
SINUMERIK 840D sl, CNC system software 6 axes)	6FC5850-1XG21-5YA0
with HMI-sl, 6 languages, on CF Card; with license) Export	6FC5850-1YG21-5YA0
SINUMERIK 840D sl, CNC system software 31 axes)	6FC5850-3XG21-5YA0
with HMI-sl, 6 languages, on CF Card; with license) Export	6FC5850-3YG21-5YA0

Information on the installation and operation for SINUMERIK NCU 710.2, NCU 720.2, NCU 720.2 PN, NCU 730.2, NCU 730.2 PN.

The CNC software 2.6 SP1 HF4 (internal version 02.06.01.04.007) comprises the following components:

- NCK Software V78.06.03
- SNCK V02.06.00.00.001
- PLC OpSys V20.70.44 (PLC 317)
- PLC OpSys V27.90.13 (PLC 319)
- PLC-FB15 V02.06.22
- CP V01.40.03
- MCP Client V01.04.35
- SINAMICS Software V02.60.52.00
- Sinumerik Operate V02.06.01.07.002
- LinuxBase V02.70.27.00
- SNC V01.03.00.00
- Technology Cycles V02.06.61.01
- Measuring Cycles V02.06.61.01
- Shopmill Cycles V02.06.61.01
- ShopTurn Cycles V02.06.61.01
- Cycles ISO Compatibility V02.06.61.01
- Advanced contour cycles V02.06.58.01
- MachineDataForCycles V02.06.61.01
- Adapting Cycles V02.06.61.01

Functional improvements included in NCK as compared to Version 2.6 SP1 HF3

PR number

AP00914458	AP00969629	AP01062717	AP01099773
AP01102940	AP01116485	AP01121555	

Functional improvements included in Operate as compared to Version 2.6 SP1 HF3

PR number

AP01108764	AP00977701	AP01002557	AP01006421
AP01114522	AP01070289	AP01075734	AP01059434
AP01051444	AP01037149	AP01083742	AP01081541
AP01094469	AP01008609	AP01124848	AP01140529
AP00979014	AP01081624	AP01108092	AP01108100
AP01108394	AP01109428	AP01108088	AP01108102
AP01108704	AP01108259	AP01112691	AP01065337
AP01129577	AP00995078	AP01007157	AP01060364
AP00892444	AP01125173	AP01095872	AP01128609
AP01033815	AP01035182	AP01092645	AP01104042

AP01091955	AP00970727	AP01009932	AP01051401
AP01083176	AP01082762	AP01082871	AP01119423
AP01112171	AP01116535	AP01127729	AP01099420
AP00999882	AP01049490	AP01126084	AP00981507
AP01078187	AP01079154	AP01063627	AP01078424
AP01078270	AP01083501	AP01083461	AP01017048
AP01018242	AP01070058		

To operate a NCU with the option "Operation without SINUMERIK OP", you can set the image size of Operate in the file /card/user/sinumerik/hmi/cfg/run_hmi.ini with the entry [HMI]

Resolution = ; permissible values: 640x480, 800x600, 1024x768

Functional improvements included in Cycles (technology, measurement, JobShop) as compared to Version 2.6 SP1 HF3
PR number

AP01044255	AP01066533	AP01082943	AP01063840
AP01047057	AP01105455	AP01097000	AP01093385
AP01092166	AP01043049	AP01083076	AP01099801
AP01048056	AP01104736	AP01125868	AP01127729
AP01075872	AP01130584	AP01138181	AP01125698
AP01084221	AP01028593	AP01078454	AP01083941
AP01148457	AP01093210	AP01058068	AP01140008
AP01140054	AP01014210	AP01081192	AP00446575

Functional changes / extensions of the configurable machine data

- New MD 52248 \$MCS_REV_2_BORDER_TOOL_LENGTH
- New MD 51024 \$MNS_BLOCK_SEARCH_MODE_MASK_JS
Bitmask for available search run modes (ShopMill, ShopTurn single-channel)
- MD 52006 DISP_PLANE_TURN – write permission now SIEMENS

Functional improvements included in NCK as compared to Version 2.6 SP1 HF2
PR number

AP00870940	AP00900512	AP00929470	AP00931319
AP00954987	AP00958059	AP00967338	AP00967383
AP00975035	AP00976720	AP00980739	AP00981649
AP00982894	AP00988061	AP00993548	AP00994578
AP01005974	AP01012510	AP01015339	AP01016338
AP01025331	AP01030227	AP01033474	

Functional improvements included in Operate as compared to Version 2.6 SP1 HF2
PR number

AP00940019	AP00948387	AP00954677	AP00958898
AP00961306	AP00967256	AP00969685	AP00970628
AP00973162	AP00973691	AP00976957	AP00977718
AP00979936	AP00985554	AP00985912	AP00987647
AP00988148	AP00992451	AP00997089	AP00999744
AP01001224	AP01004705	AP01006556	AP01007425
AP01009168	AP01011116	AP01016807	AP01017048
AP01024065	AP01034371	AP01041245	AP01047164

AP01048515	AP01055528	AP01057357	AP01059263
AP01020024			

Functional improvements included in cycles (technology, measuring, JobShop) as compared to Version 2.6 SP1 HF2

PR number

AP00790072	AP00966091	AP00988448	AP00988452
AP00991485	AP00994534	AP00996447	AP01001710
AP01002669	AP01013928	AP01017563	AP01026468
AP01040350	AP01059756		

1. Installing the CNC software:

The NCU service system >= V02.60.29 on a USB stick is required to install the CNC software.

The software can be installed for the first time using the NCU service system and TCU with full keyboard or using WinSCP. Installation without keyboard or WinSCP is only possible using a USB stick that has been prepared for automatic upgrade (refer to 1.5).

The software may only be installed on a SanDisk CompactFlash 5000 1GB. The Order No. [MLFB] of the empty card is 6FC5313-5AG00-0AA0. Optionally, you can use a CF Card 8GB 6FC5313-6AG00-0AA0.

1.1 Installing the NCU service system on a USB stick:

The NCU service system is available as USB stick image in the directory emergency_bootsys_ncu of the DVD supplied. The installdisk.exe program for copying is located next to it. Connect a USB stick >= 512MB, preferably Siemens 6ES7648-0DCx0-0AA0, to your PG or PC (with Windows XP) and determine the associated driver letters. Call up installdisk to copy the NCU service system to the USB stick:

```
installdisk --verbose --blocksize 1m <Image file> <Drive letter>
```

Example:

(-- means 2x minus characters)

```
installdisk --verbose --blocksize 1m D:\emergency_bootsys_ncu\linuxbase-512M.img X:
```

This means that the capacity of each USB stick is limited to 512MB.

Alternatively:

```
installdisk --verbose --blocksize 1m D:\emergency_bootsys_ncu\linuxbase-512M.img X:
```

If the resize.img is used, then after it has been downloaded, an NCU must be booted from this USB stick so that the image on the stick is unzipped and the FAT partition is generated. This means that the full capacity of the USB stick is therefore available.

The command specified above is preferably executed in a DOS shell.

To do this, you require administrator rights on your PG/PC

After completing installdisk, remove the USB stick from the PG / PC and re-insert it into the PG / PC. Under Windows, you will now see an empty USB stick. Now, copy the required CNC software (file with the .tgz extension) to this USB stick from the DVD supplied, directory ncu_sw.

The USB stick can now be inserted in one of the two USB connectors of the NCU 7x0. When it is powered-up, the NCU boots from this USB stick. Operator control is either from a TCU that is connected to the NCU or via PG / PC using WinSCP under "Open Terminal".

The use of the NCU service system is described in the documentation /IM7/ on the DVD supplied.

1.2 Upgrading an NCU 7x0.2 with CNC-SW 2.6 preliminary

A SanDisk 1GB CF card is required! It is not permissible to upgrade from other software releases. A new installation is then required! It may then be necessary to observe Section 9.5 upgrading cycles.

For an upgrade, all user data on the CF card in the directories /user, /addon, /oem and the license key is kept.

When upgrading systems with several NCUs / PCU50, please carefully note Section 7 regarding networking!

- Boot the NCU from the USB stick (refer to 1.1).
- Using F3, select the service shell.
- Log-on as user "manufact". In this case, it may be necessary to use an external keyboard as the user name must be written using lower-case letters.

- After the \$ operator prompt of the service shell, enter the following command:
sc restore -update /data/<cnc-sw>.tgz
The software update has been completed when the \$ prompt reappears.
- Remove the USB stick.
- Boot the NCU by powering it down/up again.
- The PLC, drives and NC can then be commissioned.

1.3 New installation

IMPORTANT: With this procedure, the contents of the CF card are completely deleted, this also applies for an empty CF card.

- Boot the NCU from the USB stick (refer to 1.1).
- Using F3, select the service shell.
- Log on as user "manufact" - for an empty CF card with "admin", password "SUNRISE". In this case, it may be necessary to use an external keyboard as the user name must be written in lower-case letters.
- After the \$ operator prompt of the service shell, enter the following command:
sc restore -full /data/<cnc-sw>.tgz
The software installation has been completed if the \$ prompt reappears.
- Remove the USB stick.
- Boot the NCU by powering it down/up again
- When booting for the first time with TCU(s), the TCU(s) must be log onto the system. The TCU name (default TCUx) and the address of an assigned MCP must be specified.
- The PLC, drives and NC can then be commissioned.

1.4 Systems without TCU

If there is no OP with TCU to operate the NCU service system when installing the software corresponding to 1.2 or 1.3, then operation is also possible from PCU50 or PC/PG using WinSCP (Commands / Open Terminal) or VNC viewer.

Under certain circumstances, it is not possible to install the software without an NCU service system on the USB stick because there is not enough free memory space on the CF card.

1.5 Automatic upgrade using a boot-capable USB stick:

Using an appropriately prepared USB stick ≥ 1 GB, it is possible to execute an automatic "restore -updated" or "restore -full". In this case, a script (autoexec.sh) and the CNC software must be copied to the stick. It is not permissible to change the name of the script. The CNC software copied to the stick must be renamed update.tgz or full.tgz. The SIM/NCK rotary switch on the NCU must then be set to position 7 and the NCU booted from the stick. The script only runs when the switch is in the 7 position. Otherwise, the NCU boots from the stick and a branch is then made into the service menu. Depending on the designation of the CNC software, the script decides whether a "restart -update" or a "restore -full" is to be carried out. In addition, before the restore, the script runs a data backup of the CF card. The progress made in the individual script steps can be tracked on the 7-segment display or also at the internal SINUMERIK Operate. The precise significance of the displays and the individual steps are described in a separate document. The script is available on the DVD supplied.

2. Excerpt of the new functions from NCK 78.04.02

- Modified braking behavior at Stop D
Stopping within the configured Stop D time is now ensured.
- The direction of spindle rotation can be activated via a MD bit and adapted to the rotational direction of M3/M4 when tapping.
- Progevent-poweron ASUPS can be processed despite pending alarms.
- The max. number of part programs has been increased to 1000.
- Multi-channel sequencer programming PROGRAMSYNC.
- Multitools
- Monitoring for maximum tool speed and acceleration

- ADI4-Board with NCU7xx.PN (PLC319)
- Online Help from the PLC symbol table
- NC-controlled Extended stopping and retraction ESR.

3. Notes:

- After installing the CNC Software Version 2.6 SP1 on the CF card, a general reset must be made for the NCU and PLC: SIM/NCK switch in position 1, PLC switch in position 3 and then power-down/power-up.
- NCU730: When alarm "2120 NCK fan alarm" is output, then an immediate response (approx. 20 seconds) must be realized in the PLC program and the axes shut down in a controlled fashion, if a double-fan module is **not** being used.
- NCU710 / NCU720: The NCU does not boot if either the fan module is not available or if it is defective. This only applies to the NCU730 equipped with a double fan module if both of the fans have failed.
- Alarm 15122 Power ON after power failure "%1 data was restored, of which %2 machine data, %3 errors"
If %3 - the number of errors occurred - is greater than zero, then it is not recommended to continue processing with the data. In order to avoid subsequent problems, an actual data back-up should be read-in (downloaded).
- It is not always possible to port an NCK series commissioning archive from 840D power line to 840D sl without processing.
- Before overwriting a licensed CF card, it is absolutely necessary to back up the license key. The key is included in the 'keys.txt' file and is located in the /card/keys/sinumerik path.
The key can be backed-up e.g. using WinSCP from the PG/PC.
- The licenses are permanently linked to the particular CF card (card ID) and can only be used on this card.
- Data backups should be read-in (downloaded) in the following sequence - NC, PLC, drive. It makes sense to separately generate the NC, PLC and drive archives.
- Contour handwheel and velocity override using the handwheel are only released with Profibus MCP.
- The reset knob at the NCU allows the NCU module to restart. It cannot be guaranteed that the complete system can be restarted for all configurations. This also applies to the PI service from the PLC with FB4.
- A template of the actual standard basesys.ini is available in the catalog /card/siemens/system/etc.
- Port 102 on X130 is interlocked as standard. If the control is to be accessed via X130 using Step 7 or a SINUMERIK Operate, then port 102 must be enabled.
This can be done by making the following entry in the file /user/system/etc/basesys.ini:
[LinuxBase]
FirewallOpenPorts=TCP/102
If required, port 5900 can also be enabled for an external VNC viewer.
- The Ethernet handwheel of the HT2 is connected (marshalled) to the fifth handwheel interface.
Example for three Ethernet handwheels. The third handwheel is located in HT2:
MD11350[0]=7 11351[0]=1 11352[0]=1
MD11350[1]=7 11351[1]=1 11352[1]=2
MD11350[2]=7 11351[2]=1 11352[2]=5
- **HT2:** The PLC application example for the HHU (handheld unit), included in the toolbox for Powerline, cannot be transferred to the HT2 without first making some changes. The variable descriptions of the NCVAR must be adapted. FC13 now supports the visualization of four lines. As a consequence, the significance of the "ROW" parameter has changed as follows:

0 = no display output
 1 = 1st line
 2 = 2nd line
 3 = line 1 and line 2, alternating
 4 = 3rd line
 5 = line 1 and line 3, alternating
 8 = 4th line
 F = automatic change of all lines

The contents of the display must be saved in the "ChrArray" field, type string[64].

Example of the parameter setting for the HT2 at FB1 (OB100):

```

BHG          :=5
BHGIIn       :=DB100.BhgIn_170
BHGOOut      :=DB100.BhgOut_150
BHGStatSend  :=DB100.DBD80
BHGStatRec   :=DB100.DBD84
BHGIInLen    :=
BHGOOutLen   :=
BHGTimeout   :=
BHGCycl       :=
BHGRecGDNo   :=2 // corresponds to the setting of the rotary switch * the connection box or the MPP.
BHGRecGBZNo  :=2 // corresponds to the setting of the rotary switch * the connection box or the MPP.
BHGRecObjNo   :=1
BHGSendGDNo   :=2
BHGSendGBZNo  :=1
BHGSendObjNo  :=1
BHGMPI
BHGStop
BHGNotSend

```

* Rotary switches S1 and S2 at the connection box or MPP are used to define the DIP number with which the participant registers itself in the system (here, S1=0, S2=2).). Address "0" is not permissible, as with this setting, the DHCP server cannot allocate any addresses.

- HT2: The upper key row is displayed in the PLC as follows:
 The key on the top left (SK1) is mapped in EBn+2 Bit 1
 SK2 = EBn+2 Bit 6
 SK3 = EBn+3 Bit 7
 SK4 = EBn+4 Bit 4

The LEDs of the upper key row can be activated by the PLC as follows:
 Signals to handheld unit ABn+0 Bit 0 correspond to LED top-left
 Bit 1 for 2nd LED from top left, etc.

- HT2: Display of 12 characters incl. the decimal point and sign with FC13. In order to be able to use the extended display at the HT2, the values (these are generally the position values) must be transferred to the FC13 in the real 2 format. In order that FC13 can appropriately process the values, the Parameter DataType must be set to B#16#30. The values must be transferred in exactly the same way as they are read from FB2 / FB5 in the real 2 format. It is not possible to interpret the values between output FB2 / FB5 and input in FC13. The values read-in from FB2 / FB5 in the real 2 format must be appropriately converted in FC13.
 The Digits parameter specifies the number of decimal places (value range 1..9). The display update is managed in FC13. The signals "Acknowledge numerical display" in the EBm+5 and "New data for selected line" in ABm+1 no longer have to be interconnected in the PLC.
 Example:
 - displaying four axis position values that are read with FB2.
 - The results of the read operation from FB2 are saved in the real 2 format in DB399.DBX0.0,... DB399.DBX8.0, etc.
 - the display is to three places after the decimal point.

```

FUNCTION FC 399 : VOID
TITLE =
{ S7_language := '9(1) English (USA) 01.04.2009 15:23:07' }
VERSION : 0.0
CODE_VERSION1

```

```
VAR_TEMP
```

```

END_VAR
BEGIN
NETWORK
TITLE = NETWORK

//attention: FC13 writes to AB1 of HT2

//1st axis actual position to row 1

SET ;
= DB399.DBX 150.7; //always one in QB m.7

CALL FC 13 (
Row      := B#16#F, // display four rows
ChrArray := DB106.display, // string array[64]
Convert   := TRUE,
Addr      := DB399.DBX 0.0, // 1st result from FB2
DataType  := B#16#30,
StringAddr := 16, // row 1 address in string
Digits    := B#16#3,
Error     := M 610.0);

//2nd axis actual position to row 2

CALL FC 13 (
Row      := B#16#0,
ChrArray := DB106.display,
Convert   := TRUE,
Addr      := DB399.DBX 8.0, // 2nd result from FB2
DataType  := B#16#30,
StringAddr := 32, // row 2 address in string
Digits    := B#16#3,
Error     := M 610.1);

//3rd axis actual position to row 3

CALL FC 13 (
Row      := B#16#0,
ChrArray := DB106.display,
Convert   := TRUE,
Addr      := DB399.DBX 16.0, // 3rd result from FB2
DataType  := B#16#30,
StringAddr := 48, // row 3 address in string
Digits    := B#16#3,
Error     := M 610.2);

//34th axis actual position to row 4

CALL FC 13 (
Row      := B#16#0,
ChrArray := DB106.display,
Convert   := TRUE,
Addr      := DB399.DBX 24.0, // 4th result from FB2
DataType  := B#16#30,
StringAddr := 64, // row 4 address in string
Digits    := B#16#3,
Error     := M 610.3);

BE ;

END_FUNCTION

```

- Alarm 46xx: The machine data for the Ethernet handwheel must be checked.
Example for the first handwheel: MD11350[0]=7, 11351[0]=1, 11352[0]=1
- Traversing the spindle with limited torque (Focon) or traversing the spindle to a fixed stop:
The power displayed at the SINUMERIK Operate is calculated from the limited torque as 100% and displayed.

- From NCK >= V67.05.03 onwards and ADI4 board V01.04.04, the ADI4 board can be operated at the 840D sl with internal PLC 317.
- Dbsi 1 , just like before, has not been released in conjunction with SINUMERIK and integrated drive control.
- An NCU Bios >= V1.4 is required for operating a 1GB CompactFlashCard in an NCU730. The BIOS is only available through e_support as an upgrade is only required very infrequently.
- Starter, in conjunction with 840 D sl, has, as before, only been released for diagnostics.
- If the number of part programs set by the machine data approximately correspond to the number of actually used part programs, the value in the machine data must be increased (as a result of the additional cycles).
- Interpolatory traversing of positioning axes is prevented with Alarm 8031 "...axis has no IPO functionality."
- SPI and PW are keywords (they have always been keywords) and cannot be used as axis identifiers.
- The function G643 (internal block blending) has been released for applications in the tool change area (e.g. optimizing the approach to the tool change position). It has not been released for applications in the machining process itself.
- The function G644 (blending with possible dynamic performance) has been released for applications in the tool change area (e.g. optimizing the approach to the tool change position). It has not been released for applications in the machining process itself.
- Software version, max. 6 axes: The standard pre-assignment for the number of axes is defined as 3.
- The "extended measuring" function with the distributed measuring input at the SINAMICS modules does not function (MEAC, MEASA, MEAWA).
- No channel gaps are possible in a system with a maximum of two channels.
- Access to drive data via system variables \$nn_nn has not been released. Only the system variables transferred in telegram 116 are possible.
- ESR has not been released.
- Now, analog to the 840Di functionality, ASUBs can be started via Profibus PLC I/O. The machine data should be selected the same as for 840Di. There are no fast NCK I/O (peripherals) that are mapped in the DB10 of the PLC. However, the known ASUB start options (from DB10 or FC9 via PLC program) are still possible.
- Fast ET200 Simatic modules can be used to replace the DMP modules used for Powerline. In this case, for the PLC317 - in conjunction with NCK >= V 67.07.05 - there is a possibility of operating one of the two Profibus lines in clock cycle synchronism (details on this are provided in a separate description).
- When using 31-axis software on an NCU710.1, 6 of the 31 axes can be used and 4 channels from 10 channels.
- Machine data 10008 \$MN_MAXNUM_PLC_CTRL_AXES is no longer in the data set. It has been replaced by MD19160.
- MD 10062 \$MN_POSCTRL_CYCLE_DELAY must be zero. Check the existing data backup.
- Machine data 32250 \$MA_RATED_OUTVAL[] must have a value of zero.
- IMD (Integrated Monitoring & Diagnostic) :
The feedback signal in the GUD variable _PM_MISSING_TOOL_REFRESH after writing "1" to variables is only updated when the screen changes.
- Safety: There is a new handling option that involves synchronized actions or the synchronized action elements. Up to status 1.3 (NCK 62), using the SI option - synchronized action level 2 was simultaneously internally set. This meant that the channel MD 28250, NUM_SYNC_ELEMENTS was able to be set to a value > 159.
This situation changes with NCK release 67. The synchronized action level 2 is no longer included in Safety. This is the reason that there is a new machine data in which the synchronized action elements for SAFE.SPF are defined, MD 28251, NUM_SAFE_SYNC_ELEMENTS.
With option SLP_I_O=1, a maximum of 500 can be written to this machine data - and for SPL_I_O=2, a maximum of 5000.
However, the number (count) of required synchronized action elements should be determined in order to avoid that the performance is unnecessarily reduced.
The number (count) of the free SI synchronized action elements can be read using the system variable \$AC_SAFE_SYNAC_MEM.
If this variable is called before the start and after SAFE.SPF has run, then the difference is the number (count) of elements that SAFE.SPF occupies. This difference should be entered into

MD 28251 with a certain amount of reserve.

An index 1-5 must be specified when writing to MD 25300 using synchronized actions.

- Safety: Changed checksums for safety functionality integrated in the drive.
As a result of the new safety functions integrated in the drive, the checksums for these functions must be re-acknowledged.

To do this, "95" (Safety-commissioning) must be entered into parameter p10.

The parameters of the actual checksums must then be copied to the parameters of the reference checksums:

p9798 to p9799

p9898 to p9899

Then, p10 must be again set to zero. As a consequence, the values are automatically saved (p971 is set to 1). Wait until the data has been completely saved.

The operations can also be initiated in HMI-Advanced under IBN/NC/Safety Integrated using the softkeys "Activate commissioning mode" and "Deactivate commissioning mode".

- The help function M6 is no longer output as standard a block search.

Counter-measure:

Change the help function group in MD 22040 \$MC_AUXFU_PREDEF_GROUP[5] into a free group.

- If the value of MD18210 deviates from the standard pre-assignment, in order to upgrade from SW1.4 / 2.4 to SW1.5 / 2.5, then as a minimum, MD18210 must be increased by 21 MB DRAM.
- HT2 can be used as handheld operator unit from software release 1.5 HF5 / 2.4 SP1 and higher. Depending on the setting in basesys.ini, the HT2 is booted from the master (refer to the general information on networked systems). The master can be an NCU as well as also a PCU 50.
- Tool manager: There is a new handling option. If several real magazines are being used, then this can be enabled using an option. A real magazine is included in the basic scope.
For compatibility reasons, the previous option \$ON_TECHNO_FUNCTION_MASK Bit4=1 must still be set to 1 - however it is not included in the license handling.
- Toolbox from V01.05.01 and higher and Step 7 from V5.4 SP2 and higher are required.
- The retentive memory of the PLC 319 is limited to 256kB.
- Deleting PLC 319:
After deleting the PLC, by actuating the PLC rotary switch or from Step 7, the PLC program is subsequently automatically reloaded.
If PLC initialization is initiated using the operator action - PLC switch in position 3 and power off/on, then the PLC program is not automatically loaded. This is also then no longer realized with the above mentioned sequence of operator actions.
- The actual cycle time is no longer available in DB5 but in DB8. The cycle time can also be called via the start infos of the OB1.
- The PLC module IM153-2 MLFB 6ES7 153-2AA02-0XB0 cannot be used.
Counter-measure: 6ES7 153-1AA03-0XB0
- The PLC series (standard) commissioning archive must be generated when the PLC is in the stop state. Otherwise, it cannot be guaranteed that the PLC resumes cyclic operation after loading the data back-up.
- The star/delta changeover with FC17 requires Sinamics parameters.
Prerequisites:
The appropriate DDS/MDS must be set-up in the drive!
P827[0] ⇔ P827[1] ⇔ P827[n] must not be equal to one another!
The contactor is changed over by the application=> P833, bit0=1
Pulses are cancelled by the drive => P833, bit1=0
PLC output setting: Star operation, this is the reason that when booting (powering-up), a "1" should be set in the axis DB bit 21.5
- The service interface X127 of the NCU should only be used for commissioning and service.
- The machine control panel (MCP) is operated on Profibus or Ethernet. Mixed operation is not permissible.
- Profibus1 must be configured so that the softkeys CU, Infeed, Drives are displayed at the SINUMERIK Operate.
- For PLC 319, Profibus diagnostics using FB125 are not possible.
- PLC 319, ProfiNet functionality: CBA PLC communication has been released.
- Blocks FC1007 AG_LOCK, FC1008 AG_UNLOCK, FC1010 AG_CNTRL have not been released.

- The FORCEN [FORCING] function of the PLC in conjunction with 840D sl has only been released. It is possible with the PLC317 from PLC operating system >= V20.70.37 (e.g. 2.4 SP1 HF11) / PLC319 and higher with a PLC operating system >= V26.90.10 (e.g. 2.4 SP1 HF11) and higher.
- For 840D sl, it is not permissible that the VDI interface signal DB10.DBX57.3 is connected up.
- HMI-Advanced software / commissioning tool from 7.6 and higher is required to commission the drive.
- Functions to measure i and n using Starter and HMI Advanced cannot be used in parallel. If Starter measurements are required, this requires a power OFF=>ON and then measurements must be immediately made using Starter. Measurements performed with Starter must not be preceded with measurements performed using HMI-Advanced.
- If a SINAMICS component is replaced or upgraded, then the firmware release must be checked and if required, brought to the original release status.
(Key word: Macro 150399)
The firmware releases can be checked in the following parameters:
Control Unit R18 → Firmware release of the CU
Infeed R128 → Firmware release of the infeed
Drive MD R128 → Firmware release of the power unit
R148 → Firmware release of the sensor module
- Initially, Starter is still required to determine the motor code.
- Line supply voltages: In order that the system operates smoothly in the final destination country, the following parameters must be set in the specified sequence
P010 = 1
P210 = Rated line supply voltage of the country in which the equipment is to be operated
P211 = Rated line supply frequency of the country in which the equipment is to be operated
P340 = 1
P3410 = 4
P3900 = 3
Save RAM to ROM
Power-down the system, only power-up again when it is actually connected to the line supply in the country in which the equipment is to be finally used.
A line supply identification is performed with the next ON command at the ALM - and the values determined saved so that they are not lost if the line supply fails.
- The APC function increases the NCU load. The impact on performance should be estimated before it is used.
- p1240, p1244, p1248, p1250:
If, in SW V2.4, VDC control and DDS changeover were activated, then after an upgrade, the contents of the indices >0 from p1240 should be checked to ensure that they have the correct value.
- Drive clock cycles of 62.5 µs have been released with 840D sl and SW 2.5 SP1. The following conditions then apply:
 - two axes can be operated with this setting on a CU or NX.
 - only the same clock cycles can be set on a double-axis module
- For SINUMERIK software releases 1.3 and 1.4/2.4, different firmware versions of the components involved in the **safety functions** (NCU, NX, Motor Modules, DRIVE-CLiQ motors) can be mixed without having to adapt the firmware versions.
From SINUMERIK software release 1.5/2.5 and higher, the following applies:
The firmware versions of the Motor Modules, Sensor Modules and DRIVE-CLiQ motors involved in the safety functions (these include integrated Sensor Modules) must be adapted to the SINAMICS firmware version of the NCU.
This is realized automatically when booting if parameter p9826 (firmware, automatic) is set to 1 (standard setting). When **Safety Integrated** is used, parameter p9826 (firmware, automatic) must be set to 1 and must not be re-parameterized. For a **Safety Integrated** acceptance test, the safety firmware versions of all of the Motor Modules, Sensor Modules and DRIVE-CLiQ motors involved in the safety functions must be read-out, logged and checked against the following list:
<http://support.automation.siemens.com/WW/view/de/28554461>
Every line in the tables represents a permissible combination of the safety firmware versions.
- The maximum drive system utilization of the CU or NX must not exceed 80% (the utilization level is displayed in parameter 9976[xx]).

- The NCU load level as a result of the position controller and interpolator should not exceed **60%** in the "reset" state. The actual load can be checked under Diagnosis / System resources.
- Cam output (position switching cycles) for modulo rotary axes is not possible in a time window < 4 IPO clock cycles.
- The MPPs and MCPs PN are operated in the Ethernet mode at the 840D sl. Switch positions 9 and 10 simultaneously "on" (PN mode) is not permissible.
- The machine data to describe the spindle dynamics must be set so that they approximately correspond to the actual dynamics of the spindle. If the values are unnecessarily increased, then alarms can occur at the transition from spindle operation to positioning operation.
- NCU 7xx.2 PN: It is not possible to access Profinet PLC I/O from the NCK via system variables.
- NCU 7xx.2 PN: Profinet interfaces 1 and 2 (upper two) are available.
- The "Parking axis" function with an SMI encoder is not possible without power off/on.
- Alarm 7300: If NC archives from software releases < NCK 75.00.00 are used, Alarm 7300 is output if MD18235=0. MD18235=20000 is the standard setting.
- The function "Approach fixed stop G75" is not permissible for active radius compensation G41 / G42 (Alarm 14091, Index 9).
- During fixed-point approach with G75, the fixed point is approached with non-linear interpolation (RTLIOF). As a result, the axis are traversed with the set jerk for the positioning axes (\$MA_JOG_AND_POS_MAX_JERK).
- Machine data 11295[0..9] now configures the memory. When a change is made, this is not signaled by an alarm. Values deviating from the standard must be removed in existing archives before making the upgrade.
- Alarm 8025: Advanced Surface 6FC5800-0AS07-0YB0 is an option and is interlocked using an option data.
- If you wish to use the X127 service interface with a PG/PC for an NCU7x0.2 with SW 2.6, then it has to be noted that the network interface of the PG/PC operates in the "DHCP client" mode - i.e. the "IP address is automatically allocated".
If the network interface of the PG/PC has been set to a fixed IP (192.168.215.xx), then although a ping goes to X127, neither with Step7 nor with an HMI is it possible to go online. The firewall is activated as the default setting.
- STEP 7 hardware configuration Sinumerik NCU 7xx.2 PN:
The different versions V2.4 / V2.6 / V2.7 in the hardware catalog refer to the appropriate PLC operating system of the PLC 319. The PLC operating system is part of the NCU software and thus depends on the NCU software version. The operating system included in the software version can be checked in the diagnostic screen (Diagnosis / Version / PLC / Details).
As a consequence, the NCU must be selected in the STEP 7 hardware configuration.
Example:
The NCU Software Version 2.6 HF2 comprises a PLC operating system 319-3PN/DP Version 27.90.xx.
- Therefore, a NCU 7xx.2 PN (V2.7) must be selected in the hardware configuration.
- The Software Version 2.6 SP1 requires the PLC Toolbox V02.06.06.
- The NCU Link has not been released in combination with safety axes.
- The behavior of the NCK with regard to the dynamic offset values ACC, ACCLIMA, VELOLIM, VELOLIMA, JERKLIM, JERKLIMA has changed. The machine data description shows the individual effect.
- Archives with MD 19730.11 = false are incompatible. The machine data 19730.11 (hmi_function_mask) must always be set.
- The machine data 18150 must be increased when defining more than two channels. Archives with 18150=150 (standard) may be incompatible.
- Archives with MD 32250 > 0 are incompatible. With MD32250 > 0, speed setpoint or torque setpoint standardization is no longer transferred from the drive.
- The interface signal "Invert M3/M4" now also acts when tapping with G331/G332.
In applications in which the interface signal is always set to "1", the spindle is now rotated in the incorrect direction with G331/G332. To achieve a behavior that is compatible with earlier versions, the bit 22 in MD35035 must be set to "1" (the standard default is 0).
- Archives with MD28253=100 (old default value) may be incompatible. Change the MD into 200 (new default).

- Archives with MD19730[0] =0 are incompatible. Softkeys are missing in MDA. Change the MD into 804hex.
- Due to an implementation error, Spline Interpolation could be released without a license alarm. If this feature has been used, you require a new license key.
- So far, the gear stage 1 could be preset with 0 and 1 in the DB[axis].DBB16. Now, a gear stage change is always requested when specifying 0 in the data byte 16. Upon acknowledgement of the gear stage change with "0", the Alarm 22010 "Actual gear stage does not correspond to the setpoint gear stage" is output. It may be necessary to adapt the user PLC program.
- The function TANGON with additional parameter "P" has not been released. Remedy: Use the standard setting "S".
- The Siemens cycles are loaded upon each startup from the CF card to the CPU. This behavior can be switched off / on by using the service commands `sc disable s_cycles` / `sc enable s_cycles` and performing a subsequent general NC reset.
- The contents of the Siemens GUD variables (SGUD) have been relocated in PGUD. To be able to load archives comprising SGUD, these must be processed. Otherwise, the contents of the SGUD and PGUD variables may be provided twice.
- Grinding technology:
The new function "Calculate grinding wheel peripheral speed in diameter" has not been released due to AP01041616.
- The SD43235 has a speed limit of 10,000 rpm as default value. When upgrading to software version NCK 78.00 or later and spindle speeds exceeding 10,000 rpm, the SD43235 must be increased to the corresponding value. The speed is limited by SD43235 if the system variable `$AC_SMAXVELO_INFO[n]` has the value 21.
- Multitool as manual tool:
With repeated selection (of tools within this manual multitool), in the sequence `T="x" M06 --> T0 M06 --> T="Y" M06 --> T0 M06`, the identifier "manual tool" is not set upon the second tool selection. As a result, the system tries to store the multitool in the magazine with the next T0 M06.
- When loading the topology from a Sinumerik 840D sl with NCU730.2 PN (0AA2) into an empty Starter project, errors occur during uploading.
The online access to the CU_INT functions properly.

Operating the program "NC_ARC_UPDATE"

System requirement: Windows XP with SP2 or SP3

Area of validity:

This tool allows to process NC archives which have been created with SINUMERIK 840D sl, SW 2.5 or later, before reading them in in SW 2.6 SP1.

The definitions of data block SGUD.DEF are adapted to the new Software Version 2.6 SP1 or later.

Function:

The program "NC_ARC_UPDATE" removes GUD variables from NC archives, which are included in the files SGUD.DEF and PGUD.DEF.

Operation:

1. Copy the file NC_ARC_UPDATE.exe into a directory on the drive C:.
2. Double-click on NC_ARC_UPDATE.exe.

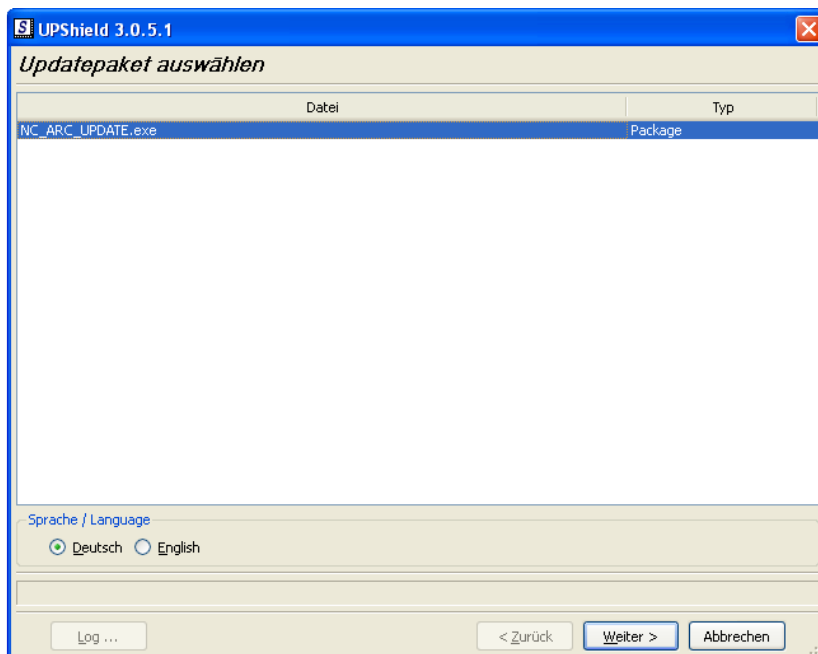


Fig. 1: Start screen

3. Actuate the "Next" softkey.

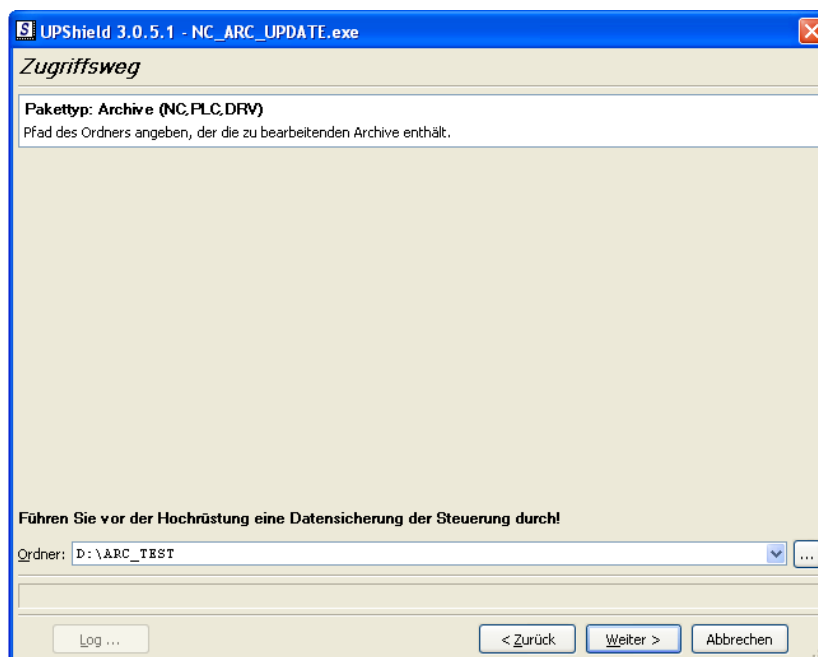


Fig. 2: Drive and directory selection for original archive

4. Actuate the "Next" softkey.

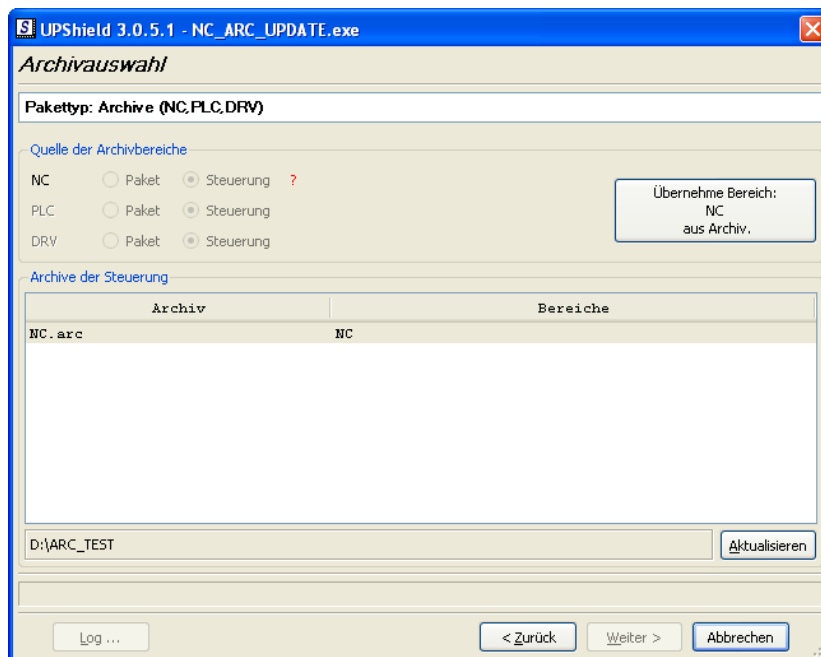


Fig. 3: Display of the NC archives which can be converted.

5. Press the button “Arrow down” resp. use the mouse to select the archive.
The selected NC archive is highlighted in blue.

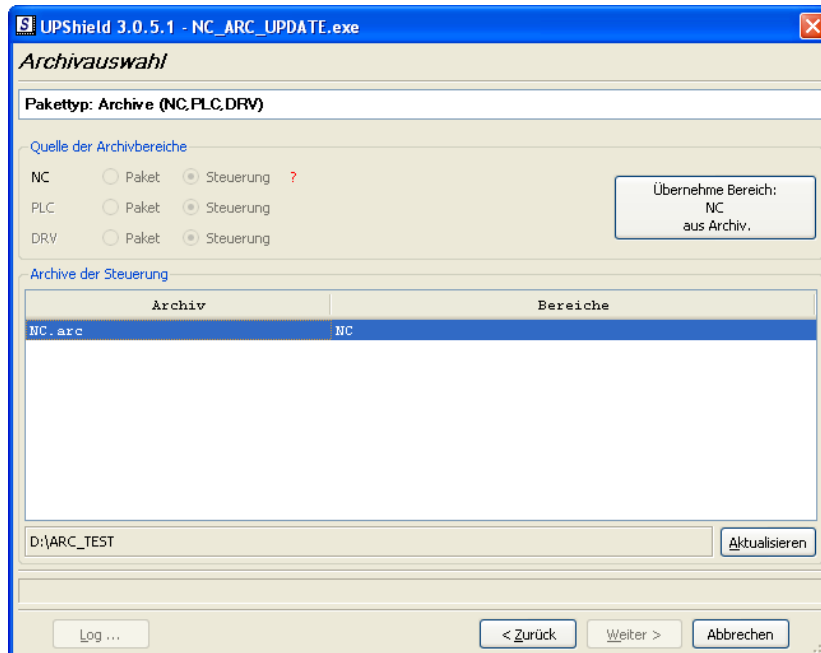


Fig. 4: Archive selection

6. Actuate the softkey “Accept area:“.

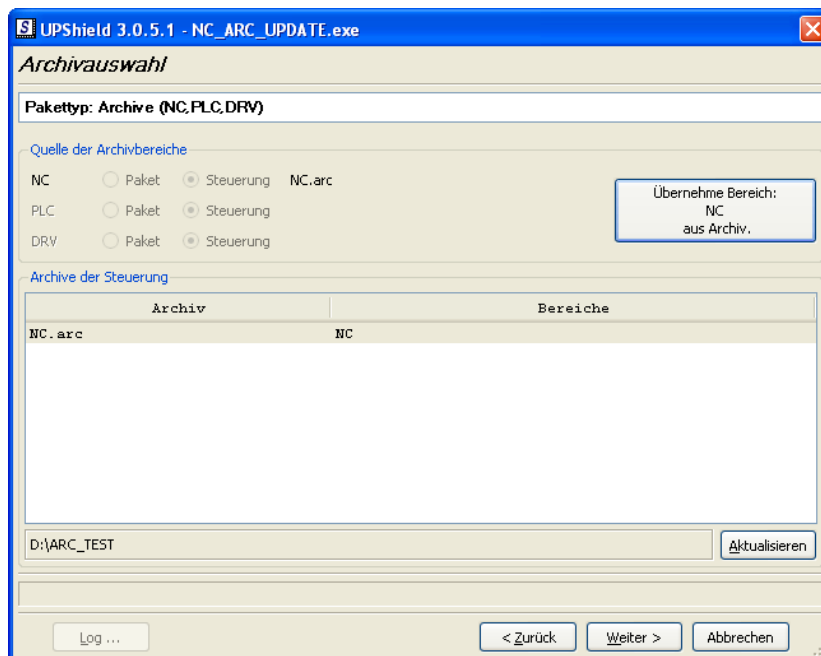


Fig. 5: Archive selected

7. Actuate the “Next” softkey

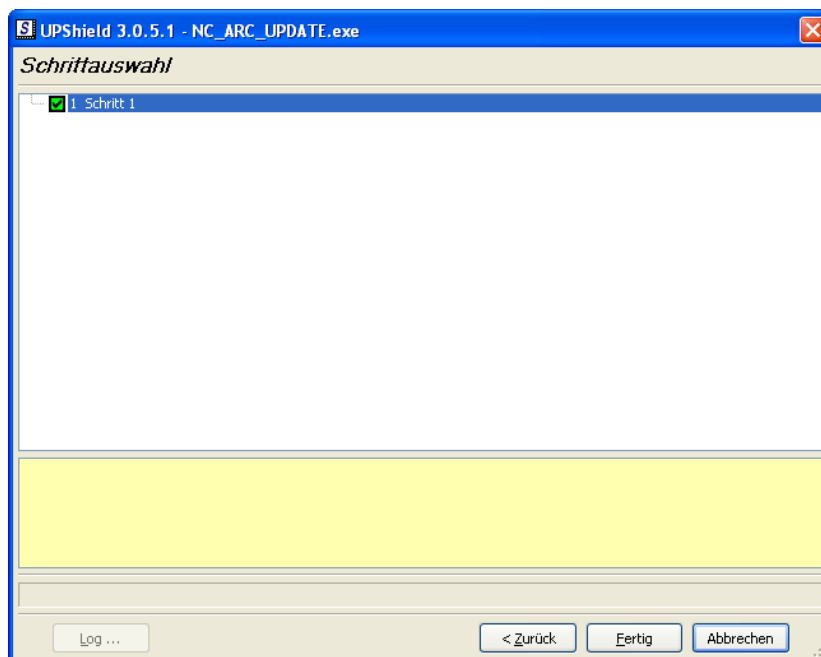


Fig. 6: Step display 1st step

8. Actuate the “Next” softkey

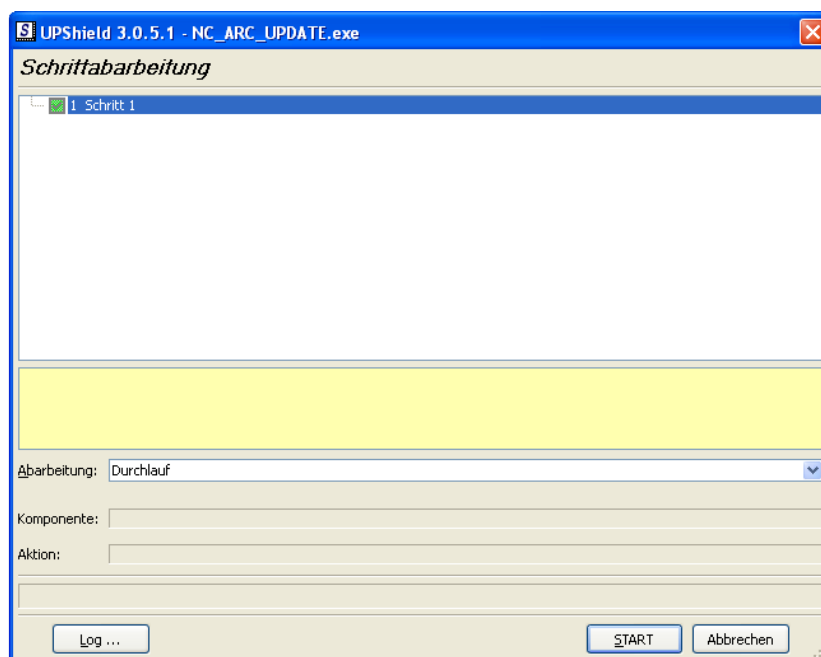


Fig. 7: Step processing

9. Actuate the “Start” softkey.

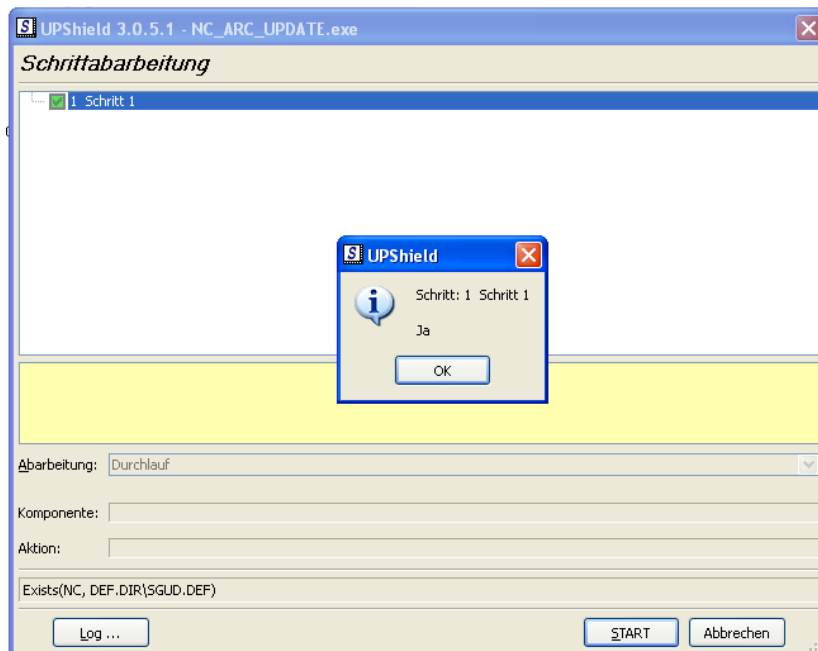


Fig. 8: Start the 1st step

10. Actuate the “OK” softkey.

The selected NC archive is processed and a new archive called “Update.arc” is generated. Update.arc is stored in the same directory as the original archive.

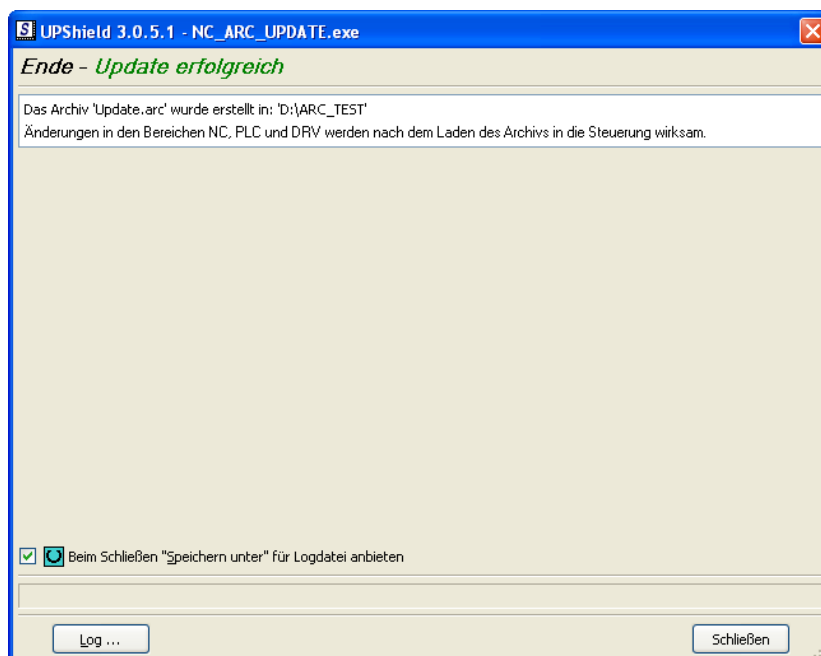


Fig. 9: End of program

- **Machine data change as a result of the changed Drive ES SlaveOM**

Drive ES SlaveOM is responsible for allocating addresses of the drive units at the Profibus of the PLC. Addresses are allocated in the PLC HW Config. The addresses allocated here must be entered into the NC machine data MD13050[nn] and when safety is active they must be entered into MD10393[nn] - corresponding to the axis configuration required.

When Starter from V4.1.n and higher is installed (later, also with the installation of Toolbox V2.6), the "new" Drive ES SlaveOM is linked in. Now - for each CU or NX - an address space is reserved for 6 axes - this is different than previously. This occurs when newly generating or adapting a PLC hardware configuration. As a result, under certain circumstances, addresses can shift or gaps can occur.

This modified address distribution **must** then be communicated to the NC in machine data 13050[nn] and when safety is active, in MD10393[nn] – as otherwise, the axis assignments are no longer correct. This is especially the case if you are working with the existing NC data backups. The reason for this is that they no longer match the PLC hardware configuration.

Further, in HW Config, the address of telegram 390 (PZD-2/2) of the first NX changes from 6516 to 6530. When using additional NC modules, the address is incremented with an offset of 10. Machine data MD13120[1+n] must be appropriately adapted.

If existing PLC projects are imported into an S7 environment with "new" Drive ES SlaveOM, then the old address configurations are kept. However, drive objects that have been newly inserted in this project have the new address allocation. A standard "new" address allocation is achieved using "reorganized addresses".

If, for NX objects from an existing configuration, "Standard telegram 1 (PZD-2/2)" is entered, then this must be replaced by telegram 390 in order to achieve a standard, new address allocation.

Example:

An NCU is configured with a Sinamics Integrated and two NX10 each with 3 axes.

Address distribution with the "old" version of Drive ES SlaveOM:

On the NX10_1, the 3rd axis has address 4420

On the NX10_2, the 1st axis has address 4460

Address distribution with the "new" version of Drive ES SlaveOM:

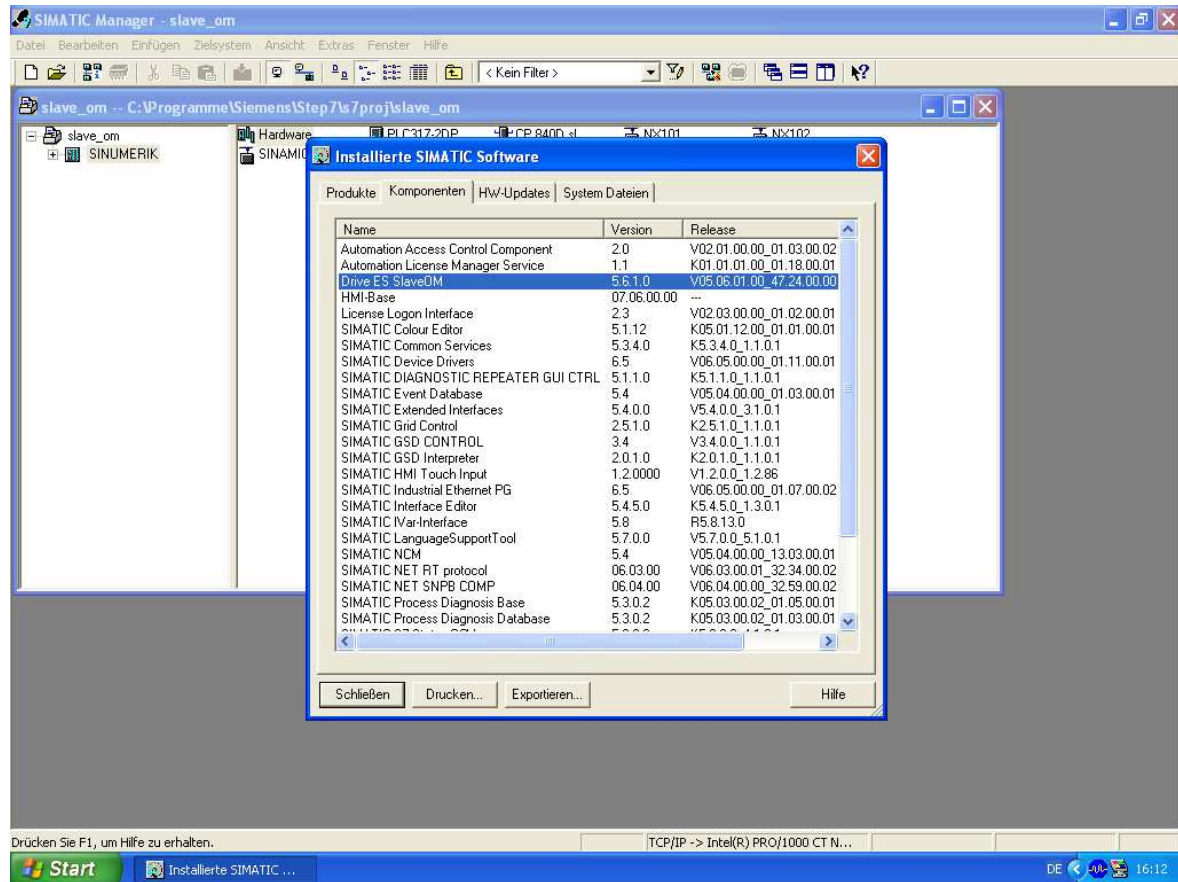
On the NX10_1, the 3rd axis has address 4420

On the NX10_2, the 1st axis has address 4580

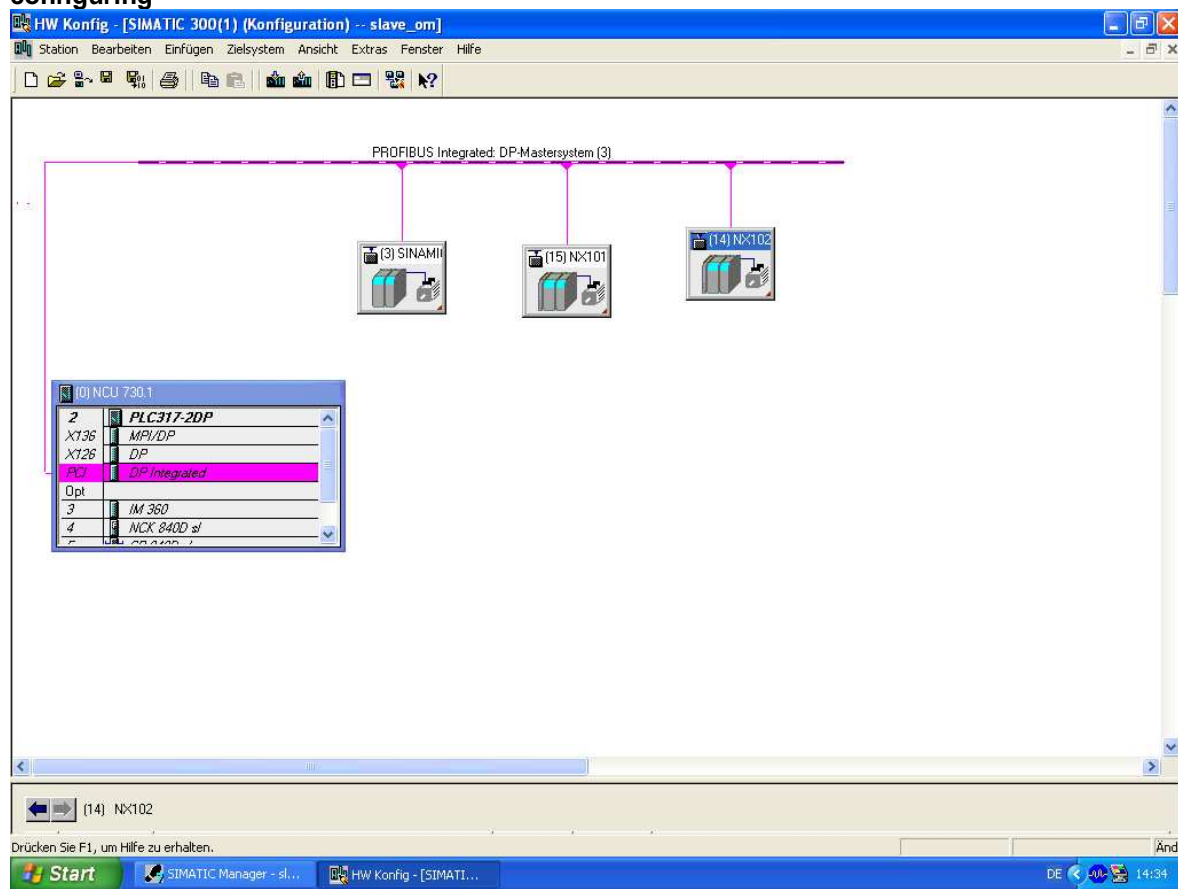
Tip:

When re-configuring existing configurations, in order that a complete change over is made to the new addressing, a start should be made at the lowest slave number to initiate the address allocation using the key "addresses".

All of the slaves have been allocated new addresses, if the note "No change" is output for each slave when initiating the address allocation.

"Old" version of Drive ES SlaveOM

PLC HW configuring



HW Konfig - [SIMATIC 300(1) (Konfiguration) -- slave_om]

Station Bearbeiten Einfügen Zielsystem Ansicht Extras Fenster Hilfe

[0] NCU 730-1

2 PLC 31

X136 MPI/DP

X126 DP

3 DP

4 IM 360

5 NCK 84

PROFIBUS Integrated DP-Mastersystem (3)

[3] SINAM

DP Slave Eigenschaften

Allgemein Konfiguration Takt synchronisation

Slot	Antrieb	PROFIBUS Partner
Typ	Adre...	Typ PR... E/A... Pro... L... Einheit Konsistenz
9	Istwert PZD 1 Eingang	2 4380 --- 19 Wwort Gesamte ...
10	Sollwert PZD 1 Ausgang	2 4380 --- 11 Wwort Gesamte ...
11	Achstrenger	
12	Safety Ein-/Ausgang	2 6892 --- 12 Wwort Gesamte ...
13	Istwert PZD 1 Eingang	2 4420 --- 19 Wwort Gesamte ...
14	Sollwert PZD 1 Ausgang	2 4420 --- 11 Wwort Gesamte ...
15	Achstrenger	
16	Istwert PZD 1 Eingang	2 6516 --- 2 Wwort Gesamte ...
17	Sollwert PZD 1 Ausgang	2 6516 --- 2 Wwort Gesamte ...

Übersicht Details

Slot einfügen Slot löschen

Master-Slave-Konfiguration 1

Master: (2) DP Integrated

Station: SINUMERIK

Kommentar:

OK Abbrechen Hilfe

(15) SINUMERIK_NX10

Slot	Baugru...	Telegrammauswahl/Vorb...
4	Drive Data	SIEMENS Telegramm 116, PZD-11/19
5	Drive Data	SIEMENS Telegramm 116, PZD-11/19
6	Drive Data	SIEMENS Telegramm 116, PZD-11/19
7	Drive Data	SIEMENS Telegramm 116, PZD-11/19
8	Drive Data	SIEMENS Telegramm 116, PZD-11/19
9	Drive Data	SIEMENS Telegramm 116, PZD-11/19
10	Drive Data	SIEMENS Telegramm 116, PZD-11/19
11	Drive Data	SIEMENS Telegramm 116, PZD-11/19
12	Drive Data	SIEMENS Telegramm 116, PZD-11/19
13	Drive Data	SIEMENS Telegramm 116, PZD-11/19

Drücken Sie F1, um Hilfe zu erhalten.

Start SIMATIC Manager - sl... HW Konfig - [SIMATI... Dokument1 - Microsof... DE 14:26

NX10_1

6SL3040-0NC00-0AA0
DP-Slave SINUMERIK NX10: SINUMERIK-Schnittstelle,
zyklische Kommunikation, Takt synchronisation

HW Konfig - [SIMATIC 300(1) (Konfiguration) -- slave_om]

Station Bearbeiten Einfügen Zielsystem Ansicht Extras Fenster Hilfe

[0] NCU 730-1

PLC 31

X136 MPI/DP

X126 DP

DP DP

Dpt IM 360

4 NCK 84

PROFIBUS Integrated DP-Mastersystem [3]

(15) SINUM

(14) SINUM

(3) SINAM

DP Slave Eigenschaften

Allgemein Konfiguration Takt synchronisation

Slot	Antrieb	Typ	Adre...	Typ	PR...	E/A...	Pro...	L...	Einheit	Konsistenz
4	Safety	Ein-/Ausgang	2	6916	12	Wort	Gesamte ...			
5	Istwert	PZD 1	Eingang	2	4460	---	19	Wort	Gesamte ...	
6	Sollwert	PZD 1	Ausgang	2	4460	---	11	Wort	Gesamte ...	
7	Achstrener									
8	Safety	Ein-/Ausgang	2	6940	12	Wort	Gesamte ...			
9	Istwert	PZD 1	Eingang	2	4500	---	19	Wort	Gesamte ...	
10	Sollwert	PZD 1	Ausgang	2	4500	---	11	Wort	Gesamte ...	
11	Achstrener									
12	Safety	Ein-/Ausgang	2	6964	12	Wort	Gesamte ...			

Übersicht Details

Slot-einfügen Slot-föschen

Master-Slave-Konfiguration 1

Master: (2) DP Integrated

Station: SINUMERIK

Kommentar:

OK Abbrechen Hilfe

(14) SINUMERIK_NX10

Slot	Baugru...	Telegrammauswahl/Vorbelegung	E-Adresse	A-Adresse	Kommentar
4	Drive Data	SIEMENS Telegramm 116, PZD-11/19	6916... 6939	6916... 6939	
5	Drive Data	SIEMENS Telegramm 116, PZD-11/19	4460... 4497		
6	Drive Data	SIEMENS Telegramm 116, PZD-11/19		4460... 4481	
7	Drive Data				
8	Drive Data	SIEMENS Telegramm 116, PZD-11/19	6940... 6963	6940... 6963	
9	Drive Data	SIEMENS Telegramm 116, PZD-11/19	4500... 4537		
10	Drive Data	SIEMENS Telegramm 116, PZD-11/19		4500... 4521	
11	Drive Data				
12	Drive Data	SIEMENS Telegramm 116, PZD-11/19	6964... 6987	6964... 6987	
13	Drive Data	SIEMENS Telegramm 116, PZD-11/19	4540... 4577		

Drücken Sie F1, um Hilfe zu erhalten.

Start SIMATIC Manager - sl... HW Konfig - [SIMATI...

DE 14:23

SINAMICS S120 CU310 DP

SINAMICS S120 CU320

SINAMICS S150

SINUMERIK NX10

SINUMERIK NX15

SINAMICS S

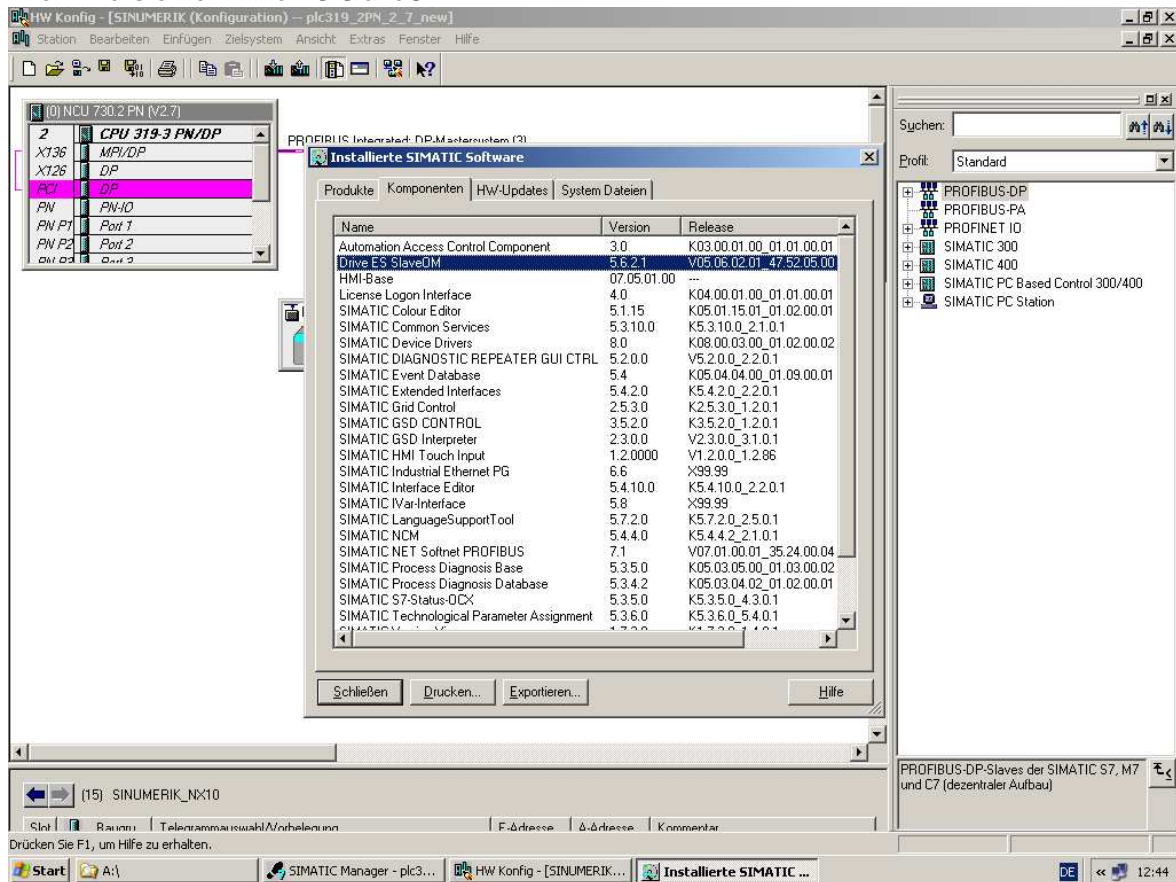
SINAMICS G130/G150

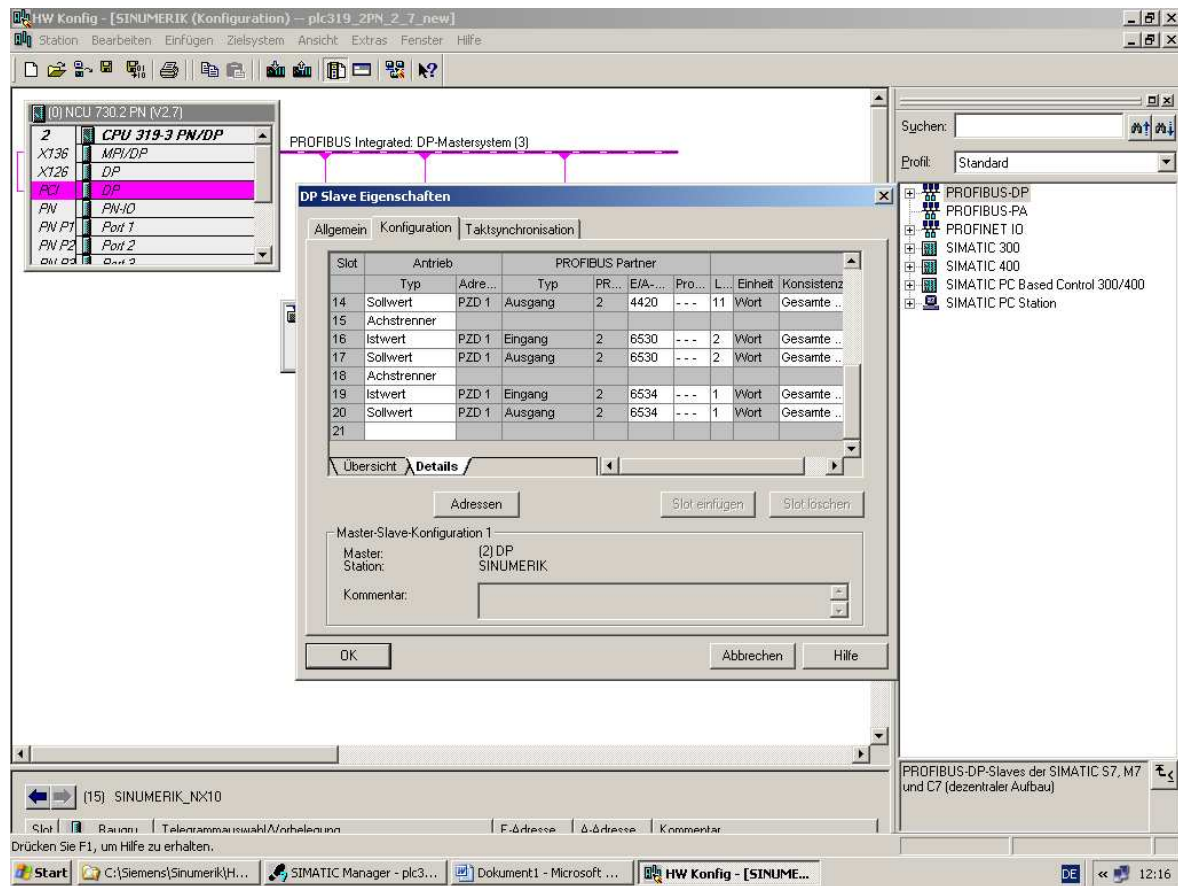
SINUMERIK

6SL3040-0NC00-0AA0

DP-Slave SINUMERIK NX10, SINUMERIK-Schnittstelle, zyklische Kommunikation, Takt synchronisation

NX10_2

"New" version of Drive ES SlaveOM



NX10_1

HW Konfig - [SINUMERIK (Konfiguration) - plc319_2PN_2_7_new]

Station Bearbeiten Einfügen Zielsystem Ansicht Extras Fenster Hilfe

[0] NCU 730.2 PN [V2.7]

2 CPU 319-3 PN/DP

X136 MPI/DP

X126 DP

PC DP

PN PN-IO

PN P1 Port 1

PN P2 Port 2

Port 3

PROFIBUS Integrated: DP-Mastersystem (3)

Suchen: Profil: Standard

PROFIBUS-DP

PROFIBUS-PA

PROFINET IO

SIMATIC 300

SIMATIC 400

SIMATIC PC Based Control 300/400

SIMATIC PC Station

DP Slave Eigenschaften

Allgemein Konfiguration Taktsynchronisation

Slot	Antrieb	Typ	Adre...	Typ	PR...	E/A...	Pro...	L...	Einheit	Konsistenz
4	Safety	Ein-/Ausgang	2	6988	---	12	Wort	Gesamte ..		
5	Istwert	PZD 1	Eingang	2	4580	---	19	Wort	Gesamte ..	
6	Sollwert	PZD 1	Ausgang	2	4580	---	11	Wort	Gesamte ..	
7	Achstrener									
8	Safety	Ein-/Ausgang	2	7012	---	12	Wort	Gesamte ..		
9	Istwert	PZD 1	Eingang	2	4620	---	19	Wort	Gesamte ..	
10	Sollwert	PZD 1	Ausgang	2	4620	---	11	Wort	Gesamte ..	
11	Achstrener									
12	Safety	Ein-/Ausgang	2	7036	---	12	Wort	Gesamte ..		

Übersicht Details

Adressen Slot einfügen Slot löschen

Master-Slave-Konfiguration 1

Master: (2) DP

Station: SINUMERIK

Kommentar:

OK Abbrechen Hilfe

(14) SINUMERIK_NX10

Slot Baugruppe Teletermauswahl/Verknüpfung F-Adresse A-Adresse Kommentar

Drücken Sie F1, um Hilfe zu erhalten.

PROFIBUS-DP-Slaves der SIMATIC S7, M7 und C7 (dezentraler Aufbau)

NX10_2 Start C:\Siemens\Sinumerik\H... SIMATIC Manager - plc3... Dokument1 - Microsoft ... HW Konfig - [SINUME... DE 12:18

Machine data

13050[nn]

Inbetriebnahme: CHAN1 JOG Ref: MPF0
Kanal RESET Programm abgebrochen
ROV

120402 DP003.Slave003: CU: Erstinbetriebnahme erforderlich

Allgemeine-MD (\$MN_)

Adresse	Variable	Wert	Einheit
13050[0]	\$MN_DRIVE_LOGIC_ADDRESS	4100	po
13050[1]	\$MN_DRIVE_LOGIC_ADDRESS	4140	po
13050[2]	\$MN_DRIVE_LOGIC_ADDRESS	4180	po
13050[3]	\$MN_DRIVE_LOGIC_ADDRESS	4220	po
13050[4]	\$MN_DRIVE_LOGIC_ADDRESS	4260	po
13050[5]	\$MN_DRIVE_LOGIC_ADDRESS	4300	po
13050[6]	\$MN_DRIVE_LOGIC_ADDRESS	4340	po
13050[7]	\$MN_DRIVE_LOGIC_ADDRESS	4380	po
13050[8]	\$MN_DRIVE_LOGIC_ADDRESS	4420	po
13050[9]	\$MN_DRIVE_LOGIC_ADDRESS	4460	po
13050[10]	\$MN_DRIVE_LOGIC_ADDRESS	4500	po
13050[11]	\$MN_DRIVE_LOGIC_ADDRESS	4540	po
13050[12]	\$MN_DRIVE_LOGIC_ADDRESS	4580	po
13050[13]	\$MN_DRIVE_LOGIC_ADDRESS	4620	po
13050[14]	\$MN_DRIVE_LOGIC_ADDRESS	4660	po
13050[15]	\$MN_DRIVE_LOGIC_ADDRESS	4700	po
13050[16]	\$MN_DRIVE_LOGIC_ADDRESS	4740	po
13050[17]	\$MN_DRIVE_LOGIC_ADDRESS	4780	po
13050[18]	\$MN_DRIVE_LOGIC_ADDRESS	4820	po
13050[19]	\$MN_DRIVE_LOGIC_ADDRESS	4860	po

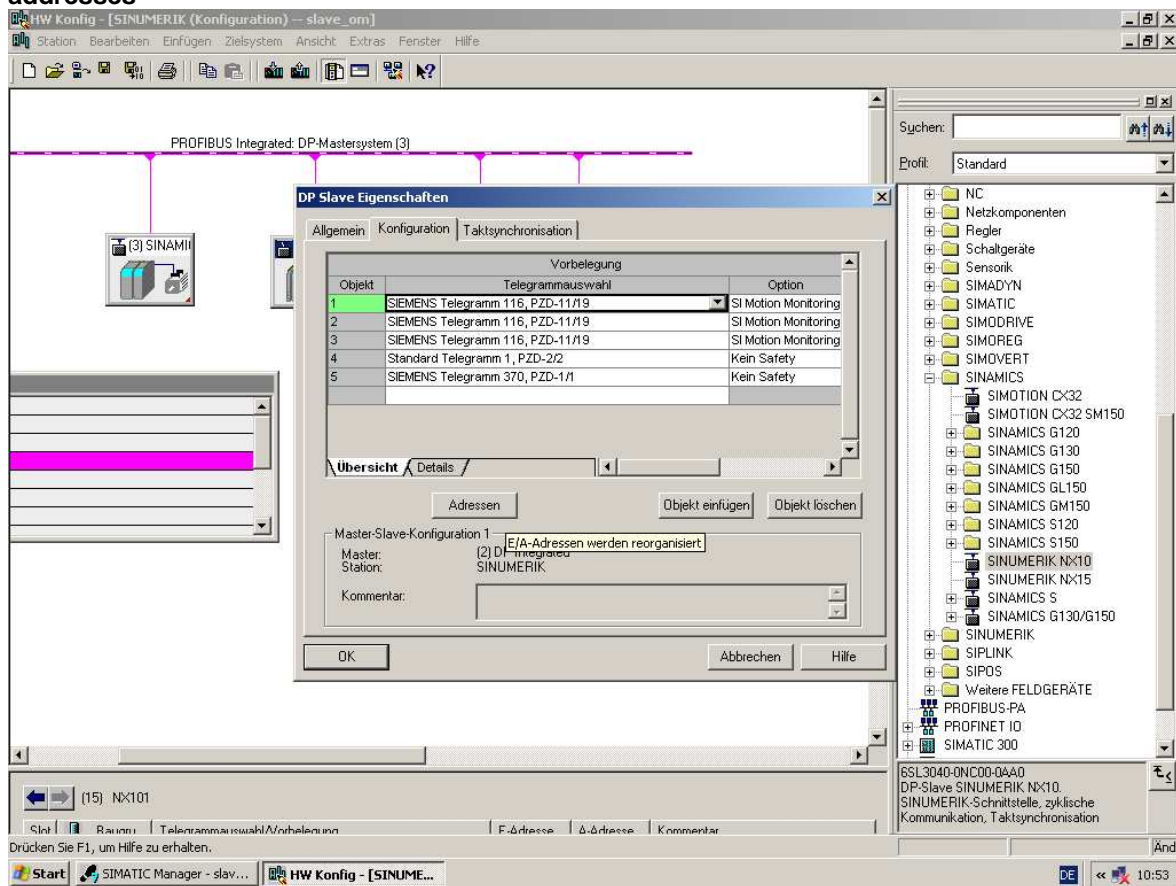
logische Antriebsadressen

Suche: MD wirksam setzen, Reset (po)..., Suchen..., Weiter-suchen, Anzeigeoptionen...

Start: T., p., H., d., d., d., m., P., ib, i...

DE 12:26

Reorganizing addresses



4. Functional improvements and further developments of NCK as compared to V2.6 SP1 (NCK 78.04.02)

5. SINUMERIK Operate

Functional extensions in SINUMERIK Operate 2.6 SP1 HF1 as compared to 2.6 SP1

- Display of user icons in the large header of the Machine area

User icons can be displayed in the second header line of the machine operator area. In this case, the program name is displayed in the right field of the third header line. Active stop conditions overlay the program name display. The user icon display is controlled via PLC bits. 32 bits are available for this. 16 positions are provided to display the user icons in the header. The icons must be provided as PNG files and stored in the file system (/user/hmi/ico/ico640, etc) for the specific resolution.

The user icons are configured in the section [UserIcons] of the file slmahdconfig.ini.

The following must be stated:

- The basic address of the PLC double word including the bits required to control the icon display and
- for each bit used, the file name of the user icon and the position where the user icons shall be displayed.

Example:

[UserIcons]

USER_ICON_BASE=DB19.DBB80 ; set the start byte of the plc double word that displays the icons
; (DB19.DBD80)

UI_0 = icon1.png,4 ; show icon1.png on position 4 if bit 0 (DB19.DBX83.0) is set
 UI_1 = icon2.png,6 ; show icon2.png on position 6 if bit 1 (DB19.DBX83.1) is set

5.1 Functional extensions in SINUMERIK Operate 2.6 SP1 HF3 as compared to 2.6 SP1

- Drive reset: With immediate effect, a warm restart of the drive can no longer be performed, that means, the softkeys Reset Extended Reset / Drive Device and Drive System have been removed.
- Store setup data: “_TMZ” is automatically appended to the name suggested for the backup file.
- Simulation: The hotkey “Ctrl+ M” allows to switch over the simulation speed between the speed currently set via override and the maximally possible speed. Make the following configuration setting in the file slsimconfigsettings before activating this hotkey:
 Parameter displayoptionmask/OverrideOverdrive
 0 = No overdrive
 1 = is deleted upon leaving the simulation
 2 = will be retained beyond leaving.

5.2 Notes regarding SINUMERIK Operate:

- The SINUMERIK Operate 2.6 SP1 software is automatically started as a component of the CNC software 2.6 when NCU 7x0 is started. SINUMERIK Operate is also called "internal SINUMERIK Operate" (contrary to the "external SINUMERIK Operate" on the PCU 50.3).
- The internal SINUMERIK Operate can only be operated from an operator panel with TCU (e.g. OP 012+TCU, HT 8,...) which is connected at X120 of NCU 7x0 using Ethernet. Operator control via PC/PG using the VNC viewer is possible.
- The configuration data such as e.g. PLC message and alarm texts must be saved on the CF card of the NCU in the corresponding directories under /card/user/sinumerik/hmi/... or /card/oem/sinumerik/hmi/... (refer to the commissioning instructions HMI sl). The file system on the CF card can only be accessed "online", i.e. only when the NCU is running. Data can be transferred using a USB stick or network connection via the SINUMERIK Operate operator interface (Commissioning / System data area) or using a network connection and the RCS Commander tool or WinSCP.
 IMPORTANT: Names of configuration files must always be written in lower case letters.
- When upgrading from CNC-SW 2.4, under certain circumstances, display MD values must be manually converted (from the hmi_md.ini file) into the corresponding new NC-MD. Refer to HMI sl commissioning instructions, section 9.1 for the conversion table.
- For storing part programs and archives on the CF card ("local drive"), option 6FC5800-0AP12-0YB0 "additional HMI user memory on CF card" is required. Notice: For a general NCK reset, the option is also deleted and as a consequence, the "local drive" is no longer available until the option is set again. Existing data is kept.
- When operating an NCU without TCU (i.e. only with HMI Advanced or HMI sl on PCU 50.3), the internal HMI sl must be deactivated. This is realized using a service command "sc disable hmi".
- Operator interface software HMI-Advanced 7.6 SP1 or the commissioning tool 7.6 SP1 is required to commission the drive.
- Only 1 SINUMERIK Operate may be active at 1 NCU - either the internal SINUMERIK Operate or 1 external HMI-Advanced or 1 SINUMERIK Operate for PCU 50.3 / PC.
 Exceptions: Commissioning / service; HMI-Advanced for the main operator station with permanently assigned MCP and 1 tool loading station with SINUMERIK Operate without MCP.
- After changing the NC configuration or reading-in or downloading an NC series commissioning archive, then an explicit data alignment may be necessary for the simulation. This is initiated in the commissioning / HMI area using the "Simulation Power On" softkey on the 2nd vertical softkey bar.
- Option 6FC5800-0AP22-0YB0 simultaneous recording: The program runtime display can be activated using MD 27860 \$MC_PROCESSTIMER_MODE.
- Loadable compile cycles are not backed up using NC series commissioning archive because they are saved on the CF card of the NCU and are kept for a general NC reset. They can be handled the same as HMI configuration data.
- The use of upper case/lower case letters when specifying paths in SELECT instructions of job lists, which refer to the part programs on the CF card or USB stick, is relevant and must be strictly observed.

- Handling special characters in the editor:
Text files can be edited using the SINUMERIK Operate Editor if the text files use the LF character (0aH) or the character string CRLF (0d0aH) as line or end of block identifier. The editor cannot open binary files. Files with the following extensions .EXE, .LIB, .ELF, .ARC, .TS, .ZIP, .SO, .PNG, .BMP, .ICO, .CFS, .BIN, .QM, .HMI, .CFG, .ACX, .EMF, .ALM, .ARD, .TGZ, .PTE, .CYC can neither be opened. Files that are newly generated from the SINUMERIK Operate Editor are UTF-8-coded - and have the LF characters as end of block identifier. For UTF-8-coded files, all special characters are correctly displayed. When opening files, the SINUMERIK Operate Editor assumes that the files are UTF-8-coded. If files with another coding are opened, e.g. with Windows page coding, then the special characters are only correctly displayed if the SINUMERIK Operate was changed over to the appropriate system language. This also involves e.g. files that were generated using the HMI-Advanced Editor. When opening with the SINUMERIK Operate Editor, the coding of such files is not changed. There is no automatic conversion into UTF-8-coding. If files were generated or processed with an external editor (e.g. Notepad under Windows) and not the SINUMERIK Operate Editor, then it should be noted that the file is saved, UTF-8-coded. When using Notepad, and when saving the file as encoding select "UTF-8" in the "Save As" dialog box. If special characters are not being used, then "ANSI" can also be specified as encoding.
- For the V24 data transfer, the V24 module 6FC5312-0FA01-0AA0 must be integrated into the NCU. The function is activated in HMI in the file /oem/sinumerik/hmi/cfg/slpconfig.ini with the entry
[V24]
userV24 = true
A template for this file is provided under /siemens/sinumerik/hmi/template/cfg.
The V24 softkeys are provided in the ProgramManager under "Archive". The V24 baudrate is limited to max. 19200.

6. Information regarding the NCU base software:

- The Linux operating system of the NCU 7x0 is also known as the NCU base software, analog to the base software for the PCU 50.3. The associated documentation is provided on the DVD supplied in IM7. When booting, the NCU base software ensures that the NC, PLC and HMI software start - and if it is being used - that the TCU is also booted. The NCU base software is user-orientated, i.e. you must log-on with a login and password and you are then allocated certain access rights. Presently, this is only relevant for the access to a Linux service shell or for access to the CF card using RCS commander or WinSCP. For commissioning and service, the "manufact" login is used together with the password "SUNRISE" (observe upper and lower case letters!). The Linux service shell is entered at the TCU by simultaneously pressing the "Area changeover" and "Recall" keys (F10 and F9), followed by "Scan for Servers", "2" or by booting the NCU service system from the USB stick.
- After booting the NCU 7x0 from a USB stick with the NCU service system, the "manufact" login and "SUNRISE" password must also be entered assuming that the CF card contains CNC software that can run. If this is not the case (e.g. if the CF card is empty), then in this case, the login is "admin" followed by "SUNRISE" as password.
- Using the command "sc help", in this service shell you obtain a list of the syntax of all of the available service commands.

6. 1 Networking:

- **Please observe the current documentation "Operator components and networking (IM5) Version 03/2010"!**
- **All of the settings regarding networking and TCU configuration can also be performed using the "System Network Center"; this is available on the PCU 50.3 as well as on the NCU.**
- Important system and network settings of the NCU base software are present in the **basesys.ini** file in the directory /card/user/system/etc. - and can be changed there. The original basesys.ini is located under /card/siemens/system/etc with the name "template-basesys.ini". Every NCU in the plant or system network should be allocated a unique ("informative") computer name with the entry "Host name=..." in basesys.ini. Upper case/lower case letters, numbers and minus symbol characters are permitted.
- The DHCP server of the NCU should always be switched on.
- When changing IP addresses of NCUs / PCUs, the service command "sc clear dhcp" should be run in

order that the change becomes effective.

6.1.1 Configuration of one NCU with TCUs and MCPs

With this configuration, principally, there are no special settings required in basesys.ini. DHCP server and internal HMI-sl remain switched on.

6.1.2 Configuration of one NCU with one PCU 50.3, MCPs and where applicable TCUs

With this configuration, the following settings are required in the basesys.ini of the NCU:

Host name =

SyncModeDHCPD_SysNet = ON_MASTER

Generally, the internal HMI-sl should be switched off because operating two HMIs (HMI-Advanced and Operate) on one NCU is only permissible in special cases.

We recommend that PCU 50.3 base software from V8.6 SP1 and higher is used on the PCU 50.3.

If there is a TCU (HT8) in the system that is to be switched as standard to the PCU 50.3, then the following entries

MaxHostIndex = 1

[host_1]

Address = <IP address of the PCU>

must be entered on the NCU in the file/card/user/common/tcu/<TCU-Nama>/common/tcu/config.ini.

6.1.3 Configuration of several NCUs and where applicable 1 or several PCUs, TCUs, MCPs

With this configuration, the following settings are required in the basesys.ini of the NCU:

unique host name = for each NCU

unique InternalIP=

same InternalNetMask=

precisely one NCU with SyncModeDHCPD_SysNet = ON_MASTER

When first booting after networking, the DHCP master should first boot and then the other stations.

PCU base software from V8.6 SP1 and higher is required on the PCU 50.3.

The default configuration "Complete TCUsupport" should be kept in the System Network Center, tab TCU support. "Sync mode low priority" is recommended under the tab DHCP-Settings.

All operator stations in the plant/system network (TCUs, HT8, PCU 50) are managed on the NCU with "ON_MASTER", i.e. the config.ini files - relevant during the runtime - and also the .leases file with all of the IP addresses allocated in the system are located there.

The config.ini files are distributed to all other NCUs / PCUs from the master NCU with the service command "sc distribute tcudata".

With the service command "sc clear dhcp" followed by powering down/powering-up the complete system, the NCUs / PCUs are allocated, their specified IP addresses and these are re-allocated for the TCUs and MCPs; the .leases file is then distributed to all other NCUs / PCUs.

Important: With the System Network Center, tab OPs, the config.ini files of all operator stations can be directly edited on the master NCU on each PCU 50.3. The data is automatically distributed to all NCUs / PCUs with each change.

7. Cycle packages:

In the CNC Software Version 2.6 SP1, the following cycle packages are included on the CF card:

- Cycles (technological cycles)
- Measuring cycles
- ISO cycles
- ShopMill cycles
- ShopTurn cycles

All these Siemens cycles are automatically loaded into the NC during the NCU startup. The corresponding variables are stored in the definition file PGUD.

Important information:

The "programGUIDE" (earlier, cycle support) in SINUMERIK Operate 2.6 SP1 is based on these cycle packages 2.6. Cycle calls in the part programs for these cycles cannot be re-compiled and processed with the cycle support in HMI-Advanced 7.x. This also means that the simulation function in HMI-Advanced cannot be used. If the cycle support of HMI-Advanced 7.x is to be used, then the cycle packages 7.x contained in HMI-Advanced - should be downloaded into the NC after deactivating the cycles 2.6 with the service command "sc disable s_cycles". This means that no SINUMERIK Operate operation is permissible.

7.1 Technological cycles - function scope

The following cycles / functions are included as from SW 2.6 SP1:

Drilling

Cycle	Function and entry softkeys
CYCLE801	Drilling / positions / grids or frame
CYCLE802	Drilling / positions / any positions
CYCLE81	Drilling / centering
CYCLE82	Drilling / drilling reaming / drilling
CYCLE83	Drilling / deep hole drilling
CYCLE85	Drilling / drilling reaming / reaming
CYCLE86	Drilling / boring
HOLES1	Drilling / positions / series of holes
HOLES2	Drilling / positions / circle of holes
CYCLE840	Thread / tapping with compensating chuck
CYCLE84	Thread / tapping without compensating chuck
CYCLE78	Thread / drill and thread milling

Turning

Cycle	Function and entry softkeys
CYCLE92	Turning / cutting off
CYCLE930	Turning / grooving
CYCLE940	Turning / undercut - Form E, Form F, undercut thread DIN, undercut thread
CYCLE951	Turning / stock removal
CYCLE98	Turning / thread / thread chain
CYCLE99	Turning / thread - longitudinal, taper, face
CYCLE62	Contour turning / contour / contour call
CYCLE952	Contour turning/ stock removal, plunging, plunge turning, all with residual material

Milling

Cycle	Function and entry softkeys
CYCLE60	Milling / engraving
CYCLE61	Milling / face milling
CYCLE70	Milling / thread milling
CYCLE76	Milling / spigot / square spigot
CYCLE77	Milling / spigot / circular spigot
CYCLE79	Milling / spigot / multi-edge
POCKET3	Milling / pocket / rectangular pocket

POCKET4	Milling / pocket / circular pocket
LONGHOLE	Milling / slot / long hole
SLOT1	Milling / slot / longitudinal groove
SLOT2	Milling / slot / circular slot
CYCLE899	Milling / slot / open slot
CYCLE72	Contour milling / path
CYCLE62	Contour milling / contour
CYCLE63	Contour milling / pocket, spigot, all with residual material
CYCLE64	Contour milling / pre-drilling
CYCLE800	Various / swivel plane, swivel tool
CYCLE832	Various / >> / HighSpeed settings

Compatibility cycles to 802Dsl:

- These cycles can be re-compiled and changed in screen forms

Cycle	Function
CYCLE71	Compatibility 802Dsl – face milling
CYCLE87	Compatibility 802Dsl – boring 3
CYCLE88	Compatibility 802Dsl – drilling with stop
CYCLE89	Compatibility 802Dsl – boring 5
CYCLE90	Compatibility 802Dsl – thread milling
CYCLE93	Compatibility 802Dsl – groove
CYCLE94	Compatibility 802Dsl – groove, form E and F
CYCLE95	Compatibility stock removal (re SW 2.5 and 802Dsl)
CYCLE96	Compatibility 802Dsl – thread undercut forms A, B, C, D
CYCLE97	Compatibility 802Dsl – thread cutting

Other cycles - internal:

Cycle	Function
CYCLE861	Reverse countersink only for ISO compatibility, no input screen form
CYCLE202	Help cycle for retraction
CYCLE203	Help cycle for chamfering
CYCLE204	Help cycle, calculating pitch for metric threads
CYCLE206	Help cycle, tool change in JOG
CYCLE206	Help cycle, tool change in JOG
CYCLE207	Help cycle SERUPRO
CYCLE208	Help cycle for multi-channel application (joblist processing)
CYCLE209	Help cycle for multi-channel application
CYCLE210	Help cycle machine configuration analysis
CYCLE211	Help cycle blank definition for simulation
GROUP_ADDEND	Help cycle multi-channel editor
GROUP_BEGIN	Help cycle multi-channel editor
GROUP_END	Help cycle multi-channel editor
PROG_EVENT	ASUP to support special operating modes
CUST_800	Manufacturer cycle for swiveling (earlier TOOLCARR)
CUST_832	Manufacturer cycle for HighSpeed settings (earlier CYC_832T)

CUST_M6	Manufacturer cycle for adjusting tool changes with SERUPRO
CUST_MULTICHAN	Manufacturer cycle for multi-channel editor
CUST_T	Manufacturer cycle for adjusting tool changes with SERUPRO
CUST_TECHCYC	Manufacturer cycle for technological cycles (earlier ST_CUST)

Important new functions with respect to 840Dsl SW 1.5 (cycles SW 7.5):

General

- The configuration of cycle functions or the input screen forms for cycles is made in the configurable machine or setting data. However, part programs using the old setting data in the GUDs (field _ZSD[x]) can still run.

Drilling

- Support drilling cycles, select depth referred to shaft/drill tip
- New drilling pattern frame
- New cycle, drill and thread milling (CYCLE78)

Turning

- Contour transfer using CYCLE62 when machining (stock removal)
- New cycle, cutting off
- Extended functionality, grooving
- Extended functionality, undercut
- Extended functionality, thread cutting
- New cycle, contour turning (CYCLE952) with the following functions:
 - Stock removal
 - Stock removal, residual material
 - Plunging (contour plunging)
 - Plunging, residual material
 - Plunge turning
 - Plunge turning, residual material

Milling

- Contour transfer using CYCLE62 for path milling
- Extended functionality, face milling (edge limit)
- Extended functionality, thread milling
- New cycle, multi-edge
- Milling cycles can be executed for individual positions or a pattern of positions
- Milling cycles have the new chamfering function
- New cycles, contour milling (CYCLE63) and pre-drilling (CYCLE64) with the following functions:
 - Contour pocket with or without islands (presently, a maximum of 10 islands is possible)
 - Contour pocket, residual material
 - Contour spigots
 - Contour spigots, residual material
 - Pre-drilling

Important new functions as from SW 2.6 SP1:

General

- The multi-channel editor is supported as from this Software Version.

General

The configuration of cycle functions resp. cycle input screens is included in the

List of differences, cycles/cycle functions for 840D sl SW 7.5:

The following cycles/cycle functions are not included in this cycle package:

Cycle	Function and entry softkeys
-------	-----------------------------

POCKET1 POCKET2	Rectangular pocket / circular pocket ¹
--------------------	---

Supplementary conditions / restrictions:

- The number of islands for contour pockets is limited to 10.

Special notes:

- To activate the cycle supply, the machine data
 - MD 52200 MCS_TECHNOLOGY > 0 (1 = turning or 2 = milling)
 must be set.
- There is no display or possibility of entering data for TOOLCARR data. This can only be set using the NC program.
- The following adjustment must be made in CUST_T and CUST_M6 for the "Multitool" application:

The following must always be requested when deducting tool data from the magazine assignment:

Multitool == no --> o.k. continue as usual

Multitool == yes --> which tool is located at the machining position --> fetch this T no.

Example:

```
T_No=$TC_MPP6[9998,_LOCATION]
if T_No>=1
  if $P_TMNOIS[T_No]==0 ;Multitool
    _T_Spi=$TC_MTP6[T_No,$TC_MTP_POS[T_No]]
  else
    _T_Spi=T_No
  endif
endif
```

1. Measuring cycles – functional scope

The following cycles / functions are included as from SW 2.6:

Measuring in JOG

The measuring cycles support the following set-up functions in JOG (SK "zero point workpiece"):

- Calibrate key (radius, length)
- Set edge
- Align edge
- Measure corner (3 points, right angled corner)
- Measure 1 hole
- Measure 1 circular spigot

New from SW 2.6

- Clearance, 2 edges
- Measure corner (4 points)
- Measure 2 or 3 or 4 holes
- Measure rectangular spigot
- Measure 2 or 3 or 4 circular spigots
- Align plane

The functions "zero point workpiece" are only available in milling technology.

The following measuring functions used to measure tools in JOG are available (SK "measure tool"):

¹ The POCKET1/POCKET2 function is covered by the newer pocket milling cycles POCKET3/POCKET4

- Calibrate tool probe
- Measure tool length
- Measure tool radius

New from SW 2.6 SP1

- Tool measurement on turning machines with B axis at an arbitrary angle

Measuring in the automatic program

- Workpiece measurement, milling machines with the following functions:
 - Calibrate workpiece probe in a hole or at a surface (CYCLE976)
 - Measure hole, spigot, groove (slot), rib, rectangular pocket, rectangular spigot in parallel with the axis (CYCLE977)
 - Measure edge (CYCLE978)
 - Measure segment of a circle, outer or inner (CYCLE979)
 - Measure slot or rib under an angle (CYCLE979)
 - Measure corner in the automatic program (CYCLE961)
 - Measure angle in the automatic program (CYCLE998)
 - Measure kinematics (CYCLE996)
- Tool measurement, milling machines using the following functions:
 - Measure tool in the automatic program (CYCLE971)
- Workpiece measurement, lathes using the following functions:
 - Calibrating a workpiece probe in either the slot or at the surface (CYCLE973)
 - Single point measurement (CYCLE974)
 - Two point measurement (CYCLE994)
- Tool measurement, lathes using the following functions:
 - Measuring tools in the automatic program (CYCLE982)
- General measuring cycle functions:
 - Measuring cycle support in the editor
 - Measuring result diagram display
 - Optional correction of the measuring difference in a WO or a WO data set or only measuring
 - Use of either a monoprobe or multiprobe

Prerequisites for use

- The measuring cycles require a switching, electrical probe.
- Corresponding to the pre-assignment of the machine data for measuring cycles, the workpiece probe should be connected at the first measuring input of the control (these settings can be changed using the machine data
MD 52600 MCS_MEA_INPUT_PIECE_PROBE and
MD 52601 MCS_MEA_INPUT_TOOL_PROBE)

Important new functions with respect to 840Dsl SW 1.5 (measuring cycles SW 7.5)

General

- All measuring cycle data that are important for the machine manufacturer (OEM) and user are now included in the configurable machine and setting data (e.g. data fields of the calibration values). The GUD blocks GUD5, GUD6 and GUD7_MC are no longer required.

List of differences, measuring cycles/cycle functions for 840D sl SW 7.5:

The following cycles/cycle functions are not included in this cycle package:

- Logging measuring results

List of measuring cycles omitted:

Cycle	Function and entry softkeys
-------	-----------------------------

CYCLE972	Compatibility for tool measurement on turning tool
CYCLE198 CYCLE199	Help cycles for machine manufacturer (replaced by CUST_MEACYC)
CYC_JM CYC_JMA CYC_JMC	Help cycles for measuring in JOG (replaced by CYCLE130, CYCLE131)
CYCLE100 CYCLE101 CYCLE105 CYCLE106 CYCLE113 CYCLE118	Help cycles for logging

(see also /4/ Appendix)

Special notes:

- The following two setting data must be carefully observed regarding the functionality of making measurements in JOG:
SD 54798 SCS_J_MEA_FUNCTION_MASK_PIECE
SD 54799 SCS_J_MEA_FUNCTION_MASK_TOOL
- After upgrading from SW 2.x to SW 2.6 SP1 and reading in a series commissioning archive, you have to calibrate the system because otherwise incorrect calibration data are used.

2. Cycles ISO compatibility – functional scope

The functional scope of cycles for ISO compatibility corresponds to that of SW 6.5 for SINUMERIK 840D. The two ISO dialects are still supported.

The setting data of the cycles for ISO compatibility has been changed over to the configured machine and setting data. The data fields for the setting in the GUDs are no longer relevant.

3. Configurable machine and setting data – functional scope

The following functions are included as from Software Version 2.6:

New configurable machine and setting data have been introduced from SW 2.5. When the control starts (cold start) these are automatically read in from the CF card and activated.

- This data replaces the GUD variable of the cycle packages and the display MDs of the JobShop and HMI.
- Just like all other machine and setting data, they are displayed in the "Commissioning" area (depending on the protection stage) and are located in the range of numbers starting 50000 and higher.

51xxx	General MD
52xxx	Channel MD
53xxx	Axis MD
54xxx	General SD
55xxx	Channel SD
56xxx	Axis SD
- The names of the data provide information about their significance and use; the appropriate codes are located directly after the prefix, e.g. DISP for display, ISO for ISO cycles, MEA for measuring cycles, TURN for turning, etc.
- The configurable machine and setting data support the data class concept for data backup.

4. Compatibility

4.1. Compatibility to cycle packages 840D sl to SW 1.5

The behavior of the cycles with respect to software releases up to SW 1.5 has been changed regarding the following points:

Technological cycles:

1. Milling cycles - calculating the infeed depth with / without taking into account the safety clearance (previously this was able to be set in the GUD variables `_ZSD[1]`):
In setting data `$SCS_FUNCTION_MASK_MILL_SET` bit2 it is possible to set whether the safety clearance should be included when calculating the depth - or not. Previously, "taking into account the safety clearance" was set as the default setting – now "without taking into account the safety clearance" is the default setting. This means that the individual depth infeeds can change in existing programs.
The setting of this setting data acts in the same way in the G code programs and ShopMill or ShopTurn programs.
2. Milling cycles when calling with MCALL:
Milling cycles in the G code programs can be optionally called also to position patterns with MCALL.
3. Thread drilling cycles CYCLE84, CYCLE840 – technology parameters (previously were able to be set in GUD variables):
The machinery construction OEM must enter the technology parameter settings he requires in the corresponding cycle setting data. These settings are neither changed by the cycle nor by the input screen form.
4. Thread drilling cycle CYCLE840 – parameter to reverse the direction:
The "Direction of rotation for retraction" parameter is no longer supported in the input screen form of the cycle. This makes sense, as in the meantime, the cycle has this function for both thread types and also only functions if a spindle direction has been programmed before being called.
5. Pocket milling cycles POCKET3 and POCKET4 – parameters for plunge feeding:
The programmed feed for the infeed depth is only effective for "pre-drilled" and "vertical". "Helical" and "oscillating" plunging is realized with the feed for machining in the plane.
6. Milling cycle, rectangular pocket POCKET3 – reference, angle of rotation of the pocket:
The angle of rotation now always acts at the reference point. The programming for rectangular pocket "reference point is a corner" and "angle of rotation refers to the center" (with `ZSD[2]=1` and `ZSD[9]=1`) are no longer available, but lead to Alarm 61109 "Parameter `_STA` incorrectly defined".
7. Milling cycles – parameter for the infeed width:
For the infeed width, a value > 0 must always be entered. In the screen form, the field is marked as incorrect and the cycle issues an alarm.
8. Drilling and milling cycles – safety clearance parameters:
A value > 0 must always be entered for the safety margin as this value is also effective for the changeover from G0 to G1 when approaching to machine in the tool axis. The field is marked as incorrect in the screen form.
9. High Speed settings CYCLE832: The differences are explained using the documentation:
Documentation up to SW 7.5: Programming Manual, Cycles [1]
Documentation from SW 2.6: Commissioning Instructions IHsl IM9 [2]
Operating Instructions, Milling [3] or Operating Instructions, Turning [4]
 - All functions documented in /6/ "Point 3.17" that are coded in parameter `_TOLM` - with the exception of the machining type (`_TOLM` ones location) will, from SW release 2.6, only be supported in the compatibility mode.
 - All GUDs described in /6/ Point "3.17.4.3 Adaptation of the machinery manufacturer" and the documented functionality are no longer available from SW release 2.6 onwards.
 - Refer to /6/ "Point 3.17.4.4 Adaptation of additional program parameters `CYC_832T`"
From SW release 2.6 and higher, the user cycle `CYC_832T.SPF` will be replaced by the cycle `CUST_832.SPF`. For compatibility, the marks `_M0` to `_M4` are still available in the `CUST_832` cycle. The transfer parameter `_OVL_on` of `CYC_832T` has been eliminated as the documented machine data cannot be re-written in `CYCLE832`.

- Note to /6/ Point "3.17.5 Interfaces"
- All documented machine and setting data are not rewritten in CYCLE832 from SW release 2.6 and higher. All documented channel-specific variables GUD7 have been eliminated from SW release 2.6 and higher.
- With the application of the CYCLE832, the option Advanced Surface (AS) must always be active. Otherwise, the error 8025 "Option AS not set" is output.
According to the application example AS in the Commissioning Instructions for HMI Operate (03/2010), AS requires specific G commands. These G commands are not mandatorily compatible with the settings of the "old" CYCLE832 resp. CYC_832T. These new G commands have been entered as a suggestion (commented with ;) in the individual screens of the compatibility branch (as from the mark _M1). The SOFT command is always activated because BRISK does not fit with AS.
The old calls CYCLE832 should only be used in exceptional cases. When upgrading the machine, we recommend that you replace the old calls by the new calls with CYCLE832. The settings for tolerance and machining type (roughing, finishing, ..) can be accepted.
The parameter _FACTOR should no longer be used.
Factor settings, see Commissioning Instructions for HMI Operate (03/2010) -> SD55441 to SD55443.
When writing the parameter _FACTOR in CUST_832.SPF in the compatibility branch, this value is effective.
- 10. Swivel cycle CYCLE800: (reference to documents as in Point 8 for CYCLE832):
 - The menu screens, documented in /6/ under point "3.16.7.2 Commissioning kinematic chain" to commission swivel, have been eliminated in SW release 2.6. The parameters (vectors) of the kinematic chain can be read and written to as NC variable -> refer to /5/ CYCLE800.
Example: \$TC_CARR1[2]=123.456 -> linear vector I1X of the 2nd swivel data set = 123.456
 - The coding of parameter \$TC_CARR37[swivel data set n] has changed:
The setting "Direction rotary axis 1" or "Direction rotary axis 2" in the fourth position (THOUSANDS) \$TC_CARR37[n] are no longer permitted from SW release and must be replaced by the setting "direction rotary axis 1 optimized" or "direction rotary axis 2 optimized". This means that the pole position of a rotary axis is supported with both selection options of the direction (plus or minus).
When coding parameter _MODE and _DIR in the call interface of CYCLE800, the following definition applies:
If an "old" program call is accepted, the direction setting is accepted, optimized in the HUNDRED THOUSANDS position of the the parameter _MODE:
 _DIR = -1 _MODE = 10xxxx swivel yes, direction minus
 _DIR = +1 _MODE = 20xxxx swivel yes, direction plus
 _DIR = 0 _MODE = 11xxxx swivel no, direction minus
 _DIR = 0 _MODE = 22xxxx swivel no, direction plus
 If the setting of the direction is changed in \$TC_CARR37[n] when upgrading to software release 2.6, then the corresponding NC programs must be run in again.
This is especially true for programs where, when swiveling, a rotary axis is in the pole position, e.g. swivel table, rotary axis A=0 (pole position) swivel with rotary axis C.
 - The coding, retract in the 7th and 8th position of \$TC_CARR37[n] x00xxxxxx up to x03xxxxxx has been recoded from SW release 2.6 and higher.

	up to SW 2.6	from SW 2.6
\$TC_CARR37[n]	x00xxxxxx	x01xxxxxx retract Z
\$TC_CARR37[n]	x01xxxxxx	x03xxxxxx retract Z or Z, XY
\$TC_CARR37[n]	x02xxxxxx	x02xxxxxx retract Z, XY
\$TC_CARR37[n]	x03xxxxxx	x00xxxxxx no retraction
 - From SW release 2.6, the swivel data sets must be designated as either being active or inactive. This is realized in parameter \$TC_CARR37[n] at the 9th position (HUNDRED MILLION).
 \$TC_CARR37[n] 0xxxxxxxxx to 3xxxxxxxxx means swivel data set not active
 \$TC_CARR37[n] 4xxxxxxxxx to 7xxxxxxxxx means swivel data set active
 The parameters \$TC_CARR38[n] up to \$TC_CARR40[n] are converted into the actual dimension system (inch, metric) by the NCK from SW release 75 and higher. If the parameters are to be written in (customers) user cycles, then it is absolutely necessary that this is taken into account when upgrading to SW release 2.6 in conjunction with NCK from 75 and higher.
 NC programs with the data of the swivel data set can be reused with software release 2.6 if parameter \$TC_CARR37[n] is appropriately adapted.

- Note to /6/ Point "3.16.8 Manufacturer's cycle TOOLCARR.SPF"
The user cycle TOOLCARR.SPF is replaced, from SW release 2.6 and higher, by the cycle CUST_800.SPF. From a functional perspective, cycle CUST_800.SPF corresponds to the cycle TOOLCARR.SPF, including all of the marks prepared for machinery construction OEMs for the appropriate machine-specific adaptations -> refer to the comments in CUST_800.
If the "track tool" function has been activated, then the first multi-axis transformation (TRAORI(1)) becomes active in cycle CUST_800.SPF when tracking tool.
The mark _M35 in CUST_800.SPF is new from software release 2.6 and higher. This supports semi-automatic and manual rotary axes in the block search. From a contents perspective, Mark _M35 replaces cycle CYCPE_SC.SPF, which has been eliminated from software release 2.6 and higher.
- If the optimized behavior in the basic setting (pole setting) of the rotary axes is not requested (compatibility), it can be deactivated with the following cycle setting data:
SD55221 \$SCS_FUNCTION_MASK_SWIVEL_SET bit 4
Bit 4 = 0 Evaluation of the input values CYCLE800 in the pole position of the machine kinematics
Bit 4 = 1 CYCLE800: Compatibility
- 11. Circular pocket cycle POCKET4 – plunging: With depth infeed with G0 (pre-bored), the infeed is now always performed with G0 independently of whether rough size has been programmed or not. It is assumed that there is enough space until (DP+SDIS)
With infeed into the material, the programmed helix radius is active if it is smaller than the tool radius. So far, the tool radius was active in such cases.
- 12. Circular pocket cycles POCKET3, POCKET4 – special case 1 depth infeed: During roughing / finishing, only one depth infeed is performed if the infeed depth >= material depth to be maximally cut.

These changes may require that existing programs are adapted.

Measuring cycles:

1. The data concept of the measuring cycles was revised with the introduction of new machine and setting data. Setting data, which were previously stored in GUD variables, have now become machine and setting data.
Attachment A of document /4/ contains tables with the corresponding information about:
 - Comparison of GUD parameters ⇔ machine and setting data
 - GUD variables that are no longer used
 - Changes to the names of cycles and GUD blocks.
2. When using the measuring cycles with different dimension systems (base system <> programmed system) and when programming G commands G70 or G71, the dimension units of the following tolerance parameters have changed. They now refer to the programmed system (previously, basic system):
Confidence range (_TSA), zero correction range (_TZL), average value generation with correction (_TMV), dimension difference monitoring (_TDIF).

These changes may require that existing programs are adapted.

ShopMill cycles:

1. Up until SW 1.5, it was also possible to specify the reference point (X0, Y0, Z0) for ShopMill in incremental terms. In the new opened screen forms, now the reference point can only be entered in absolute terms.
For re-compiled screen forms, in which an incremental reference point occurs, a toggle field abs/inc is displayed. For inc, the check issues an error message "reference point inc no longer supported, please convert to abs".

Error corrections in all cycle packages for SW 2.6 SP1 HF1 (RQs):

5. Commissioning notes

5.1. Notes on upgrading (840D sl only):

If a SGUD.DEF block is provided after reading in a series commissioning archive, this must be deleted. Otherwise, several alarms may be output upon startup of the simulation due to double GUD definitions (alarm numbers 12170 and 15185).

Procedure:

- Delete SGUD.DEF if it only contains the definitions of the cycle packages from Siemens (the software version can be identified by a version entry “;VERSION: 02.05.xx.xx ...” or higher);
- If it contains additional data definitions beyond the cycle packages from Siemens, these must be relocated before into the MGUD.DEF block and the SGUD.DEF block must be deleted;
- Or if it contains additional definitions which must remain in the SGUD.DEF block (e.g. due to compile cycle), the SGUD.DEF must be adapted so that it contains only these additional definitions.

After upgrading from SW 2.x to SW 2.6 SP1 and reading in a series commissioning archive, you have to recalibrate the system since otherwise incorrect calibration data are used.

5.2. Change of Documentation - SINUMERIK Operate – Commissioning Manual:

P.338

MD10602 \$MN_FRAME_GEOAX_CHANGE_MODE= 1

The current total frame (zero offsets) is recalculated when switching over geometrical axes (selection / deselection of TRAORI).

This setting is required with tool tracking.

MD11604 \$MN_ASUP_START_PRIO_LEVEL = 100

P.344 above

SC55410 \$SCS_MILL_SWIVEL_ALARM_MASK

This is now a channel-specific setting data.

P.346 above:

Swivel head

- I3 distance between the tool adapter and the pivot/intersection point of the second rotary axis
- I2 distance between the pivot/intersection point of the second rotary axis and the pivot/intersection point of the first rotary axis
- I1 closing of the vector chain $I1 = -(I2 + I3)$ if the swivel head cannot be replaced

Swivel table

- I2 distance between the machine reference point and the pivot/intersection point of the first rotary axis
- I3 distance between the pivot/intersection point of the first rotary axis and the pivot/intersection point of the second rotary axis (resp. the tool adapter reference point)
- I4 closing of the vector chain $I4 = -(I2 + I3)$ if the swivel table cannot be replaced

Swivel head / swivel table (mixed kinematics)

- I2 distance between the tool adapter and the pivot/intersection point of the first rotary axis
- I1 closing of the vector chain $I1 = -I2$ if the swivel head cannot be replaced
- I3 distance between the machine reference point and the pivot/intersection point of the second rotary axis (resp. the tool adapter reference point)
- I4 closing of the vector chain $I4 = -I3$ if the swivel table cannot be replaced

The offset vectors need not mandatorily point towards the pivot of the rotary axes. It is important that they point towards a point in the rotational direction (intersection point).

The signs of the offset vectors (I1...I4) and rotary axis vectors (V1, V2) result from the axis directions stipulated according to ISO 841-2001 resp. DIN 66217 (right-hand rule). In kinematics moving the workpiece (rotary table), the axis direction is reversed.