mobile Panel.
  - The Mobile Panel features a connecting cable that is connected to a connection box. It is used for power supply and signal transmission.
  - Mobile Panel and F-CPU communicate via PROFIsafe.
  - The emergency stop button and the enabling button of the Mobile Panel are evaluated directly using the safety program of the F-CPU.
  - Area with safety fence and access through a safety door.
  - The safety door has two position switches.
- External emergency stop command device.
- Key-operated switch to select "Service mode".

#### Figure 2-1

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#### What does the application example include?

The application example describes the following:

- Hardware used
- Circuit diagram
- Program description
  - STEP 7 user program
  - STEP 7 safety program
- How to use the application example

#### Scope

The application example does not include a description of...

- ISO 13849-1 / IEC 62061
   For more information, see the "Safety Evaluation Tool". The online tool approved by the German Technical Inspectorate provides fast and safe support in evaluating safety functions of your machine \8\.
- "safety of machinery"
- how to use the WinCC TIA Portal software

Basic knowledge of these topics is required.

#### Validity

The application example was created with the following software.

- STEP 7 Professional V14 SP1.
- STEP 7 Safety Advanced V14 SP1.
- WinCC (TIA Portal) V14 SP1 or higher.

## 2.2 Hardware configuration

#### 2.2.1 Hardware configuration overview

The diagrammatic representation below shows the most important components.



- 1. Fail-safe CPU
- 2. ET 200SP interface module
- 3. ET 200SP, fail-safe digital input / output modules
- 4. ET 200SP, standard digital input / output modules
- 5. Contactors for switching the robot drive on/off
- 6. External key-operated switch for selecting "Service mode"
- 7. Position switch (safety door)
- 8. External button for acknowledging fault messages and reintegrating the F-DI / F-DQ modules
- 9. External emergency stop command device
- 10. KTP900F Mobile Panel with connection box advanced

## 2.2.2 Hardware components used

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	20		-	

Component	No.	Article number	Note
KTP900F Mobile	1	6AV2125-2JB23-0AX0	-
Connection box advanced	1	6AV2125-2AE23-0AX0	-
Connecting cable, PN, 5m	5m	6AV2181-5AF05-0AX0	-
DIN rail, 480 mm	1	6ES7390-1AE80-0AA0	-
Load power supply. PS 307; 120/230V AC, 24V DC, 10A	1	6ES7307-1KA02-0AA0	-
CPU 1516F-3 PN/DP	1	6ES7516-3FN01-0AB0	-
SIMATIC S7, memory card for S7-1X00 CPU/SINAMICS, 3.3 V FLASH, 24 MBYTE	1	6ES7954-8LF02-0AA0	-
IM 155-6 PN HF	1	6ES7155-6AU00-0CN0	-
F-DI 8x24VDC HF	1	6ES7136-6BA00-0CA0	-
F-DQ 4x24VDC/2A PM HF	1	6ES7136-6DB00-0CA0	-
DI 8x24VDC ST	1	6ES7131-6BF00-0BA0	-
DQ 8x24VDC/0.5A ST	1	6ES7132-6BF00-0BA0	Reserve (not used in this application)
Contactors AC-3 3KW/400V, 1NC, 24V DC	3	3RT2015-1BB2	-
Auxiliary switch blocks 2NO + 2NC	3	3RH2911-1FA22	-
Command points	4	3SB3801-0EG3 3SB3801-0DD3	Emergency stop     command device
			Safety door switches
			Acknowledgment     button
			Key-operated     switch

## 2.2.3 Software components used

#### Table 2-2

Component	No.	Article number	Note
STEP 7 Professional V14 SP1	1	6ES7822-1AA04-0YA7	This version or higher
WinCC Advanced V14 SP1	1	6AV2102-0AA04-0AA5	This version or higher
STEP 7 Safety Advanced V14 SP1	1	6ES7833-1FA14-0YA5	This version or higher

#### 2.2.4 Sample files and projects

The following list contains all files and projects that are used in this example.

Table 2-3

Component	Note
103497649_KTPxxxF_Mobile_2nd_DOC_en.pdf	This document.
103497649_KTPxxxF_Mobile_2nd_Getting_Started_DOC_en.pdf	Getting Started.
103497649_KTPxxxF_Mobile_2nd_Code.zip	The .zip file contains the program for the application example and a default configuration.

# 2.3 Design of the control elements and contactors

To achieve the required PL d or SIL 2, the hardware components must meet certain requirements. These requirements are described in this chapter.

Table 2-4

No.	Device	In conjunction with a safety program
1.	Stationary emergency stop command devices	Two-channel switch with two NC contacts. The signals are read using a fail-safe digital input module. Note All emergency stop buttons associated with the emergency stop
•		command device are connected in series.
2.	Emergency stop (Mobile Panel)	Evaluation via PROFIsate
		Alternative: Evaluation using SIRIUS safety relays.
3.	Enabling button	Evaluation via PROFIsafe
		Alternative: Evaluation using SIRIUS safety relays.
4.	Error acknowledgment / reintegration of F-	Button with single-channel operating element (NO contact). The signal is read using a standard digital input module.
	DI / F-DQ modules	Alternative: Acknowledgment using "FB187" (F_ACK_OP). Only possible in conjunction with an F-CPU and STEP 7 Safety Advanced.
5.	Mode selector	Key-operated switch with operating element (e.g., NO contact). The signal is read using a standard digital input module.
		Note
		The Mobile Panel features a key-operated switch. Alternatively, this switch can be used for mode switching. Evaluation is performed via "direct key evaluation".
6.	Safety door	The safety door requires two position switches with a single-channel
	SWITCHES	operating element (NC contact). The signals are read using a fail-safe digital input module.
7.	Control of the contactors	The contactors are switched on and off using a fail-safe digital output module.

No.	Device	In conjunction with a safety program
8.	Readback signals (contactors)	Two contactors are used for safe shutdown of the drive. The first contactor's NC contact is interconnected in series with the second contactors NC contact and read using a standard digital input module. In the safety program, the certified "FB FDBACK" block is used to evaluate the signal.

#### 2.3.1 Mobile Panel, connection box advanced

#### X10 interface assignment

X10 terminal block, 12-pin: 24V DC power supply Figure 2-3



#### 2.3.2 ET 200SP, 8 F-DI electronic module

The 8 F-DI 24V DC digital electronic module is used for collecting the safety-related signals.

The external emergency stop command device is connected to two opposite inputs of the digital module on a two-channel basis (1002 evaluation).

The two position switches of the safety door are connected on a single-channel basis and each is assigned one input of the digital module (1001 evaluation).

#### Pinout

Channel 0, 4:	DI0 – DI4	(1 <sup>1</sup> ) DI0 + (9) VS0 – (5) DI4 + (13) VS4
Channel 1, 5:	DI1 – DI5	(2) DI1 + (10) VS1 - (6) DI5 + (14) VS5
Channel 2, 6:	DI2 – DI6	(3) DI2 + (11) VS2 - (7) DI6 + (15) VS6
Channel 3, 7:	DI3 – DI7	(4) DI3 + (12) VS3 - (8) DI7 + (16) VS7

For details about the pinout, see the supplied circuit diagram or Chapter <u>4.2</u> "<u>Circuit diagram</u>".

<sup>&</sup>lt;sup>1</sup> The value in brackets is the terminal on the module

# 3 Basics

# 3.1 Safety notices

Make yourself familiar with the safety notices and general information in the Mobile Panel's operating instructions. For the operating instructions, use the following link: https://support.industry.siemens.com/cs/en/en/ps/14746/man

# 3.2 Operating modes

Machine tools have predefined operating modes. This application example uses the following operating modes.

- Automatic mode
  - In this mode, it is not possible to enter the protected area. Automatic mode must be disabled before the safety door can be opened and the protected area can be entered.

If the safety door is opened in Automatic mode, the robot drive is switched off.

- Manual mode (setup mode)
  - Operators must have received specific training before they are allowed to use this mode. This mode can only be selected by entering a password. The drive is controlled in jog mode. The safety devices must be closed.
    - If the safety door is opened in Manual mode, the drive is immediately switched off.
- Service mode (process monitoring in production)
  - In contrast to the previous modes, the user can monitor and control the protected area when the safety device (door) is open.
     An additional enabling button is required to operate the robot. Releasing the enabling button immediately stops the robot drive.

In all three modes, the stationary emergency stop command device and the emergency stop button of the Mobile Panel are active.

## 3.3 Mobile Panel

#### PROFIsafe

PROFIsafe ensures F-communication between two partners.

The Mobile Panel supports communication via PROFIsafe. This functionality provides the option to evaluate the emergency stop button and the enabling button of the Mobile Panel directly in the F-CPU. It is therefore no longer necessary to wire additional modules.

#### **Connection box advanced**

Three different connection boxes are available for the Mobile Panel.

The connection box used in this application example, **advanced**, can be integrated into an existing emergency stop circuit.

The Mobile Panel can be removed from the connection box without opening the assigned emergency stop circuit.

When used in conjunction with PROFIsafe, the Mobile Panel must first be logged off of the network.

#### **Emergency stop button**

The signal of the emergency stop button of the Mobile Panel can be further processed via PROFIsafe or using suitable external evaluation units such as safety relays.

When the Mobile Panel is connected to the connection box, the emergency stop button must be active.

Depending on the operating mode, the emergency stop button lights up. In this application example, the emergency stop button lights up when the Mobile Panel is logged on to the safety program.

For details about the various operating modes, refer to the manual.

#### **Enabling button**

The signal of the enabling button of the Mobile Panel can be further processed via **PROFIsafe** or using suitable external evaluation units such as safety relays.

#### Note

The enabling button is only needed if required by the operating mode. This would be the case, for example, in "Service mode".

#### 3.4 Logging out of the safety program

Before you disconnect the Mobile Panel from the connection box, log the Mobile Panel out of the safety program using the "TerminatePROFIsafe" system function (1) or exit the running project.

If you do not log out before disconnecting, the system triggers an emergency stop.

Once you have logged out, the emergency stop button and the enabling button are **no** longer active.

# 4 Configuration Guide

# 4.1 General information

#### Sample project

The supplied sample project contains all the settings described in this chapter. The robot's movements are animated using a graphic list and only intended to illustrate the function.

#### **Program information**

The following measures were implemented in the STEP 7 program to avoid the risk of misuse by an unauthorized hold-down of the enabling button.

- The enabling button must be released within a specified period and then returned to the "acknowledgment" position.
   Select this period based on the activity of the system to be monitored.
- It is not allowed to use the enabling button alone to switch on the drive.
  - Always press the enabling button **before** switching on the drive.
  - Pressing the "Drive on" button and then pressing the enabling button does not activate the drive.

#### **STEP 7 program**

- The user program is used to control the robot drive.
- The safety program is used to evaluate the safety-related functions.

#### HMI configuration

The HMI configuration contains all the functions for controlling the robot drive. The "robot's" movements are simulated using a graphic list.

**Note** Follow the safety notices and general information in the Mobile Panel manual. (For the operating instructions, use the following link: <u>https://support.industry.siemens.com/cs/en/en/ps/14746/man</u>)

## 4.2 Circuit diagram

The circuit diagram contains the data for implementing the automation task shown in Chapter 1.2.

The circuit diagram has 8 pages and corresponds to the test setup that was used to test the functionality of the automation task.

Notes

The circuit diagram is included in this application example as a separate document.
Depending on the required automation task, additional evaluation units and protective measures may be necessary.

#### Circuit diagram, page 1

Hardware and signal exchange overview.





Load circuit overview.

Contactors -K10 and -K11 are used to switch the robot drive on and off.

Figure 4-2



#### Circuit diagram, page 3

The emergency stop button of the Mobile Panel is evaluated directly in the F-CPU via PROFIsafe.

#### Figure 4-3



The enabling button of the Mobile Panel is evaluated directly in the F-CPU via PROFIsafe.

#### Figure 4-4

#### Evaluation enabling button



Evaluation via PROFISafe

#### Circuit diagram, page 5

•

The page shows the pinout of the F-DI module.

- External emergency stop command device. Implementation of 1002 evaluation – channel 0, 4.
- Safety door position switches.
   Implementation of 1oo1 evaluation channel 3 (-S10) and channel 7 (-S11).







The page shows the pinout of the DI standard module.

- For feedback circuit monitoring of contactors -K10 and -K11.
- For the key-operated switch for changing "Service mode".
- For the external button for acknowledging fault messages and reintegrating the F-DI / F-DQ modules.
- **Note** Fault messages can also be acknowledged using the HMI operator panel. The messages are acknowledged in the control program using the F-FB187 "F\_OP" function block.

#### Figure 4-6



The page shows how to connect contactors -K10 and -K11 using the F-DO module.

The contactors are used to functionally, safely switch the robot drive on and off.

Figure 4-7



#### Circuit diagram, page 8

The page shows the power supply for the ET200 SP.

Figure 4-8



# 4.3 WinCC TIA Portal project

#### 4.3.1 Hardware configuration

**Note** The supplied sample project contains all the settings listed in this chapter.

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1 C	in a		-

No.	Description				
1.	F-CPU				
	<ul> <li>Create a new WinCC V14 project.</li> <li>Insert an F-CPU into the project tree. In this application example, insert a "CPU 1516F-3 PN/DP".</li> <li>Open the F-CPU device configuration and select the "Device view".</li> <li>Open the CPU properties.</li> <li>In the area navigation, select "General &gt; PROFINET interface [X1] &gt; Ethernet addresses".</li> <li>Interface: Use the drop-down list to select a subnet or add a new one.</li> <li>IP protocol: Enter the IP address.</li> <li>PROFINET: Optionally specify a PROFINET device name. The name is not further evaluated.</li> </ul>				
	The default settings were applied to the F-parameters of the F-CPU. List items that contain F-parameters are indicated by rectangles silhouetted in yellow. Check each parameter and modify it, if necessary.				
2.	ET 200SP				
	<ul> <li>In the Device configuration, open the Network view.</li> <li>In the hardware catalog, select the interface module in "Distributed IO &gt; ET 200SP &gt; Interface modules &gt; PROFINET &gt; IM 155-6 PN HF" and use drag and drop to move the module to the graphic area of the Network view.</li> <li>Select the module and go to the Device view.</li> <li>In the area navigation, select "General &gt; PROFINET interface [X1] &gt; Ethernet addresses".</li> <li>Interface: From the drop-down list, select the previously created subnet.</li> <li>IP protocol: Enter the IP address.</li> <li>PROFINET: Specify a PROFINET device name. The name is not further evaluated.</li> <li>In the hardware catalog, check the "Filter" check box. All available ET 200SP components will be displayed.</li> <li>Select the folders of the components used and use drag and drop to move the modules to the module slots.</li> </ul>				
	In this example: See Hardware components used, Chapter 2.2.2.				
	View of the completed station configuration				

No.	Description		
	$\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \\ \\ \end{array} \end{array} \end{array} \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \end{array} \\ $		
4.	ET200SP, configuring the F-DI module		
	<ul> <li>Select the F-DI module.</li> <li>In the area navigation, select "General &gt; F-parameters". <ul> <li>The default settings were applied.</li> </ul> </li> <li>In the area navigation, select "General &gt; DI parameters". <ul> <li>The following parameters depend on the assignment of the inputs and their evaluation (e.g., 1oo2 evaluation, etc.). Please refer to the modules in the hardware plan and the connections used there. Unused channels should be deactivated.</li> <li><b>Channel parameters</b> <ul> <li>Channel 0, 4:</li> <li>Evaluation</li> <li>Evaluation</li> <li>1oo2</li> <li>External emergency stop command device.</li> <li>Channel 1, 5:</li> <li>Deactivated.</li> <li>Channel 3, 7:</li> <li>Evaluation1oo1</li> <li>Safety door position switches.</li> </ul> </li> <li>Sensor supply for channels 0, 3, 4, 7 is activated.</li> <li>Sensor supply for channels 1, 2, 5, 6 is not activated.</li> <li>IO addresses</li> <li>The default settings were applied. In this application example: 116.0 to 121.7</li> </ul></li></ul>		
5.	Configuring the F-DQ module		
	<ul> <li>Select the F-DO module.</li> <li>In the area navigation, select "General &gt; F-parameters".         <ul> <li>The default settings were applied.</li> </ul> </li> <li>In the area navigation, select "General &gt; DQ parameters".         <ul> <li>Please refer to the hardware plan. Unused channels should be deactivated.</li> <li>DQ parameters</li></ul></li></ul>		

No.	Description	
6.	DI module	
	<ul> <li>Select the DI module.</li> <li>In the area navigation, select "General &gt; Module Parameters &gt; Channel template".</li> <li>The channel template was activated. (Channels 0 to 7 all use the "channel template".)</li> <li>In the area navigation, select "General &gt; Input 0 - 7 &gt; I/O addresses" and enter the start addresses. The default settings were applied. In this application example: 127 to 127.7</li> </ul>	
7.	DO module	
	<ul> <li>Select the DO module.</li> <li>In the area navigation, select "General &gt; Module Parameters &gt; Channel template".</li> <li>The channel template was activated. (Channels 0 to 7 all use the "channel template".)</li> <li>In the area navigation, select "General &gt;Output 0 - 7 &gt; I/O addresses". The default settings were applied. In this application example: Q2.0 to Q2.7</li> </ul>	
8.	Mobile Panel	
	<ul> <li>Go to the Network view.</li> <li>In the Mobile Panel's hardware catalog, go to "HMI &gt; SIMATIC Mobile Panel &gt; 9" display &gt; KTP900FF Mobile" and use drag and drop to move the Mobile Panel to the graphic area of the Network view.</li> <li>Select the Mobile Panel and go to the Device view.</li> <li>In the area navigation, select "General &gt; PROFINET interface [X1] &gt; Ethernet addresses".</li> <li>IP protocol: Enter the IP address.</li> <li>PROFINET: Specify a PROFINET device name. The name must match the PROFINET name in the device settings on the Mobile Panel in "Settings &gt; PROFINET". In this application example: mobile (see link).</li> </ul>	
9.	Mobile Panel	
	<ul> <li>In the area navigation, select "General &gt; PROFINET interface [X1] &gt; Operating mode".</li> <li>Check the "IO device" check box. Now you can select the IO controller from the drop-down list.</li> </ul>	
10.	Mobile Panel	
	<ul> <li>In the area navigation, select "General &gt; PROFIsafe &gt; Enable PROFIsafe ".</li> <li>Select the "Enable PROFIsafe" button. The button can only be activated if the "IO device" check box has been checked.</li> </ul>	

No.	Description		
11.	Mobile Panel		
	<ul> <li>In the area navigation, select "General &gt; PROFINET interface [X1] &gt; PROFIsafe &gt; PROFIsafe parameters".</li> <li>F-parameters: If necessary, manually modify the F-monitoring time.</li> <li>F-destination address: The F-destination address you set here must match the PROFIsafe address on the Mobile Panel in "Settings &gt; PROFIsafe" (see link). In this application example: 33.</li> </ul>		
12.	Mobile Panel		
	<ul> <li>In the area navigation, select "General &gt; PROFINET interface [X1] &gt; PROFIsafe &gt; Operating mode".</li> <li>I-device communication: Now you can modify the transfer areas for the input and output range for "IO failsafe". In the safety program, these addresses are evaluated in the "F_FB_KTP_Mobile" block (see link).</li> </ul>		
	HMI [HMI] 📴 Properties 🗓 Info 🔒		
	General IO tags System constants Texts		
	General     >     I-device communication       PROFINET Interface [X1]     Transfer areas       General		
	Ethernet addresses Transfer area Type Address in IO controller Length		
	Idevice communication     Idevice commu		
	Real time settings     I I O failsafe     F-HMI I 611     6 Byte		
	Advanced options 4 IO failsafe F-HMI Q 611 6 Byte		
	Diagnostics addresses		
	Information 4		
13.	<ul> <li>Mobile Panel</li> <li>Go to the Network view.</li> <li>Create an HMI connection between the F-CPU and the Mobile Panel.</li> </ul>		
14.	Connection box		
	Go to the Network view.		
	<ul> <li>In the hardware catalog, go to "HMI &gt; SIMATIC Mobile Panel &gt; System Components &gt; Connection Box advanced" to select the connection box and use drag and drop to move the connection box to the graphic area of the Network view.</li> </ul>		
	Select the connection box and go to the Device view.		
	• In the area navigation, select "General > PROFINET interface [X1] > Ethernet addresses".		
	- Interface: Select a subnet from the drop-down list.		
	- IP protocol: Enter the IP address.		
	- PROFINET: Specify a PROFINET device name. The name is not further evaluated.		

No.	Description
15.	Assigning the IO controller
	MobilePanel → Devices & networks
	🔐 Topology view 🎄 Network view 👔 Device view
	PLC_1 CPU 1516F-3 PN
	PINIE Addition
	<ul> <li>Go to the Network view.</li> <li>Assign an IO controller to the ET 200SP and the connection box (in this application example: the configured F-CPU).</li> <li>Left-click the text silhouetted in blue, "Not assigned".</li> <li>In the dialog, select the IO controller.</li> <li>The name of the assigned IO controller is displayed on the module.</li> </ul>
	View of the completed hardware configuration
	Topology view 🚠 Network view 🛐 Device view
	# IO system: PLC_1.PROFINET IO-System (100)       PLC_1       CPU 1516F-3 PN       PLC_1       PLC_1       PLC_1.PROFINET IO-Syste
16.	Customizing the I/O addresses (ET 200SP)
	If you want to change the default start addresses of the ET 200SP, the station must be assigned to an IO controller (in this case: the F-CPU). Otherwise, the input field is grayed out.

#### 4.3.2 STEP 7 user program

#### **Program structure**



#### Brief description of the blocks

No.	o. Action	
1.	OB1	
	Via OB1, FB10 is called, which, in turn, is used to call the blocks listed in the program structure.	
2.	"PLC-Code_KTP Mobile" block group	
	For greater clarity, all of the following blocks are grouped into this block group.	
3.	FB10, callStandardBlocks	
	The "FB200, FB202 and FB204" blocks are called via FB10. "DB10" is a multi- instance DB and contains the instances of the called FBs.	
4.	FB200, programRobot	
	The FB contains the control program to control the robot drive.	
5.	FB202, simulationMotionRobot	
	The FB contains the program to simulate the robot's movements on the HMI operator panel.	
6.	FB204, evaluationFaults	
	The FB generates fault and warning messages that are output on the HMI operator panel.	
7.	DB100, dataExchange	
	DB100 contains the data for data exchange between	
	the HMI operator panel and the control program.	
	• the individual program blocks (not the F-program part).	
8.	DB150, dataToSafety	
	For data exchange between "user program and safety program".	

No.	Action
9.	DB151, dataFromSafety
	For data exchange between "safety program and user program".

### FB200, programRobot (program information)

FB200 contains the essential program steps to control the robot drive.

No.	Action	
1.	Network 4, Automatic mode	
	To ensure that the function key for switching on the drive cannot be set to a "permanent hold-down", the signal is scanned using a positive edge.	
2.	Network 5, Manual mode	
	• To ensure that the function key for switching on the drive cannot be set to a "permanent hold-down", the signal is scanned using a positive edge.	
	<ul> <li>In "Manual mode", the drive is switched on/off using one function key (jog mode).</li> </ul>	
3.	Network 6, Service mode	
	• To ensure that the function key for switching on the drive cannot be set to a "permanent hold-down", the signal is scanned using a positive edge.	
	<ul> <li>In "Service mode", the drive is switched on/off using one function key (jog mode).</li> </ul>	
4.	Network 7, Drive on / off	
	The enable from the standard program for controlling the robot drive is given using this network.	
5.	Network 8, Output of the selected operating mode	
	A text list on the HMI operator panel outputs the current operating mode. The evaluation is performed in this network.	
6.	Network 9, Output of safety door open/closed	
	An animation on the HMI operator panel indicates whether the safety door is open or closed. The evaluation is performed in this network.	

#### FB202, simulationMotionRobot (optional – program information)

FB202 is used to simulate the robot movements and the elevator.

Using a graphic list, the simulation of the robot movements is displayed on the HMI operator panel. Depending on the selected operating mode, execution is displayed at different speeds.

The execution speed is specified using a clock memory.

Table 4-4

No.	Action
1.	Network 1, Movement in "Automatic" mode
	The execution speed is "simulated" using a clock memory. In this example: M10.0 (5Hz, 0.1 seconds)
2.	Network 2, Movement in "Manual" mode
	The execution speed is "simulated" using a clock memory. In this example: M10.2 (2.5Hz, 0.4 seconds)
3.	Network 3, Movement in "Service" mode
	The execution speed is "simulated" using a clock memory. In this example: M10.3 (2Hz, 0.5 seconds)

#### FB204, evaluationFaults

FB204 is used to evaluate fault and warning messages that are output on the HMI operator panel.

Special functions are not used.

The messages are acknowledged using the Mobile Panel or the hardware acknowledgment button.

### 4.3.3 STEP 7 safety program

#### Safety program structure

Figure 4-10



#### NOTICE

Make sure that "F\_FDBACK" (FB216) is always called after "F\_ESTOP1"(FB215) and "F\_SDFOOR" (FB217).

## Brief description of the blocks

Table 4-5	5	
No.	Action	
1.	FOB_RTG1	
	F-runtime group, FB1 "Main_Safty_RTG1" is called using this OB.	
2	FB1, DB1 (Main Safety RTG1)	
2.		
	FB1 is used to coordinate the following F-block calls. All of the following FBs are called using this FB.	
3.	FB302 (safteyRelatedRelease)	
	FB302 is used to evaluate	
	whether the safety circuit is closed.	
	- emergency stop OK.	
	- safety door closed.	
	- F-DI and F-DO modules OK.	
	the enabling button has been pressed.	
	"Service mode" is activated.	
	FB185 is called to generate a switch-on delay.	
4.	FB215 (F_ESTOP1), emergency stop shutdown with acknowledgment	
	FB215 is a protected function block from the F-library.	
	The block implements an emergency stop shutdown with acknowledgment. Internally, the block requires FB186 "F_TOF" (switch-off delay).	
5.	FB217 (F_SFDOOR), safety door monitoring	
	FB217 is a protected function block from the F-library.	
	The block implements safety door monitoring.	
6.	FB216 (F_FDBACK), feedback circuit monitoring	
	FB216 is a protected function block from the F-library.	
	The block implements feedback circuit monitoring.	
	Internally, the block requires FB186 "F_TOF" (switch-off delay).	
7.	FB198 (F_FB_KTP_Mobile)	
	F FB KTP Mobile is a protected function block from the F-library.	
	The block monitors the assigned operator panel.	
	One F_FB_KTP_Mobile is required for each Mobile Panel.	
8.	FB199 (F_FB_KTP_RNG)	
	E EB KTD DNG is a protected function block from the E library	
	The block prepares the output user data (Evaluation of enabling button and	
	emergency stop button.) One F_FB_KTP_RNG is required for each connection box.	

No.	Action
9.	FB306 (ackExecution), acknowledgment
	<ul><li>FB306 evaluates the acknowledgment using</li><li>the external acknowledgment button.</li><li>the panel.</li></ul>
	Acknowledgment using the panel requires "ACK_OP" (FB187). FB187 is a protected standard function block from the F-library. The block implements fail-safe acknowledgment from a panel.
	<b>Note</b> Make sure that the acknowledgment is always called at the end.
10.	OB83     Insert/remove OB       OB86     Rack failure

Note

For details about the function blocks used, please refer to the online help.

#### F-runtime group (FOB\_RTG1, OB123)

When inserting the F-CPU, STEP 7 Safety automatically inserts an F-runtime group.

For the F-runtime group, go to the project tree and select the "Safety Administration" project folder.

#### Figure 4-11



#### FB1, Main\_Safety\_RTG1

FB1 calls all F-function blocks and parameterizes them according to the input/output parameters.

#### FB302, safetyRelatedRelease (program information)

FB302 connects the safety circuit signals and the enabling button signals.

No.	Description	
1.	Network 1	
	Evaluation of the safety circuit	
	The network evaluates whether the safety circuit (emergency stop, etc.) is OK. It considers when the safety door may be open during operation and when it may not be open.	
2.	Network 2 and 3	
	Evaluation of the enabling button	
	The time while the enabling button is kept pressed is monitored to avoid the risk of misuse by an unauthorized hold-down of the enabling button.	
	This time value is transferred to the block as an "IN parameter".	
	In this case, the enabling button must be released within 10 seconds (see the call of FB302 call in FB1, Network 1).	
	This is monitored by the SFB4 "TON" switch-on delay.	
	Note on the SFB4 "TON" switch-on delay	
	SFB4 can be parameterized with an FB, DB call (instance DB) or, as in this example, with a multi-instance call (multi-instance DB).	

#### FB198, F\_FB\_KTP\_Mobile / FB199, F\_FB\_KTP\_RNG (program information)

**Note** Depending on the block version and F-CPU version used, it may be necessary to change the "safety system version" in the "Project tree > Safety Administration > Settings". After updating the version, select the "Clean up" button.

Table	4-7
10010	

No.	Action	
1.	Call of F_FB_KTP_Mobile	
	You will find the FB in the "Instructions" task card. Select the "Communication" tab. For a detailed description of how to parameterize the FB, please refer to the online help.	
	<ul> <li>Notes on the parameters</li> <li>Instance DB <ul> <li>You can use a multi-instance DB for the instance DB to be created.</li> </ul> </li> <li>QBAD / ACK_REQ /ACK_REI <ul> <li>When the Mobile Panel was parameterized, a start address for IO failsafe was stored in Properties <ul> <li>"General &gt; PROFINET interface [X1] &gt; Operating mode &gt; I-device communication" in the "Transfer areas" field (see link).</li> <li>The system will create an F-I/O DB of this transfer area. You will find this DB in the project tree, "Program blocks &gt; System blocks &gt; STEP 7 Safety &gt; F-I/O DBs". The name is composed of:</li> </ul> </li> </ul></li></ul>	
	<ul> <li>"F000""failsafe address"_"name of Mobile Panel""[F-I/O DB number]"</li> <li>For the sample project: "F00006_MobilePanel_01 [DB30017]".</li> <li>Navigate to this DB and select the "QBAD" / "ACK_REI" tag.</li> <li>MP_Data / MP_Data_Q</li> <li>Create a "PLC tag" of the "Integer" type for each parameter. Use the start address of the Mobile Panel's transfer area (IO failsafe address).</li> </ul>	
	Note "MP_Data / MP_Data_Q" parameters - For a SIMATIC S7-1500, use a tag of the "INTEGER" type. - For a SIMATIC S7-300, use a tag of the "WORD" type.	
2.	Call of F_FB_KTP_RNG You will find the FB in the "Instructions" task card. Select the "Communication" tab. For a detailed description of how to parameterize the FB, please refer to the online help.	
	<ul> <li>Notes on the parameters</li> <li>Instance DB <ul> <li>You can use a multi-instance DB for the instance DB to be created.</li> </ul> </li> <li>ID <ul> <li>The connection box is uniquely identified by the connection box ID. The value is specified in "decimal" format. <ul> <li>(In the connection box, the ID is set in "hex" format – see <u>link</u>).</li> <li>For the sample project:</li> </ul> </li> </ul></li></ul>	



## FB306, AckExecution (program information)

FB306 evaluates the acknowledgment.

Table 4-8

Description
Network 1
Acknowledgment using the panel
The "FB187" function block (F_ACK_OP) from the F-library is used for safe acknowledgment using the panel. This requires two buttons on the HMI operator panel (see <u>link</u> ).
A tag from a standard DB is used as an "IN parameter".
For details about fail-safe acknowledgment, please refer to the STEP 7 Online Help.
Network 2
Evaluation and output of the acknowledgment
The network combines the acknowledgment signal of the "external acknowledgment button" and the "acknowledgment" of the panel. Output is made to three outputs.

#### 4.3.4 Mobile Panel configuration

#### General

The Mobile Panel configuration does not include specifically configured functions. The safety-related functions of the Mobile Panel such as the

- emergency stop button
- and the enabling button

are evaluated using the safety program.

#### Acknowledgment using the Mobile Panel

No.	Description	
1.	Acknowledgment using the Mobile Panel	
	In conjunction with FB187 (F_ACK_OP), the Mobile Panel is used for fail-safe acknowledgment. This requires two buttons.	
	<ul> <li>Button 1</li> <li>In "Events &gt; Press", the "SetTag" function is assigned to the button.</li> <li>The tag is from the "dataExchange" DB (DB100). In this application example, the value "6" is assigned to the "DB100.DBW6" tag using the button.</li> </ul>	
	<ul> <li>Button 2         <ul> <li>In "Events &gt; Press", the "SetTag" function is assigned to the button.</li> <li>The tag is from the "dataExchange" DB (DB100).                  <ul></ul></li></ul></li></ul>	
	The two buttons are evaluated in FB306 "ackExecution" (see link).	
	The acknowledgment buttons were configured in a "pop-up window".	
	Acknoledgement         ACK Step 1       ACK         (push 1sec.)       Step 2	
	Button_1 [Button]	
	Properties Animations Events Texts	
	Click	

## 4.4 Device settings

#### **General information**

The following settings refer to the use of PROFIsafe for communication between the Mobile Panel and the F-CPU.

#### 4.4.1 Connection box

#### **Connection box ID**

The connection box is uniquely identified by the ID set on the connection box. The ID must be unique throughout the plant.

The ID must match the address stored in the Mobile Panel (see <u>link</u>) and the address assigned at the "F\_FB\_KTP\_RNG" F-block (see <u>link</u>).

#### Setting the box ID

No.	Figure	Action
1.	Image: Second secon	<ul> <li>Rotate the arrows of the rotary coding switches to the required hexadecimal value using a suitable tool. In the example on the left, the box ID is set to "23" (35 in decimal format). </li> <li>Notes <ul> <li>Values from "00" to "FF" (0 to 255 in decimal format) can be set using the rotary coding switches.</li> <li>Use the value "00" for "Stop button evaluated by safety relay" mode only.</li> <li>The value "FF" (255) is reserved and must not be used.</li> </ul> </li> </ul>

#### 4.4.2 Mobile Panel

#### General

It is assumed that the Mobile Panel is connected to the connection box and the box ID has been set.

No.	Action
1.	Opening the Control Panel
	Use the "Start Center" and the "Settings" button to open the Control Panel.
2.	Setting the Ethernet address
	Open the "Network and Dial-Up Connections" dialog.
	Enter the IP address.
	In this application example: 172.16.34.210
	255.255.0.0
3.	Transfer settings
	Open the "Transfer" dialog.
	In "Transfer channel", select <b>PN/IE</b> .
4.	Assigning the password
	Open the "Password" dialog.     Assign a password
	The password is used for the "Safety Operation" function (see <u>link</u> ). In addition, it protects access to the Control Panel (see <u>link</u> ).
	In this application example: 100
5.	Entering the PROFINET name
	Open the "PROFINET" dialog
	<ul> <li>Check the "PROFINET IO enabled" check box.</li> </ul>
	<ul> <li>Enter the PROFINET name. This name must match the name stored in the configuration (see <u>link</u>).</li> </ul>
	In this application example: mobile
6.	Entering the PROFIsafe address
	<ul> <li>Open the "PROFIsate" dialog.</li> <li>Enter the PROFIsate address. This address must match the address stored in the Mobile</li> </ul>
	Panel's hardware configuration (see <u>link</u> ).
	In this application example: 33

No.	Action
7. \$	Safety Operation
	<ul> <li>Open the "Safety Operation" dialog.</li> <li>From the drap down list, coloct "E Stop button evoluated by PROElecto" (1)</li> </ul>
	From the diop-down list, select E-Stop button evaluated by PROFisate (1). In the "Decimal field" enter the connection has ID (in "decimal" format). The "her value" is
	output automatically. The box ID must match the address stored in the connection box (see <u>link</u> ).
	In this application example:23 (35 decimal)
•	• Select the "Save" button to confirm your entries. A password prompt window opens.
•	<ul> <li>Enter your stored password (see <u>link</u>).</li> </ul>
	In this application example: 100
•	• If the entered box ID and the password are correct, this is indicated by a green "check mark".
•	Select the "Close" button to close the window.
	Certificates Date/Time Display InputPanel Internet Keyboard Mouse Network and Network ID OP
	Options Diał-up Co
	Password Printer Satety operation System
	Parameters
	Transfer WinCC Morify Pay The 25 Decimal 22 Hay
	Intern Verify Bux ID: 55 Declinar 25 Hex
	Operation mode parameters successfully stored in Connection Box.
	Save Close



# 5 Operation of the Application Example

# 5.1 HMI user interface

#### Table 5-1

No.	Action	Screenshot
1.	Start screen	Home Mobile Panels 2nd Generation the next level of mobile HMI devices
	Start screen view	PROFINET / PROFIlade Performance like a Comfort Panel
2.	Right-hand slide-in screen	I forme United Earlies and Generation the next level of mobile HMI devices
	Use this slide-in screen to navigate to the individual panel screens. The slide-in screen can be opened from any screen.	PROFINET / PROFinade Proformance like a Comfort Panel
3.	Top slide-in screen	No. Time Date Status Text Acknowledge gr 1 12092-17120014 k Emergency-stop togened 0
	Use this slide-in screen to open the alarm window. The slide-in screen can be opened from any screen.	
		Performance like a Comfort Panel Sturdy and brilliant at once
4.	Plant screen	Operating mode 1: Automatic mode
	Use the "Application" button to open the plant screen.	
	Use this screen to operate the robot.	23300000000000000000000000000000000000

# 5.2 Controlling the plant

#### **Basic information**

- After switching on the control voltage for the plant, it is necessary to completely open and close the safety door once.
- Changing the operating mode during operation interrupts control of the drive.
- When "Service mode" is deselected, a new operating mode must be deliberately selected on the panel.

#### Automatic mode

#### Table 5-2

No.	Description
1.	Selecting Automatic mode
	Use the "Autom. mode" function key to select Automatic mode.
	This operating mode can only be selected when "Service mode" is <b>not</b> selected using the key- operated switch.
2.	Drive on/off
	Use the "On" function key to switch the drive on.
	Use the "Off" function key to switch the drive off.
	If the safety door is opened or an emergency stop is triggered during operation, the drive is immediately switched off using the contactors (-K10 / -K11).

#### Manual mode

Table 5-3

No.	Description	
1.	Selecting Manual mode	
	Use the "Manual mode" function key to select Manual mode. This operating mode can only be selected when "Service mode" is <b>not</b> selected. This selection is protected by a password. After selecting the function key, a login dialog	
	User: user1	
	Password: 111  Enter the correct password and you can select the operating mode	
	Enter the correct password and you can select the operating mode.	

No.	Description
2.	Drive on/off
	<ul> <li>In this operating mode, only jog mode is possible.</li> <li>Pressing the "On" function key switches the drive on.</li> <li>Releasing the "On" function key switches the drive off.</li> <li>The "Off" function key is not evaluated.</li> </ul>
	If the safety door is opened or an emergency stop is triggered during operation, the drive is immediately switched off using the contactors (-K10 / -K11).

#### Service mode

Table 5-4

Description	
Selecting Service mode	
This operating mode <b>cannot</b> be selected using the Mobile Panel. It is selected using a separate key-operated switch.	
The safety door may be opened in this operating mode. When the door has been opened once, it is displayed as open on the HMI operator panel – regardless of whether or not it has since been closed.	
"Resetting" the view requires acknowledgment using the "ACK" button.	
Drive on/off	
In this operating mode, only jog mode is possible.	
Before you switch on the drive using the "On" function key, <b>always</b> press the enabling button first and keep it pressed.	
Pressing the "On" function key switches the drive on.	
Releasing the "On" function key switches the drive off.	
Do not continuously hold down the enabling button for more than 10 seconds (specified by the F-program). If held down longer, the drive (-K10 / -K11) is immediately switched off. The same is the case when the enabling button is released during operation or when an operation or when an	

#### Error acknowledgment

Table 5-5

	Description
1.	If a fault occurs during operation, e.g. because an emergency stop was triggered, clear the cause of the fault (release the emergency stop button) and acknowledge the message before you switch the plant back on.
	Use the "ACK" button or the "Pop-up-ACK_HMI" pop-up screen to acknowledge the fault.
	A PROFIsafe communication error must be acknowledged twice.
	<ul> <li>Error acknowledgment of PROFIsafe communication.</li> </ul>
	<ul> <li>Error acknowledgment of other messages.</li> </ul>

# 6 Debugging

The purpose of the following items is to support you in debugging.

- Why is the "PROFIsafe" function in the Mobile Panel configuration grayed out and cannot be activated?
  - To be able to activate the PROFIsafe option, the "IO device" check box in "Operating mode" must be checked (see <u>link</u>).
- Why is there no secure connection after replacing a device?
  - Check the PROFIsafe settings. After replacing a device, these settings need to be **re**parameterized.
- In which PII word can the emergency stop / enabling button be evaluated?

Word 0	0010-0010 Emergency stop button
Word 1	0010-0010 Enabling button
Word 2-5	Reserved

- Why is the entered box ID not applied to the Mobile Panel?
  - Check the settings of the rotary switches in the connection box. In the connection box, the box ID is set in "hexadecimal" format.
     At the F-FB and on the Mobile Panel, it is entered in "decimal" format.
- Problems with PROFIsafe communication
  - Check the PROFIsafe address in the configuration and on the Mobile Panel.
  - Check the PROFIsafe name in the configuration and on the Mobile Panel.
  - In the configuration, open the Device configuration and go to the Network view. Make sure that you have assigned the device names to the IO devices.
  - Make sure that the "IO device" check box is checked in "PROFINET" on the Mobile Panel.
- Problems when evaluating safety-relevant Mobile Panel functions
  - Check the F\_FB\_KTP\_Mobile parameter
  - Check the F-data block address
  - Check IW / OW at the F\_FB
  - View status information online

- Cannot find description of blocks in online help
  - Enter the complete F-FB name as the search term.
     For example, F\_FB\_KTP\_Mobile
- Why are the IO addresses of the ET200 SP modules (DI / DO modules) grayed out and cannot be changed?
  - If you want to change the default start addresses of the ET 200SP, the station must be assigned to an IO controller (in this case: the F-CPU). Otherwise, the input field is grayed out.
- Why are the robot movements not simulated?
  - In the F-CPU properties, select "System and clock memory" and make sure that the clock memory check box is checked / the correct byte is used.
- How can I set the box IDs of multiple connection boxes on the Mobile Panel?
  - Always use the same menu. Go to each connection box and plug in the Mobile Panel. Open the "Safety Operation" menu and enter the associated box ID.
- Is it possible to reactivate the PROFIsafe connection on the Mobile Panel using a system function if the PROFIsafe connection was deactivated using the "TerminatePROFIsafe" system function?
  - No. Activating the PROFIsafe connection requires that the panel's runtime be restarted.
- Why does the drive switch off when I remove the Mobile Panel from the connection box?
  - Make sure to disconnect the PROFIsafe connection before removing the panel. To do this, you can use the "TerminatePROFIsafe" system function; you can configure it, for example, to a button.
     Alternatively, stop the Mobile Panel runtime and confirm the PROFIsafe disconnection in the logoff dialog.

# 7 Links & Literature

Table 7-1

	Торіс	Title
\1\	Siemens Industry Online Support	https://support.industry.siemens.com
121	Download page of the entry	https://support.industry.siemens.com/cs/ww/en/view/103497649
\3\	Manual	Overview of various Mobile Panel manuals
		https://support.industry.siemens.com/cs/ww/en/ps/14746/man
\4\	Manual	SIMATIC ET 200SP Manual Collection
		https://support.industry.siemens.com/cs/ww/en/view/84133942
\5\	Manual	SIMATIC Industrial Software SIMATIC Safety – Configuring and Programming
		https://support.industry.siemens.com/cs/ww/en/view/54110126
\6\	Manual	SIMATIC Industrial Software SIMATIC Safety V13 – Getting Started
		https://support.industry.siemens.com/cs/ww/en/view/101177693
\7\	Manual	SIMATIC Industrial Software SIMATIC Safety – Configuring and Programming
		https://support.industry.siemens.com/cs/ww/en/view/54110126
\8\	Safety	Safety Evaluation Tool
		https://www.industry.siemens.com/topics/global/en/safety-
		integrated/machine-safety/safety-evaluation- tool/Pages/default.aspx

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# 8 History

#### Table 8-1

Version	Date	Modifications
V1.0	06/2014	First version
V1.1	02/2016	S7 Distributed Safety -> STEP 7 Safety Advanced
V2.0	10/2017	Key-operated switch evaluation modified (2-pole -> 1-pole). Drive control modified (hardware plan / software).